

AN ABSTRACT OF THE THESIS OF

Anil Kumar Yadav for the degree of Master of Science in
Electrical and Computer Engineering presented on October 26, 1989.

Title : Performance Monitoring of Parallel Applications at Large
Grain Level

Redacted for privacy

Abstract approved : _____

Prof. T. G. Lewis

This thesis is an attempt to create a methodology to analyze the performance of parallel applications on a wide variety of platforms and programming environments. First we determined the monitoring functions required to collect traces for accurate representation of the parallel application. We used the Extended Large Grain Data Flow (**E L G D F**) representation of an application to determine granularity and which monitoring functions should be inserted for sufficient feedback to application designer. The monitoring routines (real time clock access procedures) with a common interface were developed for the Sequent™ multiprocessor machine and the C-Linda programming environment . We also developed an Execution Profile Analyzer(**E P A**) for post-processing the traces. The **E P A** gives feedback to the mapping and scheduling (**TaskGrapher**) tool by providing actual performance data. These tools are being developed as a part of Parallel Programming Support Environment (**P P S E**) research . Results indicate that when actual grain execution time is made available to scheduling tools, accurate projections of program behavior are obtained.

Performance Monitoring of Parallel Applications at
Large Grain Level

by

Anil Kumar Yadav

A THESIS
submitted to
Oregon State University

in partial fulfillment of
the requirements for the
degree of

Master of Science

Completed October 26, 1989

Commencement June 1990

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Redacted for privacy

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Date thesis is presented October 26, 1989

ACKNOWLEDGEMENT

I would like to take this opportunity to thank the staff and faculty of the Departments of Electrical and Computer Engineering and Computer Science for extending their constant support and encouragement.

In particular I am very grateful to my major professor Dr. T. G. Lewis for introducing me to the exciting field of parallel computing and Dr. Shreekant Thakkar of Sequent Computer Systems, Inc. Beaverton, Oregon, for his constant guidance and support.

I would also like to express my sincere thanks to Oregon Advanced Computing Institute, Beaverton, Oregon and Sequent Computer Systems Inc, for letting me have access to their valuable equipment for conducting the experiments.

I am also very thankful to the PPSE researchers and guests at the PPSE meeting on 2nd and 3rd October 1989. The presentation of this work and subsequent discussions made me view this thesis from a broader perspective.

And last but not the least I am thankful to my friends and my family members for making things easy for me.

Anil Kumar Yadav

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Performance Monitoring of Parallel Applications at Large Grain Level

Chapter 1

Introduction

One of the most serious problems in the full utilization of multiprocessor architectures for parallel applications is the lack of tools and techniques for debugging and doing performance analysis. An approach to performance analysis of parallel applications should provide the program designer with sufficient synchronization and execution information for fine tuning the application. It should present a consistent interface and parameters for evaluation across a wide variety of machines and programming environments. The methodology should be independent of specific architectures and should provide a high level abstraction of application performance.

The performance of parallel programs can be analyzed in basically two ways :- 1) On-line analysis and 2) Postmortem analysis. In on-line analysis execution trace is collected and analyzed during a program execution [1, 2, 3]. The on-line analysis approach requires the creation of trace collection and analysis process on the machine. Online analysis leads to an interactive analysis tool that is dynamically controlled by the programmer. Since the profile gathering computations take place on an additional processor, this method is less intrusive than the Postmortem method. Furthermore, online

analysis is capable of handling large profiling tasks since the traces are summarized prior to storing them in off-line database files. Online analysis has intrinsic machine dependencies since it needs an additional processor and may be ineffective for architectures which have substantial interprocessor communicational delays such as cube machines. Therefore while online analysis yields excellent results for specific architectures (e.g. shared memory multiprocessors) , it can not form the basis of a more general approach.

Postmortem analysis of applications [4, 5, 6, 7] involves collection of execution traces and then processing the traces off-line to obtain performance parameters such as processor utilization, order of execution, task mapping and speedup. This method is more intrusive than on-line analysis since the executing application is diverted to collection of trace information. However this approach has no machine dependencies and can therefore form the basis of a more general approach. The trace data can also be analyzed by more sophisticated programs thus giving different views of the history of execution of a program.

One of the earliest systems for monitoring multiprocessor programs was the **METRIC** system [3] for applications that communicate over a local area network. This system is divided into three parts : *probes*, *accountants* and *analysts*. *Probes* are the procedure calls used by a programmer to generate trace data. A *probe* inserted into the program source code sends data over the network to an *accountant*. *Accountants* record or filter the incoming data. *Analysts*

are the collection of processes which summarize the trace data. This system helped to define the explicit separation of data generation, selection and analysis. The **METRIC** system has been the basis of later analysis tools.

Most of the recent work in performance monitoring [1, 2, 4, 5, 6, 7] has centered around creating exclusive environments for trace collection and analysis. Trace collection has been done either by inserting special routines in the source code or by means of special hardware hooks. The trace analysis approach used most frequently is the creation of a relational database of execution history and a set of queries for obtaining performance information about the application. These methods have shown efficacy for the systems on which these were implemented but the portability of such methods over completely different architectures and the integration of performance analysis tools with programming environments are issues which have been addressed marginally at best [8]. The more portable UNIX™ profilers *prof* and *gprof* are sufficient for static analysis of sequential programs but fail to represent the synchronization behavior of parallel applications.

The work of this thesis is an attempt to create a methodology to analyze the performance of parallel applications on a wide variety of platforms and programming environments. First we determined the monitoring functions required to collect traces for accurate representation of the parallel application. We used the Extended Large Grain Data Flow (**E L G D F**) [10] representation of an application to

determine granularity and which monitoring functions should be inserted for sufficient feedback to application designer. The monitoring routines (real time clock access procedures) with a common interface were developed for the Sequent™ multiprocessor machine and the C-Linda programming environment¹. We also developed an Execution Profile Analyzer(**E P A**) for post-processing the traces. The **E P A** gives feedback to the mapping and scheduling tool (**TaskGrapher**) by providing actual performance data. These tools are being developed as a part of Parallel Programming Support Environment (**P P S E**) research [11].

The rest of this thesis is organized as follows : Chapter 2 describes the approach and the experiments for determining the instrumentation and correct granularity for performance analysis. The context of this work is further explained with a brief overview of the **P P S E**. Chapter 3 describes the timing routines and their usage with the **SuperGlue** [12] source code generator. The mapping of these routines to real machines is also explained. The analysis program, **E P A** is explained in Chapter 4. Chapter 5 presents a complete example of application design and performance analysis using the **P P S E** tools. And finally chapter 6 summarizes the work done, effectiveness of the approach developed and the work needed to be done in the future.

¹ C-Linda supports a common interface for parallel application development on different architectures such as cube, shared memory and connection machines .

Chapter 2

An Approach to Performance Analysis

2.0 Introduction

This chapter describes the proposed performance analysis methodology in concert with the **P P S E** research. We used the solution of the Traveling Salesman Problem (**T S M**) by Simulated Annealing [13] as a test for determining suitable instrumentation, levels of granularity at which to insert instrumentation, and the effects of such instrumentation on program execution time. The experiments and the results are also summarized in this chapter.

2.1 Existing Analysis Tools

In our brief survey of general purpose monitoring tools we found *gprof* and *parasight* to be portable across different UNIX™ platforms. *gprof* is a stand-alone utility used in post-mortem mode[14]. The application to be profiled, is compiled with an option to link the trace collection procedures e.g

```
>> < cc, pascal, fortran > -pg prog.< c, p, f >
```

On successful execution the application dumps a binary trace file *gmon.out*. The *gprof* utility then translates this trace to yield a call graph of the application along with call statistics such as time spent in

a particular function, number of times a function is called and percentage of user time occupied by various functions. While *gprof* presents a coarse overview of a sequential program, it is unsuitable for analyzing parallel applications since it completely hides the order of execution and the synchronization events.

Another interesting approach to monitoring parallel programs is considered in *parasight* [1]. It is a parallel programming environment for shared memory multiprocessors. The main idea behind *parasight* is to use one processor in the machine to harbor monitoring processes called *parasites*. These *parasites* periodically examine the process tables of the running application and build an on-line view of the application. The approach is very non-intrusive, has scope for dynamic monitoring and control of the application by the programmer, and produces a summary of traces rather than raw traces. However we find this approach unsuitable because it requires an additional processor for monitoring and may not be effective if the inter-processor communication delays are more than grain execution times.

2.2 Overview of P P S E

The Parallel Programming Support Environment (**P P S E**) is a set of software tools developed under the aegis of Oregon Advanced Computing Institute (**O A C I S**) to address the problems associated with parallel application development in an integrated fashion [11]. Numerous prototype tools address almost all aspects of parallel programming such as :-

- partitioning of application into parallel parts
- mapping parallel parts onto multiple processors
- optimal scheduling of parallel parts
- reverse engineering existing serial code into parallel programs
- performance measurement and analysis
- how to coordinate design, coding, debugging and performance

Fig. 2.1 illustrates the various **P P S E** tools and their interaction. The application designer uses the Application Design System (**Parallax**) to construct a data flow design of the desired program. The design system produces a data flow graph which describes the interconnections and data dependencies of the proposed program.

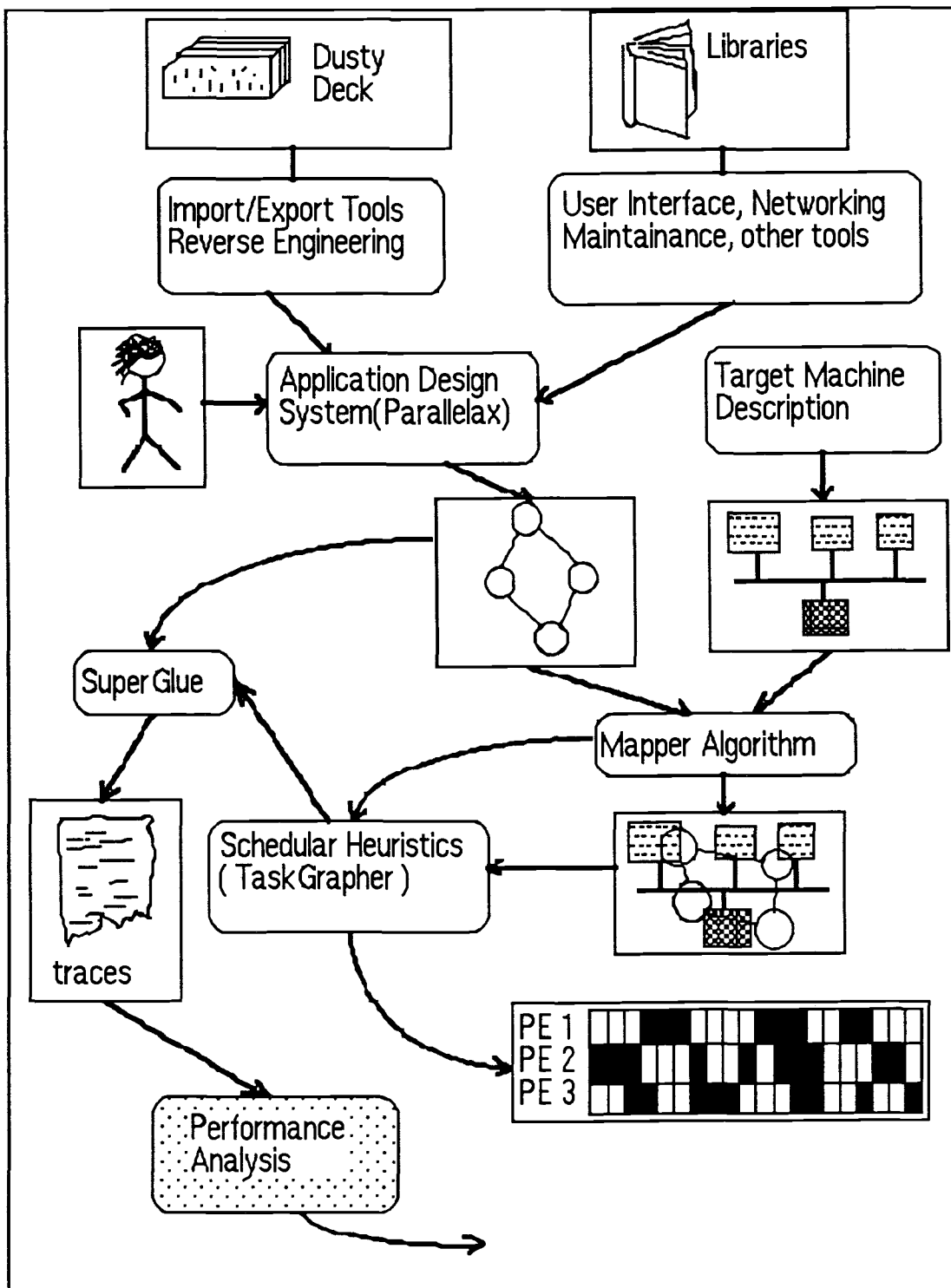


Fig. 2.1 : Overview of P P S E

Parallax can also be used to write the code fragments for implementing the nodes in the data flow diagram in a particular programming language. These code fragments are used by source code generator **SuperGlue** [12] to produce compilable source code for a particular platform. Similarly the target machine(s) for the proposed program is designed and stored as a file of architectural properties such as connection topology, communication delays, cache structures etc. using the Target Machine Editor (**T M E**).

The programmer next uses a mapper and scheduler (**TaskGrapher**) to allocate and schedule the data flow design onto the target machine. This produces an execution schedule as a Gantt chart of processing elements versus time. The output at this stage also includes the plot of the speed up versus number of processors (PEs). This information is used to evaluate the " goodness" of the design (the program and the target machine).

From this preliminary analysis of a number of designs the programmer chooses one for actual execution on a real machine. At this stage **SuperGlue** is used to yield the compilable code for the specified machine and programming language. When the resulting program is actually run on the machine, an execution profile is collected and analyzed by Execution Performance Analyzer (**E P A**). This analysis yields feedback to the application design system about the actual execution time, actual scheduling Gantt chart and statistics for speedup, processor utilization and distribution of execution time

among grains. Collecting traces for generating feedback is the work of this thesis.

2.3 Steps in Performance Analysis

The methodology which we found appropriate for analyzing parallel applications in **P P S E** is illustrated in Fig. 2.2. It consists of the following steps :-

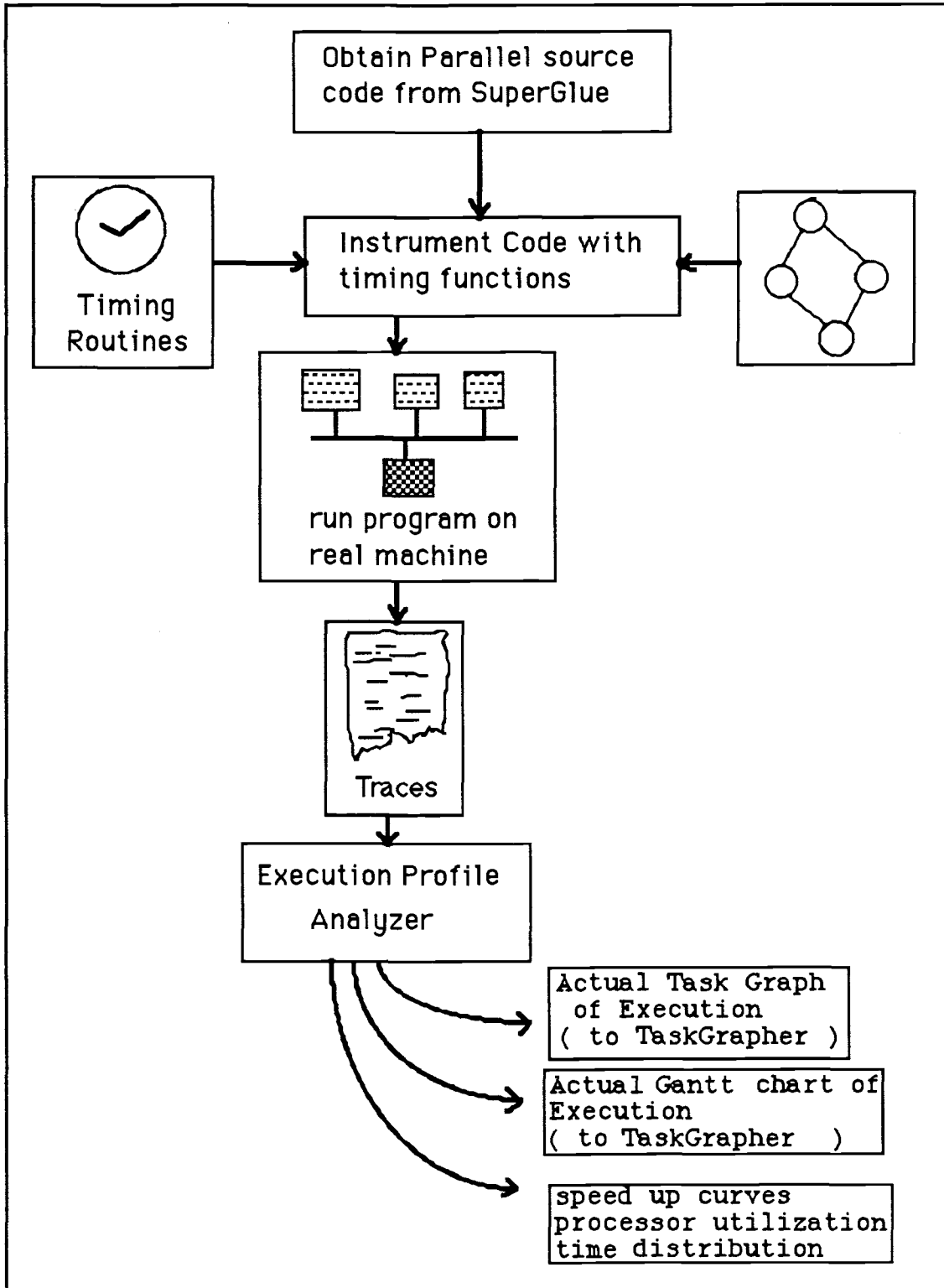


Fig.2.2 : Performance Analysis Methodology

- Identify synchronization points and grain boundaries in the program with the help of **E L G D F** description and programming language constructs such as `m_fork` and `m_multi` in Sequent™ environment and `in()` and `out()` in the C-Linda language.
- Insert real-time measurement routines into the source code of the application at the synchronization points and large grain boundaries¹ (the time measurement routines are described in chapter 3) .
- Run the instrumented program on the target machine and collect the execution traces.
- Analyze the traces off-line using the analysis program (described in chapter 4) .

