AN ABSTRACT OF THE THESIS OF

<u>SUEY-HUEY TARNG</u> for the degree of <u>DOCTOR OF PHILOSOPHY</u> in <u>STATISTICS</u> presented on <u>March 6, 1980</u> Title: <u>ESTIMATION OF THE POPULATION TOTAL WHEN THE SAMPLE IS TAKEN FROM A</u>

LIST CONTAINING AN UNKNOWN AMOUNT OF DUPLICATION Abstract approved: Redacted for privacy

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A frame contains a known number, N, of units, but the units are grouped into an unknown number of M distinct classes. A measurement y_j is associated with each class, and, based on the information obtained from a simple random sample of units from the frame, we wish to estimate the population total, $\sum_{j=1}^{M} y_j$, without knowing M. Several researchers have proposed methods for estimating M based on a sample. In this thesis five of these methods are generalized to obtain estimates of the population total. Estimation of The Population Total When The Sample Is Taken From A List Containing An Unknown Amount of Duplication

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TABLE OF CONTENTS

CHAPTER	P	AGE
1	INTRODUCTION	1
	1.1 Notation	3
2	GOODMAN'S METHOD	6
	2.1 Introduction	6
	2.2 Derivations	6
	2.3 Discussion	11
	2.4 Example	12
3	GOOD AND TOULMIN'S METHOD	14
	3.1 Introduction	14
	3.2 Estimation of the Total Measurement	
	$M_{\substack{\Sigma \\ j=1}} y_j \dots \dots$	15
	3.3 Variance of the Estimate of $\sum_{j=1}^{M} y_j \dots y_j$	17
	3.4 Summation of the Series	22
	3.5 Example	27
4	HARRIS' METHOD	30
	4.1 Introduction	30
	4.2 Derivations	31
	4.3 Example	37
5	GOOD AND RAO'S METHOD	10
	5.1 Introduction	40
	5.2 Derivation of Ml	41

<u>CHAPTER</u>

	5.2.1 P	Seudo Metho and β .	od of Mo	ment:	s for 	Es	tima	ati:	ng	•	42
	5 .2.2 V	'arianc <mark>e</mark> of	Σy _j . j=1	•••	••	• •	•	• •	•	•	43
5.3	Example	of Ml		••	• •	••	•	•••	•	•	46
5.4	Derivati	ion of M2 .	• • • •	••	••	• •	•	• •	•	•	47
	5.4.1 P α	seudo Metho and β	od of Mo	ment:	s for	Es	tima	ati	ng •	•	48
	5.4.2 V	ariance of	Σy.: j=1 ^j	•••	•••	• •	• •	• •	•	•	48
5.5	Example	of M2		• •	• •	••	• •	•	•	•	54
EFRON AND THISTED'S METHOD 61					61						
6.1	Introduc	tion	• • • •	•••	• •	••	• •	•	•	•	61
6.2	Nonparam	etric Model		• •	••	•••	• •	•	•	•	62
6.3	Parametr	ic Model Ga	amma Dis	tribı	ution	•		•	•	•	64
	6.3.1 E	xample .		••	••	••	• •	•	•	•	65
6.4	Euler's	Transformat	ion	• •		•••	• •	•	•	•	67
	6.4.1 N	onparametri	c Estim	ator	for	∆ (t).	•	•	•	67
	6.4.2 P	arametric E	stimato	r for	r∆(t).	• •	•	•	•	68
	6.4.3 E	xample	••••		• •	•••	•••	•	•	•	68
6.5	The Bias	of $\hat{\Delta}(t)$.		• •	•••	• •	•••	•	•	•	74
	6.5.1 E	xample	• • • •		• •	•••	• •	•	•	•	78
SUMM	ARY	• • • • •	• • • •	• •	• •	••	• •	•	•	•	83

PAGE

6

7

ESTIMATION OF THE POPULATION TOTAL WHEN THE SAMPLE IS TAKEN FROM A LIST CONTAINING AN UNKNOWN AMOUNT OF DUPLICATION

CHAPTER 1

INTRODUCTION

The problem considered here arose in connection with a sample survey of the owners of fishing licenses. The objective of the survey was to estimate the total number of fish caught. A list of fishing licenses was available from which to select a sample, but since it is possible for one individual to buy more than one license, the same fisherman could appear two or more times in the list. The presence of an unknown amount of duplication causes much difficulty. Two distinct conditions exist. One can either determine how many licenses each person in the sample has, or this cannot be determined. The estimate of the total number of fish caught for the first condition was obtained by Rao [14]. We shall consider only the estimation of the total number of fish caught for.

In an abstract setting, there is a list of a known number, N, of units (licenses) which is subdivided into an unknown number, M, of distinct classes, C_j , j=1, 2, ..., M (each fisherman represents a class of licenses). If the number of units in a class is R_j , then $\sum_{j=1}^{N} R_j = N$. The class of a unit is readily identifiable when the unit is examined. To each class, a measurement, y_j , (the number of fish caught by the fisherman) is associated. From a sample of size n, we wish to estimate the total of these measurements, $T = \sum_{j=1}^{M} y_j$, without knowing the R_j values j=1 for units in the sample. Several researchers have proposed methods for estimating the total number M of distinct classes. In this thesis we

generalize five of these methods to obtain estimates of the population total, T. Note that in the special case when $y_j = 1$ for all j, the total is simply M.

The statistical methods used in this study can be classified as follows:

(A) Nonparametric models

(a) Sampling without replacement - Goodman's Method
 Goodman offered an unbiased estimate of the total
 number M of distinct classes. In this thesis we generalize his estimate to find the unbiased estimate of the population total, T.

 (b) Sampling with replacement - Good and Toulmin's Method, Harris' Method, and one of Efron and Thisted's Methods Good, Toulmin, Efron, and Thisted obtained reasonable estimates of the total number M of distinct classes. Harris found approximations to the supremum and infimum

of these estimates. We generalize these results to find estimates of the population total and approximations to the supremum and infimum of the estimates.

(B) Parametric Models

Sampling with replacement - Good and Rao's Method and one of Efron and Thisted's Methods

2

Good, Rao, Efron, and Thisted found reasonable estimates of the total number, M, of distinct classes by assuming gamma and/or beta distribution. We generalize these estimates to obtain estimates of the population total.

The performance of each method was tested on a set of simulated data.

1.1 Notation

We define the following notation:

the list size
the number of distinct classes of the list
the jth class (j=1, , M)
the measurement of the jth class
the total of the measurements of all classes
the number of units in the jth class
the maximum number of units contained in any class,
i.e., q = max R _j
j=1, , M
the collection of indices of all the classes consisting
of ℓ elements, i.e., $J_{\ell} = \{j:R_j=\ell\}$
the number of units in the jth class showing in the
sample
$y_{j}I_{\{r\}}(X_{j})$ where I(.) is the indicator function
${ t y}_{{ extbf{j}}}$ if the jth class has r units in the sample
0 otherwise

M (r) Hence $\sum_{j=1}^{\Sigma} Z_j$ is the total of the measurements of all the classes

having r units in the sample.

$$\delta_{j} = \begin{cases} 1 & \text{if the jth class shows in the sample} \\ 0 & \text{otherwise} \end{cases}$$

$$Y_{j} = \delta_{j} y_{j} = \begin{cases} y_{j} & \text{if the jth class shows in the sample} \\ 0 & \text{otherwise} \end{cases}$$

$$T_{s} = \sum_{j=1}^{N} Y_{j} = \sum_{r=1}^{N} \sum_{j=1}^{N} z_{j} z_$$

T': the total of the measurements of all the units of the

list, i.e.,
$$T' = \sum_{j=1}^{M} R_j y_j$$

 T_{s}^{i} : the total of the measurements of the units of the

sample, i.e.,
$$T'_{s} = \sum_{r=1}^{n} r \begin{pmatrix} M & (r) \\ \sum Z_{j} \\ j=1 \end{pmatrix}$$

 $d_i: \qquad \mbox{unit i of the random sample for i=1, ..., n} \\ P_j: \qquad \mbox{the probability that the ith unit of the sample is} \\ \mbox{in the jth class, i.e., } P_j = P_r\{d_{i\epsilon}C_j\} > 0 \mbox{(not} \\ \mbox{depending on i)}$

We regard the random sample of size n as being the basic sample. We imagine a second hypothetical sample of size tn. Since the estimates of the population total based on Good and Toulmin's method, Harris' method, and Efron and Thisted's method are the prediction of the population total that will be observed in the second sample of size N where t = $\frac{N}{n}$, we need the following notation: $X_{i}^{(t)}$: the number of units of the jth class showing in the

second sample of size tn $Z_{i}^{(r)}$ (tn) = $y_{j}I_{\{r\}}(X_{j}^{(t)})$ $= \begin{cases} y_{j} & \text{if the jth class has r units in the sample of size} \\ 0 & \text{otherwise} \end{cases}$

Hence $\sum_{j=1}^{M} Z_{j}^{(r)}$ (tn) is the total of the measurements of all the

classes having r units in the sample of size tn.

$$\delta_{j}^{(t)} = \begin{cases} 1 & \text{if the jth class shows in sample of size tn} \\ 0 & \text{otherwise} \end{cases}$$

$$Y_{j}(tn) = y_{j}\delta_{j}^{(t)} = \begin{cases} y_{j} & \text{if the jth class shows in the sample of size tn} \\ 0 & \text{otherwise} \end{cases}$$

Hence $\sum_{j=1}^{M} Y_j(tn) = \sum_{r=1}^{n} \sum_{j=1}^{M} Z_j^{(r)}(tn)$ is the total of the measure-

ments of all the classes in the second sample.

CHAPTER 2

GOODMAN'S METHOD

2.1 Introduction

In this chapter the sampling is done without replacement.

Goodman [8] offered the unbiased estimator $\sum_{i=1}^{n} A_i f_i$ of the total number M of distinct classes, where $A_i = 1 - (-1)^i \frac{[N - n + i - 1]^{(i)}}{n^{(i)}}$, $a^{(t)} = \begin{cases} a(a-1) \dots (a-t+1) & \text{for } t > 0 \\ 1 & \text{for } t = 0 \end{cases}$ and $f_i = \text{the number of classes}$

containing i units in the sample. Knott [13] showed that by considering a second sample of size tn = N he got the same unbiased estimator of M. We generalize their results to find an unbiased estimator of the total

 $T = \sum_{j=1}^{M} y_j$. The unbiased estimator is $\sum_{r=1}^{n} A_r \begin{pmatrix} M & (r) \\ \sum Z_j \\ j=1 \end{pmatrix}$.

2.2 Derivations

In order to find the unbiased estimator of T = $\sum_{j=1}^{M} y_j$ we need:

Assumption: The sample size n is not less than the maximum number, q, of individuals contained in any one class.

This assumption is reasonable for our practical problems.

Lemma 2.1:
$$E\begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \\ j=1 \end{bmatrix} = \sum_{\substack{\ell=r \\ \ell = r}}^{q} \frac{\binom{\ell}{r}\binom{N-\ell}{n-r}}{\binom{N}{n}} \binom{\Sigma & y_{j}}{j \in J_{\ell}}$$

Proof:
$$E\begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \end{bmatrix} = \frac{M}{j=1} y_{j} E\begin{bmatrix} I_{\{r\}}(X_{j}) \end{bmatrix} = \frac{M}{j=1} y_{j} \frac{\binom{R_{j}}{r} \binom{N-R_{j}}{n-r}}{\binom{N}{n}}$$
$$= \frac{q}{R_{j}=r} \frac{\binom{R_{j}}{r} \binom{N-R_{j}}{n-r}}{\binom{N}{n}} \binom{\Sigma}{j^{\varepsilon} J_{R_{j}}}$$

Using this lemma we obtain an unbiased estimator of T in the following theorem.

Theorem 2.1: Let
$$A_r = 1 - (-1)^r \frac{[N - n + r - 1]^{(r)}}{n^{(r)}}$$
,
where $a^{(t)} = \begin{cases} a(a-1) \dots (a-t+1) & \text{for } t \ge 0\\ 1 & \text{for } t = 0 \end{cases}$.
Then $E\left[\sum_{r=1}^{n} A_r \begin{pmatrix} M & (r)\\ j=1 & Z_j \end{pmatrix}\right] = \sum_{j=1}^{n} y_j$.
Proof: $E\left[\sum_{r=1}^{n} A_r \begin{pmatrix} M & 2 \\ j=1 & Z_j \end{pmatrix}\right] = \sum_{r=1}^{n} A_r E\left[\sum_{j=1}^{M} Z_j^{(r)}\right]$
 $= \sum_{r=1}^{n} \left[1 - (-1)^r \frac{[N - n + r - 1]^{(r)}}{n^{(r)}}\right] \left[\sum_{\ell=r}^{q} \frac{\binom{\ell}{r} \binom{N-\ell}{n-r}}{\binom{N}{n}} \sum_{j \in J_q} y_j\right]$
 $= \sum_{\ell=1}^{q} \left[\sum_{j \in J_q} y_j\right] \left[\sum_{r=1}^{\ell} \left(1 - (-1)^r \frac{[N - n + r - 1]^{(r)}}{n^{(r)}}\right) \frac{\binom{\ell}{r} \binom{N-\ell}{n-r}}{\binom{N}{n}}\right]$
 $= \sum_{\ell=1}^{q} \sum_{j \in J_q} y_j = \sum_{j=1}^{M} y_j$ by lemma 2 of [8].

An alternative derivation of the result in Theorem 2.1 can be obtained as follows: Theorem 2.2: Suppose the statistics W_1 , W_2 , ..., W_n are the solution of the system of linear equations

$$\sum_{j=1}^{M} Z_{j}^{(r)} = \sum_{\ell=r}^{n} \frac{\binom{\ell}{r} \binom{N-\ell}{n-r}}{\binom{N}{n}} W_{\ell} \text{ for } r = 1, 2, ..., n.$$

Then $E(W_{\ell}) = \sum_{j \in J_{\ell}} y_{j}.$

Proof: The same proof as Theorem 4 of [8].

Therefore $\sum_{\ell=1}^{n} W_{\ell}$ is an unbiased estimator of T.

There always exists a unique solution of the system of linear equations in Theorem 2.2 since the determinant of the coefficients of W_{g} , $l=1, \ldots, n$ is not equal to zero. The following theorem shows that

 Σ^n & W is an unbiased estimator of T', the sum of the measurements of $\mathfrak{L}=1$

all the units of the list.

Theorem 2.3: If W_1 , ..., W_n are as in Theorem 2.2,

Then
$$E\left(\sum_{\substack{k=1\\ k=1}}^{n} \& W_{k}\right) = T'$$
.

Proof: Recall T'_S , the sum of the measurements of the units of the sample, and note that

$$T_{s}^{i} = \sum_{r=1}^{n} r \left(\sum_{j=1}^{M} Z_{j}^{(r)} \right)$$
$$= \sum_{r=1}^{n} r \left[\sum_{\ell=r}^{n} \frac{\binom{\ell}{r} \binom{N-\ell}{n-r}}{\binom{N}{n}} W_{\ell} \right]$$

$$= \sum_{\ell=1}^{n} W_{\ell} \left[\sum_{r=1}^{\ell} r \frac{\binom{\ell}{r} \binom{N-\ell}{n-r}}{\binom{N}{n}} \right]$$
$$= \frac{n}{N} \sum_{\ell=1}^{n} \ell W_{\ell} .$$
Thus $\sum_{\ell=1}^{n} \ell W_{\ell} = \frac{N}{n} T'_{s}$, so
$$E \left(\sum_{\ell=1}^{n} \ell W_{\ell} \right) = T' .$$

In some of the later chapters the problem of estimating the total is considered as the prediction of the total of a second sample drawn from the same infinite population. Here we give the similar result for a second sample from a finite list. The following theorem gives an unbiased estimator of

 $E\left[\sum_{j=1}^{M} Z_{j}^{(r)}(tn)\right], \text{ for a second sample of size tn.}$ Theorem 2.4: $E\left[\sum_{s=r}^{n} \frac{\left(tn\right)\left(n-tn\right)}{n} \left(\sum_{j=1}^{M} Z_{j}^{(s)}\right)\right] = E\left[\sum_{j=1}^{M} Z_{j}^{(r)}(tn)\right]$ Proof: Since $E\left[\sum_{j=1}^{M} Z_{j}^{(r)}(tn)\right] = \frac{n}{2} \frac{\left(\frac{l}{r}\right)\left(\frac{N-l}{tn-r}\right)}{\left(\frac{N}{tn}\right)} \left(\sum_{j\in J_{k}}^{\Sigma} y_{j}\right),$ Hence $E\left[\sum_{s=r}^{n} \frac{\left(tn\right)\left(n-tn\right)}{n} \left(\sum_{j=1}^{M} Z_{j}^{(s)}\right)\right] = \frac{n}{s=r} \frac{\left(tn\right)\left(n-tn\right)}{n} \left(\sum_{\ell=s}^{n} \frac{\left(\frac{l}{s}\right)\left(N-l\right)}{n} \left(\sum_{\ell=s}^{N} y_{\ell}\right)\right)$ $= \frac{n}{2} \frac{l}{s=r} \frac{\left(tn\right)\left(n-tn\right)}{s-r} \left(\frac{l}{s}\right)\left(\frac{N-l}{s-r}\right)}{n} \left(\sum_{\ell=s}^{N} y_{\ell}\right)$

by lemma of [11]

$$= \sum_{\ell=r}^{n} \frac{\binom{\ell}{r} \binom{N-\ell}{tn-r}}{\binom{N}{tn}} \binom{\Sigma}{j \in J_{\ell}} y_{j} = E \begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \\ j=1 \end{bmatrix}$$

Remark:

(1) If tn = N (i.e. we sample the whole population), then In other words, $\sum_{s=r}^{n} \frac{\binom{N}{r}\binom{n-N}{s-r}}{\binom{n}{s}}\binom{M}{\sum}\binom{s}{j=1}^{j}$ is an unbiased estimator of Σy_j (2) Note $\sum_{j=1}^{M} Y_j(tn) = \sum_{r=1}^{n} \sum_{j=1}^{M} Z_j(tn)$. An unbiased estimator of $E\begin{bmatrix} M & n & M & (r) \\ \Sigma & Y_j(tn) & = \Sigma & E & \Sigma & Z_j & (tn) \\ i=1 & r=1 & i=1 & j \end{bmatrix}$ $\begin{array}{c} n & n \\ \text{is } \Sigma & \Sigma \\ r=1 \\ \text{s=r} \end{array} \left[\begin{array}{c} tn \\ r \end{array} \left[\begin{array}{c} n-tn \\ s-r \end{array} \right] \left[\begin{array}{c} M \\ \Sigma \\ j=1 \end{array} \right] \left[\begin{array}{c} z \\ z \\ j=1 \end{array} \right] = \begin{array}{c} n \\ \Sigma \\ s=1 \end{array} \left[\begin{array}{c} 1 \\ - \end{array} \left[\begin{array}{c} n-tn \\ s \\ s \\ s \end{array} \right] \left[\begin{array}{c} M \\ \Sigma \\ z \\ j=1 \end{array} \right] \left[\begin{array}{c} M \\ s \\ z \\ j=1 \end{array} \right] \right] .$ (3) If tn = N, then an unbiased estimator of T = $\sum_{j=1}^{n} y_j$ is $\sum_{s=1}^{n} \left[1 - \frac{\binom{n-N}{s}}{\binom{n}{s}} \right] \left[\sum_{j=1}^{M} Z_j \right] = \sum_{s=1}^{M} A_s \left(\sum_{j=1}^{N} Z_j \right).$ Thus, Theorem 2.4 leads us to the same estimator of T as Theorem 2.1 does.

