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Title: THE ANALYSIS OF DIRECTIONAL WAVE SPECTRA FROM CURRENT AND
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ABSTRACT APPROVED:

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Directional wave spectra have been estimated in this study based upon simultaneous subsurface measurements of current and pressure. Two previously developed methods, the stochastic and deterministic approaches, have been reviewed and restudied. It is demonstrated by means of the Correlation Theorem that the stochastic and deterministic approaches are, under certain conditions, identical. In order to improve directional spectrum results obtained from the combined stochastic/deterministic approach, a new method, the geometric approach, has been developed as part of this research effort. The geometric approach matches Fourier transformed wave properties to frequency dependent wavelet pairs in each frequency interval. The amplitude, direction and phase of each wavelet are uniquely specified by equating kinematic and dynamic properties for each frequency component. Wavelets evaluated in each frequency interval do not have an artificially imposed phase constraint in the geometric approach as they have in the stochastic/deterministic approach, providing a more realistic model to represent the directional properties of ocean random waves. This study shows that the geometric approach provides more reliable predictions of the water surface one-dimensional spectra as well as directional spectra. Finally, some semi-empirical equations are proposed and combined to represent the directional spectrum model. A least square error minimization analysis is used to quantify empirical equation parameters. The resulting directional spectra obtained from alternative methods are compared based on either real ocean data or computer simulated data.

THE ANALYSIS OF DIRECTIONAL WAVE SPECTRA
FROM CURRENT AND PRESSURE MEASUREMENTS

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TABLE OF CONTENTS

	<u>Page</u>
1. INTRODUCTION.....	1
1.1 Background.....	1
1.2 Scope of Work.....	6
2. THEORY.....	10
2.1 Introduction.....	10
2.2 Spectrum Definitions.....	10
2.3 Stochastic Approach.....	14
2.3.1 Linear Wave Superposition.....	15
2.3.2 Co-spectrum and Fourier Analysis.....	18
2.3.3 Directional Spreading Analysis.....	25
2.4 Deterministic Approach.....	37
2.4.1 Deterministic Study of Ocean Waves.....	39
2.4.2 Estimating of Wave Spectrum.....	44
2.4.3 Similarities Between the Stochastic and Deterministic Approaches.....	48
2.5 Geometric Approach.....	55
2.5.1 Kinematic Description.....	55
2.5.2 A solution Procedure.....	59
2.6 Discussion and Comparison of Alternative Method.....	62
3. NUMERICAL MODELS.....	68
3.1 Introduction.....	68
3.2 Pre-calculations for Measured Wave Properties.....	69
3.3 Smoothing Procedure for Directional Spectrum Estimations.....	72
3.3.1 Smoothing Procedure for the One-dimensional Frequency Spectrum.....	72
3.3.2 Smoothing of the Spreading Parameter and Central Angle.....	76
3.4 Proposed Models for Directional Wave Spectra.....	77
3.4.1 JONSWAP spectrum.....	78
3.4.2 Proposing Equations for the Spreading Parameter and Central Angle.....	79
3.5 Systematic Analysis of the Estimated Directional Spectrum.....	82
4. DATA ANALYSIS.....	87
4.1 Introduction.....	87
4.2 Seasonal Behavior of Measured Samples.....	87
4.3 Selection of Sample Length for Spectral Analysis.....	91
4.4 Comparisons of Results from Alternative Directional Spectrum Solution Methods.....	100
4.4.1 Direct Comparison of Selected Numerical Results.....	100
4.4.2 Directional Wave Properties Estimated in the Time and Frequency Domains.....	106
4.4.3 Selection of Significant Data Sets.....	110

TABLE OF CONTENTS
(Continued)

4.4.4	Graphical Presentation and Comparison of Directional Wave Spectrum Outputs.....	113
4.5	Parametric Analysis.....	127
4.6	Directional Wave Simulation Study.....	138
5.	CONCLUSIONS.....	144
5.1	Summary.....	144
5.2	Conclusions.....	145
5.3	Future Studies.....	147
	REFERENCES.....	148
	APPENDICES.....	150
	Appendix A - Summary of Least Square Analysis.....	151
A.1	JONSWAP Spectrum.....	151
A.2	Two Parameter Power Function of Spreading Parameter.....	153
A.3	Third-order Polynomial Function of Central Angle.....	154
	Appendix B - Statistics of Ocean Waves Evaluated in the Time and Frequency Domains.....	155
B.1	Statistics Evaluated in the Time Domain.....	155
B.2	Statistics Evaluated in the Frequency Domain.....	157
	Appendix C - Computer Program Listing.....	160
C.1	Pre-calculation: Program PRECAL.....	160
C.2	Directional Spectrum Estimation: the stochastic/deterministic approach, Program STOCH.....	164
C.3	Directional Spectrum Estimation: the geometric approach, Program GEOME.....	184

LIST OF FIGURES

<u>Figure</u>		<u>Page</u>
1.1	Directional frequency spectrum of water surface waves.....	2
1.2	Cross profile of directional frequency spectrum for a given frequency f_0	3
1.3	One-dimensional frequency spectrum.....	3
2.1	Data collecting system at location $\vec{s}_1=(x_1, y_1)$	12
2.2	Weighting function $W(\phi^*)=\sin[\frac{5}{2}\phi^*]/\sin[\frac{1}{2}\phi^*]$	26
2.3	Smoothed weighting function $\underline{W}(\phi^*)=\frac{8}{3}\cos^4[\frac{1}{2}\phi^*]$	28
2.4	Theoretical curve and sample values of C_1 and C_2	33
2.5	Normalized angular distribution function $E^*(\sigma, \phi')$	34
2.6	Parameter s versus frequency $f=\sigma/2\pi$ (Longuet-Higgins et al., 1963).....	35
2.7	Example frequency spectrum, central angle, spreading parameter behavior (Mitsuyasu et al., 1975).....	35
2.8	Example frequency spectrum, central angle, spreading parameter behavior (Forristall et al., 1978).....	35
2.9	Parameter s versus dimensionless frequency $\sigma_{1,-1}^*$	37
2.10	Directional velocity components.....	57
3.1	Flow chart of pre-calculation system.....	73
3.2	Bartlett spectral window.....	75
3.3	Flow chart of directional wave spectrum estimates.....	86
4.1	C.D.F. of Rayleigh distribution and empirical C.D.F. of V_{rms}/V_{RMS}	91
4.2	Plot of dimensionless parameters $\frac{\overline{V_t^2}}{V_t^2}$ versus $V_c/V_{c,1024}$	97
4.3	Plot of dimensionless parameters $E_{total}/E_{total,1024}$ versus $E_p/E_{p,1024}$	99
4.4	Plot of s_c versus ϕ_{main}	103

LIST OF FIGURES
(Continued)

4.5	Plot of s_c versus f_c	104
4.6	Plot of main direction $\bar{\phi}$ versus ϕ_{main}	107
4.7	Plot of mean square velocities $\overline{V_t^2}$ versus $\overline{V_f^2}$	108
4.8	Plot of E_{total} versus $\overline{V_t^2}/\overline{V_{\text{rms}}^2}$	111
4.9	Results of directional wave spectrum from the geometric approach.....	114
4.10	Results of directional velocity spectrum from the geometric approach.....	115
4.11	Results of directional wave spectrum from the stochastic/deterministic approach one angle mode solution.....	118
4.12	Results of directional velocity spectrum from the stochastic/deterministic approach one angle mode solution.....	119
4.13	Results of directional wave spectrum from the stochastic/deterministic approach double angle mode solution.....	120
4.14	Results of directional velocity spectrum from the stochastic/deterministic approach double angle mode solution.....	121
4.15	Comparison of directional spectra for alternative spreading function presentations.....	124
4.16	Comparison of directional spectra for alternative central angle presentations.....	126
4.17	Correlation study of E_{total} and A_{Ro}	137

LIST OF TABLES

Table	Page
4.1	Summary of measured wave property samples.....88
4.2	Sample statistics evaluated in the time domain.....93
4.3	Sample statistics evaluated in the frequency domain•94
4.4	Comparison of sample statistics in the time domain•96
4.5	Comparison of ratios $E_{total}/E_{total,1024}$ and $E_p/E_{p,1024}$98
4.6	Comparison of s_c and ϕ_{main}102
4.7	The mean and standard deviation of E_{total} , E_p , s_c and ϕ_{main}105
4.8	Tabular summary of E_{total} and $\sqrt{V_t^2}$112
4.9	Directional spectra summary.....122
4.10	Total energy densities and root mean square errors of directional spectra for alternative spreading function representations.....123
4.11	Total energy densities and root mean square errors of directional spectra for alternative central angle representations.....125
4.12	Empirical directional water surface elevation spectrum summary for ten high energy data sets.....128
4.13	Empirical directional water surface elevation summary for all significant data sets.....129
4.14	Numerical behavior of directional wave properties — GEOMETRIC APPROACH132
4.15	Numerical behavior of directional wave properties — STO./DET. APPROACH ₁133
4.16	Numerical behavior of directional wave properties — STO./DET. APPROACH ₂134
4.17	Mean and standard deviations of parameters γ , σ_L , σ_R , B_R135
4.18	Correlation among parameters E_{total} , E_p , A_{R0} , A_{R1}136

LIST OF TABLES
(Continued)

4.19	Empirical spreading parameter coefficient equations.....	137
4.20	Maximum likelihood resolution of directional wave simulation.....	142
B.1	Summary of statistics evaluated in the time domain.....	155
B.2	Summary of statistics evaluated in the frequency domain.....	157

THE ANALYSIS OF DIRECTIONAL WAVE SPECTRA FROM CURRENT AND PRESSURE MEASUREMENTS

1. INTRODUCTION

1.1 Background

Spectral analysis has become a useful procedure for studying the stochastic properties of ocean waves. The induced wave spectrum implies the pattern of wave energy distribution with respect to several important variables. Common variables include: wave frequency, wave number, and direction of propagation. The wave number is often defined as the product of 2π with the reciprocal of wave length. Much of the knowledge concerning the generation, growth and decay of waves is based on the analysis of the one-dimensional spectrum, which is a function of wave number or frequency. The wave frequency spectrum quantifies the wave energy per unit water surface area per unit water weight per unit frequency as a function of wave frequency. However, to fully describe the behavior of ocean waves, one also needs to know how wave energy is distributed with respect to direction. The property of directional spreading of wave energy acknowledges that not all waves travel in the same direction. This leads to the concept of the directional spectrum, which is a topic of considerable interest in contemporary coastal engineering research. The directional spectrum of ocean waves is essentially a joint distribution of wave energy density per unit water surface area with respect to direction and either wave number or frequency.

A fundamental assumption in spectral analysis is that the irregular sea surface may be regarded as a linear superposition of many sinusoidal, small amplitude wavelets with respect to direction and wave number or frequency. From linear wave theory, the wave energy per unit water surface area per unit water weight of a sinusoidal, small amplitude wave is known to be identical to the mean square value of water surface elevation or half of the squared amplitude of that wave. Thus, the wave energy per unit water surface area per unit water weight for a parti-

cular directional interval and wave number or frequency range can be computed in accordance with linear wave theory; the resulting quantity divided by that direction interval and wave number or frequency range is defined as the directional spectrum of water surface waves. However, other spectral densities may be defined in terms of important wave properties such as velocity, pressure and acceleration, evaluated at some specified depth of interest. This is accomplished at that specified depth by transferring the water surface elevation of each sinusoidal, small amplitude wavelet to the wave properties of interest, utilizing linear wave theory.

An example graphical presentation of the directional spectrum of water surface waves as a function of wave frequency and direction of propagation appears in Fig. 1.1. The volume under the spectral surface for a specific interval of direction and frequency indicates the corresponding mean square value, or variance, of water surface elevation.

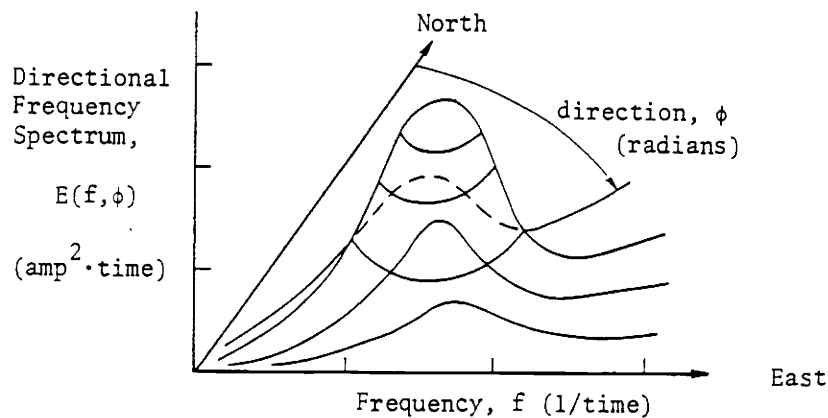


FIG. 1.1 Directional frequency spectrum of water surface waves

A cross section of the directional frequency spectrum in Fig. 1.1 for a given frequency shows the distribution of wave energy density with respect to direction. Such a profile is called a directional spectrum for that frequency; an example appears in Fig. 1.2. The integral of the directional spectrum over all directions presented as a function of frequency is simply the one-dimensional frequency spectrum, as shown in Fig. 1.3.

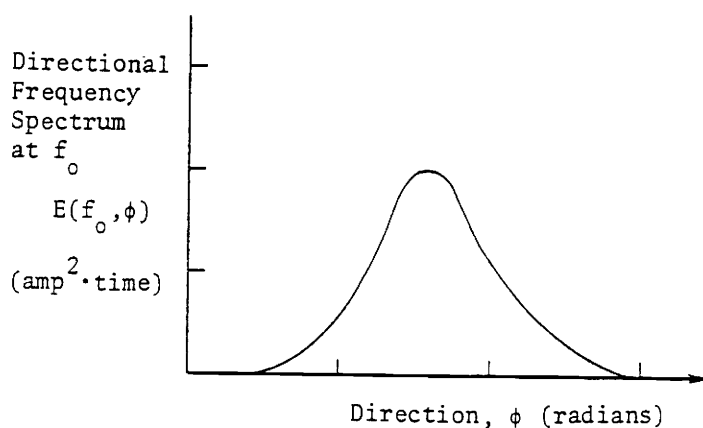


FIG. 1.2 Cross profile of directional frequency spectrum for a given frequency f_0

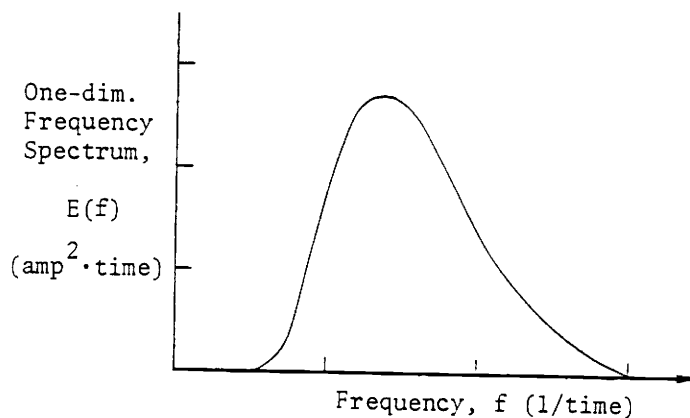


FIG. 1.3 One-dimensional frequency spectrum

The integral of the one-dimensional frequency spectrum over all frequencies gives the total mean square value of water surface elevation; the resulting quantity also indicates the total wave energy of ocean waves per unit water surface area per unit water weight. Therefore, the directional frequency spectrum which is presented in Fig. 1.1 can be interpreted as distribution of total mean square value of water surface elevation with respect to propagation direction and frequency.

The directional spectrum expressed as a function of wave number and direction is essentially a function of the vector wave number. That is, the directional spectrum allocated in a wave number plane is equivalent to the same surface allocated in a polar co-ordinates with direction and scalar wave number as radius. The wave number is a wave property which is related to wave frequency through a theoretically determined dispersion equation. Wave frequency is thought to be a more fundamental wave property than wave number. In particular, most records of wave properties are measured in time at a point and direct transformation of this record yields frequency dependence. Wave number dependence can only be obtained directly from spatial records, i.e., photographs, which do not have the required resolution for water surface elevation measurements. Consequently, the frequency spectrum is preferred by most researchers and is utilized exclusively in this study. However, the wave number spectrum can be obtained indirectly from the frequency spectrum via a transformation with the linear wave theory dispersion equation.

Another issue arising in spectral analysis is that both one-sided and two-sided spectra are used in various studies. The two-sided spectrum, which allows a symmetrical distribution about zero frequency, is preferred by some due to mathematical considerations of the Fast Fourier Transform technique. The one-sided spectrum concentrates the distribution of wave property variance along positive frequency axis, and hence provides an intuitive, more satisfying presentation of a physically measurable wave property. Therefore the one-sided spectrum concept is preferred for use in this study.

Two methods are presently utilized to resolve directional spectra based upon wave property measurements from a single point: the stochastic and deterministic methods. Both methods are based on Fourier transformation procedures and linear wave theory. The stochastic approach has been utilized in various applications of science and engineering since 1950. The algorithm used in the stochastic approach is based on evaluation of frequency dependent Fourier coefficients through cross spectral analysis of simultaneous wave property records. It is shown in

Chapter 2 that the directional spectrum can be estimated by its frequency dependent Fourier coefficients. The fact that the resulting Fourier coefficients can only provide a finite Fourier Series limits the results to an approximate representation of the directional spectrum. One attempt to improve the directional spectrum estimate utilizes the assumption that the spectral distribution is symmetric with respect to direction at all frequencies. The intuitive, symmetric distribution is represented analytically by a squared cosine function with a dependent power relationship which yields the definition for a spreading parameter. The symmetry center of individual angular distributions is located at a mean direction unique to each frequency. The overall distribution of these central angles with respect to frequency is referred as directional spreading of the central angle. Hence, the directional spectrum is characterized by those spreading parameters and central angles which are pre-calculated from the frequency dependent Fourier coefficients.

It should be noted, however, that in the real ocean, waves can be a superposition of many wave systems coming from various sources, each with its own directional spectrum. Although the individual spectra may be symmetric for each frequency with respect to direction, the superposed spectrum may not be symmetric for each frequency with respect to direction. Therefore the directional distribution of wave energy density for a given frequency may not be appropriately represented by a single square-cosine-power function. Nevertheless, symmetric spectral shapes with respect to frequency can be reasonably assumed based on many real observations of the directional properties of ocean waves. Because of its simplicity and utility, the square-cosine-power function is utilized in estimating the directional properties in this study. The stochastic approach ignores phase information and therefore cannot be used to reproduce the irregular sea state which generated the measured random property records.

The deterministic approach was developed in 1978 as a phase resolving alternative to the stochastic approach. Its algorithm simply generates a group of infinitesimal amplitude wavelets directly from Fourier

coefficients of simultaneous wave property measurements. The relative frequency, direction and phase are determined for each mutually independent wavelet. The frequency dependent Fourier coefficients of the directional spectrum are obtained approximately by summing wavelet properties over small but finite frequency and direction intervals. The procedure used to obtain the directional properties in the deterministic approach then follows the method described in the stochastic approach, based on the square-cosine-power function. The deterministic approach was originally developed to provide a prediction of the sea surface as well as the subsurface kinematic field. In addition, it provides an estimate of the directional spectrum.

1.2 Scope of Work

The detailed research included in this study can be briefly described as follows:

- (1) The stochastic and deterministic approaches are rederived, illustrating basic assumptions and fundamental principles.
- (2) It is demonstrated by means of the Correlation Theorem that the stochastic and deterministic approaches are, under certain conditions, actually identical.
- (3) A new method, called the geometric approach, is derived as a phase independent resolution alternative to the stochastic/deterministic approach.
- (4) Computer algorithms for the stochastic/deterministic approach and the geometric approach are generated in order to input the simultaneous wave property measurements and output the one-dimensional frequency spectra and directional frequency spectra.
- (5) Semi-empirical equations are proposed to represent one-dimensional frequency spectrum, spreading parameter and central angle, respectively, by utilizing a least square error minimization analysis.

(6) Results from the stochastic/deterministic approach and the geometric approach are compared.

(7) Correlation studies of the spreading parameter with other spectral parameters shows power function dependence between the spreading parameter and total wave energy density.

(8) A simulated sea surface and its subsurface kinematics are generated for testing the validity of various approaches of directional spectra.

A theoretical analysis of pre-existing methods has demonstrated that evaluation of the one-dimensional frequency spectrum is essential for estimating the directional frequency spectrum. Utilizing an inappropriate one-dimensional frequency spectrum can cause a considerable change in the resulting directional wave energy distribution properties. A Correlation theorem, which simply transforms correlation in the time domain to products in the frequency domain, is then used to analyze the one-dimensional frequency spectrum and improve the directional frequency spectrum estimate. This study shows that the stochastic and deterministic approaches can yield identical one-dimensional frequency spectra and directional frequency spectra. Thus, the two methods are theoretically equivalent. The stochastic approach is preferred by some due to its mathematical elegance while the deterministic approach is preferred in terms of its physical interpretation. A combined name, stochastic/deterministic approach, has been assigned to the method to identify that some improvements have been made in the frequency spectrum estimates. The stochastic/deterministic approach also provides a means for quantifying the time series of various other wave properties, not actually measured. A disadvantage of this method is that orthogonal components of the same frequency are by definition 90° out of phase. This phase constraint is viewed as an arbitrary limitation by some investigators. Errors in the directional spectrum estimates caused by this constraint can not be corrected. It is concluded that a new unconstrained, phase resolving procedure would be desirable.

As part of this study effort, a geometric approach has been developed to satisfy this requirement. The algorithm of the geometric approach also utilizes the wavelet concept from the deterministic approach. However, a number of infinitesimal amplitude wavelets are generated with independent frequencies, directions and phases. Since these infinitesimal amplitude wavelets are solved from Fourier coefficients of simultaneous wave property measurements, they can be used to reproduce precisely the measured wave properties and to predict various other time series of wave properties not actually measured. The directional frequency spectrum is obtained utilizing a square-cosine-power spreading function.

One consequence of the wavelet concept is that the frequency dependent Fourier coefficients can be obtained by summing wavelet properties over small but finite frequency and direction intervals. Another consequence is that the induced directional frequency spectrum can be simply expressed by the product of the one-dimensional frequency spectrum and the normalized square-cosine-power function. Thus, the one-dimensional frequency spectrum, spreading parameter and directional spreading of central angle, all as functions of frequency, are combined to provide a quantitative description of the directional frequency spectrum.

The utility of a directional frequency spectrum representation can be enhanced immeasurably if the quantitative spectrum results can be summarized in equation form rather than on three dimensional graphs or in tabular matrix form. Equations allow one to quickly evaluate the spectral properties over any frequency and direction range of interest and to readily predict the behavior of related wave properties. Also, spectrum behavior at different times and locations can be quickly compared. To that end, the numerical representation of the directional spectrum has been described semi-empirically by defining some appropriate general models for the one-dimensional frequency spectrum, spreading parameter and central angle. A five parameter JONSWAP spectrum has been chosen as a general representation of the one-dimensional spec-

trum. The spreading parameter has been represented on each side of the spectral peak by unique, two parameter power functions of frequency. The central angle has been defined by a third-order polynomial function of frequency. The parameters of each semi-empirical equation are evaluated using a least square error analysis of a comparison between the proposed equation and actual, numerical results.

Bi-axial current meters with one pressure transducer were used in this study to measure simultaneous wave properties which include pressure and orthogonal components of horizontal water particle velocities. Comparisons between the proposed and smoothed directional frequency spectra are made, based on the analysis of real ocean data. The root mean square errors have been estimated for this purpose, and all errors are less than 2% of the smoothed directional spectral density. The resulting small errors indicate the validity of the proposed models. However, significant root mean square errors can be found between the measured one-dimensional frequency spectra and proposed JONSWAP spectra. It is noted that the JONSWAP spectrum model is suitable for describing a one-dimensional frequency spectrum with one spectral peak. However, for those measured one-dimensional frequency spectra which contain two or more spectral peaks, the JONSWAP spectrum is less applicable. Nevertheless, the JONSWAP spectrum is simple and useful, even if the accuracy is reduced for those frequency spectra with multiple peaks. The mean JONSWAP parameters obtained in this study indicate that spectra from offshore Coos Bay, Oregon, have sharper peaks than those measured in the JONSWAP project at North Sea.

The results obtained from the geometric and stochastic/deterministic approaches are compared based upon both ocean measured data and computer simulated data. The comparison shows that more stable results are obtained from the geometric approach than those obtained from the stochastic/deterministic approach. This study also shows that statistics of ocean waves estimated in the frequency domain would be more reliable than those estimated in the time domain.

2. THEORY

2.1 Introduction

Three methods have been employed in the present study for analyzing directional spectra based upon wave property measurements from a single point. These three methods are: (1) Stochastic Approach, (2) Deterministic Approach, and (3) Geometric Approach. The methods of the stochastic approach and deterministic approach were previously developed by other investigators. The geometric approach has been developed as a new method as part of this research effort. The material presented in this chapter includes the theoretical definitions of directional spectra as well as one-dimensional frequency spectra, and a presentation of the theoretical analysis of the three methods. It is shown that the stochastic approach and deterministic approach yield the same solution to the directional spectra. Hence, the numerical analysis of directional spectra in this study is actually limited to the geometric approach and combined stochastic/deterministic approach. The advantages and disadvantages of using these methods are discussed and summarized at the end of this chapter.

The mathematical analysis of the stochastic approach presented here is similar to that developed from buoy measurements, which was first suggested by Barber(1946) and was then used by Longuet-Higgins(1946,1955,1962) and by Cartwright and Smith(1964). The mathematical analysis of the deterministic approach presented here is similar to that described by Sand(1978). Finally, the derivation of the geometric approach is an extension of the deterministic approach with less restrictive assumptions regarding phase.