In selecting this particular approach we addressed the following issues :-

- What execution data is necessary and sufficient for validating the prediction of current **P P S E** tools ?
- At what level of granularity should the measurement functions be placed ? (" level of granularity" is shown in Fig. 2.5 and explained in section 2.5)

¹ **SuperGlue** automatically inserts timing functions at the grain boundaries if "Timing" option is chosen while generating source code.

- What are the measurement functions which make this performance analysis method portable ?
- What is the effect of the measurement functions on the execution time of the application ?

To determine the answers to these issues we conducted a series of instrumentation experiments using the Sequent™ Symmetry™ shared memory multiprocessor. These experiments are summarized in section 2.5. Using this methodology we conducted analysis of applications developed using **P P S E** tools. A complete example is explained in Chapter 5.

2.4 Instrumentation Experiments

We solved the parallel implementation of the Traveling Salesman Problem (**T S M**) using simulated annealing to fine tune the methodology and to address the issues mentioned in section 2.4. The **T S M** problem is an example of the NP-complete class of combinatorial problems. In **T S M** a salesperson visits N cities, each of which is represented by coordinates $[X_i, Y_i]$ on a two dimensional plane. Each city is to be visited exactly once and the total path length for such a trip is to be minimized. This rather simple problem is of practical importance in cell placement in VLSI design, and process-processor mapping in parallel machines, for example.

In NP class of combinatorial problems the computational load increases exponentially with the number of variables handled. Therefore approximate solutions along with manual improvements have been found to yield optimal results [15]. Simulated annealing [13] solves this class of problems by iterative improvement of an assumed solution in association with a hill climbing algorithm. Fig. 2.3 shows a generic simulated annealing algorithm.

```

S = state of solution.
Sn = new state of solution.
E = cost function.
T = control parameter for finding
    low-cost state.
To = initial value of control parameter.
Tf = Final value of control parameter
c = rate of change in T.

frozen = FALSE
Start with some state, S
T = To
Repeat {
    While ( not in equilibrium ) {
        Perturb S to get new state Sn
        ΔE = E(Sn) - E(S)
        if ΔE < 0
            Replace S with Sn
        Else with probability exp(-ΔE/T )
            replace S with Sn.
    }

    T = c*T. /* c < 1 */
    if ( T <= Tf )
        frozen = TRUE
} Until( frozen )

```

Fig. 2.3 : A generic Simulated Annealing Algorithm

An initial guess to the solution is made (in our case the path of the salesman), then this solution is modified slightly and the variable to be minimized is recalculated. If there is an improvement in the solution, the new solution is accepted; otherwise the new solution is *still* accepted with a probability which depends on the 'state' of the solution. Therefore this algorithm makes it possible to escape from local minima in search space and approach absolute minima with greater probability of success.

A top level **E L G D F** description of **T S M** problem is shown in Fig.2.4. The program begins with the grain `Read Data` which inputs the cities to be covered by the salesman. Then the grain `Link Points` creates a circular linked list of cities thus forming the initial guess about the salesman path. The program then forks a selected number of parallel processes `Anneal` which perform simulated annealing on the salesman's path. During an iteration each parallel process makes modification to the shared structure `Path`. After the selected number of iterations have been performed , the final path is written to an output file by the grain `Write Data`.

In our experiments we manually wrote the source code for this application in C language on Sequent™ Symmetry™ machine ¹.

¹ Current prototype of **SuperGlue** provides source code in C-Linda language only.

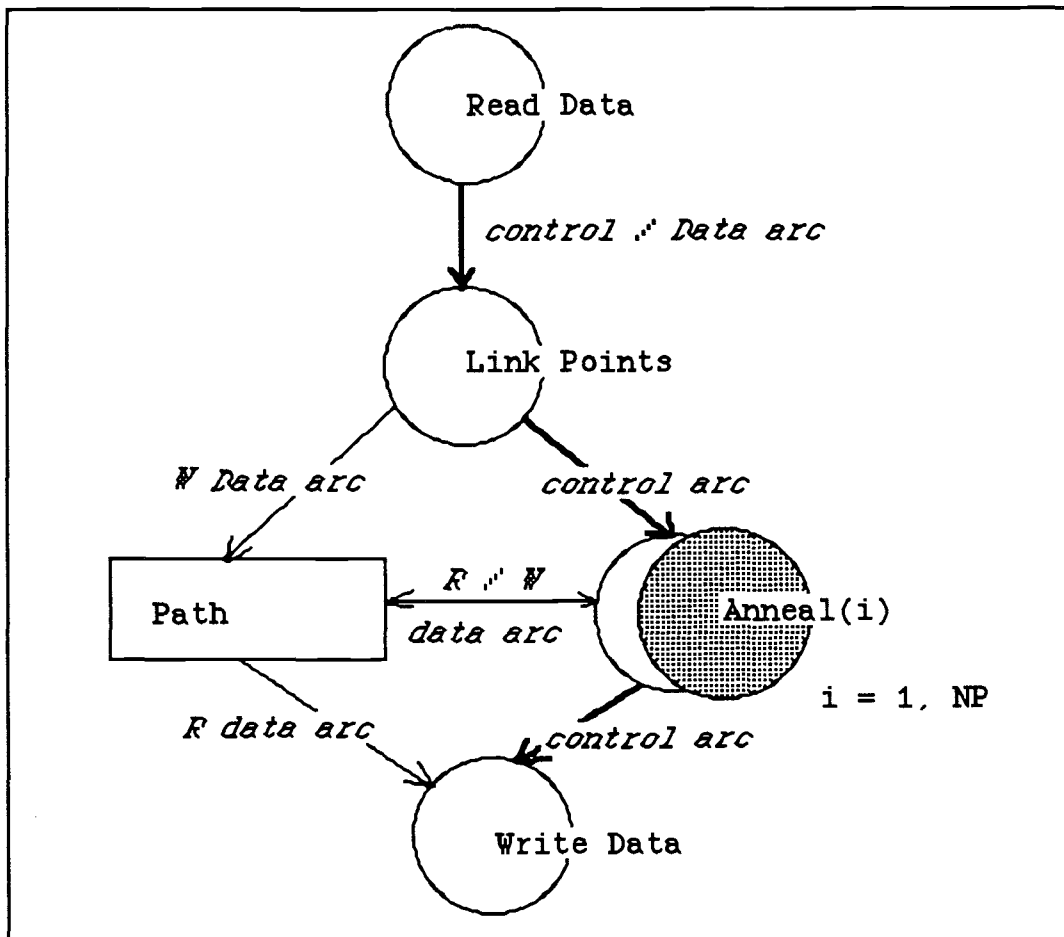


Fig.2.4 : ELGDF representation of TSM

To enforce parallel execution, routines from micro-tasking and parallel library were used [16, 17, 18]. These routines also served to identify the synchronization points and grain boundaries in the source code and thus helped in placing time measurement functions. Appendix A show the implemented source code of one of the versions of **TSM** problem¹.

Execution traces can be collected at three levels of detail as shown in Fig.2.5. Program level provides total execution time, large

¹ The timing routines have been highlighted for easy identification.

grain level provides the execution time for each grain. The small grain level of instrumentation involves tracking each variable and the time spent on their access. We conducted experiments with all the three levels of instrumentation and found that in **P P S E**

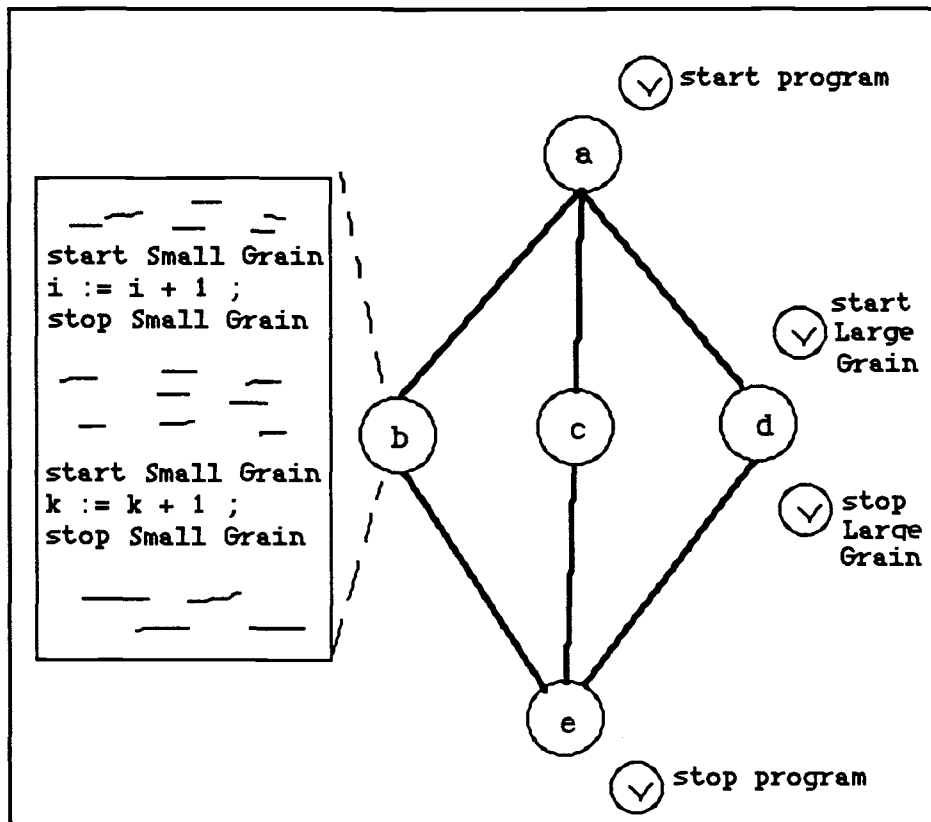


Fig.2.5 : Instrumentation Levels

the large grain level of instrumentation is suitable as it provides sufficient and manageable information on program execution.

The experiments also indicated that real-time measurement at the beginning and ending of each large grain is the data required. By comparing the total execution time of the *clean* and *instrumented*

programs, it was deduced that instrumentation at large grain level produced at most 8% deviation. It was also noted that as grain size became smaller the perturbation due to instrumentation increased. The trace collected could also identify differences between the underlying hardware by means of the differences in the execution times. However, the trace collected is not enough to identify which part of the architecture (CPU, I/O subsystem, Cache, primary memory) is responsible for delay/speedup of an application.

In conclusion, by instrumenting programs at the large grain level with real time measurement we were able to characterize the performance of the parallel application without significant distortion in actual behavior.

Chapter 3

Timing Routines

3.0 Introduction

This chapter describes the timing routines used to generate an execution profile of an application. These routines are the common interface of performance analysis to the **SuperGlue** source code generator. The actual implementation of these routines for a machine or programming environment is dependent on the timing functions available on a particular system. The implementation of these routines and the procedure for incorporating them into **SuperGlue** are described for the Sequent machine and Linda-C programming environment.

3.1 Common Interface

Following are the common interface routines for the **SuperGlue** source code generator :-

```
initialize_clock()
```

Routine to set up and activate the time measurement facility on the target machine. It involves creation and initialization of variables so that times for the application start with 0.

Routines for Measuring Grain Execution Time :-

```
get_grain_start_time( processor_id, grain_id)
```

Routine to access the current value of the clock when the grain begins computation. The identifier *start*¹, the variables *processor_id* and *grain_id* and value of the time are printed on the standard output².

```
get_grain_stop_time(processor_id, grain_id)
```

Routine to access the current value of the clock when computations in a grain are finished. The identifier *stop*, the variables *processor_id* and *grain_id* and value of the time are printed on the standard output.

Routines for finding data dependencies between grains and approximating³ communication delays :-

```
get_send_begin_time(grain_id, structure_name)
```

Routine to access the current value of the clock prior to placing a variable into tuple⁴ space. The identifier *sendBegin*, the variable *structure_name* and *grain_id* and the value of time is printed on the standard output.

¹ The identifiers *start*, *stop*, *sendBegin*, *sendEnd*, *recvBegin* and *recvEnd* are printed on the execution trace. These are used by EPA to recreate actual Gantt Chart, Task Graph etc.

² The redirected standard output file is the execution trace file of the application.

³ The communication delay is approximate since I/O activity in parallel with the receiving grain can make the variable collect time for receiving grain appear when measured using these routines.

⁴ The word 'tuple' is Linda specific. Here it means a message queue for hypercube, shared structure for shared memory machine etc.

```
get_send_end_time(grain_id, structure_name)
```

Routine to access the current value of the clock after placing a variable into tuple space. The identifier *sendEnd*, the variable *structure_name* and *grain_id* and the value of time is printed on the standard output.

```
get_recv_begin_time(grain_id, structure_name)
```

Routine to access the current value of the clock prior to obtaining a variable from tuple space. The identifier *recvBegin*, the variable *structure_name* and *grain_id* and the value of time is printed on the standard output.

```
get_send_end_time( grain_id, structure_name)
```

Routine to access the current value of the clock after obtaining a variable from tuple space. The identifier *recvEnd*, the variable *structure_name* and *grain_id* and the value of time is printed on the standard output.

processor_id = integer number identifying a processor on the target machine.

grain_id = integer number identifying a grain in the ELGDF description of the problem.

structure_name = string identifying a structure passed between two grains.

The communication time for a structure is calculated by the following expression :-

communication time = (sendEndTime - sendBeginTime) +
 (recvEndTime - recvBeginTime).

These routines are suitable for obtaining dependencies between grains when message passing paradigm is used for inter-grain communication. In Linda the message passing is implemented by the functions `in()` and `out()` while on a hypercube this is implemented by the system functions `send()` and `receive()`.

The placement of these routines and general model of grain is shown in Fig. 3.1. A section of the execution trace generated using these routines is shown in Fig. 3.2. The execution trace is used by Execution Profile Analyzer (**E P A**) to yield the execution times of the grain and the communication delay or synchronization wait time.

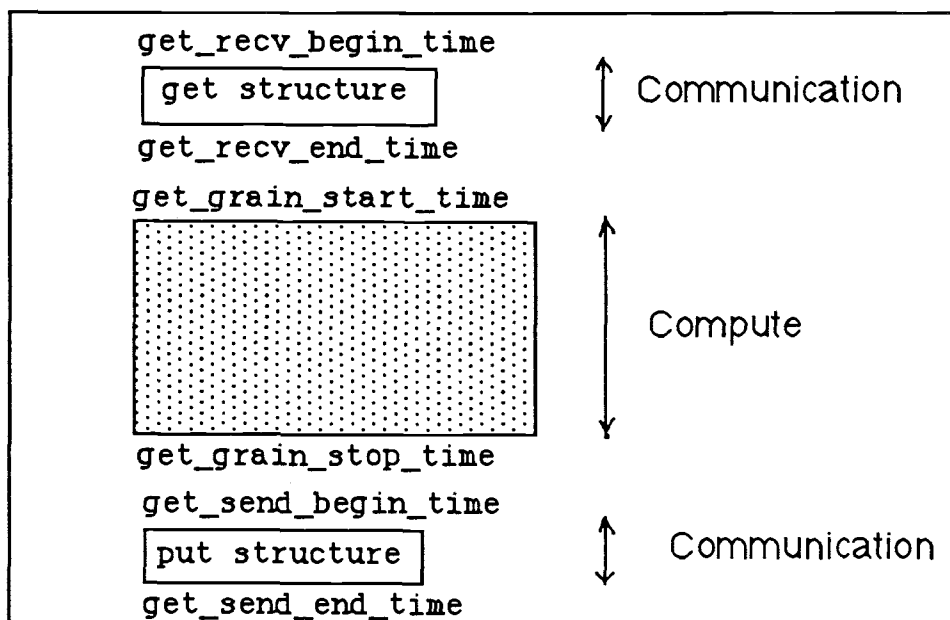


Fig. 3.1 : Grain Model and timing interface.