The following theorem shows the variance of the unbiased estimator

$$\sum_{r=1}^{n} A_{r} \left(\sum_{j=1}^{M} Z_{j}^{(r)} \right)$$

Theorem 2.5:

$$\begin{aligned} & \operatorname{Var}\left[\sum_{r=1}^{n} A_{r} \begin{pmatrix} M & (r) \\ \Sigma & Z_{j} \\ j=1 & J \end{pmatrix}\right]^{=} \\ & \left[\sum_{r=1}^{n} \sum_{s=1}^{n} A_{r} A_{s} \left\{ \begin{array}{c} q & q \\ \Sigma & \Sigma & Cov \left(I_{\{r\}}(X_{v}), I_{\{s\}}(X_{w})\right) \left(\sum_{j \in J_{k}} y_{j}\right) \left(\sum_{k \in J_{k}} y_{k}\right) \right. \\ & \left. v \in J_{h} \\ & w \in J_{k} \\ & w \in J_{h} \\ & W \in J$$

where

$$\operatorname{Cov}\left(I_{\{r\}}(X_{j}), I_{\{s\}}(X_{k})\right) = \begin{cases} 0 \quad j=k \text{ and } r\neq s \\ \operatorname{Var}\left(I_{\{r\}}(X_{j})\right) \quad j=k \text{ and } r=s \\ \operatorname{Cov}\left(I_{\{r\}}(X_{j}), I_{\{s\}}(X_{k})\right) \quad j\neq k \end{cases}$$

2.3 Discussion

Since $W = \sum_{r=1}^{n} A_r \begin{pmatrix} M & (r) \\ \Sigma & Z_j \\ j=1 \end{pmatrix}$, the unbiased estimator of T, can be

negative, we consider other possible estimators of T.

(1) In many practical problems $\sum_{j=1}^{M} (r)$ is small for $r \ge 3$, and a

reasonable estimator is $W' = A_{1} \sum_{j=1}^{\Sigma} Z_{j} + A_{2} \sum_{i=1}^{\Sigma} Z_{j}$

$$= \frac{N}{n} T'_{s} - \frac{N(N-1)}{n(n-1)} \sum_{j=1}^{M} Z_{j}^{(2)}$$

(2) Another estimator sometimes used in W" = $\frac{N}{n}T_s = \frac{N}{n}\sum_{r=1}^{n}\sum_{j=1}^{r}Z_j$.

It may be shown to overestimate when $q \neq 1$.

If the value of W is positive, then it is reasonable to use W as the estimator of T. If the value of W is negative, then we might consider W'. And if the value of W' is negative, we might prefer to use W" as the estimator of T, which is always positive.

2.4 Example

Consider a list of size N = 14,115 with M = 12,000 distinct classes, 9,885 of them having 1 unit and 2,115 of them having 2 units. Suppose the measurements y_j , j = 1, ..., 12,000, are from a Poisson distribution with mean 15. We simulated a sample of size n = 1,000 without replacement from such a population.

Let n_1 be the number of classes that occur once in the sample and let n_2 be the number of classes that occur twice in the sample. We

obtained
$$n_{j} = 968$$
, $n_{2} = 16$, $\sum_{j=1}^{M} Z_{j}^{(1)} = 14,669$, $\sum_{j=1}^{M} Z_{j}^{(2)} = 56$. The unbiased
estimate of $T = \sum_{j=1}^{M} y_{j}$ is $W = \frac{N}{n} \sum_{j=1}^{M} Z_{j}^{(1)} + \left[1 - \frac{(N-n+1)(N-n)}{n(n-1)}\right]_{j=1}^{M} Z_{j}^{(2)} = \frac{M}{2}$

163,652. In this example, the measurements of y_{j} are actually random.

The expected value of T is $12,000 \times 15 = 180,000$. Using the expected value of the Poisson variables the variance of W is Var(W) = 89,166,177 and the standard deviation is 9,442.78. The relative standard deviation is 0.0577.

CHAPTER 3

GOOD AND TOULMIN'S METHOD

3.1 Introduction

In this chapter the sampling is done with replacement.

Good and Toulmin [7] considered the problem of sampling an infinite population and found an approximate relationship between $E[f_r(tn)]$ and $E[f_r]$ where f_r is the number of distinct classes which are represented exactly r times in the basic sample and $f_r(tn)$ is the number of distinct classes which are represented exactly r times in a second sample of size tn:

$$E[f_{r}(tn)] \simeq t^{r} \sum_{i=0}^{\infty} (-1)^{i} {r+i \choose r} (t-1)^{i} E\left(f_{r+i}\right) .$$

They they define an estimator of $E[f_r(tn)]$ by

$$\hat{f}_{r}(tn) = t^{r} \sum_{i=0}^{\infty} (-1)^{i} {r+i \choose r} (t-1)^{i} f_{r+i}$$

They use the approximation

$$\operatorname{Cov}(f_r, f_s) \simeq \delta_{rs} E(f_r) - 2^{-r-s} {r+s \choose r} E \left[f_{r+s}(2n) \right]$$

to obtain

$$\operatorname{Var}\left(\widehat{f}_{r}(\operatorname{tn})\right) \simeq \operatorname{t}^{2r} \left\{ \begin{array}{l} \sum \\ \Sigma \\ i=0 \end{array}^{\infty} (t-1)^{2i} {\binom{r+i}{r}}^{2} \operatorname{E}\left(f_{r+i}\right) \\ - {\binom{2r}{r}} (2t)^{-2r} \operatorname{E}\left[f_{2r}(2\operatorname{tn})\right] \right\}$$

We generalize these derivations to obtain an approximate formula for $E\begin{bmatrix} M & (r) \\ \Sigma & Z_j & (tn) \end{bmatrix}$ in terms of $E\begin{bmatrix} M & (r) \\ \Sigma & Z_j \\ j=1 \end{bmatrix}$. From this we obtain an approximate formula for $E\!\!\left[\begin{matrix} M \\ \Sigma & Y_j(tn) \\ j=1 \end{matrix} \right]$, which lead us to an estimator of

 $T = \sum_{j=1}^{M} y_j.$ We also derive an approximate expression for the variance

of this estimator.

3.2 Estimation of the Total Measurement T

Suppose that C_j is the jth class and d_i is the ith unit of the random sample. Hence

$$P_{r}\left\{d_{i} \in C_{j}\right\} = P_{j} > 0 \quad \text{for } j = 1, \dots, M, \text{ } i = 1, \dots, r$$
and
$$\sum_{j=1}^{M} P_{j} = 1.$$
Theorem 3.1:
$$E\left[\binom{M}{\Sigma} Z_{j}^{(r)}(tn)\right] = t^{r} \sum_{i=0}^{J} (-1)^{i} (t-1)^{i} \binom{r+i}{r} E\left[\binom{M}{\Sigma} Z_{j}^{(r+i)}\right]$$
Where I is some integer such that I << n-r.
Proof:
$$E\left[\sum_{j=1}^{M} Z_{j}^{(r)}(tn)\right] = \sum_{j=1}^{M} y_{j} \binom{tn}{r} P_{j}^{r} (1 - P_{j})^{tn-r}$$

$$= \sum_{j=1}^{M} y_{j} \binom{tn}{r} P_{j}^{r} (1 - P_{j})^{n-r} \binom{m}{1 + \frac{P_{j}}{1 - P_{j}}}^{-(t-1)n}$$

$$= \sum_{i=0}^{M} (tn)^{r} \binom{r}{r} (t-1)^{n} \sum_{j=1}^{M} y_{j} P_{j}^{r+i} (1 - P_{j})^{n-(r+i)}$$

$$= \sum_{i=0}^{\infty} (tn)^{r} \binom{-(t-1)n}{i} E\left[\binom{M}{2} Z_{j}^{(r+i)}\right]$$

For
$$i < r n$$
, we have $r+i < r$, and $i < (t-1)n$, so

$$\frac{\binom{tn}{r}\binom{(-(t-1)n)}{i}}{\binom{n}{r+i}} = \frac{(tn)^{r}(-(t-1)n)^{i}(r+i)!}{r! i! n^{r+i}} = (-1)^{i}t^{r}(t-1)^{i}\binom{r+i}{r}$$
Hence, retaining only terms with $i < n-r$, we obtain

$$E\left[\frac{M}{2}Z_{j}^{(r)}(tn)\right] = t^{r}\frac{I}{2}(-1)^{i}(t-1)^{i}\binom{r+i}{r}E\left[\frac{M}{2}Z_{j}^{(r+i)}\right]$$
Corollary 3.1: $E\left[\sum_{j=1}^{M}\binom{(r)}{Z_{j}}(tn)\right]^{2}\right] = t^{r}\frac{I}{2}(-1)^{i}(t-1)^{i}\binom{r+i}{r}E\left[\sum_{j=1}^{M}\binom{Z_{j}^{(r+i)}}{Z_{j}}\right]$
Proof: The same as that of Theorem 3.1.
Remark 3.1: (1) We define an estimator of $E\left[\frac{M}{2}Z_{j}^{(r)}(tn)\right]$ by
 $\hat{M}_{j=1}^{2}Z_{j}^{(r)}(tn) = t^{r}\frac{I}{2}(-1)^{i}\binom{r+i}{r}(t-1)^{i}\binom{M}{2}Z_{j}^{(r+i)}$.
(2) $E\left[\frac{M}{2}Y_{j}(tn)\right] = \frac{M}{2}y_{j}\left[1 - (1 - P_{j})^{tn}\right] = \frac{M}{2}y_{j}$
 $- \frac{M}{2}y_{j}(1 - P_{j})^{tn} = \frac{M}{2}y_{j}$ for large t
(3) $E\left[\frac{M}{2}Y_{j}(tn)\right] = E\left[\frac{M}{2}Z_{j}^{(r+i)}\right]$
(4) Since $E\left[\frac{M}{2}Z_{j}^{(0)}(tn)\right] = \frac{I}{2}E\left[\frac{M}{2}Z_{j}^{(r)}(tn)\right] = \frac{M}{2}Z_{j}^{(r)}(tn)$
 $= \frac{M}{2}y_{j}-E\left[\frac{M}{2}Z_{j}^{(0)}(tn)\right]$

$$= \prod_{j=1}^{M} y_j - E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Z_j^{(0)} - \prod_{i=1}^{I} (-1)^i (t-1)^i E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Z_j^{(i)}$$

$$= \prod_{r=1}^{n} E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Z_j^{(r)} - \prod_{i=1}^{I} (-1)^i (t-1)^i E\begin{bmatrix} M \\ \Sigma \\ \Sigma \\ j=1 \end{bmatrix} Z_j^{(i)}].$$

$$(5) \text{ Therefore, we can estimate } T = \prod_{j=1}^{M} y_j \text{ by }$$

$$\hat{\Sigma Y_{j}}(tn) = T_{s} - \frac{I}{\sum_{i=1}^{S} (-1)^{i} (t-1)^{i} \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} when t is$$

large.

However, the factor $(t-1)^{i}$ increases rapidly with i if t > 2 and attaches weight to terms for which $\sum_{j=1}^{M} Z_{j}^{(i)}$ is small. This is likely to produce

a large percentage error when estimated from the basic sample. We follow Good and Toulmin in using a summation method to try to overcome this difficulty.

(6) In the case when the second sample is an enlargement of the basic one, the expectation of the new total measurement is approximately

$$(t-1)\sum_{j=1}^{M} Z_{j}^{(1)} - (t-1)^{2} \sum_{j=1}^{M} Z_{j}^{(2)} + - \dots$$

3.3 Variance of the Estimator of T

In this section we find the variance of

$$\sum_{j=1}^{M} Y_{j}(tn) = T_{s} - \sum_{i=1}^{\Sigma} (-1)^{i} (t-1)^{i} \left(\sum_{j=1}^{M} Z_{j}^{(i)} \right) .$$

First, we find
$$Cov \begin{bmatrix} M & (r) & M & (s) \\ \Sigma & Z_j & , & \Sigma & Z_j \\ j=1 & j=1 \end{bmatrix}$$
.

Theorem 3.2: For rs << n,

Proof:

$$\begin{split} & \mathsf{E}\left[\left(\begin{array}{c}\mathsf{M} & (\mathbf{r})\\ \mathtt{j=1}^{\Sigma} \mathtt{J}\right)\left(\begin{array}{c}\mathsf{M} & \mathtt{j=1}^{\Sigma} \mathtt{J}\\ \mathtt{j=1}^{\Sigma} \mathtt{J}\end{array}\right)\right] \\ & = \delta_{\mathsf{rs}}\mathsf{E}\left[\begin{array}{c}\mathsf{M} & \mathtt{M}\\ \mathtt{J} & \mathtt{I}\\ \mathtt{j=1}^{\Sigma} \mathtt{J}\end{array}\right]^{2} + \mathsf{E}\left[\begin{array}{c}\mathsf{M} & (\mathbf{r})\\ \mathtt{J} & \mathtt{I}\\ \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J} & \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{J} & \mathtt{J} & \mathtt{J}\\ \mathtt{J} & \mathtt{$$

•

$$= \delta_{rs} E \left[\sum_{j=1}^{M} \left(Z_{j}^{(r)} \right)^{2} \right] + \sum_{j \neq k} \sum_{j \neq k} \sum_{j \neq k} \frac{n!}{r! s! (n-r-s)!} P_{j}^{r} P_{k}^{s} \left(1 - P_{j} - P_{k} \right)^{n-r-s} \right]$$

$$= \delta_{rs} E \left[\sum_{j=1}^{M} \left(Z_{j}^{(r)} \right)^{2} \right] + \frac{n!}{r! s! (n-r-s)!} \left[\sum_{j \neq k} \sum_{j \neq k} \sum_{j \neq k} P_{k}^{r} P_{k}^{s} \left(1 - P_{j} - P_{k} \right)^{n-r-s} \right]$$

$$= \delta_{rs} E \left[\sum_{j=1}^{M} \left(Z_{j}^{(r)} \right)^{2} \right] + \frac{n!}{r! s! (n-r-s)!} \left[\sum_{j \neq k} \sum_{j \neq k} \sum_{j \neq k} P_{k}^{r} P_{k}^{s} \left(\sum_{u=0}^{s} \left(\sum_{u}^{s} P_{j}^{u} P_{j}^{u} \right)^{u} \right) \right]$$

$$= \delta_{rs} E \left[\sum_{j=1}^{M} \left(Z_{j}^{(r)} \right)^{2} \right] + \frac{n!}{r! s! (n-r-s)!} \left[\sum_{j \neq k} \sum_{j \neq k} \sum_{j \neq k} P_{k}^{r} P_{k}^{s} \left(\sum_{u=0}^{s} \left(\sum_{u}^{s} P_{j}^{u} P_{j}^{u} \right)^{u} \right) \right]$$

$$= \delta_{rs} E \left[\sum_{j=1}^{M} \left(Z_{j}^{(r)} \right)^{2} \right] + \frac{n!}{r! s! (n-r-s)!} \left[\sum_{j \neq k} \sum_{u \neq k} \sum_{u=0}^{n-s-s} \left(\sum_{u=0}^{n-r-s} \left(-1 \right)^{u} P_{j}^{u} P_{k}^{u} P_{k}^{u} P_{k}^{u} P_{k}^{u} P_{k}^{u} P_{k}^{v} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{s} P_{k}^{u} P_{j}^{u} P_{j}^{u} P_{k}^{u} P_{k}^{u}$$

$$= \delta_{rs} E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \left(Z_{j}^{(r)} \right)^{2} + \frac{n!}{r!s!(n-r-s)!} \begin{bmatrix} \Sigma \\ u,v,w \end{pmatrix} \frac{(-1)^{w} \left(s \\ u \right) \left(r \\ v \right) \left(n-r-s \\ w \end{pmatrix}}{\left(r+u+w \right)} + \frac{n!}{s+v+w} + E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \left[Z_{j}^{(r+u+w)} \right] = E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \left[Z_{j}^{(s+v+w)} \right] - \frac{n-r-s}{u=0} \frac{(-1)^{u} \left(n-r-s \\ u=0 \end{bmatrix}}{\left(r+s+u \right)} + \frac{1}{2} +$$

if u, v, w, r, s are all << n, then the coefficient in the first sum is $O((rs/n)^{U+V+W})$ and when u=v=w=0, use of Stirling's formula shows that it is 1+O(rs/n). Hence if rs << n it is proved.