2.2 Spectrum Definitions

A directional wave spectrum is essentially a representation of the wave number spectrum of water surface waves that follow the linear wave theory dispersion relationship between wave number and wave frequency.

According to the superposition of linear waves, an irregular water surface can be approximated by taking the stochastic integral of linear waves over the wave number plane, s , which is identical to the still water surface plane. (Thomson, 1972).

$$\begin{aligned} \eta(\vec{s}_1, t) &= \text{Re} \left[\iint_s da(\vec{k}) e^{i(\vec{k} \cdot \vec{s}_1 - \sigma t)} \right] \\ &= \iint_s \frac{1}{2} [da(\vec{k}) e^{i(\vec{k} \cdot \vec{s}_1 - \sigma t)} + da^*(\vec{k}) e^{-i(\vec{k} \cdot \vec{s}_1 - \sigma t)}] \end{aligned} \quad (2.1)$$

where η is water surface elevation, t is time, $\vec{s}_1 = (x_1, y_1)$ is the horizontal location of interest in rectangular co-ordinates (see Fig. 2.1), σ is radian frequency, $\vec{k} = (k \cdot \cos \phi, k \cdot \sin \phi)$ is a vector wave number with magnitude $k = |\vec{k}|$ and direction ϕ , $da(\vec{k})$ indicates an infinitesimal wave amplitude (complex number) which is the contribution of waves in a wave number interval $d\vec{k}$, an asterisk appearing in superscript indicates the complex conjugate, the operator $\text{Re}[]$ indicates the real part of a complex number. Note that $da(\vec{k})$ can be denoted as $da(\sigma, \phi)$ since \vec{k} can be expressed by a direction ϕ and a frequency σ . That is, to a first approximation, the wave frequency satisfies the well-known linear wave theory dispersion equation (Ippen, 1966).

$$\sigma^2 = gk \cdot \tanh(kh), \quad k = |\vec{k}| \quad (2.2)$$

where g is gravitational constant and h is water depth (see Fig. 2.1). A small contribution of the water surface waves representing a specific vector wave number is

$$d\eta(\vec{s}_1, t) = \frac{1}{2} [da(\vec{k}) e^{i(\vec{k} \cdot \vec{s}_1 - \sigma t)} + da^*(\vec{k}) e^{-i(\vec{k} \cdot \vec{s}_1 - \sigma t)}] \quad (2.3)$$

Thus, the mean square value of $d\eta$ can be evaluated, which has a form

$$\overline{[d\eta(\vec{s}_1, t)]^2} = \frac{1}{4} \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \{ [da(\vec{k})]^2 e^{i2(\vec{k} \cdot \vec{s}_1 - \sigma t)} + 2da(\vec{k}) da^*(\vec{k}) \}$$

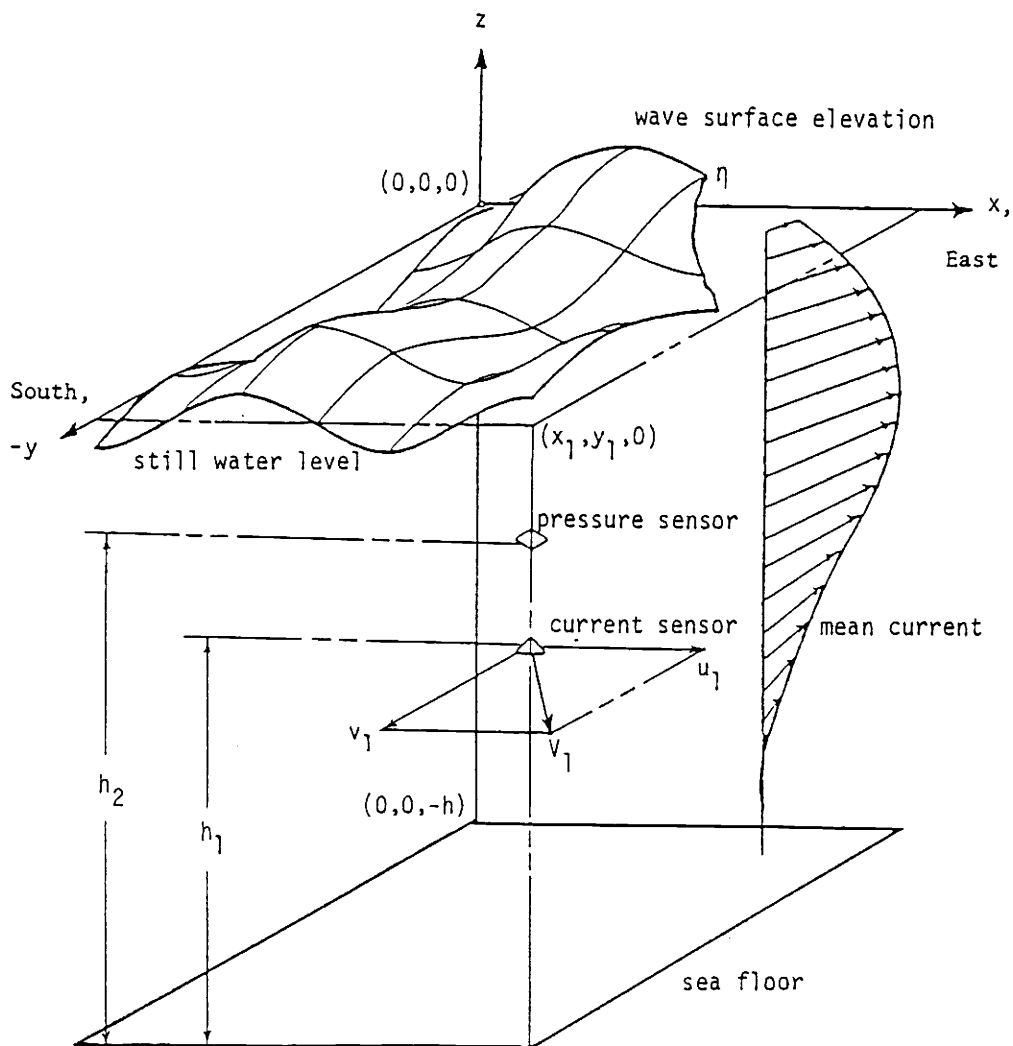


FIG. 2.1 Data collecting system at location $\vec{s}_1 = (x_1, y_1)$

$$\begin{aligned}
& + [da^*(\vec{k})]^2 e^{-i2(\vec{k} \cdot \vec{s}_1 - \sigma t)} \} dt = \frac{1}{2} da(\vec{k}) da^*(\vec{k}) \\
& = \frac{1}{2} |da(\vec{k})|^2 = \frac{1}{2} |da(\sigma, \phi)|^2 = E(\sigma, \phi) d\sigma d\phi = dE(\sigma, \phi)
\end{aligned} \tag{2.4}$$

where T is time duration of interest, an overhead bar indicates the operation of arithmetic mean; $E(\sigma, \phi)$ is the directional frequency spectrum which is defined as

$$E(\sigma, \phi) = \overline{[dn(\vec{s}_1, t)]^2} / d\sigma d\phi = \frac{1}{2} |da(\sigma, \phi)|^2 / d\sigma d\phi \tag{2.5}$$

According to linear wave theory, the wave energy per unit water surface area per unit water weight is equal to half the squared value of wave amplitude (Ippen, 1966). Therefore, Eq.(2.4) specifies a quantity proportional to wave energy associated with a particular frequency range, $d\sigma$, and directional interval, $d\phi$. However, Eq.(2.4) may be regarded as a contribution from an infinitesimal amplitude wave with amplitude $da(\sigma, \phi)$ at the mid $d\sigma$ and $d\phi$. Thus, $E(\sigma, \phi)$ is interpreted as the distribution of wave energy per unit water surface area per unit water weight per unit frequency per unit direction. The corresponding one-dimensional frequency spectrum $E(\sigma)$ is defined by integrating $E(\sigma, \phi)$ over all ϕ .

$$E(\sigma) = \int_{-\pi}^{\pi} E(\sigma, \phi) d\phi \tag{2.6}$$

The total wave energy per unit water surface area per unit water weight is defined by integrating $E(\sigma)$ over all σ , or integrating $E(\sigma, \phi)$ over all σ and ϕ .

$$E_{\text{total}} = \int_0^{\infty} E(\sigma) d\sigma = \int_{-\pi}^{\pi} \int_0^{\infty} E(\sigma, \phi) d\sigma d\phi \tag{2.7}$$

Since the spectral density defined in Eq.(2.5) or Eq.(2.6) has dimensions of rate of change of wave energy density, the name 'power spectral density' is often used. However, an alternate name 'energy spectral density' is more commonly used in ocean engineering.

The spectral density may be defined in terms of wave properties other than water surface elevation. This is accomplished at a specified depth by transferring the frequency components of water surface elevation to the frequency components of wave properties of interest. Examples utilizing linear wave theory to transfer spectral density of water surface elevation to the subsurface spectral densities of wave-induced dynamic pressure and horizontal components of water particle velocity will be shown in Section 2.3.1.

2.3 Stochastic Approach

It is useful to think of an irregular sea as being made of the sum or superposition of many independent, small amplitude wavelets. The importance of this linear superposition is that spectral concepts can be established through Fourier analysis of various wave properties. Utilizing the linear superposition technique, the stochastic approach has been developed in order to obtain the directional spectra. The phase information is ignored in the method. A summary of steps used to derive the stochastic approach in this chapter is as follows.

(1) Based on linear wave theory, the water surface elevation is transferred to wave-induced dynamic pressure and horizontal components of water particle velocity by introducing transfer functions.

(2) The so called co-spectra are determined from the Fourier transforms of correlation functions among various wave properties and are utilized to evaluate the frequency dependent Fourier coefficients for an energy spectrum estimate.

(3) A directionally symmetric angular spreading function is introduced, which covers a broad range of spectral shapes with respect to direction at all frequencies. This angular spreading function is composed of a squared cosine function with a spreading parameter as its power and a central angle as its mean direction.

(4) The final expression of directional spectrum is as product of one-dimensional frequency spectrum with a normalized angular spreading function. Two methods are used in resolving the spreading parameter and central angle, as functions of frequency, with respect to the first-order and second-order frequency dependent Fourier coefficients. Hence, two separate directional spectra of a wave property can be obtained from the stochastic approach.

2.3.1 Linear Wave Superposition

A sinusoidal wave profile which is observed at a horizontal location \vec{s}_1 may be expressed as

$$\eta_1(\vec{s}_1, t) = a(\vec{k}) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t + \theta) \quad (2.8-1)$$

where wave amplitude $a(\vec{k})$ is defined as a real number here, and θ is phase. The x, y, z co-ordinate system is defined as shown in Fig. 2.1. According to linear wave theory, the dynamic pressure due to this water surface wave at the same horizontal location but at a height h_2 above the bottom is (Ippen, 1966)

$$p_1(\vec{s}_1, t) = a(\vec{k}) \gamma_0 \frac{\cosh(kh_2)}{\cosh(kh)} \cos(\vec{k} \cdot \vec{s}_1 - \sigma t + \theta) \quad (2.8-2)$$

where γ_0 is specific weight of sea water. The horizontal water particle velocity component at the same horizontal location but at a height h_1 above the bottom is (Ippen, 1966)

$$V_1(\vec{s}_1, t) = a(\vec{k}) \sigma \frac{\cosh(kh_1)}{\sinh(kh)} \cos(\vec{k} \cdot \vec{s}_1 - \sigma t + \theta) \quad (2.8-3)$$

Since the water surface elevation, the wave-induced dynamic pressure and horizontal velocity component are all in phase with one another, the phase θ is dropped from Eqs. (2.8-1, 2, 3). Note that the phase information is then ignored in the stochastic approach. Therefore, we have

$$\eta_1(\vec{s}_1, t) = a(\vec{k}) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t) \quad (2.9-1)$$

$$p_1(\vec{s}_1, t) = a(\vec{k}) K_p(\sigma) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t) \quad (2.9-2)$$

$$V_1(\vec{s}_1, t) = a(\vec{k}) K(\sigma) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t) \quad (2.9-3)$$

where

$$K_p(\sigma) = \gamma_0 [\cosh(kh_2) / \cosh(kh)] \quad (2.10)$$

$$K(\sigma) = \sigma [\cosh(kh_1) / \sinh(kh)] \quad (2.11)$$

are known as transfer functions. Now, the horizontal velocity V_1 is decomposed into x and y components, denoted as u_1 and v_1 , respectively, according to a direction of propagation, ϕ_1 . The direction considered in mathematical derivations will be defined as follows: +x (East) is defined as the zero direction; positive rotation is in a counterclockwise direction. Directions utilized in example solutions are redefined as follows: +y (North) is defined as the zero direction; positive rotation is in a clockwise direction. Then,

$$u_1(\vec{s}_1, t) = V_1(\vec{s}_1, t) \cos\phi_1 = a(\vec{k}) K(\sigma) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t) \cos\phi_1 \quad (2.12-1)$$

and

$$v_1(\vec{s}_1, t) = V_1(\vec{s}_1, t) \sin\phi_1 = a(\vec{k}) K(\sigma) \cos(\vec{k} \cdot \vec{s}_1 - \sigma t) \sin\phi_1 \quad (2.12-2)$$

Since all these wave properties are linearly proportional to the wave amplitude, a linear superposition of wavelets with various frequencies and directions at the water surface implies a similar superposition of these wave properties at a subsurface location. By assigning the horizontal location of interest to the origin of our co-ordinates, i.e., $\vec{s}_1 = 0$, superposing these wave properties can be expressed as integrations over all frequencies and directions. That is

$$p(t) = \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a(\sigma, \phi)}{d\sigma d\phi} \right] K_p(\sigma) \cos(\sigma t) d\sigma d\phi \quad (2.13-1)$$

and

$$u(t) = \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a(\sigma, \phi)}{d\sigma d\phi} \right] K(\sigma) \cos(\sigma t) \cos\phi d\sigma d\phi \quad (2.13-2)$$

$$v(t) = \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a(\sigma, \phi)}{d\sigma d\phi} \right] K(\sigma) \cos(\sigma t) \sin\phi d\sigma d\phi \quad (2.13-3)$$

where $a(\sigma, \phi) = a(\vec{k})$ represents a wavelet amplitude corresponding to the contribution in an interval $d\sigma d\phi$. That is, in each interval $d\sigma d\phi$ we assign a wavelet amplitude which is specified at the midpoint of that interval. Therefore, $a(\sigma, \phi)$ can be regarded as a discrete function. However, the bracketed terms in Eqs. (2.13-1,2,3) can be regarded as a continuous function.

Examples of spectral densities defined in terms of other wave properties and induced by a single sinusoidal, uni-direction wave are presented here. As an extension of spectral concepts from Eq. (2.4), the one-dimensional frequency spectrum of a particular wave property may be defined as half the squared amplitude of a wave property fluctuation in a frequency interval. Hence, the one-dimensional frequency spectrum of wave-induced dynamic pressure, defined in Eq. (2.9-2), is

$$E_{pp}(\sigma) = \frac{1}{2} [a(\sigma) K_p(\sigma)]^2 / d\sigma = K_p^2(\sigma) E(\sigma) \quad (2.14-1)$$

Note that $E_{pp}(\sigma)$ is simply the product of water surface frequency spectrum with the square of the transfer function. Similarly, the frequency spectra of x and y components of water particle velocities, defined in Eqs. (2.12-1,2), are

$$E_{uu}(\sigma) = \frac{1}{2} [a(\sigma) K(\sigma) \cos\phi_1]^2 / d\sigma = K^2(\sigma) \cos^2\phi_1 E(\sigma) \quad (2.14-2)$$

$$E_{vv}(\sigma) = \frac{1}{2} [a(\sigma) K(\sigma) \sin\phi_1]^2 / d\sigma = K^2(\sigma) \sin^2\phi_1 E(\sigma) \quad (2.14-3)$$

or the horizontal velocity frequency spectrum, denoted as $E_{VV}(\sigma)$, can be obtained by combining $E_{uu}(\sigma)$ and $E_{vv}(\sigma)$ as

$$E_{VV}(\sigma) = \frac{1}{2} [a(\sigma)K(\sigma)]^2 / d\sigma = E_{uu}(\sigma) + E_{vv}(\sigma) = K^2(\sigma)E(\sigma) \quad (2.14-4)$$

Note that the one-dimensional frequency spectrum of water surface wave can be obtained from $E_{pp}(\sigma)$ or $E_{VV}(\sigma)$. That is

$$E(\sigma) = E_{pp}(\sigma) / K_p^2(\sigma) = E_{VV}(\sigma) / K^2(\sigma) \quad (2.15)$$

Therefore, a relationship between $E_{pp}(\sigma)$ and $E_{VV}(\sigma)$ is

$$E_{pp}(\sigma) = E_{VV}(\sigma) K_p^2(\sigma) / K^2(\sigma) = [E_{uu}(\sigma) + E_{vv}(\sigma)] K_p^2(\sigma) / K^2(\sigma) \quad (2.16)$$

These expressions imply the usefulness of utilizing linear wave theory in spectral analysis since transformation among spectral densities of various wave properties makes random wave analysis both simple and direct.

2.3.2 Co-spectrum and Fourier Analysis

To obtain the one-dimensional spectrum, it is necessary to analyze only one wave property of interest in accordance with linear wave theory. However, to obtain the directional spectrum, it is necessary to analyze simultaneous wave property measurements relative to one another. The stochastic approach of directional spectrum calls for a cross spectral analysis (Cartwright, 1963) or a comparison of simultaneous wave properties. The cross spectrum is a useful product of spectral analysis; it quantifies the frequency response of correlations between two simultaneous wave property measurements.

The definition of cross spectrum, denoted as $\zeta_{ij}(\sigma)$, is written as (Jenkins and Watts, 1968)

$$\zeta_{ij}(\sigma) = C_{ij}(\sigma) - iQ_{ij}(\sigma) = \lim_{T \rightarrow \infty} \frac{1}{2\pi} \int_{-T/2}^{T/2} \Pi_{ij}(\tau) e^{-i\sigma\tau} d\tau \quad (2.17)$$

where subscript ij indicates the analysis between wave properties i and j , $C_{ij}(\sigma)$ is the real part of $\zeta_{ij}(\sigma)$ and is called the co-spectrum, $Q_{ij}(\sigma)$ is

the imaginary part of $\zeta_{ij}(\sigma)$ and is called the quadrature-spectrum; $\Pi_{ij}(\tau)$ is the covariance function defined as (Jenkins and Watts, 1968)

$$\Pi_{ij}(\tau) = \overline{\omega_i(t)\omega_j(t+\tau)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \omega_i(t)\omega_j(t+\tau) dt \quad (2.18)$$

where τ is a delay of time and is called lag, $\omega_i(t)$ and $\omega_j(t)$ are any two wave properties, and T is the total duration of interest. Note that cross spectrum is simply the Fourier transform of the covariance function. Two points should be mentioned concerning the cross spectrum. First, if $i=j$, the covariance function becomes the auto-covariance function and the induced cross spectrum is a real number and reduces to a one-dimensional frequency spectrum. This is because all auto-covariance functions are symmetric about a zero lag if a stationary process is presented. The imaginary part of the Fourier transform of the auto-covariance function (indicating an odd function transformation) will vanish since the symmetry of the auto-covariance function indicates an even function (Brighan, 1974). Second, the covariance functions of various wave properties shown here are actually correlations since all of these wave-induced properties have zero means. Therefore terms containing the means of relative wave properties vanish in Eq.(2.18) because of these zero means. This has been regarded as an important property for applying the Correlation Theorem in spectral analysis as discussed in Section 2.4.3.

An example of the covariance function and cross spectrum of velocity component $u(t)$ is given as follows (Nagata, 1964). Combining Eqs.(2.18) and (2.13-2) yields

$$\begin{aligned} \Pi_{uu}(\tau) &= \overline{u(t)u(t+\tau)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} u(t)u(t+\tau) dt \\ &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \left\{ \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a(\sigma', \phi')}{d\sigma' d\phi'} \right] K(\sigma') \cos(\sigma't) \cos\phi' d\sigma' d\phi' \right\} \end{aligned}$$

$$\int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a(\sigma, \phi)}{d\sigma d\phi} \right] K(\sigma) \cos(\sigma(t+\tau)) \cos\phi d\sigma d\phi dt \quad (2.19-1)$$

The equations are simplified by assuming that interactions among waves coming from various directions can be ignored. Hence, $\phi = \phi'$ and one integral of direction vanishes from Eq.(2.19-1).

$$\begin{aligned} \Pi_{uu}(\tau) &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\pi}^{\pi} \int_0^{\infty} \int_0^{\infty} \left[\frac{a(\sigma', \phi) a(\sigma, \phi)}{d\sigma' d\sigma d\phi} \right] K(\sigma') K(\sigma) \cos^2 \phi \cdot \\ &\quad \left\{ \int_{-T/2}^{T/2} \cos(\sigma' t) \cos(\sigma(t+\tau)) dt \right\} d\sigma' d\sigma d\phi \cdot \\ &= \int_{-\pi}^{\pi} \int_0^{\infty} \int_0^{\infty} \left[\frac{a(\sigma', \phi) a(\sigma, \phi)}{d\sigma' d\sigma d\phi} \right] K(\sigma') K(\sigma) \cos^2 \phi \cdot \\ &\quad \left\{ \lim_{T \rightarrow \infty} \frac{1}{T} \cos(\sigma \tau) \left[\frac{\sin((\sigma' - \sigma)T/2)}{\sigma' - \sigma} + \frac{\sin((\sigma' + \sigma)T/2)}{\sigma' + \sigma} \right] \right\} d\sigma' d\sigma d\phi \end{aligned} \quad (2.19-2)$$

Now, the function $\sin(qT/2)/(qT/2)$, where $q = \sigma' - \sigma$ or $q = \sigma' + \sigma$, behaves like an impulse function as $T \rightarrow \infty$ (Brighan, 1974).

$$\lim_{T \rightarrow \infty} \frac{\sin(qT/2)}{(qT/2)} = \delta(q) \quad (2.20)$$

where $\delta(q)$ indicates a Dirac δ function which is a unit impulse. The Sifting property (Brighan, 1974) of the δ function is

$$\int_{-\infty}^{\infty} F(\sigma) \delta(\sigma' - \sigma) d\sigma = F(\sigma') \quad (2.21)$$

where $F(\sigma)$ is an analytic function. The interpretation of Eq.(2.21) is

that if one lets σ' continuously vary one can sift out each value of the function $F(\sigma)$.

Combining Eq.(2.19-2) and Eqs.(2.20,21) yields

$$\begin{aligned} \Pi_{uu}(\tau) &= \int_{-\pi}^{\pi} \int_0^{\infty} \int_0^{\infty} \left[\frac{a(\sigma', \phi) a(\sigma, \phi)}{d\sigma' d\sigma d\phi} \right] K(\sigma') K(\sigma) \cos^2 \phi \cdot \\ &\quad \frac{\cos(\sigma\tau)}{2} [\delta(\sigma' - \sigma) + \delta(\sigma' + \sigma)] d\sigma' d\sigma d\phi \\ &= \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a^2(\sigma', \phi)}{2d\sigma' d\phi} \right] K^2(\sigma') \cos^2 \phi \cos(\sigma'\tau) d\sigma' d\phi \end{aligned} \quad (2.22)$$

Since $\sigma' > 0$, $\sigma > 0$, $\delta(\sigma' + \sigma)$ gives no contribution to Eq.(2.22)

The corresponding cross spectrum, upon substitution of Eq.(2.22) into Eq.(2.17), becomes

$$\begin{aligned} \zeta_{uu}(\sigma) &= \lim_{T \rightarrow \infty} \frac{1}{2\pi} \int_{-T/2}^{T/2} \left\{ \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a^2(\sigma', \phi)}{2d\sigma' d\phi} \right] K^2(\sigma') \cos^2 \phi \cos(\sigma'\tau) d\sigma' d\phi \right\} e^{-i\sigma\tau} d\tau \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a^2(\sigma', \phi)}{2d\sigma' d\phi} \right] K^2(\sigma') \cos^2 \phi \cdot \\ &\quad \left\{ \lim_{T \rightarrow \infty} \left[\frac{\sin((\sigma' - \sigma)T/2)}{\sigma' - \sigma} + \frac{\sin((\sigma' + \sigma)T/2)}{\sigma' + \sigma} \right] \right\} d\sigma' d\phi \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a^2(\sigma', \phi)}{2d\sigma' d\phi} \right] K^2(\sigma') \cos^2 \phi \left\{ \frac{T}{2} [\delta(\sigma' - \sigma) + \delta(\sigma' + \sigma)] \right\} d\sigma' d\phi \end{aligned} \quad (2.23-1)$$

Note that the covariance function $\Pi_{uu}(\tau)$ is an even function and, thus, the cross spectrum $\zeta_{uu}(\sigma)$ is a real number, i.e., $\zeta_{uu}(\sigma) = C_{uu}(\sigma)$. The

imaginary part has vanished in Eq.(2.23-1). Also note that there is no limit to σ in Eq.(2.23-1), i.e., σ could be negative and this is allowed in the Fourier transformation as well. However, if σ is regarded as a positive variable, based on the one-sided spectral concept, the term containing $\delta(\sigma'+\sigma)$ vanishes and a factor 2 must be inserted in Eq.(2.23-1). Furthermore, the fundamental frequency $d\sigma=2\pi/T$ considered in the Fourier transformation is also substituted into Eq.(2.23-1). Utilizing the Sifting property again in Eq.(2.23-1) yields

$$\begin{aligned} \tau_{uu}(\sigma) &= 2 \int_{-\pi}^{\pi} \int_0^{\infty} \left[\frac{a^2(\sigma', \phi)}{2d\sigma'd\phi} \right] K^2(\sigma') \cos^2 \phi \left[\frac{1}{2d\sigma} \delta(\sigma' - \sigma) \right] d\sigma' d\phi \\ &= \int_{-\pi}^{\pi} \left[\frac{a^2(\sigma, \phi)}{2d\sigma d\phi} \right] K^2(\sigma) \cos^2 \phi d\phi \\ &= \int_{-\pi}^{\pi} E(\sigma, \phi) K^2(\sigma) \cos^2 \phi d\phi \end{aligned} \quad (2.23-2)$$

where $E(\sigma, \phi)$ is the directional spectrum as defined in Eq.(2.5).

