

## AN ABSTRACT OF THE DISSERTATION OF

Carlos F. Gonzalez for the degree of Doctor of Philosophy in Chemistry presented on July 10, 2007.

Title: From Electrophoresis to Dielectrophoresis: Designing, Fabricating, and Evaluating an Electroformed Ratchet Type Microfluidic Dielectrophoresis Device

Abstract approved:

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Dielectrophoresis (DEP) is a separation method in which a non-uniform electric field is used to induce a dipole moment in a suspended particle. If the polarization of the particle is greater than that of the suspending medium, the particle will move towards the region of higher field strength (positive DEP); while if the particle is polarized less than the suspending medium, the particle will be moved towards the low potential area (negative DEP). In recent years DEP has been gaining popularity through the construction of microscale devices, and this is due largely to the decrease in electrode spacing which allows for higher effective field strengths.

Presented is the design, fabrication, and evaluation of a novel dielectrophoretic based ratchet device. The electrodes required to produce the asymmetrical field

were constructed of electroformed nickel features grown on the surface of a resist patterned seedlayer coated glass slide, and this is the first time electroforming has been used to produce electrodes in the field of DEP. The electrodes were then made stand alone features located on the glass slide by wet etch removal of the unplated portions of the seedlayers located on the surface of the glass substrate. The fluidic component of this device was constructed using replica molding of poly(dimethylsiloxane), which contained a fluidic reservoir located over the ratchet electrode features.

Particle selection was conducted using an *a priori* approach for particles of known dielectric properties. The frequency responses of perspective test particles to an asymmetrical electric field were determined through calculation of the real component of the Clausius-Mossotti factor ( $\text{Re}[K(\omega)]$ ). From these calculations, magnetite and polystyrene spheres were selected as test particles. The device was then evaluated using the test particles selected to determine if particle collection occurred in the regions dictated by  $\text{Re}[K(\omega)]$ . Suspensions consisting of single particle types and a mixture were then evaluated, and it was found that the particles collected in the regions specified by the theoretical calculations. These results showed that the device is capable of collecting particles based on the dielectric properties of the magnetite particles and polystyrene spheres.

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From Electrophoresis to Dielectrophoresis: Designing, Fabricating, and Evaluating  
an Electroformed Ratchet Type Microfluidic Dielectrophoresis Device

by  
Carlos F. Gonzalez

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I understand that my dissertation will become part of the permanent collection of Oregon State University libraries. My signature below authorizes release of my dissertation to any reader upon request.

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Carlos F. Gonzalez, Author

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## CONTRIBUTIONS OF AUTHORS

Corey R. Koch assisted in master production, imaging, and measurements used in Chapter 3.

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**Chapter 1:**  
**Harnessing dielectric forces for separations of cells, fine particles  
and macromolecules : A review**

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## Abstract

A review of conventional dielectrophoresis on a microchip platform is presented. The benefits of miniaturization, some device geometries used to accomplish on-chip separations, and applications of these devices are discussed.

### 1.1 Introduction

Dielectrophoresis (DEP) is a separation method in which particles are segregated according to their susceptibility to a non-uniform electric field. A non-uniform electric field is generated by applying voltage across electrodes of appropriate geometry or by placement of insulating posts between a pair of electrodes. In both cases, the components are configured to spatially distort the electric field. Unlike electrophoresis where only dc voltage is used, either dc voltage or an ac waveform can be used in DEP to discriminate between different particles in a sample. By varying the frequency of the applied voltage, it is possible to induce a dipole moment in a particle and thereby cause the particle to experience a positive dielectrophoretic moment or a negative dielectrophoretic moment and cause the particle to move into a region of high potential or low potential respectively. The first investigator of this phenomenon as a tool in separations was Herbert Pohl, with his analysis of suspended particles in an organic medium [1]. From his observations in this initial study, Pohl coined the term “dielectrophoresis” for the motion of particles within a medium arising from an induced dipole in a non-uniform electric field.

Some initial devices used by Pohl to produce non-uniform electric fields were constructed by placing a wire in the center of a glass tube in which another wire was wrapped along the inner wall of the glass tube [2]. These devices required high potentials and were limited to analysis of particles 1  $\mu\text{m}$  in diameter or larger due to Joule heating effects which led to Brownian movement that countered dielectrophoretic force [3]. Benefits in decreasing the scale of dielectrophoretic devices, thereby increasing the dielectrophoretic force, were discussed by Bahaj and Bailey [4]. From their study, the following scalar relation can be derived:

$$F_{DEP} \propto \frac{V^2}{L_e^3} \quad (1)$$

where  $F_{DEP}$  is the dielectric force,  $V$  is the applied voltage and  $L_e$  is the length between electrodes. From Eq. 1, one can see that  $F_{DEP}$  is inversely proportional to the cube of the dimensions of the electrodes used; hence by miniaturization of DEP devices, the magnitude of the dielectrophoretic force exerted on a particle is increased. Another finding was that decreasing electrode size led to a reduction in Joule heating.

In recent years, with the use of semiconductor manufacturing technologies such as lithography, electron beam writing, and laser ablation, a move towards device



miniaturization has been occurring. Benefits of device miniaturization include decreased consumption of reagents and sample, reduced analysis time, and the possibility of portable instrumentation.

Several different modes of microchip based DEP exist. These modes include focusing/trapping DEP [5-7], isomotive DEP [8], traveling wave DEP [9-11], and DEP field-flow fractionation [12-13]. In this article we will focus on “conventional” DEP in the microchip format: focusing and trapping of particles in devices that utilize parabolic electrodes, castellated electrodes, electrode arrays, and arrays of insulating posts as the geometries.

## 1.2 Theory

A force will be experienced by a dielectric particle when it is placed in a non-uniform electric field [14,15]. A non-uniform electric field is necessary to create an imbalanced force on the suspended particle in the field. This force variation can induce a dipole moment in the particle, and as long as the electric field is non-homogeneous the force imbalance can be used to move particles. For conventional dielectrophoresis, the dielectrophoretic force experienced by a particle in a non-uniform electric field can be approximated by [15]:

$$F_{DEP} = 2\pi r^3 \text{Re}[K(\omega)] \nabla E_{rms}^2 \quad (2)$$

where  $r$  is the radius of the particle,  $\nabla$  is the del vector operator, and  $E_{\text{rms}}$  is the root mean square applied electric field.

$\text{Re}[K(\omega)]$  refers to the real component of the Clausius-Mossotti factor [15] which is found by taking the real component of:

$$K(\omega) = \frac{(\varepsilon_p^* - \varepsilon_m^*)}{(\varepsilon_p^* + 2\varepsilon_m^*)} \quad (3)$$

where  $\varepsilon_p^*$  and  $\varepsilon_m^*$  are the complex permittivity of the particle and medium respectively, and  $\varepsilon^* = \varepsilon - j\sigma/\omega$  where  $\varepsilon$  is the permittivity,  $j$  is  $\sqrt{-1}$ ,  $\sigma$  is the conductivity, and  $\omega$  is the angular frequency of the applied electric field.

A useful solution for  $\text{Re}[K(\omega)]$  which illustrates its dependency on the applied frequency is the derivation found by Benguigui and Lin [16].

$$\text{Re}[K(\omega)] = \frac{\varepsilon_p - \varepsilon_m}{\varepsilon_p + 2\varepsilon_m} + \frac{3(\varepsilon_m \sigma_p - \varepsilon_p \sigma_m)}{\tau_{MW} (\sigma_p - 2\sigma_m)^2 (1 + \omega^2 \tau_{MW}^2)} \quad (4)$$

where  $\tau_{MW}$  is the Maxwell-Wagner charge relaxation time given by  $\tau_{MW} = (\varepsilon_p + 2\varepsilon_m)/(\sigma_p + 2\sigma_m)$ . This factor accounts for the rate at which free charges distribute themselves along the surface of a sphere.

Equation 2 is the first order contribution to the dielectrophoretic force. The first order dielectrophoretic force accounts for dipole contributions produced in a moderate non-uniform electric field [15,17-20]. The real component of the Clausius-Mossotti factor accounts for the polarization of a particle relative to the polarization of the suspending medium [15,17,18], and it is this induced dipole that will dictate the direction a polarized particle will move in a non-uniform field. Since the movement of a dielectric particle is mitigated by the complex permittivities of the particle and suspending medium, as indicated by the Clausius-Mossotti factor, it is possible to discriminate between particles based on their polarizability, and (unlike electrophoresis) separation of neutral particles is therefore attainable. The Maxwell-Wagner charge relaxation time describes how charges will accumulate on the surface of a suspended particle based on the conductivity and permittivity of the particle and suspending medium. These charges are within the suspended particle and are located at the interface with the suspending medium.

Equations for higher orders of the dielectrophoretic force have been derived and like the first order dielectrophoretic force are frequency dependent [16,19-21]. For this discussion, we assume that the contributions of higher order dielectrophoretic forces are negligible which is often the case. One instance where higher order dielectrophoretic forces do come into effect, however, is when trapping particles

using a quadrupole electrode geometry [17], where the net dipole moment experienced by a particle is near zero.

### 1.3 Benefits of Miniaturization

Through their experimentation utilizing a ring electrode placed above a planar electrode, Bahaj and Bailey conducted levitating DEP on divinyl benzene particles with diameters of 50  $\mu\text{m}$  [3]. Though they did not conduct separations using dielectrophoretic forces, they showed that by reduction of electrode size they could harness DEP with electrical fields produced using only a few volts.

Miniaturization of DEP devices has been beneficial in improving the effectiveness of DEP. The use of microscale electrodes allows for production of devices with more pronounced non-uniform fields [18]. Also, safety is improved because high fields can be produced by use of low voltage power supplies instead of high voltage power supplies as previously used. The sheer size of early DEP devices having machined electrodes produced appreciable heating, particularly in aqueous solutions, due to the high voltages needed to accomplish dielectrophoresis [3]. Heating effects are markedly reduced when smaller systems are employed, which reduces the effects of thermal motion and thus allows DEP to be applied to particles smaller than 1  $\mu\text{m}$  which was not possible prior to the use of miniaturized devices. Also, the reduction in heating attenuates the possibility of denaturation of

thermolabile analytes. This is important particularly in the analysis of biological macromolecules.

#### 1.4 Particle movement in non-uniform electric fields

When a polarizable particle is subjected to an electrical field, a dipole moment will be induced in the particle regardless of whether it is charged or neutral [14,15]. If the electric field is uniform, a particle with an induced dipole moment will not move because the force experienced on the opposite sides of the particle will be identical. Charged particles too will experience a dipole and will move to their respective pole if the frequency of the applied potential is at or near zero, but will otherwise oscillate along with the applied frequency [22]. If the electric field is made non-uniform, the forces experienced on either side of the particle will be unequal. As a result, the particle will move in accordance with its polarizability relative to the polarizability of the medium and the angular frequency of the applied potential in accordance with equation (2) [14,15]. If the polarizability of the particle is greater than the polarizability of the medium, the particle will move towards a region of higher potential, and thereby experience a positive dielectrophoretic moment. In the case of a particle being less polarizable than the medium, the particle will migrate towards the lower potential region and experience a negative dielectrophoretic moment due to being displaced by the suspending medium towards the low field region [14]. A visual representation of

particles experiencing positive and negative dielectrophoretic moments is shown in figure 1.1.

Determination of the type of dielectrophoretic moment a particle will experience can be accomplished by calculating  $\text{Re}[K(\omega)]$  using equation (4). As previously stated, the real portion of the Clausius-Mossotti factor will dictate whether the dielectrophoretic force on a particle will be positive or negative. The Clausius-Mossotti factor is frequency dependent because it is determined from the frequency dependent complex permittivities of the particle and the medium [15,16,18]. As such, by constructing a plot of the real component of the Clausius-Mossotti factor as a function of frequency it is possible to estimate the frequency ranges in which a particle will exhibit positive DEP and negative DEP. Figure 1.2 is a plot of the real component of the Clausius-Mossotti of  $\text{Fe}_3\text{O}_4$  in water.

When an appropriate frequency is applied across the electrodes in a dielectrophoretic device, a dipole moment is induced in particles in suspension [14,15]. If the frequency of the applied potential closely correlates to the relaxation time of the particle, defined as the time required for the induced dipole to react to the applied field, then the direction of the dipole moment experienced by the particle will reverse along with the oscillation of the ac voltage. When the frequency of the ac voltage does not correspond to the relaxation time of the particle, an induced dipole can still occur but the induced dipole will not be as

great because the charge density within the particle will not have enough time to properly accumulate [14]. The influence of directionality of the applied field on the movement of a particle is not important because if the applied field is reversed then the direction of the induced dipole moment on a particle will too be reversed [14,23]. A schematic of this phenomenon is shown in figure 1.3.

It is possible to dictate the type of DEP experienced by a particle through proper selection of the frequency. Some particles will exhibit positive dielectrophoresis through a certain frequency range and negative dielectrophoresis in another frequency range. As shown in figure 1.2,  $\text{Fe}_3\text{O}_4$  particles would be expected to experience positive DEP in the frequency domain up to  $1 \times 10^{13}$  Hz and would be under negative DEP beyond  $1 \times 10^{13}$  Hz. The frequency at which the direction of DEP experienced by a particle changes is known as the crossover frequency. At the crossover frequency the particle will experience no net force [18].

Careful selection of the suspending medium (and more specifically its conductivity) can be used to increase the selectivity in discriminating between different analytes as stated in the Clausius-Mossotti factor [17,18,22,24-31]. The conductivity of the medium can be altered by addition of salts. Ions present in an aqueous solution create a double layer surrounding a particle and as mentioned by Pohl [14] will have electrokinetic interactions with the particle. The thickness of

the double layer can be estimated using the Debye-Hückel screening length equation [17,32]:

$$d = \left( \frac{\epsilon_m k T}{8 \pi n^o z^2 e_o^2} \right)^{\frac{1}{2}} \quad (5)$$

where  $\epsilon_m$  is the permittivity of the medium,  $k$  is the Boltzmann constant,  $T$  is the absolute temperature,  $n^o$  is the ion concentration in the bulk of the suspending medium,  $z$  is the valency of the suspending medium, and  $e_o$  is the charge of an electron. As shown in equation 5, the thickness of the double layer is inversely proportional to the concentration of ions present in the suspending medium and is not dependent on the surface area or volume of the suspended particle. The close proximity of the double layer to the surface of a particle will contribute to a particles response to an oscillating electric field through electrokinetic effects [14,17]. Therefore, it stands to reason that double layer effects on the movement of a dielectric particle will be more pronounced for small particles in a low ionic strength medium.

As just stated, the DEP effects experienced by a particle will be affected by the presence of a double layer, but these added effects are especially noticed when analyzing submicron particles and macromolecules. This relation can be better understood by close examination of equation 2. From equation 2, the DEP force



experienced by a particle is related to the cube of the particle radius. When dealing with particles where the size is submicron, the contribution of the double layer thickness will have a more profound impact on the DEP force exerted on a particle than for particles of micron and larger sizes having similar dielectric properties because of the relative contribution of the ionic double layer [26,27]. The effects of conductivity of the medium have been studied by several researchers [24-31]. Green and Morgan observed these behaviors for the study of latex spheres [24]. Huang and Pethig showed that by altering the conductivity of the solution and maintaining other conditions constant it was possible to cause a change in the DEP behavior of yeast cells [25].

## 1.5 Dielectrophoresis geometries

### 1.5.1 Parabolic electrodes

Typical devices utilizing parabolic electrodes employ four electrodes to produce a quadrupole geometry where the electrodes are offset by 90 degrees as shown in figure 1.4a. Voltage application is accomplished by wiring electrodes diagonally opposite one another identically [5,34-37]. Once voltage is applied after sample introduction, particles will begin to collect in regions of high or low potential depending on the dielectrophoretic moment experienced. In parabolic geometries, the potential gradient expands radially from the center of the device towards the electrode surface [24, 33, 34, 38-41].

### 1.5.2 Castellated electrodes

As shown in figure 4b, castellated electrodes can be configured in two manners: directly opposite or offset. With either case, the device is wired so that every other electrode has the same voltage input [5,40,42,43]. In the case of castellated electrodes that are directly opposite each other, positive and negative dielectrophoresis regions will be found as follows [40]: Particles focused in the positive dielectrophoresis region will be found between the faces of the electrodes located across from each other. Negative dielectrophoresis will congregate particles in the rectangular areas between the castellations in the electrode. Positive and negative dielectrophoresis regions for offset castellated electrodes will be found as follows [40,44]: positive dielectrophoretic particle collection again occurs in the region between castellated electrodes located across from each other, the difference being that the positive region is now found between the corners of the electrode faces. The low potential region for offset castellated electrodes is identical to that for parallel castellated electrodes (electrodes aligned directly across from each other) and therefore the negative dielectrophoresis region is located in the rectangular “wells” between electrodes.

### 1.5.3 Electrode Arrays

Figure 1.4c shows a common electrode array geometry. In devices containing electrode arrays, voltage applications to the electrodes vary [45,46]. One approach is to use a checker-board pattern where electrodes having voltage applied and

those that are grounded are alternated. Another possibility is to have the voltage vary in concentric squares and to have the voltage vary between ground and applied voltage with each concentric square. With electrode array geometries, the high potential region is located on the electrode surface and therefore particles experiencing a positive dielectrophoretic moment will gather on the electrode surface. Particles with a negative dielectrophoretic moment aggregate in the low potential region located in the areas surrounded by four electrodes that form a square [45,46].

#### 1.5.4 Electrodeless/Insulator Based Devices

Figure 1.4d is a representation of a dielectrophoretic device utilizing an array of insulating posts, in this case circular insulators. Unlike the previously mentioned methods of achieving focusing/trapping mode dielectrophoretic separations, devices constructed with an array of insulating posts do produce an inhomogeneous electrical field with electrodes. The non-uniform electrical field is produced by compressing the electrical field, applied by the electrodes adjacent to the insulating posts, through the gaps between the insulating posts [7,47,48]. From the preceding description it should be evident that the high potential regions will be located between the insulators where the electrical field is being compressed, as highlighted in the figure. The low potential regions are found along the axis where the applied voltage is being compressed [7,47-49].

## 1.6 Applications

Miniaturized DEP devices have successfully been used for analysis of several types of samples. These include particles [24,33,35,36,38,41,50-57], cells [6,7,25,36,37,40,42-46,48,49,57-62], and macromolecules/subcellular biological analytes [5,34,36,39,47,63-65]. Prior to listing examples, it is important to mention some potential pitfalls that may be encountered when conducting DEP separations on the microchip platform.

The first of these pitfalls deals with fluid motion that can be mistaken for DEP. Fluid motion around electrodes can be caused by electroosmotic forces [17,33,50,66-68]. In an electrolytic solution typically below 500 kHz [50], the interaction between the double layer located on an electrode surface and the electrical field will create a phenomenon known as electrode polarization. Electrode polarization occurs when a portion of the potential is lost across the double layer as the field travels from the surface of the electrode into the bulk solution. This potential decrease thereby induces a force on the ions in the double layer and creates fluid motion. Heating is also responsible for fluid movement through electrothermal effects [33,50,69]. Electrothermal effects create a temperature gradient and are usually experienced when applying a high frequency electric field across a high conductivity medium. This temperature gradient will also create a density gradient. This established density gradient will create convection as denser fluids begin to displace fluids with lower densities. Both

electroosmotic forces and electrothermal effects have the potential to create fluid motion that may overcome the dielectrophoretic forces being exerted on an analyte.

Care must be taken when selecting the conductivity of a medium when studying biological samples. First, if the conductivity of the medium is too high, the temperature increase may be sufficient to degrade biological analytes. Also, when dealing with cells care must be taken to make sure an iso-osmotic environment is established as to not affect the cell wall/membrane [18].

An additional caveat is the production of free radicals through electrochemical processes [17,70-72]. Free radicals have been shown to produce changes in pH in dielectrophoretic devices [71], and these pH changes may disrupt the function of biological analytes.  $\text{H}_2\text{O}_2$  has been formed in sugar containing solutions, and the free radicals are created from the  $\text{H}_2\text{O}_2$  decomposition. Catalase has also been shown to increase the rate of decomposition of  $\text{H}_2\text{O}_2$  and in most cases eliminate  $\text{H}_2\text{O}_2$  from the system [72]. Free radicals have too been shown to react directly with analytes and degrade biological samples [73,74].