Remark 3.2:

$$Cov \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} Z_{j}^{(r)}, \quad M \\ j=1 \end{pmatrix} Z_{j}^{(s)} = \delta_{rs} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} Z_{j}^{(r)} + \sum_{u}^{2} - \sum_{u}^{2} (-1)^{u} \\ \frac{(r+s+u)!}{r!s!u!} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} Z_{j}^{(r+s+u)} Z_{j}^{2} \\ \approx \delta_{rs} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} Z_{j}^{(r)} + \sum_{u}^{2} - 2^{-r-s} \begin{pmatrix} r+s \\ r \end{pmatrix} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} Z_{j}^{(r+s)} (2n) Z_{j}^{2} \end{bmatrix}$$

Theorem 3.3:
$$\operatorname{Var}\begin{bmatrix} \mathbf{n} \\ \boldsymbol{\Sigma} \\ \mathbf{j}=1 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \boldsymbol{\Sigma} \\ \mathbf{i}=0 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \mathbf{r} \\ \mathbf{i}=0 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{r}+\mathbf{i} \\ \mathbf{r} \\ \mathbf{r} \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \mathbf{L} \\ \mathbf{J}=1 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \mathbf{L} \\ \mathbf{J}=1 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \mathbf{L} \\ \mathbf{J} \\ \mathbf{J}=1 \end{bmatrix} \stackrel{\circ}{\simeq} t^{2r} \left\{ \begin{array}{c} \mathbf{I} \\ \mathbf{L} \\ \mathbf{J} \\ \mathbf{J} \end{bmatrix} \right\} \right\}$$

where I is an integer such than I << n-r.
Proof:
$$\operatorname{Var}\begin{bmatrix} x \\ z \\ j=1 \end{bmatrix}^{2} (tn) = \operatorname{Var}\begin{bmatrix} t^{r} \frac{\infty}{z} (-1)^{i} {r^{r+i} \choose r} (t-1)^{i} {\frac{M}{z} z} (r+i) \\ j=1 \end{bmatrix}^{2} = t^{2r} \begin{cases} \frac{\infty}{z} (-1)^{i+k} (t-1)^{i+k} {r^{r+i} \choose r} {r^{r+i} \choose r} cov {\frac{M}{z} z} (r+i) \\ j=1 \end{bmatrix}^{2} = t^{2r} \begin{cases} \frac{\infty}{z} (-1)^{i+k} (t-1)^{i+k} {r^{r+i} \choose r} {r^{r+k} \choose r} cov {\frac{M}{z} z} (r+i) \\ j=1 \end{bmatrix}^{2} = t^{2r} \begin{cases} \frac{\infty}{z} (-1)^{i+k} (t-1)^{i+k} {r^{r+i} \choose r} {r^{r+k} \choose r} cov {\frac{M}{z} z} (r+i) \\ j=1 \end{bmatrix}^{2} \\ - 2^{-2r-i-k} {2r+i+k \choose r+i} e \begin{bmatrix} M z (2r+i+k) (2n) \\ j=1 \end{bmatrix}^{2} \end{bmatrix}^{2} \\ = t^{2r} \begin{cases} \frac{\infty}{z} (-1)^{2} (r+i)^{2} 2 e \begin{bmatrix} M z \\ j=1 \end{bmatrix} (z (r+i))^{2} \end{bmatrix}^{2} \\ - \frac{\infty}{2 = 0} (-1)^{2} (t-1)^{2} 2^{-2r-2r} e E \begin{bmatrix} M z (2r+2) (2n) \\ j=1 \end{bmatrix}^{2} \frac{(2r+2)!}{2!r!r!} \\ \frac{i+k=2}{2!r!r!r!} \frac{(i+k)!}{1!k!} \\ = t^{2r} \begin{cases} \frac{\infty}{z} (-1)^{2i} (r+i)^{2} 2 e \begin{bmatrix} M z \\ j=1 \end{bmatrix} (z (r+i))^{2} \end{bmatrix}^{2} \\ - \frac{\infty}{z = 0} (-1)^{2} (t-1)^{2} 2 e^{-2r-2r} \frac{(2r+2)!}{2!j!r!r!} e \begin{bmatrix} M z (2(2r+2) (2n))^{2} \\ j=1 \end{bmatrix}^{2} \end{cases}$$

$$-(2t)^{-2r} {2r \choose r} E \left[\begin{matrix} M & (2r) \\ \Sigma \\ j=1 \end{matrix} \right] \left[\begin{matrix} Z_{j} \\ Z_{j} \end{matrix} \right] \left[2tn \end{matrix} \right]^{2} \right]$$

Remark 3.3:

Since
$$\Sigma \hat{Y}_{j}(tn) = \Sigma y_{j} - \sum_{j=1}^{M} \hat{Z}_{j}^{(0)}(tn),$$

 $Var \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Y}_{j}(tn) = Var \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(0)}(tn)$
 $\approx \sum_{i=0}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(1)} \hat{Z}_{j}^{2} - E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(0)}(2tn) \hat{Z}_{j}^{2}$
 $= \sum_{i=0}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(1)} \hat{Z}_{j}^{2} - \sum_{i=0}^{\infty} (-1)^{i} (2t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(1)} \hat{Z}_{j}^{2}$
 $= \sum_{i=1}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(1)} \hat{Z}_{j}^{2} - \sum_{i=1}^{\infty} (-1)^{i} (2t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \hat{Z}_{j}^{(1)} \hat{Z}_{j}^{2}$

3.4 Summation of the Series

Euler's transformation with parameter q, generally called the (E, q) method, is a method of forcing series like $\sum_{i=1}^{\infty} (-1)^i (t-1)^i E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} (Z_j^{(i)})$, $\sum_{i=1}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} (Z_j^{(i)})^2$, $\sum_{i=1}^{\infty} (-1)^i (2t-1)^i E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} (Z_j^{(i)})^2$, etc. to converge rapidly. This is to transform the series $\sum_{i=0}^{\infty} a_i$ into $\sum_{j=0}^{\infty} a_j^{(q)}$ where $a_j^{(q)} = \frac{1}{(q+1)^{j+1}} \sum_{i=0}^{j} (j)^i q^{j-i} a_i$.

First consider $\sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}$. In our example,

22

 $\begin{bmatrix} M & (r) \\ \Sigma & Z_j \\ i=1 \end{bmatrix}$ generally decreases slowly for $r \ge 2$ and so we will write $\sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} E \left| \sum_{j=1}^{M} Z_{j} \right| \simeq -(t-1) E \left[\sum_{i=1}^{M} Z_{j} \right]$ + $E \begin{vmatrix} M & (2) \\ \Sigma & Z_j \\ i=1 \end{vmatrix} (t-1)^2 \sum_{i=0}^{\infty} (-1)^i (t-1)^i$. We apply the (E, q) method to $\sum_{i=0}^{\infty} (-1)^{i} (t-1)^{i}$. Define $a_{i} = (-1)^{i} (t-1)^{i}$ $a_{j}^{(q)} = \frac{1}{(q+1)^{j+1}} \sum_{i=0}^{j} {j \choose i} q^{j-i} a_{i} = \frac{1}{q+1} \left(\frac{q-(t-1)}{q+1} \right)^{j}$ $\sum_{j=0}^{\infty} a_j^{(q)} = \frac{1}{t}.$ Hence $\sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} E \begin{bmatrix} M & (i) \\ \Sigma & Z_{j} \end{bmatrix} \approx -(t-1) E \begin{bmatrix} M & (1) \\ \Sigma & Z_{j} \end{bmatrix} + \frac{(t-1)^{2}}{t} E \begin{bmatrix} M & (2) \\ \Sigma & Z_{j} \end{bmatrix}.$ Remark 3.4: Recall the estimator $\sum_{j=1}^{M} Y_j(tn)$ in Remark 3.1.(5). The summation in that expression has upper limit I. Let us, however, change the upper limit to ∞ and then use Euler's transformation to obtain $E \begin{vmatrix} M & \\ \Sigma & Y_{j}(tn) \end{vmatrix} \approx \sum_{r=1}^{n} E \begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \\ i=1 \end{vmatrix} + (t-1) E \begin{bmatrix} M & (1) \\ \Sigma & Z_{j} \\ i=1 \end{vmatrix}$ $-\frac{(t-1)^2}{t} \in \begin{bmatrix} M & (2) \\ \Sigma & Z_j \\ j=1 \end{bmatrix}$ We previously argued that $\sum_{j=1}^{M} Y_j(tn)$ is a reasonable estimator of T

when t is large, say t = $\frac{N}{n}$. We now see that another expression for

a reasonable estimator of T is

$$\sum_{j=1}^{M} Y_{j}(tn) = \sum_{r=1}^{n} \sum_{j=1}^{M} Z_{j}^{(r)} + \left(\frac{N}{n} - 1\right) \sum_{j=1}^{M} Z_{j}^{(1)} - \left(\frac{N}{n} - 1\right)^{2} \sum_{j=1}^{M} Z_{j}^{(2)}$$

$$If \sum_{j=1}^{M} Z_{j}^{(r)} = 0 \text{ for } r \ge 2 \text{ (this is nearly true in many examples), then }$$

$$\sum_{j=1}^{M} Y_{j}(N) = \sum_{j=1}^{M} Y_{j}(N) = -\frac{N}{n} T_{s}^{'}, \text{ which is the natural estimator of the }$$

population total when there is no duplication.

To obtain an approximate expression for the variance of

$$\sum_{j=1}^{M} \widehat{Y}_{j}(tn), \text{ now consider } \sum_{i=1}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ Z_{j} \end{pmatrix} = 1$$
 and
$$\sum_{i=1}^{\infty} (-1)^{i} (2t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ Z_{j} \end{pmatrix} = 1$$
 is nearly constant for $r \ge 2$, and so we write
$$\sum_{i=1}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ \Sigma \\ j=1 \end{bmatrix} = (t-1)^{2} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (1) \\ \Sigma \\ j=1 \end{bmatrix} + E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (2) \\ \Sigma \\ j=1 \end{bmatrix} = (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} = 1$$

Applying the (E, q) method to $\sum_{i=2}^{\infty} (t-1)^{2i}$, we obtain

$$\frac{\sum_{i=1}^{\infty} (t-1)^{2i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ \Sigma \\ j \end{bmatrix}^{2} \approx (t-1)^{2} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (1) \\ \Sigma \\ j \end{bmatrix}^{2} + \frac{(t-1)^{2}}{1-(t-1)^{2}} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (2) \\ \Sigma \\ j \end{bmatrix}^{2}.$$

Also, we can write

$$\sum_{i=1}^{\infty} (-1)^{i} (2t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ Z_{j} \end{pmatrix}^{2} = -(2t-1) E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (1) \\ Z_{j} \end{pmatrix}^{2}$$

$$+ E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \sum_{i=2}^{\infty} (-1)^{i} (2t-1)^{i} .$$

Applying the (E, q) method to $\sum_{i=2}^{\infty} (-1)^{i} (2t-1)^{i}$, we obtain

$$\sum_{i=1}^{\infty} (-1)^{i} (2t-1)^{i} E \left[\sum_{j=1}^{M} {\binom{i}{z_{j}}}^{2} \right] \simeq -(2t-1) E \left[\sum_{j=1}^{M} {\binom{1}{z_{j}}}^{2} \right]$$

$$+ \frac{(2t-1)^{2}}{t} E \left[\sum_{j=1}^{M} {\binom{2}{z_{j}}}^{2} \right].$$

Remark 3.5:

Using Euler's transformation

$$\operatorname{Var}\left[\begin{array}{c} M\\ \Sigma\\ j=1 \end{array}^{\mathcal{N}} Y_{j}(tn) \right] \simeq t^{2} \operatorname{E}\left[\begin{array}{c} M\\ \Sigma\\ j=1 \end{array}^{\mathcal{N}} \left(Z_{j} \right)^{2} \right] + \frac{4t^{2} - 10t + 5}{2(2 - t)} \operatorname{E}\left[\begin{array}{c} M\\ \Sigma\\ j=1 \end{array}^{\mathcal{N}} \left(Z_{j} \right)^{2} \right].$$

$$E\left[\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \left(1 \right)^{j} \left(1 \right)^$$

write

$$\sum_{i=0}^{\infty} (-1)^{i} {\binom{2+i}{2}} (t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+i}{j}}^{2} = E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ \end{bmatrix} {\binom{2+$$

and

$$\sum_{i=0}^{\infty} (-1)^{i} {\binom{1+i}{1}} (t-1)^{i} E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ Z_{j} \end{bmatrix}^{2} \cong E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ Z_{j} \end{bmatrix}^{2}$$
$$- 2(t-1) E \begin{bmatrix} M \\ \Sigma \\ j=1 \\ Z_{j} \end{bmatrix}^{2} \sum_{i=0}^{\infty} (-1)^{i} (t-1)^{i}.$$

Applying the (E, q) method to $\sum_{i=0}^{\infty} (-1)^{i} (t-1)^{i}$, we obtain

$$\sum_{i=0}^{\infty} (-1)^{i} \frac{2+i}{2} (t-1)^{i} E \sum_{j=1}^{M} z_{j}^{(2+i)} 2$$

$$\simeq \frac{1}{t} E \sum_{j=1}^{M} z_{j}^{(2)} 2, \text{ and}$$

$$\sum_{i=0}^{\infty} (-1)^{i} \frac{1+i}{1} (t-1)^{i} E \sum_{j=1}^{\Sigma} Z_{j}^{(1+i)} \cong E \sum_{j=1}^{M} Z_{j}^{(1)} - \frac{2(t-1)}{t} E \sum_{j=1}^{M} Z_{j}^{(2)}$$

$$= \frac{1}{2} \sum_{j=1}^{M} Z_{j}^{(2)} = \frac{1}{2} \sum_{j=1}^{M} Z_{j}^{(2)}$$

Remark 3.6:

$$\operatorname{Var} \begin{bmatrix} M & 0 \\ \Sigma & Y_{j}(tn) \end{bmatrix} = \operatorname{Var} \begin{bmatrix} n & (0) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} + (t-1)^{2} \operatorname{Var} \begin{bmatrix} M & (1) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} + \frac{(t-1)^{4}}{t^{2}} \operatorname{Var} \begin{bmatrix} M & (2) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} \\ - 2(t-1) \operatorname{Cov} \begin{bmatrix} M & (0) & M & (1) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} + 2 \frac{(t-1)^{2}}{t} \operatorname{Cov} \begin{bmatrix} M & (0) & M & (2) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} \\ - 2 \frac{(t-1)^{3}}{t} \operatorname{Cov} \begin{bmatrix} M & (1) & M & (2) \\ \Sigma & Z_{j} \\ j=1 & j \end{bmatrix} .$$

Without considering Euler's transformation we obtain

3.5 Example

Consider a list of size N = 14,115 with M = 12,000 distinct classes, 9,885 of them having 1 unit and 2,115 of them having 2 units. Suppose the measurements y_j , j = 1, ..., 12,000, are from a Poisson distribution with mean 15. We simulated a sample of size n = 1,000 with replacement such a population.

Let n_1 be the number of classes that occur once in the sample, let n_2 be the number of classes that occur twice in the sample, and let n_3 be the number of classes that occur three times in the sample.

We obtained
$$n_1 = 900$$
, $n_2 = 47$, $n_3 = 2$, $\sum_{\substack{j=1 \ j=1}}^{M} Z_j^{(1)} = 13,461$, $\sum_{\substack{j=2 \ j=1}}^{M} Z_j^{(2)} = 671$, $\sum_{\substack{j=1 \ j=1}}^{Z} Z_j^{(1)} = 33$, $\sum_{\substack{j=1 \ j=1}}^{M} Z_j^{(1)} = 214,613$, $\sum_{\substack{j=1 \ j=1}}^{M} Z_j^{(2)} = 10,157$, and

Therefore, we obtain the estimate of $T = \int_{\Sigma}^{M} y_j$ is 182,529 with Euler's transformation. Using Remark 3.6 without using Euler's transformation, we find that the variance of the estimates is 41,158,599.42, its standard deviation is 6,415.50, and its relative standard deviation is .0351. Using Euler's transformation we find its variance is 42,645,357.32, its standard deviation is 6530.34, and its relative standard deviation is .0358.





CHAPTER 4

HARRIS' METHOD

4.1 Introduction

and

In this chapter samples are taken with replacement.

In Chapter 3 we found that the estimator of $\sum_{j=1}^{M} y_j$ using Euler's transformation gives a reasonably good answer in our examples. Harris [10] gives us a check on the accuracy of this estimator. His approach offers approximations of the supremum and infimum of $E\begin{bmatrix}M\\ \Sigma\\ j=1\end{bmatrix} Y_j(tn)$ which for large t is approximately equal to $T = \sum_{j=1}^{M} y_j$. If an estimate

of T falls wihtin these bounds, we can regard it as reasonable (from this rather conservative viewpoint).