Similarly, various other cross spectra among $p(t)$, $u(t)$, and $v(t)$, may be derived. All are real numbers and, therefore, are co-spectra. Co-spectra result because the individual covariance functions are even. A list of these co-spectra are as follows:

$$C_{pp}(\sigma) = K_p^2(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) d\phi \quad (2.24-1)$$

$$C_{pu}(\sigma) = K(\sigma) K_p(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) \cos \phi d\phi \quad (2.24-2)$$

$$C_{pv}(\sigma) = K(\sigma) K_p(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) \sin \phi d\phi \quad (2.24-3)$$

$$C_{uv}(\sigma) = K^2(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) \sin \phi \cos \phi d\phi \quad (2.24-4)$$

$$C_{uu}(\sigma) = K^2(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) \cos^2 \phi d\phi \quad (2.24-5)$$

$$C_{vv}(\sigma) = K^2(\sigma) \int_{-\pi}^{\pi} E(\sigma, \phi) \sin^2 \phi d\phi \quad (2.24-6)$$

The left side of Eqs. (2.24-1,2,3,4,5,6) can be evaluated numerically by a Fast Fourier Transform (FFT) technique. These co-spectra are presented here because they are so closely related to the directional spectrum that they provide an estimate to the directional spectrum properties.

The directional spectrum can be expanded in a Fourier Series with respect to direction at all frequencies. That is

$$E(\sigma, \phi) = \frac{1}{2} A_0(\sigma) + \sum_{n=1}^{\infty} [A_n(\sigma) \cos(n\phi) + B_n(\sigma) \sin(n\phi)] \quad (2.25-1)$$

in which

$$A_n(\sigma) + iB_n(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) e^{in\phi} d\phi, \quad n=0,1,2,\dots \quad (2.25-2)$$

and $A_n(\sigma)$, $B_n(\sigma)$ are called frequency dependent Fourier coefficients. The relationships among the first five frequency dependent Fourier coefficients and the co-spectrum listed in Eqs. (2.24-1,2,3,4,5,6) are derived as follows:

$$A_0(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) d\phi = \frac{E(\sigma)}{\pi} = \frac{C_{pp}(\sigma)}{\pi K_p^2(\sigma)} \quad (2.26-1)$$

$$A_1(\sigma) + iB_1(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) e^{i\phi} d\phi = \frac{C_{pu}(\sigma) + iC_{pv}(\sigma)}{\pi K(\sigma) K_p(\sigma)}$$

$$A_1(\sigma) = \frac{C_{pu}(\sigma)}{\pi K(\sigma) K_p(\sigma)} \quad (2.26-2)$$

$$B_1(\sigma) = \frac{C_{pv}(\sigma)}{\pi K(\sigma) K_p(\sigma)} \quad (2.26-3)$$

$$A_2(\sigma) + iB_2(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) e^{i2\phi} d\phi$$

Then

$$\begin{aligned} A_2(\sigma) &= \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) \cos(2\phi) d\phi \\ &= \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) (\cos^2 \phi - \sin^2 \phi) d\phi = \frac{C_{uu}(\sigma) - C_{vv}(\sigma)}{\pi K^2(\sigma)} \end{aligned} \quad (2.26-4)$$

or

$$A_2(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) (2\cos^2 \phi - 1) d\phi = \frac{2C_{uu}(\sigma)}{\pi K^2(\sigma)} - A_0(\sigma) \quad (2.26-5)$$

or

$$A_2(\sigma) = \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) (1 - 2\sin^2 \phi) d\phi = A_0(\sigma) - \frac{2C_{vv}(\sigma)}{\pi K^2(\sigma)} \quad (2.26-6)$$

and

$$\begin{aligned} B_2(\sigma) &= \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) \sin(2\phi) d\phi \\ &= \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi) (2\sin\phi \cos\phi) d\phi = \frac{2C_{uv}(\sigma)}{\pi K^2(\sigma)} \end{aligned} \quad (2.26-7)$$

Combining Eqs. (2.26-5,6) and (2.26-1) yields

$$C_{pp}(\sigma) = \frac{K_p^2(\sigma)}{K^2(\sigma)} [C_{uu}(\sigma) + C_{vv}(\sigma)] \quad (2.27)$$

Since the auto-covariance function is always even, a Fourier transform of the auto-covariance function yields the frequency spectrum which is essentially the co-spectrum of the measured variable. Therefore, the co-spectra, $C_{pp}(\sigma)$, $C_{uu}(\sigma)$, and $C_{vv}(\sigma)$, are essentially the frequency

spectra, $E_{pp}(\sigma)$, $E_{uu}(\sigma)$, and $E_{vv}(\sigma)$, respectively. Hence, Eq.(2.27) is identical to Eq.(2.16), and the one-dimensional frequency spectrum of water surface waves can be estimated from Eq.(2.15).

Since the first five Fourier coefficients, $A_0(\sigma)$, $A_1(\sigma)$, $B_1(\sigma)$, $A_2(\sigma)$, and $B_2(\sigma)$, can be computed from Eqs.(2.26-1,2,3,4,7), the directional spectrum is then approximated by the first five terms of the Fourier Series in Eq.(2.25-1). That is

$$\begin{aligned} \hat{E}(\sigma, \phi) = & \frac{1}{2}A_0(\sigma) + A_1(\sigma)\cos\phi + B_1(\sigma)\sin\phi \\ & + A_2(\sigma)\cos 2\phi + B_2(\sigma)\sin 2\phi \end{aligned} \quad (2.28)$$

where $\hat{E}(\sigma, \phi)$ indicates an estimator of directional spectrum. It is impossible to obtain more higher-order frequency dependent Fourier coefficients if only $p(t)$, $u(t)$ and $v(t)$ are measured. In order to obtain more higher-order frequency dependent Fourier coefficients, quantities such as components of velocity gradients $\partial u(x, y, z, t)/\partial x$, $\partial u(x, y, z, t)/\partial y$, $\partial v(x, y, z, t)/\partial y$, etc., are necessarily measured. The cross spectra among the wave-induced pressure, two components of horizontal orbital velocities and three components of horizontal orbital velocity gradients enable one to compute the Fourier coefficients up to the fourth-order in Eq.(2.25-1), i.e., nine coefficients (Mitsuyasu et al., 1975).

2.3.3 Directional Spreading Analysis

In order to see how the first five Fourier coefficients present an estimation to the directional spectrum, $A_0(\sigma)$, $A_1(\sigma)$, $B_1(\sigma)$, $A_2(\sigma)$, and $B_2(\sigma)$ specified in Eq.(2.25-2) are substituted in Eq.(2.28). The notation ϕ appearing in these five Fourier coefficients is changed to ϕ' to distinguish the angle ϕ in Eq.(2.28). Then,

$$\begin{aligned} \hat{E}(\sigma, \phi) = & \frac{1}{\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') \left[\frac{1}{2} + \cos\phi' \cos\phi + \sin\phi' \sin\phi \right. \\ & \left. + \cos(2\phi') \cos(2\phi) + \sin(2\phi') \sin(2\phi) \right] d\phi' \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') [1 + 2\cos(\phi' - \phi) + 2\cos(2\phi' - 2\phi)] d\phi \\
&= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') \frac{\sin[\frac{5}{2}(\phi' - \phi)]}{\sin[\frac{1}{2}(\phi' - \phi)]} d\phi \\
&= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') W(\phi' - \phi) d\phi \tag{2.29-1}
\end{aligned}$$

where

$$W(\phi' - \phi) = \sin[\frac{5}{2}(\phi' - \phi)] / \sin[\frac{1}{2}(\phi' - \phi)] \tag{2.29-2}$$

behaves as a weighting function (Barber, 1946). It is apparent that this directional spectrum estimator, Eq.(2.24), is a smoothed spectrum of the actual directional spectrum $E(\sigma, \phi')$ by the weighting function $W(\phi' - \phi)$. A sketch of this weighting function is shown in Fig. 2.2 and a dummy variable $\phi^* = \phi' - \phi$ is utilized.

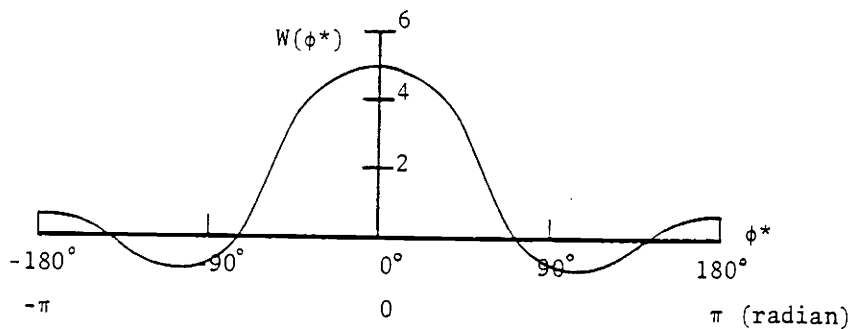


FIG. 2.2 Weighting function $W(\phi^*) = \sin[\frac{5}{2}\phi^*] / \sin[\frac{1}{2}\phi^*]$

Since $W(\phi^*)$ can be negative, it is possible that $\hat{E}(\sigma, \phi)$ in Eq.(2.24) may become negative too, whereas the directional spectrum itself is positive in real physical systems. An alternate approximation to the weighting function to maintain a positive estimate to the energy spectrum is

presented as follows (Longuet-Higgins et al., 1963). Using the identities:

$$1 + \cos \phi^* = 2 \cos^2(\phi^*/2), \quad (1 + \cos \phi^*)^s = 2^s \cos^{2s}(\phi^*/2)$$

Let $s=2$, a modified weighting function is then defined as

$$\underline{W}(\phi^*) = 1 + \frac{4}{3} \cos(\phi^*) + \frac{1}{3} \cos(2\phi^*) = \frac{8}{3} \cos^4(\phi^*/2) \quad (2.30)$$

where $\phi^* = \phi' - \phi$. Thus, the directional spectrum estimator due to $\underline{W}(\phi' - \phi)$ is

$$\begin{aligned} \hat{E}(\sigma, \phi) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') \underline{W}(\phi' - \phi) d\phi' \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') \left[\frac{8}{3} \cos^4\left(\frac{\phi' - \phi}{2}\right) \right] d\phi' \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} E(\sigma, \phi') \left[1 + \frac{4}{3} \cos(\phi' - \phi) + \frac{1}{3} \cos(2\phi' - 2\phi) \right] d\phi' \end{aligned} \quad (2.31-1)$$

Using the addition formula for cosine functions in Eq.(2.31-1) yields

$$\begin{aligned} \hat{E}(\sigma, \phi) &= \frac{1}{2} A_0(\sigma) + \frac{2}{3} [A_1(\sigma) \cos \phi + B_1(\sigma) \sin \phi] \\ &\quad + \frac{1}{6} [A_2(\sigma) \cos 2\phi + B_2(\sigma) \sin 2\phi] \end{aligned} \quad (2.31-2)$$

Since $\underline{W}(\phi^*)$ defined in Eq.(2.30) is always positive, the resulting $\hat{E}(\sigma, \phi)$ in Eq.(2.31-1) is also positive. A sketch of $\underline{W}(\phi^*)$ appears in Fig. 2.3. The weighting function $\underline{W}(\phi^*)$ is not only non-negative but a decreasing function of $|\phi^*|$. This smoothed weighting function has the disadvantage of making the resolution of any distribution narrower than $\cos^4(\phi^*/2)$ impossible. Equation (2.31-2) provides different weights in front of each frequency dependent Fourier coefficient in contrast to those in Eq.(2.28).

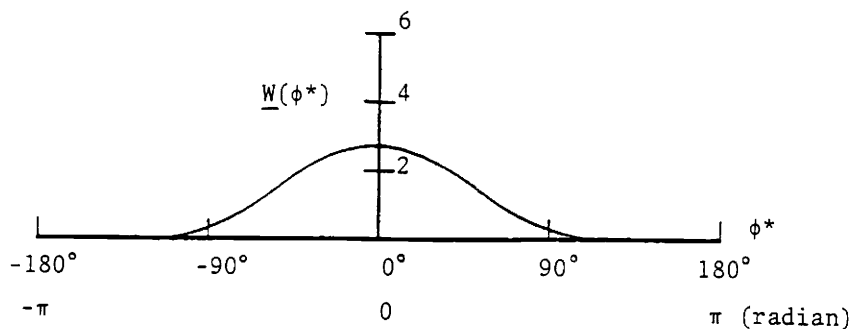


FIG. 2.3 Smoothed weighting function $\underline{W}(\phi^*) = \frac{8}{3} \cos^4 \left[\frac{1}{2} \phi^* \right]$

Since both Eqs.(2.28) and (2.31-2) are based on finite Fourier Series, they are limited to an approximate representation of the directional spectrum. However, spectral analysis using Eqs.(2.28) and (2.31-2) quantifies many useful properties of directional spectra.

The analysis of directional properties of real ocean waves based on Eqs.(2.28) and (2.31-2) has revealed that directional distribution of wave energy density for any given frequency is approximately symmetric about a central direction. Accordingly, it is assumed that a fundamental property of directional distribution for any frequency is one that is symmetric about a central direction. In order to make the assumed symmetric directional distribution have a more universal shape, the so called Angular Distribution function is defined as the ratio (Cartwright, 1963)

$$H(\sigma, \phi) = \frac{E(\sigma, \phi)}{E(\sigma)} \quad (2.32)$$

Therefore, the directional spectrum becomes

$$E(\sigma, \phi) = E(\sigma)H(\sigma, \phi) = \pi A_0(\sigma)H(\sigma, \phi) \quad (2.33)$$

A number of functional forms of $H(\sigma, \phi)$ have been suggested (Sand, 1979) but all have similar shape, i.e., they are symmetric about a central direction. It is usually difficult to choose one in prefer-

ence to another in practical applications. A commonly used function, which is proportional to a power cosine function, is adopted here not only for its simplicity but its similarity to Eq.(2.30). This angular distribution function possesses the following properties (Sand, 1979).

$$(1) \quad H(\sigma, \phi) \geq 0 \quad (2.34-1)$$

$$(2) \quad \int_{-\pi}^{\pi} H(\sigma, \phi) d\phi = \int_{-\pi}^{\pi} E(\sigma, \phi) d\phi / E(\sigma) = 1 \quad (2.34-2)$$

$$(3) \quad H(\sigma, \phi) = G(s) \cos^{2s} \left(\frac{\phi - \phi_0}{2} \right), \quad s = s(\sigma), \quad \phi_0 = \phi_0(\sigma) \quad (2.34-3)$$

where $s(\sigma)$ is called a spreading parameter, which is always positive and a function of frequency, $\phi_0(\sigma)$ is called a central angle, and $G(s)$ is a normalizing factor. It is apparent that $H(\sigma, \phi)$ is always positive and symmetric about a central angle $\phi_0(\sigma)$. Also $H(\sigma, \phi)$ is a function that tends to expand the one-dimensional frequency spectrum to a directional spectrum. Therefore, the procedure to determine the directional spectrum reduces to determining the corresponding one-dimensional frequency spectrum, the spreading parameter and the central angle.

The spreading parameter and central angle dependence on frequency is determined as follows. Substituting Eq.(2.34-3) into Eq.(2.34-2), $G(s)$ is solved as

$$G(s) = \frac{2^{2s-1}}{\pi} \frac{(s!)(s!)}{(2s)!} = \frac{2^{2s-1}}{\pi} \frac{\Gamma^2(s+1)}{\Gamma(2s+1)} \quad (2.35)$$

where $\Gamma(s) = \int_0^{\infty} r^{s-1} e^{-r} dr$, the Gamma function. Thus, $H(\sigma, \phi)$ has an explicit form as

$$H(\sigma, \phi) = \frac{2^{2s-1}}{\pi} \frac{\Gamma^2(s+1)}{\Gamma(2s+1)} \cos^{2s} \left(\frac{\phi - \phi_0}{2} \right) \quad (2.36)$$

Combining Eqs.(2.36) and (2.33) yields

$$\begin{aligned}
E(\sigma, \phi) &= E(\sigma)H(\sigma, \phi) = \pi A_o(\sigma)G(s) \cos^{2s} \left(\frac{\phi - \phi_o}{2} \right) \\
&= E(\sigma) \frac{2^{2s-1}}{\pi} \frac{\Gamma^2(s+1)}{\Gamma(2s+1)} \cos^{2s} \left(\frac{\phi - \phi_o}{2} \right)
\end{aligned} \tag{2.37}$$

Equation (2.37) can be also expanded in a Fourier Series (Sand, 1979) which has the following form

$$\begin{aligned}
E(\sigma, \phi) &= \pi A_o(\sigma)H(\sigma, \phi) \\
&= \frac{A_o(\sigma)}{2} + A_o(\sigma) \sum_{n=1}^{\infty} [C_n \cos(n\phi_o) \cos(n\phi) + C_n \sin(n\phi_o) \sin(n\phi)]
\end{aligned} \tag{2.38-1}$$

in which

$$C_n = \frac{\Gamma^2(s+1)}{\Gamma(s+n+1)\Gamma(s-n+1)} \tag{2.38-2}$$

Since only first five frequency dependence Fourier coefficients can be computed with simultaneous measurements of $p(t)$, $u(t)$ and $v(t)$, the directional spectrum can be approximated by the first five terms in the Fourier Series. That is

$$\begin{aligned}
E(\sigma, \phi) &= \frac{1}{2} A_o + (C_1 A_o \cos \phi_o) \cos \phi + (C_1 A_o \sin \phi_o) \sin \phi \\
&\quad + (C_2 A_o \cos 2\phi_o) \cos 2\phi + (C_2 A_o \sin 2\phi_o) \sin 2\phi
\end{aligned} \tag{2.38-3}$$

Comparing Eq. (2.38-3) with Eq. (2.28) allows one to evaluate two solutions to s as well as ϕ_o from the first-order and second-order coefficients, respectively.

Comparing the first-order coefficients from Eqs. (2.38-3) and (2.28), we have

$$A_1 = C_1 A_o \cos \phi_o, \quad B_1 = C_1 A_o \sin \phi_o \tag{2.39-1}$$

Then

$$\phi_{o1} = \phi_o = \tan^{-1} \left(\frac{B_1}{A_1} \right) \quad (2.39-2)$$

$$C_1 = \sqrt{A_1^2 + B_1^2} / A_o = \frac{s}{s+1} \quad (2.39-3)$$

$$s_1 = s = \frac{C_1}{1-C_1} \quad (2.39-4)$$

To identify the solutions solved from Eqs.(2.39-1,2,3,4), the subscript 1 has been reserved for the resulting parameters. The directional properties obtained from this case will be referred to as the One Angle Mode solution in this study.

Comparing the second-order coefficients from Eqs.(2.38-3) and (2.28), we have

$$A_2 = C_2 A_o \cos 2\phi_o, \quad B_2 = C_2 A_o \sin 2\phi_o \quad (2.40-1)$$

Then

$$\phi_{o2} = \phi_o = \frac{1}{2} \tan^{-1} \left(\frac{B_2}{A_2} \right) \quad (2.40-2)$$

$$C_2 = \sqrt{A_2^2 + B_2^2} / A_o = \frac{s(s-1)}{(s+1)(s+2)} \quad (2.40-3)$$

$$s_2 = s = \frac{1+3C_2 + \sqrt{(1+3C_2)^2 + 8C_2(1-C_2)}}{2(1-C_2)} \quad (2.40-4)$$

To identify the solutions solved from Eqs.(2.40-1,2,3,4), the subscript 2 has been reserved for the resulting parameters. The directional properties solved from this case will be referred to as the Double Angle Mode solution.

The wave property measurements, $p(t)$, $u(t)$, and $v(t)$, are necessary

input for the one angle mode solution. However, $u(t)$, $v(t)$ are sufficient input for the double angle mode solution. This is because $A_0(\sigma)$ can be obtained from the velocity components in accordance with Eqs.(2.26-1) and (2.27). The latter has a problem in that the estimate of the central angle could be indeterminate by 180° , since the angle is estimated by half of the inverse tangent function as indicated in Eq.(2.40-2). This indeterminate angle is usually corrected by either estimating the gross main travel direction of waves, e.g., towards the coastline, or by referring to the central angle obtained from the one angle mode solution.

Substituting Eq.(2.39-4) into Eq.(2.40-3), the relationship between C_1 and C_2 is obtained under the condition $s_1=s_2$ (Cartwright, 1963).

$$C_2 = \frac{C_1(2C_1-1)}{2-C_1} \quad (2.41)$$

If the angular distribution function is valid to describe the real directional distribution of wave energy density at a particular frequency, the resulting C_1 and C_2 of that frequency should satisfy Eq.(2.41). A comparison of Eq.(2.41) to real ocean data obtained in this study is graphed in Fig. 2.4.

It has been observed by many investigators that the skewness of angular distribution of wave energy is negligible, and a symmetric shape of angular distribution function is deemed suitable. Hence, the function $H(\sigma, \phi)$ used in this analysis provides a reasonable approximation to real ocean data. Therefore, Eq.(2.37) has been chosen as a reasonable representation of the directional spectrum. To utilize this directional spectrum, it is necessary to evaluate the one-dimensional spectrum, the spreading parameter, and the central angle, all as functions of frequency.

The variation of angular distribution shape relative to a central angle is dependent on the spreading parameter. A normalized form of Eq.(2.37), used to represent this variation of angular distribution shape relative to a central angle, is (Mitsuyasu, 1975)

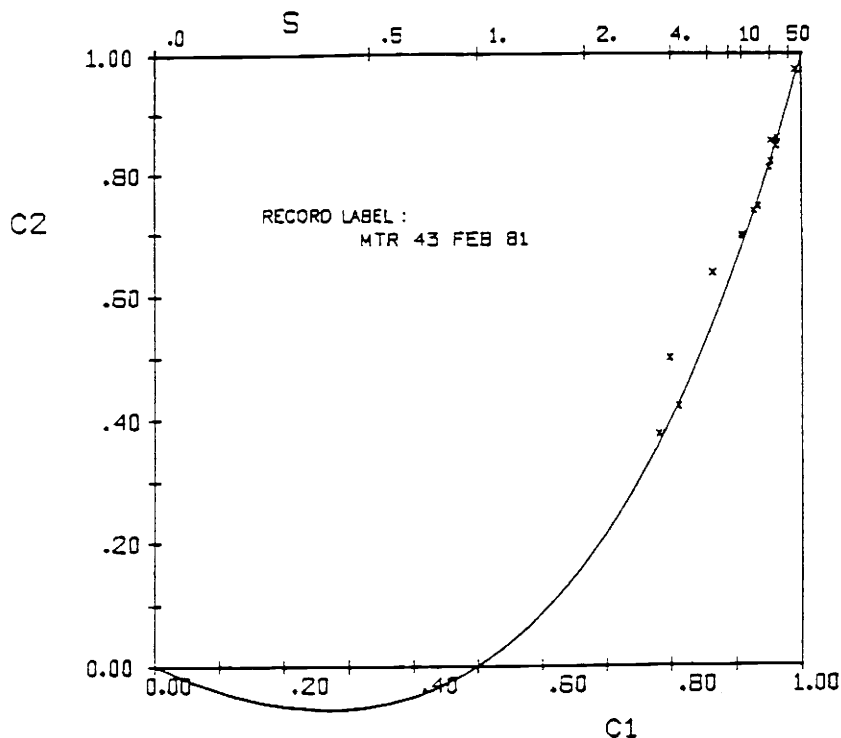


FIG. 2.4 Theoretical curve and sample values of C_1 and C_2

$$E^*(\sigma, \phi') = \frac{E(\sigma, \phi')}{A_0(\sigma)} = \pi G(s) \cos^{2s} \left(\frac{\phi'}{2} \right) \quad (2.42)$$

where $\phi' = \phi - \phi_0$. A graphical presentation of Eq. (2.42) for different values of s is shown in Fig. 2.5. Note that large values of s provide narrow angular spreading of spectral energy while small values of s provide broad angular spreading of spectral energy. In practice s and ϕ_0 are found to vary with frequency.