The first two examples presented are the works conducted by Green and Morgan [52], and Watarai et al. [38] and their investigations on the effects on the motion of submicron latex spheres in a non-uniform electric field. Though these studies do

not directly demonstrate separations, we feel they must be mentioned because they are to our knowledge the first examples of the use of DEP forces on submicron particles. Morgan and Green used castellated electrodes with castellations spaced at 6  $\mu\text{m}$  and gaps between electrodes measuring 4  $\mu\text{m}$  to study 93  $\mu\text{m}$  diameter carboxylate modified latex spheres. The applied voltage used was 1 V peak-peak which produced a field strength of  $2.5 \times 10^8 \text{ V mm}^{-1}$ . The suspending medium was pH 7.1 phosphate buffer with a concentration of 1 mM and conductivity of  $18 \mu\text{S cm}^{-1}$ . Morgan and Green found that for the frequency range of 1 kHz – 1 MHz the particles exhibited positive DEP and migrated to the electrode tips. The particles experienced negative DEP for frequencies greater than 20 MHz and collected in the wells in the electrodes. Watarai, Sakamoto, and Tsukahara too used microparticles composed of carboxylated polystyrene latex to study the mobility of these particles due to the dielectrophoretic force. They used a parabolic electrode device with a quadrupole geometry with a central region of 65  $\mu\text{m}$ . Aqueous suspensions were made containing  $(0-5.0) \times 10^{-3} \text{ M KCl}$  and  $2.6 \times 10^{-7} \text{ M Rhodamine B}$  to fluorescently label the spheres. The pH of the solutions were in the range of 6.08-6.80, and the conductivity of the aqueous solutions were in the range of 3.11 to 701  $\mu\text{S cm}^{-1}$  and were adjusted by addition of KCl.

Separation of carboxylate-modified latex spheres on both non-offset and offset castellated electrodes is shown in figure 1.5 [5]. Electrode distances used were 10  $\mu\text{m}$ . Fluorescently labeled latex spheres of 216 and 557 nm diameters were

suspended in an aqueous KCl solution with a conductivity of  $2.5 \mu\text{S cm}^{-1}$ . Separation was accomplished using a voltage of 10 V peak-peak at a frequency of 2 MHz. Upon voltage application, the 216 nm particles collected in the high potential region located between electrode faces and electrode tips for non-offset and offset electrodes respectively. The 557 nm diameter particles collected in the interelectrode gaps under negative DEP. Figure 1.5 is a photograph of the above mentioned separation of 216 nm and 557 nm carboxylate-modified latex spheres using a castellated electrode DEP device.

Huang and Pethig [25] used parabolic electrodes to study the effects of varying the conductivity of the aqueous suspending medium on the type of dielectrophoretic force on yeast cells. The electrodes were produced from gold and had a thickness of 70 nm. The 70 nm gold electrodes were laid on a 5 nm thick chromium seed layer. The final spacing of the electrodes was  $64 \mu\text{m}$  radial opening to the electrode tips. Suspensions were prepared under two different sets of conditions for the suspending medium, the first being a suspending medium composed of 280 mM mannitol with a conductivity of  $3.61 \mu\text{S cm}^{-1}$ , and the second prepared with 280 mM mannitol and 1.4 mM KCl and having a conductivity of  $170 \mu\text{S cm}^{-1}$ . The applied voltage was held constant at 10 V peak-peak and 10 kHz. The investigators found that yeast cells suspended in 280 mM mannitol experienced positive DEP, and yeast cells suspended in 280 mM mannitol and 1.4 mM KCl were focused in the central region between the electrodes.

Dielectrophoresis utilizing a castellated geometry has been shown to be a suitable extraction method for removing cancer cells from blood [58]. Non-offset castellated gold electrodes with 80  $\mu\text{m}$  electrode spacing were used. A mixture of MDA 231 breast cancer cells and bovine serum was suspended in an aqueous solution consisting of 8.5% w/v sucrose and 0.3% w/v dextrose. Hemisodium EDTA was used to adjust the conductivity of the aqueous solution to 100  $\mu\text{S cm}^{-1}$ . Upon sample introduction a voltage of 5 V peak-peak at 200 kHz was applied to trap all cells under positive DEP. A flow of the suspending medium was then started at 5  $\mu\text{L min}^{-1}$ . The frequency was lowered to 80 kHz to reduce the number of blood cells trapped on the electrodes. To further purify the breast cancer cells the frequency was swept between 80 and 20 kHz at a rate of two times per second for 20 min to free any blood cells that have been trapped on the electrodes by the cancer cells. At the end of the 20 minute sweeping cycle cell fractions were found to be >95% pure after the cell fractions were examined using Liu's modified Wright staining.

In 1998, another example of separation of cancer cells from blood was demonstrated using DEP on a 5 x 5 array of electrodes [45]. The array consisted of circular electrodes composed of a 100 nm Ti-W seed layer covered with a 300 nm thick platinum layer. The electrode diameters were 80  $\mu\text{m}$  and were spaced 200  $\mu\text{m}$  on center. The sample analyzed consisted of epithelial carcinoma cell line



(HeLa) derived from a human cervical tumor and EDTA-anticoagulated human blood cells. The separation buffer was composed of 225 mM Tris, 225 mM boric acid, and 5 mM EDTA, pH 8.2, and 250 mM sucrose. The conductivity of the separation buffer was measured to be  $10 \mu\text{S cm}^{-1}$ . The separation voltage was 6 V peak-peak and the frequency was determined empirically. It was discovered that at 30 kHz the HeLa cells experienced positive DEP and separated from the peripheral human blood cells which were under a negative dielectrophoretic moment.

Another dielectrophoretic separation of different cells lines was conducted using an array of circular electrodes [6]. 25 circular platinum electrodes with diameters of 80  $\mu\text{m}$  spaced at 200  $\mu\text{m}$  center to center were arranged in a 5x5 geometry. The electrodes were manufactured as in the previous example and were composed of a 100 nm Ti-W seed layer covered with a 300 nm thick platinum layer. Mixtures of human glioma cell line (HTB) cells with human neuroblastoma cell line SH-SY5Y (SH-SY5Y), monocytic cells (U937) with human peripheral blood mononuclear cells (PBMC), and tax-transformed cells (Ind-2) with PBMC were studied. DEP buffer was 250 mM sucrose/RPMI 1640, and the final conductivity of the DEP buffer was  $1200 \mu\text{S cm}^{-1}$ . Voltage was applied in a checkerboard pattern at 7 V peak-peak and the field frequency varied depending on the cell mixture being analyzed. Separations occurred in 3-5 minutes after the voltage was applied. Then cells experiencing negative DEP were flushed from the device at  $40 \mu\text{L min}^{-1}$  for

10 min. The voltage was then turned off and the remainder of cells were evacuated with DEP buffer at  $400 \mu\text{L min}^{-1}$  for 20 sec. The frequency of the applied fields were 400, 500, and 600 kHz for HTB and SH-SY5Y, U937 and PBMC, and Ind-2 and PBMC mixtures respectively. Cell lines experiencing positive DEP were HTB, U937, and Ind-2 and were collected on the electrode surfaces, as shown in figure 1.6a. SH-SY5Y and PBMC were collected under negative DEP, also shown in figure 1.6a. Photographs of the separation of HTB and SH-SY5Y, U937 and PBMC, and Ind-2 and PBMC mixtures are shown in figure 1.6a, and the separation procedure for the U937 and PBMC mixture is illustrated in figure 1.6b.

Separation of tobacco mosaic virus (TMV) from herpes simplex virus Type 1 (HSV) was demonstrated by Morgan, Hughes, and Green on a polynomial electrode device [5]. Electrode spacing was  $2 \mu\text{m}$  for interelectrode and  $6 \mu\text{m}$  in cross center distance. The suspending medium was DI water adjusted to a conductivity of  $100 \mu\text{S cm}^{-1}$  using KCl. An applied voltage of 5 V peak-peak at a frequency of 6 MHz was used to separate TMV from HSV. Under these conditions TMV experienced positive DEP and collected in the high field regions, and HSV with a negative dielectrophoretic moment aggregated in the low potential region. A drawing and photograph of this separation are shown in figure 1.7a and figure 1.7b respectively.

An insulator based DEP system was used to separate and concentrate live and dead *E. coli*. [7]. The insulators were produced in glass and had a height of 10  $\mu\text{m}$ , diameter of 200  $\mu\text{m}$ , and were spaced 250  $\mu\text{m}$  on centers. The cells were suspended in DI water with a conductivity of 22.5  $\mu\text{S cm}^{-1}$ . Direct current voltage at different voltage levels was used and it was found that at 16 V/mm only live *E. coli*. cells were trapped. At a potential gradient of 40 V  $\text{mm}^{-1}$  and 60 V  $\text{mm}^{-1}$  it was noticed that both live and dead *E. coli*. cells were both trapped but formed distinct bands. The separation of live and dead *E. coli* at 16 V  $\text{mm}^{-1}$ , 40 V  $\text{mm}^{-1}$ , and 60 V  $\text{mm}^{-1}$  are shown in figure 1.8a, 1.8b, and 1.8c respectively.

Another example from the researchers at Sandia National Laboratories using insulator based DEP is their work on separating live bacteria from water using dc voltage [48]. The separation device was again constructed of glass with circular insulators with heights of 10  $\mu\text{m}$ , 150  $\mu\text{m}$  diameters, and distanced 200  $\mu\text{m}$  on centers. The suspending medium was DI water adjusted to pH 8 with 0.01 N NaOH and a conductivity of either 22  $\mu\text{S cm}^{-1}$  with 0.01 M KCl. Results for a total of six cell mixtures were presented. These cell mixtures were *E. coli*. (BL21) and *Bacillus subtilis* (ATCC #6633), *E. coli*. (BL21) and *Bacillus cereus* (ATCC #14579), *E. coli*. (BL21) and *Bacillus megaterium* (ATCC #10778), *Bacillus cereus* (ATCC #14579) and *Bacillus subtilis* (ATCC #6633), *Bacillus megaterium* (ATCC #10778) and *Bacillus subtilis* (ATCC #6633), and *Bacillus cereus* (ATCC #14579) and *Bacillus megaterium* (ATCC #10778). For the mixture containing *E.*

coli. and *B. subtilis*, it was found that with a field of  $50 \text{ V mm}^{-1}$  only *E. coli* was trapped in the high potential region, and at  $75 \text{ V mm}^{-1}$  both *E. coli* and *B. subtilis* were trapped in the higher field region. *E. coli.* and *Bacillus cereus* studied at field strengths of  $50 \text{ V mm}^{-1}$  and  $75 \text{ V mm}^{-1}$  and in both of these conditions were not separated. The mixture of *E. coli.* and *Bacillus megaterium* was studied at  $50 \text{ V mm}^{-1}$  and it was found that only *E. coli* was trapped and when the field strength was raised to  $90 \text{ V mm}^{-1}$  both *E. coli.* and *Bacillus megaterium* were trapped. At a field of  $25 \text{ V mm}^{-1}$  the fourth mixture, *Bacillus cereus* and *Bacillus subtilis*, only *B. subtilis* was trapped, and at a field of  $75 \text{ V mm}^{-1}$  both analytes were retained in the high field region. *Bacillus megaterium* and *Bacillus subtilis* could not be separated into separate bands at  $50$  and  $75 \text{ V mm}^{-1}$ . The final mixture mentioned was *Bacillus cereus* and *Bacillus megaterium*. It was found that at a field strength of  $30 \text{ V mm}^{-1}$  only *Bacillus megaterium* was trapped and at  $75 \text{ V mm}^{-1}$  both *Bacillus cereus* and *Bacillus megaterium* were trapped into separate bands.

As noted in the discussion above, extensive analysis of suspended particles has been conducted utilizing microfabricated DEP devices. Particle types studied include but are not limited to: latex spheres, cells, viruses, proteins, and DNA. A listing of the references from this article, categorized into particle type and device geometry used in the analysis is given in Table 1.1.

## 1.7 Conclusions

Recent advancements in manufacturing have allowed researchers to produce more effective dielectrophoresis devices than were possible in years past. Miniaturization has made it possible to conduct separations by applying potentials of only a few volts. Also, due to the reduction in Joule heating it is possible to separate particles in the submicron range, which extends the utility of DEP to biological samples. Current dielectrophoretic devices have been used successfully for separation of various types of analytes, but depending on the requirements of the analysis being conducted some geometries will be of greater use than others. Both conventional dielectrophoresis and unconventional modes of dielectrophoresis have been gaining popularity as separation tools in the laboratory and commercially.

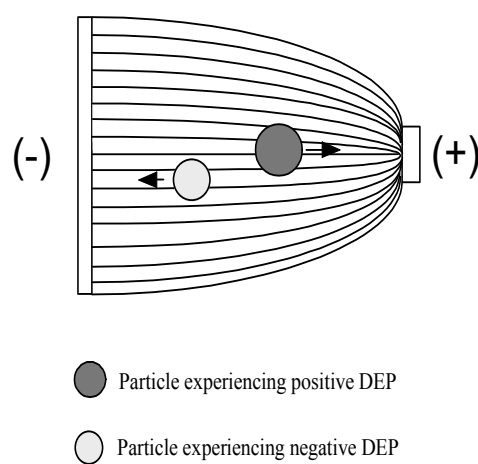


Figure 1.1: Particle motion in a non-uniform electrical field. A particle that is more polarizable than the suspending medium will experience positive DEP, while a particle less polarizable than the suspending medium will migrate towards the low potential region under negative DEP.

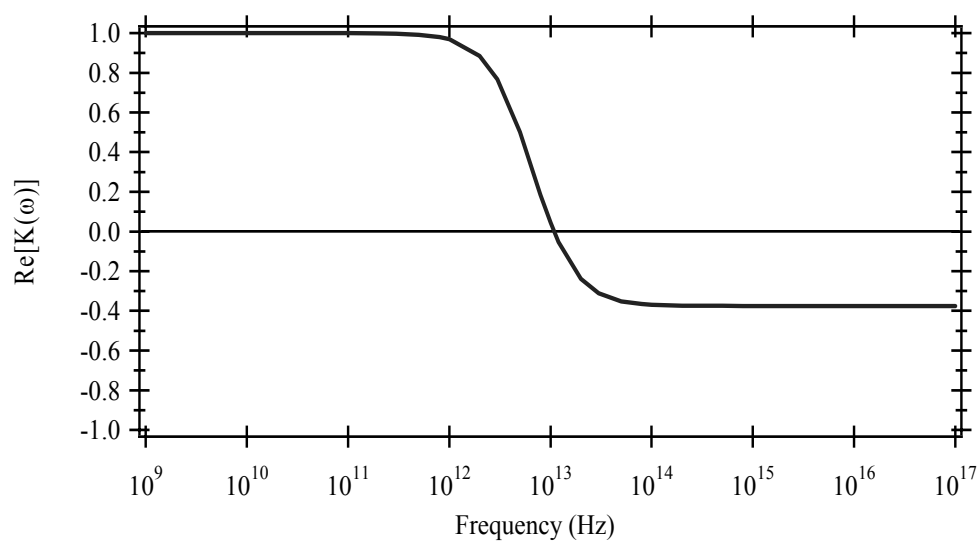


Figure 2: Plot of  $\text{Re}[K(\omega)]$  vs. frequency which illustrates the frequency dependence on the polarization of  $\text{Fe}_3\text{O}_4$  in  $5.62 \times 10^{-2} \mu\text{S cm}^{-1}$  water.

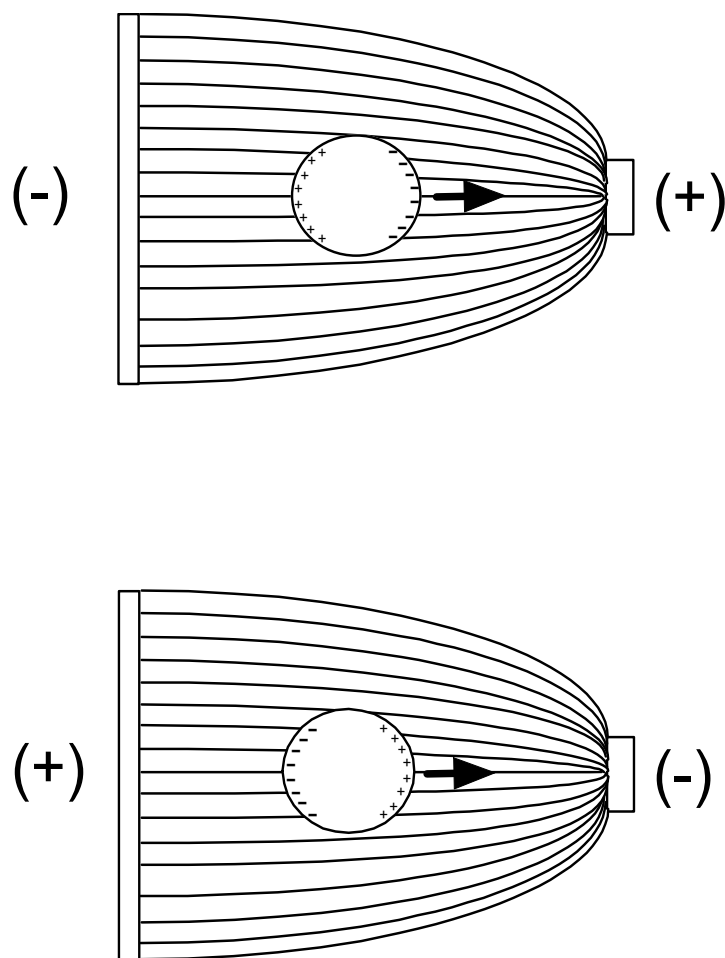


Figure 1.3: Visual depiction showing that particle movement in DEP is not dependent on the direction of the applied electrical field, as shown for a particle experiencing positive DEP. For an AC applied waveform, the figure depicts an applied potential at a given point in time.



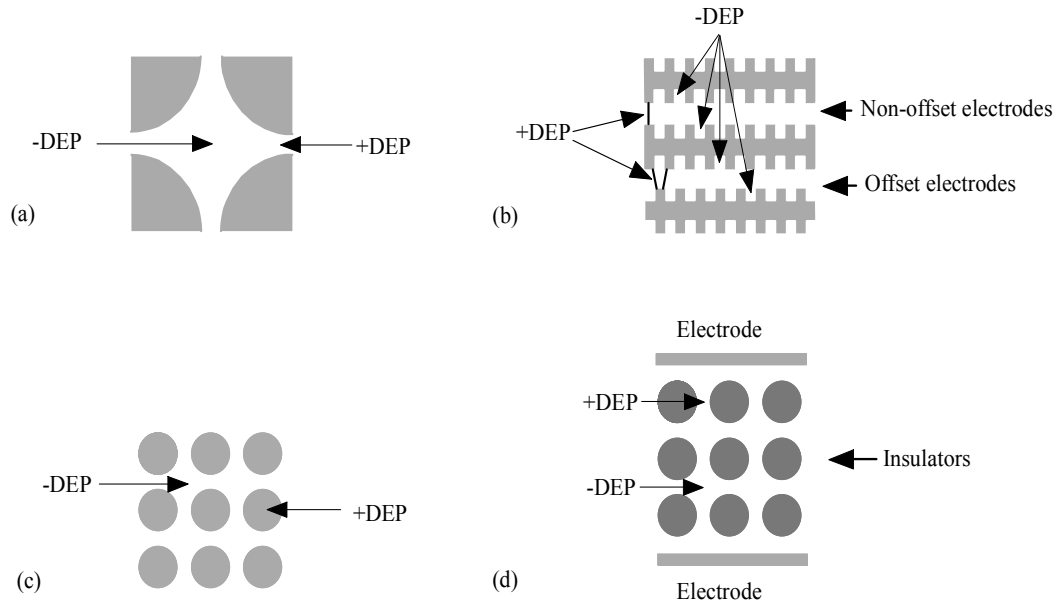


Figure 1.4: Typical device geometry and regions where positive dielectrophoresis (+DEP) and negative dielectrophoresis (-DEP) are located: (a) polynomial electrode geometry. (b) castellated electrode geometry showing both non-offset and offset castellated electrodes. (c) an array of circular electrodes. (d) electrodeless geometry where regions of high and low field strength are produced by the compression of the electric field between the array of insulators.

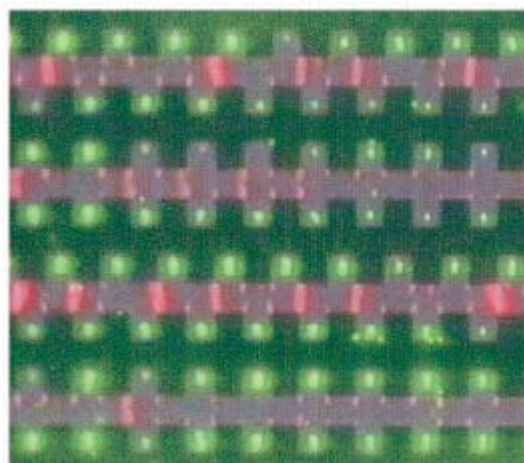


Figure 1.5. A video-image capture showing 216 nm and 557 nm diameter latex particles separating on a 10  $\mu\text{m}$  castellated electrode. The red 216 nm spheres experience positive DEP and form pearl chains between opposing electrode tips, while simultaneously the green 557 nm particles experience negative DEP and become trapped in triangular patterns in the interelectrode bays. The applied potential was 10 V peak to peak at a frequency of 2 MHz, and the medium conductivity was  $2.5 \mu\text{S cm}^{-1}$ . Reprinted with permission from [5].