Define d to be the number of distinct classes observed in the sample and d(tn) to be the number of distinct classes which would be observed in a second sample of size tn. Harris [10] showed

$$E[d(tn)] \simeq E(d) + E(f_1) \int_0^{\infty} \frac{1 - e^{-(t-1)x}}{x} dG(x)$$
$$\int x^r dG(x) \simeq \frac{(r+1)! E(f_{r+1})}{E(f_1)}$$

where f_r is as in Section 3.1 and G is a constructed cumulative distribution function. Harris computed the supremum and infimum of E[d(tn)]
taken over all cumulative distribution functions whose first k moments are specified by $\int x^{r} dG(x)$.

Now we generalize his computations to obtain the supremum and

infimum of
$$E\begin{bmatrix} M \\ \Sigma Y_j(tn) \\ j=1 \end{bmatrix}$$
.

4.2 Derivations

Proof:

Lemma 4.1: For large n we have

(i)
$$E[T_s] = \sum_{j=1}^{M} y_j \left[1 - \left(1 - P_j \right)^n \right] \approx \sum_{j=1}^{M} y_j \left[1 - e^{-nP_j} \right]$$

and

(ii)
$$E\begin{bmatrix} M & (r) \\ j=1 & Z_{j} \end{bmatrix} = \sum_{j=1}^{M} y_{j} \binom{n}{r} P_{j}^{r} \binom{1-P_{j}}{1-P_{j}}^{n-r} \simeq \sum_{j=1}^{M} y_{j} \frac{(nP_{j})^{r} e^{-nP_{j}}}{r!}$$

(i) $\begin{bmatrix} \frac{M}{j=1} y_{j} \begin{bmatrix} 1-(1-P_{j}) & n \end{bmatrix} - \sum_{j=1}^{M} y_{j} \begin{bmatrix} 1-e^{-nP_{j}} \end{bmatrix}$
 $\leq \sup_{j} y_{j} \begin{bmatrix} e^{-nP_{j}} - (1-P_{j}) & n \end{bmatrix}$
 $\leq \sup_{j} \frac{y_{j} \begin{bmatrix} e^{-nP_{j}} - (1-P_{j}) & n \end{bmatrix}}{y_{j} \begin{bmatrix} 1-e^{-nP_{j}} \end{bmatrix}}$
 $= \sup_{j} \frac{e^{-nP_{j}} - (1-P_{j}) & n}{1-e^{-nP_{j}}}$

By Harris' proof on p. 545 [10], we know

$$\sup_{j} \frac{e^{-nP_{j}} - (1 - P_{j})^{n}}{1 - e^{-nP_{j}}} \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

31

(ii) As stated by Harris,
$$\binom{n}{r} \approx \frac{n^r}{r!} \exp\left[-\frac{r(r-1)}{2n}\right]$$
 and
 $\left(1 - P\right)^{n-r} \approx \exp\left[-(n-r)P - \frac{(n-r)P^2}{2}\right]$ for $P < 1$.

Hence, we have

$$= \sum_{j=1}^{M} \frac{y_j (nP_j)^r e^{-nP_j}}{r!} - \sum_{j=1}^{M} y_j (n) P_j^r (1 - P_j)^{n-r}$$

$$= \sum_{j=1}^{M} \frac{y_j (nP_j)^r e^{-nP_j}}{r!} - \sum_{j=1}^{M} y_j \frac{n^r e^{-r(r-1)}}{2n} P_j^r e^{-(n-r)P_j - (n-r)P_j^2}}{r!}$$

$$= \frac{M}{\sum_{j=1}^{\Sigma} \frac{y_{j} (nP_{j}) r_{e}^{-nP_{j}}}{r!}}{\sum_{j=1}^{T} \frac{y_{j} (nP_{j}) r_{e}^{-nP_{j}}}{r!}} \left\{ 1 - \exp \left[rP_{j} - \frac{r(r-1)}{2n} - \frac{(n-r)}{2} P_{j}^{2} - \dots \right] \right\}$$

(a) If
$$P \ge \frac{1}{n^{2/3}}$$
, then

$$\sum_{\substack{p_{j} \geq 1 \\ p_{j} \geq 1 \\ p_{j} \geq 1 \\ n^{2/3}}} \frac{y_{j} (nP_{j})^{r}}{r!} e^{-nP_{j}} \left\{ 1 - \exp\left[rP_{j} - \frac{r(r-1)}{2n} - \frac{(n-r)}{2}P_{j}^{2} + \frac{r^{2}}{2}P_{j}^{2} + \frac{r^{2}}{2}$$

as $n \rightarrow \infty$.

(b) If
$$P < \frac{1}{n^{2}/3}$$
, then

$$\frac{\sum_{\substack{p_{j} < \frac{1}{n^{2}/3}}}{\frac{y_{j} \left(nP_{j}\right) r_{e}^{-nP_{j}}}{r!} \left\{ 1 - \exp\left[rP_{j} - \frac{r(r-1)}{2n} - \frac{(n-r)}{2}P_{j}^{2} - \cdots\right] \right\}$$

$$\frac{\sum_{\substack{p_{j} < \frac{1}{n^{2}/3}}}{\frac{y_{j} \left(nP_{j}\right) r_{e}^{-nP_{j}}}{r!}$$

$$\leq \frac{\sup_{j < 1/2/3}}{P_{j} < \frac{y_{j} (nP_{j})^{r} e^{-nP_{j}}}{r!}} \frac{\left\{1 - \exp\left[rP_{j} - \frac{r(r-1)}{2n} \frac{(n-r)_{p}}{2}^{2} - \ldots\right]\right\}}{\frac{y_{j} (nP_{j})^{r} e^{-nP_{j}}}{r!}}$$

$$= \frac{\sup_{P_{j} < 1/2/3}}{\Pr_{j} < 1/2/3} \left\{ 1 - \exp\left[rP_{j} - \frac{r(r-1)}{2n} - \frac{(n-r)}{2}P_{j}^{2} - \dots\right] \right\}$$
$$= 1 - e^{O\left(\frac{1}{2}/3\right)} \left[1 - \exp\left[rP_{j} - \frac{r(r-1)}{2n} - \frac{(n-r)}{2}P_{j}^{2} - \dots\right] \right\}$$

Now we have by lemma 4.1.(i) $E\begin{bmatrix}M\\ \Sigma\\ j=1\end{bmatrix}Y_{j}(tn) = \frac{M}{j=1}y_{j}\left[1 - (1 - P_{j})^{tn}\right] \approx \frac{M}{j=1}y_{j}\left[1 - e^{-tnP_{j}}\right]$ which is $= \frac{M}{j=1}y_{j}\left(1 - e^{-nP_{j}}\right) + \frac{M}{j=1}y_{j}\left(e^{-nP_{j}} - e^{-tnP_{j}}\right)$

$$\simeq E(T_{s}) + \sum_{j=1}^{M} y_{j} e^{-nP_{j}} \left[1 - e^{-(t-1)nP_{j}}\right]$$

$$\simeq E(T_{s}) + E\left[\sum_{j=1}^{M} z_{j}^{(1)}\right] \frac{\prod_{j=1}^{M} y_{j} \left(nP_{j}\right) e^{-nP_{j}} \left[\frac{1 - e^{-(t-1)nP_{j}}}{nP_{j}}\right]}{\prod_{j=1}^{M} y_{j} \left(nP_{j}\right) e^{-nP_{j}}}$$

$$Define F(c) = \frac{\prod_{j=1}^{N} y_{j}^{nP_{j}} e^{-nP_{j}}}{\prod_{j=1}^{N} y_{j}^{nP_{j}} e^{-nP_{j}}} . \quad One readily observes that F(c)$$

is a cumulative distribution function, and it depends on the unknown parameters $(y_1, y_2, \ldots, y_M, P_1, P_2, \ldots, P_M)$. We have just shown that

Theorem 4.1:

$$E\begin{bmatrix}M\\ \Sigma Y_{j}(tn)\\ j=1\end{bmatrix} \simeq E(T_{s}) + E\begin{bmatrix}M\\ \Sigma Z_{j}(1)\\ j=1\end{bmatrix} \int_{0}^{\infty} \frac{1-e^{-(t-1)x}}{x} dF(x).$$

Remark 4.1:

(1) We can follow the procedure of Harris to obtain upper and lower bounds $of \int_{0}^{\infty} \frac{1 - e^{-(t-1)x}}{x} dF(x)$ for any cumulative distribution function F with given values of the first k moments. By substituting those bounds in the equation of Theorem 4.1, and also substituting T_s for $E(T_s)$ and $\sum_{j=1}^{M} Z_j^{(1)}$ for $E\begin{bmatrix}M\\ \Sigma\\ j=1\end{bmatrix}_{j=1}^{K} Z_j^{(1)}$, we obtain upper and lower bounds of $E\begin{bmatrix} M \\ \Sigma & Y_j(tn) \end{bmatrix}$.

(2) To apply the procedure of Harris (see Section 4 and5 of [10]) we only need to specify the moments

 $\mu_r = \int_0^\infty x^r d F(x)$. Since F(x) is unknown, we use the

approximation

$$m_{r} = \frac{\binom{(r+1)!}{\sum} Z_{j}}{\binom{M}{j=1} j} \text{ because } \mu_{r} = \frac{\binom{M}{\sum} y_{j} \binom{nP_{j}}{j}^{r+1} e^{-nP_{j}}}{\binom{M}{j=1} j}$$
$$\approx \frac{\binom{(r+1)!}{\sum} Z_{j}}{\binom{M}{j=1} j} \frac{\binom{M}{j=1} \binom{(r+1)}{j}}{\binom{N}{j=1} j} .$$

(3) The bounds for $E\begin{bmatrix}M\\\Sigma & Y_j(tn)\\j=1\end{bmatrix}$ can be used as bounds for T if t is large. As indicated in Remark 3.4, $t = \frac{N}{n}$ seems to be a good choice for t. The following theorem shows that the estimator $\hat{P}_{j=1}^{N}Y_j(tn)$ in Chapter 3 is the same as the $\hat{P}_{j=1}^{N}Y_j(tn)$ above if we replace I by ∞ .

$$\sum_{j=1}^{M} \sum_{j=1}^{r} Y_{j}(tn) = T_{s} + \left(\sum_{j=1}^{M} Z_{j}^{(1)} \right) \int_{0}^{\infty} \frac{1 - e^{-(t-1)x}}{x} dF(x)$$

$$= T_{s} - \sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix}$$

Proof:

Harris showed (see p. 540 of [10])

$$\int_{0}^{\infty} \frac{1 - e^{-(t-1)x}}{x} dF(x) = \int_{0}^{\alpha} \int_{0}^{-1} e^{-tx} dF(x) dt$$
where $\int_{0}^{\infty} e^{-tx} dF(x)$ is the moment generating function of (-X).

Since
$$\mu_{r} \approx \frac{(r+1)! E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}}{E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}},$$

we have

$$\int_{0}^{\infty} e^{-tx} dF(x) \simeq \sum_{r=0}^{\infty} \frac{(-1)^{r}(r+1)\sum_{j=1}^{M} Z_{j}^{(r+1)} t^{r}}{\prod_{j=1}^{M} Z_{j}^{(1)}}$$

Upon integrating $\int_{0}^{\infty} e^{-tx} dF(x)$ term by term, we get

$$\begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \int_{0}^{1} \frac{1 - e^{-(t-1)x}}{x} dF(x) = \sum_{r=0}^{\infty} (-1)^{r} \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} (t-1)^{r+1} dF(x) = \sum_{r=0}^{\infty} (-1)^{r} \left(\sum_{j=1}^{M} Z_{j}^{(r+1)} \right) (t-1)^{r+1} dF(x) = \sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} \left(\sum_{j=1}^{M} Z_{j}^{(i)} \right) dF(x) dF(x) = \sum_{i=1}^{\infty} (-1)^{i} (t-1)^{i} \left(\sum_{j=1}^{M} Z_{j}^{(i)} \right) dF(x) dF(x)$$

4.3 Example

This is the same example as that in the last chapter. By Remark 4.1.(2) we get

$$m_{1} = 2! \sum_{j=1}^{M} Z_{j} / \sum_{j=1}^{M} Z_{j}^{(1)} = .0996954$$
$$m_{2} = 3! \sum_{j=1}^{Z} Z_{j} / \sum_{j=1}^{M} Z_{j}^{(2)} = .0147092$$

When we do not consider the addition of any moment constraint (i.e., k=0), we have

$$\sup \prod_{j=1}^{M} Y_{j}(tn) = T_{s} + \left(\prod_{j=1}^{M} Z_{j}^{(1)} \right) \lim_{x \to 0} \frac{1 - e^{-(t-1)x}}{x}$$

$$= \prod_{j=1}^{M} Y_{j} + (t-1) \prod_{j=1}^{M} Z_{j}^{(1)}$$

$$= 14165 + 13461(t-1)$$

$$= 190,706 \text{ when } t = \frac{N}{n} = 14.115$$

$$\inf \prod_{j=1}^{M} Y_{j}(tn) = T_{s} + \left(\prod_{j=1}^{M} Z_{j}^{(1)} \right) \lim_{b \to \infty} \frac{1 - e^{-(t-1)b}}{b} = \prod_{j=1}^{M} Y_{j}^{(1)}$$

$$= 14165.$$

The lower bound 14,165 seems quite conservative because, as noted in Section 2.4, the (expected) value of T is 180,000. If we add the first moment constraint m_1 , then using Theorem 9 in [10], we conclude that

$$\begin{array}{l} M \\ \Sigma Y_{j}(tn) = 149186.2748 - 135021.2748e^{-.0996956(t-1)} \\ j=1 \ j \end{array} \\ = 112,663.8231 \quad \text{when } t = 14.115. \end{array}$$

If we add the second moment constraint m_2 , then using Theorem 9 in [10], we conclude that

$$\sup \sum_{j=1}^{M} Y_{j}(tn) = \left\{ \frac{m_{2} - m_{1}^{2}}{m_{2}} \lim_{x \to 0} \frac{1 - e^{-(t-1)x}}{x} + \frac{m_{1}^{2}}{m_{2}} \right\}$$
$$\frac{1 - e^{-(t-1)m_{1}}}{\frac{m_{2}}{m_{1}}} \left\{ \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} + \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} + \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} + \frac{M}{j=1} \right\}$$
$$= 71448.54382 + 4365.250075t - 61648.79308$$
$$= 119.795 \qquad \text{when } t = 14.115$$

From Theorem 9 of [10] the extremum which is attained for any moment constraint (m_1, \ldots, m_r) is not improved by the addition of the (r+1)st moment constraint. Since $\sum_{j=1}^{M} Y_j(N) = 149,734$ and $\sum_{j=1}^{M} Y_j(N) = j=1$

182,529 are between 14,165 and 190,706, the bounds for k=0 make our estimator appear reasonable. But this is not true if we use the upper bound for k=2. Our feeling is that the bounds for $k \ge 1$ involve too many approximations to be accurate.



This figure shows the approximations of the supremum and infimum of population total based on a sample of size 1000 where y_j 's are from a Poisson distribution with mean 15.

CHAPTER 5

GOOD AND RAO'S METHOD

5.1 Introduction

In this chapter sampling is done with replacement.

From Chapter 3 we have the model

(M1)
$$E\begin{bmatrix} M & (r) \\ \Sigma & Z_j \\ j=1 \end{bmatrix} P_j, j=1, 2, ..., M = \begin{bmatrix} M \\ \Sigma & y_j \\ r \end{bmatrix} P_j r \begin{pmatrix} 1 - P_j \end{pmatrix} r^{n-r}$$

and

$$E[T_{s}|P_{j}, j=1, 2, ..., M] = \sum_{j=1}^{M} y_{j} [1 - (1 - P_{j})^{n}],$$

or when n is large enough from Chapter 4 we have

(M2)
$$E\begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \\ j=1 \end{bmatrix}^{\lambda} j, j=1, 2, ..., M \end{bmatrix} \cong \begin{bmatrix} M & e^{-\lambda} j\lambda_{j}^{r} \\ \Sigma & y_{j} \\ j=1 \end{bmatrix}^{r} where \lambda_{j} = nP_{j}.$$
 Also
 $E\begin{bmatrix} T_{s} \\ \lambda j, j=1, 2, ..., M \end{bmatrix} \cong \begin{bmatrix} M \\ \Sigma & y_{j} \\ j=1 \end{bmatrix}^{r} [1 - e^{-\lambda_{j}}].$

As prior distributions for P₁, P₂, ..., P_M and λ_1 , λ_2 , ..., λ_M we take beta distribution and gamma distributions respectively. We cal-

culate the posterior means of
$$\sum_{j=1}^{M} Z_{j}$$
 and T_{s} , which involve the

parameters of the prior distribution. In dealing with the model M2 (with $y_j = 1$ for all j), Rao [13] offered the pseudo method of moments to estimate the parameters of the gamma distribution. We extend this

method to model M1 and to arbitrary y_j . The expression for the posterior mean leads to an estimator of T.