It has been observed that the variation of the central angle with respect to frequency is mainly dependent on the actual wind direction while the variation of the spreading parameter with respect to frequency is rather independent of wind, but very dependent on frequency. An example of the spreading parameter dependence on frequency, obtained

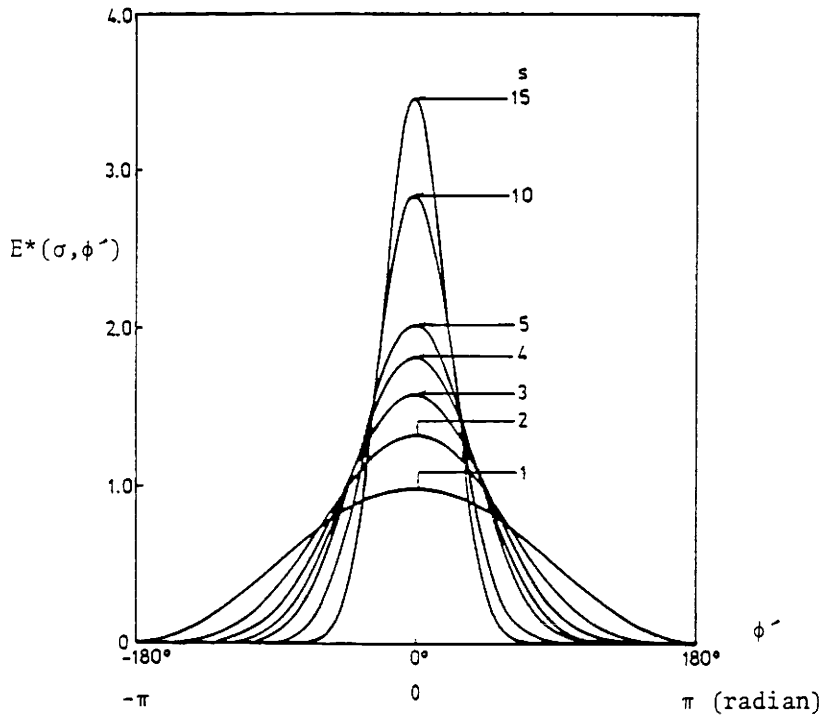


FIG. 2.5 Normalized angular distribution function $E^*(\sigma, \phi')$
(Sand, 1979)

by Longuet-Higgins, Cartwright and Smith(1963) using buoy measurements, is shown in Fig. 2.6. Another example showing the one-dimensional spectrum, as well as variations of s and ϕ_0 appears in Fig. 2.7; this was obtained by Mitsuyasu et al.(1975) using a cloverleaf buoy in the Pacific Ocean in 1971. Also, directional properties obtained by Forristall et al.(1978) using measurements of $\eta(t)$, $u(t)$, and $v(t)$, (Gulf of Mexico, tropical hurricane Delia, 1973) are shown in Fig. 2.8. The procedure used to analyze the directional properties in these examples is the stochastic approach. From these examples, one can deduce that the central angles of low frequency waves vary with long period swell from multiple storm sources, while the high frequency components follow the local wind direction. The great variation in ϕ_0 for hurricane measurements as seen in Fig. 2.8 is due to the relatively rapid change in the storm track. The variation in the spreading parameter, however, shows a

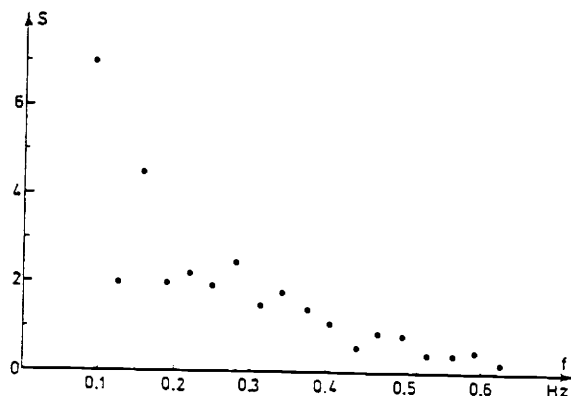


FIG. 2.6 Parameter s versus frequency $f = \sigma / 2\pi$
(Longuet-Higgins et al., 1963)

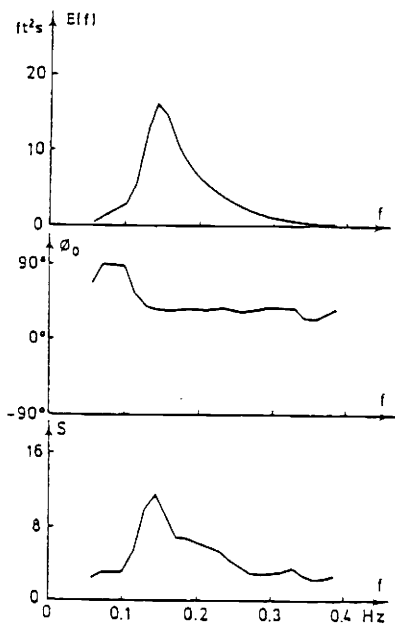


FIG. 2.7 Example frequency spectrum, central angle, spreading parameter behavior
(Mitsuyasu et al., 1975)

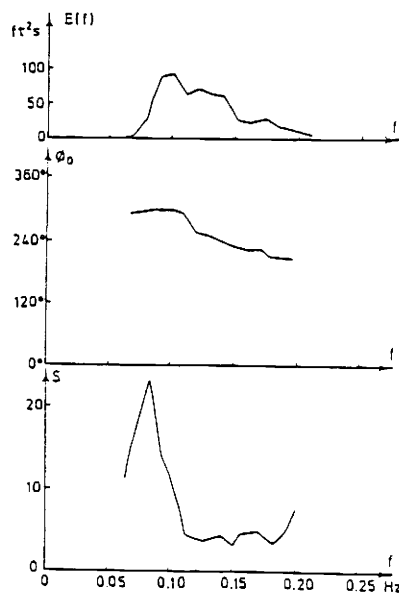


FIG. 2.8 Example frequency spectrum, central angle, spreading parameter behavior
(Forristall et al., 1978)

maximum near the spectral peak, decreasing on both sides of the peak. These are features commonly observed by many researchers utilizing this method of analysis on real ocean data.

The decrease of the spreading parameter on the low frequency, left side, of the spectral peak is not always significant. It is believed that a high spreading parameter should be reasonable for low frequency components if the measured wave properties are generated by a single storm. The low frequency wave components generally decay very slow and resist angular dispersion due to cross wind and currents. Consequently, low frequency waves must have high spreading parameters which indicate narrow angular distributions of wave energy. In contrast, a broad angular distribution of wave energy, which occurs for low spreading parameters, will spread energy over a wide range of directions. This will appear as a rapid decay of wave amplitude with distance. An irregular water surface elevation may be composed of swell coming from various remote storms. This could appear, numerically, as a high degree of spreading at low frequency yielding low spreading parameter values.

The variation of the spreading parameter with respect to spectral shape has been studied by Sand(1979). Utilizing the least square method, an empirical formulation has been defined in his research as (Sand, 1979)

$$s(\sigma) = 5 \cdot (\sigma_{1,-1}^*)^{-2.7} = 5 \cdot \left(\frac{\sigma}{\sigma_{1,-1}} \right)^{-2.7} \quad (2.43-1)$$

where

$$\sigma_{1,-1} = \sqrt{m_1/m_{-1}}, \quad (2.43-2)$$

$\sigma_{1,-1}^*$ is a dimensionless parameter, m_n is the n 'th moment of the one-dimensional spectrum. The reason he chose the parameter $\sigma_{1,-1}$ is that the mean frequency $\sigma_{1,0} = m_1/m_0$ emphasizes the high frequency components, while $\sigma_{0,-1} = m_0/m_{-1}$ emphasizes the low frequency components. Therefore,

a reasonable parameter seems to be $\sigma_{1,-1} = \sqrt{m_1/m_{-1}}$. The variation of the spreading parameter with respect to $\sigma_{1,-1}^*$ for the Baltic Sea (Sand et al., 1979) is compared with similar functions obtained in the Gulf of Mexico (Forristall et al., 1978) and in the Atlantic Ocean (Longuet-Higgins et al., 1963), in Fig. 2.9. Although the data have been obtained in quite different conditions, the curves, appearing in Fig. 2.9, agree well with the empirical formula.

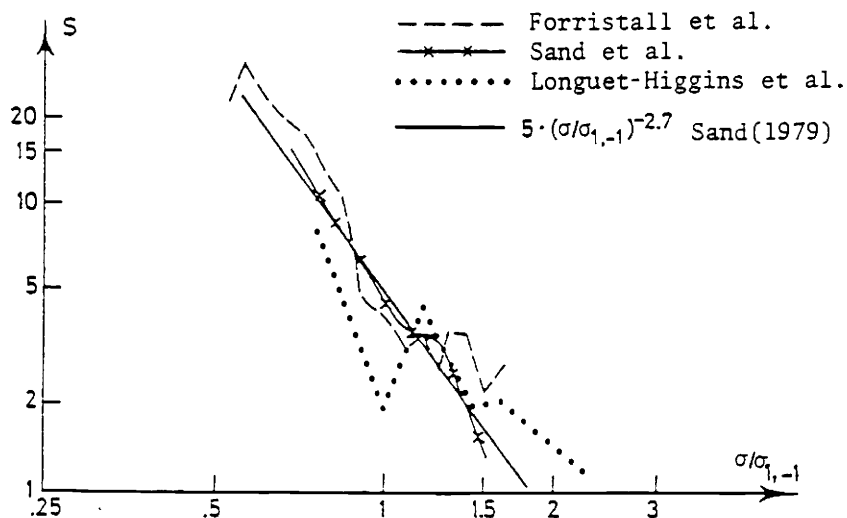


FIG. 2.9 Parameter s verses dimensionless frequency $\sigma_{1,-1}^*$
(Sand, 1979)

2.4 Deterministic Approach

It has been mentioned in the theoretical development of the stochastic approach that the phase information is ignored in the method. This limitation does not interfere with directional spectrum calculations, however, it does preclude computations required to predict the water surface profile or other wave properties. Thus, for applications wherein interest lies in the actual shapes of the higher waves, or wave grouping, etc., a description of the phase relationship among the decomposed

frequency components of various wave property measurements must be included in the spectral analysis. A procedure which analyzes directional wave properties utilizing phase information has been derived by Sand (1978). The method is called the Deterministic approach, and it is based on generating a group of small amplitude wavelets directly from a Fourier decomposition of simultaneous wave property measurements. The frequencies of the individual wavelets are uniformly spaced along the frequency axis in accordance with traditional Fourier analyses. The directions and phases are also determined for these wavelets at each frequency. Then, the one-dimensional frequency spectrum and its directional wave properties are evaluated from the relative wavelet properties at each frequency. Further interpretation of the wavelet properties leads to an estimate of the directional spectrum. The deterministic approach provides sufficient information to predict the sea surface profile as well as subsurface kinematic and dynamic wave properties. However, a disadvantage of the method is that orthogonal components of the same frequency are by definition 90° out of phase. It will be demonstrated later that this phase constraint is an arbitrary limitation, and will cause inappropriate estimates to the directional wave properties.

A summary of the steps used to derive the deterministic directional spectrum in the following discussion is presented below.

(1) The linear decomposition of various wave property measurements is performed by Fourier transformation.

(2) Orthogonal components of various wave property measurements at the same frequency are used to determine a pair of wavelets at that frequency, each propagating with its own direction and phase. However, the phases of such a pair of wavelets have been specified to be 0° and 90° , respectively, by representing one component as a cosine wave and the other as a sine wave.

(3) The wavelets can be obtained from either the pressure record

or the two velocity component records. The two solutions are combined via a redistribution procedure based upon a least square error analysis.

(4) Utilizing the wave energy density concept of linear wave theory, a progressive wavelet quantifies a parcel of wave energy in the direction of the wavelet. Thus, the frequency dependent Fourier coefficients, which have been introduced in Section 2.3.2, can be evaluated by the relative wavelet properties. The procedure used to quantify the central angle and spreading parameter then follows the method elaborated in section 2.3.3.

2.4.1 Deterministic Study of Ocean Waves

To start the analysis, a simple harmonic fluctuation at the water surface is assumed to be observed from a single point and is expressed by taking the real part of a complex number presentation of wave profile

$$\eta_n(\vec{s}_1, t) = \text{Re}[\alpha_n(\sigma_n) e^{i(\vec{k} \cdot \vec{s}_1 - \sigma_n t)}] \quad (2.44-1)$$

where $\alpha_n(\sigma_n)$ denotes a complex number amplitude at a frequency σ_n . Let $\alpha_n(\sigma_n) = a_n(\sigma_n) + ib_n(\sigma_n)$ and translate the origin of our co-ordinates to the point where the measurements are made, i.e., $\vec{s}_1 = 0$. Thus, Eq.(2.44-1) can be simplified as

$$\begin{aligned} \eta_n(t) &= \eta_n(0, t) = \text{Re}[(a_n(\sigma_n) + ib_n(\sigma_n)) e^{i(-\sigma_n t)}] \\ &= a_n(\sigma_n) \cos \sigma_n t + b_n(\sigma_n) \sin \sigma_n t \\ &= a_{\eta n} \cos \sigma_n t + b_{\eta n} \sin \sigma_n t \end{aligned} \quad (2.44-2)$$

where subscript n indicates the frequency σ_n . Equation (2.44-2) may be interpreted in two different ways. The traditional interpretation for one-dimensional waves is that orthogonal components can be combined to present one single harmonic wave propagating unidirectionally with a phase specified by the relative magnitudes of $a_{\eta n}$ and $b_{\eta n}$. However, for

directional wave analysis, each of the orthogonal components of the same frequency may be regarded as a simple harmonic wave propagating with its own unique direction and phase. The latter prescribes the existence of a cosine wave and a sine wave propagating on the water surface in different directions. However, the sine and cosine waves are by definition 90° out of phase.

By a linear superposition, an irregular sea surface can be represented by summing together numerous frequency dependent harmonic wavelets, identified in Eq.(2.44-2). This representation of surface waves, subsurface wave-induced dynamic pressure and horizontal velocity components is summarized below.

$$\eta(t) = \sum_{n=1}^{\infty} \text{Re}[\alpha_{\eta n} e^{-i\sigma_n t}] = \sum_{n=1}^{\infty} [a_{\eta n} \cos \sigma_n t + b_{\eta n} \sin \sigma_n t] \quad (2.45-1)$$

$$u(t) = \sum_{n=1}^{\infty} \text{Re}[\alpha_{u n} e^{-i\sigma_n t}] = \sum_{n=1}^{\infty} [a_{u n} \cos \sigma_n t + b_{u n} \sin \sigma_n t] \quad (2.45-2)$$

$$v(t) = \sum_{n=1}^{\infty} \text{Re}[\alpha_{v n} e^{-i\sigma_n t}] = \sum_{n=1}^{\infty} [a_{v n} \cos \sigma_n t + b_{v n} \sin \sigma_n t] \quad (2.45-3)$$

$$p(t) = \sum_{n=1}^{\infty} \text{Re}[\alpha_{p n} e^{-i\sigma_n t}] = \sum_{n=1}^{\infty} [a_{p n} \cos \sigma_n t + b_{p n} \sin \sigma_n t] \quad (2.45-4)$$

Note that Eqs.(2.45-1,2,3,4) anticipate the application of Fourier analysis, and the zero-order coefficients have been omitted due to zero-mean wave properties. Therefore, the relative Fourier coefficients are expressed as

$$a_{\eta n} + ib_{\eta n} = \alpha_{\eta n} = \frac{2}{T} \int_{-T/2}^{T/2} \eta(t) e^{i\sigma_n t} dt \quad (2.46-1)$$

$$a_{u n} + ib_{u n} = \alpha_{u n} = \frac{2}{T} \int_{-T/2}^{T/2} u(t) e^{i\sigma_n t} dt \quad (2.46-2)$$

$$a_{vn} + ib_{vn} = \alpha_{vn} = \frac{2}{T} \int_{-T/2}^{T/2} v(t) e^{i\sigma_n t} dt \quad (2.46-3)$$

$$a_{pn} + ib_{pn} = \alpha_{pn} = \frac{2}{T} \int_{-T/2}^{T/2} p(t) e^{i\sigma_n t} dt \quad (2.46-4)$$

where T is the total record length, and $n=1,2,3,\dots$. A factor, 2, appears in Eq.(2.46-1,2,3,4) because only the positive frequency has been considered in this analysis. According to the Fourier transformation, the fundamental frequency is inversely proportional to total record length T and is defined as

$$\Delta\sigma = \frac{2\pi}{T}$$

Then, frequencies are equally spaced on both positive and negative sides of frequency axis. If a total of N points is applied in the Fourier transformation, the positive frequencies which are considered here will be represented as

$$\sigma_n = n\Delta\sigma, \quad n=1,2,\dots,N/2$$

From linear wave theory, the water surface components, Eq.(2.46-1), can be transferred to subsurface wave property components, Eqs.(2.46-2,3,4), and such a procedure can be easily reversed. Utilizing transfer functions, defined in Eqs.(2.10) and (2.11), we have the following identities for an arbitrary frequency σ_n :

$$a_{un} + ib_{un} = K_n [a_{2nn} \cos\phi_{an} + ib_{2nn} \cos\phi_{bn}] \quad (2.47-1)$$

$$a_{vn} + ib_{vn} = K_n [a_{2nn} \sin\phi_{an} + ib_{2nn} \sin\phi_{bn}] \quad (2.47-2)$$

$$a_{pn} + ib_{pn} = K_{pn} [a_{0nn} + ib_{0nn}] \quad (2.47-3)$$

where subscript 0 indicates the wavelet properties obtained from the

pressure record $p(t)$, subscript 2 indicates the wavelet properties obtained from the velocity records $u(t)$ and $v(t)$, and ϕ_{an} , ϕ_{bn} are the propagating directions of the frequency dependent cosine and sine wavelets, respectively. Therefore, the wavelets and their propagating directions can be solved simultaneously from Eqs.(2.47-1,2,3).

$$a_{0nn} = a_{pn}/K_{pn}, \quad b_{0nn} = b_{pn}/K_{pn} \quad (2.48-1)$$

$$|a_{2nn}| = \sqrt{a_{un}^2 + a_{vn}^2} / K_n, \quad |b_{2nn}| = \sqrt{b_{un}^2 + b_{vn}^2} / K_n \quad (2.48-2)$$

$$\phi_{an} = \tan^{-1}\left(\frac{a_{vn}}{a_{un}}\right), \quad \phi_{bn} = \tan^{-1}\left(\frac{b_{vn}}{b_{un}}\right) \quad (2.48-3)$$

The sign of a_{2nn} and b_{2nn} is determined from a_{pn} and b_{pn} , respectively. Negative values are possible for a_{0nn} and b_{0nn} , and this will change the wavelet direction by 180° relative to positive amplitudes. Accordingly, the sign of the pressure amplitude is used to interpret the sign of the wavelet amplitude, and to remove the 180° ambiguity from the wavelet direction. Thus,

$$a_{2nn} = |a_{2nn}| \frac{|a_{pn}|}{a_{pn}}, \quad b_{2nn} = |b_{2nn}| \frac{|b_{pn}|}{b_{pn}} \quad (2.48-4)$$

$$\phi_{an} = \tan^{-1}\left[\frac{(a_{vn}|a_{pn}|/a_{pn})}{(a_{un}|a_{pn}|/a_{pn})}\right], \quad \phi_{bn} = \tan^{-1}\left[\frac{(b_{vn}|b_{pn}|/b_{pn})}{(b_{un}|b_{pn}|/b_{pn})}\right] \quad (2.48-5)$$

Fourier analysis of the pressure and velocity records provides six known pressure and velocity coefficients at each frequency to solve for two wavelet amplitudes and two wave directions. The deterministic approach prescribes the phase of the sine and cosine wavelets, thereby eliminating two more unknowns which could be solved from the six Fourier coefficients. As a result the solution is overprescribed, yielding one set of wavelet amplitudes from the pressure measurements, Eq.(2.48-1), and

one set of wavelet amplitudes from the velocity measurements corrected for sign with pressure in Eq.(2.48-4). Then a single set of wavelet amplitudes is determined by minimizing the difference between the two solutions in a least square error sense (Sand, 1979). In this procedure, wavelets of a frequency band comprising L successive frequencies are used to evaluate the final wavelet amplitudes, denoted as a_{nn} and b_{nn} , according to:

$$\left\{ \sum_{n=\ell-L/2}^{\ell+L/2} (a_{nn} - a_{0nn}) \right\}^2 + \left\{ \sum_{n=\ell-L/2}^{\ell+L/2} (a_{nn} - a_{2nn}) \right\}^2 = \text{minimum} \quad (2.49-1)$$

$$\left\{ \sum_{n=\ell-L/2}^{\ell+L/2} (b_{nn} - b_{0nn}) \right\}^2 + \left\{ \sum_{n=\ell-L/2}^{\ell+L/2} (b_{nn} - b_{2nn}) \right\}^2 = \text{minimum} \quad (2.49-2)$$

where $\ell=1+L/2, 2+L/2, \dots, (N-L)/2$. The solution from Eqs.(2.49-1,2) can be approximated by (Sand, 1979)

$$a_{nn} = a_{2nn} + \frac{1}{2L} \sum_{\ell=n-L/2}^{n+L/2} [a_{0n\ell} - a_{2n\ell}] \quad (2.50-1)$$

$$b_{nn} = b_{2nn} + \frac{1}{2L} \sum_{\ell=n-L/2}^{n+L/2} [b_{0n\ell} - b_{2n\ell}] \quad (2.50-2)$$

Finally, the directions can be corrected from the wavelets quantified in Eqs.(2.50-1,2) as

$$\phi_{an} = \tan^{-1} \left[\frac{(a_{vn} | a_{nn} | / a_{nn})}{(a_{un} | a_{nn} | / a_{nn})} \right], \quad \phi_{bn} = \tan^{-1} \left[\frac{(b_{vn} | b_{nn} | / b_{nn})}{(b_{un} | b_{nn} | / b_{nn})} \right] \quad (2.50-3)$$

The choice of the number of frequencies in the frequency band, L, has been determined by trial and error. The appropriate choice for the band is said to be sufficiently small to provide detailed information on frequency dependence while allowing the error to be minimized over a finite number of adjacent frequency components.

One direct consequence of the deterministic approach is that the

water surface elevation at a site near the point where measurements were made can be predicted as

$$\begin{aligned} \eta(x,y,t) = & \sum_{n=1}^{N/2} \{ a_{nn} \cos[k_n \cos(\phi_{an})x + k_n \sin(\phi_{an})y - \sigma_n t] \\ & + b_{nn} \sin[k_n \cos(\phi_{bn})x + k_n \sin(\phi_{bn})y - \sigma_n t] \} \end{aligned} \quad (2.51-1)$$

where k_n is the wave number. Also, a prediction of subsurface wave properties is available by transferring the water surface wavelets to the subsurface wavelet properties. For example, the wave-induced subsurface dynamic pressure and horizontal velocity components can be represented as follows:

$$\begin{aligned} p(x,y,t) = & \sum_{n=1}^{N/2} K_{pn} \{ a_{nn} \cos[k_n \cos(\phi_{an})x + k_n \sin(\phi_{an})y - \sigma_n t] \\ & + b_{nn} \sin[k_n \cos(\phi_{bn})x + k_n \sin(\phi_{bn})y - \sigma_n t] \} \end{aligned} \quad (2.51-2)$$

$$\begin{aligned} u(x,y,t) = & \sum_{n=1}^{N/2} K_n \{ a_{nn} \cos[k_n \cos(\phi_{an})x + k_n \sin(\phi_{an})y - \sigma_n t] \cos(\phi_{an}) \\ & + b_{nn} \sin[k_n \cos(\phi_{bn})x + k_n \sin(\phi_{bn})y - \sigma_n t] \cos(\phi_{bn}) \} \end{aligned} \quad (2.51-3)$$

$$\begin{aligned} v(x,y,t) = & \sum_{n=1}^{N/2} K_n \{ a_{nn} \cos[k_n \cos(\phi_{an})x + k_n \sin(\phi_{an})y - \sigma_n t] \sin(\phi_{an}) \\ & + b_{nn} \sin[k_n \cos(\phi_{bn})x + k_n \sin(\phi_{bn})y - \sigma_n t] \sin(\phi_{bn}) \} \end{aligned} \quad (2.51-4)$$

2.4.2 Estimating the Wave Spectrum

In the previous section, it has been shown that orthogonal wave property components of the same frequency are used to determine a pair of wavelets at that frequency. Since wavelet frequencies have been uniformly spaced on a frequency axis, a pair of wavelets of the same frequency actually represent the contribution of the irregular water

surface profile within a fundamental frequency interval centered at that frequency. Then, the one-dimensional frequency spectrum can be estimated as

$$E(\sigma_n) = E_n = \frac{1}{2}(a_{\eta n}^2 + b_{\eta n}^2) / \Delta\sigma \quad (2.52)$$

where $\Delta\sigma$ is a fundamental radian frequency interval. The total wave energy per unit water surface area per unit water weight can be estimated by summing together all wave energy contributions with respect to frequency. The expression of this total energy density,

$$E_{\text{total}} = \sum_{n=1}^{N/2} \frac{1}{2}(a_{\eta n}^2 + b_{\eta n}^2) = \sum_{n=1}^{N/2} E_n \Delta\sigma \quad (2.53)$$

is equivalent to Eq.(2.7), and Eq.(2.53) indicates the application of Parseval's theorem (Brighan, 1974). Parseval's theorem says that the energy density computed in the time domain is equal to the energy computed in the frequency domain.