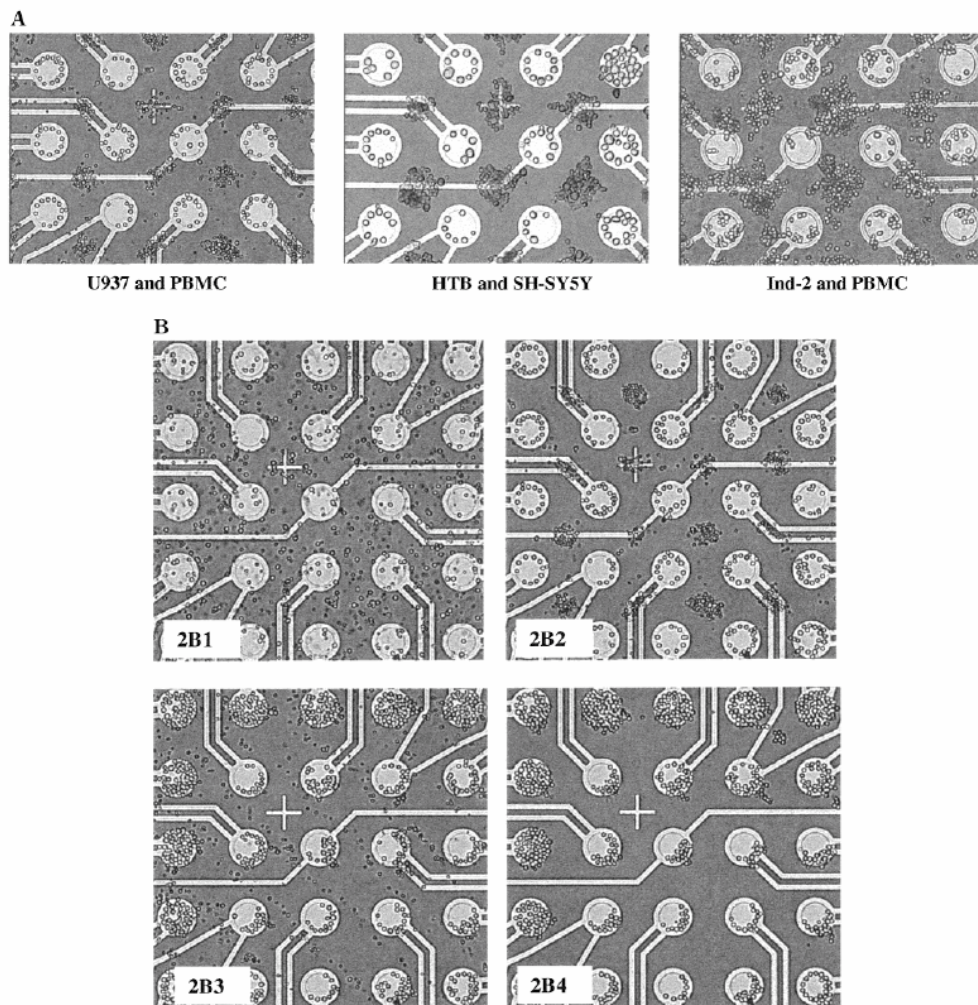


Figure 1.6. (A) DEP separation of U937 and PBMC, HTB and SH-SY5Y, and Ind-2 and PBMC in a medium with conductivity of  $1200 \mu\text{S cm}^{-1}$  at 500, 400, and 600 kHz, respectively. (B) The procedure of DEP separation for U937 and PBMC mixture. B1: Mixture is introduced to the array. B2: U937 cells are separated from PBMC on array by dielectrophoresis 5 min after an ac voltage of 500 kHz, 7 Vpp is applied. U937 cells are collected on the electrodes and PBMC are accumulated at the space between the electrodes. B3: Buffer is introduced from reservoir to the array by fluid flow of  $40 \mu\text{L min}^{-1}$  while the voltage is kept on. PBMC are carried away with the fluid stream. B4: PBMC are washed off from the array and U937 cells are retained on the electrodes after 10 min of washing. Reprinted with permission from [6].

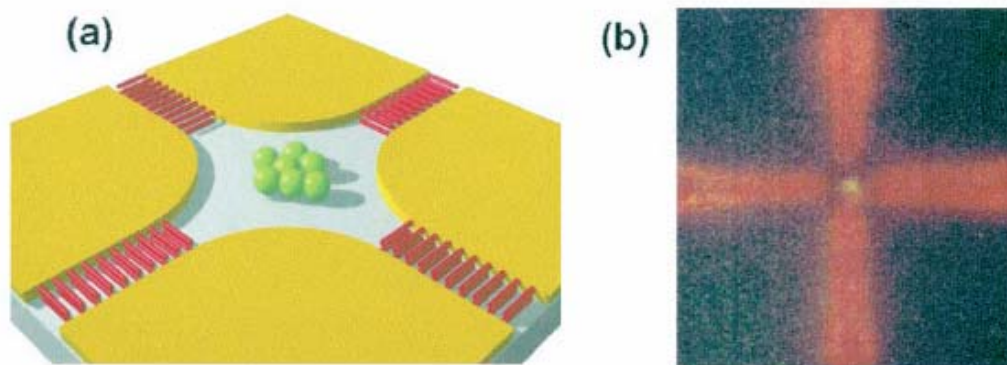


Figure 1.7. A diagram and photograph illustrating the separation of TMV and HSV in a parabolic electrode. The HSV is trapped under negative DEP forces at the field minimum in the center of the electrode array, while simultaneously TMV experiences positive DEP and collects at the high-field regions at the electrode edges, resulting in the physical separation of the two particle types. This is illustrated schematically in (a); the photograph appears in (b). The TMV (labeled with rhodamine B) can be seen as a red glow in the arms of the electrodes, and the green/yellow HSV (labeled with NBD-dihexadecylamine) is visible in the center of the electrode. Both viruses were suspended in an electrolyte of conductivity  $100 \mu\text{S cm}^{-1}$ , and the applied potential was 5 V peak to peak at a frequency of 6 MHz. Reprinted with permission from [5].

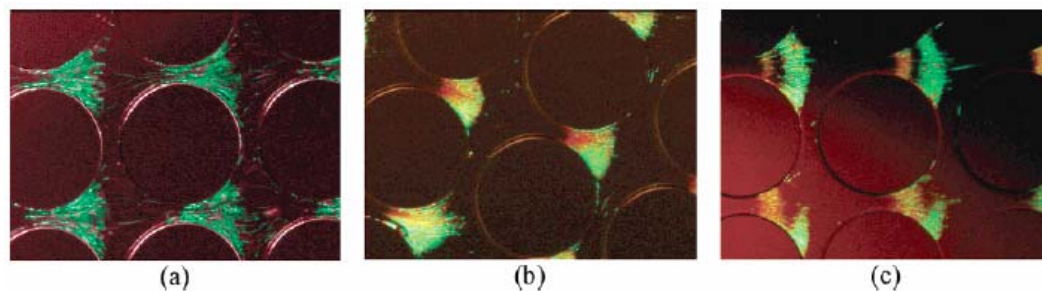


Figure 1.8. Simultaneous concentration and separation of live (green) and dead (red) *E. coli* by using iDEP. Conductivity of the DI water was  $22.5 \mu\text{S cm}^{-1}$ . Live *E. coli* cells were at a concentration of  $6 \times 10^7 \text{ cells mL}^{-1}$  and were labeled green (Syto 9, Molecular Probes, Eugene, OR). Dead cells were at a concentration of  $6 \times 10^7 \text{ cells mL}^{-1}$  and labeled red with propidium iodide (red dye, Molecular Probes, Eugene, OR). The circular posts in the arrays are  $10\text{-}\mu\text{m}$  deep,  $200\text{-}\mu\text{m}$  in diameter, on  $250\text{-}\mu\text{m}$  centers, at  $0^\circ$  offset in (a) and (c), and  $20^\circ$  offset in (b). The electric fields applied are (a)  $16 \text{ V mm}^{-1}$ , only live cells are trapped; (b)  $40 \text{ V mm}^{-1}$ , differential banding on live and dead cells is observed; and (c)  $60 \text{ V mm}^{-1}$ , differential trapping of live and dead cells is shown by two separate bands of different color. Live cells (green) are trapped at the wider regions between the circular posts (negative DEP), and dead cells (red) exhibit less negative DEP, since they are trapped at the narrower regions between the circular posts. Reprinted with permission from [7].

## Tables

**Table 1.1: References for each particle type analyzed and the device geometry utilized.**

Particle Type	Electrode Geometry			
	Parabolic	Castellated	Electrode Arrays	Electrodeless
Latex Spheres	24, 33, 35, 36, 38, 39, 41, 50, 54, 56	5, 33, 50-53, 57		55
Cells	25, 36, 37, 40, 61	40, 42-44, 57-60	6, 45, 46, 62	7, 48, 49
Macromolecules/subcellular analytes	5, 34, 36, 39	40, 65	63	47, 49, 64

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## Chapter 2:

### Dielectrophoretic Ratchet Devices

## 2.1 Introduction

Chapter 1 detailed the fact that semiconductor manufacturing technology has been successfully implemented in the manufacture of miniaturized dielectrophoretic devices. Benefits of device miniaturization include tighter electrode spacing, lower applied potentials to create high field gradients, decreased consumption of reagents and sample, reduced analysis time, possibility of portable instrumentation, and lower limits of detection.

Currently, miniaturized devices are being coupled to one another to produce micro total analysis systems ( $\mu$ TAS) [1-4]. In the case of dielectrophoresis, dielectrophoretic components have been successfully coupled with mixers, electrophoresis chips, electrorotation systems, and field deployable devices. The different miniaturized components used in a  $\mu$ TAS device can be selected for a specific sample and can be built to incorporate sample preconcentration, separation, and detection units on a single integrated device.  $\mu$ TAS devices can reduce the chance of human error, such as mislabeling and contamination, by decreasing the number of times a sample is handled, in the process generating the required measurements.

Several dielectrophoretic device geometries have been successfully fabricated and utilized for selective collection of a wide range of suspended analytes. Though utilization of semiconductor technology has been shown to be beneficial for miniaturizing devices, one device geometry that has seen limited use in the field of dielectrophoresis is ratchet devices. Presented in this chapter, is a brief overview of current ratchet dielectrophoretic devices, and also described is a ratchet type dielectrophoretic device constructed and used for the research efforts of this dissertation.

## 2.2 Ratchet Devices

The ratchet concept was originally described by Pierre Curie to describe how motion can be limited to one direction, and was later revisited by Richard Feynman who described how in theory an item could be lifted without any energy input [5,6]. Building upon the ideas presented by Curie and Feynman, Chauwin, Ajdari and Prost then applied the concept of ratchets to show that Brownian motion can be controlled to the extent that selective particle movement can be attained [7].

Later, Rousselet et al. showed that Brownian motion and dielectrophoretic phenomena could be used in combination to “selectively” move latex particles in a single direction, and as such, these devices were labeled thermal ratchets [8]. The device consisted of a photolithographically produced interdigitated electrode

geometry in which the electrode edges resembled “Christmas tree” shapes. A schematic representation of a “Christmas tree” portion of the device is shown in Figure 2.1. In this device, particles experiencing positive dielectrophoresis are collected at the electrode tips and particles under negative dielectrophoresis were found to collect, through empirical observations, in a crescent-shaped region near the widest distance between respective electrode sets, as shown in figure 2.2. Particle movement was attained by first collecting particles at the electrode tips under positive dielectrophoresis. Once the particles collected, the electrodes were de-energized and the particles were allowed to diffuse. During the diffusion process, a portion of the particles collected at the previously energized electrode tip diffused into the subsequent (2<sup>nd</sup>) ratchet portion. Then by reenergizing the electrodes, the particles in the 2<sup>nd</sup> ratchet portion were collected at the electrode tip located downstream of the first electrode tip. The process was repeated until the particles moved down the ratchet.

### 2.3 Stacked Ratchets Device

Building upon the thermal ratchet work conducted by Rousselet et al., Gorre-Talini et al. developed a stacked ratchet device and implemented it in the movement of 0.5  $\mu\text{m}$  latex spheres [9]. Unlike the thermal ratchet device, which depends on Brownian motion to move particles into successive ratchet sets, particle movement in the stacked ratchet geometry depends solely on dielectrophoretic manipulation.



Figure 2.3 is an illustration of a stacked ratchet device and is composed of two sets of “Christmas tree” shaped electrodes that are stacked on top of one another.

The device was operated as follows, and is illustrated in figure 2.4. After sample introduction, power was applied to the first set of electrodes, the gold electrodes in figure 2.4. Once particles had collected in the positive dielectrophoretic region as shown in figure 2.4b, power to the first electrode set was turned off. Power was then applied to the second electrode set and particles experiencing a positive dielectrophoretic moment moved to the tips of the second electrode pair, figure 2.4c. By altering the power application between the sets of electrodes, latex particles were transported towards the opposite end of the device. To date only movement of particles experiencing positive dielectrophoresis has been accomplished<sup>7</sup>, and no successful separation has been conducted utilizing this electrode geometry. No separation has been demonstrated because thermal motion caused by electrode heating countered the dielectrophoretic force exerted on a particle.

#### 2.4 Proposed Ratchet Type Device

From the preceding, it can be seen that dielectrophoretic ratchet devices offer the possibility to induce particle movement through a device by combining Brownian motion and dielectrophoresis (thermal ratchets) or solely dielectrophoretic forces

(stacked ratchets). Though ratchet geometries offer an interesting avenue for particle movement without the use of any external flow, no separations to date have been conducted. Also, no investigations have been made into device optimization through modification of the required electrodes. The following is a description of a proposed design of a ratchet type dielectrophoretic device.

One possibility in modifying the electrode features is shown in figure 2.5a. In this device, the two sets of Christmas tree shaped electrodes are replaced with electrode pairs in a V shaped geometry. These electrode features can be constructed using LIGA (**L**ithographie **G**alvanformung **A**bformung, German for: Lithography Electroplating Molding) technology to produce electroformed nickel electrodes.

To produce the fluidic component for this device a PDMS cover layer can be employed, and can be constructed to configure the device as either a flow through or static system. For the flow through system, the PDMS component will be constructed with a “Christmas tree” shaped channel which will serve two functions, as shown in figure 2.5b. The first purpose is to create the separation channel, and secondly to cover the top of the electrodes, thereby reducing the total electrode surface area that is in contact with solution, thus reducing thermal motion. A second benefit created by capping the electrode features with a PDMS cover layer is that the vertical sidewalls of the dielectrophoretic device are

composed of electrodes which will ensure that all particles located within the device are subjected to the induced dielectrophoretic force. For the static geometry, the PDMS cover layer contains the same features as the flow through geometry, and differs in only two respects. First, the static PDMS fluidic component will not contain the fluidic connections because a well will be placed around the ratchet type components. Secondly, since a sample aliquot will be pipetted directly into the reservoir, a microscope cover slip will be used to cover the well to reduce evaporation of the suspending medium.

This device can be operated in a similar fashion to a ratchet geometry device. Upon energizing the electrodes, particles experiencing +DEP will collect at the electrode tips, and particles experiencing -DEP will also collect in a crescent-shaped line along the widest regions of the ratchet types, shown in chapters 4 and 5 of this dissertation. Figure 2.6 illustrates the aggregation regions for particles experiencing +DEP and -DEP. When attempting to operate the device as a stacked ratchets device, the sets of electrodes can be divided into two groups as shown in figures 2.5a and 2.5c. Each of the two groups of electrodes will be connected to the same function generator, and through the use of an on/off switch the electrodes can be divided into the two separate groups.

Possible applications of the proposed dielectrophoretic device are as follows. The first possible application of this device is for sorting of biological samples such as

benign and malignant cells, live and dead viruses, and isolation of blood serum components. A second application is as a sample cleanup component of a  $\mu$ TAS to collect and concentrate analytes prior to subsequent analysis. For this current work, the process taken in fabricating this device (chapters 3 and 4) and the initial evaluation of this device by collection of particles based on the dielectric properties of the test analytes (chapter 4 and 5) are presented.

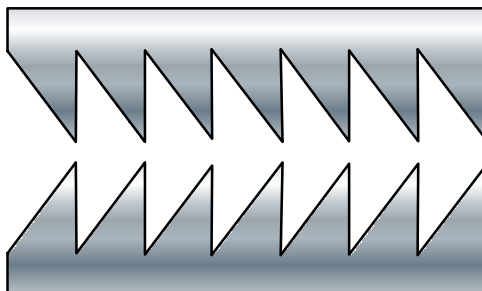
**Figures**

Figure 2.1. Schematic of a thermal ratchet device.

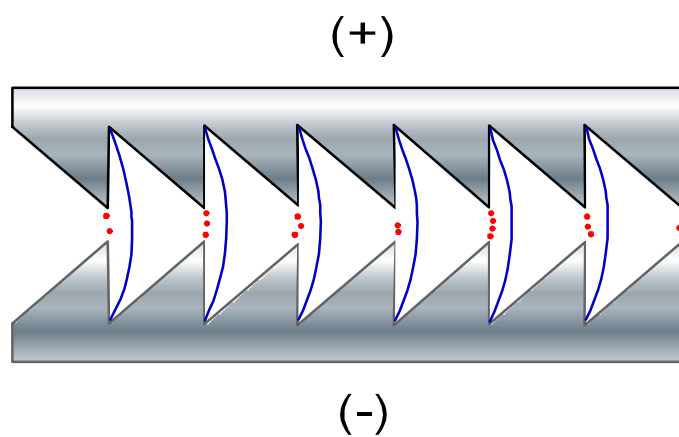


Figure 2.2. Illustration showing regions of particle collection during application of an electric field across the electrode set. Particles collected at the bottle necks under +DEP, and aggregate along the crescent-shaped line is region of particle aggregation under -DEP.

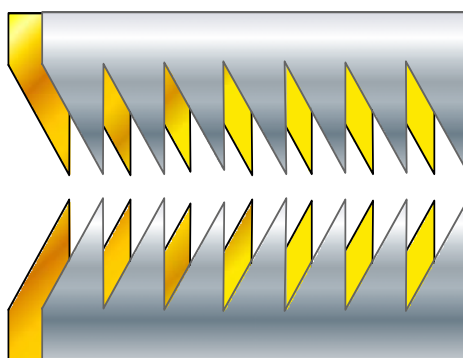


Figure 2.3. Schematic of a stacked ratchets device.

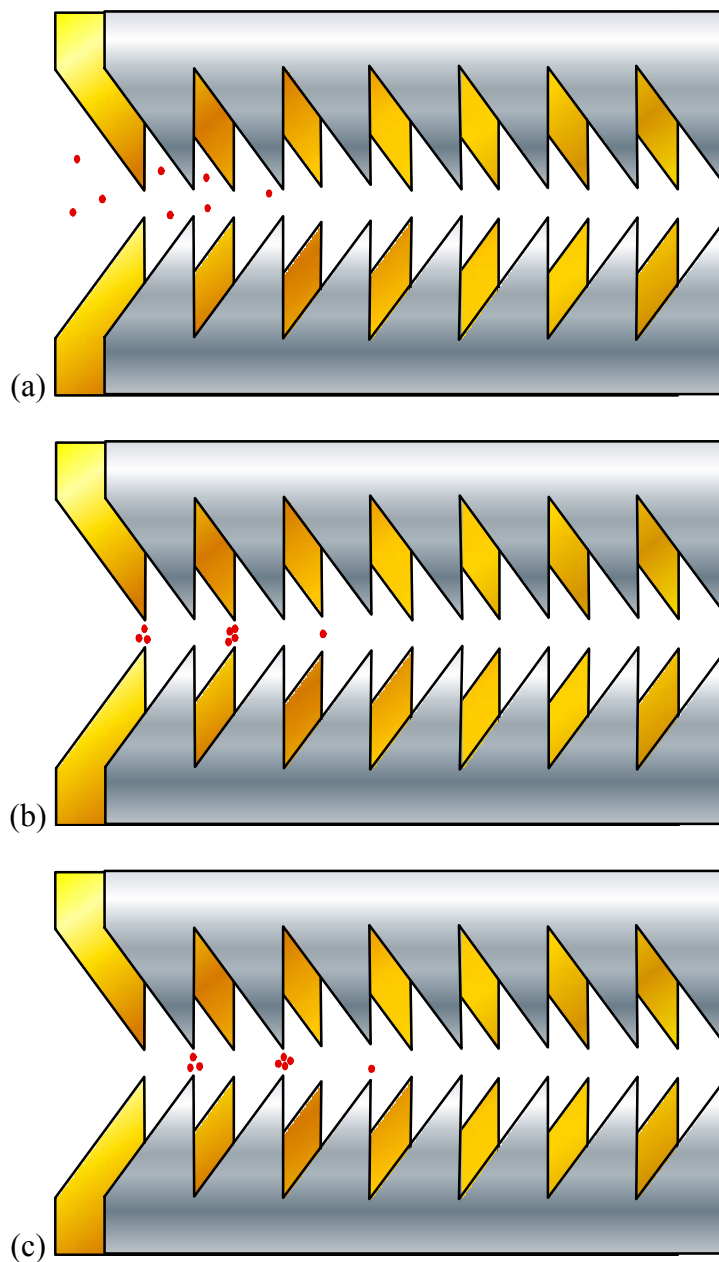


Figure 2.4. Illustration of a stacked ratchets device functioning over a single cycle of operation. (a) Sample is introduced into the device and is randomly distributed. (b) Lower electrode set is energized and particles collect under +DEP. (c) Upper electrode set is then energized and particles migrate under +DEP to the following ratchet tip.