5.2 Derivations for M1

Let $f(P;\alpha,\beta) = \frac{1}{B(\alpha,\beta)} P^{\alpha-1} (1-P)^{\beta-1}, 0 \leq P \leq 1$, be the density

f a beta distribution such that $\frac{\alpha+\beta}{\alpha} = M$. Therefore

$$\begin{split} & E_{p}E\begin{bmatrix} M & (r) \\ \Sigma & Z_{j} \\ j=1 \end{bmatrix} P_{j}, \ j=1, \ 2, \ \dots, \ M \end{bmatrix} = \frac{M}{j=1} y_{j} \binom{n}{r} \int_{0}^{1} P^{r} (1-P)^{n-r} f(p;\alpha,\beta) dp \\ & = \binom{n}{r} \frac{B(\alpha+r, \ \beta+n-r)}{B(\alpha,\beta)} \binom{M}{j=1} y_{j}, \ \text{and} \\ & E_{p}E\begin{bmatrix} T_{s} \middle| P_{j}, \ j=1, \ 2, \ \dots, \ M \end{bmatrix} = \frac{M}{j=1} y_{j} \int_{0}^{1} (1 - (1-P)^{n}) f(P;\alpha,\beta) dp \\ & = \begin{bmatrix} 1 - \frac{B(\alpha,\beta+n)}{B(\alpha+1, \ \beta)} \end{bmatrix} \binom{M}{j=1} y_{j} \end{pmatrix} \end{split}$$

If we can estimate α and $\beta,$ then we can form the following estimators

of
$$\sum_{j=1}^{M} y_j$$

 $T_1(M1,r) = \frac{\prod_{j=1}^{j} j_j}{\binom{n}{r} \frac{B(\hat{\alpha}+r, \hat{\beta}+n-r)}{B(\hat{\alpha}, \hat{\beta})}}$ for all r (5.1)
or $T_2(M1) = \frac{T_s}{\frac{B(\hat{\alpha}, \hat{\beta}+n)}{B(\hat{\alpha}+1, \hat{\beta})}}$ (5.2)

Let f_r be the frequency of the classes represented by r individuals,

i.e.,
$$f_r = \int_{j=1}^{M} [r_j(X_j)]$$
. Then

$$E\left[f_r \middle| P_j, j=1, 2, ..., M\right] = \int_{j=1}^{M} {n \choose r} P_j r \left(1 - P_j\right)^{n-r}, \text{ so}$$

$$E_p E\left[f_r \middle| P_j, j=1, 2, ..., M\right] = {n \choose r} \frac{B(\alpha + r, \beta + n - r)}{B(\alpha, \beta)}.$$

5.2.1 Pseudo Method of Moments for Estimating α and β

Let S denote the number of classes observed and R the number of individuals observed. Then

$$S = \sum_{r=1}^{n} f_{r}, \quad R = \sum_{r=1}^{n} r f_{r}$$

and
$$E_{p}E(S) = \sum_{r=1}^{n} {n \choose r} \frac{B(\alpha + r, \beta + n - r)}{B(\alpha, \beta)}$$
(5.3)
$$E_{p}E(R) = \sum_{r=1}^{n} r {n \choose r} \frac{B(\alpha + r, \beta + n - r)}{B(\alpha, \beta)}.$$
(5.4)

Consider the equations obtained by equating the observed values of S and R to their expectations. If these equations can be solved, we use the solutions as estimates $\hat{\alpha}$ and $\hat{\beta}$ of α and β .

5.2.2 Variances of the estimators of $\sum_{j=1}^{n} y_j$

- (I) Find the variance of $\hat{T}_1(M1, r)$: The variance of $\hat{T}_1(M1, r)$ is
- $\operatorname{Var}(\widehat{T}_{1}(M1, r)) \simeq a_{r}^{2} \operatorname{Var}(S) + b_{r}^{2} \operatorname{Var}(R) + c_{r}^{2} \operatorname{Var}\begin{pmatrix}M & (r) \\ \Sigma & Z_{j} \end{pmatrix}$ $+ 2a_{r}b_{r} \operatorname{Cov}(S, R) + 2a_{r}c_{r} \operatorname{Cov}\left(S, \frac{M}{j=1}Z_{j}\right)$ $+ 2b_{r}c_{r} \operatorname{Cov}\left(R, \frac{M}{j=1}Z_{j}\right). \qquad (5.5)$ Since R = n, Var(R) = Cov(S, R) = Cov $\left(R, \frac{M}{2}Z_{j}\right) = 0.$

To find Var(S), Var $\begin{pmatrix} M & (r) \\ \Sigma & Z_j \\ j=1 \end{pmatrix}$, and Cov $\begin{pmatrix} M & (r) \\ S, & \Sigma Z_j \\ j=1 \end{pmatrix}$, we use the following

formulas.

From Remark 3.2 we have

$$\operatorname{Cov}\left(\begin{array}{ccc} M & (r) & M & (s) \\ \Sigma & Z_{j} & \Sigma & Z_{j} \\ j=1 & j & j=1 \end{array}\right) \simeq \delta_{rs} \operatorname{E}\left[\begin{array}{c} M \\ \Sigma \\ j=1 \end{array} \begin{pmatrix} (r) \\ Z_{j} \end{pmatrix}^{2}\right] - 2^{-r-s} \begin{pmatrix} r+s \\ r \end{pmatrix} \operatorname{E}\left[\begin{array}{c} M \\ \Sigma \\ j=1 \end{pmatrix} \begin{pmatrix} (r+s) \\ Z_{j} \end{pmatrix}^{2}\right]$$

$$(5.6)$$

From (30) of [7]

$$Cov(f_r, f_s) \approx \delta_{rs} E(f_r) - 2^{-r-s} {r+s \choose r} E\left(f_{r+s}(2n)\right)$$
(5.7)

and by the same proof we get

$$\operatorname{Cov}\begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \stackrel{(r)}{=} f_{j} \stackrel{(r)}{=} f_{s} \stackrel{(r)}{=} \delta_{rs} \stackrel{(r)}{=} \left[\begin{array}{c} M \\ \Sigma \\ j=1 \end{array} \right] \stackrel{(r)}{=} 2^{-r-s} \stackrel{(r)}{=} \left[\begin{array}{c} M \\ \Sigma \\ j=1 \end{array} \right] \stackrel{(r+s)}{=} (2n) \stackrel{(r+s)}{=} (2n) \stackrel{(r)}{=} 1 \stackrel{$$

The following is to derive it.

Define
$$g_{r}(\alpha, \beta, \omega) = \frac{\omega B(\alpha, \beta)}{\binom{n}{r} B(\alpha + r, \beta + n - r)}$$
 and note that
 $\hat{T}(M1,r) = g_{r}(\hat{\alpha}, \hat{\beta}, \hat{\omega})$ where $\hat{\omega} = \sum_{j=1}^{\infty} Z_{j}$. Then
 $dg_{r} = \frac{\partial g_{r}}{\partial \alpha} d\alpha + \frac{\partial g_{r}}{\partial \beta} d\beta + \frac{\partial g_{r}}{\partial \omega} d\omega$
 $= \frac{\omega}{\binom{n}{r}} \frac{B_{\alpha}(\alpha, \beta)B(\alpha + r, \beta + n - r) - B_{\alpha}(\alpha + r, \beta + n - r)B(\alpha, \beta)}{[B(\alpha + r, \beta + n - r)]^{2}} d\alpha$
 $+ \frac{\omega}{\binom{n}{r}} \frac{B_{\beta}(\alpha, \beta)B(\alpha + r, \beta + n - r) - B_{\beta}(\alpha + r, \beta + n - r)B(\alpha, \beta)}{[B(\alpha + r, \beta + n - r)]^{2}} d\beta$
 $+ \frac{B(\alpha, \beta)}{\binom{n}{r} B(\alpha + r, \beta + n - r)} d\omega$.

Define

$$S(\alpha, \beta) = \sum_{r=1}^{n} {n \choose r} \frac{B(\alpha + r, \beta + n - r)}{B(\alpha, \beta)}$$
$$R(\alpha, \beta) = \sum_{r=1}^{n} {n \choose r} \frac{B(\alpha + r, \beta + n - r)}{B(\alpha, \beta)}$$

and note that $S(\hat{\alpha}, \hat{\beta}) = S$ and $R(\hat{\alpha}, \hat{\beta}) = R$.

We have

$$dS = \frac{n}{r=1} {n \choose r} \frac{B_{\alpha} (\alpha + r, \beta + n - r)B(\alpha, \beta) - B_{\alpha} (\alpha, \beta)B(\alpha + r, \beta + n - r)}{[B(\alpha, \beta)]^{2}} d\alpha$$

$$+ \frac{n}{r=1} {n \choose r} \frac{B_{\beta} (\alpha + r, \beta + n - r)B(\alpha, \beta) - B_{\beta} (\alpha, \beta)B(\alpha + r, \beta + n - r)}{[B(\alpha, \beta)]^{2}} d\beta$$

$$dR = \frac{n}{r=1} r {n \choose r} \frac{B_{\alpha} (\alpha + r, \beta + n - r)B(\alpha, \beta) - B_{\alpha} (\alpha, \beta)B(\alpha + r, \beta + n - r)}{[B(\alpha, \beta)]^{2}} d\alpha$$

$$+ \frac{n}{r=1} r {n \choose r} \frac{B_{\beta} (\alpha + r, \beta + n - r)B(\alpha, \beta) - B_{\beta} (\alpha, \beta)B(\alpha + r, \beta + n - r)}{[B(\alpha, \beta)]^{2}} d\beta$$

In other words, we get

$$\begin{pmatrix} dS \\ dR \end{pmatrix} = J \begin{pmatrix} d\alpha \\ d\beta \end{pmatrix}$$
where $J = \begin{pmatrix} n \\ r=1 \begin{pmatrix} n \\ r \end{pmatrix} \psi_{\alpha}^{(r)}(\alpha, \beta) \frac{n}{r=1} \begin{pmatrix} n \\ r \end{pmatrix} \psi_{\beta}^{(r)}(\alpha, \beta)$

$$\begin{pmatrix} n \\ r=1 \end{pmatrix} \psi_{\alpha}^{(r)}(\alpha, \beta) \frac{n}{r=1} r \begin{pmatrix} n \\ r \end{pmatrix} \psi_{\beta}^{(r)}(\alpha, \beta)$$

$$\frac{B_{\alpha}(\alpha+r, \beta+n-r)B(\alpha, \beta) - B_{\alpha}(\alpha, \beta)B(\alpha+r, \beta+n-r)}{[B(\alpha, \beta)]^{2}}$$

$$\dot{\psi}_{\beta}^{(r)}(\alpha, \beta) = \frac{B_{\beta}(\alpha+r, \beta+n-r)B(\alpha, \beta) - B_{\beta}(\alpha, \beta)B(\alpha+r, \beta+n-r)}{[B(\alpha, \beta)]^{2}}$$

Solving for $d\alpha$ and $d\beta$ in terms of dS and dR we obtain

$$dg_r = a_r dS + b_r dR + c_r d\omega$$

Where $a_{r}, \, b_{r}$ and c_{r} are suitable functions of α and $\beta.$ Then the

asymptotic variance of $g(\hat{\alpha}, \hat{\beta}, \hat{\omega})$, using the formula (6a.2.9) on page 322 in [12], is obtained as stated.

(II) Find the variance of $\hat{T}_2(M1)$:

In order to get $Var(\hat{T}_2(M1))$ we need for formulas (5.6), (5.7), and (5.8) and $Var(T_s) \simeq -\sum_{i=1}^{\infty} (-1)^i E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \begin{pmatrix} (i) \\ Z_j \end{pmatrix}^2$.

The approach to find $Var(\hat{T}_2(M1))$ is the same as that of (I)

except $\omega = T_s$ and

 $\psi_{\alpha}(\alpha, \beta) = \frac{\partial}{\partial \beta} \frac{\omega B(\alpha+1, \beta)}{B(\alpha, \beta+n)}$ $\psi_{\beta}(\alpha, \beta) = \frac{\partial}{\partial \beta} \frac{B(\alpha+1, \beta)}{B(\alpha, \beta+n)} .$

5.3 Example of M1

For the example of Section 3.5, the equations of the pseudo method of moments estimators for α and β are

$$949 = \begin{pmatrix} 1000 \\ 1 \end{pmatrix} \frac{B(\alpha+1, \beta+999)}{B(\alpha, \beta)} + \begin{pmatrix} 1000 \\ 2 \end{pmatrix} \frac{B(\alpha+2, \beta+998)}{B(\alpha, \beta)} + \begin{pmatrix} 1000 \\ 3 \end{pmatrix} \frac{B(\alpha+3, \beta+997)}{B(\alpha, \beta)}$$

$$1,000 = \begin{pmatrix} 1000\\1 \end{pmatrix} \frac{B(\alpha+1, \beta+999)}{B(\alpha, \beta)} + 2 \begin{pmatrix} 1000\\2 \end{pmatrix} \frac{B(\alpha+2, \beta+998)}{B(\alpha, \beta)} + 3 \begin{pmatrix} 1000\\3 \end{pmatrix} \frac{B(\alpha+3, \beta+997)}{B(\alpha, \beta)} .$$

Unfortunately, there do not exist solutions for α and β . That is, the method of moments does not work in this example.

5.4 Derivations for M2

We have

and
$$E\begin{bmatrix} M & Z_{j}(r) \\ j=1 & Z_{j}(r) \\ j=1 & J \end{bmatrix} \begin{pmatrix} M & J \\ j=1 & J \end{pmatrix} \begin{pmatrix} M & J \\ j=1 & J \end{pmatrix} \begin{pmatrix} -\lambda & J \end{pmatrix} \begin{pmatrix} -\lambda & J \\ j=1 & J \end{pmatrix} \begin{pmatrix} -\lambda & J \end{pmatrix} \begin{pmatrix} -\lambda$$

Suppose that λ_1 , λ_2 , ... , and λ_M can be approximated by a gamma distribution with density

$$\frac{1}{\Gamma(\alpha)\beta^{\alpha}} \lambda^{\alpha-1} e^{-\lambda/\beta} d\lambda .$$

Hence

and

$$E_{\lambda}E\begin{bmatrix}M\\\Sigma\\j=1\\J\end{bmatrix} Z_{j}^{(r)} \left[\lambda_{j}, j=1, 2, ..., M\right] = \frac{\Gamma(\alpha+r)}{r!\Gamma(\alpha)} \frac{1}{(1+\beta)^{\alpha}} \left(\frac{\beta}{1+\beta}\right)^{r} \left(\frac{M}{2}y_{j}\right)$$

$$E_{\lambda}E\begin{bmatrix}T_{s} \left[\lambda_{j}, j=1, 2, ..., M\right] = \left[1 - \frac{1}{(1+\beta)^{\alpha}}\right] \left(\frac{M}{2}y_{j}\right)$$

If we can estimate α and $\beta,$ then we can form the following estimators

of
$$\sum_{j=1}^{M} y_{j}$$
:
 $\hat{T}_{1}(M2,r) = \frac{\prod_{j=1}^{M} Z_{j}(r)}{\prod_{j=1}^{r} (\hat{\alpha}+r) \prod_{j=1}^{r} (\hat{\alpha}+r) \prod_{j=1}^{r} (\hat{\alpha}) \prod_{j=1}^{r} (\hat{\beta})^{\hat{\alpha}} (\hat{\beta}) \prod_{j=1}^{r} for all r$
(5.9)

or

T

$$\hat{T}_{2}(M2,r) = \frac{\frac{1}{1}}{1 - \frac{1}{(1+\hat{\beta})^{\hat{\alpha}}}} \cdot$$

Since

(5.10)

$$E_{\lambda} E\left[f_{r} \middle| \lambda_{j}, j=1, 2, ..., M\right] = M \frac{\Gamma(\alpha+r)}{r! \Gamma(\alpha)} \frac{1}{(l+\beta)^{\alpha}} \left(\frac{\beta}{l+\beta}\right)^{r}$$
$$= \tau \frac{\Gamma(\alpha+r)}{r! \Gamma(\alpha)} \frac{1}{(l+\beta)^{\alpha}} \left(\frac{\beta}{l+\beta}\right)^{r} \quad \text{where } \tau = M\alpha ,$$

we can find estimators of α , $\beta,$ and τ in terms of the fr.

5.4.1 Pseudo Method of Moments for Estimating α , β , and τ

Define
$$S = \sum_{r=1}^{n} f_r$$
, $R = \sum_{r=1}^{n} r f_r$ and $U = \sum_{r=1}^{n} r^2 f_r$. Then

$$E_{\lambda} E(S) = \tau \frac{\left[1 - (1 + \beta)^{-\alpha}\right]}{\alpha}$$
(5.11)

$$E_{\lambda}E(R) = \tau\beta$$
 (5.12)

$$E_{\lambda}E(U) = \tau\beta(1 + \beta + \alpha\beta) . \qquad (5.13)$$

Equating observed values of S, R, and U to their expectations, we obtain estimates $\hat{\alpha}$, $\hat{\beta}$, and $\hat{\tau}$ (if the solutions exist) of α , β , and τ .