To prove Parseval's theorem, it is necessary to first prove the Correlation theorem, which transforms correlation in the time domain to simple products in the frequency domain by utilizing the Fourier transformation (Brighan, 1974). Substituting Eq.(2.18) into Eq.(2.17) yields

$$\zeta_{ij}(\sigma) = \lim_{T \rightarrow \infty} \frac{1}{2\pi T} \int_{-T/2}^{T/2} \omega_i(t) \left[\int_{-T/2}^{T/2} \omega_j(t+\tau) e^{-i\sigma\tau} d\tau \right] dt \quad (2.54-1)$$

Let $t' = t + \tau$, then $\tau = t' - t$, $d\tau = dt'$, and

$$\zeta_{ij}(\sigma) = \lim_{T \rightarrow \infty} \frac{1}{4\pi} \int_{-T/2}^{T/2} \omega_i(t) \left[\frac{2}{T} \int_{-T/2}^{T/2} \omega_j(t') e^{-i\sigma t'} dt' \right] e^{i\sigma t} dt \quad (2.54-2)$$

The bracketed term is a complex conjugate of Eqs.(2.46-1,2,3,4), etc. Equation (2.54-2) can be further simplified as

$$\begin{aligned}\zeta_{ij}(\sigma) &= \lim_{T \rightarrow \infty} \frac{T}{8\pi} \left[\frac{2}{T} \int_{-T/2}^{T/2} \omega_i(t) e^{i\sigma t} dt \right] [a_j(\sigma) - ib_j(\sigma)] \\ &= \lim_{T \rightarrow \infty} \frac{T}{8\pi} [a_i(\sigma) + ib_i(\sigma)] [a_j(\sigma) + ib_j(\sigma)]^*\end{aligned}\quad (2.54-3)$$

As mentioned in Section 2.3.2, a factor of 2 must be inserted in Eq. (2.54-3) to convert from a two-sided spectrum to a one-sided spectrum. Also, the fundamental frequency interval, $\Delta\sigma = 2\pi/T$, is substituted in Eq. (2.54-3). Thus, we have

$$\zeta_{ij}(\sigma) = \lim_{\Delta\sigma \rightarrow \infty} \frac{[a_i(\sigma) + ib_i(\sigma)] [a_j(\sigma) + ib_j(\sigma)]^*}{2\Delta\sigma} \quad (2.54-4)$$

Now, the wave properties considered here, i.e., $p(t)$, $u(t)$ and $v(t)$, are all in phase; refer to Eqs. (2.13-1,2,3). Therefore, the correlation functions among them are even functions, e.g., Eq. (2.22), and the induced cross spectra are all real numbers, i.e., co-spectra $C_{ij}(\sigma)$. That is

$$\begin{aligned}C_{ij}(\sigma) &= \text{Re}[\zeta_{ij}(\sigma)] = \frac{1}{2}[\zeta_{ij}(\sigma) + \zeta_{ij}^*(\sigma)] = \frac{1}{2}[\zeta_{ij}(\sigma) + \zeta_{ji}(\sigma)] \\ &= \lim_{\Delta\sigma \rightarrow \infty} \frac{[a_i(\sigma)a_j(\sigma) + b_i(\sigma)b_j(\sigma)]}{2\Delta\sigma}\end{aligned}\quad (2.54-5)$$

where $\zeta_{ij}^*(\sigma) = \zeta_{ji}(\sigma)$ from Eq. (2.54-2). Equation (2.54-4) presents a general expression of the Correlation theorem, while Eq. (2.54-5) provides a particular case of the Correlation theorem for $p(t)$, $u(t)$ and $v(t)$, measured at the same horizontal location. However, for $i=j$, the auto-correlation function will always be even and the induced spectrum will be real; this is represented by Eq. (2.54-5). Thus,

$$C_{ii}(\sigma) = \lim_{\Delta\sigma \rightarrow \infty} \frac{1}{2} [a_i^2(\sigma) + b_i^2(\sigma)] / \Delta\sigma = E(\sigma) \quad (2.55)$$

which is a definition of the one-dimensional spectrum. Also, the correlation function can be expressed as a inverse Fourier transform of the cross spectrum. An equivalent expression is

$$\Pi_{ij}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \omega_i(t) \omega_j(t+\tau) dt = \int_0^{\infty} \zeta_{ij}(\sigma) e^{-i\sigma\tau} d\sigma$$

Let $\tau=0$ and $i=j$,

$$\begin{aligned} \overline{\omega_i^2(t)} &= \int_0^{\infty} C_{ii}(\sigma) d\sigma = \int_0^{\infty} E_{ii}(\sigma) d\sigma \\ &= \sum_{n=1}^{N/2} E_{ii}(\sigma_n) \Delta\sigma = \sum_{n=1}^{N/2} \frac{1}{2} [a_{in}^2 + b_{in}^2] / \Delta\sigma \end{aligned} \quad (2.56)$$

The expression represented by Eq.(2.56) is Parseval's theorem. According to Parseval's theorem, the mean square value, or variance, of a wave property record $\omega_i(t)$ computed in the time domain can be obtained from a computation in the frequency domain. Note that the existence of Eq.(2.56) provides that a_{in} and b_{in} are directly computed from Fourier transform of the wave property record $\omega_i(t)$. Since the wavelet amplitudes $a_{\eta n}$ and $b_{\eta n}$ which appear in Eq.(2.53) are not the direct Fourier coefficients, Eq.(2.53) does not present a mean square value of the time series $\eta(t)$. However, the value computed in Eq.(2.53) may be interpreted in a mean square sense via the presentation of Eq.(2.4). That is, a total mean square value of waves is a summation of each mean square value of frequency component wavelets. Therefore, the value computed in Eq.(2.53) is interpreted as a mean square value of waves, and the value computed in Eq.(2.56) is interpreted as a mean square value of the time series of a wave property, either measured or predicted.

The analysis of directional wave properties in the deterministic approach is similar to the procedure described in the stochastic approach in Section 2.3.3. The directional spectrum has been expressed as a Fourier series with simple harmonic direction components and frequency dependent coefficients. The Fourier coefficients are defined by the integral in Eq.(2.25-2). The deterministic approach yields two unique wave components at specified directions in each of the equally spaced frequency intervals. Therefore, the continuous integral in Eq.(2.25-2) becomes a simple summation of weighted energy densities of the two di-

rectional components. The first five frequency dependent Fourier coefficients are evaluated from wavelet properties at that same frequency in accordance with:

$$A_{0n} = \frac{1}{2} [a_{nn}^2 + b_{nn}^2] / \Delta\sigma \quad (2.57-1)$$

$$A_{1n} = \frac{1}{2} [a_{nn}^2 \cos\phi_{an} + b_{nn}^2 \cos\phi_{bn}] / \Delta\sigma \quad (2.57-2)$$

$$B_{1n} = \frac{1}{2} [a_{nn}^2 \sin\phi_{an} + b_{nn}^2 \sin\phi_{bn}] / \Delta\sigma \quad (2.57-3)$$

$$A_{2n} = \frac{1}{2} [a_{nn}^2 \cos 2\phi_{an} + b_{nn}^2 \cos 2\phi_{bn}] / \Delta\sigma \quad (2.57-4)$$

$$B_{2n} = \frac{1}{2} [a_{nn}^2 \sin 2\phi_{an} + b_{nn}^2 \sin 2\phi_{bn}] / \Delta\sigma \quad (2.57-5)$$

With these five coefficients, the directional frequency spectrum can be estimated with respect to the one angle mode and the double angle mode solution techniques summarized in Section 2.3.3.

2.4.3 Similarities Between the Stochastic and Deterministic Approaches

Two uncertainties related to the minimum error principle mentioned in Eqs.(2.49-1,2) should not be ignored. First, the number of frequencies considered in each redistribution of wavelet amplitudes, a_{nn} and b_{nn} , is a priori unknown. Second, numerical results have shown that the wavelet amplitudes estimated from Eqs.(2.48-1) and (2.48-4), separately, do not often relate to each other. Also, a redistribution of wavelet amplitudes will change the estimate of the one-dimensional frequency spectrum and the Fourier coefficients expressed in Eqs.(2.57-1,2,3,4,5). Although the directions, ϕ_{an} and ϕ_{bn} , which are evaluated from measured velocity data will not be affected by the redistribution of wavelet amplitudes, the directional properties of energy distribution can be in error if the frequency component energy densities are not correct. Therefore, the determination of frequency component energy densities

will be restudied in this section by comparing the stochastic and deterministic solutions to the one angle mode and double angle mode directional distributions of wave energy densities. This study is based on the Correlation theorem and is summarized as follows.

According to the Correlation theorem, the co-spectrum among simultaneous wave property measurements, $p(t)$, $u(t)$ and $v(t)$, can be expressed in terms of Fourier coefficients of these wave properties.

$$C_{ppn} = \frac{1}{2}[a_{pn}^2 + b_{pn}^2]/\Delta\sigma \quad (2.58-1)$$

$$C_{pun} = \frac{1}{2}[a_{pn}a_{un} + b_{pn}b_{un}]/\Delta\sigma \quad (2.58-2)$$

$$C_{pvn} = \frac{1}{2}[a_{pn}a_{vn} + b_{pn}b_{vn}]/\Delta\sigma \quad (2.58-3)$$

$$C_{uvn} = \frac{1}{2}[a_{un}a_{vn} + b_{un}b_{vn}]/\Delta\sigma \quad (2.58-4)$$

$$C_{uun} = \frac{1}{2}[a_{un}^2 + b_{un}^2]/\Delta\sigma \quad (2.58-5)$$

$$C_{vvn} = \frac{1}{2}[a_{vn}^2 + b_{vn}^2]/\Delta\sigma \quad (2.58-6)$$

Note that Eqs. (2.58-1,2,3,4,5,6) are estimated at equally spaced frequencies. Substituting Eqs. (2.58-1,2,3,4,5,6) into Eqs. (2.26-1,2,3,4,7), the first five frequency dependent Fourier coefficients in the stochastic approach yield

$$A_{on} = \frac{1}{2\pi K_{pn}^2}[a_{pn}^2 + b_{pn}^2]/\Delta\sigma \quad (2.59-1)$$

$$A_{1n} = \frac{1}{2\pi K_n K_{pn}}[a_{pn}a_{un} + b_{pn}b_{un}]/\Delta\sigma \quad (2.59-2)$$

$$B_{1n} = \frac{1}{2\pi K_n K_{pn}}[a_{pn}a_{vn} + b_{pn}b_{vn}]/\Delta\sigma \quad (2.59-3)$$

$$A_{2n} = \frac{1}{2\pi K_n^2}[a_{un}^2 + b_{un}^2 - a_{vn}^2 - b_{vn}^2]/\Delta\sigma \quad (2.59-4)$$

$$B_{2n} = \frac{1}{2\pi K_n^2} [a_{un} a_{vn} + b_{un} b_{vn}] / \Delta\sigma \quad (2.59-5)$$

Also, A_{on} can be expressed in terms of C_{uun} and C_{vvn} from Eqs. (2.26-1) and (2.27).

$$A_{on} = \frac{1}{2\pi K_n^2} [a_{un}^2 + b_{un}^2 + a_{vn}^2 + b_{vn}^2] / \Delta\sigma \quad (2.59-6)$$

Obviously A_{on} , which is evaluated in Eq. (2.59-6), should be used in procedures utilizing the double angle mode solutions. This is because A_{2n} will be unique from either Eq. (2.26-4) or Eq. (2.26-5) or Eq. (2.26-6). The coefficients A_{1n} and B_{1n} in the one angle mode solution procedure are expressed in terms of C_{pun} and C_{pvn} which are defined by the integral in Eq. (2.24-2,3). However, there is no evidence which A_{on} , i.e., that obtained from either Eq. (2.59-1) or Eq. (2.59-6), should be used in a procedure utilizing the one angle mode solutions.

In the deterministic approach, the first five Fourier coefficients are approximated by the summations of relative wavelet properties in Eqs. (2.57-1,2,3,4,5). Thus, all five coefficients, estimated from Eqs. (2.57-1,2,3,4,5) can be in error if a redistribution of wavelet amplitudes is not exact the induced spectra from these five Fourier coefficients will be in question relative to accuracy. Since ϕ_{an} and ϕ_{bn} solved in Eq. (2.48-5) in the deterministic approach are more dependent on the velocity component data, and less dependent on pressure data, they can be regarded to provide relatively accurate direction information. Thus, with the Fourier coefficients A_{1n} , B_{1n} , A_{2n} , B_{2n} , and the wavelet directions ϕ_{an} , ϕ_{bn} , one may obtain alternative solutions to A_{on} depending on whether the one angle mode or the double angle mode solutions are utilized. Alternative solutions to A_{on} are obtained as follows.

To express $\cos\phi_{an}$, $\sin\phi_{an}$, $\cos\phi_{bn}$, $\sin\phi_{bn}$ in terms of a_{pn} , b_{pn} , a_{un} , b_{un} , a_{vn} , b_{vn} , we have

$$\cos\phi_{an} = \frac{a_{un}}{(a_{un}^2 + a_{vn}^2)^{1/2}} \frac{|a_{pn}|}{a_{pn}}, \quad \sin\phi_{an} = \frac{a_{vn}}{(a_{un}^2 + a_{vn}^2)^{1/2}} \frac{|a_{pn}|}{a_{pn}} \quad (2.60-1)$$

$$\cos\phi_{bn} = \frac{b_{un}}{(b_{un}^2 + b_{vn}^2)^{1/2}} \frac{|b_{pn}|}{b_{pn}}, \quad \sin\phi_{bn} = \frac{b_{vn}}{(b_{un}^2 + b_{vn}^2)^{1/2}} \frac{|b_{pn}|}{b_{pn}} \quad (2.60-2)$$

Then, $\cos 2\phi_{an}$, $\sin 2\phi_{an}$, $\cos 2\phi_{bn}$, and $\sin 2\phi_{bn}$ can be derived as

$$\cos 2\phi_{an} = \frac{a_{un}^2 - a_{vn}^2}{a_{un}^2 + a_{vn}^2}, \quad \sin 2\phi_{an} = \frac{2a_{un}a_{vn}}{a_{un}^2 + a_{vn}^2} \quad (2.60-3)$$

$$\cos 2\phi_{bn} = \frac{b_{un}^2 - b_{vn}^2}{b_{un}^2 + b_{vn}^2}, \quad \sin 2\phi_{bn} = \frac{2b_{un}b_{vn}}{b_{un}^2 + b_{vn}^2} \quad (2.60-4)$$

By substituting $\cos 2\phi_{an}$, $\sin 2\phi_{an}$, $\cos 2\phi_{bn}$, $\sin 2\phi_{bn}$, derived above, into right sides of Eqs. (2.57-4,5) and A_{2n} , B_{2n} , derived in Eqs. (2.59-4,5), into left sides of Eqs. (2.57-4,5), a pair of wavelet amplitudes can be solved at each frequency, σ_n .

$$|a_{2\eta n}| = \frac{(a_{un}^2 + a_{vn}^2)^{1/2}}{K_n}, \quad |b_{2\eta n}| = \frac{(b_{un}^2 + b_{vn}^2)^{1/2}}{K_n} \quad (2.61-1)$$

Similar to Eq. (2.48-4), the sign of wavelet amplitudes obtained in Eq. (2.61-1) is determined from the pressure components. Thus,

$$a_{2\eta n} = |a_{2\eta n}| \cdot |a_{pn}| / a_{pn}, \quad b_{2\eta n} = |b_{2\eta n}| \cdot |b_{pn}| / b_{pn} \quad (2.61-2)$$

Note that Eqs. (2.61-1,2) are identical to Eqs. (2.48-2,4), and therefore wavelet amplitudes solved from Eq. (2.61-2) or (2.48-4) are suitable in a procedure estimating directional spectrum from the double angle mode solution. The subscript 2 appearing in Eqs. (2.61-1,2) indicates that the wavelet amplitudes solved from Eqs. (2.61-1,2) are more related to velocity component data and are suitable for the double angle mode solution procedure in both stochastic and deterministic approaches.

Now, by substituting $\cos\phi_{an}$, $\sin\phi_{an}$, $\cos\phi_{bn}$, $\sin\phi_{bn}$, derived in Eq. (2.60-1,2), into the right sides of Eqs. (2.57-2,3) and A_{1n} , B_{1n} , derived

in Eqs.(2.59-2,3), into left sides of Eqs.(2.57-2,3), another pair of wavelet amplitudes can be solved at each frequency, σ_n .

$$|a_{1nn}| = \left\{ \frac{\sqrt{a_{un}^2 + a_{vn}^2} |a_{pn}|}{K_n K_{pn}} \right\}^{\frac{1}{2}} = \{ |a_{2nn}| \cdot |a_{0nn}| \}^{\frac{1}{2}},$$

$$|b_{1nn}| = \left\{ \frac{\sqrt{b_{un}^2 + b_{vn}^2} |b_{pn}|}{K_n K_{pn}} \right\}^{\frac{1}{2}} = \{ |b_{2nn}| \cdot |b_{0nn}| \}^{\frac{1}{2}} \quad (2.62-1)$$

Note that a_{0nn} and b_{0nn} are the wavelet amplitudes estimated from pressure data, i.e., Eq.(2.48-1). The sign of wavelet amplitudes obtained in Eq.(2.62-1) is determined from the pressure components. Thus,

$$a_{1nn} = |a_{1nn}| \cdot |a_{pn}| / a_{pn}, \quad b_{1nn} = |b_{1nn}| \cdot |b_{pn}| / b_{pn} \quad (2.62-2)$$

The wavelet amplitudes solved from Eqs.(2.62-1,2) are suitable for procedures estimating directional spectrum from the one angle mode solution. The subscript 1 appearing in Eqs.(2.62-1,2) indicates that the wavelet amplitudes solved from Eqs.(2.62-1,2) are suitable for the one angle mode solution procedure in both stochastic and deterministic approaches.

It is apparent that the magnitude of a_{1nn} is equivalent to the geometric mean of the magnitudes of a_{2nn} and a_{0nn} , and the magnitude of b_{1nn} is equivalent to the geometric mean of the magnitudes of b_{2nn} and b_{0nn} . Therefore, the wavelet energy density estimates of a_{0nn} , b_{0nn} , a_{1nn} , b_{1nn} , a_{2nn} and b_{2nn} , have the following properties:

$$E_{1an} = \frac{1}{2} a_{1nn}^2 / \Delta\sigma = \{ E_{0an} \cdot E_{2an} \}^{\frac{1}{2}}, \quad E_{1bn} = \frac{1}{2} b_{1nn}^2 / \Delta\sigma = \{ E_{0bn} \cdot E_{2bn} \}^{\frac{1}{2}} \quad (2.63)$$

where

$$E_{0an} = \frac{1}{2} a_{0nn}^2 / \Delta\sigma, \quad E_{0bn} = \frac{1}{2} b_{0nn}^2 / \Delta\sigma \quad (2.64)$$

$$E_{2an} = \frac{1}{2} a_{2nn}^2 / \Delta\sigma, \quad E_{2bn} = \frac{1}{2} b_{2nn}^2 / \Delta\sigma \quad (2.65)$$

Thus, the one-dimensional frequency spectra of water surface elevation may be estimated by either of the following three expressions:

$$E_{0n} = E_{0an} + E_{0bn} = \frac{1}{2}(a_{0n}^2 + b_{0n}^2) / \Delta\sigma \quad (2.66-1)$$

$$E_{1n} = E_{1an} + E_{1bn} = \frac{1}{2}(a_{1n}^2 + b_{1n}^2) / \Delta\sigma \quad (2.66-2)$$

$$E_{2n} = E_{2an} + E_{2bn} = \frac{1}{2}(a_{2n}^2 + b_{2n}^2) / \Delta\sigma \quad (2.66-3)$$

E_{0n} is estimated from pressure data alone. E_{1n} is estimated from both pressure and velocity data and is referred to as the one angle mode solution. E_{2n} is estimated from velocity data alone and is referred to as the double angle mode solution.

Substituting the relative energy estimates from the one angle mode and double angle mode solutions for A_{1n} , B_{1n} , A_{2n} , B_{2n} in Eqs.(2.57-2,3,4,5) and then combining these equations with the directional wave property estimators in Eqs.(2.39-1) and (2.40-1), we have the following identities:

$$A_{1n} = E_{1an} \cos\phi_{an} + E_{1bn} \cos\phi_{bn} = E_{1n} C_{1n} \cos\phi_{o1n} \quad (2.67-1)$$

$$B_{1n} = E_{1an} \sin\phi_{an} + E_{1bn} \sin\phi_{bn} = E_{1n} C_{1n} \sin\phi_{o1n} \quad (2.67-2)$$

$$A_{2n} = E_{2an} \cos 2\phi_{an} + E_{2bn} \cos 2\phi_{bn} = E_{2n} C_{2n} \cos 2\phi_{o2n} \quad (2.67-3)$$

$$B_{2n} = E_{2an} \sin 2\phi_{an} + E_{2bn} \sin 2\phi_{bn} = E_{2n} C_{2n} \sin 2\phi_{o2n} \quad (2.67-4)$$

Therefore, C_{1n} , ϕ_{o1n} , C_{2n} and ϕ_{o2n} can be solved as

$$C_{1n} = \frac{\sqrt{E_{1an}^2 + E_{1bn}^2 + 2E_{1an}E_{1bn} \cos(\phi_{an} - \phi_{bn})}}{E_{1n}} \quad (2.68-1)$$

$$\phi_{o1n} = \tan^{-1} \frac{E_{1an} \sin\phi_{an} + E_{1bn} \sin\phi_{bn}}{E_{1an} \cos\phi_{an} + E_{1bn} \cos\phi_{bn}} \quad (2.68-2)$$

$$C_{2n} = \frac{\sqrt{E_{2an}^2 + E_{2bn}^2 + 2E_{2an}E_{2bn}\cos 2(\phi_{an} - \phi_{bn})}}{E_{2n}} \quad (2.68-3)$$

$$\phi_{o2n} = \frac{1}{2} \tan^{-1} \frac{E_{2an} \sin 2\phi_{an} + E_{2bn} \sin 2\phi_{bn}}{E_{2an} \cos 2\phi_{an} + E_{2bn} \cos 2\phi_{bn}} \quad (2.68-4)$$

The ambiguity in direction ϕ_{o2n} by 180° can be corrected by the methods mentioned in section 2.3.3.

The Correlation theorem has been used as a main tool in the similarity study between the stochastic and deterministic approaches in this section. Correlation theorem says that the Fourier transform of the correlation function is equal to products of the relative Fourier coefficients of individual time series at the same frequency. Evidently, the stochastic method estimates the directional distribution of wave energy from the Fourier transform of correlation function of simultaneous wave property measurements. The deterministic method estimates the directional distribution of wave energy from the direct Fourier transform of simultaneous wave property measurements. Hence, utilizing the interpretation of Correlation theorem, both stochastic and deterministic approaches should yield the same method. Since a redistribution of wavelet amplitudes based upon a minimum error principle in the deterministic approach may not improve the estimates of directional energy spreading, the indeterminate wavelet amplitudes make it different to evaluate the frequency dependent Fourier coefficients A_{on} , A_{1n} , B_{1n} , A_{2n} and B_{2n} , which are necessary in directional frequency spectrum estimate. However, coefficients A_{1n} , B_{1n} , A_{2n} and B_{2n} , can be obtained from the stochastic solutions. These four coefficients, A_{1n} , B_{1n} , A_{2n} , B_{2n} , and two wavelet directions, ϕ_{an} , ϕ_{bn} , obtained from the deterministic approach enable us to solve the wavelet amplitudes and determine the coefficient A_{on} . However, the similarity study between the stochastic and deterministic approaches described herein suggests alternative evaluations of the one-dimensional spectrum or the coefficient A_{on} for the one and double angle mode solutions. A combined name, stochastic/deterministic approach, is assigned to the resulting combined method to identify that some improve-

ments have been made for directional spectrum estimates.

The combined stochastic/deterministic one angle mode solution to wave energy spreading is summarized in Eqs.(2.68-1,2). The spreading parameter, s , may be evaluated in terms of C_1 via Eq.(2.39-4). The one-dimensional spectrum is evaluated from Eq.(2.66-2).

The combined stochastic/deterministic double angle mode solution to wave energy spreading is summarized in Eqs.(2.68-3,4). The spreading parameter, s , may be evaluated in terms of C_2 via Eq.(2.40-4). The one-dimensional spectrum is evaluated from Eq.(2.66-3).

2.5 Geometric Approach

It has been demonstrated theoretically in the previous section that a combined stochastic/deterministic approach is superior to the traditional stochastic or deterministic approaches. One limitation of the method, however, is that the deterministic wavelet pairs at each frequency are arbitrarily defined to be 90° out of phase. Also, a contradiction exists for one-dimensional frequency spectrum estimates between the one angle mode and double angle mode solutions.

To correct these limitations, a geometric approach is proposed which releases the phase constraint mentioned above and which employs both pressure and velocity data to quantify a single one angle mode solution. The geometric approach is an extension of the deterministic approach, utilizing a pair of wavelets in each frequency. A Fourier analysis of pressure and horizontal velocity records provides three known coefficient pairs to quantify two wave amplitudes, two wave directions and two wave phases at each specified frequency.

2.5.1 Kinematic Description

The geometric approach defines two simple harmonic wavelets at the water surface to reproduce the behavior of each frequency component of the Fourier analyzed pressure and velocity records. It will be shown

that the measurements of pressure and horizontal vector velocity are sufficient to specify the amplitude, phase and direction of two wavelets at each frequency. Additional measurements would be required to quantify additional wavelet components. The subsurface kinematics and dynamics due to each wavelet are transferred linearly from each wavelet to the subsurface. Furthermore, the gross subsurface kinematics and dynamics are expressed as a linear summation of the transformed wavelet properties (Nagata, 1964).