Identifier	Processor_id	Structure_name	Grain_id	Clock value
recvBegin	superGlue01		1	520
recvEnd	superGlue01		1	540
start	2		1	540
stop	2		1	2350
sendBegin	superGlue16		1	2350
sendEnd	superGlue16		1	2360
recvBegin	superGlue05		5	2360
recvEnd	superGlue05		5	2360
start	2		5	2360
stop	2		5	4170

Fig. 3.2 : Trace file format

3.2 Implementation on Sequent™ Machine

Following steps are required to use the timing routines on the Sequent™ Symmetry™ machine :-

1. Include the interface file in the source code of the application by

```
#include "time_sequent_c.h"
```

The time_sequent_c.h file is as shown in Table 3.1

 Table 3.1 : Timing Routines for Sequent™ Symmetry™ multiprocessor

```
#include <usclkc.h>          /* microsecond clock header file */
#include <stdio.h>

#define CONVERSION_FACTOR 1000 /* factor to convert to milli-seconds */
usclk_t clock_offset ;      /* value of real time at start */
void initialize_clock()     /* procedure to setup the clock */
{
    usclk_init();
    clock_offset = getusclk();
}

void get_grain_start_time( processor_id, grain_id )
int processor_id ;
int grain_id ;
```

```

{

    usclk_t temp ;          /* scratch variables */

    usclk_t time_now ;     /* get the time since program start */

    temp = ( getusclk() - clock_offset ) ;

    time_now = temp / CONVERSION_FACTOR ;

    printf(" start  \t%d\t%d\t\t%d\n", processor_id, grain_id,

           time_now ) ;

}

void get_grain_stop_time( processor_id, grain_id )

int processor_id ;

int grain_id ;

{

    usclk_t temp ;          /* scratch variables */

    usclk_t time_now ;     /* get the time since program start */

    temp = ( getusclk() - clock_offset ) ;

    time_now = temp / CONVERSION_FACTOR ;

    printf(" stop  \t%d\t%d\t\t%d\n", processor_id, grain_id,

           time_now ) ;

}

get_send_begin_time( grain_id, structure_name )

int grain_id ;

char structure_name[100];

{

    usclk_t temp ;          /* scratch variables */

    usclk_t time_now ;     /* get the time since program start */

    temp = ( getusclk() - clock_offset ) ;

    time_now = temp / CONVERSION_FACTOR ;

```



```

        printf(" sendBegin %s  %d  %d\n", structure_name, grain_id,
                time_now ) ;
    }

```

```

get_send_end_time( grain_id, structure_name )

```

```

int grain_id ;
char structure_name[100];
{
    usclk_t temp ;          /* scratch variables */
    usclk_t time_now ;     /* get the time since program start */
    temp = ( getusclk() - clock_offset ) ;
    time_now = temp / CONVERSION_FACTOR ;
    printf(" sendEnd %s  %d  %d\n", structure_name, grain_id,
            time_now ) ;
}

```

```

get_recv_begin_time( grain_id, structure_name )

```

```

int grain_id ;
char structure_name[100];
{
    usclk_t temp ;          /* scratch variables */
    usclk_t time_now ;     /* get the time since program start */
    temp = ( getusclk() - clock_offset ) ;
    time_now = temp / CONVERSION_FACTOR ;
    printf(" recvBegin %s  %d  %d\n", structure_name, grain_id,
            time_now ) ;
}

```

```

get_recv_end_time( grain_id, structure_name )

```

```
int grain_id ;
char structure_name[100];
{
    usclk_t temp ;          /* scratch variables */
    usclk_t time_now ;     /* get the time since program start */
    temp = ( getusclk() - clock_offset ) ;
    time_now = temp / CONVERSION_FACTOR ;
    printf(" recvEnd %s  %d  %d\n", structure_name, grain_id,
           time_now ) ;
}
```

The microsecond clock on the Symmetry™ machine is a 32-bit register which is synchronously incremented across all the processors. The clock overflows after 4195 seconds and there is no system function to inform the process of this event. Thus these routines can give incorrect time measurements and are not suitable for measuring programs which last more than 4195 seconds. This drawback could be removed by using system clock to determine such overflows. However using system clock makes the execution time of the clock routines large thus suppressing the 1 microsecond resolution of the clock¹. For tracing programs with large execution times the clock routines in `time_linda_c.h` file should be used. The timing routines in the file `time_linda_c.h` use the standard UNIX™ system timer and do not make any Linda dependent calls. Thus these routines could be used on any UNIX™ system and C programming environment.

2. Modify compilation option to include the microsecond timing library `/usr/lib/libseq.a` e.g.

```
cc -o myprog myprog.c -lseq
```

3. Placement

`init_clock` : preferably the first executable statement in the source code of the application. This must be run prior to any other timing routine.

¹In course of instrumentation experiments it was found that clock resolution of 1 microsecond is not necessary for monitoring performance at large grain level.

`get_grain_start_time` : the first statement in the grain to be measured.

`get_grain_stop_time` : the last statement in the grain to be measured.

`get_send_begin_time` : before an `m_lock()` statement.

`get_send_end_time` : after an `m_unlock()` statement.

`get_rcv_begin_time` : before an `m_lock()` statement.

`get_rcv_end_time` : after an `m_unlock()` statement.

The grain boundaries can be detected by the synchronization points in the program. Table 3.2 shows the synchronization functions available in the parallel programming/microtasking library of the Sequent™ Symmetry™.

Table 3.2: Parallel Programming Library Microtasking Routines

Routine	Descriptions
<code>m_fork</code>	execute a subprogram in parallel
<code>m_get_myid</code>	return process identification number
<code>m_get_numprocs</code>	return number of child processes
<code>m_kill_procs</code>	terminate child process
<code>m_lock</code>	lock a lock
<code>m_multi</code>	end of single process code section
<code>m_next</code>	increment global counter
<code>m_park_proc</code>	suspend child process execution

<code>m_rele_procs</code>	resume child process execution
<code>m_set_procs</code>	set number of child process
<code>m_single</code>	begin single process code section
<code>m_sync</code>	check in at barrier
<code>m_unlock</code>	unlock a lock
<code>shared</code>	indicates a shared variable
<code>private</code>	indicates private variable

Source : Guide to Parallel Programming on Sequent Computer Systems, Second Edition, 1987.

Appendix A shows an example source code instrumented for Sequent™ Symmetry™ machine.

4. For detailed information about the implementation of the timing routines refer to the Dynix™ Programmer's Manual, system commands *getusclk(3)*, *usclk_conf(8)*, *usclk(4)*.

3.3 Implementation using Linda-C

Following steps are required for using the timing routines on *any* machine supporting Linda-C parallel programming environment :-

1. Include the interface file in the source code of the application by

```
#include "time_linda_c.h"
```

The file `time_linda_c.h` is shown in Table 3.3.

2. There are no compile time modifications.

3. Placement

`initialize_clock` : preferably the first executable function in the source code.

`get_grain_start_time` : the first statement in the grain to be measured.

`get_grain_stop_time` : the last statement in the grain to be measured.

`get_send_begin_time` : before an `out()` statement.

`get_send_end_time` : after an `out()` statement.

`get_recv_begin_time` : before an `in()` statement.

`get_recv_end_time` : after an `in()` statement.

In Linda-C environment the grains are implemented as functions, thus there are no specific grain boundary identifiers.

4. For detailed information about the implementation of the timing routines refer to the UNIX Programmer's Manual, system commands *gettimeofday(2)*.

3.4 Extensions to Timing Routines

The ability of SuperGlue to insert timing functions from a common interface into source code of parallel application makes it easy to extend the performance analysis methodology to animation and

debugging. For example if we replace the current implementation of `init_clock` by having this routine setup an animation process and if we change the other 'timing' routines to send the event messages to the animation process then we can animate the application as it is run on a real machine. Similarly debugging can be viewed as performance monitoring at a small grain level.

Table 3.3 : Timing Routines for Linda-C environment

```
#include <sys/time.h>

struct timeval clock_offset ;

initialize_clock()

{
    gettimeofday( &clock_offset, 0 );
}

get_grain_start_time( processor_id, grain_id )

int processor_id ;
int grain_id ;

{
    struct timeval temp ;
    long time_elapsed ;
    gettimeofday( &temp, 0 );
    time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;
    time_elapsed += ( temp.tv_usec - clock_offset.tv_usec ) / 1000 ;
    printf(" start   %d   %d   %d\n", processor_id, grain_id,
           time_elapsed);
}

get_grain_stop_time( processor_id, grain_id )

int processor_id ;
int grain_id ;
```



```

{
    struct timeval temp ;
    long time_elapsed ;
    gettimeofday( &temp, 0 );
    time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;
    time_elapsed += ( temp.tv_usec - clock_offset.tv_usec )/1000 ;
    printf(" stop      %d      %d      %d\n",processor_id,
           grain_id, time_elapsed);
}

```

```

get_send_begin_time( grain_id, structure_name )

```

```

int grain_id ;

```

```

char structure_name[100];

```

```

{
    struct timeval temp ;
    long time_elapsed ;
    gettimeofday( &temp, 0 );
    time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;
    time_elapsed += ( temp.tv_usec - clock_offset.tv_usec )/1000 ;
    printf(" sendBegin    %s    %d      %d\n",structure_name,
           grain_id, time_elapsed);
}

```

```

get_send_end_time( grain_id, structure_name )

```

```

int grain_id ;

```

```

char structure_name[100];

```

```

{

```

```

struct timeval temp ;

long time_elapsed ;

gettimeofday( &temp, 0 );

time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;

time_elapsed += ( temp.tv_usec - clock_offset.tv_usec )/1000 ;

printf(" sendEnd      %s      %d      %d\n",structure_name,

      grain_id, time_elapsed);

}

```

```

get_recv_begin_time( grain_id, structure_name )

```

```

int grain_id ;

char structure_name[100];

{

    struct timeval temp ;

    long time_elapsed ;

    gettimeofday( &temp, 0 );

    time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;

    time_elapsed += ( temp.tv_usec - clock_offset.tv_usec )/1000 ;

    printf(" recvBegin      %s      %d      %d\n",structure_name,

          grain_id, time_elapsed);

}

```

```

get_recv_end_time( grain_id, structure_name )

```

```

int grain_id ;

char structure_name[100];

{

    struct timeval temp ;

```

```
long time_elapsed ;  
gettimeofday( &temp, 0 );  
time_elapsed = ( temp.tv_sec - clock_offset.tv_sec ) * 1000 ;  
time_elapsed += ( temp.tv_usec - clock_offset.tv_usec )/1000 ;  
printf(" recvEnd      %s      %d      %d\n",structure_name,  
       grain_id, time_elapsed);  
}
```

Chapter 4

Execution Profile Analyzer

Execution Profile Analyzer (**E P A**) is a program which reads the execution profile produced by the timing routines in a parallel application and generates result files which serve as input to **TaskGrapher**. It also produces a general report giving the overall speedup, overall processor utilization and per processor data on utilization and the time distribution among the grains which were mapped onto it. This chapter explains the operation and structure of **E P A** so that this analyzer can be used for generating different reports.

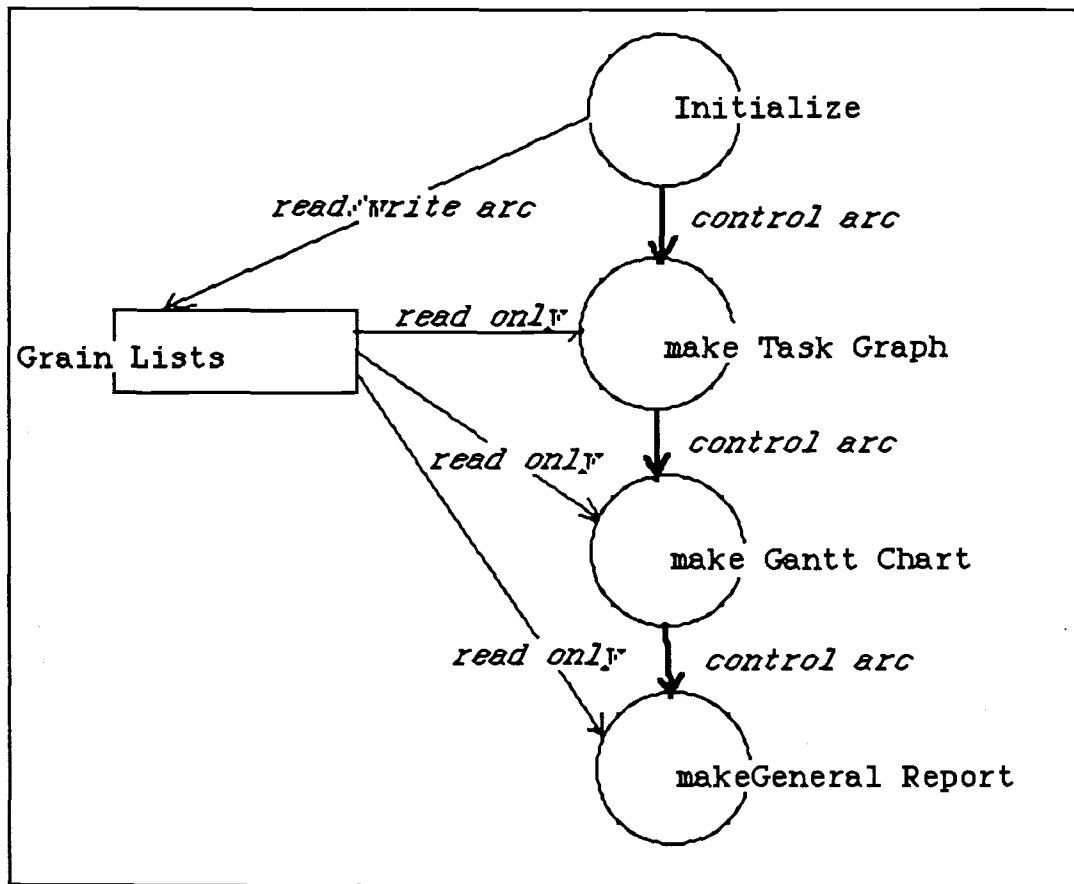


Fig. 4.1 : Top level ELGDF of E P A

The **E P A** is implemented using the Standard Pascal available on most UNIX™ machines (see Appendix B). The traces generated from an instrumented program can be piped directly to the **EPA** thus removing the intermediate trace storage. The **EPA** is also implemented on Apple™ Macintosh™ computer for off-line analysis. The UNIX™ version of **EPA** was developed for easy portability to different systems. The top level **E L G D F** of the program is shown in Fig.4.1. The main data structures manipulated in E P A are a doubly linked list of trace elements for all the processors in the application (see Fig. 4.2), a doubly linked list of all the arc elements (see Fig.4.3), and a doubly linked list of all the processors which

were used in the application(see Fig. 4.4). Each of the processor in the list of processors also has a doubly linked list of trace elements of the grains which were mapped onto that processor during actual execution.

The program first reads the trace file to create the three linked lists. Then report generation functions are executed yielding textual description of actual Gantt chart of execution, task graph of application and a General performance report. The General performance report contains the actual speedup, processor utilization and the percentage of times occupied by the grains mapped on the processors. Fig. 4.5 show an example of the reports generated. Table 4.1 gives the list of the procedures and functions in the current version of **E P A**. A complete listing of the program for UNIX™ based machines is provided in the Appendix B .