5.4.2 Variances of the estimators of $\sum_{j=1}^{M} y_j$ (I) Find the variance of $\hat{T}_1(M_2, r) = \frac{\prod_{j=1}^{M} Z_j(r)}{\prod_{j=1}^{r} (\hat{\alpha}+r) \prod_{j=1}^{r} (\hat{\alpha}) (1+\hat{\beta})^{\hat{\alpha}} (\hat{\beta}) r}$: Define $g_r(\alpha, \beta, \tau, \omega) = \frac{\omega}{\prod_{j=1}^{r} (\alpha+r) \prod_{j=1}^{r} (1+\beta)^{\alpha}} (\frac{\beta}{1+\beta})^r$ and note that $\hat{T}_1(M_2, r) = g_r(\hat{\alpha}, \hat{\beta}, \hat{\tau}, \hat{\omega})$ where $\hat{\omega} = \sum_{j=1}^{M} Z_j(r)$. Then

$$dg_{r} = \frac{\partial g_{r}}{\partial \alpha} d\alpha + \frac{\partial g_{r}}{\partial \beta} d\beta + \frac{\partial g_{r}}{\partial \tau} d\tau + \frac{\partial g_{r}}{\partial \omega} d\omega \qquad (5.14)$$

where

$$\frac{\partial g}{\partial \alpha} = \omega r! (l+\beta)^{\alpha} \left(\frac{1+\beta}{\beta}\right)^{r} \left\{ \frac{\Gamma'(\alpha)\Gamma(\alpha+r) - \Gamma'(\alpha+r)\Gamma(\alpha)}{[\Gamma(\alpha+r)]^{2}} + \frac{\Gamma(\alpha)}{\Gamma(\alpha+r)} \ln(1+\beta) \right\}$$

$$\frac{\partial g}{\partial \beta} = \omega \frac{r!\Gamma(\alpha)}{\Gamma(\alpha+r)} (l+\beta)^{\alpha-1} \left(\frac{1+\beta}{\beta}\right)^{r-1} \left\{ \alpha \left(\frac{1+\beta}{\beta}\right) - \frac{r}{\beta^{2}} (l+\beta) \right\}$$

$$\frac{\partial g}{\partial \tau} = 0$$

$$\frac{\partial g}{\partial \omega} = \frac{r!\Gamma(\alpha)}{\Gamma(\alpha+r)} \alpha (l+\beta)^{\alpha-1} \left(\frac{1+\beta}{\beta}\right)^{r}.$$

Define

$$S(\alpha, \beta, \tau) = \tau \frac{\left[1 - (1+\beta)^{-\alpha}\right]}{\alpha}$$

$$R(\alpha, \beta, \tau) = \tau\beta$$
$$U(\alpha, \beta, \tau) = \tau\beta(l+\beta + \alpha\beta)$$

and note that $S(\alpha, \beta, \tau) = S$, $R(\alpha, \beta, \tau) = R$, and $U(\alpha, \beta, \tau) = U$. We have

 $\begin{bmatrix} dS \\ dR \\ dU \end{bmatrix} = J_1 \begin{bmatrix} d\alpha \\ d\beta \\ d\tau \end{bmatrix}$

where

$$J_{1} = \begin{pmatrix} \frac{\tau}{\alpha^{2}} \left\{ -1 + (\mathbf{l} + \beta)^{-\alpha} [\mathbf{l} + \log (\mathbf{l} + \beta)] \right\} & \tau (\mathbf{l} + \beta)^{-\alpha - 1} & \frac{1 - (\mathbf{l} + \beta)^{-\alpha}}{\alpha} \\ 0 & \tau & \beta \\ \tau \beta^{2} & \tau (\mathbf{l} + 2\beta + 2\alpha\beta) & \beta (\mathbf{l} + \beta + \alpha\beta) \\ \end{pmatrix}.$$

Solving for $d\alpha$, $d\beta$, and $d\tau$ in terms of dS, dR, and dU we obtain

$$dg_r = a_r dS + b_r dR + c_r dU + d_r d\omega$$

where a_r , b_r , c_r , and d_r are suitable functions of α , β , τ , and ω . Then the asymptotic variance of $g(\hat{\alpha}, \hat{\beta}, \hat{\tau}, \hat{\omega})$, using the formula (6a.2.9) on page 322 in [12], is

$$\operatorname{Var}(\widehat{T}_{1}(M2, r)) = a_{r}^{2}\operatorname{Var}(S) + b_{r}^{2}\operatorname{Var}(R) + c_{r}^{2}\operatorname{Var}(U)$$

$$+ d_{r}^{2}\operatorname{Var}\begin{pmatrix} M & (r) \\ \Sigma & Z_{j} \end{pmatrix} + 2a_{r}b_{r}\operatorname{Cov}(S, R) + 2a_{r}c_{r}\operatorname{Cov}(S, U)$$

$$+ 2a_{r}d_{r}\operatorname{Cov}\left(S, \begin{array}{c} M & (r) \\ j=1 \end{array}\right) + 2b_{r}c_{r}\operatorname{Cov}(R, U) + 2b_{r}d_{r}\operatorname{Cov}\left(R, \begin{array}{c} M & (r) \\ j=1 \end{array}\right)$$

$$+ 2c_{r}d_{r}\operatorname{Cov}\left(U, \begin{array}{c} M & Z_{j} \\ j=1 \end{array}\right) + 2b_{r}c_{r}\operatorname{Cov}(R, U) + 2b_{r}d_{r}\operatorname{Cov}\left(R, \begin{array}{c} M & (r) \\ j=1 \end{array}\right)$$

$$(5.15)$$

From [13] on page 136 we get

$$\operatorname{Cov}\left[\begin{array}{c} S\\ R\\ U\end{array}\right] = \left[\begin{array}{c} \frac{\tau\left[\left(1+\beta\right)^{-\alpha}-\left(2+\beta\right)^{-\alpha}\right]}{\alpha} & \tau\beta(1+\beta)^{-\alpha-1} & \tau\beta(1+\beta)^{-\alpha-2}(2+\alpha+\beta) \\ \tau\beta(1+\beta)^{-\alpha-1} & \tau\beta & \tau\beta[1+2\beta(\alpha+1)] \\ \tau\beta(1+\beta)^{-\alpha-2}(2+\alpha+\beta) & \tau\beta[1+2\beta(\alpha+1)] & \tau\beta[4+3\beta(\alpha+1)+4\beta^{2}(\alpha+1)(\alpha+2)] \end{array}\right] (5.16)$$

Remark 5.1:

(1)
$$\sum_{j=1}^{M} Z_{j}^{(r)}(tn) = t^{r} \sum_{i=0}^{\infty} (-1)^{i} {r+i \choose r} (t-1)^{i} {M \choose \Sigma} Z_{j}^{(r+i)} by Remark 3.1$$

If we consider Euler's transformation assuming that $\sum_{j=1}^{M} Z_j^{(r)}$

decreases slowly after the first term, then

$$\sum_{j=1}^{M} Z_{j}^{(1)}(tn) \approx t \sum_{j=1}^{\Sigma} Z_{j}^{(1)} - 2(t-1) \sum_{j=1}^{M} Z_{j}^{(2)}$$
(5.17)

and

$$\begin{split} & \underset{j=1}{\overset{M}{\Sigma}} Z_{j}^{(r)}(tn) = t^{r-1} \underset{j=1}{\overset{M}{\Sigma}} Z_{j}^{(r)} \text{ when } r \geq 2. \end{split} (5.18) \\ & (2) \quad \text{Since } \operatorname{Cov}\left(S, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = \operatorname{Cov}\left(M - f_{0}, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = -\operatorname{Cov}\left(f_{0}, \\ & \\ & \\ & \\ & \underset{j=1}{\overset{M}{\Sigma}} Z_{j}^{(r)} \end{array}\right) = 2^{-r} E\left[\begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)}(2n) \\ \frac{\Sigma}{j=1} Z_{j}^{(r+1)} \end{array}\right], \\ & (2) \quad \operatorname{Cov}\left(S, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = \frac{\sigma}{1=0} (-1)^{1} \binom{r+1}{r} \underset{j=1}{\overset{K}{J}} Z_{j}^{(r+1)} \text{ without Euler's transformation} \\ & \text{or } (2) \quad \left(S, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = \left(\begin{array}{c} M \\ \frac{\Sigma}{2} Z_{j}^{(r)} - \frac{M}{2} Z_{j}^{(2)} \\ \frac{1}{2} - \frac{\Sigma}{2} Z_{j}^{(r)} \end{array}\right) \text{ when } r \geq 2. \end{aligned} \\ & (3) \quad \operatorname{Cov}\left(R, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = 0 \quad \text{for all } r \text{ since } R = n. \end{aligned} \\ & (4) \quad \operatorname{Since } \operatorname{Cov}\left(U, \begin{array}{c} M \\ \frac{\Sigma}{j=1} Z_{j}^{(r)} \end{array}\right) = \operatorname{Cov}\left(\begin{array}{c} n \\ \frac{\Sigma}{2} S^{2} f_{s}, \begin{array}{c} M \\ \frac{\Sigma}{2} Z_{j}^{(r)} \end{array}\right) = \\ & \quad \\$$

$$\hat{\text{Cov}}\left(U, \frac{M}{\sum} Z_{j}^{(r)}\right) = r^{2} \frac{M}{\sum} Z_{j}^{(r)} - \frac{n}{\sum} s^{2} \frac{n}{\sum} (-1)^{i} \binom{r+s+i}{r}$$

$$\begin{pmatrix} \frac{M}{\sum} Z_{j}^{(r+s+i)} \\ j=1 \end{pmatrix} \text{ without Euler's transformation}$$
or $\hat{\text{Cov}}\left(U, \frac{M}{\sum} Z_{j}^{(r)}\right) = r^{2} \frac{M}{\sum} Z_{j}^{(r)} - \frac{1}{2} \sum_{s=1}^{n} s^{2} \binom{M}{\sum} Z_{j}^{(r+s)}$

with Euler's transformation.

(5) From Remark 3.2(1) we have

$$\operatorname{Var}\left(\frac{M}{\substack{\Sigma\\j=1}}Z_{j}^{(r)}\right) = \frac{M}{\substack{\Sigma\\j=1}}\left(Z_{j}^{(r)}\right)^{2} - 2^{-2r}\left(\frac{2r}{r}\right)\sum_{j=1}^{M}\left(Z_{j}^{(2r)}(2n)\right)^{2}$$
$$= \frac{M}{\substack{\Sigma\\j=1}}\left(Z_{j}^{(r)}\right)^{2} - \left(\frac{2r}{r}\right)\sum_{i=0}^{\infty}(-1)^{i}\left(\frac{2r+i}{2r}\right)\left[\frac{M}{\substack{\Sigma\\j=1}}\left(Z_{j}^{(2r+i)}\right)^{2}\right]$$

without Euler's transformation.

or
$$\operatorname{Var}\begin{pmatrix} M \\ j=1 \\ j \end{pmatrix} = \frac{M}{j=1} \begin{pmatrix} Z(r) \\ j \end{pmatrix}^2 - \frac{1}{2} \begin{pmatrix} 2r \\ r \end{pmatrix} \frac{M}{j=1} \begin{pmatrix} Z(2r) \\ j \end{pmatrix}^2$$

with Euler's transformation assuming that $\sum_{j=1}^{M} \begin{pmatrix} Z(r) \\ j \end{pmatrix}^2$

decreases slowly after the first term.

(II) Find the variance of $\hat{T}_2(M2) = \frac{T_s}{1 - \frac{1}{(1 + \hat{\beta})^{\hat{\alpha}}}}$:

Define
$$g(\alpha, \beta, \tau, \omega) = \frac{\omega}{1 - \frac{1}{(1+\beta)^{\alpha}}}$$
 and note that

$$\hat{T}_{2}(M2) = g(\hat{\alpha}, \hat{\beta}, \hat{\tau}, \hat{\omega}) \text{ where } \hat{\omega} = T_{s}. \text{ Then}$$

$$dg = \frac{\partial g}{\partial \alpha} d\alpha + \frac{\partial g}{\partial \beta} d\beta + \frac{\partial g}{\partial \tau} d\tau + \frac{\partial g}{\partial \omega} d\omega \qquad (5.19)$$

where

$$\frac{\partial g}{\partial \alpha} = \frac{-\omega(1+\beta)^{\alpha} \ln(1+\beta)}{\left[(1+\beta)^{\alpha} - 1\right]^{2}}$$
$$\frac{\partial g}{\partial \beta} = \frac{-\alpha\omega(1+\beta)^{\alpha-1}}{\left[(1+\beta) - 1\right]^{2}}$$

$$\frac{\partial g}{\partial \tau} = 0$$

$$\frac{\partial g}{\partial \omega} = \frac{(1+\beta)^{\alpha}}{(1+\beta)^{\alpha} - 1}$$

Using the same approach as (I) we get

$$\partial g = a \partial S + b \partial R + c \partial U + d \partial \omega$$
 (5.20)

where a, b, c and d are suitable functions of $\alpha,\ \beta,\ \tau,$ and ω and

$$Var (\hat{T}_2(M2)) = a^2 Var(S) + b^2 Var(R) + c^2 Var(U) + d^2 Var(T_S)$$

+ 2abCov(S, R) + 2acCov(S, U) + $2adCov(S, T_S)$ + 2bcCov

 $(R, U) + 2bdCov(R, T_s) + 2cdCov(U, T_s)$

where

$$Cov(S, T_{s}) = \sum_{r=1}^{n} Cov\left(S, \sum_{j=1}^{M} Z_{j}^{(r)}\right)$$

$$Cov(R, T_s) = 0$$

$$Cov(U, T_s) = \sum_{r=1}^{n} Cov\left(U, \sum_{j=1}^{M} Z_j^{(r)}\right).$$

5.5 Example of M2

We now apply this method to the example in Section 3.5. We have

$$\hat{\tau} \frac{\left[1 - (1 + \hat{\beta})^{-\hat{\alpha}}\right]}{\hat{\alpha}} = 949 ,$$
$$\hat{\tau}\hat{\beta} = 1,000 , \text{ and}$$
$$\hat{\tau}\hat{\beta}(1 + \hat{\beta} + \hat{\alpha}\hat{\beta}) = 1,106.$$

The solutions are

For

$$\begin{cases} \hat{\alpha} = 8.78268266064 \\ \hat{\beta} = .01083547363 \text{ or } \\ \hat{\tau} = 92287.45906 \end{cases} \begin{cases} \hat{\alpha} = -.00000057585 \text{ (not reasonable)} \\ \hat{\beta} = .10600006104 \\ \hat{\tau} = 9433.956832 \text{ .} \end{cases}$$
$$r=1, \hat{T}_{1}(M2, r=1) = \frac{M}{\Gamma(\hat{\alpha}+1)} \frac{\hat{\beta}}{(\hat{\alpha})} \frac{\hat{\beta}}{(1+\hat{\beta})^{\hat{\alpha}+1}} = 157,177$$

for r=2,
$$\hat{T}_{1}(M2, r=2) = \frac{\prod_{j=1}^{K} Z_{j}}{\frac{\Gamma(\hat{\alpha}+2)}{2!\Gamma(\hat{\alpha})} - \frac{\hat{\beta}^{2}}{(1+\hat{\beta})^{\hat{\alpha}+2}}} = 149,431$$
, and
for r=3, $\hat{T}_{1}(M2, r=3) = \frac{\prod_{j=1}^{K} Z_{j}^{(3)}}{\frac{J_{j=1}}{3!\Gamma(\hat{\alpha})} - \frac{\hat{\beta}^{3}}{(1+\beta)^{\alpha+3}}} = 190,747$.
Also,
 $\hat{T}_{2}(M2) = \frac{\prod_{j=1}^{K} Y_{j}}{1 - \frac{1}{(1+\hat{\beta})^{\hat{\alpha}}}} = 156,847$

Now let us consider the variance $\hat{Var}(\hat{T}_1(M2, r))$

٢٩	9536.16	899.92	9609.16
$Cov \begin{vmatrix} S \\ R \end{vmatrix} =$	899.92	999.98	1211.97
	9609.16	1211.97	4367.23

$$J_{1}^{-1} = \begin{cases} -.0109521933736 & .016007251633 & -.005069705794336 \\ .00001213084646318 & -.0001307821596695 & .000107839046779 \\ -103.3903909322 & 1206.182399682 & -918.4826883093 \end{cases}$$

when r=1

 $a_1 = 19.936073931$ $b_1 = 1438.915688$

 $c_1 = -1318.114736$ $d_1 = 101.45170575$

$$\hat{Cov}\left(S, \sum_{j=1}^{N} Z_{j}\right) = \begin{cases} 12,218 \text{ without Euler's transformation} \\ 12,790 \text{ with Euler's transformation} \end{cases}$$

ć

$$\hat{Cov}$$
 $\begin{pmatrix} M & (1) \\ \Sigma & Z_{j} \\ j=1 \end{pmatrix}$ =
 $\begin{cases} 11,822 \text{ without Euler's transformation} \\ 13,059.5 \text{ with Euler's transformation} \end{cases}$

$$\hat{Var}\begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} = \begin{cases} 197,593 & \text{without Euler's transformation} \\ 204,456 & \text{with Euler's transformation} \end{cases}$$

Therefore

$$Var(\hat{T}_{1}(M2, r=1) = \begin{cases} 3.532533918 \times 10^{9} & \text{without Euler's transformation} \\ 3.274515433 \times 10^{9} & \text{with Euler's transformation} \end{cases}$$

The relative standard error is

{ .38 without Euler's transformation
 .36 with Euler's transformation

when r=2

$$a_2 = 20.754798748$$

 $b_2 = 2907.842194$
 $c_2 = -2646.960626$
 $d_2 = 1934.924667$

 $\hat{Cov}\left(S, \begin{array}{c}M\\j=1\end{array}^{\Sigma}Z_{j}\right) = \begin{cases} 572 \text{ without Euler's transformation}\\ 335.5 \text{ with Euler's transformation} \end{cases}$

$$\hat{\text{Cov}}\begin{pmatrix} M & (2) \\ J = 1 & j \end{pmatrix} = \begin{cases} 2,585 \text{ without Euler's transformation} \\ 2,667.5 \text{ with Euler's transformation} \end{cases}$$

$$\hat{\text{Var}}\begin{pmatrix} M & (2) \\ \Sigma & Z_j \\ j=1 & j \end{pmatrix} = 10,157 \text{ with and without Euler's transformation}$$

Therefore

$$\hat{Var}(\hat{T}_1(M2, r=2) = \begin{cases} 3.104794347 \times 10^{10} & \text{without Euler's transformation} \\ 3.018387282 \times 10^{10} & \text{with Euler's transformation} \end{cases}$$

The relative standard error is

when r=3

ag ≈	8.967069573	p3 =	5706.407682
C3 =	-5167.194706	d3 =	50,221.67689

$$\hat{cov}\left(S, \begin{array}{c}M & (3)\\ j=1\end{array}\right) = \begin{cases} 33 \text{ without Euler's transformation} \\ 16.5 \text{ with Euler's transformation} \end{cases}$$

$$\hat{\text{Cov}}\left(\bigcup_{j=1}^{M} Z_{j}^{(3)}\right) = 297$$
 with and without Euler's transformation
 $\hat{\text{Cov}}\left(\bigcup_{j=1}^{M} Z_{j}^{(3)}\right) = 549$ with and without Euler's transformation

Therefore

$$\hat{Var}(\hat{T}_{1}(M2, r=3)) = \begin{cases} 1.307477378 \times 10^{12} & \text{without Euler's transformation} \\ 1.307376523 \times 10^{12} & \text{with Euler's transformation} \end{cases}$$

The relative standard error is

= $\begin{cases} 5.99 & \text{without Euler's transformation} \\ 5.99 & \text{with Euler's transformation} \end{cases}$

Now let us consider $Var(\hat{T}_2(M2))$

Since	a	=	19.961152284	þ	=	1522.798549
	с	=	-1393.979799	d	=	11.072835296

and $\hat{Cov}(S, T_S) = \begin{cases} 12,823 & \text{without Euler's transformation} \\ 13,142 & \text{with Euler's transformation} \end{cases}$

 $\hat{Cov}(U, T_s) = \begin{cases} 14,704 & \text{without Euler's transformation} \\ 16,024 & \text{with Euler's transformation} \end{cases}$

$$\hat{cov}(T_{s}) = \begin{cases} 208,299 \text{ without Euler's transformation} \\ 215,162 \text{ with Euler's transformation} \end{cases}$$

$$\hat{Var}(\hat{T}_{2}(M2)) = \begin{cases} 4.76078734 \times 10^{9} \text{ without Euler's transformation} \\ 4.721020597 \times 10^{9} \text{ with Euler's transformation} \end{cases}$$

The relative standard error is

{ .44 without Euler's transformation
 .44 with Euler's transformation

These calculations are summarized in Table 5.1.