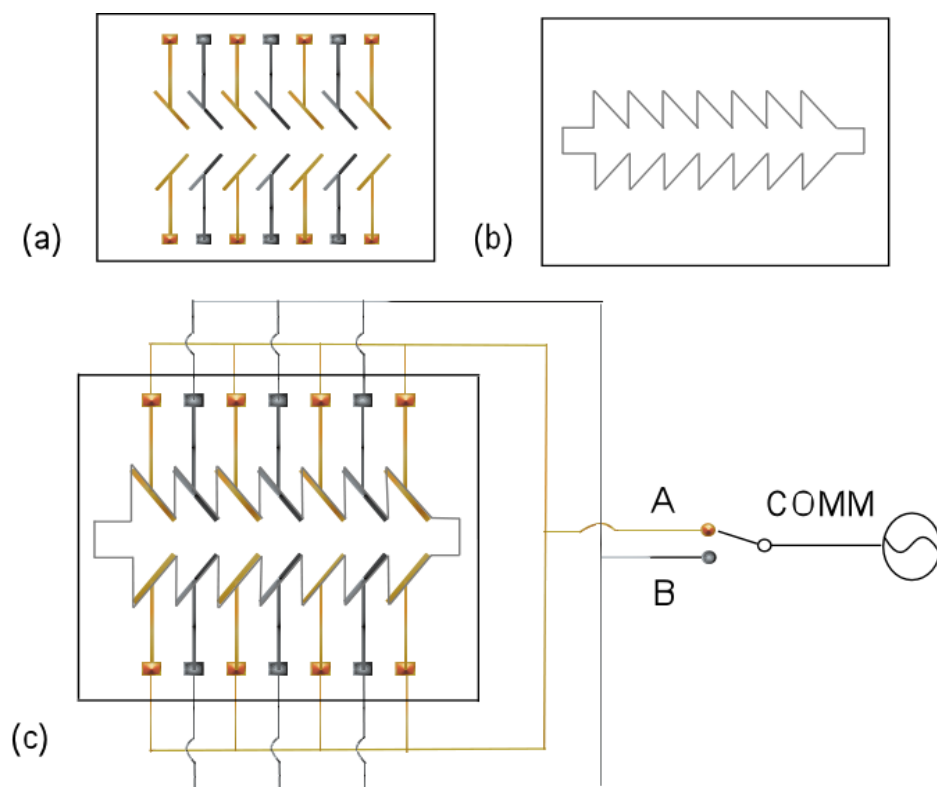


Figure 2.5. Schematic of the parts necessary for constructing a ratchet type device. (a) Glass slide containing the electroformed electrodes. (b) PDMS layer housing fluidic components. (c) Device assembled and each group of electrodes connected to their respective terminals of an on/on switch.

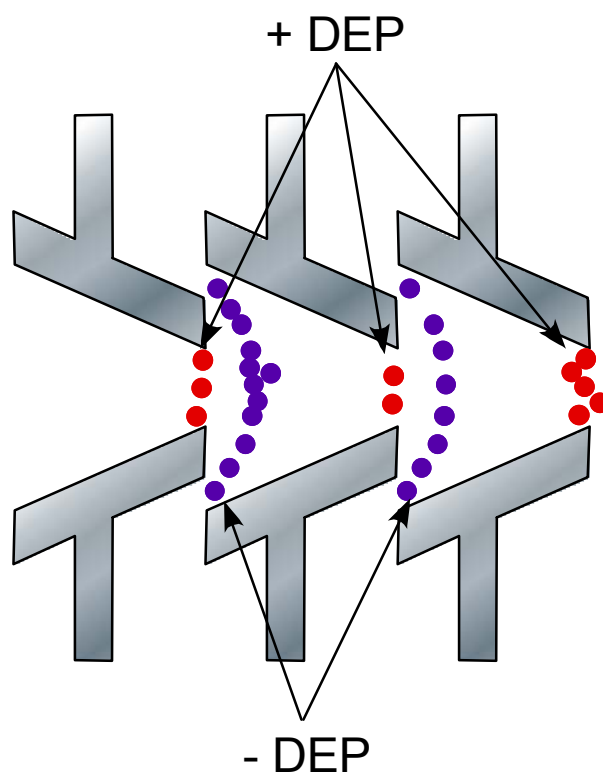


Figure 2.6. Illustration showing the aggregation zones for particles experiencing +DEP and -DEP in the ratchet type device.

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## **Chapter 3:**

### **Use of Dupont MX-5000 Series Dry Film Photoresist for Fabrication of Soft Lithography Masters**

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## Abstract

Presented is a method for production of negative image masters for soft lithography replica molding using Dupont MX-5000 series microlithographic dry film photoresist. Factors studied include substrate suitability, appropriate exposure source, exposure source effects on feature size, and maximum height to width aspect ratio attainable. Masters studied were constructed from a single resist layer. Master performance was tested through replica molding to produce poly(dimethylsiloxane) components containing a negative image of the lithographic features contained on the master.

## 3.1 Introduction

Soft lithographic production of poly(dimethylsiloxane) (PDMS) components has become common practice in the construction of microfluidic devices, and a key step in the patterning of PDMS is the manufacture of suitable masters. Currently, masters used for replica molding of PDMS are made by etching silicon wafers [1] or glass slides [2], patterning printed circuit boards [3], creating resist features from liquid photoresists such as SU-8 [4], solid object printing [5], embossing acrylic masters from machined aluminum wafers [6], and casting and curing of polyester resin in a PDMS mold patterned using an SU-8 master containing negative features of the final PDMS component [7]. Another interesting possibility for a producing master for use in replica molding of PDMS

microfluidic device components is the use of dry film resist, which has seen limited use in microfluidics.

Some of the first uses of dry film resist in microfluidics were for the construction of resist-glass hybrid devices [8-11]. Negative image masters patterned with dry film resist have been shown to be suitable molds for producing hot embossed microfluidic device components [12]. The possibility of masters manufactured from dry film resist for patterning of PDMS has been discussed [9], and to the best of our knowledge, there have been no examples of replica molded PDMS components using negative image dry film resist masters presented in the literature. Here, we describe a method by which Dupont MX-5000 series dry film photoresist is used for the construction of masters for replica molding.

The MX-5000 series resist is a negative tone resist and is processed similarly to other negative resists, while exhibiting differences that make it an intriguing alternative. First, this resist is a dry film that is laminated onto a substrate and not spun on like a liquid photoresist, thereby eliminating the need for a spin coater. Also, eliminated are resist edge beads and other non-uniformities common with spin coating liquid photoresist. The resist is supplied as sheets or on a roll, and in either case the resist is sandwiched between a polyethylene layer and polyester layer. The polyethylene layer is removed prior to lamination, and then the resist is laminated onto the substrate by rolling and pressing to the substrate surface. The

polyester layer is retained throughout the exposure procedure in order to keep the photomask clear of the resist.

The MX5000 series exhibits maximum absorption at 365 nm, and exposure is accomplished through the use of a UV exposure system containing the 365 nm mercury i-line. Due to this quality, the resist can be exposed using a conventional UV lithographic exposure system, while offering the possibility of using other less costly systems. Upon exposure, the resist turns from green to dark blue thereby making the features visible, and this characteristic also allows for the assurance of an adequate exposure dosage. Per the Dupont technical data, care must be taken to minimize exposing the resist to light up to 450 nm due to undesired resist crosslinking that may lead to loss of feature resolution.

Another key feature of the resist is the developing and rinsing solutions used. With many photoresists in current use, development and rinsing is accomplished with organic solvents. For the MX-5000 series resist, development is conducted with a potassium carbonate solution, and the rinse employed is water with a 300 ppm calcium carbonate hardness. This feature is of particular interest because disposal of waste organic developer and rinsing solutions is eliminated. Development can be accomplished outside of a fume hood due to the lack of organic vapors.

## 3.2 Experimental

### 3.2.1 Reagents and Materials

Technical grade acetone and methanol were used for substrate cleaning (Northwest Solvents, Eugene, OR). Ultrapure water used for substrate cleaning and developer/rinsing solution preparation was obtained from a Barnstead E-Pure system (Dubuque, IA). Dupont D-4000 IC concentrated developer, used for preparation of the developing solution, was purchased from Microchem (Newton, MA). Technical grade calcium carbonate (Fischer Scientific, Pittsburgh, PA) was used for preparation of the rinsing solution. 2 x 3 inch borosilicate glass slides used as master substrates were purchased from VWR (West Chester, PA). 3 inch mechanical grade silicon wafers also used for master substrates were purchased from University Wafers (South Boston, MA). Dupont MX-5000 photoresist for patterning was purchased from Microchem (Newton, MA). Dry film resist thicknesses of 20  $\mu\text{m}$  (MX-5020) and 50  $\mu\text{m}$  (MX-5050) were used. Mylar photomasks were designed using AutoCAD 2007 (Autodesk, San Rafael, CA) and were photoplotted by CAD/Art Services, Inc. (Bandon, OR).

### 3.2.2 Equipment

For descumming the substrate surface, a home-built oxygen plasma was used. The plasma system consists of an MDC Vacuum Products Corporation (Hayward, CA) 6 inch x 10 inch 4-port stainless steel vacuum chamber, and an XEI Scientific (Redwood City, CA) Evactron Decontaminator RF Plasma Cleaner. A homemade



rolling pin for laminating substrates with photoresist was constructed by inserting a glass rod into a piece of rubber tubing. A 3M rubber squeegee for smoothing the resist was purchased from an automotive paint supply shop. Quarter inch aluminum plates used for promoting adhesion between the resist and substrate were purchased from McMaster-Carr (Los Angeles, CA). The four exposure sources tested were a homemade UV flood exposure system consisting of an Oriel 6186 mercury arc lamp (Oriel Light Sources and Spectroscopy Instrumentation, Stratford, CT) and a Durst 606 photo enlarger (purchased used, locally) to direct the UV light at a right angle towards the substrate, a Spectroline X-15A longwave 365 i-line light source (Spectronics Corporation, Westbury, NY), an MG Chemicals (Surrey, B.C., Canada) fluorescent light, and a Kepro BTX-200 Ultra Violet Exposure Frame (Fenton, MO) which was donated by our electronics shop. A Paschee VLS airbrush (Chicago, IL) was used for resist development. For imaging a Leica Wild Stereozoom microscope (Wetzlar, Germany) fitted with a Sony Power HAD DXC-970MD camera (Sony Corporation, New York, NY) and ImagePro Plus 6.0 software (MediaCybernetics, Silver Spring, MD) was utilized. A Zeiss Axiotron (Carl Zeiss MicroImaging, Inc., Thornwood, NY) equipped with a Sony Power HAD DXC-970MD camera (Sony Corporation, New York, NY) and ImagePro Plus 6.0 (MediaCybernetics, Silver Spring, MD) was used to image and measure resist feature widths. To measure resist thickness and to map surfaces, a Veeco Dektak 8 Stylus Profiler with a 12.5  $\mu\text{m}$  tip (Veeco Instruments Inc., Woodbury, NY) was employed.

### 3.2.3 Factors Studied

Several factors were studied in determining if Dupont MX-5000 microlithographic dry film photoresist is well suited for constructing masters intended for soft lithographic replica molding. These items include: exposure sources, selection of a substrate that provides sufficient adhesion with the resist, exposure source effects on feature size and maximum height to width aspect ratio attainable, master production, and performance of each master type.

#### 3.2.3.1 Exposure Sources

Our first focus was on finding a suitable exposure source capable of crosslinking the resist. For this particular resist, an appropriate exposure source is one which will cause the resist to change color from green to dark blue. In this portion of the experiment, borosilicate glass slides were laminated with a single layer of resist, either MX-5020 or MX-5050, as described below. The laminated slides were cleaned, exposed, and patterned with a photomask containing five straight lines of different widths (25  $\mu\text{m}$ , 50  $\mu\text{m}$ , 100  $\mu\text{m}$ , 150  $\mu\text{m}$ , and 200  $\mu\text{m}$ ) by 3 cm long for increasing amounts of time to determine the minimum amount of time required for one of the four previously described exposure sources to provide a sufficient exposure dosage.

#### 3.2.3.2 Resist Adhesion

Using the exposure systems that adequately exposed the resist, the next factor evaluated substrate efficacy in providing sufficient adhesion to the resist. For this, borosilicate glass slides and silicon wafers were examined for suitability, and again a single layer of MX-5020 and MX-5050 was laminated onto either a wafer or slide. The slides were again patterned with the straight line feature mask described above, and were then processed as described in the single layer master production section.

#### 3.2.3.3 Exposure Source Effects on Feature Size and Maximum Aspect Ratio

In this section of the study, the straight line resist patterned substrates produced to test the adhesion of the resist to the substrate were used. A representative example of each resist thickness produced using the light sources found to be appropriate was employed. These masters were then used to determine if the line widths produced varied with exposure source. Then the maximum height to width aspect ratio was determined for both the MX-5020 and MX-5050 resist. The maximum aspect ratios were ascertained using the linear lithographic feature with the smallest width that was successfully produced.

To measure the line widths, the previously described Zeiss AxioTron microscope equipped with ImagePRO Plus 6.0 video capture image software was used. The lines were measured randomly at five locations. From these measurements, the

average line width was determined. The calculated averages were then used to see if the exposure source yielded the expected line width.

In determining the maximum attainable height to width aspect ratio, a Veeco Dektak 8 Stylus Profiler was employed to measure the resist height. Five measurements of the resist height for the linear features with the smallest width were taken to find an average resist height. The maximum height to width aspect ratio was then determined using the average resist height and widths calculated.

#### 3.2.3.4 Single Resist Layer Masters

After determining which substrate provided the best adhesion, single layered masters were patterned and produced to contain features for a microchip: a double-tee capillary electrophoresis device. The feature dimensions of the double-tee photomask were as follows: 1 cm long sample and sample waste side arms, 4.25 cm total main channel length with an injection length of 2.5 mm and a separation length of 3 cm, and for all features mentioned, the line widths were 100  $\mu\text{m}$ . These masters were produced as described in the single layer master production.

#### 3.2.3.5 Master Performance

To test the performance of the masters, replica molding of PDMS was conducted using the single layer, multilayer resist, and multidimensional resist masters.

PDMS was mixed in a 10:1 oligimer to curing agent ratio. Following mixing, gas bubbles were removed by placing the PDMS mixture in a vacuum desiccator and applying vacuum. The degassed PDMS was then poured over the master. The assembly was then placed in a 95 °C oven for 1 hr to cure the PDMS. The cured PDMS was then peeled from the master after the assembly was removed from the oven and was allowed to cool to room temperature.

Once at room temperature, the cured PDMS was removed from the master. The master and PDMS were then examined to see if there were any resist adhesion issues. The first issue examined was adhesion failure between the resist and master surface. Also studied was loss of interlayer resist adhesion for the masters fabricated with multiple resist layers. If resist was present in the PDMS features, the corresponding region of the master was examined with a microscope to determine the extent to which the resist was removed from the substrate surface. If resist was absent in these regions, it was taken as an indication that there was an adhesion issue between the resist and substrate. Also, all of the masters were inspected to determine if there was delamination between the resist and substrate surface. For the multilayer and multidimensional masters interlayer resist separation was too scouted for by eye and with a microscope.

### 3.2.4 Methods Used for Producing Masters

#### 3.2.4.1 Substrate Cleaning

Substrate cleaning was conducted as follows. The glass slides were rinsed with acetone, methanol, and ultra pure water. Following the rinse, the substrates were dried with a stream of nitrogen gas. To ensure the substrate surface was free of any residual organic contaminants, the surface was descummed in an oxygen plasma. The oxygen plasma parameters used were a chamber pressure of 200 mTorr and a power setting of 22 W. The total time the substrate was exposed to the oxygen plasma was in the range of 2-3 min. For the silicon wafers, the cleaning process consisted of rinsing the substrate surface with ultra pure water, drying under a stream of nitrogen gas, and descuming the substrate surface in an oxygen plasma. The plasma parameters used for cleaning the silicon wafers was identical to that of the glass slides.

#### 3.2.4.2 Single Layer Master Production

Resist lamination was carried out as follows. First, the polyethylene layer was removed from the resist. The resist was then laminated onto the substrate by employing the homemade rolling pin. The laminated substrate was then placed on an aluminum plate at 95 °C. The laminated substrate was allowed to warm and any imperfections present were removed using a rubber squeegee. A second aluminum plate at 95 °C was then placed on top of the laminated for 30 s. The laminated substrate was then subjected to a post lamination bake of 20 min in a 65 °C oven, to improve adhesion between the resist and substrate surface. After the

post lamination bake, the laminated substrate was allowed to cool to room temperature in a dark drawer.

The laminated substrate was then masked using a Mylar photomask, and to ensure the photomask was in direct contact with the resist it was weighted down using a glass slide. Exposure was accomplished using one of the four exposure sources previously described. The exposure times for the mercury arc lamp system and Spectraline light source was 2 min, and for the MG Chemicals and Kepro sources exposure times up to 1 hr were examined. The exposed laminated substrate was post exposure baked at 100 °C for 25 min on a hot plate.

Prior to developing, the polyester layer was removed from the resist. The resist was then developed using an aqueous 0.75 vol. % D-4000 IC concentrated developer solution and rinsed using an aqueous 300 ppm carbonate solution. Both the diluted developer solution and rinsing solution were heated in a water bath to 45 °C. The developer was sprayed onto the resist using an air brush operated at 20 psi of nitrogen gas, or as otherwise stated. The rinsing solution was sprayed onto the substrate using a plastic spray bottle. The rinsing/developing stages were carried out as follows. Working from the edge of the substrate towards the center, a small area of the substrate was developed, and then immediately rinsed. After the 300 ppm final calcium carbonate rinse, the master was rinsed with ultra pure

water, and then dried with a stream of nitrogen gas. The dried master was then baked on a 100 °C hot plate for 25 min.

### 3.3 Results and Discussion

#### 3.3.1 Exposure Sources

Resist-laminated glass slides masked with the five line photomask were exposed to one of the four exposure systems. It was found that only two of the four systems appropriately crosslinked the single layer resist laminated glass slides: the homemade mercury arc lamp exposure system and the Spectroline X-15 365 nm i-line light source. Both systems successfully exposed every line width on the test mask, spanning a range of feature widths from 25-200  $\mu\text{m}$ . The minimum exposure time for both systems was determined to be 2 min. These results agree with the resist specifications which state this photoresist will have maximum absorbance at 365 nm.

The MG Chemicals and Kepro fluorescent light sources were found to not appropriately crosslink the resist, even for exposure times of up to 1 hr. It was observed that these two light sources did crosslink the resist, but not to the extent attained using the homemade mercury arc lamp exposure system and the Spectroline X-15 365 nm i-line light source. The homemade mercury arc lamp exposure system and Spectroline X-15 365 i-line light source were thus considered to be suitable exposure sources for the Dupont MX-5000 series resist.



### 3.3.2 Adhesion to Substrates

Glass slides and silicon wafers were laminated with single layers of MX-5020 and MX-5050 resist. The resist was again patterned with the 5 line Mylar transparency, and the light sources found to be suitable in the previous portion of this study. The homemade mercury arc lamp exposure system and the Spectroline X-15 365 i-line light source were used to produce examples for each possible resist and substrate combination.

Upon development, inconsistent results were obtained for the resists laminated onto borosilicate glass slides. During the development process catastrophic delamination was a recurring issue for the straight line features patterned on the borosilicate slides, even when the air brush was operated at the lower pressure limit, 10-12 psi, during development. Masters produced on silicon wafers yielded consistent results. For masters produced using MX-5020 all linear lithographic features, ranging from 25-200  $\mu\text{m}$ , were successfully developed. Silicon wafers patterned with MX-5050 resist consistently produced the linear features with widths ranging from 50-200  $\mu\text{m}$ . In each instance using the MX-5050 resist, a lack of adhesion was encountered for the 25  $\mu\text{m}$  wide features, which resulted in distorted lithographic features. Thus, silicon wafers were found to be a better substrate for creating resist features than glass slides because the resist features were attainable on a consistent basis.