Now, let us define two wavelets at each frequency as cosine functions with unspecified phase. Let a_{3n} , b_{3n} denote the wavelet amplitudes and ϕ_{3an} , ϕ_{3bn} , θ_{3an} , θ_{3bn} denote their directions and phases, respectively, at the frequency σ_n . The subscript 3 on wavelet amplitude, direction and phase, identifies the results of the geometric method. Let $A(\sigma_n)$ and $B(\sigma_n)$ denote horizontal orbital velocity amplitudes of surface wavelets a_{3n} and b_{3n} , respectively, at a height h_1 above bottom. Then, according to Eq.(2.9-3), we have

$$A(\sigma_n) = a_{3n} K_n, \quad B(\sigma_n) = b_{3n} K_n \quad (2.69)$$

In Fig. 2.10, two vector velocities induced by two such surface wavelets are shown by solid lines and a resultant velocity is shown by a bold line. From the addition formula of cosine functions, the individual horizontal velocities can be expanded by the following identities:

$$\begin{aligned} A(\sigma_n) \cos(\sigma_n t - \theta_{3an}) &= A(\sigma_n) (\cos \sigma_n t \cos \theta_{3an} + \sin \sigma_n t \sin \theta_{3an}) \\ &= A c_n \cos \sigma_n t + A s_n \sin \sigma_n t \end{aligned} \quad (2.70-1)$$

$$\begin{aligned} B(\sigma_n) \cos(\sigma_n t - \theta_{3bn}) &= B(\sigma_n) (\cos \sigma_n t \cos \theta_{3bn} + \sin \sigma_n t \sin \theta_{3bn}) \\ &= B c_n \cos \sigma_n t + B s_n \sin \sigma_n t \end{aligned} \quad (2.70-2)$$

where

$$A c_n = A(\sigma_n) \cos \theta_{3an}, \quad A s_n = A(\sigma_n) \sin \theta_{3an}, \quad (2.71-1)$$

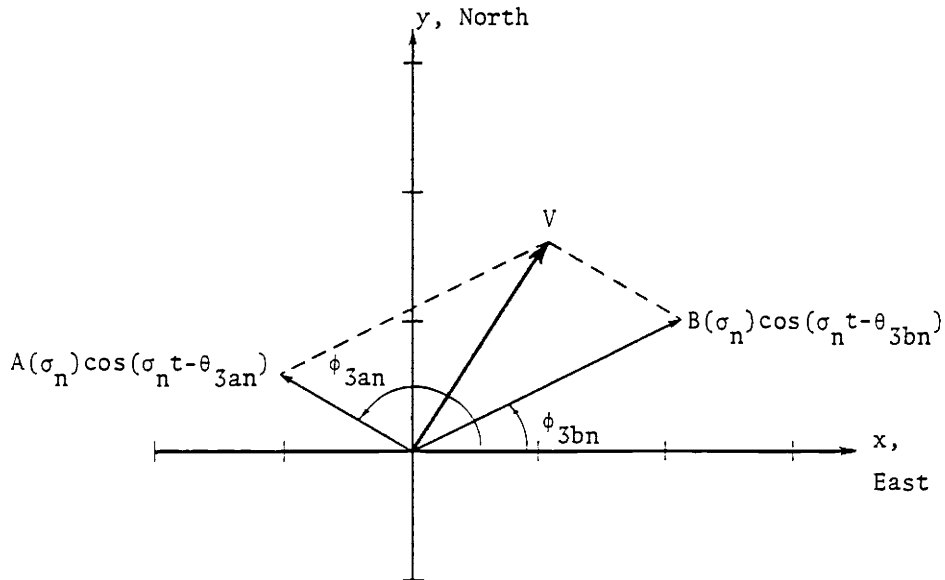


FIG. 2.10 Directional velocity components

$$Bc_n = B(\sigma_n) \cos \theta_{3bn}, \quad Bs_n = B(\sigma_n) \sin \theta_{3bn}, \quad (2.71-2)$$

are unknown constants.

The Fourier transform of velocity components $u(t)$ and $v(t)$ yields coefficients a_{un} and a_{vn} corresponding to the $\cos(\sigma_n t)$ transform, while b_{un} and b_{vn} correspond to a $\sin(\sigma_n t)$ transform. Thus, Eqs.(2.70-1,2) can be decomposed into x-axis and y-axis components with respect to directions ϕ_{3an} and ϕ_{3bn} , respectively, and equated to the coefficients a_{un} , a_{vn} , b_{un} , b_{vn} , of the corresponding $\cos(\sigma_n t)$ and $\sin(\sigma_n t)$ components. Four equations can be expressed as follows:

$\cos(\sigma_n t)$ component on x-axis:

$$a_{un} = Ac_n \cos \phi_{3an} + Bc_n \cos \phi_{3bn} \quad (2.72-1)$$

$\sin(\sigma_n t)$ component on x-axis:

$$b_{un} = A_s \cos \phi_{3an} + B_s \cos \phi_{3bn} \quad (2.72-2)$$

$\cos(\sigma_n t)$ component on y-axis:

$$a_{vn} = A_c \sin \phi_{3an} + B_c \sin \phi_{3bn} \quad (2.72-3)$$

$\sin(\sigma_n t)$ component on y-axis:

$$b_{vn} = A_s \sin \phi_{3an} + B_s \sin \phi_{3bn} \quad (2.72-4)$$

The Fourier transform of wave-induced dynamic pressure $p(t)$ yields the coefficient a_{pn} corresponding to a $\cos(\sigma_n t)$ transform, while b_{pn} corresponds to a $\sin(\sigma_n t)$ transform. Since pressure is a scalar, the amplitudes a_{pn} and b_{pn} can be simply transferred to orthogonal components of velocity, denoted as V_{an} and V_{bn} , at a height h_1 above bottom without considering wavelet direction. Thus, two more equations are obtained by equating the corresponding terms of velocity components expressed in Eqs. (2.70-1,2) to orthogonal velocity components obtained from pressure data, separated as coefficients of the $\cos(\sigma_n t)$ and $\sin(\sigma_n t)$ transformations.

$\cos(\sigma_n t)$ component:

$$V_{an} = a_{pn} K_n / K_{pn} = A_c \cos \phi_{3an} + B_c \cos \phi_{3bn}, \quad (2.72-5)$$

$\sin(\sigma_n t)$ component:

$$V_{bn} = b_{pn} K_n / K_{pn} = A_s \sin \phi_{3an} + B_s \sin \phi_{3bn}, \quad (2.72-6)$$

Therefore, at each frequency, we have six equations, Eqs. (2.72-1,2,3,4,5,6), with six unknown parameters, A_c , B_c , A_s , B_s , on the right hand side and known values on the left hand side. It is possible to solve the six equations simultaneously to obtain the amplitude, phase and direction of two wavelets at each frequency.

2.5.2 A Solution Procedure

With wave property measurements of $p(t)$, $u(t)$ and $v(t)$, one can solve two wavelets at each frequency with independent directions and phases as given by governing equations, Eqs.(2.72-1,2,3,4,5,6). In the stochastic/deterministic approach, there are also two wavelets defined in each frequency with independent directions but with established phases. This phase constraint may be a severe restriction in directional spectrum estimates. Therefore, Eqs.(2.72-1,2,3,4,5,6) represent a new, geometrically significant, method which is likely to yield improved directional spectrum estimates.

Solving six simultaneous equations can be a tedious, time consuming procedure. Some algebraic operations are performed on the equations in this section to provide a numerically efficient solution technique.

As a first step, $\cos\phi_{3an}$ and $\cos\phi_{3bn}$ can be expressed as follows, from Eqs.(2.72-1,2).

$$\cos\phi_{3an} = \frac{B_s a_{n un} - B_c b_{n un}}{B_s A_c - B_c A_s}, \quad \cos\phi_{3bn} = \frac{A_c b_{n un} - A_s a_{n un}}{B_s A_c - B_c A_s} \quad (2.73-1)$$

Similarly, $\sin\phi_{3an}$ and $\sin\phi_{3bn}$ can be derived as follows, from Eqs.(2.72-3,4)

$$\sin\phi_{3an} = \frac{B_s a_{n vn} - B_c b_{n vn}}{B_s A_c - B_c A_s}, \quad \sin\phi_{3bn} = \frac{A_c b_{n vn} - A_s a_{n vn}}{B_s A_c - B_c A_s} \quad (2.73-2)$$

Combining Eqs.(2.73-1) and (2.73-2) yields

$$(B_s a_{n un} - B_c b_{n un})^2 + (B_s a_{n vn} - B_c b_{n vn})^2 = (B_s A_c - B_c A_s)^2 \quad (2.74)$$

Then, subtracting the square of Eq.(2.72-5) from the sum of the squares of Eq.(2.72-1) and Eq.(2.72-3) yields

$$a_{un}^2 + a_{vn}^2 - V_{an}^2 = 2A_c B_c \cos(\phi_{3an} - \phi_{3bn}) \quad (2.75-1)$$

Similarly, the same procedure can be applied to Eqs.(2.72-2,4,6).

$$b_{un}^2 + b_{vn}^2 - V_{bn}^2 = 2A_{sn} B_{sn} \cos(\phi_{3an} - \phi_{3bn}) \quad (2.75-2)$$

Dividing Eq.(2.75-1) by Eq.(2.75-2) yields

$$\frac{a_{un}^2 + a_{vn}^2 - V_{an}^2}{b_{un}^2 + b_{vn}^2 - V_{bn}^2} = \frac{A_{cn} B_{cn}}{A_{sn} B_{sn}} \quad (2.75-3)$$

Now, two parameters, X_{an} and X_{bn} , are defined by the following expressions, according to Eqs.(2.72-5,6).

$$A_{cn} = \frac{1}{2}(V_{an} + X_{an}), \quad B_{cn} = \frac{1}{2}(V_{an} - X_{an}) \quad (2.76-1)$$

$$A_{sn} = \frac{1}{2}(V_{bn} + X_{bn}), \quad B_{sn} = \frac{1}{2}(V_{bn} - X_{bn}) \quad (2.76-2)$$

Substituting Eqs.(2.76-1,2) into Eqs.(2.74) and (2.75-3), respectively, yields two equations with two unknowns, X_{an} and X_{bn} .

$$\begin{aligned} & [(V_{bn} - X_{bn})a_{un} - (V_{an} - X_{an})b_{un}]^2 + [(V_{bn} - X_{bn})a_{vn} - (V_{an} - X_{an})b_{vn}]^2 \\ &= [V_{bn}X_{an} - V_{an}X_{bn}]^2 \end{aligned} \quad (2.77-1)$$

$$\frac{a_{un}^2 + a_{vn}^2 - V_{an}^2}{b_{un}^2 + b_{vn}^2 - V_{bn}^2} = \frac{V_{an}^2 - X_{an}^2}{V_{bn}^2 - X_{bn}^2} \quad (2.77-2)$$

Then, the parameters X_{an} and X_{bn} are solved as

$$|X_{an}| = \sqrt{\frac{(a_{un}^2 + a_{vn}^2)(P_n + Q_n) - V_{an}^2 R_n}{P_n + Q_n - R_n}} \quad (2.77-3)$$

$$|X_{bn}| = \sqrt{\frac{(b_{un}^2 + b_{vn}^2)(P_n + Q_n) - V_{bn}^2 R_n}{P_n + Q_n - R_n}} \quad (2.77-4)$$

where

$$P_n = (a_{un} V_{bn} - b_{un} V_{an})^2, \quad Q_n = (a_{vn} V_{bn} - b_{vn} V_{an})^2, \quad R_n = (a_{un} b_{vn} - a_{vn} b_{un})^2 \quad (2.77-5)$$

The correct sign of X_{an} and X_{bn} is determined as follows. Two solutions may be obtained from

$$Ac_n = \frac{1}{2}(V_{an} + |X_{an}|), \quad Bc_n = \frac{1}{2}(V_{an} - |X_{an}|) \quad (2.78-1)$$

$$As_n = \frac{1}{2}(V_{bn} + |X_{bn}|), \quad Bs_n = \frac{1}{2}(V_{bn} - |X_{bn}|) \quad (2.78-2)$$

Two more solutions can be obtained by changing the sign simultaneously in Eq.(2.78-1). However, these are equivalent to the above two solutions since the two wavelets are a priori unknown. Now, only one exact solution is possible from Eqs.(2.78-1,2). Each solution from Eqs.(2.78-1,2) is used to compute sine and cosine angles in Eqs.(2.73-1,2) and, hence, regress a_{un} , b_{un} , a_{vn} , b_{vn} in Eqs.(2.72-1,2,3,4). The correct solution should be able to return the original known values of a_{un} , b_{un} , a_{vn} , b_{vn} . The other does not.

Finally, the amplitudes, directions and phases of two independent wavelets of frequency σ_n can be expressed as

$$a_{3n} = \frac{A(\sigma_n)}{K_n} = \frac{1}{K_n} \sqrt{Ac_n^2 + As_n^2}, \quad b_{3n} = \frac{B(\sigma_n)}{K_n} = \frac{1}{K_n} \sqrt{Bc_n^2 + Bs_n^2} \quad (2.79-1)$$

$$\theta_{3an} = \tan^{-1} \left(\frac{As_n}{Ac_n} \right), \quad \theta_{3bn} = \tan^{-1} \left(\frac{Bs_n}{Bc_n} \right) \quad (2.79-2)$$

$$\phi_{3an} = \tan^{-1} \frac{[(Bs_n a_{vn} - Bc_n b_{vn})/U_n]}{[(Bs_n a_{un} - Bc_n b_{un})/U_n]} \quad (2.79-3)$$

$$\phi_{3bn} = \tan^{-1} \frac{[(Ac_n b_{vn} - As_n a_{vn})/U_n]}{[(Ac_n b_{un} - As_n a_{un})/U_n]} \quad (2.79-4)$$

where $U_n = Bs_n Ac_n - Bc_n As_n$; U_n is used to maintain the correct direction

estimates in Eqs.(2.79-3,4). Note that Eqs.(2.79-3,4) are derived from Eqs.(2.73-1,2) and U_n is the denominator in those equations presented in Eqs.(2.79-3,4).

The amplitudes obtained from Eq.(2.79-1) are always positive since $A(\sigma_n)$ and $B(\sigma_n)$ have been defined as positive values in Eq.(2.79-1). Negative signs in A_{cn} , B_{cn} , A_{sn} , B_{sn} , are included in phase values to maintain positive amplitudes. To check the values in the radicals of Eqs.(2.77-3,4), one may substitute Eqs.(2.72-1,2,3,4,5,6) into Eqs.(2.77-3,4), and obtain

$$|X_{an}| = \sqrt{\frac{S_n (A_{cn} - B_{cn})^2}{S_n}} = |A_{cn} - B_{cn}| \quad (2.80-1)$$

$$|X_{bn}| = \sqrt{\frac{S_n (A_{sn} - B_{sn})^2}{S_n}} = |A_{sn} - B_{sn}| \quad (2.80-2)$$

where

$$S_n = A^2(\sigma_n) B^2(\sigma_n) \sin^2(\theta_{3an} - \theta_{3bn}) [1 + \cos(\phi_{3an} - \phi_{3bn})]^2 \quad (2.80-3)$$

The frequency dependent Fourier coefficients, A_{on} , A_{1n} , B_{1n} , A_{2n} , B_{2n} , can be approximated by summing the appropriate wavelet properties in Eqs.(2.57-1,2,3,4,5), in accordance with the deterministic approach. Directional wave property analysis then proceeds as discussed in section 2.3.3. It should be noted that the one angle mode solution for the geometric approach is more appropriate than the double angle mode solution. Wavelets are obtained from the geometric approach utilizing both pressure and velocity data. It follows that the one angle mode solution, which also utilizes both pressure and velocity information, should provide an analytically consistent method of resolving the direction properties of the geometric wave energy distribution.

2.6 Discussion and Comparison of Alternative Methods

In the Section 2.5.2, the unconstrained wavelet phase relationship

has distinguished the geometric approach from the stochastic/deterministic approach. In this section, however, the differences among individual methods will be investigated from various other point of views including both theory and application. The central points included in this discussion are: (1) the one-dimensional frequency spectrum estimators, (2) the theoretical basis of the methods, and (3) the ability to predict the water surface elevation and its subsurface kinematics.

The one-dimensional frequency spectrum estimate in the geometric approach can be simply evaluated from the water surface wavelet amplitudes.

$$E_{3n} = E_{3an} + E_{3bn} = \frac{1}{2}(a_{3nn}^2 + b_{3nn}^2) / \Delta\sigma = \frac{1}{2K_n^2} [A^2(\sigma_n) + B^2(\sigma_n)] / \Delta\sigma \quad (2.81)$$

The geometric approach one-dimensional spectrum estimate, Eq.(2.81), is compared with various other frequency spectrum estimates as follows, by expressing the latter, summarized in Section 2.4.3, in terms of the geometric approach parameters $A(\sigma_n)$, $B(\sigma_n)$, ϕ_{3an} , ϕ_{3bn} , θ_{3an} , and θ_{3bn} . The pressure data frequency spectrum in Eq.(2.66-1) becomes

$$\begin{aligned} E_{0n} &= \frac{1}{2K_{pn}^2 \Delta\sigma} (a_{pn}^2 + b_{pn}^2) = \frac{1}{2K_n^2 \Delta\sigma} (V_{an}^2 + V_{bn}^2) \\ &= \frac{1}{2K_n^2 \Delta\sigma} [A^2(\sigma_n) + B^2(\sigma_n) + 2A(\sigma_n)B(\sigma_n)\cos(\theta_{3an} - \theta_{3bn})] \end{aligned} \quad (2.82-1)$$

The stochastic/deterministic approach one angle mode frequency spectrum in Eq.(2.66-2) becomes

$$\begin{aligned} E_{1n} &= \frac{1}{2K_n^2 \Delta\sigma} (|V_{an}| \sqrt{a_{un}^2 + a_{vn}^2} + |V_{bn}| \sqrt{b_{un}^2 + b_{vn}^2}) \\ &= \frac{1}{2K_n^2 \Delta\sigma} \{ [A_n^2 \cos^2 \theta_{3an} + 2A_n B_n \cos \theta_{3an} \cos \theta_{3bn} + B_n^2 \cos^2 \theta_{3bn}] \cdot \\ &\quad [A_n^2 \cos^2 \theta_{3an} + B_n^2 \cos^2 \theta_{3bn} + 2A_n B_n \cos \theta_{3an} \cos \theta_{3bn} \cos(\phi_{3an} - \phi_{3bn})] \}^{\frac{1}{2}} \end{aligned}$$

$$\frac{1}{2K_n^2 \Delta \sigma} \{ [A_n^2 \sin^2 \theta_{3an} + 2A_n B_n \sin \theta_{3an} \sin \theta_{3bn} + B_n^2 \sin^2 \theta_{3bn}] \cdot$$

$$[A_n^2 \sin^2 \theta_{3an} + B_n^2 \sin^2 \theta_{3bn} + 2A_n B_n \sin \theta_{3an} \sin \theta_{3bn} \cos(\phi_{3an} - \phi_{3bn})] \}^{\frac{1}{2}}$$

(2.82-2)

The frequency spectrum, E_{1n} , is an intermediate value between E_{0n} and E_{2n} as derived in Eqs.(2.66-1,3). The stochastic/deterministic approach double angle mode frequency spectrum in Eq.(2.66-3) becomes

$$E_{2n} = \frac{1}{2K_n^2 \Delta \sigma} (a_{un}^2 + a_{vn}^2 + b_{un}^2 + b_{vn}^2)$$

$$= \frac{1}{2K_n^2 \Delta \sigma} [A_n^2(\sigma_n) + B_n^2(\sigma_n) + 2A_n(\sigma_n)B_n(\sigma_n) \cos(\theta_{3an} - \theta_{3bn}) \cos(\phi_{3an} - \phi_{3bn})]$$

(2.82-3)

In general, E_{0n} is not equal to E_{2n} or E_{1n} , which is indicated in Eqs.(2.82-1,2,3). However, this is in conflict with the concept that the one-dimensional frequency spectrum of water surface waves should be unique whether it is estimated from pressure or velocity data, or both wave property data. Also Eqs.(2.82-1,2,3) show that the phase differential, $\theta_{3an} - \theta_{3bn}$, has been included in the frequency spectrum estimates, E_{0n} , E_{1n} , E_{2n} , and the direction differential, $\phi_{3an} - \phi_{3bn}$, has been included in the frequency spectrum estimates, E_{1n} and E_{2n} . But from a spectral point of view, neither wave phase nor wave direction should appear in the one-dimensional frequency spectrum estimates. A unique one-dimensional frequency spectrum estimate, E_{3n} , is obtained from the geometric method and is independent to wavelet direction and phase. To interpret this condition more explicitly, if only two waves of the same frequency are propagating on the water surface with different directions and phases, the correct frequency spectrum estimate will be provided by the geometric approach, not the stochastic/deterministic approach. Therefore, the procedure of estimating the frequency spectrum in the stochastic/deterministic

approach, based on a direct Fourier transform of the auto-covariance functions of wave properties is not totally satisfactory. Note however that if $\theta_{3an} - \theta_{3bn} = 90^\circ$, as specified for the stochastic/deterministic approach, all frequency spectrum estimates in Eqs.(2.82-1,3) and (2.81) are identical. Since θ_{3an} and θ_{3bn} which are solved from the geometric method do not present this phase relation, $\theta_{3an} - \theta_{3bn} = 90^\circ$, in general, the geometric approach would be desirable in estimating the frequency spectrum of water surface waves.

Also note that if all wavelets are propagating in the same direction, i.e., for the one-dimensional waves, we will have $a_{vn} = b_{vn} = 0$ and $\phi_{3an} = \phi_{3bn}$ in the geometric method, $\phi_{an} = \phi_{bn}$ in the stochastic/deterministic method. Therefore, $V_{an} = a_{un}$ and $V_{bn} = b_{un}$ from Eqs.(2.72-1,2,3,4,5,6). Note that we assume $\phi_{3an} = \phi_{3bn} = \phi_{an} = \phi_{bn} = 0^\circ$. Two results can be solved from the geometric method. One solution shows that $B(\sigma_n) = 0$, $A^2(\sigma_n) = a_{un}^2 + b_{un}^2$, and $\theta_{3an} = \tan^{-1}(b_{un}/a_{un})$. Another solution shows that $A(\sigma_n) = a_{un}$, $B(\sigma_n) = b_{un}$, $\theta_{3an} = \theta_{an} = 0^\circ$ and $\theta_{3bn} = \theta_{bn} = 90^\circ$, where θ_{an} and θ_{bn} denote the phases of two wavelets at a frequency σ_n in the stochastic/deterministic approach. Essentially, the two results are theoretically equivalent and deduce that $E_{0n} = E_{1n} = E_{2n} = E_{3n}$ for one-dimensional waves.

The theoretical similarity between the geometric and deterministic approaches is that they are, in fact, satisfying the simultaneous equations of measured wave properties. In the deterministic approach, three, complex number, fundamental equations are equivalent to six, real number, equations. In the geometric approach, the theory also solves six, real number, simultaneous equations. These fundamental equations are somewhat similar when comparing methods. Actually, the Fourier transform of wave property records on the left hand side of these equations are identical. However, the relationships specified on the right hand side of these equations are not the same for both methods. The solution is over specified in the deterministic approach because only two unknown amplitudes and directions are sought. In the geometric approach, two wavelet amplitudes, two directions and two phases are the unknown parameters in six equations. Thus, the geometric approach seeks a unique solution.

A further advantage of the geometric approach is evident if one has additional measured wave properties. Then, one may solve for more than two wavelets with their respective directions and phases at each frequency and present a closer approximation to the actual directional wave energy distribution. In the stochastic/deterministic approach, one will always obtain additional versions of the frequency spectrum with additional wave property measurements. The redistribution of wavelet amplitudes, or frequency spectra, for the error minimizing procedure will not necessarily provide an improved representation of the directional wave properties. For example, if one has more wave property measurements such as velocity gradients $u_x(t)$, $u_y(t)$ and $v_x(t)$, two additional wavelets can be solved at each frequency in the geometric approach, while five alternative representations of the water surface spectra can be estimated in the stochastic/deterministic approach.

Both the stochastic/deterministic and geometric approaches are capable of predicting the original measured wave properties. Example predictions from the stochastic/deterministic approach were expressed in Eqs.(2.51-1,2,3,4), where the water surface wavelet amplitudes can either be solved from the pressure data or from the one angle mode or double angle mode methods. The water surface elevation due to waves at sites adjacent to the point of measurement can be expressed from the geometric approach as

$$\eta(x,y,t) = \sum_{n=1}^{N/2} \{ a_{3n} \cos[k_n \cos(\phi_{3an})x + k_n \sin(\phi_{3an})y + \sigma_n t - \theta_{3an}] + b_{3n} \sin[k_n \cos(\phi_{3bn})x + k_n \sin(\phi_{3bn})y + \sigma_n t - \theta_{3bn}] \} \quad (2.83)$$

Predictions of subsurface kinematics and dynamics due to this predicted sea state can be obtained by simply transferring the surface wavelet information, i.e., the right hand side of Eq.(2.83), to subsurface wave properties. As a check, one may calculate the wave properties originally measured at the origin, $x=0$, $y=0$. The geometric approach has the ability to return the original measured, wave-induced data since the resolved water surface wavelets are exact solutions of simul-

taneous wave property measurements. However, the stochastic/deterministic approach has the ability to return only a portion of the original wave-induced data, depending on which wave property dominates the one-dimensional frequency spectrum estimate. For example, if the frequency spectrum is estimated from pressure data, the original measured pressure record can be exactly returned without error, but not the measured velocity components. If the frequency spectrum is estimated from velocity components, the original measured velocity components can be precisely returned, but not the pressure data. If the frequency spectrum is estimated from an average or a redistribution of the pressure and velocity data, neither the original measured pressure nor velocity component records can be precisely returned.

It is concluded that the geometric approach presents a good explanation of the theory and provides an appropriate one-dimensional frequency spectrum estimate. Moreover, the geometric approach can reproduce the original measured wave properties. Therefore, results from the geometric approach should provide reliable directional wave energy distribution information for directional spectrum estimates.

3. NUMERICAL MODELS

3.1 Introduction

Fourier analysis in spectral analysis presents a frequency response of a time series. The application of Fourier analysis implies a linear transformation. The validity of a spectral analysis utilizing Fourier analysis is dependent upon the existence of a linear system, which in time series terminology is said to be a stationary process. A property of a stationary process is that the covariance function of the time series is a function of lag only, not time. Therefore, the covariance functions of simultaneous wave properties derived in Section 2.3.2 have been theoretically defined as lag dependent functions.