From the information above in this case we would choose the estimate of $\sum_{j=1}^{r} y_j$ to be $\hat{T}_1(M2, r=1) = 157,177$

with the relative standard error is .36.

		estimated variance		relative standard error		
	population total	without Euler's transformation	with Euler's transformation	without Euler's transformation	with Euler's transformation	
Ĵ,(M2,r=1)	157,177	3.532533918x10 ⁹	3.274515443x10 ⁹	.38	.36	
(M2,r=2)	149,431	3.104794347×10 ¹⁰	3.018387282x10 ¹⁰	1.18	1.16	
Ĵ _l (M2,r=3)	190,747	1.307477378X10 ¹²	1.307376523x10 ¹²	5.99	5.99	
τ ₂ (M2)	156,847	4.76078734x10 ⁹	4.721020597x10 ⁹	. 44	.44	

Table 5.1: Estimated population total, estimated variance, and relative standard error.

CHAPTER 6

EFRON AND THISTED'S METHOD

6.1 Introduction

In this chapter we still consider sampling with replacement. Efron and Thisted [2] tried to find a reasonable estimator of d(∞) supposing that E(f_r) = $M \int \frac{e^{-\lambda} \lambda^{X}}{x!} dG(\lambda)$ for some distribution G. If G(λ) is a gamma distribution with parameters α , β , then an estimator of d(tn) is

$$\hat{d}(tn) = \begin{cases} \frac{f_1}{\gamma \alpha} \left[1 - \frac{1}{(1+\gamma t)^{\alpha}} \right] & \text{if } \alpha > 0 \\ \frac{f_1}{\gamma} \log (H\gamma t) & \text{if } \alpha = 0 \end{cases}$$

where $\gamma = \frac{\beta}{1+\beta}$.

He also found other possible estimators.

(1)
$$\hat{d}(tn) = \sum_{X=1}^{\infty} (-1)^{X+1} f_X t^X$$
, or

if Euler's transformation is considered, then

$$\hat{d}(tn) = \sum_{y=1}^{X_0} \xi_y u^y \text{ where } \xi_y = \sum_{X=1}^{Y} \left(\frac{y-1}{x-1} \right) \frac{(-1)^{X+1}}{2^Y} f_X \text{ and } t = \frac{u}{2-u}$$

$$(2) \quad \hat{d}(tn) = \sum_{X=1}^{\infty} (-1)^{X+1} \hat{f}_X t^X \text{ where } \hat{f}_X = f_1 \frac{\Gamma(X+\alpha)}{X!\Gamma(1+\alpha)} \gamma^{X-1}$$

=
$$f_1 t \sum_{x=1}^{\infty} (-1)^{x+1} \frac{\Gamma(x+\alpha)}{x! \Gamma(1+\alpha)} (\gamma t)^{x-1}$$

which can also be modified by Euler's transformation.

We generalize their derivations to estimate T = $\sum_{j=1}^{M} y_j$ by using

$$\Delta(\infty) \text{ where } \Delta(tn) = E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Z_j^{(1)} \int \frac{e^{-\lambda}(1-e^{-\lambda t})dG(\lambda)}{\int e^{-\lambda}\lambda dG(\lambda)} \text{ , and we also derive}$$

the biases of these estimators to measure their precision.

6.2 Nonparametric Model

From Chapter 4, lemma 4.1, we know

$$E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Z_{j}^{(x)} \lambda_{j} = \frac{M}{j=1} y_{j} \frac{e^{-\lambda_{j}} \lambda_{j} x}{x!^{j}}$$

1

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Suppose that M is large and the frequency distribution of values λ_1 , ..., λ_M can be approximated by a continuous distribution G(λ). Then,

$$E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} = E_{\lambda} E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \lambda_{j}, j=1, \dots, M = \begin{pmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \int \frac{e^{-\lambda_{\lambda} x}}{x!} dG(\lambda).$$

Define

$$Y_j(tn) = y_j \delta_j(tn) = \begin{cases} y_j & \text{if the jth class shows in the second} \\ sample of size tn but does not show the basic sample \\ 0 & \text{otherwise} \end{cases}$$

where

$$\delta_{j}(tn) = \begin{cases} 1 & \text{if the jth class shows in the second sample of size tn but does not show in the basic sample} \\ 0 & \text{otherwise} \end{cases}$$

and

$$\Delta(t) = E_{\lambda} E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} Y_{j}(tn) \left| \lambda_{j} \right|.$$

We have

$$\Delta(t) = E_{\lambda} \begin{cases} M \\ \Sigma \\ j=1 \end{cases} y_{j} \left(1 - P_{j}\right)^{n} \left[1 - \left(1 - P_{j}\right)^{n}t\right] \end{cases}$$

$$\approx E_{\lambda} \begin{cases} M \\ \Sigma \\ j=1 \end{cases} y_{j} e^{-nP_{j}} \left(1 - e^{-ntP_{j}}\right) \end{cases}$$

$$= E_{\lambda} \begin{cases} M \\ \Sigma \\ j=1 \end{cases} y_{j} e^{-\lambda_{j}} \left(1 - e^{-\lambda_{j}t}\right) \end{cases} \text{ where } \lambda_{j} = nP_{j}$$

$$= \left(\sum_{j=1}^{M} y_{j} \right) \int e^{-\lambda} \left(1 - e^{-\lambda t}\right) dG(\lambda) \qquad (6.1)$$

$$= E \begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} \frac{\int e^{-\lambda} (1 - e^{-\lambda t}) dG(\lambda)}{\int e^{-\lambda} \lambda dG(\lambda)}$$
(6.2)

We wish to estimate $\Delta(t)$. Substituting the expansion

$$1 - e^{-\lambda t} = \lambda t - \frac{\lambda^2 t^2}{2!} + \frac{\lambda^3 t^3}{3!} - + \dots$$

into (6.1), we obtain

$$\Delta(t) \simeq E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} t - E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} t^{2} + E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix} t^{3} -+ \dots (6.3)$$

This result appears in Remark 3.1.(5) in Chapter 3. The right-hand side need not converge, but assuming it does, this suggests an estimator for $\Delta(t)$

$$\hat{\Delta}(t) = \begin{pmatrix} M \\ \Sigma Z_{j}^{(1)} \\ j=1 \end{pmatrix} t - \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} t^{2} + \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} t^{3} -+ \dots$$
 (6.4)

The estimator $\hat{\Delta}(t)$ is a function of the data only through the statistics $\stackrel{M}{\underset{j=1}{\Sigma}} Z_{j}^{(x)}$. Unfortunately $\hat{\Delta}(t)$ is useless for values of t larger than 1. The geometrically increasing magnitude of t^{x} produces wild oscillations in $\hat{\Delta}(t)$ as the number of terms increases.

6.3 Parametric Model with a Gamma Distribution for $G(\lambda)$

The c.d.f. $G(\lambda)$ is approximated by a gamma distribution with density,

$$g(\lambda) = \frac{1}{\Gamma(\alpha)\beta^{\alpha}} \lambda^{\alpha-1} e^{-\lambda/\beta}$$
(6.5)

Therefore

$$E\begin{bmatrix}M\\\Sigma\\j=1\\Z\end{bmatrix} = \begin{pmatrix}M\\\Sigma\\j=1\\Z\end{bmatrix} \int \frac{e^{-\lambda}\lambda^{X}}{x!} dG(\lambda) = \begin{pmatrix}M\\\Sigma\\j=1\\Y\end{bmatrix} \frac{1}{\Gamma(\alpha)\beta^{\alpha}} \frac{\lambda^{\alpha+X-1}e^{-\lambda(1+\frac{1}{\beta})}}{x!} d\lambda$$
$$= \begin{pmatrix}M\\\Sigma\\j=1\\Y\end{bmatrix} \frac{1}{\Gamma(\alpha)\beta^{\alpha}} \frac{\Gamma(X+\alpha)}{x!} \gamma^{\alpha+X} \text{ where } \gamma = \frac{\beta}{1+\beta}$$
$$= E\begin{bmatrix}M\\\Sigma\\j=1\\Z\end{bmatrix} \frac{\Gamma(X+\alpha)}{x!\Gamma(1+\alpha)} \gamma^{X+1} \tag{6.6}$$

 $E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}$ is proportional to the negative binomial distribution with

parameters α and γ . Integrating (6.2) we obtain

$$\Delta(t) \simeq \begin{cases} \frac{E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}}{\alpha \gamma} \left[1 - \frac{1}{(1+\gamma t)^{\alpha}}\right] \text{ if } \alpha > 0 \\ \frac{E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}}{\gamma} \log(1+\gamma t) \text{ if } \alpha = 0 \end{cases}$$

$$(6.7)$$

Hence

$$\hat{\Delta}(\tau) = \begin{cases} \frac{M}{\sum Z_{j}^{(1)}} \left[1 - \frac{1}{(1+\hat{\gamma}t)^{\hat{\alpha}}}\right] & \text{if } \hat{\alpha} > 0 \\ \frac{M}{\sum Z_{j}^{(1)}} \left[\frac{1}{j=1} - \frac{1}{(1+\hat{\gamma}t)^{\hat{\alpha}}}\right] & \text{if } \hat{\alpha} = 0 \end{cases}$$

6.3.1 Example

From Section 5.5 we obtained

$$\hat{\alpha} = 8.78268266064$$
 $\hat{\beta} = .01083547363$ $\hat{\gamma} = .01071932467$
so $\hat{\Delta}(t) = 142,982.4414 \left[1 - \frac{1}{(1+.01071932467t)^{8.78268266064}} \right]$

(see Figure 6.1). Hence we can claim $\hat{T} = \hat{\Delta}(\infty) = 142,982$. Using the same approach as that of the last chapter, we can find the asymptotic variance of $\hat{\Delta}(t)$

 $\hat{Var}(\hat{\Delta}(\infty)) \simeq \begin{cases} 4.29237317 \times 10^9 & \text{without Euler's transformation} \\ 4.258910831 \times 10^9 & \text{with Euler's transformation} \end{cases}$ The relative standard error is

Figure 6.1



66
6.4 Euler's Transformation

Euler's transformation is a method of forcing oscillating series

like
$$\Delta(t) = \sum_{x=1}^{\infty} (-1)^{x+1} \pi_x t^x$$
, where $\pi_x = E\begin{bmatrix} M \\ \Sigma \\ j=1 \end{bmatrix}$, to converge rapidly.

Efron and Thisted showed

$$\Delta(t) = \sum_{X=1}^{\infty} (-1)^{X+1} \eta_X t^X = \sum_{y=1}^{\infty} \xi_y u^y \text{ where } t = \frac{u}{2-u} , \ 0 \le u \le 2,$$

and $\xi_y = \sum_{X=1}^{y} {\binom{y-1}{x-1}} \frac{(-1)^{X+1}}{2^y} \eta_X .$

6.4.1 Nonparametric Estimator for $\Delta(t)$

Define

$$\Delta_{E}(u) = \sum_{y=1}^{\infty} \xi_{y} u^{y}$$
$$\Delta^{X_{0}}(t) = \sum_{x=1}^{X_{0}} (-1)^{x+1} \eta_{x} t^{x}$$
$$\Delta_{E}^{X_{0}}(u) = \sum_{y=1}^{X_{0}} \xi_{y} u^{y} .$$

Good and Toulmin suggest estimating $\Delta(t)$ by

$$\hat{\Delta}^{X_0}(u) = \sum_{\substack{y=1\\y=1}}^{X_0} \hat{\xi}_y u^y \text{ where } u = \frac{2t}{1+t} \text{ and}$$

$$\hat{\xi}_y = \sum_{\substack{x=1\\x=1}}^{y} \binom{y-1}{x-1} \frac{(-1)^{x+1}}{2^y} \hat{\eta}_x \text{ . The } \hat{\eta}_x \text{ is taken to be the nonparametric estimator } \prod_{\substack{z=1\\i=1}}^{M} Z_j^{(x)}.$$

6.4.2 Parametric Estimator for $\Delta(t)$

From (6.3) and (6.6) we know

$$\Delta(t) \approx n_1 t - n_2 t^2 + n_3 t^3 - + \dots$$

$$\eta_{\mathbf{X}} = \eta_{1} \frac{\Gamma(\mathbf{x}+\alpha)}{\mathbf{x}!\Gamma(\mathbf{1}+\alpha)} \gamma^{\mathbf{X}-1}$$

We obtain $\Delta(t) \approx n_1 t \sum_{x=1}^{\infty} (-1)^{x+1} \frac{\Gamma(x+\alpha)}{x!\Gamma(1+\alpha)} (\Upsilon t)^{x-1}$

which diverges for $\Upsilon t > 1$. If we estimate n_1 , α , and Υ , we obtain an estimator of $\Delta(t)$. According to Efron and Thisted, for $-1 < \alpha \leq 1$, the series $\sum_{y=1}^{\infty} \xi_y u^y$ converges in the nicest possible way, having $\xi_y \geq 0$ for all y. Using Euler's transformation we obtain the esti-

mator

$$\hat{\Delta}_{E}^{X_{0}}(u) = \sum_{v=1}^{X_{0}} \hat{\xi}_{y} u^{y} \text{ where } u = \frac{2t}{1+t}$$

and
$$\hat{\xi}_{y} = \sum_{x=1}^{y} \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \frac{(-1)^{x+1}}{2^{y}} \hat{\eta}_{1} \frac{\Gamma(x+\hat{\alpha})}{x!\Gamma(1+\hat{\alpha})} \hat{\gamma}^{x-1}$$

6.4.3 Example

Initially let us consider the parametric estimator $\hat{\Delta}_{E}^{X_{0}}(u)$ with Euler's transformation. The values of $\hat{\xi}_{y}$ are in Table 6.1. One way to choose x_{0} is to require $\hat{\Delta}^{X_{0}}(1) \simeq \sum_{j=1}^{M} \gamma_{j} = 14,165$. This gives $x_{0} = 38$,

and so we do not consider $\hat{\xi}_y$, $y \ge 39$. Since $\sum_{y=29}^{38} \xi_y = .00000522259$, we decide to choose $x_0 = 29$. Let us choose t = 100. From Figure

У	ξ̂y	У	ξ̂y		
1	6730.5	26	.00003380035		
2	3188.80362999268	27	.00001514092		
3	1509.57766569919	28	.00000673407		
4	714.02261275796	29	.00000296968		
5	337.42502726722	30	.00000129620		
6	159.30509997155	31	.00000055862		
7	75.13553619057	32	.00000023690		
8	35.39960803598	33	.00000009839		
9	16.65943914926	34	.0000003968		
10	7.83068586624	35	.00000001535		
11	3.67605589976	36	.0000000556		
12	1.72333189187	37	.0000000178		
13	.80671026984	38	.0000000042		
14	.37703393043	39	00000000001		
15	.17591546659	40	0000000011		
16	.08192720133	41	0000000010		
17	.03807890877	42	00000000007		
18	.01766019281	43	00000000005		
19	.00817093799	44	0000000003		
20	.00377060640	45	0000000002		
21	.00173497792	46	00000000001		
22	.00079575682	47	00000000001		
23	.00036366811	48	-0		
24	.00016552792	49 and more			
25	.00007499638		-		

Table 6.1

 $\xi_{y} = \sum_{x=1}^{y} \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \frac{(-1)^{x+1}}{2^{y}} \hat{n}_{1} \frac{r(x+\alpha)}{x!r(1+\alpha)} \hat{\gamma}^{x-1} \text{ where } \hat{n}_{1} = 13,461, \hat{n}_{2} = 8.78268266$ and $\hat{\gamma} = .01071932467$

6.1 this seems large enough and if we suppose that $\lambda_j = \frac{1000}{14,115}$, the expected fraction of distinct units observed in the second sample is

$$1 - e^{-100\lambda} j = .9991621419$$
.