### 3.3.3 Exposure Source Effects on Feature Size and Maximum Aspect Ratio Attainable

The silicon wafers patterned with the straight line resist features used in the adhesion to substrate section were again used. Resist-patterned silicon wafers were employed to study two factors. These factors were: (1) exposure source effects on resist feature size, and (2) maximum aspect ratio attainable. A representative example for each resist thickness and both of the appropriate sources was imaged with a Zeiss Axiotron. The video capture images were then processed with Image Pro 6 software to obtain an average line width for each resist line created. The average and standard deviation of the calculated line width for each of the representative examples are listed in Table 2.

From the data obtained and listed in Table 2, it can be concluded that the mercury arc lamp exposure system resulted in resist features with dimensions nearest those on the photomask. The masters created using the Spectroline X-15 light source resulted in features with widths greater than the line features in the photomask used. This deviation from the expected line widths is most likely due to the light source not being collimated. The increased feature widths are not thought to be due to diffusional crosslinking because the resist was only exposed the minimum amount of time required to crosslink the resist.

To determine the maximum height-to-width aspect ratio, the masters produced using the homemade UV exposure system was used. The heights of the resist features were measured using a profiler and the average height, from a total of five measurements, was calculated for each line measured. The line widths used were the 25  $\mu\text{m}$  wide linear lithographic feature for the master produced from MX-5020 resist and the 50  $\mu\text{m}$  wide linear resist feature for the master made using MX-5050 resist. These features were selected because these were the narrowest lithographic features attained for each of these masters and are thus representative of the largest height-to-width aspect ratio. The average feature height for the MX-5020 and MX-5050 resist was found to be  $20.5 \pm 0.06 \mu\text{m}$  and  $52.0 \pm 0.30 \mu\text{m}$ , respectively. The maximum height-to-width aspect ratio attainable was found to be approximately 0.8 for the MX-5020 resist and 1 for the MX-5050 resist.

### 3.3.4 Masters and Master Performance

Masters produced with a single resist layer were patterned with a double-tee microchip capillary electrophoresis design, previously described. These masters were produced using silicon wafers, and a single layer of either MX-5020 or MX-5050 resist was used for feature patterning. Exposure was accomplished in 2 min using the mercury arc lamp exposure system. The width of the main channel, sample channel, and sample waste channel were obtained using a Zeiss Axiotron microscope, and the height of the resist was measured using a Veeco Dektak 8 Stylus Profiler. Each of these feature dimensions was measured a total of 5 times,

and the average dimension value for each master was found to be as follows. The MX-5020 master had a main channel width of  $99.7 \pm 1.2 \mu\text{m}$ , a sample channel width of  $104.4 \pm 2.4 \mu\text{m}$ , a sample waste channel width of  $101.9 \pm 1.2 \mu\text{m}$ , and a height of  $19.1 \pm 0.19 \mu\text{m}$ . The MX-5050 master exposed with the mercury arc lamp exposure system had the following dimensions: a main channel width of  $103.6 \pm 1.0 \mu\text{m}$ , a sample channel width of  $101.9 \pm 1.2 \mu\text{m}$ , a sample waste channel width of  $103.7 \pm 1.8 \mu\text{m}$ , and a height of  $49.4 \pm 0.95 \mu\text{m}$ . The resultant feature widths for both resist thicknesses were found to be within a 1.9-3.7  $\mu\text{m}$  of the expected value of 100  $\mu\text{m}$ . The measured resist height for the MX-5020 resist and MX-5050 resist were both measured to be within one micrometer of the expected height values of 20  $\mu\text{m}$  and 50  $\mu\text{m}$ , respectively. Figure 3.1 shows an image of a representative master produced with MX-5020.

Replica molding was accomplished by casting PDMS onto a master placed in a molding jig. Then the polymer was cured in a 95 °C oven for 1 h. Once cured, the PDMS was removed from the master and the master was examined. Upon examination, it was found that the resist features were not compromised. It was found that the masters properly patterned the lithographic features into the PDMS. The masters were used multiple times for replica molding without failure and thus would be suitable for replica molding of PDMS components. In figure 3.2, an image of a replica molded PDMS component patterned using the master displayed in figure 3.1 is shown.

### 3.4 Conclusions

Dupont MX-5000 series microlithographic photoresist was found suitable for use in creating masters for replica molding of PDMS, and successfully yielded single layer resist masters. Silicon was found to be a better substrate choice because the resist was found to have better adhesion to silicon wafers than borosilicate glass slides. Also, a homemade UV flood exposure system and the Spectronics X-15A exposure sources adequately exposed and crosslinked the resist. Unfortunately, the Spectroline X-15A light source resulted in features that were wider than expected. This is most likely due to the light source not being collimated and future work will need to be conducted with a collimated 365 i-line source to show appropriate master results with such an exposure source. The maximum height to width aspect ratio attainable was one.

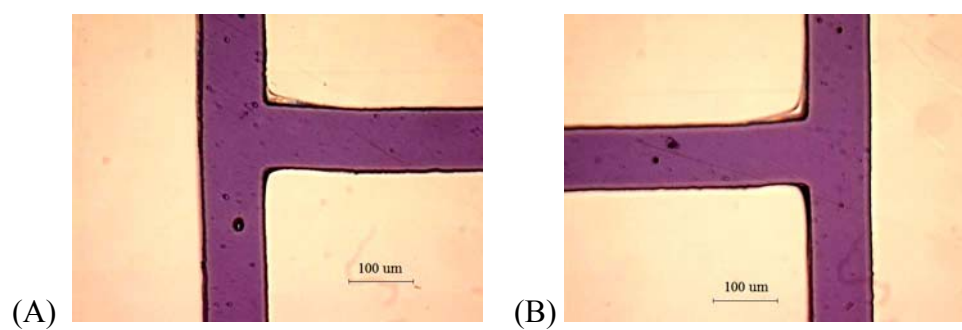
**Figures**

Figure 3.1. Images of a double-T microfluidic master with 100 $\mu$ m wide features produced with MX-5020 dry film resist. (A) Image showing intersection between the sample channel and main channel. (B) Image of sample waste channel intersecting with the main channel.

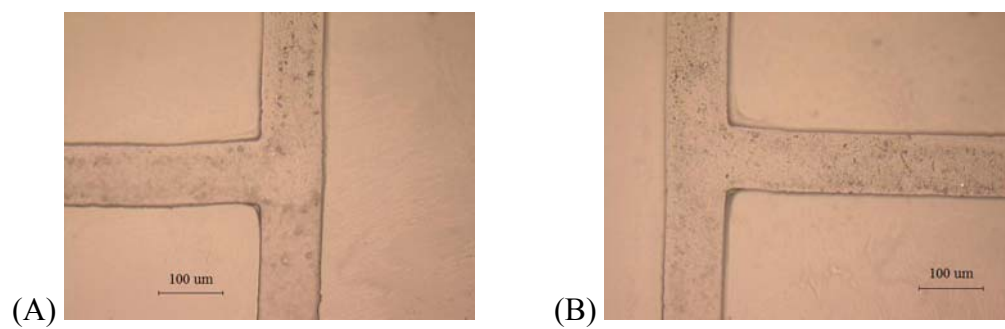


Figure 3.2. Images of the replica molded PDMS component produced from the double-T microfluidic master in Figure 3.1. (A) Image showing intersection between the sample channel and main channel. (B) Image of sample waste channel intersecting with the main channel.

## Tables

Table 2. Line widths for linear features patterned in MX5020 and MX5050 using mercury arc lamp and Spectroline X-15 exposure sources.

Exposure Source	Resist	Expected Line Width	Actual Line Width	Standard Deviation
		( $\mu\text{m}$ )	( $\mu\text{m}$ )	( $\mu\text{m}$ )
Arc Lamp	MX5020	25	29.4	1.2
Arc Lamp	MX5020	50	56.2	1.2
Arc Lamp	MX5020	100	105.4	1.6
Arc Lamp	MX5020	150	154.6	1.2
Arc Lamp	MX5020	200	204.2	1.6
Arc Lamp	MX5050	50	54.0	1.2
Arc Lamp	MX5050	100	104.1	1.2
Arc Lamp	MX5050	150	150.2	1.2
Arc Lamp	MX5050	200	200.7	1.2
Spectroline	MX5020	25	142.7	1.6
Spectroline	MX5020	50	202.0	1.6
Spectroline	MX5020	100	267.9	2.2
Spectroline	MX5020	150	309.2	2.9
Spectroline	MX5020	200	360.1	1.6
Spectroline	MX5050	50	174.8	2.5
Spectroline	MX5050	100	244.2	2.9
Spectroline	MX5050	150	290.7	2.5
Spectroline	MX5050	200	332.0	2.4



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**Chapter 4:**  
**Fabrication of an electroformed ratchet type dielectrophoresis**  
**device**

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## Abstract

Presented is the fabrication of an electroformed ratchet type dielectrophoresis device. Discussed are the processes used in the fabrication of the required device components: electrode features patterned onto a glass slide using UV-LIGA and wet etching, and a PDMS fluidic component produced through replica molding. Two distinct PDMS components were used to show how the device can be configured as either a flow-through system or non-flow-through system.

## 4.1 Introduction

With the advent of micro-electromechanical systems (MEMS) brought forth by advances in the semiconductor industry and improved machining technology, the electrokinetic phenomenon of dielectrophoresis (DEP) has made a recent resurgence due to the possibility of creating devices with smaller interelectrode distances. Through dimensional reduction, higher effective field strengths are now possible using only a few volts applied potential, which were not previously attainable. The phenomenon of DEP occurs when a dipole moment is induced in a suspended analyte particle within the confines of an asymmetrical electric field [1-3]. Depending on the degree of polarization of the analyte particle relative to the polarization of the suspending medium, motion may be induced. If the polarizability of an analyte particle is *greater* than that of the suspending medium, the particle will be moved to the *higher* field strength region (positive DEP). If the particle is *less* polarizable than the suspending medium the particle will aggregate

in the *low* potential area (negative DEP). If both the analyte particle and suspending medium are polarized to the same extent the particle will experience no net movement.

In the past few years, DEP has been successfully implemented in the analysis of a vast array of sample types. Sample types analyzed include: cells [4,5], *E. coli* [6-10], viruses [5,6,11-13], blood serum components [4,5,14-19], latex spheres [11,14,19-25], and fine particles [26]. Many dielectrophoretic devices have been successfully constructed, as previously mentioned, via commonly used MEMS fabrication technology, such as direct write electron beam lithography [25], micromachining [27], laser machining [28], and lift-off technology [4,8,10,11,14,24,29]. One avenue which has not been explored, to the best of our knowledge, in constructing electrodes to produce the asymmetrical required for operating a DEP device is electroforming through LIGA or UV-LIGA.

Electroforming has been successfully implemented in many fields for the production of various components. One area where electroforming has been shown as a viable option is in the injection molding industry for fabricating molds [30,31]. Another field which has seen success in producing electromolded components is electrodischarge machining for constructing machining electrodes [32,33]. Multilevel electroplating has also been shown to be feasible in producing acceleration sensors, and single mechanical components containing a gear, pinion,

and axle [34,35]. Presented here is the fabrication of a microfluidic dielectrophoresis device containing electroformed electrodes, along with methods by which to configure the device as a flow-through or non-flow-through system, depending on the geometry of the poly(dimethylsiloxane) (PDMS) fluidic layer employed.

#### 4.2 Objectives and Device Description

The aim here is to present how electroforming, which has been successfully implemented in several fields, can be applied to the field of dielectrophoresis to produce a microfluidic device containing ten independently addressable ratchet type electrode sets. The device consists of two main components. The first component is an electrode layer which was constructed by sputtering conductive seedlayers onto a glass slide, patterning with dry film photoresist, nickel electroforming using a nickel sulfamate plating solution, resist stripping, and wet etching of the unused regions of the conductive seedlayers to electrically isolate the electrodes. The second component needed is a replica molded PDMS fluidic layer fabricated using conventional soft lithography technology.

The geometry of the electrode features contained on the glass slide is shown on the photomask used in patterning the film resist, figure 4.1, and a brief description is as follows. Each electrode contained three main features: a 2.5 mm square solder pad onto which electrical connections to a function generator are made, a ratchet

type electrode feature for dielectrophoretic manipulation of analyte particles, and an electrical lead connecting the solder pad and electrode features. The electrode features had widths of 100  $\mu\text{m}$  and were grown to a height of 20  $\mu\text{m}$ . Interelectrode distances between electrode pairs were 50  $\mu\text{m}$  at the narrowest portion and 325  $\mu\text{m}$  at the widest region, and the total length from the narrowest to widest region is 200  $\mu\text{m}$ . The offset between successive electrode pairs was set to zero.

The fluidic layer was attained through replica molding of PDMS by using masters fabricated with silicon wafers patterned with dry film photoresist. Figure 4.2 shows the features contained on the photomasks used produce the masters needed for replica molding of the PDMS fluidic components, which were required to render the device as either a flow through or non-flow through system. As can be seen in figure 4.2, both masters contained similar features. Identical features included on both master types are: solder pads, electrode leads which join the solder pad and the ratchet type electrodes, and an outline of the outer-most ratchet type feature. The difference between these masters is that the flow through geometry contains a fluidic inlet and outlet. Fluidic access into the ratchet type electrode regions of the device was attained through use of magnets and a molding fixture containing a galvanized steel base. The magnets served as posts during the replica molding of PDMS. Magnets were selected for use as posts because magnetic forces allow for easy configuration and variety of geometries are

possible, as magnets are available in a variety of shapes and sizes [36]. For the flow through configuration, the magnets were placed at the both ends of the channel features. In producing the PDMS component of the non-flow through geometry, a magnet was placed over the electrode region to produce a well into which to place a sample aliquot.

Final device assembly was accomplished by marrying the PDMS layer onto the electrode feature layer to produce a conformal seal. Conformal sealing was selected because this method allows for disassembly of the device for cleaning, thereby making the device reusable. By constructing the PDMS fluidic layer to contain negative images of the electroformed electrodes, reproducible registration between the device components can be attained over numerous cleanings.

## 4.3 Experimental

### 4.3.1 Reagents and Materials

Borosilicate glass slides, 50 mm by 75 mm, used as substrates onto which the electrodes were electroformed, were purchased from VWR (West Chester, PA, USA). The conductive seedlayers required for electroforming were sputtered onto the glass slides by Sulzer Metaplas Inc. (RI, USA), and the seedlayers deposited were a 40 nm layer of titanium and a 50 nm layer of copper. Mechanical grade silicon wafers, 3 inch radius, for use as substrates for masters were purchased from University Wafers (South Boston, MA, USA). A dry-film photoresist, Dupont



MX-5000 series, used for laminating and patterning was purchased from Microchem (Newton, MA, USA). Photoresist thicknesses of 20  $\mu\text{m}$  (MX-5020) and 50  $\mu\text{m}$  (MX-5050) were used. AutoCAD 2007 (Autodesk, San Rafael, CA, USA) software was used for designing of the Mylar transparencies for use as photomasks during resist exposure. Upon designing, the Mylar transparencies were then photoplotted by CAD/Art Services, Inc. (Bandon, OR, USA). Acetone and methanol (Northwest Solvents, Eugene, OR, USA) of technical grade were used for rinsing substrate surfaces. Spectroscopic grade methanol (Mallinckrodt Chemicals, Phillipsburg, NJ, USA) was used as a lubricant during alignment of the PDMS cover layer with the electrode layer. Ultrapure water from a Barnstead E-Pure system (Dubuque, IA, USA) was used for rinsing and solution preparation. An aqueous 0.75% resist developing solution was prepared from Dupont D-4000 IC concentrated developer, and was purchased from Microchem. The 300 ppm calcium carbonate developing rinsing solution was produced from technical grade calcium carbonate (J.T. Baker, Phillipsburg, PA, USA). Sylgard 184 silicone elastomer kit (Dow Corning Corp., Midland, MI, USA) was used for production of the PDMS cover layer. Neodymium magnets used as posts to create fluidic *vias* during PDMS replica molding were purchased from K&J Magnetics, Inc. (Jamison, PA, USA). Nickel Sulfamate RTU mechanical agitation plating solution and nickel anode were purchased from Technic Inc. (Anaheim, CA, USA). Dynasolve 2000 (Dynaloy Engineered Chemistries, Indianapolis, IN, USA) was used for removal of the photoresist after electroforming of the nickel electrodes.

Ferric chloride solution (MG Chemicals, Surrey, Canada) was used for etching of unused portions of the copper seedlayer. Reagent grade hydrogen peroxide (Mallinckrodt Chemicals, Phillipsburg, NJ, USA) and potassium hydroxide (Mallinckrodt Chemicals, Phillipsburg, NJ, USA) were used to produce a 1:1 mixture of 5% hydrogen peroxide and 5% potassium hydroxide for use as an etchant for removal of the titanium seedlayer, exposed upon etching of the copper seedlayer.

#### 4.3.2 Equipment

A home-made oxygen plasma etching system for descumming substrate surfaces prior to lamination and electroforming was used. The plasma system was constructed using a 6 inch x 10 inch 4-port stainless steel vacuum chamber from MDC Vacuum Products Corporation (Hayward, CA, USA), and an Evactron Decontaminator RF Plasma Cleaner from XEI Scientific (Redwood City, CA, USA). For laminating substrates with photoresist, a homemade rolling pin constructed by inserting a glass rod into a piece of rubber tubing was employed. For removal of any resist imperfections resulting from the lamination process, a rubber squeegee was used to smooth the resist. One foot square by quarter inch thick aluminum plates (McMaster-Carr, Los Angeles, CA, USA) were used to press the resist onto the substrate surface, thus improving resist adhesion. Resist exposure was accomplished using a homemade UV flood exposure system consisting of an Oriel 6186 mercury arc lamp (Oriel Light Sources and

Spectroscopy Instrumentation, Stratford, CT, USA) and a Durst 606 photo enlarger (purchased used, locally) to direct the UV light at a right angle towards the substrate. For resist development, a Paschee VLS airbrush (Chicago, IL, USA) was utilized. To attain appropriate registration between the PDMS cover layer and the electrode layer a Leica Wild Stereozoom microscope (Wetzlar, Germany) was employed. For imaging, a Zeiss Axiotron (Carl Zeiss MicroImaging, Inc., Thornwood, NY, USA) equipped with a Sony Power HAD DXC-970MD camera (Sony Corporation, New York, NY, USA) and ImagePro Plus 6.0 (MediaCybernetics, Silver Spring, MD, USA) was used. A Dynatronix (Amery, WI, USA) DuP 10-1-3 pulsed power supply was used to electroform the nickel electrodes. For determining the plating rate of nickel, a Veeco Dektak 8 Stylus Profiler fitted with a 12.5  $\mu\text{m}$  tip (Veeco Instruments Inc., Woodbury, NY, USA) was employed.

#### 4.3.3 Device Fabrication

Electrodes were fabricated using Ti-Cu seedlayer coated glass slides which were patterned using dry film resist, and then electroformed with nickel to produce the desired electrode features. The second portion of the device is a replica molded PDMS slab patterned with necessary fluidic features.

#### 4.3.3.1 Photolithography

Both of the above mentioned components were constructed using a photolithographic approach with a dry film photoresist, described in greater detail in chapter 3. The resist came supplied in a roll from the manufacturer encased between a polyethylene layer and polyester layer. For the electrode layer, lithography was employed for creating void spaces into which nickel was then electroformed to create the electrode features. The PDMS slab containing the required fluidic features was cast onto a master containing negative features of the final desired PDMS component. Due to the commonality in producing the above mentioned components, the photolithography process engaged will be addressed separately.

First, the surface of the substrate (either the seedlayer sputtered glass slide or silicon wafer) to be laminated with resist was rinsed with acetone, methanol, ultrapure water, and then dried with a stream of nitrogen gas. The surface was then descummed using an oxygen plasma for 1 min. at a chamber pressure of 200 mTorr and a power of 20 W.

The cleaned surface was then laminated with the dry film photoresist as follows. The resist was prepared for lamination by removal of the polyethylene layer. Then by using a homemade rolling pin, the resist was laminated onto the substrate.

Imperfections occurring during the lamination process were then removed by first placing the laminated substrate onto an aluminum plate at 95 °C to soften the resist. Once the resist had softened, its surface was smoothed using a rubber squeegee and was pressed between two aluminum plates at 95 °C for 30 s to improve the adhesion between the resist and surface being laminated. The laminated substrate was then baked in a 65 °C oven for 20 min., then placed in a dark drawer and allowed to cool to room temperature.

To produce the negative image of either the final electrode features to be electroformed or the PDMS fluidic component, a Mylar transparency was employed. The transparency was placed in contact with the photoresist under a glass slide. The assembly was then exposed with a UV flood exposure system for 1.5 min or 2 min for electroform masking and PDMS master production, respectively. The now exposed resist laminated substrate was then baked for 25 min on an 85 °C hot plate.