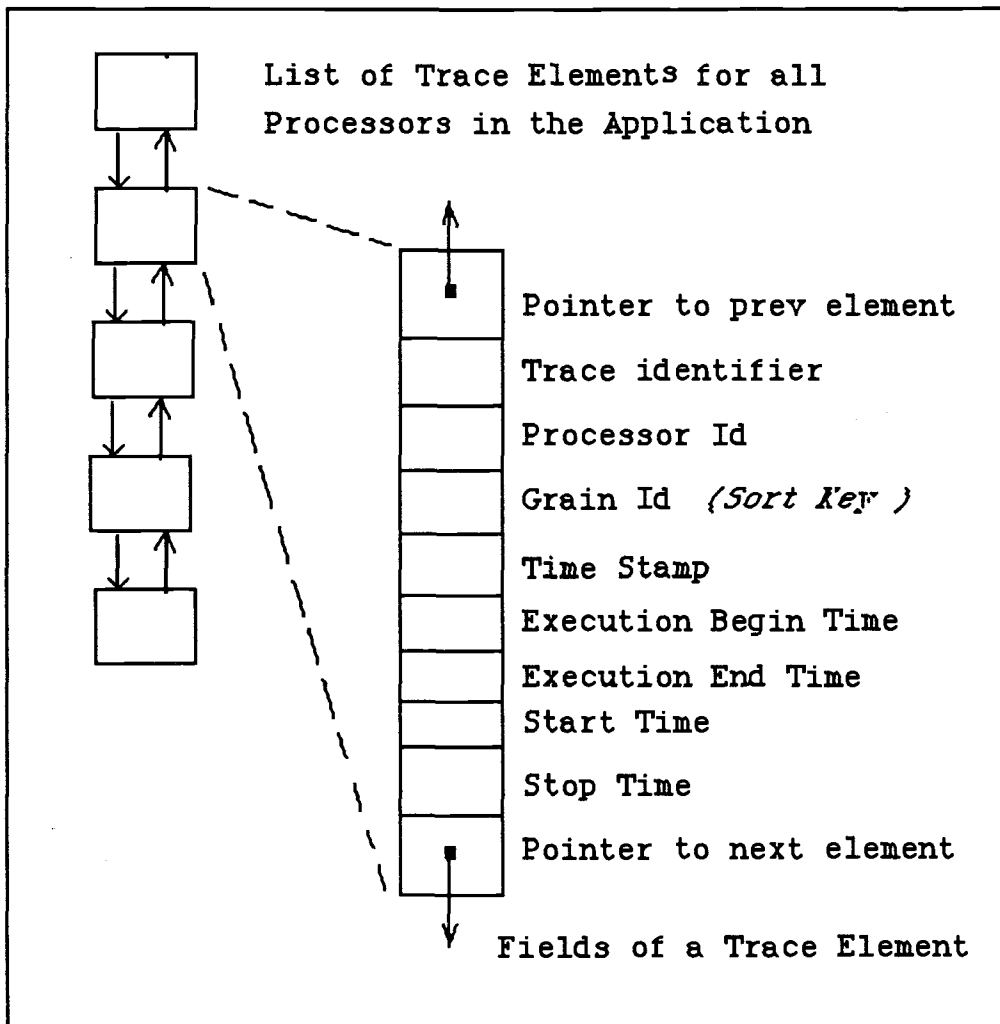


Fig. 4.2 : Data structures of E P A

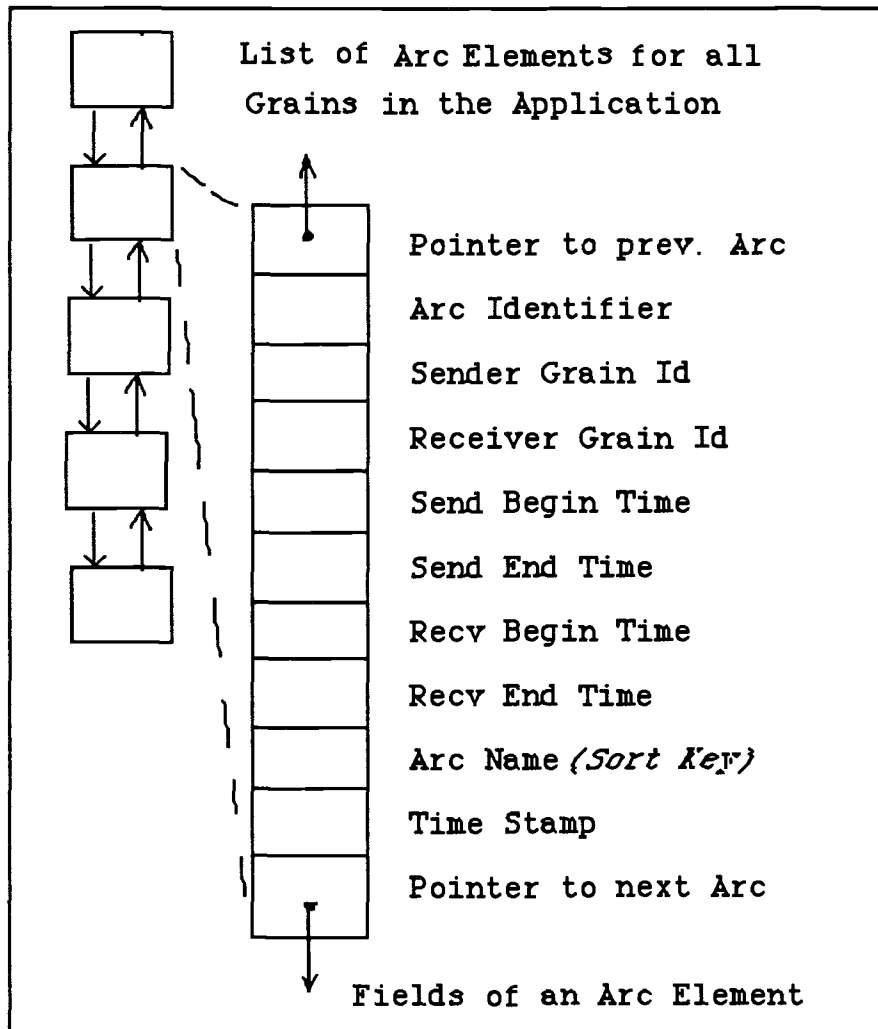


Fig. 4.3 Data structures of E P A

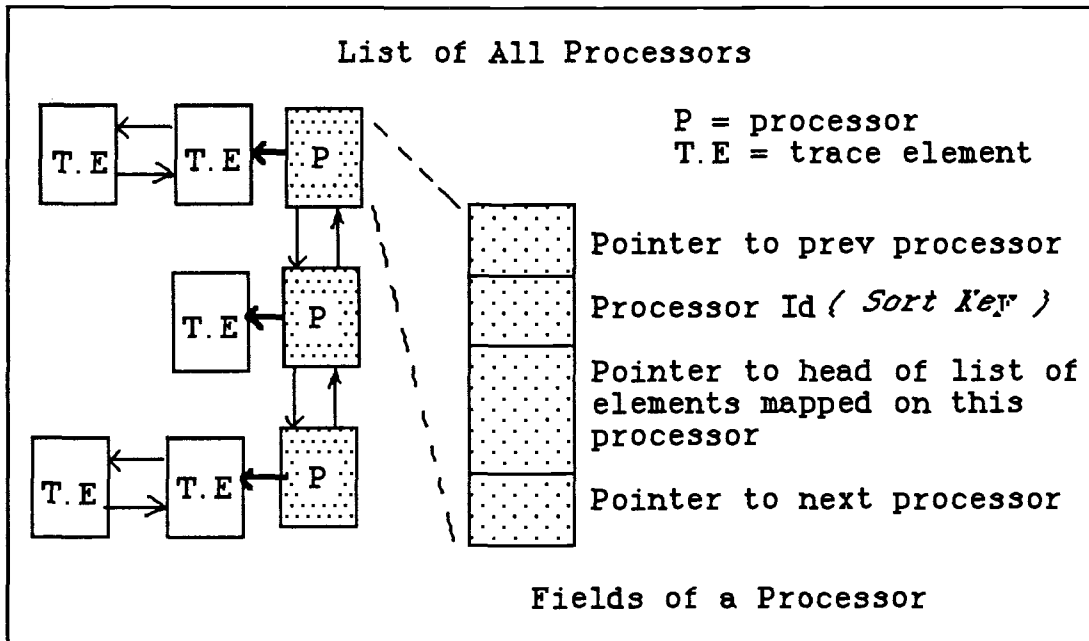


Fig. 4.4 : Data Structures of E P A

```

Speed up = 1.55
Overall Processor Utilization = 77
Data on Processor 1
Utilisation = 93
Grain id    % time
1           0
3           31
4           30
5           30
7           0

Data on Processor 2
Utilisation = 62
Grain id    % time
2           31
6           31

```

Fig. 4.5a : General Performance Report

```

Task_Graph <Identifies a Task Graph file >
7 < Total Number of Nodes >
  1    20    40    80    6    0
  2   1810   40   160    1    1
  3   1810   40   240    1    1
  4   1790   40   320    1    1
  5   1800   40   400    1    1
  6   1810   80    80    1    1
  7    10    80   160    0    6
11 < Total Number of Edges >
  1    3    0
  1    4   20
  1    5    0
  1    7   10
  1    6   10
  1    2   20
  2    7   10
  3    7    0
  4    7   10
  5    7    0
  6    7   10

```

Fig. 4.5b : Actual Task Graph file

```

Schedule < Identifies this as a schedule file >
7 < Total Number of Tasks on All Processors >
2 1.0 < Number of Processors, Transfer Rate >
1 < Processor# >
5 < Number of Tasks on this processor >
1 290 310 0 0
3 350 2160 0 0
4 2170 3960 0 0
5 3980 5780 0 0
7 5810 5820 0 0
2 < Processor# >
2 < Number of Tasks on this processor >
2 590 2400 0 0
6 2410 4220 0 0

```

Fig. 4.5c : Actual Gantt chart file

Table 4.1 : Procedures in E P A

Procedure	Called By	Calls
readMarker	getTracePoint	none
getTracePoint	makeTraceList	readMarker
swapTracePoints	orderByGrainId	none
swapProcessors	orderByProcessorId	none
swapProcessorTracePoints	orderByStartTime	none
placeTraceElement	makeTraceList	none
makeTraceList	initialize	getTracePoint placeTracePoint
orderByGrainId	initialize	swapTracePoints
orderByStartTime	orderByProcessorId	swapProcTracePts.
regroupTraceByProcessor	initialize	none
orderByProcessorId	initialize	swapProcessors orderByStartTime
makeELGDFfile	program	none
getTraceCount	makeMacScheduleReport makeGeneralReport	none
getProcessorCount	makeMacScheduleReport	none
getTotalExecutionTime	makeGeneralReport	none
makeMacScheduleReport	program	getTraceCount getProcessorCount getTotalExecTime

getRealExecutionTime	makeGeneralReport	none
makeGeneralReport	program	getRealExecTime
		getTotalExecTime
initialize	program	makeTraceList
		orderByGrainId
		regroupTraceByProc
		orderByProcId

Chapter 5

All Together

This chapter presents an example of the usefulness of **P P S E** tools for parallel programming. We consider the complete design, implementation and performance analysis of a program consisting of large grained, loosely coupled processes.

The example we consider approximates π using the rectangle rule[19]. The parallel version of this program is a typical broadcast, calculate and aggregate (BCA) problem where the data is sent(broadcast) to a number of worker tasks which after doing the calculations, send the data to a task which collects (aggregate) the results. An **ELGDF** expression¹ of the problem using the **Parallax** editor is shown in Fig.5.1.

¹ A succinct **ELGDF** representation of this problem would replace the workers by a Repetition symbol. However this is not done here since current version of **SuperGlue** requires simple nodes in the **ELGDF** representation of problem.

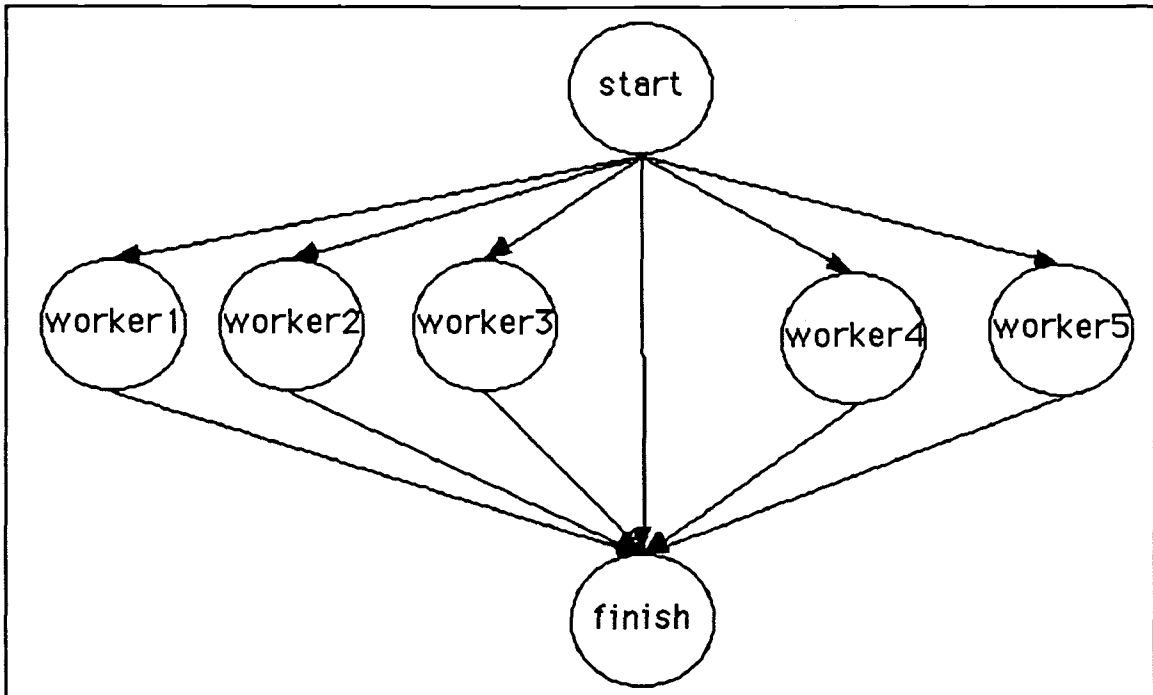


Fig. 5.1 : ELGDF representation of pi approximation problem

While editing the **ELGDF** description we enter the data to be passed along the arcs. Fig. 5.2 show the dialog box for entering data for the arc between the node "start" and "worker 1" .

Arc Information	
Arc Vars	<input type="text" value="interval,start1,stop1"/>
Arc Usage	<input type="radio"/> Read <input checked="" type="radio"/> Write <input type="radio"/> R/W
Mutual Exclusion	<input checked="" type="radio"/> No <input type="radio"/> Yes
Compound Arc	<input checked="" type="radio"/> No <input type="radio"/> Yes
Num. Of Iteration	<input type="text" value="1"/> Times
Message Size	<input type="text" value="1"/> Bytes
Documentation	<input type="text" value="refer start_worker1"/>
<input type="button" value="Cancel"/> <input type="button" value="OK"/>	

Fig. 5.2 : Specifications of an arc

The specifications of the nodes are similarly entered. Fig.5.3. shows the data entry dialog box for the node "start". The code fragment implementing the node start could be also entered at this stage¹. The code fragment for node "start" is shown in Fig.5.4.

After the Data flow design of application is completed, a transformer² would convert this ELGDF description into a task graph of the application. Using the task graph of the application we schedule the program using the scheduling tool **TaskGrapher**. From the ELGDF description of the problem it is clear that having five processors would yield the greatest speedup for this problem. However for this example

¹ Current implementation of **SuperGlue** uses a separate code fragment file rather than the code fragments entered through **Parallax**.

² This transformer has not been implemented in **PPSE**. Currently this transformation is done manually.

we used *Hu's Highest Level First* heuristic with two processors to illustrate the optimizing features of **TaskGrapher**.

Symbol Information

Compound Symbol No Yes

Symbol Name

Execution Time NS

Num. Of Iteration Times

Documentation

Fig. 5.3 : Specification of a node

Fig. 5.5 shows the task graph for this example. Each bubble represents the task to be scheduled. The number on the top of each bubble is the `grain_id` while the number at the bottom is the estimated time of execution. Note that at this stage we have no idea as to how long each task will take. Thus we use the default value of 1 at 'cold start'. The numbers on the arcs represent the communication delay which are similarly assumed to be unity.


```

<$$$StartCodeFragmentBlock$$$>
start
<$$$StartFragment$$$>
int i,l=1,m,n, workers,processors;
int start1,start2,start3,start4,start5;
int stop1,stop2,stop3,stop4,stop5;
double interval,h;
<$$$EndDCL$$$>
n = 10000;
interval = 1.0/n;

start1=1;
start2=2000;
start3=4000;
start4=6000;
start5=8000;
stop1=1999;
stop2=3999;
stop3=5999;
stop4=7999;
stop5=10000;
<$$$EndCodeFragmentBlock$$$>

```

Fig. 5.4 : Code fragment for node "start"

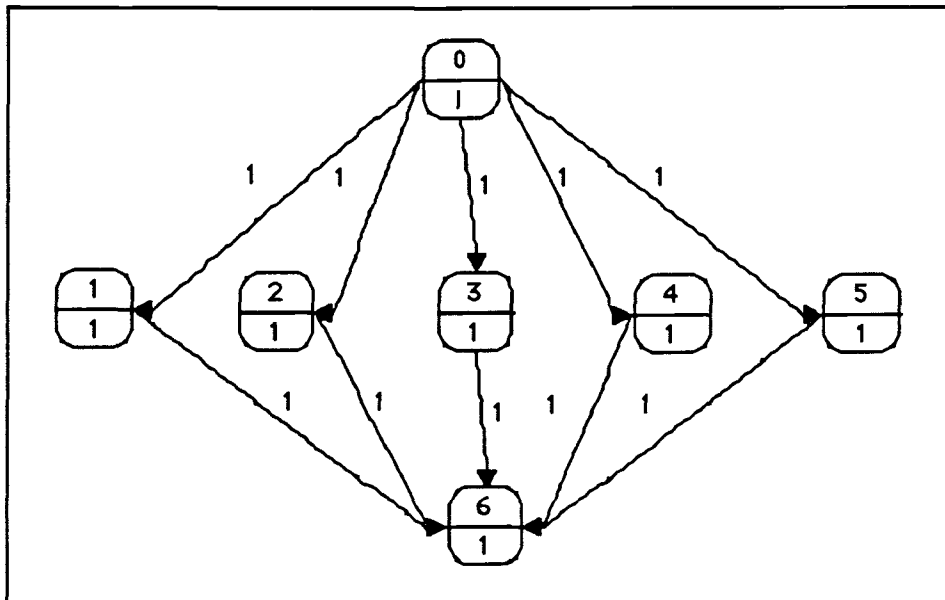


Fig. 5.5 : Task graph at 'cold start'

On the basis of this information the projected execution Gantt chart is obtained from the **TaskGrapher**. This is chart #1 in Fig.5.6.