We calculate

$$\sum_{j=1}^{M} y_j = \hat{\Delta}_{E_{\perp}}^{29} \left(\frac{200}{101} \right) = 167,493$$

and $\hat{\Delta}_{E_{\perp}}^{38} \left(\frac{200}{101} \right) = 172,129$

(see Figure 6.2).

If we consider the nonparametric estimator $\hat{\Delta}(t)$ without Euler's transformation

 $\hat{\Delta}(t) = \hat{\eta}_1 t - \hat{\eta}_2 t^2 + \hat{\eta}_3 t^3 = 13461t - 671t^2 + 33t^3$ = 149,118 when t = 14.115

The reasons we consider t = 14.115 are that t = $\frac{N}{n}$ and, if there do not exist duplicated cases, then $\sum_{j=1}^{M} y_j = \frac{N}{n} \sum_{j=1}^{n} Y_j$ where

 $\sum_{i=1}^{n} Y_i = \sum_{j=1}^{M} Z_j^{(1)}.$

If we consider the nonparametric estimate of $\hat{\Delta}_E^{\chi_0}(u)$ with Euler's transformation, we get

$$\hat{\xi}_{y} = \frac{13,461}{2}y - \frac{671(y-1)}{2}y + \frac{33(y-1)(y-2)}{2}y+1$$

and the table of values of $\hat{\xi}_y$ is in Table 6.2. From this table we

У	ξy	У	ξy		
1	6730.5	27	0.00005021691		
2	3197.5	28	0.00002580509		
3	1519.0	29	0.00001331232		
4	721.6875	30	0.00000689179		
5	342.96875	31	0.0000357907		
6	163.0625	32	0.00000186381		
7	77.578125	33	0.0000097288		
8	36.94140625	34	0.0000050885		
9	17.611328125	35	0.0000026659		
10	8.408203125	36	0.00000013986		
11	4.021484375	37	0.0000007345		
12	1.92749023438	38	0.0000003861		
13	0.92614746094	39	0.0000002030		
14	0.4462890625	40	0.0000001068		
15	0.21575927734	41	0.0000000562		
16	0.10469055176	42	0.0000000296		
17	0.05100250244	43	0.0000000156		
18	0.02495574951	44	0.0000000082		
19	0.01226806641	45	0.0000000043		
20	0.00606060028	46	0.0000000023		
21	0.00300931931	47	0.0000000012		
22	0.00150203705	48	0.0000000006		
23	0.00075364113	49	0.0000000003		
24	0.00038009882	50	0.0000000002		
25	0.00019267201	51	0.0000000000		
26	0.00009813905	52 and more	0		

$$\xi_{y} = \frac{1}{2^{y}} \hat{n}_{1} - \begin{pmatrix} y-1 \\ 1 \end{pmatrix} \frac{1}{2^{y}} \hat{n}_{2} + \begin{pmatrix} y-1 \\ 2 \end{pmatrix} \frac{1}{2^{y}} \hat{n}_{3} \text{ where } \hat{n}_{x} = \sum_{j=1}^{M} Z_{j}^{(x)} \text{ and}$$
$$\hat{n}_{1} = 13.461, \hat{n}_{2} = 671, \hat{n}_{3} = 33$$

Accumulative

У	ξy	У	ξ y		
1	12823.0	27	0.00010371208		
2	6092.5	28	0.00005349517		
3	2895.0	29	0.00002769008		
4	1376.0	30	0.00001437776		
5	654.3125	31	0.00000748597		
6	311.34375	32	0.0000390690		
7	143.28125	33	0.0000204309		
8	70.703125	34	0.00000107021		
9	33.76171875	35	0.0000056135		
10	16.150390625	36	0.0000029476		
11	7.7421875	37	0.00000015491		
12	3.720703125	38	0.0000008145		
13	1.79321289064	39	0.0000004285		
14	0.86706542968	40	0.0000002254		
15	0.42077636719	41	0.0000001186		
16	0.20501708984	42	0.0000000624		
17	0.10032653809	43	0.0000000328		
18	0.04932403564	44	0.0000000173		
19	0.02436828613	45	0.0000000091		
20	0.01210021973	46	0.0000000048		
21	0.00603961945	47	0.0000000025		
22	0.00303030014	48	0.0000000013		
23	0.00152826309	49	0.0000000007		
24	0.00077462196	50	0.0000000004		
25	0.00039452314	51	0.0000000002		
26	0.00020185113	52	0.0000000000		
		53 and more	0		

Figure 6.2



PREDICTED TOTAL OF SECOND SAMPLE

know we can choose $x_0 = 31$ since $\sum_{x=31}^{\infty} \hat{\xi}_y < .00001$ (see Table 6.3). We

calculate $\hat{\Delta}_{E}^{31} \begin{pmatrix} 200 \\ 101 \end{pmatrix} = 221,314$. This is the value we claim for the estimate of $\prod_{j=1}^{M} y_{j}$ (see Figure 6.3). Note $\hat{\Delta}_{E}^{29} \begin{pmatrix} 200 \\ 101 \end{pmatrix} = 210,177$.

6.5 The Bias of $\hat{\Delta}(t)$

From the expressions for $\hat{\Delta}(t)$ and $\hat{\Delta}^{X_0}(t)$ in Section 6.4, we see that it would be difficult to find their variances. In this section we try to find their biases. Using Euler's transformation and substituting $u = \frac{2t}{1+t}$, we have

$$\hat{\Delta}^{x_0}(t) = \sum_{x=1}^{x_0} (-1)^{x+1} \hat{\eta}_x t^x \sum_{y=x}^{x_0} \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \left(\frac{1}{1+t} \right)^x \left(\frac{t}{1+t} \right)^{y-x}$$

Define

$$h_{x}^{x_{0}} = (-1)^{x+1} t_{y=x}^{x} {y-1 \choose x-1} \left(\frac{1}{1+t}\right)^{x} \left(\frac{t}{1+t}\right)^{y-x} , \text{ and}$$
$$h_{x} = (-1)^{x+1} t_{y=x}^{x} {y-1 \choose x-1} \left(\frac{1}{1+t}\right)^{x} \left(\frac{t}{1+t}\right)^{y-x}$$

so that

$$\hat{\Delta}^{\mathbf{x}_{0}}(\mathbf{t}) = \sum_{x=1}^{\mathbf{x}_{0}} h_{x}^{\mathbf{x}_{0}} \hat{\eta}_{x}^{\mathbf{x}_{0}}$$

and

$$\hat{\Delta}(t) = \sum_{x=1}^{\infty} \hat{h_x}_x$$
 where $\hat{h_x} = \sum_{j=1}^{M} Z_j^{(x)}$

Figure 6.3



PREDICTED TOTAL OF SECOND SAMPLE

Define
$$H(\lambda) = \sum_{x=1}^{\infty} h_x \lambda^x / x!$$
 where $0 < \lambda < \infty$

and
$$H^{X_0}(\lambda) = \sum_{x=1}^{X_0} h_x^{X_0} \lambda^X / x!$$

Then

$$E[\hat{\Delta}(t)] = \sum_{x=1}^{\infty} h_{x} \eta_{x} = \sum_{x=1}^{\infty} h_{x} \left(\sum_{j=1}^{y} y_{j} \right) \int_{0}^{\infty} \frac{e^{-\lambda_{\lambda} x}}{x!} dG(\lambda)$$
$$= \left(\sum_{j=1}^{M} y_{j} \right) \int_{0}^{\infty} e^{-\lambda_{\mu} H(\lambda)} dG(\lambda)$$

$$E\left\{\widehat{\Delta}(t) - \Delta(t)\right\} = \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \int_{0}^{\infty} e^{-\lambda} \left[H(\lambda) - (1 - e^{-\lambda t})\right] dG(\lambda)$$

÷,

which, for $t = \infty$, becomes

$$\mathsf{E}\left\{\widehat{\Delta}(\infty)-\Delta(\infty)\right\} = \begin{pmatrix}\mathsf{M}\\ \Sigma \mathbf{y}\\ \mathbf{j}=\mathbf{p}\end{pmatrix} \int_{0}^{\infty} \mathsf{e}^{-\lambda} \left[\mathsf{H}(\lambda) - 1\right] \mathsf{d}\mathsf{G}(\lambda) .$$

It is convenient to rewrite this in a form which depends on

$$n_{\pm} = \sum_{x=1}^{\infty} n_{x} \text{ rather than } \sum_{j=1}^{M} y_{j} \text{ . Define}$$

$$P = \int_{0}^{\infty} \left(1 - e^{-\lambda}\right) dG(\lambda)$$

$$d_{G}^{(\lambda)} = \frac{1 - e^{-\lambda}}{P} dG(\lambda) \text{ .}$$
Since $n_{\pm} = \sum_{x=1}^{\infty} n_{x} = \sum_{x=1}^{\infty} \left(\sum_{j=1}^{M} y_{j}\right) \int_{0}^{\infty} \frac{e^{-\lambda} \lambda^{x}}{x!} dG(\lambda) = \left(\sum_{j=1}^{M} y_{j}\right) \int_{0}^{\infty} \left(1 - e^{-\lambda}\right) dG(\lambda)$

$$= \left(\Sigma y_{j}\right)P,$$

$$E\left\{\hat{\Delta}(t) - \Delta(t)\right\} = \left(\frac{M}{\sum_{j=1}^{\infty} y_{j}}\right)\int_{0}^{\infty} e^{-\lambda} \left[H(\lambda) - (1 - e^{-\lambda t})\right] dG(\lambda)$$

$$= \frac{\frac{1-e^{-\lambda}}{P}}{\frac{1-e^{-\lambda}}{P}} \begin{pmatrix} M \\ \Sigma \\ j=1 \end{pmatrix} \int_{0}^{\infty} e^{-\lambda} \left[H(\lambda) - (1-e^{-\lambda t}) \right] dG(\lambda)$$
$$= n \int_{0}^{\infty} \frac{e^{-\lambda}}{1-e^{-\lambda}} \left[H(\lambda) - (1-e^{-\lambda t}) \right] d\widetilde{G}(\lambda)$$

and

$$E\{\widehat{\Delta}(\infty) - \Delta(\infty)\} = n_{+} \int_{0}^{\infty} \frac{e^{-\lambda}}{1 - e^{-\lambda}} \left[H(\lambda) - 1\right] d\widehat{G}(\lambda) .$$

Similarly

$$E\{\hat{\Delta}^{X_0}(t)-\Delta(t)\} = n_{\pm} \int_{0}^{\infty} \frac{e^{-\lambda}}{1-e^{-\lambda}} \left[H^{X_0}(\lambda) - \left(1-e^{-\lambda t}\right) \right] d\tilde{G}(\lambda) ,$$

and for $t = \infty$

$$E\{\hat{\Delta}^{X_0}(\infty) - \Delta(\infty)\} = \eta_+ \int_0^{\infty} \frac{e^{-\lambda}}{1 - e^{-\lambda}} \left[H^{X_0}(\lambda) - 1 \right] d\tilde{G}(\lambda) .$$

We use the integrands

$$B_{t}(\lambda) = \frac{e^{-\lambda}}{1 - e^{-\lambda}} \left[H(\lambda) - \left(1 - e^{-\lambda t}\right) \right]$$
$$B_{t}^{X_{0}}(\lambda) = \frac{e^{-\lambda}}{1 - e^{-\lambda}} \left[H^{X_{0}}(\lambda) - \left(1 - e^{-\lambda t}\right) \right]$$

to measure the bias of $\hat{\Delta}$ for any G(λ).

6.5.1 Example

We compute $B_t^{X_0}(\lambda)$ in Table 6.4 and Figures 6.4, 6.5 and 6.6. The maximum bias of $\hat{\Delta}_E^{X_0}\left(= n_+\left\{ Max \ B_t^{X_0}(\lambda) \right\} \right)$ is .00000694085 for $x_0 = 29$, t=1; .00000198310 for $x_0 = 31$, t=1; 1,062,375 for $x_0 = 29$, t=100; 1,034,045 for $x_0 = 31$, t=100; and the relative bias $\left(= \text{Bias}/\hat{\Delta}^{X_0}(t)\right)$ is: .54 x 10⁻⁹ for $x_0 = 29$, t=1 and the parametric model with the gamma distribution; .15 x 10⁻⁹ for $x_0 = 31$, t=1, and the nonparametric model; 6.34 for $x_0 = 29$, t=100, and the parametric model with the gamma distribution; 4.67 for $x_0 = 31$, t=100, and the nonparametric model.

$\frac{B_{t}^{X_{0}}(\lambda)}{t}$	1×10 ⁻¹¹	1000 14115	<u>2000</u> 14115	<u>3000</u> 14115	4000	<u>5000</u> 14115	<u>6000</u> 14115	7000 14115	, <u>8000</u> 14115	<u>9000</u> 14115
$B_{1}^{29}(\lambda)$	0	49x10 ⁻⁹	1x10 ⁻¹¹	.3x10 ⁻⁹	.23x10 ⁻⁹	.7x10 ^{~10}	4x10 ⁻¹⁰	8x10 ⁻¹⁰	11x10 ⁻⁹	9x10 ⁻¹⁰
$B_{1}^{j_{1}}(\lambda)$	0	8x10 ⁻¹⁰	5x10 ⁻¹⁰	14x10 ⁻⁹	.8x10 ⁻¹⁰	.3x10 ⁻¹⁰	2x10 ⁻¹⁰	0	2x10 ⁻¹⁰	1×10 ⁻¹⁰
Β ² 8υ(λ)	-74.999999999930	1.29090387654	2.08045834322	0.7447105037	13649066111	49577148252	52078000274	38115206215	19140356295	01734218806
$L_{100}^{31}(\lambda)$	-72.999999999930	1.65384757369	1.99291149494	0.55014339244	28611353371	55553788581	49916822146	30762042606	09824700846	.06921067045

Table 6.4 The Bias Function $B_t^{X_0}(\lambda)$; in Section 6.5, for $\hat{\Delta}^{X_0}(t)$, at $x_0 = 29$ or $x_0 = 31$ and t = 1 or t = 100







Figure 6.5 for $B_1^{31}(\lambda)$









 $B_{100}^{29}(\lambda)$ and $B_{100}^{31}(\lambda)$.

CHAPTER 7

SUMMARY

In the literature there are five methods for estimating the population size when sampling from a list that contains duplication and when the extent of duplication cannot be determined. In this thesis these methods are generalized to estimate population totals when a measurement is associated with each member of the population. Also, the variances of those estimates are estimated.

The five estimators are illustrated and compared for a population of size N = 14,115 with M = 12,000 distinct classes, 9,885 of them having 1 unit and 2,115 of them having 2 units. The measurements y_j , j=1, 2, ..., 12,000, are assumed to be Poisson distributed with mean 15. In other words, the expected population total is 180,000. We simulate two samples of size n = 1,000, the first sampling without replacement (Goodman's method) and the second sampling with replacement for the other methods. The five sampling methods compared as follows:

(1) By Goodman's method we have an unbiased estimate

 $\sum_{j=1}^{M} y_j = \sum_{r=1}^{n} A_r \sum_{j=1}^{M} Z_j^{(r)} = 163,652, \text{ where } A_r$ $= 1 - (-1)^r \frac{[N-n+r-1]^{(r)}}{n^{(r)}}, \text{ with relative standard}$

error .058.

(2) By Good and Toulmin's method we have

$$\sum_{j=1}^{M} y_{j} = \sum_{j=1}^{M} \frac{\gamma}{Y_{j}} (N) = \sum_{r=1}^{n} \sum_{j=1}^{M} Z_{j}^{(r)} + \left(\frac{N}{n} - 1\right) \sum_{j=1}^{M} Z_{j}^{(1)}$$

$$- \left(\frac{N}{n} - 1\right)^{2} \sum_{j=1}^{M} Z_{j}^{(2)} = 182,529$$

with relative standard error .036.

(3) By Harris' method for obtaining the upper and lower bounds of a population total we have

$$\sup \sum_{j=1}^{M} Y_{j}(N) = \sum_{j=1}^{M} Y_{j} + (t-1)\sum_{j=1}^{M} Z_{j}^{(1)} = 190,706$$

$$\inf \sum_{j=1}^{M} Y_{j}(N) = \sum_{j=1}^{M} Y_{j} = 14,165.$$

(4) By Good and Rao's method we have

$$\underset{j=1}{\overset{M}{\sum}} y_{j} = \frac{\underset{j=1}{\overset{\Sigma}{\sum}} Z_{j}}{\frac{\Gamma(\hat{\alpha}+1)}{\Gamma(\hat{\alpha})} \frac{\hat{\beta}}{(1+\hat{\beta})^{\hat{\alpha}+1}}} = 157,177 \text{ with relative standard}$$

error .36.

(5) By Efron and Thisted's method we have

standard error .45.

$$\sum_{j=1}^{M} y_j = \hat{\Delta}_E^{29}(u) = 167,493 \text{ in Section 6.4.2, with relative}$$

bias 6.34.

 $M^{\hat{x}}_{j=1} = \hat{\Delta}_{E}^{31}(u) = 221,314, \text{ in Section 6.4.1, with relative}$ bias 4.67.

Goodman's method does not involve any approximation. Good and Toulmin's method is based on some approximation but less than the other methods. Furthermore the relative standard deviations of these two estimators are small. Since Good and Toulmin's method and Efron and Thisted's method are to find the prediction of population total, they can be applied for the growing population. Since the precision of Good and Rao's method is low and Efron and Thisted's method even lower, extreme care should be exercised if either of these methods is employed.

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