Developing and rinsing of the photoresist was accomplished using 0.75 vol. % D-4000 IC concentrated developer solution and an aqueous 300 ppm calcium carbonate solution, respectively. Prior to use, the developing solution and rinsing solution were warmed to 45 °C in a water bath. The unexposed photoresist was developed by first removing the polyester layer from the resist surface, and then soaking the resist laminated substrate in developing solution for 5 min. The

substrate was sprayed with carbonate rinsing solution, and then fully developed using an airbrush operated at 12 psi of nitrogen gas to apply the developer. After rinsing a final time with the carbonate rinsing solution, the patterned substrate was rinsed with ultrapure water, dried under a stream of nitrogen gas, and baked for 25 min on a 100 °C hot plate.

#### 4.3.3.2 Electrode Fabrication

Electrode fabrication was accomplished by electroforming nickel into the voids created in the resist on the coated glass slide as a result of the lithographic processing. Following electroforming, the resist was removed from the substrate surface and then the exposed seedlayers were removed using conventional wet etching processes. The process utilized is described in detail below.

##### 4.3.3.2.1 Electroforming of Electrodes

Electroforming of nickel electrodes was conducted using a ready made nickel sulfamate plating solution and a pulsed DC power supply. The plating bath temperature was 49 °C, pH 4, and was stirred using a magnetic stir bar. The nickel anode was covered with filter paper to reduce the possibility of introducing anode residues produced during the electroforming process. Prior to electroforming, the cathodes (resist-patterned, seedlayer-coated glass slides) were cleaned and prepared for electroforming by cleaning in an oxygen plasma at 200 mTorr and 22 W for 1 min. to descum the exposed copper surface of any residues remaining

from the lithography processing. The copper surfaces of the cathodes were prepared for electroforming by rinsing with diluted detergent and ultrapure water to remove any residual organics, then immersing into a 20%  $\text{H}_2\text{SO}_4$  solution and rinsing with ultrapure water to remove any oxides from the copper surface.

Once cleaned, the patterned glass slide was connected to the cathode of the power supply. The anode and cathode were then submerged in the plating bath. The power supply pulse duty cycle was set to 1.5 ms on and 0.5 ms off, and the plating current was set to 40 mA to produce a current density of  $2.2 \text{ A/dm}^2$ . A plating rate of  $0.4 \text{ }\mu\text{m/min}$  was established with the above conditions, and thus a total plating time of 50 min was required to obtain electrodes with a final height of  $20 \text{ }\mu\text{m}$ .

#### 4.3.3.2.2 Resist Stripping and Seedlayer Removal

Once the electroformed nickel electrodes were produced, the electrodes were made independently addressable by removing the sputtered conductive seedlayers found around the nickel features by first stripping the photoresist and then wet etching the portions of the seedlayers exposed upon removal of the resist. Photoresist removal was accomplished by immersing the electroformed substrate into a beaker containing Dynasolve 2000 until the resist was completely stripped. The entire surface is rinsed with acetone, methanol, and ultrapure water and dried under nitrogen. The exposed copper seedlayer was then removed by coating the surface with a thin film of concentrated  $\text{FeCl}_3$  solution at  $55 \text{ }^\circ\text{C}$ , then rinsing with

deionized water in order to minimize the possibility of distorting the nickel features. To selectively remove the exposed titanium seedlayer, a 1:1 solution of 5% KOH and 5% H<sub>2</sub>O<sub>2</sub> was utilized. The substrate and now electrically isolated electrodes were rinsed with ultrapure water and dried under a stream of nitrogen. A photograph of the electrically isolated electrodes is shown in figure 4.3.

#### 4.3.3.3 Replica Molding of PDMS

Production of both PDMS cover layer geometries was accomplished via replica molding. First, masters were produced using 3 inch silicon wafers and dry film photoresist. The photolithography processing was accomplished using the process described in the photolithography section.

The master was placed into a molding fixture containing a galvanized steel base. The steel base in the molding fixture was essential as magnets were used as posts to create fluidic access to the ratchet type features. For the flow through system, a 1/16" dia. x 1/4" tall cylindrical magnet was placed at the end of each fluidic via to produce 1/16" diameter *vias*. To create the fluidic well in the static geometry, a 1/8" x 1/8" x 1/16" block magnet was employed and placed over the ratchet type region of the device to create an 1/8" x 1/16" rectangular well. An image of the masters fitted with magnets is shown in figure 4.4. PDMS was then prepared by mixing the elastomer and crosslinker in a 10:1 ratio. The PDMS was then degassed using a vacuum desiccator, cast over the master, and then placed in a 95



°C oven for 1 hr. The magnets used as posts were then removed and the PDMS was peeled from the master.

#### 4.3.3.4 Device Assembly

Prior to mating the glass slide containing the electrode features with the replica molded PDMS component, rosin core lead solder was added to the nickel contact leads located on the glass slide. To prevent flux and solder contamination elsewhere on the slide, all other electroformed electrode features were covered with a piece of foil. The replica molded PDMS component was then trimmed to contain only the features corresponding to the electroformed leads, ratchet types, and fluidic component features. In the case of the PDMS component configured with the well geometry, the PDMS meniscus around the well was removed using a razor blade to yield a flat surface onto which to place a glass microscope cover slip.

Registration between the patterned PDMS component and glass slide containing the electroformed features was attained using a process used to align oxygen plasma activated PDMS surfaces [37]. This process uses an organic solvent (in this application, methanol) which acts as a lubricant and preserves the activated PDMS surface. A few drops of methanol were placed on both surfaces to be mated together. Then the layers were aligned using a microscope. Upon

alignment, the assembly was placed in a 95 °C oven to evaporate the methanol. Figure 4.4 shows the assembled devices.

#### 4.4 Results and Discussion

Proper device function was tested using the non-flow through configuration. To test if particles will collect in the high potential regions (positive DEP) and low potential regions (negative DEP) magnetite and polystyrene particles were used, respectively. The particles were found to collect in appropriate regions over a frequency range of 60 Hz to 20 MHz, and a representative example is shown in figure 4.5. During these analyses, the PDMS fluidic component was removed to clean the electroformed ratchet type features, and was realigned in a reproducible manner due to the mating between the electrodes and their negative images cast into the PDMS. In chapter 5 a thorough explanation of the operation of this device and the above results will be presented, as the aim of this work was to show the feasibility of constructing a dielectrophoretic device containing electroformed nickel electrodes.

#### 4.5 Summary and Outlook

A microfluidic ratchet type dielectrophoresis device was constructed using UV-LIGA, wet etching, and replica molding of PDMS. The device was successfully constructed with ten electroformed electrode pairs, which can be independently

controlled. The electrode assembly was fitted with replica molded PDMS to configure the device as either a flow-through or static system. Appropriate registration between the electrode layer and fluidic layer of the device was aided by the manufacturing techniques selected in fabricating the device, electroforming and replica molding. With electroformed electrodes and a replica molded PDMS fluidic component containing a negative image the electrodes, the PDMS fluidic layer was easily coupled onto the electrode layer.

Electroforming was shown to be a viable method for the production of this dielectrophoretic device. An area of the electroforming process which will require further optimization is the lithographic processing in order to produce straighter electrode sidewalls. As illustrated in figure 4.3, some of the electroformed electrodes contain regions where the nickel features contain slightly rough sidewalls. One possible option which may rectify this problem includes use of a developing station. Use of a developing station will allow for reproducible photoresist development by having temperature control of the developer, consistent spray pressure/developer flow, and thus eliminating human error.

Figures

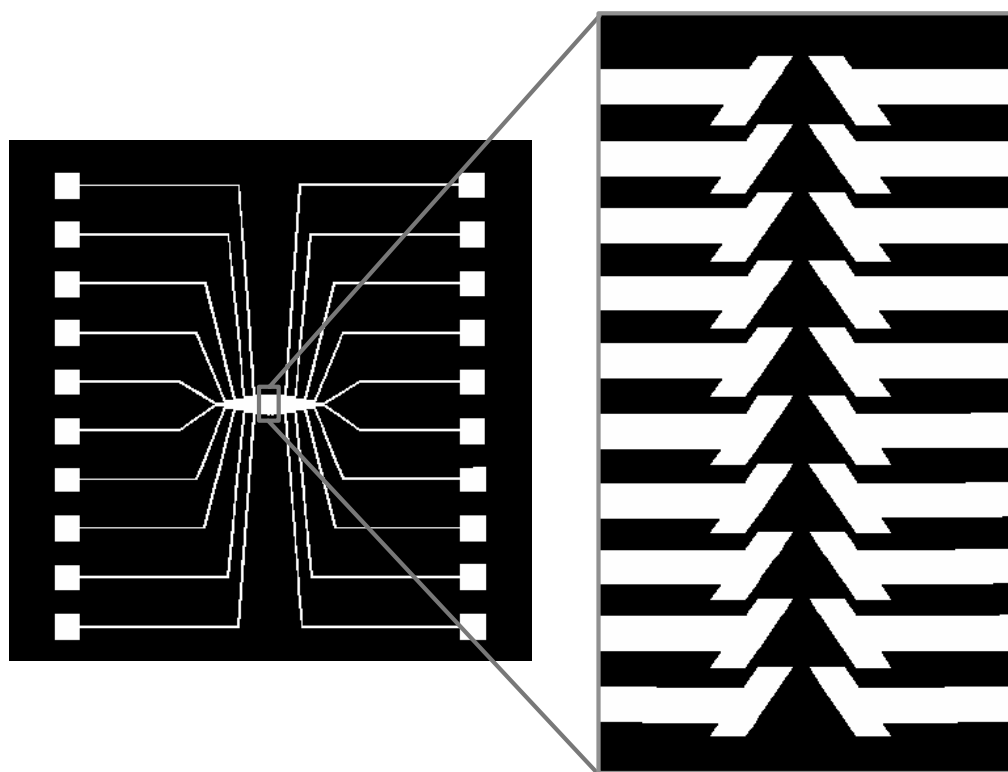


Figure 4.1. AutoCAD images of the photomask used to pattern the desired electrode pattern onto the glass substrate.

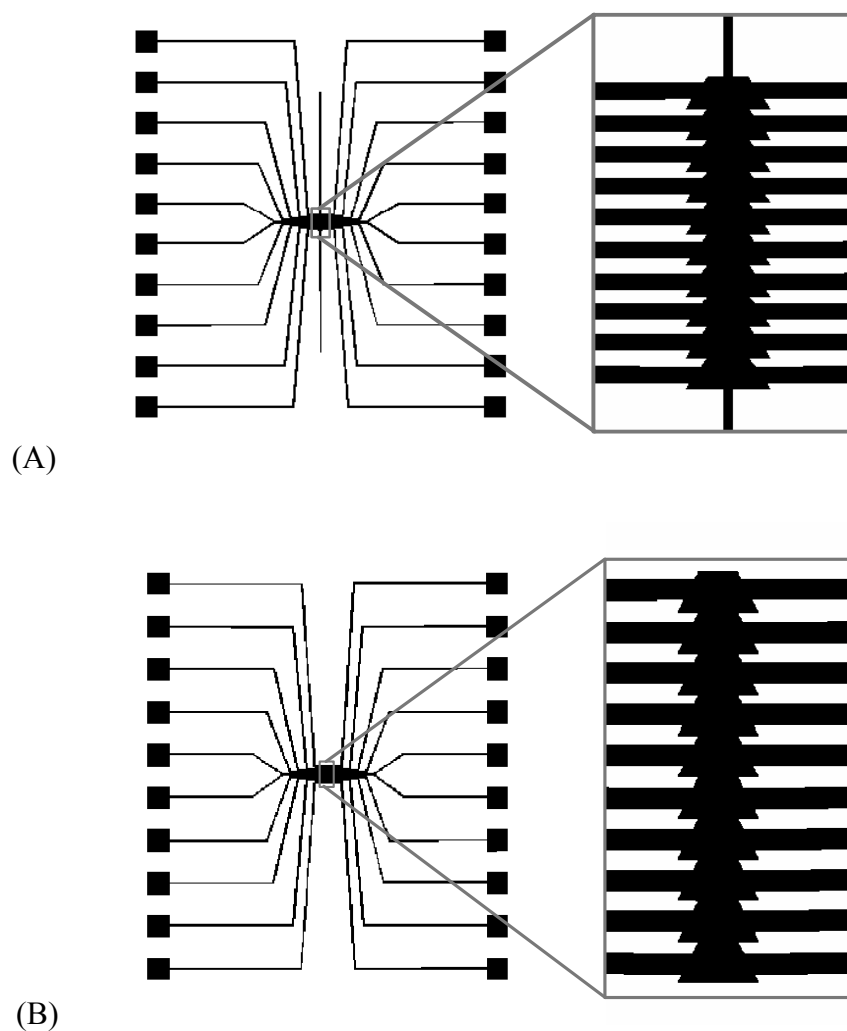


Figure 4.2. AutoCAD images of the photomasks used to produce the masters used for replica molding of the PDMS fluidic components. (A) Flow-through system geometry, with expanded view of central mask features. (B) Static system geometry, with expanded image of central mask features.

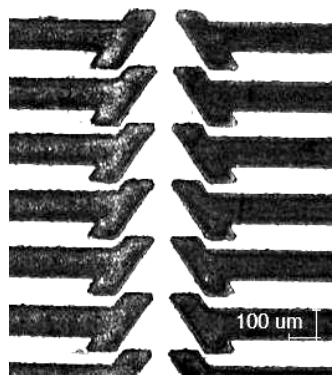


Figure 4.3. Photomicrograph of the electrically isolated electroformed nickel electrode features.

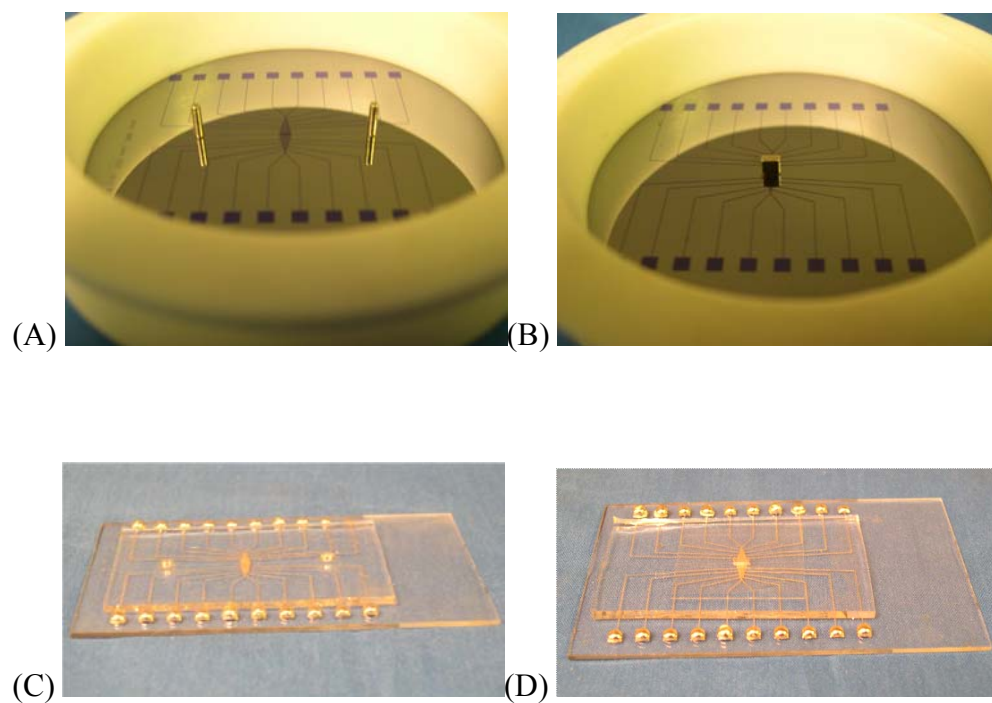


Figure 4.4. Photographs of the masters used for replica molding of the PDMS fluidic layer, and the final mating of the replica molded PDMS component onto the electrode features. (A) Flow-through master. (B) Static system master. (C) Assembled flow through device. (D) Assembled non-flow through device.

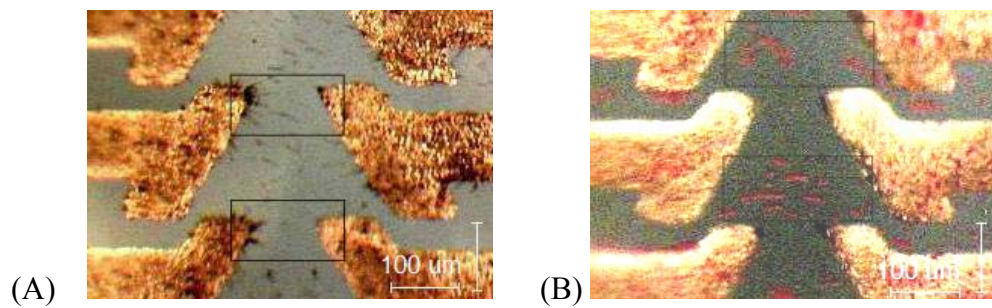


Figure 4.5. Images showing particle collection while subjected to an asymmetrical electric field,  $2 V_{\text{RMS}}$  at a frequency of 500 kHz. (A) Magnetite collection at the electrode tips under an induced positive dielectrophoretic moment. (B) Polystyrene spheres aggregating under negative dielectrophoresis in the low potential region of the ratchet geometry.



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**Chapter 5:**

**Evaluation of a ratchet type dielectrophoretic device**

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## Abstract

Dielectrophoresis is an electrokinetic phenomenon which utilizes an asymmetric electric field to separate analytes based on their polarizability relative to the polarizability of the suspending agent. One dielectrophoretic device geometry which offers interesting possibilities for particle transport without the use of external flow are ratchet devices. Shown are the initial tests of a novel electrode based dielectrophoretic ratchet type device geometry using a series of fine test particles. The asymmetrical electric field required to selectively transport target analytes has been produced for the first time using electroformed electrodes which offer the possibility of reducing convective heating and can be used to construct a device where all particles located within the fluidic channel are exposed to the applied field. Initial results of the examination of this device were conducted using fine particle test analytes to show selective particle collection and a separation based on the electrical properties of the analytes employed.

## 5.1 Introduction

The use of electrokinetic phenomena in the field of separations has seen increased use in the analytical laboratory. Electrokinetic separations offer the analyst the ability to conduct a separation based on the electronic state of an analyte while subjected to an electric field gradient. The electronic properties of an analyte exposed to an electrical field which can be exploited to conduct separations are charge to mass ratio and relative polarizability of an analyte. Electromechanical separation techniques used to harness the above mentioned electrical properties are electrophoresis and dielectrophoresis (DEP), respectively. As stated, electrophoretic separations are based on differences in the charge to mass ratios of the analytes being studied, and this makes electrophoresis applicable only to the separation of charged species. DEP, unlike electrophoresis, is applicable to neutral species because particles are separated by inducing a dipole moment in an analyte particle confined within an asymmetrical electric field. Since these separations are dependent on the polarizability of a suspended particle, the analyte being examined can be either neutral or charged.

The first investigations into conducting particle movement and separations of neutral species through induced dipoles in an asymmetrical field was Herbert Pohl [1,2]. In these studies, Pohl studied the motion of suspended polymer spheres in and organic medium, and found that particle migration in an asymmetrical field was dependent on the polarizability of the suspended polymers relative to the

polarizability of the suspending medium. He determined that particles more polarized than the suspending agent will collect in regions of high field intensity within the applied nonuniform field, positive DEP. For particles less polarized than the suspending medium, the particles were shown to collect in regions of low field intensity, negative DEP. These studies laid the groundwork for the field of dielectrophoresis which has been gaining popularity in recent years with the growing success of microfluidic devices.

Currently, two classes of microfluidic based dielectrophoretic devices have been successfully employed to create a nonuniform electric field. The first class of DEP devices in current use is known as insulator based dielectrophoresis [3-16]. Insulator based dielectrophoretic devices function by using insulators placed between a set of electrodes to produce the required nonuniform electric field. The second class of devices is electrode DEP devices, which utilize the electrode geometry to create the required asymmetrical field [17-47].

One device geometry which has been investigated in both electrode and insulator based devices is a ratchet geometry [16,48-51]. The theoretical aspects of ratchet mechanisms were first presented by Curie [52] and later Feynman [53], and by adapting these works the theoretical basis of dielectrophoretic ratchets was developed [54,55]. Ratchet based dielectrophoretic systems have been applied in the collection of particles under dielectrophoretic forces [16,48-51], and more



importantly, ratchet configurations offer the possibility of particle movement through the ratchet device without the use of an external agent (Brownian ratchets and stacked ratchets) [48-51]. Though ratcheting devices offer the possibility of particle movement without the need of an external force for electrode based systems, the relatively large surface areas used create sufficient thermal motion which counters the dielectrophoretic force exerted on a polarizable particle [51].