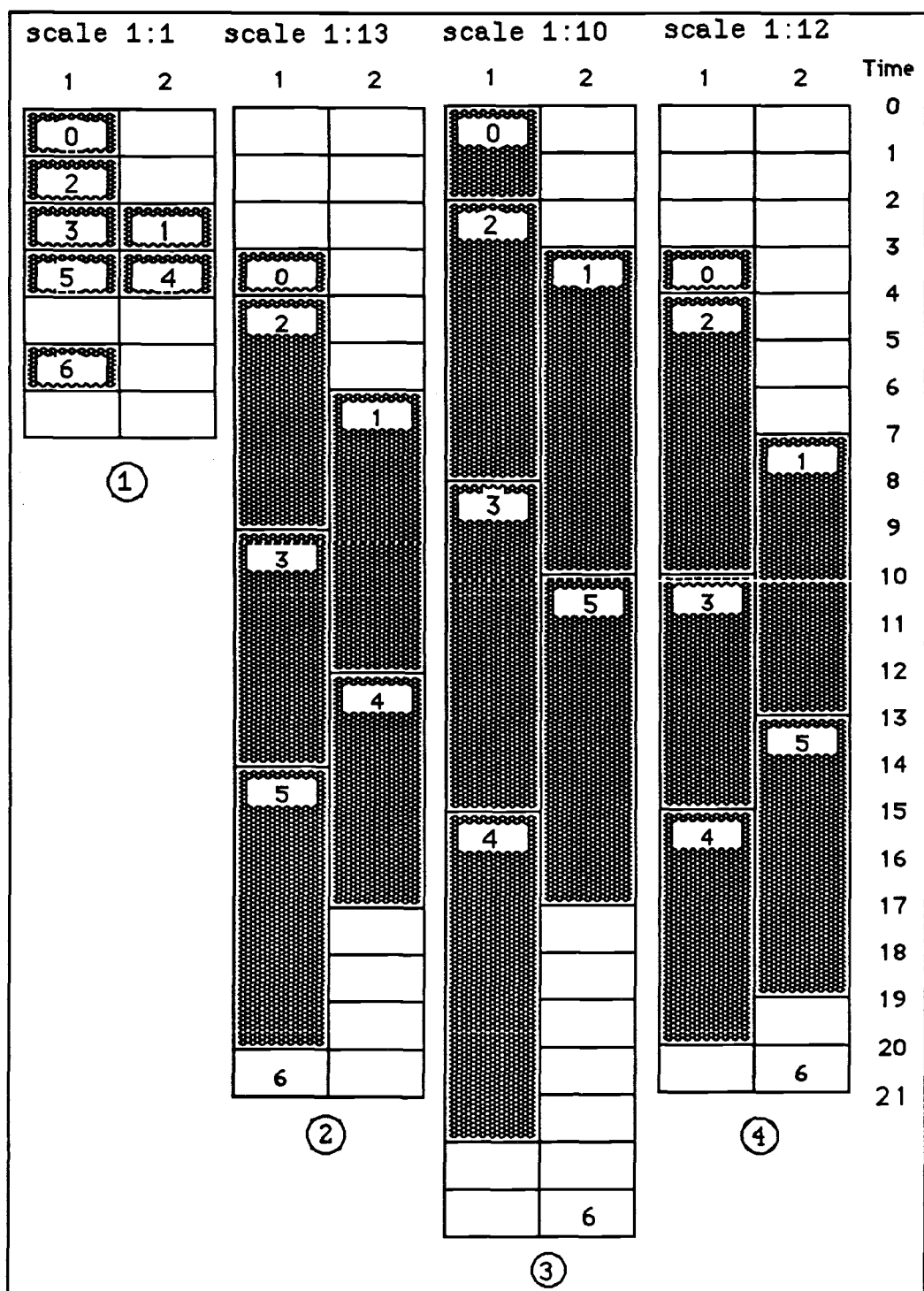


Fig. 5.6 : Execution Gantt Charts

Now we use **SuperGlue** to generate the source code for the Sequent™ machine and Linda-C parallel programming environment. **SuperGlue** takes in the description of the target machine, code fragments and the Gantt chart to yield the compilable source code as shown in Appendix C. The instrumented source code is produced when **SuperGlue Build Application** menu is selected with the timing option enabled. The program was compiled and run on the Sequent™ Symmetry™ in at 3:00 am when there were only two users on the machine. This was done to minimize the effects of operating system on process scheduling.

When the execution trace was analyzed by Execution Profile Analyzer(**E P A**) we obtained the actual execution time of the grains and the actual schedule. The actual Gantt chart of the first iteration is shown as chart # 2 in Fig.5.6. The total execution time was 260 millisecond, therefore the Gantt chart was scaled by a factor of 13 to fit on the screen.

Note that in the actual Gantt chart the execution of the program begins at the time of 40 milliseconds and not at 0 as shown in the projected Gantt chart. This apparent anomaly is due to the fact that the first 40 milliseconds are spent in the initialization of the program and the first grain starts execution after this interval. **TaskGrapher** assumes that the grains start executing when the program is launched. The order in which grains are executed is the same as projected but the execution times are much bigger than expected.

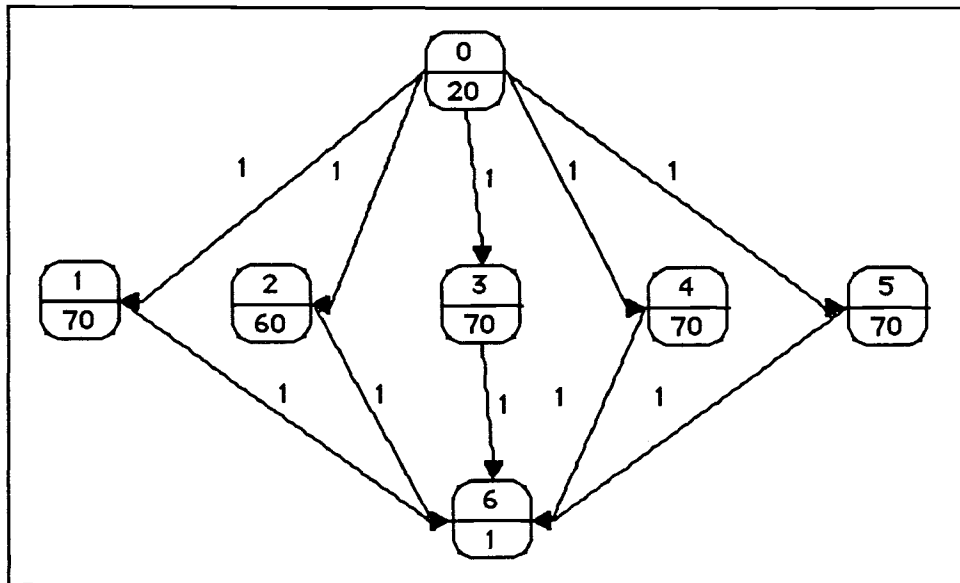


Fig. 5.7 : Task graph after first run

The task graph of the actual application is shown in Fig.5.7. Again using *Hu's Highest Level First* heuristic we get the projected execution Gantt chart. The projected execution time is 222 milliseconds, the Gantt Chart is too long to fit on the paper, so we scale it by 1:10. The scaled execution chart is shown as chart # 3 in Fig.5.6. We also note that on the basis of actual execution times the mapping of the tasks on the processors has been changed. The grains 5 and 6 have been moved to processor 2 while grain 4 has been mapped onto processor 1.

Armed with the new schedule, we go back again to **SuperGlue** and generate the instrumented source code and run it on the target machine. The traces are collected and analyzed. The actual execution

Gantt chart on the basis of this feedback is shown as chart # 4 in Fig.5.6. This actual chart is very close to the projected chart # 3 except for the initialization part of the program.

We also used **TaskGrapher** to get the speedup in this application as the number of processors in the machine is changed. The number of processors was set to five in the **TaskGrapher**. Then the **Speed up Curve** item in the **Analyze** menu is chosen. The **TaskGrapher** then draws the speedup curves for the selected scheduling heuristic(in this example *Hu's highest level first*). Fig. 5.8 shows the speedup curve for the graph in Fig. 5.5. For the graph in Fig.5.7 the projected speedup curve is shown in Fig. 5.9.

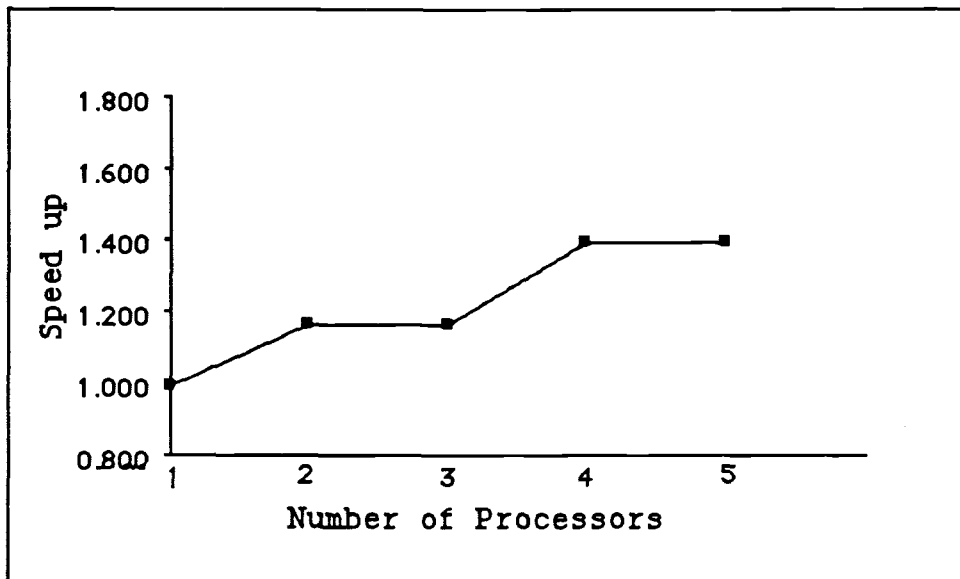


Fig. 5.8 : Speed up projections with 'cold start' data

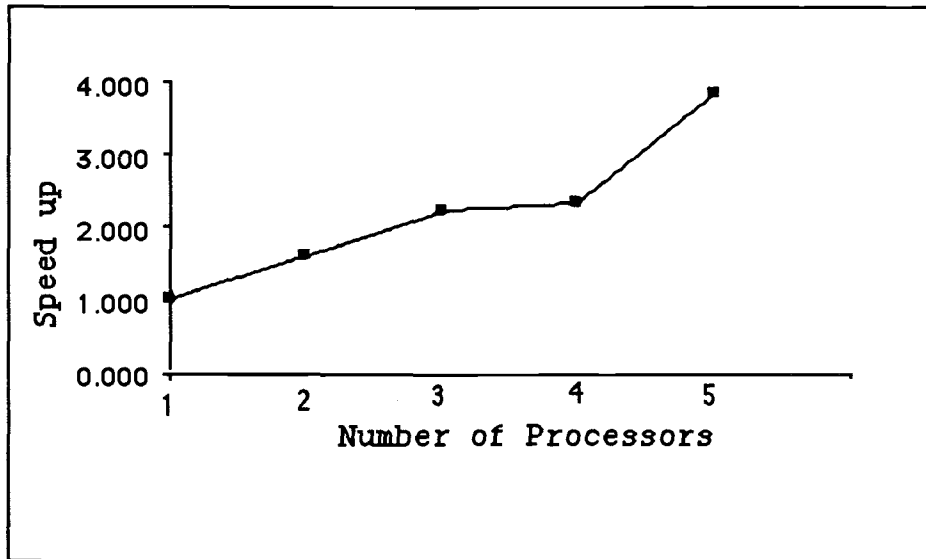


Fig. 5.9: Speedup projections with actual data

By changing the number of processors in the Task Graph of the application we obtained a set of Gantt charts for *Hu's highest level first* heuristic. These were used by SuperGlue to generate source code for the selected number of processors. When these applications were run we obtained the actual speedup. The actual speedups are shown in Fig. 5.10.

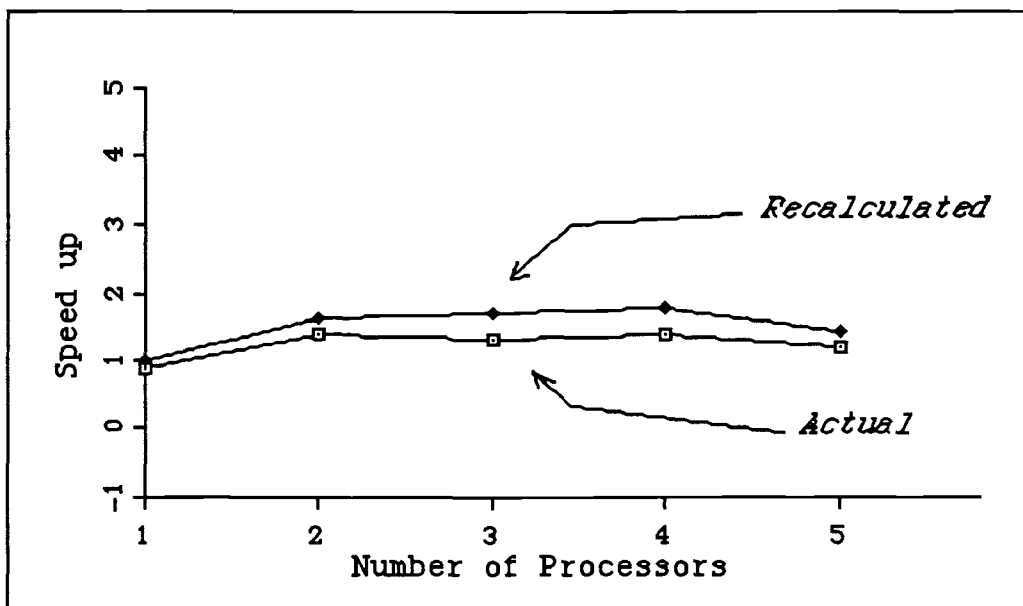


Fig. 5.10: Actual speedups

It is seen that there is considerable difference between the speed-ups especially when the number of processors is increased. A possible cause for this could be the fact that initialization time is not used by **TaskGrapher** for calculating speedups. We recalculated the speedups from the Gantt charts after ignoring the initialization to check if this was the only cause. As seen in Fig. 5.10 ignoring the initialization cost is not the only reason for mismatch. Notice that each grain in this example, is implemented as a set of three phases :- get variables, compute and put variables. By changing the number of iterations in the compute portion of the grain we can change the grain size (execution time). We experimented with changing the grain size to see how it compares with TaskGrapher predictions. The results of these experiments are summarized in Fig. 5.11.

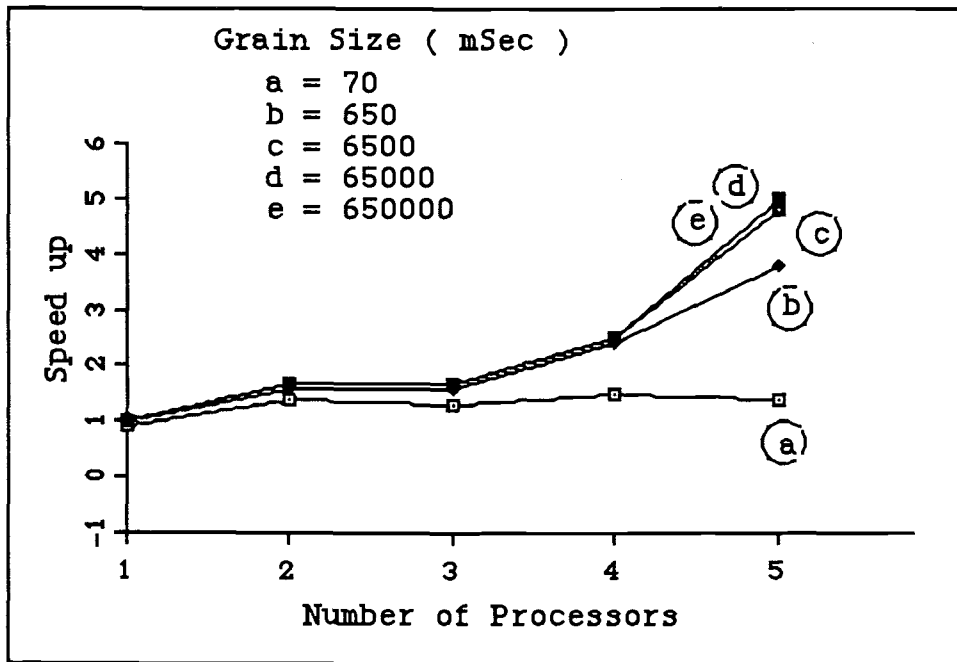


Fig. 5.11 : Effect of Grain Size on actual Speedup

It is seen that the prediction of **TaskGrapher** is close to the actual speedup for large grains (execution time more then 6500 milliseconds) for the C-Linda environment on the Sequent™ Symmetry™ machine. This also indicates that it is okay for **TaskGrapher** to ignore the initialization and process creation time in making the projections if large grains are used.

Chapter 6

Conclusions and Summary

In this thesis a methodology to analyze the performance of parallel applications was devised. The methodology involves inserting real-time measurement routines in the application's source code, collecting execution traces and off-line analysis of traces. It was seen that measurement of grain start and stop time in the **E L G D F** representation of an application provided data which makes it possible for **TaskGrapher** tool to accurately predict the application performance. The methodology presented in this thesis is most useful to the software engineer. However this method is unable to identify hardware bottlenecks within a specific architecture for a given application.

While developing the instrumentation and conducting the experiments, it was noted that Linda-C programming environment provided a straight forward model of parallel application in terms of interprocessor communication via shared tuple space. This high level abstraction frees the programmer from being concerned about synchronization or process scheduling. On the other hand the Sequent's parallel programming/microtasking library provides low level synchronization primitives which require a programmer's constant attention. On the basis of rather limited experience with these two environments, I found the choice of Linda based parallel

programming environment for **SuperGlue** to be appropriate in **PPSE** context.

The **PPSE** tools used most in connection with the work of this thesis were **ELGDF / Parallelax**, **TaskGrapher** and **SuperGlue**. The tools **ELGDF** and **TaskGrapher** are conceptually fully functional, but the human interface needs work. **Parallax** needs the following features :-

- On screen display of basic information about the nodes and arcs of the data flow diagram. This includes full name and type of the symbol¹.
- Printing dataflow diagram or a part of it.