A stochastic process may not be stationary. For the non-stationary process time series are characterized by random changes of frequencies, amplitudes and phases. Therefore, Fourier analysis which is based upon the assumption of fixed frequencies, amplitudes and phases is likely to break down when applied to non-stationary processes. Hence, when the spectrum estimate, namely the sample spectrum, is quantified for such a time series its behavior may be so erratic as to render it useless for estimation purposes. In order to overcome this non-stationary effect in spectral analysis, it is necessary to smooth the sample spectrum. This smoothing procedure produces the spectrum estimate, namely the smoothed spectrum, emphasizing the linear behavior of a time series from a statistical point of view. Hence, the smoothed spectrum provides a means of extracting the linear properties of a system, as if the time series were a stationary process (Jenkins and Watts, 1968).

In Chapter 2, theoretical analyses show that the spreading parameter and central angle are also functions of frequency. This implies that the spreading parameter and central angle are also affected by non-stationary processes. Therefore, a smoothing technique, different from that used to generate the sample spectrum, has been employed to evaluate the spreading parameter and central angle. The directional spectrum

obtained from the smoothed frequency spectrum and the smoothed spreading parameter and central angle is named the smoothed directional spectrum.

The utility of a smoothed directional spectrum representation can be enhanced measurably if the quantitative spectrum results can be briefly summarized in equation form. From the equation form, directional spectra can be simply reproduced and quickly applied to other research purposes. In this study, general models have been defined for the one-dimensional frequency spectrum, spreading parameter and central angle to represent the measured directional spectrum.

In the following sections of this chapter, both spectral smoothing and model building will be discussed for directional spectra. A pre-calculation of wave property time domain records will be described first. This will be followed by a summary of computer computational procedures.

3.2 Pre-calculations for Measured Wave Properties

Two methods are presented to analyze directional spectra; they are the stochastic/deterministic approach and the geometric approach. Computer algorithms of these two methods have been developed as part of this research effort, applying the theoretical results of Chapter 2. The algorithms used in both approaches are based upon a wavelet concept, i.e., Eqs.(2.68-1,2,3,4), (2.79-1,2,3,4) and (2.81). Therefore, the co-spectra are not evaluated in the stochastic/deterministic approach, although they can be efficiently computed by means of the Correlation theorem as demonstrated in Section 2.4.2.

Both algorithms require zero-mean input data of wave-induced dynamic pressure and horizontal orbital velocity components. However, the original recorded data are simultaneously measured, instantaneous pressure and horizontal velocity components. The mean current and hydrostatic pressure have been included in the measurements. Thus, a pre-calculation is necessary to process the original recorded data. The tasks included in this pre-calculation are: (1) evaluating the magnitude and

direction of the current, (2) estimating the water depth from the mean pressure, (3) calculating the zero-mean wave properties, (4) collecting some statistical values from time domain calculations, and (5) computing Fourier coefficients of each measured wave property.

Let $p_r(t_n)$, $u_r(t_n)$, $v_r(t_n)$ denote the original recorded pressure and horizontal velocity components, where the subscript n is the index of discrete time t_n . The mean current of the measured record is defined as

$$\bar{u} = \sum_{n=1}^N u_r(t_n)/N, \quad \bar{v} = \sum_{n=1}^N v_r(t_n)/N \quad (3.1)$$

$$V_c = \sqrt{(\bar{u})^2 + (\bar{v})^2} \quad (3.2)$$

$$\phi_c = \frac{\pi}{2} - \tan^{-1}\left(\frac{\bar{v}}{\bar{u}}\right) \quad (3.3)$$

where V_c , ϕ_c denote the magnitude and direction, respectively, of the mean current. Note that the final expression of direction in this research corresponds to the poles of the compass, i.e., 0° indicates north.

The water depth can be estimated from the mean pressure as

$$\bar{p} = \sum_{n=1}^N p_r(t_n)/N, \quad h = h_2 + \frac{\bar{p}}{\gamma_o} \quad (3.4)$$

where h_2 is the height of the pressure sensor above the sea floor, and γ_o is the specific weight of sea water. This water depth is compared with the depth measured by a sensor installed on the bottom of the research vessel.

The zero-mean dynamic pressure and horizontal orbital velocity components can be then obtained by subtracting the relative mean values from the original measurements. That is,

$$u(t_n) = u_r(t_n) - \bar{u}, \quad v(t_n) = v_r(t_n) - \bar{v}, \quad p(t_n) = p_r(t_n) - \bar{p} \quad (3.5)$$

The statistics of interest calculated in the time domain are the variance of the zero-mean horizontal velocity and the gross propagating direction of waves. The variance, or sample mean square value, of zero-mean horizontal velocity can be simply calculated as

$$\overline{V_t^2} = \sum_{n=1}^N [u^2(t_n) + v^2(t_n)]/N \quad (3.6)$$

where the subscript t indicates the sample variance, $\overline{V_t^2}$, computed in the time domain. The root mean square value of zero-mean horizontal velocity evaluated in frequency domain may not equal this value according to the results of the geometric approach. However, the double angle mode solution of the stochastic/deterministic approach can return precisely the sample variance, $\overline{V_t^2}$, from a frequency domain evaluation, since the frequency components are directly computed from Fourier transform of the time domain data. The latter can be simply proved from Eq. (2.56) by specifying that $i=V$ and $a_{Vn}^2 = a_{un}^2 + a_{vn}^2$, and $b_{Vn}^2 = b_{un}^2 + b_{vn}^2$.

The gross propagating direction of waves can be approximated as

$$\overline{\phi} = \frac{\pi}{2} - \frac{\sum_{n=1}^N V(t_n) \cdot \phi_n}{\sum_{n=1}^N V(t_n)} \quad (3.7-1)$$

where

$$V(t_n) = \sqrt{u^2(t_n) + v^2(t_n)}, \quad (3.7-2)$$

and

$$\phi_n = \begin{cases} \tan^{-1} \left[\frac{v(t_n)}{u(t_n)} \right] \\ \tan^{-1} \left[\frac{v(t_n)}{u(t_n)} \right] \pm \pi \end{cases} \quad (3.7-3)$$

The option in Eq. (3.7-3) is selected by estimating the gross main travel direction of waves e.g., towards the coastline.

The zero-mean time series in discrete form, Eq.(3.5), are satisfactory inputs for directional spectrum analysis utilizing either the stochastic/deterministic or geometric approach. Computer software included in this research is based on FORTRAN V. The Fast Fourier Transform technique employed here is based on the Cooley-Tukey procedure, requiring a number of data points equal to some power of two (Brighan, 1974); hence, $N=2^P$ (P is a positive integer). An elementary flow chart which presents the logical route of this pre-calculation software appears in Fig. 3.1.

3.3 Smoothing Procedures for Directional Spectrum Estimations

Random wave property measurements are not necessarily stationary processes, thus any linearly transformed frequency response of zero-mean wave properties needs to be smoothed. As a result, the one-dimensional frequency spectrum, spreading parameter and central angle require smoothing in directional spectrum analyses.

3.3.1 Smoothing Procedure for the One-dimensional Frequency Spectrum

A general class of smoothing techniques for one-dimensional frequency spectra has been developed by others (Jenkins and Watts, 1968). The idea of this smoothing procedure is to estimate the one-dimensional spectrum in sub-sections and to compute the total record spectrum from the mean of the spectra from the sub-sections. The total record length T is subdivided into J sections of length M and J spectra are averaged. However, an efficient and equivalent way to do this smoothing is to convolve the total sample spectrum with a function called the spectral window (Jenkins and Watts, 1968). A number of spectral windows are commonly used in spectral analysis but all have similar shape. The choice of a spectral window in the smoothing procedure is of secondary importance. A commonly used spectral window, the Bartlett window, is utilized and denoted as $Y(f)$ in this study. Note that $f=\sigma/(2\pi)$ the wave frequency with units 1/time. The wave frequency f is simply the reciprocal of wave period for a simple harmonic wave. The wave fre-

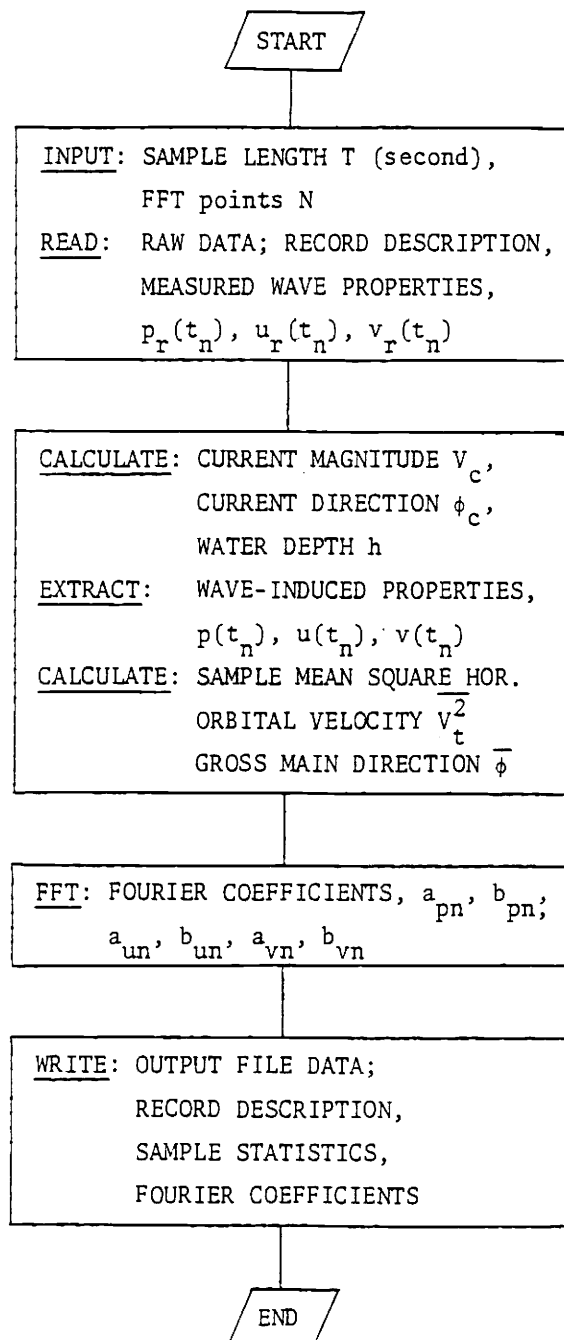


FIG. 3.1 Flow chart of pre-calculation system

quency used in the following discussion will be the frequency f instead of σ . Also, the wave frequency considered in results of spectrum estimates will be the frequency f instead of σ . This is because one can easily calculate the wave period for a specified wave frequency f in accordance with linear wave theory. Thus, we have

$$E(f_n) = \frac{1}{2}(a_n^2 + b_n^2) / \Delta f = 2\pi \left(\frac{1}{2}\right) (a_n^2 + b_n^2) / \Delta\sigma = 2\pi E(\sigma_n) \quad (3.8-1)$$

where

$$\Delta f = \frac{1}{T} = \frac{2\pi}{T} \left(\frac{1}{2\pi}\right) = \frac{\Delta\sigma}{2\pi} \quad (3.8-2)$$

The smoothing procedure for the one-dimensional frequency spectrum by means of Bartlett spectral window is

$$E(f) = \int_{-\infty}^{\infty} \hat{E}(f-f') Y(f') df' \quad (3.9)$$

where $E(f)$ denotes the smoothed spectrum, $\hat{E}(f)$ denotes the sample spectrum, and

$$Y(f) = M \left[\frac{\sin(\pi f M)}{\pi f M} \right]^2 \quad (3.10)$$

is the Bartlett spectral window (Jenkins and Watts, 1968). Equation (3.9) shows that the one-dimensional frequency spectrum is smoothed from the convolution of the sample spectrum and spectral window.

The Bartlett spectral window is plotted in Fig. 3.2 and is seen to be symmetric about the origin. The area under the curve of the spectral window is one, or

$$\int_{-\infty}^{\infty} Y(f) df = 1 \quad (3.11)$$

Therefore, the one-dimensional frequency spectrum is smoothed in an average sense. The total energy density of water surface waves will not change by this smoothing procedure.

The base width of the Bartlett window, that is, the distance between the first zeros on either side, is $2/M$ (Hz). By controlling the length M of the sub-sections, one can quantify the base width of the spectral window. There is no rigid rule for determining the number of sub-sections, J , or size M . Ideally, the larger the number of sub-sections and the larger the size M , the more accurate is the resulting spectrum estimate. Hence, T must be sufficiently large. Also, as M is large, the Bartlett spectral window behaves like an impulse function. However, the statistics of wave properties may change considerably during a long time period. Thus, one is compelled to choose an intermediate length T and size M . A general study of spectral smoothing suggests that the base width of the spectral window should be of the same order as the narrowest important detail in the spectrum. For example, in order to estimate the property of the spectral peak, the base width of the spectral window should be chosen to be of the same order as the width of the spectral peak (Jenkins and Watts, 1968).

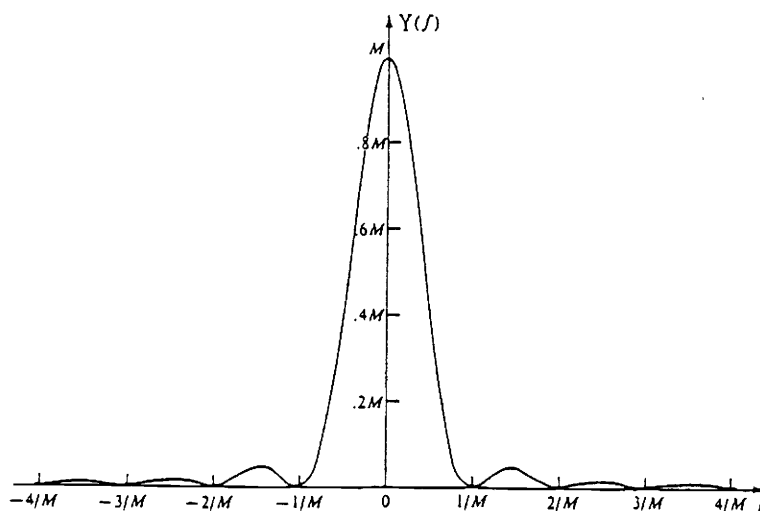


FIG. 3.2 Bartlett spectral window (Jenkins and Watts, 1968)

It will be shown later that a sample length of 512 seconds, digitized every second, satisfies the input requirement for spectral analy-

sis in this study. The base width of the spectral window has been chosen as .016 (Hz) for a sample length of 512 seconds and is assumed to present the narrowest detail required to cover the width of the spectral peak. Hence, the smoothing procedure is equivalent to subdividing the sample length of 512 seconds into four sub-sections of 128 seconds. Since the fundamental frequency interval is $1/T$, we have $(2/M)/(1/T)=2T/M=8$ fundamental intervals in a base width of .016 (Hz). The discrete convolution in Eq.(3.9) is then performed by products of the sample spectrum with seven weighted coefficients, which are normalized constants of the spectral window in the discrete formula. These seven weighted coefficients are: $1/36, 4/36, 8/36, 10/36, 8/36, 4/36, 1/36$.

3.3.2 Smoothing of the Spreading Parameter and Central Angle

The spreading parameter and central angle also require smoothing in order to remove irregularities due imperfect data sets and digital numerical procedures. Equations (2.39-4) and (2.40-4) reveal that the one angle and double angle mode spreading parameters are functions of C_1 and C_2 , respectively. Thus, the spreading parameter is smoothed by smoothing the coefficients C_1 and C_2 .

Instead of estimating $C_{1n}, C_{2n}, \phi_{o1n}, \phi_{o2n}$ at frequency f_n , as indicated in Eqs.(2.67-1,2,3,4) and (2.68-1,2,3,4), wavelets in the neighborhood of f_n are included in this smoothing procedure. That is, a wider frequency band is considered to yield the directional wave property estimates at the central frequency, f_n , of that band. Parameters $C_{1n}, C_{2n}, \phi_{o1n}, \phi_{o2n}$, are computed in a smooth, or local average, sense. The number of frequencies, denoted as I , involved in this wider band should be of the same order as the width of the narrowest important detail of frequency dependent directional wave properties. Then, Eqs.(2.67-1,2,3,4) are rewritten as

$$\sum_{i=n-I/2}^{n+I/2} \{E_{1an} \cos \phi_{an} + E_{1bn} \cos \phi_{bn}\}_i = C_{1n} \cos \phi_{o1n} \sum_{i=n-I/2}^{n+I/2} \{E_{1n}\}_i \quad (3.12-1)$$

$$\sum_{i=n-1/2}^{n+1/2} \{E_{1an} \sin\phi_{an} + E_{1bn} \sin\phi_{bn}\}_i = C_{1n} \sin\phi_{o1n} \sum_{i=n-1/2}^{n+1/2} \{E_{1n}\}_i \quad (3.12-2)$$

$$\sum_{i=n-1/2}^{n+1/2} \{E_{2an} \cos 2\phi_{an} + E_{2bn} \cos 2\phi_{bn}\}_i = C_{2n} \cos 2\phi_{o2n} \sum_{i=n-1/2}^{n+1/2} \{E_{2n}\}_i \quad (3.12-3)$$

$$\sum_{i=n-1/2}^{n+1/2} \{E_{2an} \sin 2\phi_{an} + E_{2bn} \sin 2\phi_{bn}\}_i = C_{2n} \sin 2\phi_{o2n} \sum_{i=n-1/2}^{n+1/2} \{E_{2n}\}_i \quad (3.12-4)$$

where the subscript n indicates the frequency f_n . In the geometric approach, E_{1an} and E_{2an} will be replaced by E_{3an} , and E_{1bn} , E_{2bn} will be replaced by E_{3bn} ; E_{1n} and E_{2n} will be replaced by E_{3n} , and ϕ_{an} , ϕ_{bn} will be replaced by ϕ_{3an} , ϕ_{3bn} , respectively. Note that the one-dimensional frequency spectra appearing on the right hand side of Eqs.(3.12-1,2,3,4) are the smoothed spectra. Thus, the wavelet energy densities appearing on the left hand side of Eqs.(3.12-1,2,3,4) are considered as smoothed energy densities, corrected by the ratio of the sample spectrum to the smoothed frequency spectrum at each frequency. In this research, $I=5$ has been chosen for a total sample length of 512 seconds. This is equivalent to smoothing the information from five adjacent wavelet pairs to obtain the smoothed spreading parameter and central angle for the central frequency in each band.

The smoothed directional wave spectrum is then evaluated in Eq.(2.37) with respect to a smoothed one-dimensional frequency spectrum, a smoothed spreading parameter and central angle at each frequency. The smoothed directional spectrum of other wave properties can be evaluated by simply transferring the smoothed frequency spectrum of water surface wave elevation to any other wave property.

3.4 Proposed Models for Directional Wave Spectra

In this study, the one-dimensional frequency spectrum, spreading parameter and central angle have been identified as frequency dependent variables which control the behavior of the direction spectrum. Therefore, proposing a model for the directional spectrum is equivalent to proposing models for the one-dimensional frequency spectrum, spreading parameter and central angle. Some general semi-empirical equations will be defined in the following sections.

3.4.1 JONSWAP Spectrum

The JONSWAP spectrum is selected to describe the frequency dependence of the one-dimensional frequency spectrum. The JONSWAP spectrum is known to cover a large range of spectral shapes (Hasselmann et al., 1975). The expression

$$E_J(f_n) = \frac{\alpha g^2}{(2\pi)^4 f_n^5} \gamma^\beta \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] \quad (3.13)$$

gives the general form of the JONSWAP spectrum, where

$$\beta = \exp\left[-\frac{(f_n - f_p)^2}{2\sigma_{LR}^2 f_p^2}\right]$$

$$\sigma_{LR} = \begin{cases} \sigma_L, & \text{for } f_n \leq f_p \\ \sigma_R, & \text{for } f_n > f_p \end{cases} \quad n = 1, 2, \dots, n_p, \dots, N/2$$

n_p = index of frequency at maximum $E(f_n)$

f_p = frequency at maximum $E(f_n)$

The parameters defined in the JONSWAP spectrum are: α the Phillips' constant, γ the ratio of the maximum spectral density of $E_J(f)$ to that of the corresponding Pierson-Moskowitz spectrum, σ_L and σ_R are constants proportional to the widths of the left and right sides of the spectral

peak. These parameters are evaluated via a least square error analysis using the measured, smoothed frequency spectrum. The derivation of this least square error analysis is presented in Appendix A.1.

The error of the proposed JONSWAP spectrum compared to the smoothed spectrum, $E(f_n)$, has been defined in a root mean square sense in this study as

$$\epsilon_{\text{rms},1-D} = \frac{\sqrt{\sum_{n=1}^N [E_J(f_n) - E(f_n)]^2}}{\sum_{n=1}^N E(f_n)} \quad (3.14)$$

Since $\epsilon_{\text{rms},1-D}$ presents a ratio of total root square error to total energy density, a small value of $\epsilon_{\text{rms},1-D}$ implies that the proposed JONSWAP spectrum is a good approximation to the measured, smoothed spectrum.

The statistical values collected from this proposed JONSWAP spectrum in the frequency domain are: total spectral density E_{total} , peak spectral density E_p , and dimensionless frequency $f_{1,-1}$ which is identical to $\sigma_{1,-1}$ defined in Eq.(2.43-2). This dimensionless frequency, $f_{1,-1}$, is relatively insensitive to slight changes in spectral shape. Since a slight change in spectral shape may cause a considerable change in the JONSWAP parameters, $f_{1,-1}$ may be viewed as an important indicator of spectral shapes.

3.4.2 Proposed Equations for the Spreading Parameter and Central Angle

In Section 2.3.3, a general description of the spreading parameter distribution identified a maximum value near the spectral peak frequency with decreasing values for larger or smaller frequencies. The frequency at which the maximum spreading parameter occurs is called the critical frequency in this study and denoted as f_c . The maximum spreading parameter is s_c . Usually f_c is smaller than f_p . The observed slow decrease in the spreading parameter on the right side of s_c occurs because high

frequency waves experience greater directional spreading due to cross currents and winds. The observed decreases in the spreading parameter on the left side of s_c occur because low frequency energy may be composed of many persistent long waves arriving from independent storm sources and unique directions.

Accordingly, the spreading parameter is represented on each side of s_c by unique, two parameter power functions of frequency as

$$s_e(f_n) = A_{LR} f_n^{B_{LR}} \quad (3.15)$$

where

$$(A_{LR}, B_{LR}) = \begin{cases} (A_L, B_L), & \text{for } f_n < f_c \\ (A_R, B_R), & \text{for } f_n > f_c \end{cases} \quad n = 1, 2, \dots, n_c, \dots, N/2$$

n_c = index of frequency at maximum $s(f_n)$

and $s_e(f_n)$ denotes the proposed empirical spreading parameter. This form of the equation is an extension of that suggested by Sand (1979), as presented in Eq.(2.43-1). The determination of A_{LR} and B_{LR} also utilizes a least square error analysis, which is presented in Appendix A.2.

Under some circumstances it may be appropriate to choose a constant value for the spreading parameter on the left side of s_c . It has been observed in many data sets of this study that the behavior of spreading parameter on the left side of f_c may be approximated by a constant $.8s_c$ for the stochastic/deterministic approach and a constant $.9s_c$ for the geometric approach. Hence, Eq.(3.15) becomes

$$s_e(f_n) = A_L = \begin{cases} .8 s_c, & \text{for stochastic/deterministic approach} \\ .9 s_c, & \text{for geometric approach} \end{cases}$$

$$B_L = 0, \quad \text{for } f_n < f_c \quad (3.16)$$

The two parameter power function is still utilized for the spreading parameter utilizing two power functions on each side of s_c and will be referred to as the two-sided spreading parameter model. The proposed spreading parameter utilizing a constant on the left side of s_c and a power function on the right side of s_c will be referred to as the one-sided spreading parameter model.

A third-order polynomial function of frequency,

$$\phi_{\text{poly}}(f_n) = c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3 \quad (3.17)$$

is proposed to model the central angle. This equation allows for a relative maximum or minimum in $\phi_o(f_n)$ as observed from many data sets associated with this study. Let $\phi_{\text{oe}}(f_n)$ denote the empirically proposed central angle function. Then

$$\phi_{\text{oe}}(f_n) = \phi_{\text{poly}}(f_n) \quad (3.18)$$

The coefficients c_0 , c_1 , c_2 , and c_3 , of Eq.(3.17) are determined by a least square error analysis, weighted with the frequency spectrum energy level appropriate to each frequency. The weighting procedure emphasizes central angle behavior near the spectral peak. A detailed presentation of this least square error analysis appears in Appendix A.3.

As a first approximation, a weighted main direction, defined as

$$\phi_{\text{main}} = \frac{\sum_{n=1}^N \phi_o(f_n) E(f_n)}{\sum_{n=1}^N E(f_n)} \quad (3.19)$$

may be employed to represent the directional spreading central angle. Then a constant value is proposed for the central angle function

$$\phi_{oe}(f_n) = \phi_{main} \quad (3.20)$$

The error associated with either empirical central angle function is evaluated as

$$\epsilon_{rms, \phi_o} = \sqrt{\frac{\sum_{n=1}^N [\phi_{oe}(f_n) - \phi_o(f_n)]^2 E(f_n)}{\sum_{n=1}^N E(f_n)}} \quad (3.21)$$

Both Eqs. (3.17) and (3.19) are utilized for the empirical central angle function in the data analysis.