Presented is the initial study of a new ratchet type dielectrophoretic device containing ten independently addressable electroformed electrode pairs. Also presented is the first use of electroforming technology in the construction of DEP electrodes. For this study, a series of fine particles of known dielectric properties were utilized to theoretically determine their collection within an asymmetrical electric field. Test suspensions containing a single particle type were then examined to verify appropriate device operation by observing particle collection, relative to the theoretical expectation, within the asymmetrical electric. A particle test mixture was also examined to determine the feasibility in conducting a separation with this device geometry.

## 5.2 Theory

When a polarizable particle is subjected to an electrical field, a dipole moment will be induced in the particle regardless of whether it is charged or neutral [2,56]. If the electric field is asymmetrical a force imbalance will be exerted on the polarize

particle, which is the basis of dielectrophoretic separations. As a result of the imbalanced force, a polarized particle will move in accordance with its polarizability relative to the polarizability of the medium and the angular frequency of the applied potential [2,56]. A particle more polarized than the suspending medium will experience positive DEP and will migrate towards a region of high field intensity. When a particle is less polarized than the suspending media particle will collect in a region of lower field intensity via a negative dielectrophoretic moment [2].

The dielectrophoretic force experience by a polarized particle can be determined by:

$$F_{DEP} = 2\pi r^3 \text{Re}[K(\omega)] \nabla E_{rms}^2 \quad (2)$$

where  $r$  is the radius of a spherical particle,  $\nabla$  is the del vector operator, and  $E_{rms}$  is the root mean square applied electric field, and  $\text{Re}[K(\omega)]$  is the real component of the Clausius-Mossotti factor [56].

The  $\text{Re}[K(\omega)]$  accounts for the in-phase polarization of a suspended particle relative to the polarization of the suspending media, when using an AC waveform [32,56,57]. The  $\text{Re}[K(\omega)]$  is determined by taking the real component of the complex form of the Clausius-Mossotti factor:

$$K(\omega) = \frac{(\varepsilon_p^* - \varepsilon_m^*)}{(\varepsilon_p^* + \varepsilon_m^*)} \quad (3)$$

where  $\varepsilon_p^*$  and  $\varepsilon_m^*$  are the complex dielectric permittivities of the particle and medium, respectively. The complex dielectric permittivity for a particle or medium is found by  $\varepsilon^* = \varepsilon - j\sigma/\omega$  where  $\varepsilon$  is the dielectric permittivity,  $j$  is  $\sqrt{-1}$ ,  $\sigma$  is the conductivity, and  $\omega$  is the angular frequency of the applied electric field.

A derivation which shows the relation between  $\text{Re}[K(\omega)]$  and the frequency of the applied field is [58]:

$$\text{Re}[K(\omega)] = \frac{\varepsilon_p - \varepsilon_m}{\varepsilon_p + 2\varepsilon_m} + \frac{3(\varepsilon_m\sigma_p - \varepsilon_p\sigma_m)}{\tau_{MW}(\sigma_p - 2\sigma_m)^2(1 + \omega^2\tau_{MW}^2)} \quad (4)$$

where  $\tau_{MW}$  is the Maxwell-Wagner charge relaxation time given by  $\tau_{MW} = (\varepsilon_p + 2\varepsilon_m)/(\sigma_p + 2\sigma_m)$ , and accounts for the relaxation rate of free charges along the surface of an analyte particle while inducing a dipole moment. Calculations of the  $\text{Re}[K(\omega)]$  will have values in the range of -0.5 to +1.0 [56]. These values for the  $\text{Re}[K(\omega)]$  can be used to determine if a particle, of known electrical properties, will experience positive DEP (values greater than zero) or negative DEP (values less than zero) for a given suspending medium and frequency. Thus by solving for the  $\text{Re}[K(\omega)]$  using equation (4), an *a priori* approach can be taken to determine the frequency ranges a particle will experience positive or negative DEP.

### 5.3 Experimental

#### 5.3.1 Device Design and Description

The dielectrophoretic devices examined were constructed of two separate components. The first component was the electroformed nickel electrode features constructed on conductive seedlayer coated borosilicate glass slides. Electroforming was employed to fabricate the electrodes for two reasons. First, electroformed features can be placed within a microfluidic device to create channel walls composed of electrodes and thus reduce the electrode surface area in contact with the suspending media, which can reduce the possibility of conductive heating. Secondly by having a device with electrode walls, all analytes within the electrode region of the device will be exposed to the asymmetrical electric field thus creating the possibility of a more effective dielectrophoretic device. The second component of the device was a replica molded PDMS stamp patterned with negative images of the electroformed features and fluidic well located over the ratchet portion of the electrodes.

The geometry of the electroformed nickel electrode features produced on the glass slide is shown in figure 5.1. As shown in figure 5.1, each electrode component consisted of three main features: a square solder pad where electrical connections were made to a waveform generator, a ratchet type electrode feature for dielectrophoretic manipulation of test particles, and an electrical connector which

provided continuity between the solder pad and ratchet feature. All electrode features had final heights of 20 $\mu$ m and were 100  $\mu$ m wide, except solder pads which had widths of 2.5 mm. The offset between successive electrode pairs was zero. During operation, polarized particles located within the ratchet region of the device collected in regions A and B which correspond to positive DEP and negative DEP, respectively.

The fluidic component of this device was constructed of PDMS patterned with negative features of the electroformed features, and the only exception was that the resist features on the replica molding master encompassed the entirety of the ratchet feature region. Fluidic access into the ratchet region of the device was accomplished using a block magnet placed over the ratchet portion of the master to create a 1/8" by 1/16" rectangular well. The magnet was held in place by using a molding fixture constructed with a galvanized steel base. The use of magnets to serve as posts during replica molding was selected due to the ease of configuration created from magnetic forces and because of the variation of magnet geometries available which allowed for an array of post geometries [59].

### 5.3.2 Materials and Equipment

50 mm by 75 mm borosilicate glass microscope slides (VWR, West Chester, PA) were used as the substrates onto which the device electrodes were electroformed. 40 nm titanium and 50 nm copper conductive seedlayers needed during the

electroforming process were obtained through sputtering (Sulzer Metaplas Inc., Woonsocket, RI). Replica molding master substrates consisted of 3 inch radius mechanical grade silicon wafers (University Wafers, South Boston, MA). Technical grade solvents, acetone and methanol (Northwest Solvents, Eugene, OR), were used for substrate cleaning. Ultrapure water for rinsing and solution preparation was obtained from a Barnstead E-Pure system (Dubuque, IA).

The oxygen plasma etching system used for descumming substrate surfaces prior to lamination and electroforming was homemade and was constructed from a 6 inch x 10 inch 4-port stainless steel vacuum chamber from MDC Vacuum Products Corporation (Hayward, CA) and an Evactron Decontaminator RF Plasma Cleaner from XEI Scientific (Redwood City, CA).

20  $\mu\text{m}$  and 50  $\mu\text{m}$  thick Dupont MX-5000 series negative tone photoresists were used in constructing the replica molding masters and electrode features were purchased from MicroChem Corp. (Newton, MA). Resist lamination was accomplished using a homemade rolling pin constructed by inserting a glass rod into a piece of rubber tubing. A rubber squeegee was used to remove any resist imperfections resulting from the lamination process. Aluminum plates, one foot square by quarter inch thick (McMaster-Carr, Los Angeles, CA), were used as a press to improve resist adhesion to the substrate surface. Mylar transparencies used as masks during resist exposure were designed using AutoCAD 2007

(Autodesk, San Rafael, CA). The final Mylar transparencies were photoplotted by CAD/Art Services, Inc. (Bandon, OR). A homemade UV flood exposure system was constructed using an Oriel 6186 mercury arc lamp (Oriel Light Sources and Spectroscopy Instrumentation, Stratford, CT) and the UV light was directed towards the resist laminated substrate using a Durst 606 photo enlarger (locally purchased used). The Dupont D-4000 IC concentrated developer used to prepare the 0.75% aqueous resist developing solution was purchased from MicroChem Corp. Technical grade calcium carbonate (J.T. Baker, Phillipsburg, PA) was used to prepare an aqueous 300 ppm calcium carbonate developing rinsing solution. Spray development was accomplished using a Paschee VLS airbrush (Chicago, IL).

The PDMS fluidic component was produced using a Sylgard 184 silicone elastomer kit (Dow Corning Corp., Midland, MI). To create the fluidic well, a 1/8" x 1/8" x 1/16" neodymium block magnets (K&J Magnetics, Inc. Jamison, PA) were used as posts during PDMS replica molding to create a 1/8" x 1/16" rectangular fluidic well.

For creating the electroformed electrode features, mechanical agitation Nickel Sulfamate RTU plating solution and nickel anode were purchased from Technic Inc. (Anaheim, CA). Electroforming of the nickel electrodes was obtained through employment of a Dynatronix (Amery, WI) DuP 10-1-3 pulsed power supply. A

Veeco Dektak 8 Stylus Profiler fitted with a 12.5  $\mu\text{m}$  tip (Veeco Instruments Inc., Woodbury, NY) was used to determine the nickel plating rate. Photoresist removal upon electroforming of the nickel electrodes was accomplished using Dynasolve 2000 (Dynaloy Engineered Chemistries, Indianapolis, IN). Copper seedlayer removal was obtained using a ferric chloride solution purchased from MG Chemicals (Surrey, Canada). A 1:1 mixture of 5% hydrogen peroxide and 5% potassium hydroxide used to wet etch the titanium seedlayer, and both the hydrogen peroxide and potassium hydroxide (Mallinckrodt Chemicals, Phillipsburg, NJ) were reagent grade.

Alignment lubricant used to register the electrode and PDMS components was spectroscopic grade methanol (Mallinckrodt Chemicals, Phillipsburg, NJ). A Leica Wild Stereozoom microscope (Wetzlar, Germany) was used to visualize the registration between the device components. Test particles used to prepare test suspensions were  $\text{Fe}_3\text{O}_4$  (magnetite) with a size of 5  $\mu\text{m}$  or less (CERAC, Milwaukee, WI), and polystyrene spheres with 5  $\mu\text{m}$  diameters (Bangs Laboratories, Inc., Fishers, IN). ACS grade KCl (Mallinckrodt Chemicals, Phillipsburg, NJ) was used to adjust the conductivity of the suspending medium. Molecular biology grade polysorbate 20 (VWR International, West Chester, PA) was used as an additive in the suspending medium to reduce particle aggregation. A Zeiss Axiotron (Carl Zeiss MicroImaging, Inc., Thornwood, NY) equipped with a Sony Power HAD DXC-970MD camera (Sony Corporation, New York, NY) and



ImagePro Plus 6.0 (MediaCybernetics, Silver Spring, MD) was used for imaging particle collection during the experiments conducted. To energize the device electrodes, an Agilent 33220A function/arbitrary waveform generator (Santa Clara, CA) was employed. Verification of the amplitude and frequency of the sine wave being output by the function generator was accomplished with a DM 502A digital multimeter and DC504A counter timer produced by Tektronix (Richardson, TX).

### 5.3.3 Device Fabrication

As previously described, two key components will need to be constructed for the examination of this device. The first component fabricated is a glass slide containing the electroformed nickel electrode features, and the second portion of the device consisted of a fluidic component produced through replica molding of PDMS. The fabrication process used in the construction of the electrode and fluidic components is illustrated in figure 5.2, and described below.

#### *Resist Processing*

The electrode patterning and replica molding masters were both produced using dry film photoresist. Resist thicknesses employed were 20  $\mu\text{m}$  and 50  $\mu\text{m}$  to fabricate the replica molding masters and to pattern the conductive glass substrates, respectively.

The first step conducted in the film resist processing was lamination, which was carried out after the substrates were cleaned by rinsing with acetone, methanol, ultrapure water, drying with nitrogen gas, and then descumming with an oxygen plasma for 1 min at a chamber pressure of 200 mTorr and a power of 20 W. Lamination was then accomplished by laminating the film resist onto the substrate using a rolling pin. The resist was warmed on a 95 °C aluminum plate to soften the resist, and then a rubber squeegee was used to remove imperfections resulting during lamination. The laminated substrate was then pressed between two aluminum plates at 95 °C for a total of 30 s. A 20 min post lamination bake was conducted using a 65 °C oven, and then the laminated substrate was allowed to cool to room temperature in a dark drawer.

Resist exposure was conducted using Mylar transparencies and a UV flood exposure system. The masked resist was exposed to a UV flood exposure system for 1.5 min for the electrode patterning and 2 min for the replica molding master. A 25 min post exposure bake was then carried out using a shaded 85 °C hot plate.

0.75 vol. % D-4000 IC concentrated developing solution and an aqueous 300 ppm calcium carbonate solution, both warmed in a water bath to 45 °C, were used to develop and rinse the patterned resist. Resist development was conducted by soaking the resist laminated substrates in developing solution for 5 min, rinsing with carbonate rinsing solution, and then it was fully developed using an airbrush

operated at 12 psi. The fully developed resist was then rinsed and dried using carbonate rinsing solution, ultrapure water, dried with nitrogen gas, and post development baked on a 100 °C hot plate for 25 min.

#### 5.3.3.1 Electrode Fabrication

Electroforming of nickel electrodes was conducted using a mechanical agitation nickel sulfamate plating solution and the plating bath parameters were pH of 4, temperature of 49 °C, and it was agitated with a magnetic stir bar. The anode was covered with filter paper to minimize anode residues created during electroforming from contaminating the plating solution. Prior to electroforming, resist-patterned, seedlayer-coated glass slides were cleaned using in an oxygen plasma at 200 mTorr and 20 W for 1 min to descum and remove resist residues from the exposed copper seedlayers, rinsed with diluted detergent and ultrapure water to remove residual organics, and dipped into a 20 %  $\text{H}_2\text{SO}_4$  solution and ultrapure water rinsed to render the copper surface free of oxides. The cathode and anode were connected to their corresponding terminals and the nickel electrode features were grown at a rate of 0.4  $\mu\text{m}/\text{min}$  to a height of 20  $\mu\text{m}$ . The current density employed was 2.2  $\text{A}/\text{dm}^2$ , and the pulse rate was 1.5 ms on and 0.5 ms off. The electrodes were then electrically isolated by first removing of the resist using Dynasolve 2000, and then rinsing with acetone, methanol, and ultrapure water. The exposed seedlayers were wet etched using  $\text{FeCl}_3$  solution at 55 °C and a 1:1 solution of 5 % KOH and 5 %  $\text{H}_2\text{O}_2$  to remove the copper and titanium seedlayers, respectively.

### 5.3.3.2 PDMS Fluidic Component

The PDMS fluidic component was produced through replica molding using a master consisting of a resist patterned silicon wafer. The final PDMS stamp contained negative features of the solder pads and electrical connects between the solder pads and ratchet portion. A well allowing fluidic access to the ratchet portion of the device was incorporated into the resulting PDMS slab. To produce the fluidic well, a magnet serving as a post during casting was used in conjunction with a molding fixture containing a galvanized steel base. PDMS was then prepared by mixing the elastomer and crosslinker in a 10:1 ratio, degassing in a vacuum desiccator, poured over the master, and cured in a 95 °C for 1 hr. The magnetic post was then removed prior to peeling the PDMS from the master. The cured PDMS slab was then trimmed to contain only the fluidic well and electrical connectors between the ratchet features and the solder pads. The PDMS meniscus around the well was trimmed using a razor blade to create a flat surface onto which to place a glass cover slide.

### 5.3.3.3 Device Assembly

To create electrical connections to the waveform generator, rosin core lead solder was placed onto nickel solder pads after covering all other electroformed features with a piece of foil to prevent flux and solder contamination during soldering. The PDMS fluidic component and electrode component were mated using a

previously described process used to align oxygen plasma activated PDMS surfaces [60]. The method used an organic solvent as a lubricant which preserved the oxygen plasma activated PDMS surfaces required to create an irreversible seal between the PDMS components. In this case methanol was used as a lubricant, as only a conformal seal is required. The alignment was accomplished by placing a few drops of methanol onto the surfaces being mated together, and then using a microscope the components were appropriately registered. The methanol was then evaporated by placing the assembly in a 95 °C oven. The fluidic well was then capped using a microscope cover glass to reduce evaporation of the suspending media. The final device containing the registered electrode and fluidic components is shown in figure 5.3.

#### 5.3.4 Device Setup and Examination

The final device was connected to a function generator capable of energizing the electrodes with a sine waveform with an amplitude  $7 V_{\text{rms}}$  and a frequency of 20 MHz, via electrical leads soldered to the nickel solder pads located onto the glass slide. The amplitude and frequency of the sine wave applied to the device electrodes was verified using a digital multimeter and counter/timer. Electrode pairs were divided into groups using an on/off switch to selectively energize desired ratchet pairs. Optical observations were made using a microscope equipped with video capture software to image regions of particle collection.

In selecting the test particles to verify appropriate device function in collecting particles in the field maxima and minima an *a priori* approach was taken by calculating  $\text{Re}[K(\omega)]$ , using equation 4, for particles of known dielectric properties. From these calculations magnetite and polystyrene were selected because magnetite would experience positive DEP ( $\text{Re}[K(\omega)] > 0$ ) and polystyrene would undergo negative DEP ( $\text{Re}[K(\omega)] < 0$ ). A visual representation of  $\text{Re}[K(\omega)]$  as a function of frequency for magnetite and polystyrene in 110  $\mu\text{S}/\text{cm}$  water is shown in figure 5.4. The dielectric properties of the particles and medium used in generating figure 5.4 are listed in Table 3 [61,62].

Using magnetite particles and polystyrene spheres, three separate test particle solutions were prepared with an aqueous suspending medium consisting of ultrapure water, 1% polysorbate-20, and a final KCl adjusted conductivity of 110  $\mu\text{S}/\text{cm}$ . Appropriate particle collection was conducted using test suspensions containing only one particle type, and the concentrations for each of these suspensions were 0.02 w/v % magnetite and 0.0076 w/v % polystyrene latex spheres. The third suspension consisted of 0.02 w/v % magnetite and 0.0076 w/v % polystyrene latex spheres, to test the feasibility of separating a sample mixture. Prior to use, samples were sonicated for 5 min to break up particle aggregates and vortex mixed to create a uniform suspension. 5  $\mu\text{L}$  sample aliquots were pipetted into the fluidic well and capped with a glass microscope cover glass.

To verify the expected results from calculating  $\text{Re}[K(\omega)]$  as shown in figure 5.4, the single particle test suspensions were studied by energizing the electrodes using a sine waveform with an amplitude of  $2 V_{\text{rms}}$ . The samples were studied over a frequency range of 1 kHz to 20 MHz to verify that the magnetite particles and polystyrene spheres underwent positive DEP and negative DEP, respectively. Frequencies below 1 kHz were not studied because water electrolysis was a common occurrence. Once it was established that the particles collected in the desired regions, the test mixture was studied using a sine waveform with an amplitude of  $2 V_{\text{rms}}$  and a frequency of 500 kHz

#### 5.4 Results and Discussions

From the plot of  $\text{Re}[K(\omega)]$  as a function of frequency, figure 5.4, it was expected that the magnetite particles would experience positive DEP and the polystyrene spheres would undergo negative DEP. To verify that this device would collect the test particles in the appropriate regions, the single particle test suspensions were examined using AC waveforms with amplitudes of  $2 V_{\text{rms}}$  and frequencies in the range of 1 kHz to 20 MHz. From these examinations, it was found that the magnetite particles underwent positive DEP over the entire frequency range, and the polystyrene spheres experience negative DEP over the frequency range studied. Figure 5.5 shows a representative image of the magnetite particles collecting in pearl chains under positive DEP along the field maxima regions and the polystyrene spheres aggregating under negative DEP at the field minima

regions for an applied AC waveform  $2 V_{\text{rms}}$  and 500 kHz. These findings verify two items. First, the *a priori* approach in selecting test analytes was valid for the particles selected. Secondly, this ratchet type dielectrophoretic device is capable of collecting polarizable particles based on the dielectric properties of the test analytes employed.

Once it was established that the particles collected in the expected regions of the asymmetrical electric field, the test mixture containing both magnetite particles and polystyrene spheres was studied to test for the feasibility of conducting a separation using this device. For this portion of the experiment, the test mixture was studied by energizing the ratchet electrodes using a sine waveform with an amplitude of  $2 V_{\text{rms}}$  and frequency of 500 kHz. As with the single particle test suspensions, particles were found to collect in the desired regions. Magnetite particles collected in the high field regions under positive DEP and polystyrene spheres aggregated in the low field regions through negative DEP. Figure 5.5D is an image showing a separation of the magnetite/polystyrene mixture. This result shows that it is possible to selectively collect particles from a mixture into individual components, and as with the single particle test mixtures, these findings are also consistent with the theoretical expectations determined by calculating  $\text{Re}[K(\omega)]$ .