TaskGrapher requires the following improvements :-

- Ability to scale Gantt charts so that a full chart can be seen on the screen.
- Zoom out sections of the selected charts i.e the user selects a section of the Gantt chart and then TaskGrapher redraws the screen so that the selected section covers the complete screen.
- If the number of processors is so large that all Gantt charts can not fit on the screen then, it should be possible to select

¹This could lead to a cluttered display for large designs. But on the other hand this cluttering would indicate to the user that he must coalesce some of the nodes into compound nodes.

processors and see their Gantt chart clearly.

- Print all or selected Gantt charts or selected part of a Gantt chart.
- An alternative to long Gantt charts could be the use of color to represent length i.e using green to show small grains, red to indicate long grains, other shades for intermediate grain sizes. The use of colors would also quickly identify the important grains.

The current version of **SuperGlue** generates source code for a flat **E L G D F** diagram of an application consisting of simple nodes and arcs only. The source code is generated in Linda-C language for the Sequent™ Balance™ machine. The Parallel Program Data Base is not functional at this stage or **P P S E** research. As a result the interfacing between different tools is via one-to-one compatible files. This made the movement from one tool to another rather clumsy.

In **P P S E** context, a useful extension to **Parallelax** would be to link the actual execution time data with an execution time estimator within the **Parallelax**. Another possibility is to build a database of execution reports. Then the **Parallelax** could direct queries to it for getting the estimate of execution time a particular grain.

We had started with the intuition that high resolution clocks are required for performance monitoring. The results indicate that for **E L G D F** model of parallel programs and for accurate **P P S E** tools predictions, high resolution real-time clocks are not necessary. In fact

the standard UNIX™ system clock with a resolution of 10 milliseconds is sufficient. The real-time measurement is of tremendous use in performance monitoring of parallel programs since it captures the synchronization of events in an unambiguous manner. Therefore implementing global clocks on the system along with simple routines to access them is an idea which parallel computer manufacturers should seriously consider.

A limitation of this proposed performance analysis methodology is that the inter-grain communication delay can not be measured accurately in the presence of parallel I/O channels in the system. This is because the instrumentation itself is a part of the application and it is subject to manipulation by the system on which the application is running. A valuable extension to this methodology would be to develop a mechanism which can relate the communications occurring at the hardware level (bus traffic, cache hit etc.) to the higher level language inter-grain communication primitives (send, receive etc.).

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Appendix A : Instrumented code of Travelling Salesman Problem

```

/*****
 *
 * Traveling Salesman Problem
 *
 * This is a parallel implementation of the Travelling Salesman Problem
 * First the initial path of the salesman is read as x and y coordinates
 * of the cities to be visited. Next the annealing parameters are
 * inputted. The annealing parameters determine how quickly and
 * accurately the path of the salesman will be converged.
 * In parallel implementation, each of the processor is given a copy of
 * the current path. The processor reduce the path for a number of
 * iterations and then they join at a barrier. The best solution is
 * selected and made the latest path. This continues till the annealing
 * parameters are satisfied.
 *
 * ORIGINAL VERSION BY : Martha, 01/1986
 * CURRENT VERSION BY : Anil Kumar Yadav, 09/1989
 *
 *****/
#include "time_sequent_c.h" /* timing routines for execution trace */
#include <stdio.h>
#include <math.h>
#include <parallel/microtask.h>
#include <sys/time.h>
#include <sys/resource.h>

#define TRUE 1
#define FALSE 0

#define MAXCYC 800 /* maximum temperature drops */
#define MAXPTS 1000 /* maximum points in path */

#define MAXPROC 100
#define EPSILON 0.000001 /* for floating point comparison */
#define RANF ((double)((randx = randx * 1103515245 + 12345) &
0x7fffffff)) / 214
7483647.

typedef int boolean;

typedef struct pointtype {
    float x;
    float y;
    struct pointtype *prev; /* ptr to previous point */
    struct pointtype *next; /* ptr to next point */
} POINT; /* x,y coords of point on path */

shared float beta; /* temperature for swapping */
shared float currtmp; /* current temperature */
shared float drop; /* drop in temperature */
shared float ftemp; /* final temperature */
shared float itemp; /* initial temperature */
shared long niter; /* iterations per drop in temp */
shared int nprocs; /* number of processes participating */
shared int npts; /* number of points in the path */
shared POINT *mypath[MAXPROC]; /* first point for each processor */

```



```

shared float mypathlen[MAXPROC]; /* pathlength for each process */
shared POINT *path;             /* first point in salesman's path */
shared float pathlen;          /* current path length */
shared float plog[MAXCYC];     /* path lengths at various temperatures */
shared static long randx;      /* for randomization of swapping */
shared float tlog[MAXCYC];     /* temperature log */
shared float timelog[MAXCYC];  /* time per iteration */

```

```

/*
* function to get the latest path from common path
*/
void get_current_path(pathpointer)
POINT *pathpointer;
{
    POINT *t, *s;
    int i;

    for( i = 0, t=pathpointer, s= path;i < npts; i++, s++, t++)
    {
        t->x = s->x;
        t->y = s->y;
    }

    /* link the points */
    for(i=0, t=pathpointer; i < npts; i++,t++)
    {
        if(i==(npts-1))
            t->next = &pathpointer[0];
        else
            t->next = &pathpointer[i+1];
        if(i==0)
            t->prev = &pathpointer[npts -1];
        else
            t->prev = &pathpointer[i - 1];
    }
}

```

```

/*
* function to put the latest path to common path
*/
void put_current_path(pathpointer)
POINT *pathpointer;
{
    POINT *t, *s;
    int i;

    for( i = 0, t=pathpointer, s= path;i < npts; i++, s++)
    {
        s->x = t->x;
        s->y = t->y;
        t=t->next;
    }

    /* link the points */
    for(i=0, t=path; i < npts; i++,t++)
    {

```

```

        if(i==(npts-1))
            t->next = &path[0];
        else
            t->next = &path[i+1];
        if(i==0)
            t->prev = &path[npts -1];
        else
            t->prev = &path[i - 1];
    }
}

/*
* function to return the index of the process having the smallest path
*/
int get_smallest_path_index()
{
    int currentIndex, i;
    float minPath;

    currentIndex = 0;
    minPath = mypathlen[0];
    for( i=0; i< nprocs; i++)
    {
        if( mypathlen[i] <= minPath)
        {
            currentIndex = i;
            minPath = mypathlen[i];
        }
    }
    return(currentIndex);
}

/*
* Swap points t and t->next if they make the path length shorter or if
* they don't with a certain probability. Calculate distances using the
* point below i and the two points above.
* This function called by iterate and run by multiple processes.
*
* 1/21/86: I originally had locked this entire routine since the
* values that the pointers pointed to could change, but there was no
* speedup at all when I added multiple processors. This was because
* the swaps were essentially being done sequentially. By only locking
* the section where the swap takes place, I am introducing a little
* more randomness into the algorithm. The actual points could be
* changed by the time they are swapped, but now there is some speedup.
*
* 9/1/89 : In the barrier based version each processor is minimizing
* its own copy of the path, thus there is no contention in accessing
* this function. Hence there are no locked parts in this functions
*/
cswap(t, swap, eint, erem)
POINT *t;                /* path pointer */
boolean *swap;           /* true if points interchanged */
float eint[], erem[];    /* for randomization of swapping */
{
float delta;             /* distance between points */
int idel;               /* integer of delta */

```

```

POINT point, *p;                                /* temporary coordinates */

p = &point;

p->x = t->prev->x - t->next->x;
p->y = t->prev->y - t->next->y;
delta = sqrt(p->x * p->x + p->y * p->y);

p->x = t->x - t->next->next->x;
p->y = t->y - t->next->next->y;
delta += sqrt(p->x * p->x + p->y * p->y);

p->x = t->prev->x - t->x;
p->y = t->prev->y - t->y;
delta -= sqrt(p->x * p->x + p->y * p->y);

p->x = t->next->x - t->next->next->x;
p->y = t->next->y - t->next->next->y;
delta -= sqrt(p->x * p->x + p->y * p->y);

*swap = FALSE;
if (delta <= 0.0) *swap = TRUE;
else {
    delta *= beta;
    if (delta > 49.0) delta = 49.0;
    idel = (int)delta;
    if (RANF < eint[idel] * erem[(int)(1000.0 * (delta - idel))])
        *swap = TRUE;
}

/* Switch t and t->next. */

if (*swap) {
    t->prev->next = t->next;
    t->next->prev = t->prev;
    t->next = t->next->next;
    t->next->prev = t;
    t->prev->next->next = t;
    t->prev = t->prev->next;
}

/*
 * Calculate the distance between two points.
 */
float distance(a, b)
POINT *a, *b;
{
    POINT point, *p;

    p = &point;
    p->x = a->x - b->x;
    p->y = a->y - b->y;

    return(sqrt(p->x * p->x + p->y * p->y));
}

```

```

/*
 * Each process tries to reduce the size of its path at each
 * temperature drop. At the end of its iterations it recalculates
 * the length of its path.
 */
void iterate()
{
static float eint[100];          /* for randomization of swapping */
static float erem[1000];        /* " " " " */
int high;                       /* index of top point I work on */
long i;                          /* loop index */
int j, k, l;                     /* loop indices */
int keep;                        /* points I work on */
int low;                         /* index of bottom point I work on */
POINT *mylow;                   /* pointer to starting index of my points */
int rem;                        /* remainder when points div. by procs */
static struct rusage start, finish; /* for timing */
boolean swapped;                /* true if points interchanged */
POINT *t, *s, *tprime;         /* temporary path pointers */
double x;                       /* for randomization of swapping */

/* Each node sets up randomizing constants for swapping. */
get_grain_start_time( m_myid, ( 3 + m_myid ) );

randx = (long) (27 * m_myid);
for (i = 0; i < 50; i++)
    eint[i] = exp(-(double)i);
for (i = 0, x = 0.0005; i < 1000; i++, x += 0.001)
    erem[i] = exp(-x);

m_single();

/*
 * since the processes are acting on parallel on the same path each will
 * will be given a part of the iterations
 */
niter = niter / nprocs;

for (currtemp = itemp, j = 0; currtemp > (ftemp - EPSILON) && currtemp >
0.0;
    currtemp -= drop, j++) {
    m_multi();
    get_current_path(mypath[m_myid] );
    low = 0;
    high = low + npts - 1;
/* Find and save a pointer to the first point in my portion of the path.
*/

    mylow = mypath[m_myid];      /* save the lowest point in my path */
    beta = 1.0 / currtemp;

    /* Move points around */

    for (i = 0L; i < niter; i++) {
        if (keep > 2) {
            /* swap pts within my path? (first point not involved) */
            for (k = low + 1, tprime = mylow->next; k < high - 1; k++) {
                cswap(tprime, &swapped, eint, erem);
            }
        }
    }
}

```

```

        tprime = tprime->next;
    }
}
/* mylow may be swapped in these two calls; want to keep it
   pointing to lowest one in MY path. */
if (keep > 1) {
    cswap(mylow, &swapped, eint, erem );
    /* swap my first two points? */
    if (swapped) {
        mylow = mylow->prev;    /* back to my lowest */
    }
}
cswap(mylow->prev, &swapped, eint, erem );
/* swap with previous point? */
if (swapped) {
    mylow = mylow->next;    /* back to my lowest */
}
}

/* Calculate the length of my path and its connection to my next
   neighbor. Update the shared path length. */

mypathlen[m_myid] = 0.0;
for (l = low, t = mylow; l <= high; l++, t = t->next) {
    mypathlen[m_myid] += distance(t, t->next);
}

/* all processes come together */
m_sync();
m_single();
l = get_smallest_path_index();
pathlen = mypathlen[l];
put_current_path(mypath[l]);
/* Calculate iteration time. */
tlog[j] = currtemp;
plog[j] = pathlen;
}
m_multi() ;
get_grain_stop_time( m_myid, ( 3 + m_myid ) );
}

/*
 * Use simulated annealing to approach the solution.
 */
void anneal()
{
int i,j,k;                /* loop indices */
char yn;                 /* yes/no answer */
char filename[30];       /* log file */
FILE *fp, *fopen();      /* log file pointer */
POINT *s, *t;
get_grain_start_time( 0, 3 ) ;
/* Get input from user. */

printf("\nEnter initial temperature: ");
scanf("%f", &itemp);
printf("Initial temperature is %6.3f\n", itemp);

```

```

printf("\nEnter drop in temperature: ");
scanf("%f", &drop);
printf("Drop in temperature is %6.3f\n", drop);

printf("\nEnter final temperature: ");
scanf("%f", &ftemp);
printf("Final temperature is %6.3f\n", ftemp);

printf("\nEnter the number of iterations per drop in temperature: ");
scanf("%ld", &niter);
printf("Number of iterations per cycle is %ld\n", niter);

/* Set up multiple processes. */

printf("\nEnter number of processors: ");
scanf("%d", &nprocs);
printf("nprocs = %d\n", nprocs);
if (m_set_procs(nprocs) != 0) {
    perror("It didn't work\n");
    printf("I asked for %d processes.\n", nprocs);
    exit(-1);
}

/* shared memory for each process is generated */
for( i = 0; i < nprocs; i++ )
    mypath[i] = ( POINT * ) shmalloc(sizeof( POINT ) * npts);

get_grain_stop_time( 0, 3 ) ;
m_fork(iterate);
}
/*
 * Write data to file.
 */
void
write_data()
{
    int i;                /* loop index */
    FILE *fopen();        /* for opening file */
    char outfile[30];     /* data file names */
    FILE *outfp;          /* file pointer */
    POINT *t;             /* runs along points on path */

    do {
        printf("Enter output data file name: ");
        scanf("%s", outfile);

        if ((outfp = fopen(outfile, "w")) == NULL)
            printf("Error opening output file.\n");
        } while (outfp == NULL);

    fprintf(outfp, "%d\n", npts);
    t = path;

    for (i = 0; i < npts; i++, t = t->next)
        fprintf(outfp, "%6.3f\t%6.3f\n", t->x, t->y);
    fclose(outfp);
}

```

```

main()
{
char command;                /* user-entered */
boolean done;                /* boolean */
FILE *fopen();               /* to open file */
int i;                        /* loop index */
static char infile[30];      /* data file names */
static FILE *infp;           /* file pointer */
POINT *t;                     /* runs along points on path */

initialize_clock() ;
get_grain_start_time( 0 , 1 );

do {
    printf("Enter name of data file: ");
    scanf("%s", infile);
    printf("\nfile = %s\n", infile);
    if ((infp = fopen(infile, "r")) == NULL)
        printf("Input file not found.\n");
    } while (infp == NULL);

fscanf(infp, "%d", &npts);
if (npts > MAXPTS) {
    printf("Number of points in file (%d) exceeds maximum allowed
(%d)\n",
        npts, MAXPTS);
    exit(1);                /* error exit */
}

printf("npts = %d\n", npts);
path = (POINT *) shmalloc(sizeof(POINT) * npts);

for (i = 0, t = path; i < npts; i++, t++) {
    fscanf(infp, "%f %f", &(t->x), &(t->y));
    # ifdef DEBUG
    printf("path[%d]:\tx = %6.3f\ty = %6.3f\n", i, t->x, t->y);
    # endif
}
get_grain_stop_time( 0 , 1 ) ;

/* Link the points. */
get_grain_start_time( 0 , 2 ) ;

for (i = 0, t = path; i < npts; i++, t++) {
    if (i == npts - 1)
        t->next = &path[0];
    else
        t->next = &path[i + 1];
    if (i == 0)
        t->prev = &path[npts - 1];
    else
        t->prev = &path[i - 1];
}
get_grain_stop_time( 0 , 2 ) ;

fclose(infp);
anneal();
get_grain_start_time( 0 , (3 + nprocs) ) ;

```

```
write_data();  
get_grain_stop_time( 0 , (3 + nprocs) ) ;  
}
```



```

arcPointer = ^arcElement ;
arcElement = record
  arcType : identifier ;
  sender : integer ;
  receiver : integer ;
  sendBeginTime : integer ;
  sendEndTime : integer ;
  recvBeginTime : integer ;
  recvEndTime : integer ;
  arcName : array[1..100] of char ;
  flashTime : integer ;
  next : arcPointer ;
  prev : arcPointer ;
end ;

var
  ELGDFReport : text ;
  MacScheduleReport : text ;
  GeneralReport : text ;

  arcHead : arcPointer ;
  processorHead : processorPointer ;
  traceHead : tracePointer ;

{-----}
function readMarker : integer ;
{
  }
{ This function reads in the standard input till it finds the }
{ keywords 'start' or 'stop' which mark the beginning of a }
{ trace point. It returns 0 for 'start', 1 for 'stop' and 99 for }
{ if the keywords are not found. }
{ Called From : getTracePoint }
{ Calls : none }
var
  character : char ;
  word : array[1..100] of char ;
  found : integer ;
  counter : integer ;
  status : integer ;
begin
  status := 99 ;
  found := FALSE ;

  while(( not eof ) and ( found = FALSE )) do
  begin
    counter := 1 ; { initialize a blank word }
    while( counter <> 101 ) do
    begin
      word[counter] := ' ' ;
      counter := counter + 1 ;
    end ;

    counter := 0 ; { read word from input }
    read(character) ;

    while((character <> ' ')and( character <> chr(9))
      and ( counter < 100 )) do
    begin

```

```

        counter := counter + 1 ;
        word[counter] := character ;
        read(character) ;
    end ;

    if( word = 'start' ) then      { check if it is an identifier }
    begin
        status := START ;
        found := TRUE ;
    end ;

    if( word = 'stop' ) then      { check if it is an identifier }
    begin
        status :=STOP ;
        found := TRUE ;
    end ;

    if( word = 'sendBegin' ) then { check if it is an identifier }
    begin
        status :=SENDERBEGIN ;
        found := TRUE ;
    end ;

    if( word = 'sendEnd' ) then   { check if it is an identifier }
    begin
        status :=SENDEREND ;
        found := TRUE ;
    end ;

    if( word = 'recvBegin' ) then { check if it is an identifier }
    begin
        status :=RECVBEGIN ;
        found := TRUE ;
    end ;

    if( word = 'recvEnd' ) then   { check if it is an identifier }
    begin
        status :=RECVEND ;
        found := TRUE ;
    end ; { while }

    if( found = TRUE ) then      { return the search status }
        readMarker := status
    else
        readMarker := 99 ;

end ; { readMarker }
{-----}
function getArcPoint ( marker : integer ) : arcPointer ;
var
    temp : arcPointer ;
    counter : integer ;
    character : char ;
    word : array[1..100] of char ;
begin
    new( temp ) ;

```

```

case marker of
  SENDBEGIN : temp^.arcType := sendBegin ;
  SENDEND   : temp^.arcType := sendEnd   ;
  RECVBEGIN : temp^.arcType := recvBegin ;
  RECVEND   : temp^.arcType := recvEnd   ;
end ; { case }

counter := 1 ;
while ( counter <> 101 ) do
begin
  word[counter] := ' ' ;
  counter := counter + 1 ;
end ;

counter := 0 ;
read(character) ;
while(( character = ' ' ) or ( character = chr(9))) do
  read(character) ;

while(( character <> ' ' ) and ( character <> chr(9) )
      and ( counter < 100 ) ) do
begin
  counter := counter + 1 ;
  word[counter] := character ;
  read(character) ;
end ;

temp^.arcName := word ;

case marker of
  SENDBEGIN, SENDEND : read( temp^.sender ) ;
  RECVBEGIN, RECVEND : read( temp^.receiver) ;
end ; { case }

read(temp^.flashTime) ;
readln ;
getArcPoint := temp ;
end ; { getArcPoint }
{-----}
function getTracePoint( marker : integer ) : tracePointer ;
{
  }
{ This function reads in one trace point from the standard }
{ input and stores it in a newly created record. }
{ Called From : makeTraceList }
{ Calls : readMarker }
{
  }
var
  temp : tracePointer ;
begin
  new( temp ) ;

  if(( marker = STOP ) or ( marker = START) ) then
  begin
    read( temp^.processorId ) ;
    read( temp^.grainId ) ;
    read( temp^.flashTime ) ; { read the time stamp }
    readln ;
    temp^.next := nil ;
  end ;
end ;

```

```

temp^.prev := nil ;
temp^.startTime := 0 ;
temp^.stopTime := 0 ;
if( marker = STOP ) then
    temp^.traceType := stop
else
    temp^.traceType := start ;
getTracePoint := temp ;    { return the pointer }
end
else
    getTracePoint := nil ;

end ; { getTracePoint }
{-----}
procedure swapArcPoints( one, two : arcPointer ) ;
{
    }
{ This procedure exchanges two trace elements in the linked of }
{ trace points of all the processors }
{ Called By : orderBySenderId }
{ Calls : none }
{
    }
var
temp : arcPointer ;
begin
temp := one^.prev ;
if ( temp = nil ) then
begin
one^.next := two^.next ;
one^.prev := two ;
two^.prev := nil ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end;

two^.next := one ;

if ( one = arcHead ) then
arcHead := two ;

end { if }
else
begin
one^.next := two^.next ;
one^.prev^.next := two ;
two^.prev := one^.prev ;
one^.prev := two ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end ;

two^.next := one ;
end ; { else }
end ; { swapArcPoints }
{-----}

```

```

procedure swapTracePoints( one, two : tracePointer ) ;
{
  }
{ This procedure exchanges two trace elements in the linked of }
{ trace points of all the processors }
{ Called By : orderByGrainId }
{ Calls : none }
{
  }
var
temp : tracePointer ;
begin
temp := one^.prev ;
if ( temp = nil ) then
begin
one^.next := two^.next ;
one^.prev := two ;
two^.prev := nil ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end;

two^.next := one ;

if ( one = traceHead ) then
traceHead := two ;

end { if }
else
begin
one^.next := two^.next ;
one^.prev^.next := two ;
two^.prev := one^.prev ;
one^.prev := two ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end ;

two^.next := one ;
end ; { else }
end ; { swapTracePoints }
{-----}
procedure swapProcessors( one, two : processorPointer ) ;
{
  }
{ This procedure exchanges two processor records in the global }
{ linked list of processors. }
{ Called By : orderByProcessorId }
{ Calls : none }
{
  }
var
temp : processorPointer ;
begin
temp := one^.prev ;
if ( temp = nil ) then
begin
one^.next := two^.next ;

```

```

one^.prev := two ;
two^.prev := nil ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end;

two^.next := one ;

if ( one = processorHead ) then
processorHead := two ;

end { if }
else
begin
one^.next := two^.next ;
one^.prev^.next := two ;
two^.prev := one^.prev ;
one^.prev := two ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end ;

two^.next := one ;
end ; { else }
end ; { swapProcessors }
{-----}
procedure swapProcessorTracePoints( myProcessor : processorPointer ;
one, two : tracePointer ) ;
{
}
{ This procedure exchanges the trace points within the linked }
{ of the tracepoints of a particulat processor. }
{ Called By : orderByStartTime }
{ Calls : none }
var
temp : tracePointer ;
begin
temp := one^.prev ;
if ( temp = nil ) then
begin
one^.next := two^.next ;
one^.prev := two ;
two^.prev := nil ;

if ( two^.next <> nil ) then
begin
two^.next^.prev := one ;
end;

two^.next := one ;

if ( one = myProcessor^.grainListHead ) then
myProcessor^.grainListHead := two ;

end { if }

```

```

else
  begin
    one^.next := two^.next ;
    one^.prev^.next := two ;
    two^.prev := one^.prev ;
    one^.prev := two ;

    if ( two^.next <> nil ) then
      begin
        two^.next^.prev := one ;
      end ;

      two^.next := one ;
    end ; { else }
  end ; { swapProcessorTracePoints }
  {-----}
  procedure placeArcElement ( newPoint : arcPointer ) ;
  var
    temp : arcPointer ;
    found : integer ;
  begin
    if ( arcHead = nil ) then
      begin
        case newPoint^.arcType of
          sendBegin : newPoint^.sendBeginTime := newPoint^.flashTime ;
          sendEnd : newPoint^.sendEndTime := newPoint^.flashTime ;
          recvBegin : newPoint^.recvBeginTime := newPoint^.flashTime ;
          recvEnd : newPoint^.recvEndTime := newPoint^.flashTime ;
        end ; { case }

        arcHead := newPoint ;
      end
    else
      begin
        found := FALSE ;
        temp := arcHead ;

        while (( temp <> nil ) and ( found = FALSE )) do
          begin
            if( temp^.arcName = newPoint^.arcName ) then
              found := TRUE
            else
              temp := temp^.next ;
            end; { while }

            if ( found = FALSE ) then
              begin
                case newPoint^.arcType of
                  sendBegin : newPoint^.sendBeginTime := newPoint^.flashTime ;
                  sendEnd : newPoint^.sendEndTime := newPoint^.flashTime ;
                  recvBegin : newPoint^.recvBeginTime := newPoint^.flashTime ;
                  recvEnd : newPoint^.recvEndTime := newPoint^.flashTime ;
                end ; { case }

                newPoint^.next := arcHead ;
                arcHead^.prev := newPoint ;
                arcHead := newPoint ;
              end
            end
          end
        end
      end
    end
  end

```



```

else
begin
  case newPoint^.arcType of
    sendBegin : begin
      temp^.sendBeginTime := newPoint^.flashTime ;
      temp^.sender := newPoint^.sender ;
      end ;
    sendEnd : begin
      temp^.sendEndTime := newPoint^.flashTime ;
      temp^.sender := newPoint^.sender ;
      end ;
    recvBegin : begin
      temp^.recvBeginTime := newPoint^.flashTime ;
      temp^.receiver := newPoint^.receiver ;
      end ;
    recvEnd : begin
      temp^.recvEndTime := newPoint^.flashTime ;
      temp^.receiver := newPoint^.receiver ;
      end ;
  end ; { case }

  dispose( newPoint ) ;
end ;
end ;
end ; { placeArcElement }
{-----}
procedure placeTraceElement( newPoint : tracePointer ) ;
{
  }
{ This procedure takes in the raw timestamped trace and then }
{ recreates the starting and ending times of the grain based on }
{ the marker type. The newly created trace element is put on the }
{ top of the global linked list of such trace elements }
{ Called By : makeTraceList }
{ Calls : none }
var
  temp : tracePointer ;
  found : integer ;
begin
  { if this is the first element in the list the create the list }
  if ( traceHead = nil ) then
    begin
      if( newPoint^.traceType = start ) then
        newPoint^.startTime := newPoint^.flashTime
      else
        newPoint^.stopTime := newPoint^.flashTime ;

      traceHead := newPoint ;
    end { if }
  else
    begin
      found := FALSE ;
      temp := traceHead ;

      { check if any element related to this grain already exists }
      while (( temp <> nil ) and ( found = FALSE )) do
        begin
          if ( temp^.grainId = newPoint^.grainId ) then
            found := TRUE

```

```

        else
            temp := temp^.next ;
        end ; { while }

    if ( found = FALSE ) then
        begin
            if( newPoint^.traceType = start ) then
                newPoint^.startTime := newPoint^.flashTime
            else
                newPoint^.stopTime := newPoint^.flashTime ;

            newPoint^.next := traceHead ;
            traceHead^.prev := newPoint ;
            traceHead := newPoint ;
        end { if }
    else
        begin
            case newPoint^.traceType of
                stop :
                    temp^.stopTime := newPoint^.flashTime ;
                start :
                    temp^.startTime := newPoint^.flashTime ;
            end ; { case }
        end ; { else }

    end ; { else }

end ; { placeTraceElement }
{-----}
procedure makeTraceList ;
{
    { This procedure creates the initial global linked list of      }
    { grains, their mapping on processes and their start and stop  }
    { times.                                                         }
    { Called By : initialize                                         }
    { Calls    : getTracePoint, placeTracePoint                      }
var
    kuka : tracePointer ;
    temp : arcPointer ;
    marker : integer ;
begin
    while ( not eof ) do
        begin
            marker := readMarker ;
            case marker of
                START, STOP : begin
                    kuka := getTracePoint( marker ) ;
                    placeTraceElement( kuka ) ;
                end ;
                SENDBEGIN, SENDEND, RECVBEGIN, RECVEND :
                    begin
                        temp := getArcPoint( marker ) ;
                        placeArcElement( temp ) ;
                    end ;
                99 : ;
            end ; { case }
        end ; { while }
    end ;

```

```

end ; { makeTraceList }
{-----}
procedure orderBySenderId ;
{
}
{ This procedure goes through the global linked list of trace }
{ elements and arranges the grains by their grain Id in an }
{ ascending order. }
{ Called By : initialize }
{ Calls : swapArcPoints }
var
temp : arcPointer ;
kuka : arcPointer ;
changed : integer ;
begin
changed := TRUE ;

while ( changed = TRUE ) do
begin
temp := arcHead ;
changed := FALSE ;

kuka := temp^.next ;
while ( kuka <> nil ) do
begin
if ( temp^.sender > temp^.next^.sender ) then
begin
swapArcPoints( temp, temp^.next ) ;
changed := TRUE ;
end ;

temp := temp^.next ;

if ( temp = nil ) then
kuka := temp
else
kuka := temp^.next ;
end ; { while }
end ; { while }
end ; { orderBySenderId }
{-----}
procedure orderByGrainId ;
{
}
{ This procedure goes through the global linked list of trace }
{ elements and arranges the grains by their grain Id in an }
{ ascending order. }
{ Called By : initialize }
{ Calls : swapTracePoints }
var
temp : tracePointer ;
kuka : tracePointer ;
changed : integer ;
begin
changed := TRUE ;

while ( changed = TRUE ) do
begin
temp := traceHead ;
changed := FALSE ;

```

```

kuka := temp^.next ;
while ( kuka <> nil ) do
  begin
    if ( temp^.grainId > temp^.next^.grainId ) then
      begin
        swapTracePoints( temp, temp^.next ) ;
        changed := TRUE ;
        end ;

        temp := temp^.next ;

        if ( temp = nil ) then
          kuka := temp
        else
          kuka := temp^.next ;
        end ; { while }
      end ; { while }
    end ; { orderByGrainId }
  }
}
-----}
procedure orderByStartTime( tempProcessor : processorPointer ) ;
{
  }
{ This procedure arranges the trace elements for a processor   }
{ in the increasing order of start time, which is used for     }
{ creating MacSchedule report file.                             }
{ Called By : orderByProcessorId                               }
{ Calls : swapProcessorTracePoints                             }
var
  temp : tracePointer ;
  kuka : tracePointer ;
  changed : integer ;
begin
  changed := TRUE ;

  while ( changed = TRUE ) do
    begin
      temp := tempProcessor^.grainListHead ;
      changed := FALSE ;

      kuka := temp^.next ;
      while ( kuka <> nil ) do
        begin
          if ( temp^.startTime > temp^.next^.startTime ) then
            begin
              swapProcessorTracePoints( tempProcessor, temp, temp^.next )
            ;

              changed := TRUE ;
              end ;

              temp := temp^.next ;

              if ( temp = nil ) then
                kuka := temp
              else
                kuka := temp^.next ;
              end ; { while }
            end ; { while }
          end ; { orderByStartTime }
        end ; { orderByStartTime }
      end ; { orderByStartTime }
    end ; { orderByStartTime }
  end ; { orderByStartTime }
end ; { orderByStartTime }

```

```

{-----}
procedure regroupTraceByProcessor ;
{
{ This procedure reads in the global linked list of the trace }
{ elements and makes a linked list of processors with each }
{ processor having a linked list of grains which were mapped on }
{ itself. }
{ Called By : initialize }
{ Calls : none }
var
    found : integer ;
    tempHead : processorPointer ;
    tempTrace : tracePointer ;
    temp : tracePointer ;
begin
    temp := traceHead ;

    while( temp <> nil ) do
    begin
        new(tempTrace);
        tempTrace^.processorId := temp^.processorId ;
        tempTrace^.grainId := temp^.grainId ;
        tempTrace^.startTime := temp^.startTime ;
        tempTrace^.stopTime := temp^.stopTime ;
        tempTrace^.next := nil ;
        tempTrace^.prev := nil ;

        if ( processorHead = nil ) then
            begin
                new( processorHead ) ;
                processorHead^.processorId := tempTrace^.processorId ;
                processorHead^.grainListHead := tempTrace ;
            end
        { if }
        else
            begin
                found := FALSE ;
                tempHead := processorHead ;

                while ( ( found = FALSE ) and ( tempHead <> nil ) ) do
                begin
                    if ( tempHead^.processorId = tempTrace^.processorId ) then
                        found := TRUE
                    else
                        tempHead := tempHead^.next ;
                    end; { while }

                    if ( found = TRUE ) then
                        begin
                            tempTrace^.next := tempHead^.grainListHead ;
                            tempHead^.grainListHead^.prev := tempTrace ;
                            tempHead^.grainListHead := tempTrace ;
                        end { if }
                    else
                        begin
                            new( tempHead ) ;
                            tempHead^.prev := nil ;
                            tempHead^.grainListHead := tempTrace ;
                            tempHead^.processorId := tempTrace^.processorId ;

```

```

        processorHead^.prev := tempHead ;
        tempHead^.next := processorHead ;
        processorHead := tempHead ;
    end ; { else }
end ; { else }

    temp := temp^.next ;
    end ; { while }
end; { regroupTraceByProcessor }
{-----}
procedure orderByProcessorId ;
{
    }
{ This procedure rearranges the linked list of processors to      }
{ give an ascending order. Also within each process it          }
{ rearranges the list of trace elements in ascending order by    }
{ by the start time.                                           }
{ Called By : initialize                                         }
{ Calls : swapProcessors, orderByStartTime                       }
var
    temp : processorPointer ;
    kuka : processorPointer ;
    changed : integer ;
begin
    changed := TRUE ;

    while ( changed = TRUE ) do
    begin
        temp := processorHead ;
        changed := FALSE ;

        kuka := temp^.next ;
        while ( kuka <> nil ) do
        begin
            if ( temp^.processorId > temp^.next^.processorId ) then
            begin
                swapProcessors( temp, temp^.next ) ;
                changed := TRUE ;
            end ;

            temp := temp^.next ;

            if ( temp = nil ) then
                kuka := temp
            else
                kuka := temp^.next ;
            end ; { while }
        end ; { while }

        temp := processorHead ;

        while( temp <> nil ) do
        begin
            orderByStartTime( temp ) ;
            temp := temp^.next ;
        end ; { while }
    end ; { orderByProcessorId }
{-----}
function getTraceCount( head : tracePointer ) : integer ;