For experiments conducted using magnetite particles two observations were noticed, which were not encountered for studies conducted with polystyrene spheres. First, it was found that these particles collected at the high field regions of unenergized electrode sets. Secondly, the magnetite particles collected on the surface of the glass substrate in the lower field regions of the ratchet geometry.

The collection of particles along the unenergized electrodes is believed to be caused by the high conductivity of magnetite, 1000 S/cm, which provided electrical continuity between the energized and unenergized electrodes. To verify if the magnetite particles were providing continuity, a digital multimeter and timer/counter were used to determine if the energized and unenergized electrode pairs were being energized while applying an AC waveform to selected electrodes. It was found from the digital multimeter and timer/counter measurements that all electrode pairs were energized alike. The same procedure was conducted for the clean polystyrene suspension, and it was determined that the unenergized electrodes remained unenergized. These findings lead us to believe that the magnetite particles are responsible for all electrode pairs being energized.

The magnetite particle collection along the surface of the glass substrate is most likely due to settling effects, figures 5.5.B and 5.5.D. At this time, the settling effect is believed to be caused by the specific density of the magnetite particles, 5.18 g/cm<sup>3</sup> (obtained from the product MSDS), which may result in gravitational

and frictional forces that counter the dielectrophoretic force. To counter the problems encountered using magnetite particles a surrogate test particle will need to be found, which is less conductive and has a lower specific gravity than magnetite. One possibility are surface modified submicrometer latex spheres, which have been shown to collect under positive or negative DEP depending on the particle type, suspending medium, and applied field [19,20,28].

### 5.5 Conclusions

Presented in this work was the initial evaluation of a new ratchet type dielectrophoretic device for conducting separations based on the dielectric properties of suspended particles. Electroforming was selected to manufacture the device electrodes because electroforming provides the opportunity to impart a dielectrophoretic force to all analytes located within a fluidic device by allowing for the construction of devices with electrodes comprising channel walls. In manufacturing the electrodes for this device, we have successfully shown for the first time that electroforming is a possible method for producing the electrodes needed to produce the asymmetrical electric field in a DEP device. This ratchet device was successfully tested by collecting and separating a series of magnetite and polystyrene test particle suspensions, which collected in the asymmetrical field regions dictated by the real component of the Clausius-Mossotti, equation 4. Future studies include modeling of the asymmetric field, investigations into

conducting ratcheting mechanisms, and implementation of a dielectrophoretic device with channel sidewalls comprised of electroformed electrodes.

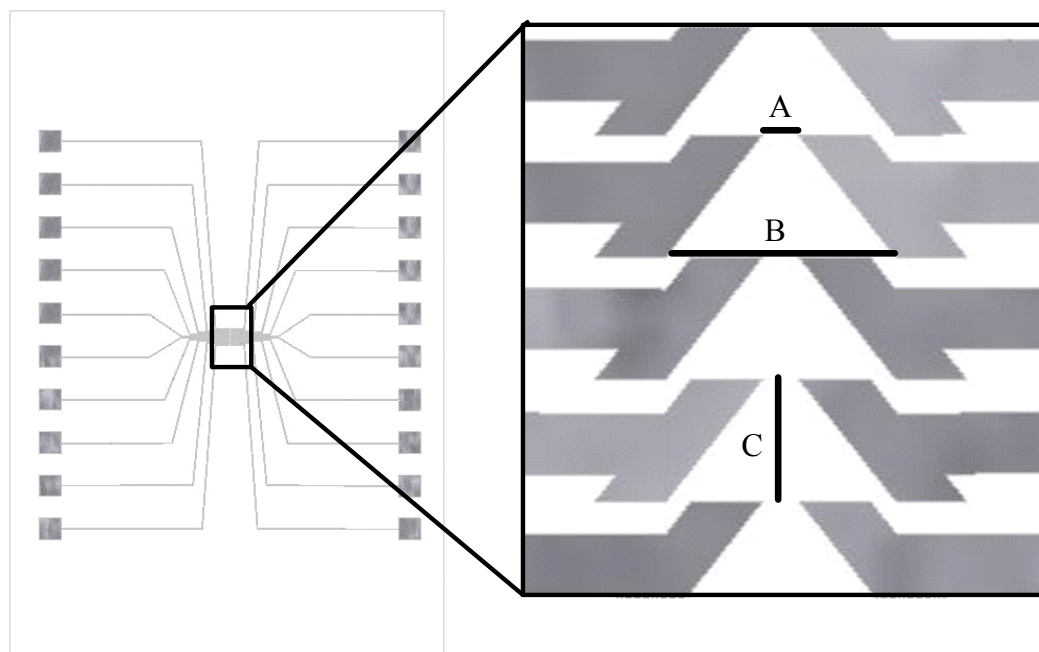
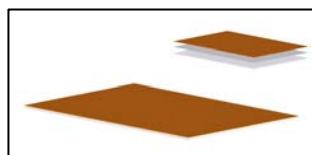
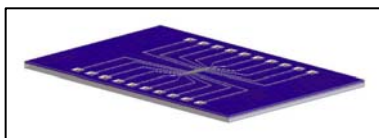
**Figures**

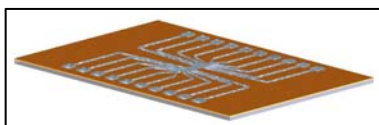
Figure 5.1. Illustration showing the entire the electrode array and an expanded view of the ratchet region. Electrode features contained include a square solder pad, ratchet type electrode features, and an electrical lead connecting the solder pad and ratchet feature. Dimensions for regions A, B, and C are 50  $\mu\text{m}$ , 325  $\mu\text{m}$ , and 200  $\mu\text{m}$ .

**(A) Electrode Array Fabrication**

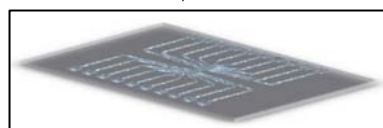
(1) Ti then Cu Sputtered Glass slide



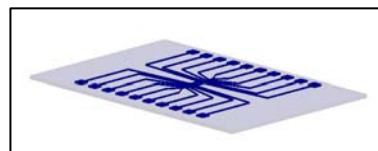
(2) Dry film resist for electrode patterns



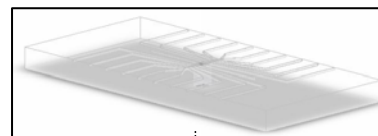
(3) Electroforming/Resist removal



(4) Ni electrodes on glass (Cu, Ti stripped)

**(B) Fluidic Layer Fabrication**

(1) Master fabrication



(2) PDMS replica for fluidic layer

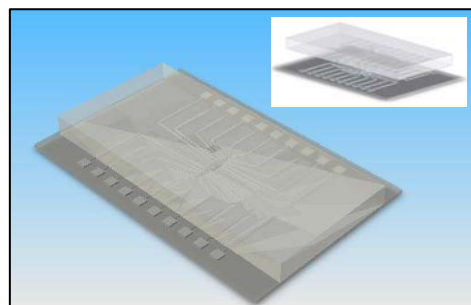
**(C) Assembled Microchip with PDMS Fluidic Layer and electrode array**

Figure 5.2. Schematic outline of the fabrication process used to construct the dielectrophoretic device. (A) Electrode array fabrication: (1) titanium and copper seedlayers sputtering, (2) resist patterning, (3) electroforming of nickel electrodes and resist removal, and (4) removal of exposed seedlayers via wet etching. (B) Fluidic layer fabrication: (1) master constructed using dry film resist and a silicon wafer, and (2) replica molded PDMS containing negative features of the patterned film resist. (C) Mated electrode array and PDMS fluidic component.

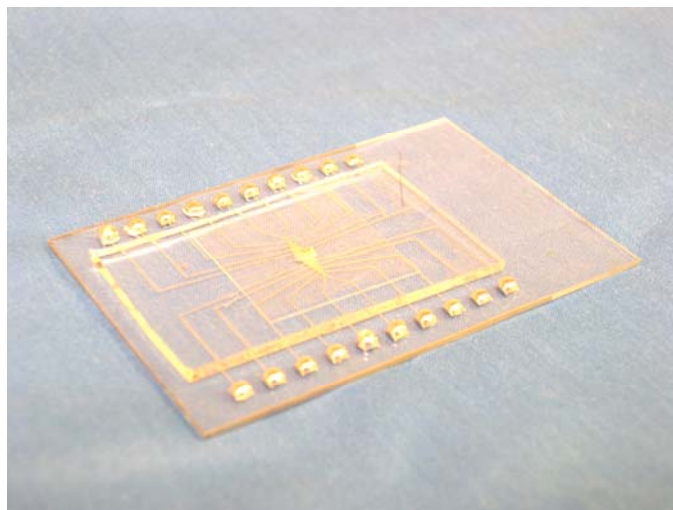


Figure 5.3. Photograph of assembled device consisting of an electrode array, fluidic layer, and microscope cover glass.

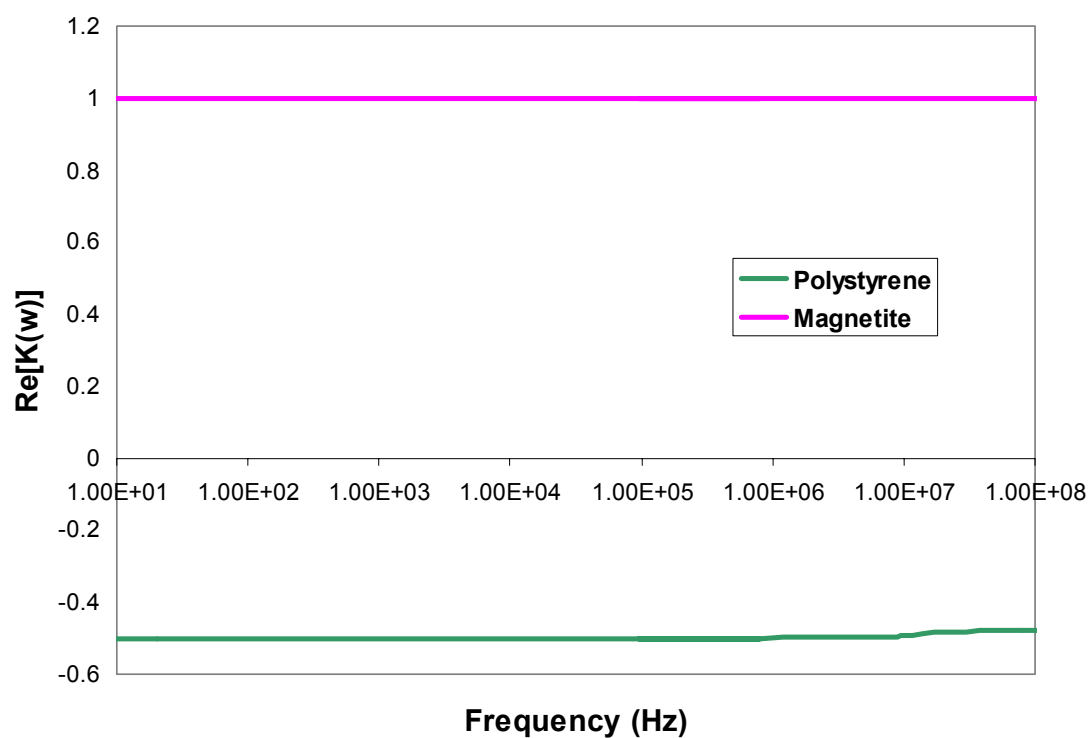


Figure 5.4. Real component of the Clausius-Mossotti factor ( $\text{Re}[K(\omega)]$ ) over the frequency range studied for magnetite and polystyrene.

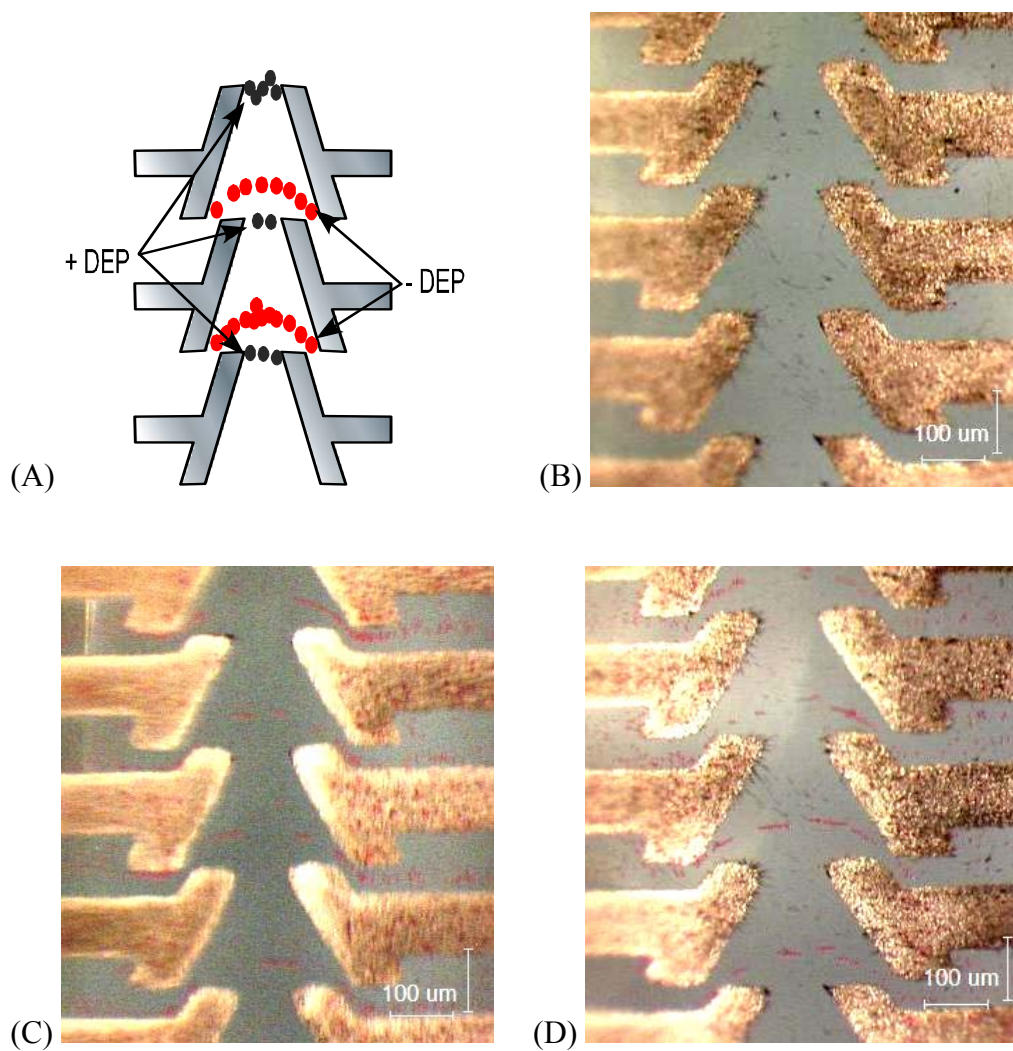


Figure 5.5. Images for experiments conducted using magnetite particles and polystyrene spheres at  $2 V_{\text{rms}}$  and 500 kHz. (A) Magnetite particles collecting at the regions of high field intensity under positive DEP. (B) Polystyrene spheres aggregating under negative DEP in regions of low field intensity. (C) Separation of a magnetite/polystyrene mixture.



## Tables

**Table 3. Dielectric Properties of Test Particles and Media**

	Magnetite	Polystyrene	Water
Dielectric Constant	14.2	2.5	78.5
Conductivity (S/cm)	$10^4$	$10^{-18}$	$1.1 \times 10^{-4}$

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## **Chapter 6: Conclusions**

Two goals comprised the research efforts of this dissertation. The first goal was to develop the fabrication methodologies necessary in constructing microfluidic devices. The second aim was to develop a novel microfluidic dielectrophoretic device to conduct separations of neutral materials.

As detailed in the introduction, several microfluidic based dielectrophoretic devices exist. Each of these designs operates through the use of an asymmetrical electric field to collect particles under positive DEP or negative DEP depending on the polarizability of the analyte relative to the polarizability of the media. The asymmetrical fields used in these devices can be created through the use of electrodes or insulators. Commonly used chip based DEP device geometries are parabolic electrodes, castellated electrode, electrode arrays, and insulator based geometries. A device geometry which has seen limited use in the field of DEP is ratchet based systems because of thermal effects which counter the dielectrophoretic force.

As stated in chapter 2, ratchet systems allow for the collection of particles under +DEP and -DEP, and at the same time create interesting possibilities for particle movement without the use of an external flow. We felt the particle collection and transport possibilities available with a ratchet design warranted an investigation into designing a novel ratchet type device. In developing the device, we decided a possible way to optimize the ratchet electrode geometry was to make each ratchet



portion a separate set of electrodes. This alteration creates the possibility of energizing each set of electrodes independently. We also felt that electroforming, a method never previously used in the fabrication of DEP electrodes, would offer the possibility to create a device with electrodes spanning the entire height of the fluidic device. We felt if these electroformed electrodes were to be embedded into a microfluidic device a more thorough dielectrophoretic investigation of a sample located within a fluidic channel could result. This is because all analytes will be exposed to the asymmetrical field and a dielectrophoretic force will be experienced by all polarizable compounds.

Initial attempts in creating the electroformed electrodes for this ratchet type device were conducted using SU-8 photoresist to pattern a conductive seedlayer coated glass slides prior to electroforming the nickel features. We selected SU-8 because of our experience in using this product to create masters for molding soft polymer devices. SU-8 ultimately was found not to be a viable option for the following reasons. First, adhesion issues between the copper seedlayer and the SU-8 were a recurring issue even with the use of adhesion promoters. These adhesion issues allowed the nickel to plate under the resist resulting in continuity between successive electrode sets. Secondly, the SU-8 processing method changed on a daily basis due to the temperature and humidity instabilities of our fabrication facilities.

Due to the problems experienced using SU-8, we decided to investigate the use of a film resist in creating our feature patterning. The film resist selected was a DuPont MX-5000. This product was selected because it was a negative tone resist which allowed us to use the same photomasks employed during our attempts in patterning with SU-8. Also, this product uses aqueous developing and rinsing solutions, versus the organic developer and rinsing solvent used for SU-8, which eliminates the creation of organic waste. The film resist was found to a viable alternative to SU-8 because of the improved adhesion between the resist and the substrate surface.

The electroforming process was conducted using a mechanically agitated nickel sulfamate plating solution, and not the air agitated formulation because of the pitting observed on the electrode surfaces via the agitation method. The electroformed features were electrically isolated by removal of the resist using an epoxy stripper, Dynasolve 2000. The un-plated regions of the conductive seedlayers were then removed using wet etching technology to successfully fabricate the electroformed electrodes. The etching solutions found not to greatly impact the electroformed nickel features were  $\text{FeCl}_3$  and a 1:1 mixture of 5 % KOH and 5 %  $\text{H}_2\text{O}_2$ , for removal of the copper and titanium seedlayers respectively.

The device was examined for appropriate operation using magnetite particles and polystyrene latex spheres. These particles were selected as the magnetite is expected to experience +DEP and polystyrene should undergo –DEP, as expected from the real component of the Clausius-Mossotti calculations. Test suspensions of these particles were examined and the test particles were found to collect in the desired region of the asymmetrical field produced by this ratchet configuration. The magnetite particles collected at the regions of highest field strength under +DEP, and the polystyrene spheres experienced –DEP and aggregated in the low field regions. These findings were found to be consistent with the calculated results of the real component of the Clausius-Mossotti factor, which leads us to believe that the device is operating as expected. A test mixture containing magnetite and polystyrene was also examined to determine the feasibility of conducting a DEP separation using this device. For this simple two component mixture the device was capable of separating the mixture into individual components.

The final electroformed device was shown to operate as expected in collecting particles under +DEP and –DEP. This novel ratchet device was fabricated using manufacturing capabilities which were brought to our research group as a result of this research effort. We also demonstrated, for the first time in the field of DEP, the use of electroformed electrodes to create the asymmetrical electric field required for dielectrophoretic manipulation of neutral particles.

Using this device, it was shown it is possible to selectively collect neutral particles based on the dielectric properties of the test analytes employed. Future studies to be conducted will be to investigate if it will be possible to operate this DEP ratchet type design in a stacked ratchet mode, as described in chapter 2. To accomplish this task, the electrode spacing between successive electrode sets will need to be determined such that the electric field of adjacent electrode sets overlap. This electric field overlap will ensure a dielectrophoretic force will be exerted on the collected particles and should allow for movement (ratcheting) of particles. To determine the required electrode distances, computer modeling will need to be employed to visualize the electric field.

Though much work will need to be conducted in order to obtain a ratchet device which moves particles through a fluidic device without the use of external flow, we feel that this geometry will have positive effects in the field of electokinetics, microfluidics, and  $\mu$ -TAS. By providing a means to selectively transport analytes through a device based on their dielectric properties the cost and use of external flow sources, such as pumps, will be eliminated.