```

```

{
}
{ This function goes through a list of trace elements and }
{ returns the number of elements present in the list. }
{ Called By : makeMacScheduleReport, makeGeneralReport }
{ Calls : none }
var
    tempCount : integer ;
    temp : tracePointer ;
begin
    tempCount := 0 ;
    temp := head ;

    while ( temp <> nil ) do
    begin
        tempCount := tempCount + 1 ;
        temp := temp^.next ;
    end ; { while }

    getTraceCount := tempCount ;
end ; { getTraceCount }
-----}
function getProcessorCount : integer ;
{
}
{ This function counts the number of elements present in the }
{ linked list of processors. }
{ Called By : makeMacScheduleReport }
{ Calls : none }
var
    tempCount : integer ;
    tempProc : processorPointer ;
begin
    tempCount := 0 ;
    tempProc := processorHead ;

    while ( tempProc <> nil ) do
    begin
        tempCount := tempCount + 1 ;
        tempProc := tempProc^.next ;
    end ;

    getProcessorCount := tempCount ;
end ; { getProcessorCount }
-----}
function getTotalExecutionTime : integer ;
{
}
{ This function goes through the linked list of all the trace }
{ elements and yeilds the overall execution time. Overall }
{ execution time is the highest value of the stop time among all }
{ the grains. }
{ Called By : makeGeneralReport }
{ Calls : none }
var
    temp : tracePointer ;
    maxTime : integer ;
begin
    maxTime := 0 ;
    temp := traceHead ;

```

```

while ( temp <> nil ) do
begin
  if ( temp^.stopTime > maxTime ) then
    maxTime := temp^.stopTime ;

    temp := temp^.next ;
  end ;

  getTotalExecutionTime := maxTime ;
end ; { getTotalExecutionTime }
-----}
function getActualStartTime : integer ;
{
  }
{ This function goes through the linked list of all the trace
{ elements and yeilds the actual start time . Overall
{ execution time is the highest value of the stop time among all
{ the grains.
{ Called By : makeGeneralReport
{ Calls : none
var
  temp : tracePointer ;
  minTime : integer ;
begin
  minTime := 9999999 ;
  temp := traceHead ;

  while ( temp <> nil ) do
  begin
    if ( temp^.startTime < minTime ) then
      minTime := temp^.startTime ;

      temp := temp^.next ;
    end ;

    getActualStartTime := minTime ;
  end ; { getActualStartTime }
  -----}
procedure makeMacScheduleFile ;
{
  }
{ This procedure goes through the linked list of the processors
{ and prints a file named 'MacScheduleReport' in the format of
{ of the MacSchedule 1.0 Gantt Chart.
{ Called By : program
{ Calls : getTraceCount, getProcessorTime,
{ getTotalExecutionTime,
var
  tempProc : processorPointer ;
  tempTrace : tracePointer ;
  count : integer ;
  factor : integer ;
begin
  rewrite(MacScheduleReport);
  writeln( MacScheduleReport, 'Schedule',
    ' < Identifies this as a schedule file >' ) ;

  count := getTraceCount( traceHead ) ;
  writeln( MacScheduleReport, count,
    ' < Total Number of Tasks on All Processors >' ) ;

```



```

count := getProcessorCount ;
writeln( MacScheduleReport, count, '    1.0',
        ' < Number of Processors, Transfer Rate > ' );

count := getTotalExecutionTime ;
writeln('The total execution time for this program was ',count,
        ' msec');
factor := 1 ; {count div CHARTLENGTH ; }
writeln( ' The Gantt Chart and Task Graph have been scaled by : ',
        factor, ' for proper display');
tempProc := processorHead ;

while( tempProc <> nil ) do
begin
    writeln( MacScheduleReport, tempProc^.processorId,
            ' < Processor# >' ) ;

    count := getTraceCount( tempProc^.grainListHead ) ;
    writeln( MacScheduleReport, count,
            ' < Number of Tasks on this processor > ' );

    tempTrace := tempProc^.grainListHead ;

    while( tempTrace <> nil ) do
    begin
        write( MacScheduleReport, tempTrace^.grainId ) ;
        write( MacScheduleReport, tempTrace^.startTime div factor ) ;
        write( MacScheduleReport, tempTrace^.stopTime div factor ) ;
        count := 0 ;
        writeln( MacScheduleReport, count, count ) ;
        tempTrace := tempTrace^.next ;
    end ;
    tempProc := tempProc^.next ;
end ;
end ; { makeMacScheduleFile }
{-----}
function getRealExecutionTime( temp : tracePointer ) : integer ;
{ This procedure totals the execution time of all the grains to }
{ indicate the amount of time it will take if the program were }
{ to be executed in serial fashion.                               }
{ Called By : makeGeneralReport                                   }
{ Calls      : none                                              }
var
    time : integer ;
begin
    time := 0 ;

    while( temp <> nil ) do
    begin
        time := time + ( temp^.stopTime - temp^.startTime ) ;
        temp := temp^.next ;
    end ;

    getRealExecutionTime := time ;
end ; { getRealExecutionTime }
{-----}
procedure makeGeneralReport ;

```

```

{
}
{ This procedure prints the information regarding overall }
{ performance of the program and also utilization by each of the }
{ the processor and grains }
{ Called By : program }
{ Calls : getTotalExecutionTime, getRealExecutionTime }
var
    count, totalTime, goodTime : integer ;
    efficiency : real ;
    tempTrace : tracePointer ;
    tempProc : processorPointer ;
begin
    totalTime := getTotalExecutionTime ;
    goodTime := getRealExecutionTime( traceHead ) ;

    rewrite(GeneralReport) ;
    writeln(GeneralReport, ' Speed up = ',
            (goodTime / totalTime):10:1 ) ;
    count := getProcessorCount ;
    efficiency := ( (goodTime * 100) / ( totalTime * count ) ) ;
    writeln(GeneralReport, ' Overall Processor Utilization = ',
            efficiency:10:1, ' %' ) ;
    writeln(GeneralReport) ;
    tempProc := processorHead ;

    while( tempProc <> nil ) do
    begin
        writeln(GeneralReport, ' Data on Processor ',
                tempProc^.processorId:6 ) ;
        goodTime := getRealExecutionTime( tempProc^.grainListHead ) ;
        writeln(GeneralReport, ' Utilisation = ',
                (goodTime*100/totalTime):10:1, ' %' ) ;
        writeln( GeneralReport, ' Grain id % time ');
        tempTrace := tempProc^.grainListHead ;

        while ( tempTrace <> nil ) do
        begin
            writeln(GeneralReport,tempTrace^.grainId,
                    ((tempTrace^.stopTime - tempTrace^.startTime)
                     * 100 / totalTime):10:1 ) ;
            tempTrace := tempTrace^.next ;
        end ; { while }

        tempProc := tempProc^.next ;
        writeln(GeneralReport) ;
    end ; { while }
end ; { makeGeneralReport }
{-----}
function getArcCount : integer ;
var
    temp : arcPointer ;
    count : integer ;
begin
    temp := arcHead ;
    count := 0 ;

    while ( temp <> nil ) do
    begin

```

```

        count := count + 1 ;
        temp := temp^.next ;
    end ; { while }

    getArcCount := count ;
end ; { getArcCount }
{-----}
function getNumberOfSuccessor( nodeId : integer ) : integer ;
var
    temp : arcPointer ;
    count : integer ;
begin
    count := 0 ;
    temp := arcHead ;

    while( temp <> nil ) do
    begin
        if ( temp^.sender = nodeId ) then
            count := count + 1 ;
            temp := temp^.next ;
        end ; { while }

        getNumberOfSuccessor := count ;
    end ; { getNumberOfSuccessor }
    {-----}
function getNumberOfPredecessor( nodeId : integer ) : integer ;
var
    temp : arcPointer ;
    count : integer ;
begin
    count := 0 ;
    temp := arcHead ;

    while( temp <> nil ) do
    begin
        if ( temp^.receiver = nodeId ) then
            count := count + 1 ;
            temp := temp^.next ;
        end ; { while }

        getNumberOfPredecessor := count ;
    end ; { getNumberOfPredecessor }
    {-----}
procedure makeELGDFfile ;
{
}
{ This procedure reads the global linked list of the grains and }
{ prints out the grain Id and the execution time in the file   }
{ named 'ELGDFReport'                                         }
{ Called By : program                                           }
{   Calls   : none                                             }
var
    factor : integer ;
    top : integer ;
    left : integer ;
    count : integer ;
    mynum : integer ;
    delay : integer ;
    temp : tracePointer ;

```

```

    tempArc : arcPointer ;
    executionTime : integer ;
begin
    rewrite( ELGDFReport ) ;
    count := getTotalExecutionTime ;
    factor := 1 ; { count div CHARTLENGTH ; }
    writeln( ELGDFReport, 'Task_Graph <Identifies a Task Graph file
>' );
    temp := traceHead ;
    count := getTraceCount( traceHead ) ;
    writeln( ELGDFReport, count, ' < Total Number of Nodes >' );
    count := 0 ;
    top := 40 ;
    left := 80 ;

    while( temp <> nil ) do
    begin
        write(ELGDFReport, ( temp^.grainId + 1 ) ) ;
        executionTime := temp^.stopTime - temp^.startTime ;
        write(ELGDFReport, ( executionTime div factor ) ) ;
        write(ELGDFReport, top ) ;
        write(ELGDFReport, left ) ;
        mynum := getNumberOfSuccessor( temp^.grainId ) ;
        write(ELGDFReport, mynum) ;
        mynum := getNumberOfPredecessor( temp^.grainId ) ;
        write(ELGDFReport, mynum) ;
        writeln(ELGDFReport) ;
        count := count + 1 ;
        top := 40 + 40 * ( count div 5 ) ;
        left := 80 + 80 * ( count mod 5 ) ;
        temp := temp^.next ;
    end ; { while }

    tempArc := arcHead ;
    mynum := getArcCount ;
    writeln(ELGDFReport, mynum, ' < Total Number of Edges >' ) ;

    while( tempArc <> nil ) do
    begin
        delay := ( tempArc^.sendEndTime - tempArc^.sendBeginTime ) ;
        delay := delay+(tempArc^.recvEndTime - tempArc^.recvBeginTime) ;
        write(ELGDFReport, (tempArc^.sender + 1 )) ;
        write(ELGDFReport, ( tempArc^.receiver + 1 )) ;
        writeln(ELGDFReport, ( delay div factor )) ;
        tempArc := tempArc^.next ;
    end ;
end ; { makeELGDFfile }
{-----}
procedure getCorrectSpeedup ;
var
    startTime : integer ;
    stopTime : integer ;
    pcount : integer ;
    speed : real ;
    realTime : integer ;
begin
    pcount := getProcessorCount ;
    stopTime := getTotalExecutionTime ;

```

```

    realTime := getRealExecutionTime( traceHead ) ;
    startTime := getActualStartTime ;
    speed := ( realTime ) / ( stopTime - startTime ) ;
    writeln('processors = ',pcount,' speedup is =',speed:10:2 );
end ;
{-----}
procedure initialize ;
{
    }
{ This procedure makes calls to appropriate routines to      }
{ create the linked lists of trace elements, processors, arrange }
{ them in order suitable for proper file generation          }
{ Called By : program                                       }
{ Calls : see inside                                       }
begin
    processorHead := nil ;
    traceHead := nil ;
    arcHead := nil ;
    makeTraceList ;
    orderByGrainId ;
    regroupTraceByProcessor ;
    orderByProcessorId ;
    orderBySenderId ;
end; { initialize }
{-----}
begin { program }

    initialize ;
    makeELGDFfile ;
    makeMacScheduleFile ;
    makeGeneralReport ;
end. { program }

```

Appendix C : Instrumented Code generated by SuperGlue

```

#include <linda.h>
#include "time_linda_c.h"
#include <stdio.h>
    /*It worked *****!!*/
real_main()
{
    int df0;
    int df1;
    int df2;
    int df3;
    int df4;
    int df5;
    int df6;
    int i;
    initialize_clock();
    scheduler();
} /* End of MainLine!! */
df0()
{
    int i,l=1,m,n, workers,processors;
    int start1,start2,start3,start4,start5;
    int stop1,stop2,stop3,stop4,stop5;
    double interval,h;

    get_grain_start_time(1,0);
    n = 100000;
    interval = 1.0/n;

    start1=1;
    start2=20000;
    start3=40000;
    start4=60000;
    start5=80000;
    stop1=19999;
    stop2=39999;
    stop3=59999;
    stop4=79999;
    stop5=100000;

    get_grain_stop_time(1,0);

    get_send_begin_time(0,"superGlue06");
    out("superGlue06", interval);
    get_send_end_time(0,"superGlue06");

    get_send_begin_time(0,"superGlue05");
    out("superGlue05", interval, start5, stop5);
    get_send_end_time(0,"superGlue05");

    get_send_begin_time(0,"superGlue04");
    out("superGlue04", interval, start4, stop4);
    get_send_end_time(0,"superGlue04");

    get_send_begin_time(0,"superGlue03");
    out("superGlue03", interval, start3, stop3);
    get_send_end_time(0,"superGlue03");

```

```

    get_send_begin_time(0,"superGlue02");
    out("superGlue02", interval, start2, stop2);
    get_send_end_time(0,"superGlue02");

    get_send_begin_time(0,"superGlue01");
    out("superGlue01", interval, start1, stop1);
    get_send_end_time(0,"superGlue01");
} /* End of function df0*/
df1()
{
    int start1,stop1;
    int i;
    double interval,x,result1=0.0;

    get_rcv_begin_time(1,"superGlue01");
    in("superGlue01", ?interval,?start1,?stop1);
    get_rcv_end_time(1,"superGlue01");

    get_grain_start_time(2,1);
    for(i=start1;i<=stop1;++i)
    {
        x=(i-0.5)*interval;
        result1+=4.0/(1.0+x*x);
    }

    get_grain_stop_time(2,1);

    get_send_begin_time(1,"superGlue16");
    out("superGlue16", result1);
    get_send_end_time(1,"superGlue16");
} /* End of function df1*/
df2()
{
    int start2,stop2;
    int i;
    double interval,x,result2=0.0;

    get_rcv_begin_time(2,"superGlue02");
    in("superGlue02", ?interval,?start2,?stop2);
    get_rcv_end_time(2,"superGlue02");

    get_grain_start_time(1,2);
    for(i=start2;i<=stop2;++i)
    {
        x=(i-0.5)*interval;
        result2+=4.0/(1.0+x*x);
    }

    get_grain_stop_time(1,2);

    get_send_begin_time(2,"superGlue26");
    out("superGlue26", result2);
    get_send_end_time(2,"superGlue26");
} /* End of function df2*/
df3()
{

```

```

int start3,stop3;
int i;
double interval,x,result3=0.0;

get_recv_begin_time(3,"superGlue03");
in("superGlue03", ?interval,?start3,?stop3);
get_recv_end_time(3,"superGlue03");

get_grain_start_time(1,3);
for(i=start3;i<=stop3;++i)
{
    x=(i-0.5)*interval;
    result3+=4.0/(1.0+x*x);
}

get_grain_stop_time(1,3);

get_send_begin_time(3,"superGlue36");
out("superGlue36", result3);
get_send_end_time(3,"superGlue36");
} /* End of function df3*/
df4()
{
    int start4,stop4;
    int i;
    double interval,x,result4=0.0;

    get_recv_begin_time(4,"superGlue04");
in("superGlue04", ?interval,?start4,?stop4);
get_recv_end_time(4,"superGlue04");

    get_grain_start_time(1,4);
for(i=start4;i<=stop4;++i)
{
    x=(i-0.5)*interval;
    result4+=4.0/(1.0+x*x);
}

    get_grain_stop_time(1,4);

    get_send_begin_time(4,"superGlue46");
out("superGlue46", result4);
get_send_end_time(4,"superGlue46");
} /* End of function df4*/
df5()
{
    int start5,stop5;
    int i;
    double interval,x,result5=0.0;

    get_recv_begin_time(5,"superGlue05");
in("superGlue05", ?interval,?start5,?stop5);
get_recv_end_time(5,"superGlue05");

    get_grain_start_time(2,5);
for(i=start5;i<=stop5;++i)
{
    x=(i-0.5)*interval;

```



```

    result5+=4.0/(1.0+x*x);
}

get_grain_stop_time(2,5);
get_send_begin_time(5,"superGlue56");
out("superGlue56", result5);
get_send_end_time(5,"superGlue56");
} /* End of function df5*/
df6()
{
    double result1,result2,result3,result4,result5;
    double h,pi_approx=0.0, interval;

    get_rcv_begin_time(6,"superGlue56");
    in("superGlue56", ?result5);
    get_rcv_end_time(6,"superGlue56");

    get_rcv_begin_time(6,"superGlue46");
    in("superGlue46", ?result4);
    get_rcv_end_time(6,"superGlue46");

    get_rcv_begin_time(6,"superGlue36");
    in("superGlue36", ?result3);
    get_rcv_end_time(6,"superGlue36");

    get_rcv_begin_time(6,"superGlue26");
    in("superGlue26", ?result2);
    get_rcv_end_time(6,"superGlue26");

    get_rcv_begin_time(6,"superGlue16");
    in("superGlue16", ?result1);
    get_rcv_end_time(6,"superGlue16");

    get_rcv_begin_time(6,"superGlue06");
    in("superGlue06", ?interval);
    get_rcv_end_time(6,"superGlue06");

    get_grain_start_time(1,6);
    pi_approx=result1+result2+result3+result4+result5;
    pi_approx=pi_approx*interval;
    printf("pi approximation %20.15lf\n",pi_approx);

    get_grain_stop_time(1,6);
} /* End of function df6*/
gant1() {
    df0();
    df2();
    df3();
    df4();
    df6();
    out("gant_done");
} /*end of gantt chart 1 */
gant2() {
    df1();
    df5();
    out("gant_done");
} /*end of gantt chart 2 */
scheduler()

```

```
{  
  eval(gant1());  
  eval(gant2());  
  in("gant_done");  
  in("gant_done");  
}
```