3.5 Systematic Analysis of the Estimated Directional Spectrum

An estimation of the smoothed directional spectrum is based upon Eq. (2.37) utilizing three smoothed frequency dependent functions: the one-dimensional spectrum, the spreading parameter and central angle. In a discrete formula, this smoothed directional spectrum can be expressed as

$$E(f_n, \phi_m) = E(f_n) \frac{2^{2s(f_n)-1} \Gamma^2[s(f_n)+1]}{\pi \Gamma[2s(f_n)+1]} \cos^{2s(f_n)} \left[\frac{\phi_m - \phi_o(f_n)}{2} \right] \quad (3.22)$$

where

$$f_n = n\Delta f, \quad n=1, 2, \dots, N'$$

$$\phi_m = m\Delta\phi, \quad m=1, 2, \dots, M'$$

The frequency interval, $\Delta f = 1/T$, has been referred as the fundamental frequency in Finite Fourier Transformation procedures. The direction interval, $\Delta\phi$, has been chosen as 1° or $2\pi/360$ radians in data analysis in this study. M' and N' (both integers) are the total number of discrete directions and frequencies, respectively, which are uniformly

spaced on the direction and frequency axes.

In general, the integer N' has a maximum value of $N/2$ where N is the total number of data points on the wave property record utilized in the Fourier transformation. The spectral density can be computed up to a frequency of $N'\Delta f$, where N' is less than $N/2$, if the spectral density of higher frequencies is not of interest. As a practical consideration, an upper limit should be set for N' to avoid high frequency signals from sources other than surface waves. For example, with a measurement system installed near the ocean bottom, the Fourier coefficients associated with high frequencies should be ignored because these high frequency components may be caused by turbulence and electronic or mechanical noise rather than water surface waves. Accordingly, spectral density analysis should be truncated at the deep-water wave frequency (Ippen, 1966) for wave sensors located at the sea bed.

The deep-water wave is usually defined in ocean engineering as

$$\tanh(kh) > 0.9962, \text{ or } kh > \pi$$

Hence, substituting this relation into the linear wave theory dispersion equation, Eq.(2.2), yields

$$(2\pi f)^2 = gk \cdot \tanh(kh) = gk > g \frac{\pi}{h}, \text{ or } f > \sqrt{\frac{g}{4\pi h}}$$

Then

$$f_{N'} = N' \Delta f = \sqrt{\frac{g}{4\pi h}} \tag{3.23}$$

is interpreted as the upper limit of frequencies considered in wave spectrum analysis. At this frequency, $f_{N'}$, the sea bed is exposed to less than 9% of the water surface wave motion. This may be demonstrated by evaluating $p(t)$ and $V(t)$ at the sea surface and sea bed in Eqs.(2.8-2,3) with $kh = \pi$. It is concluded that $f_{N'}$ is a function of h . For $h = 60$ (ft), $f_{N'} = .2$ (Hz); for $h = 200$ (ft), $f_{N'} = .11$ (Hz). Ocean waves often

reveal significant energy levels near 0.1 (Hz). In order to sense this wave motion at the sea bed the wave measurement system should be located in a water depth less than 250 feet.

Linear wave theory can be used to demonstrate that deep water breaking waves are limited to high frequency spectral densities which are proportional to the inverse fifth power of frequency. That is (Roll and Fischer, 1956) $E(f) \propto f^{-5}$ at high frequencies. As a result, beyond the frequency f_N , spectral densities and, therefore, wave amplitudes rapidly attenuate with increasing frequency. Thus, it is reasonable not to include these high frequency spectral densities in wave spectrum estimates.

Summarizing, the proposed directional spectrum is based on Eq.(2.37) and is expressed in discrete form as

$$E_e(f_n, \phi_m) = E_J(f_n) \frac{2^{2s_e(f_n)-1} \Gamma^2[s_e(f_n)+1]}{\pi \Gamma[2s_e(f_n)+1]} \cos^{2s_e(f_n)} \left[\frac{\phi_m - \phi_{oe}(f_n)}{2} \right] \quad (3.24)$$

where

$$f_n = n\Delta f, \quad n=1, 2, \dots, N'$$

$$\phi_m = m\Delta\phi, \quad m=1, 2, \dots, M'$$

N' is defined by Eq.(3.23),

M' is limited in this study to 360, or $\Delta\phi=1^\circ$,

$E_J(f_n)$ is defined by Eq.(3.13)

$s_e(f_n)$ is defined by Eq.(3.15)

$\phi_{oe}(f_n)$ is defined by Eq.(3.18) or (3.20).

However, N' has no limitation in applications of this model since one can extrapolate directional spectrum from the proposed functions, $E_j(f_n)$, $s_e(f_n)$ and $\phi_{oe}(f_n)$, outside the range indicated by Eq.(3.23). Finally, the root mean square error between the proposed empirical directional spectrum and smoothed directional spectrum is defined as

$$\epsilon_{\text{rms}, 2-D} = \frac{\sqrt{\sum_{n=1}^{N'} \sum_{m=1}^{M'} [E_e(f_n, \phi_m) - E(f_n, \phi_m)]^2}}{\sum_{n=1}^{N'} \sum_{m=1}^{M'} E(f_n, \phi_m)} \quad (3.25)$$

The statistical values collected from this proposed directional spectrum are total spectral energy, dominant frequency and direction at the spectral peak and magnitude of the spectral peak. A flow chart summarizing directional spectrum calculation in this study appears in Fig. 3.3. A computer listing of the program used to perform these digital calculation is presented in Appendix C.

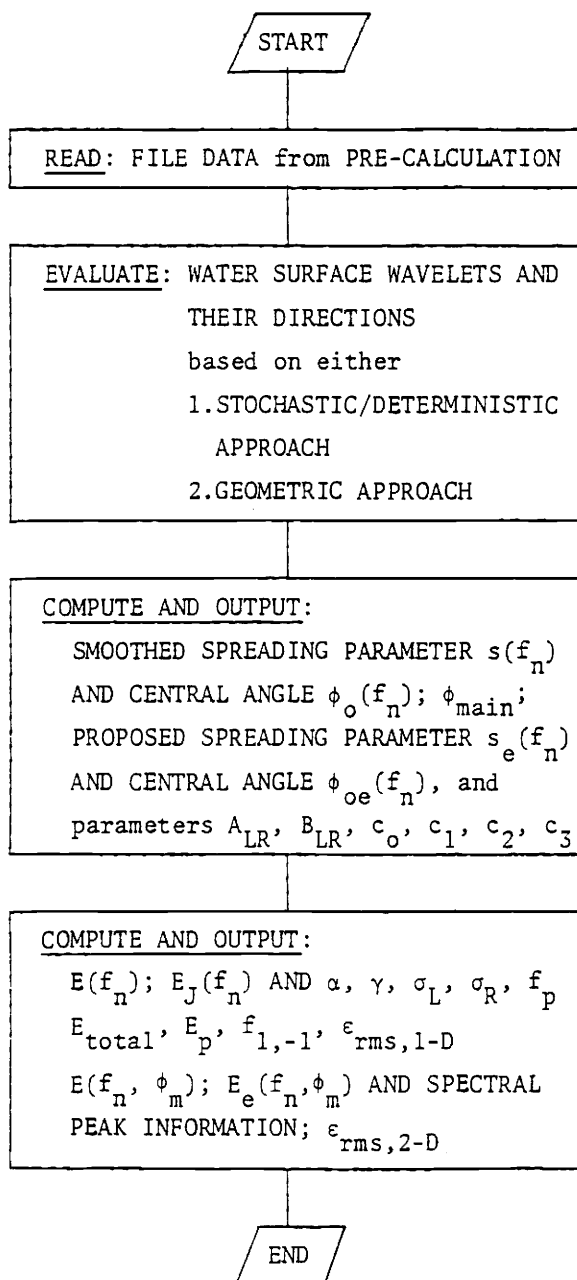


FIG. 3.3 Flow chart of directional wave spectrum estimates

4. DATA ANALYSIS

4.1 Introduction

This chapter contains a summary of numerical results of analyzed data from offshore Coos Bay, Oregon. Alternative solution methods are examined and evaluated. In Section 4.2, seasonal samples of wave properties are interpreted and a Kolmogorov-Smirnov goodness of fit test is introduced to characterize the statistical behavior of seasonal unsteady current measurements. In Section 4.3, a standard sample length is selected to provide reproducible directional spectrum results. In Section 4.4, the validity of the data collecting system is checked by analyzing simultaneously recorded samples from different depths at the same horizontal location. The resulting directional wave properties are compared with respect to the applied method. Also, directional wave properties evaluated in the time domain are compared with related properties evaluated in the frequency domain. Since wave spectra with high energy content are usually of interest in analyzing wave property behavior, significant data sets of samples which contain high wave energy are selected from the seasonal measurements. Graphical outputs of directional spectra are available from our computational system; example illustrations of real ocean data are presented. Tabular summaries of directional wave properties obtained from the geometric approach are presented for significant seasonal data sets. Seasonal variations in directional spectrum behavior are discussed. Section 4.5 is a parametric study of the proposed empirical equation coefficients. A correlation study is conducted, comparing the coefficient of the spreading parameter power function to the total energy integrated over all frequencies and directions. Section 4.6 discusses directional wave simulation. A wave simulation method is presented. Directional wave spectrum properties solved from a simulated wave sample are compared to known directional wave spectrum properties.

4.2 Seasonal Behavior of Measured Samples

Real ocean data have been measured from offshore Coos Bay, Oregon, area for this research project during August 1982, October 1982 and March 1983. Recorded data include instantaneous measurements of pressure and magnetic east and north water particle velocity components. Burst sampling, Neil Brown, Inc., acoustic current meters were employed for wave property measurements. The meters were located near the sea floor at sites with water depths ranging from 60 feet to 200 feet. Wave property samples were collected every four hours with sample durations of 8.55 or 17.1 minutes, and sample rates of one record per second. A tabular summary of sample length, total samples measured each season, approximate depth of measurement site, meter identification number, and seasonal mean square velocity, is presented in Table 4.1.

TABLE 4.1 Summary of measured wave property samples

Month, Year	Depth (ft)	Meter No.	Sample Length (sec)	Total samples v	$\overline{v_{rms}^2}$ (ft/s) ²
August, 1982	183	24	512	76	.017 ±.014
October, 1982	192	43*	1024	11	.052 ±.039
October, 1982	192	25	512	70	.082 ±.075
March, 1983	60	26	512	55	1.21 ±.554

* The current sensor on meter number 43 is located 14' above the sea bottom; all other current sensors are located 4.3' above the sea bottom. The pressure sensor is located 3.4' above the current sensor on all meters. Due to electronic problems with meter 43 during October 1982, only 11 error free samples were recorded.

The seasonal mean square value of wave-induced horizontal velocity, $\overline{V_{rms}^2}$, is defined as

$$\overline{V_{rms}^2} = \frac{1}{v} \sum_{i=1}^v (V_{rms}^2)_i = \frac{1}{v} \sum_{i=1}^v (\overline{V_t^2})_i = \frac{1}{vN} \sum_{i=1}^v \sum_{n=1}^N [u^2(t_n) + v^2(t_n)]_i \quad (4.1)$$

where

$$(V_{rms})_i = (\overline{V_t^2})_i^{\frac{1}{2}} \quad (4.2)$$

The index i indicates the i 'th sample in a total v samples per season, and $\overline{V_t^2}$ has been defined in Eq.(3.6). The mean square velocity quantifies the relative magnitude of unsteady currents.

Wave-induced current properties are of primary interest in this study. Consequently, the behavior of the root mean square velocity is analyzed first. Many previous random wave studies have demonstrated that the Rayleigh distribution function is a satisfactory model for representing the probability distribution of wave height (Kinsman, 1965). It is reasoned in this study that the root mean square velocity is proportional to the root mean square water surface elevation and that both of these quantities are proportional to the mean wave height. Thus, it is hypothesized that a Rayleigh distribution can be used to represent the probability distribution of V_{rms} . The Rayleigh distribution function of V_{rms} can be expressed as

$$PDF(V_{rms}) = \frac{2V_{rms}}{V_{rms}^2} \exp\left(-\frac{V_{rms}^2}{V_{rms}^2}\right) = \frac{2V_{rms}}{V_{RMS}^2} \exp\left[-\left(\frac{V_{rms}}{V_{RMS}}\right)^2\right] \quad (4.3-1)$$

where $V_{RMS} = (\overline{V_{rms}^2})^{\frac{1}{2}}$, the root mean square value of V_{rms} , and $PDF(V_{rms})$ is the probability distribution function of V_{rms} . Now the hypothesis is examined using the Kolmogorov-Smirnov goodness of fit test, and samples in each season are regarded as a population in the test (Benjamin and Cornell, 1970). The Kolmogorov-Smirnov test is simply a comparison between the quantity

$$\begin{aligned}
 X_{\max} &= \text{maximum } |X_i| \\
 &= \text{maximum } |\text{observed cumulative distribution function} \\
 &\quad - \text{hypothesized cumulative distribution function}|_i
 \end{aligned}$$

and

$$Y(v) = \begin{cases} 1.22/\sqrt{v}, & \alpha=0.1 \\ 1.36/\sqrt{v}, & \alpha=0.05 \\ 1.63/\sqrt{v}, & \alpha=0.01 \end{cases}$$

where v is the population of sample in test, and $Y(v)$ is a $100(1-\alpha)\%$ confidence interval for X_i . If $X_{\max} < Y(v)$ for a particular α , the hypothesis is accepted by the test in a $100(1-\alpha)\%$ confidence interval. Otherwise, the hypotheses is rejected by the test.

The cumulative distribution function of PDF(V_{rms}) is

$$\text{CDF}(V_{\text{rms}}) = \int_0^{V_{\text{rms}}} \text{PDF}(V_{\text{rms}}) dV_{\text{rms}} = 1 - \exp\left[-\left(\frac{V_{\text{rms}}}{V_{\text{RMS}}}\right)^2\right] \quad (4.3-2)$$

which is plotted versus the dimensionless parameter $V_{\text{rms}}/V_{\text{RMS}}$ in Fig. 4.1 as a continuous curve. The empirical cumulative probability distribution of V_{rms} is then computed for samples in each season. Samples of August 1982, October 1982 (meter 25), and March 1983, are included in the test. Samples of October 1982, measured by meter 43, are not included in the test because of the limited sample population (only 11 samples). Thus, three empirical cumulative distribution curves are obtained and are plotted in Fig. 4.1. One may conclude from Fig. 4.1 that all three empirical curves are closely related to the hypothesized curve. The performance of Kolmogorov-Smirnov test indicates that the hypothesis is accepted for all three empirical curves at $\alpha=0.05$. Hence, the root mean square velocity data are modeled by the Rayleigh probability distribution function within a 95% confidence interval. The 95% confidence intervals in the test for each season's empirical curves are also indicated in Fig. 4.1. This analysis suggests that extreme seasonal wave conditions could be extrapolated by interpreting sample data with the

Rayleigh probability distribution function.

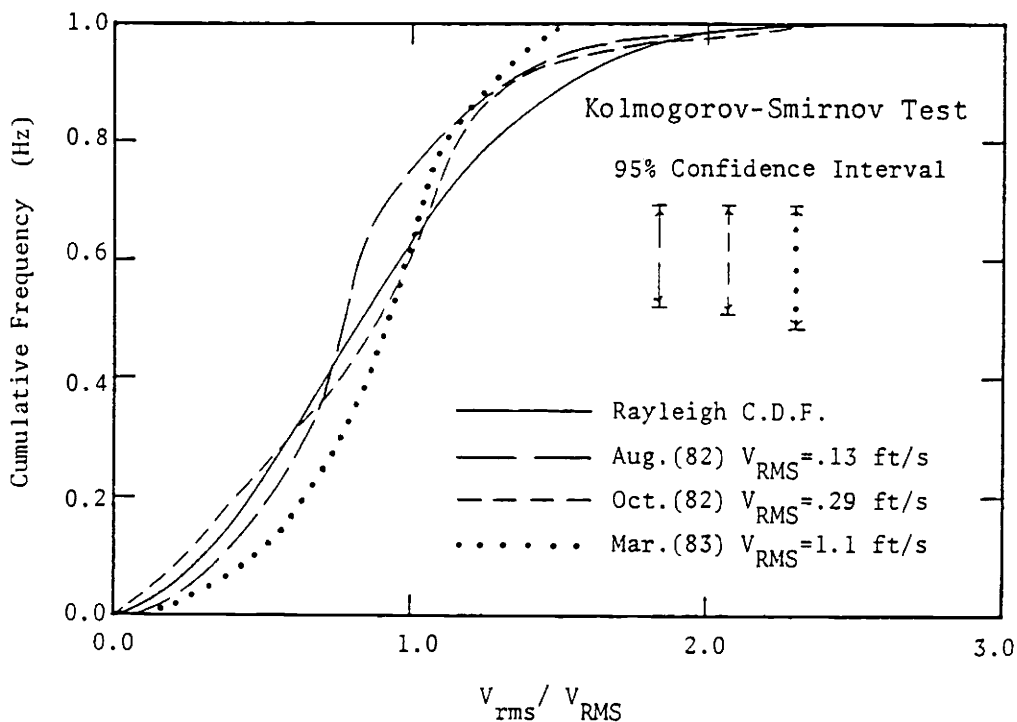


FIG. 4.1 C.D.F. of Rayleigh distribution and empirical C.D.F. of V_{rms}/V_{RMS}

4.3 Selection of a Sample Length for Spectral Analysis

For a stationary process, a long measurement record is desirable in spectral analysis in order to extract all possible frequency components of the measured process. However, for wave property measurements, a lengthy record allows contamination of wave states by tidal fluctuations, changes in wind and current patterns, etc. Thus, a shorter measurement record may be preferred to approximate a stationary process for ocean wave spectral analysis. Therefore, tradeoffs should be considered between long and short measurement records in order to obtain well behaved spectral results as well as low frequency component properties.

A satisfactory record length is to be determined for input data in directional spectral analysis. The procedure used to determine this record length is described as follows. Five October 1982, data sets from meter 43 are chosen for this study. These five data sets were chosen because each has a total record length of 1024 seconds, the maximum recorded in this study. The sample rate is one sample per second and the FFT algorithm requires a total number of data points equal to a integer power of 2. Therefore a record length of 1024 seconds allows us to monitor variation of wave property statistics evaluated from record halves (512 seconds) or quarters (256 seconds). It is hypothesized that the optimum sample length will be one which provides the least variation in wave property statistics. Thus, the optimum record length will be selected from alternative lengths of 256 (2^8) seconds, 512 (2^9) seconds and 1024 (2^{10}) seconds. It is assumed that any length greater than 1024 seconds (17.1 minutes) is contaminated by daily tides and variable wave conditions caused by winds and currents. Any length shorter than 256 seconds (4.27 minutes) can not evaluate wave periods longer than 256 seconds. Also, the fundamental frequency interval may not be small enough to discern the directional properties of ocean waves.

The samples of 512 seconds are retrieved from the first half, the second and third quarters, and the last half of 1024 seconds. The samples of 256 seconds are obtained by dividing 1024 seconds into four equi-spaced intervals (quarters). Another 256 seconds is retrieved from the contral part of 1024 seconds.

To check the accuracy of the measurement system, the resulting wave property statistics are compared with the statistics computed from simultaneously measured samples of 512 seconds, recorded by meter 25 which is located about 10 feet below meter 43. The wave property statistics evaluated in the time domain include mean current magnitude, V_c , and direction, ϕ_c , mean square wave-induced velocity, $\overline{V_t^2}$, and the main propagation direction $\overline{\phi}$. The wave property statistics evaluated in the frequency domain include total wave spectral density, E_{total} , spectral peak of frequency spectrum, E_p , peak frequency, f_p , dimensionless fre-

quency, $f_{1,-1}$, critical spreading parameter, s_c , critical frequency, f_c , main propagation direction ϕ_{main} , and the smoothed total velocity spectral density $\overline{V_f^2}$ at the sensor location. $\overline{V_f^2}$ is defined as

$$\overline{V_f^2} = \sum_{n=1}^{N'} E_{VV}(f_n) = \sum_{n=1}^{N'} K^2(f_n) E(f_n) \quad (4.4)$$

where $E_{VV}(f_n) = K^2(f_n) E(f_n)$ is the subsurface horizontal orbital velocity spectrum. The results of the October 21, 1982, data set are shown in Table 4.2 and 4.3. The initial time of each sample is also identified in these two tables. The results of the other four data sets are presented in Appendix B. In the frequency domain calculation, statistics are computed utilizing the three spectral analysis methods presented in this study. They are the one angle mode solution of the stochastic/deterministic approach, denoted as Sto./Det. approach₁ or S/D₁ in the following sections, the double angle mode solution of the stochastic/deterministic approach, denoted as Sto./Det. approach₂ or S/D₂ in the following sections, and the geometric approach, denoted as GEO. in the following sections.

TABLE 4.2 Sample statistics evaluated in the time domain

Date: <u>October 21, 1982</u>						Meter No. <u>43</u>					
Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$	Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$
(sec)		(ft/s)	(o)	(ft/s) ²	(o)	(sec)		(ft/s)	(o)	(ft/s) ²	(o)
1024	10:28	.514	-70	.155	115	256	10:28	.779	-55	.025	94
512	10:28	.496	-60	.145	132	256	10:32	.273	-71	.094	134
512*	10:32	.251	-78	.116	119	256*	10:34	.097	-64	.064	111
512	10:36	.488	-81	.181	107	256	10:36	.184	-96	.133	108
512**	10:26	.511	-78	.129	93	256	10:40	.797	-79	.035	105

* central section of 1024 seconds

** data measured from meter 25

TABLE 4.3 Sample statistics evaluated in the frequency domain

Date: <u>October 21, 1982</u>		Meter No. <u>43</u>							
Length	Init. Time	E_{total}	E_p	f_p	$f_{1,-1}$	s_c	f_c	ϕ_{main}	$\sqrt{V_f^2}$
(sec)		(ft ²)	(ft ² s)	(Hz)	(Hz)		(Hz)	(o)	(ft/s) ²
<u>STO./DET. APPROACH₁</u>									
1024	10:28	.077	7.2	.059	.069	39	.053	64	.033
512	10:28	.082	6.0	.059	.068	17	.055	56	.038
512*	10:32	.056	7.5	.059	.066	4	.051	79	.023
512	10:36	.061	3.9	.059	.067	8	.057	57	.023
512**	10:26	.075	4.0	.059	.068	28	.051	41	.015
256*	10:34	.057	2.6	.059	.064	5	.062	68	.017
<u>STO./DET. APPROACH₂</u>									
1024	10:28	.063	5.5	.059	.069	91	.055	67	.152
512	10:28	.068	5.1	.059	.067	50	.045	75	.143
512*	10:32	.043	4.0	.059	.068	20	.055	92	.112
512	10:36	.061	4.1	.059	.067	10	.057	54	.178
512**	10:26	.098	8.0	.059	.067	27	.051	65	.128
256*	10:34	.063	2.7	.059	.064	7	.055	72	.060
<u>GEOMETRIC APPROACH</u>									
1024	10:28	.076	7.6	.059	.069	5.5	.059	56	.023
512	10:28	.071	6.0	.059	.068	4.8	.066	77	.032
512*	10:32	.063	4.3	.059	.068	4.0	.063	47	.083
512	10:36	.075	4.2	.059	.065	7.0	.062	64	.081
512**	10:26	.074	7.4	.059	.068	10.	.059	58	.026
256*	10:34	.063	2.8	.059	.064	4.5	.062	64	.017

* central section of 1024 seconds, ** data measured from meter 25

A numerical stability study of wave property statistics for sample lengths of 256 and 512 seconds is first performed in the time domain for each of the five data sets. The mean and standard deviation for sample lengths of 256 and 512 seconds in each data set are computed and compared with the results from a 1024 second record length and a 512 second record from meter 25. These results are tabulated in Table 4.4 along with the date and initial time of each data set. The October 21, data indicates large standard deviations for all mean values. This is because the total wave energy content is small, i.e, about 5% of the wave energy content of the other four data sets. Hence, the resulting wave properties are sensitive to both physical and numerical disturbances. For the remaining four data sets, the standard deviations of the means are relatively small. The standard deviations of the means for all 512 second records are smaller than those for the 256 second records. A graphical summary of the results appears in Fig. 4.2. The figure shows the relative variation of statistics $\overline{V_t^2}$ and V_c for all five data sets by expressing $\overline{V_t^2}$ and V_c of the 256 and 512 second records as ratios with respect to $\overline{V_t^2}$ and V_c of the 1024 second record, respectively. $\overline{V_{t,1024}^2}$ and $V_{c,1024}$ denote the quantities $\overline{V_t^2}$ and V_c of the 1024 second record for each data set in Fig. 4.2. Although both ratios, $\overline{V_t^2}/\overline{V_{t,1024}^2}$ and $V_c/V_{c,1024}$, are close to unity in a mean sense in Fig. 4.2, results from a record length of 256 seconds are more scattered than those from a record length of 512 seconds.

A stability study in the frequency domain is performed by comparing values of the total energy density and the peak energy density of the one-dimensional frequency spectrum, computed as dimensionless ratios relative to results from a 1024 second record length. The symbols $E_{p,1024}$ and $E_{total,1024}$ denote the peak and total energy density, respectively, of the 1024 second record. The mean value and standard deviation for these ratios are calculated for sample lengths of 512 seconds, measured by meter 43, utilizing the methods identified in Table 4.5. Also ratios are computed for samples from the central 256 seconds of the records from meter 43 and for samples of 512 seconds from meter 25; these are also shown in Table 4.5. The October 25, 10:52 data from meter 25 indi-

TABLE 4.4 Comparison of sample statistics in the time domain

Year: <u>1982</u>		Meter No. <u>43</u>			
Date, (init. time)	Length (sec)	V_c (ft/s)	ϕ (o)	$\overline{V_t^2}$ (ft/s) ²	ϕ (o)
Oct 21	1024	.514	-70	.155	115
(10:28)	512	.412±.139	-73±11.3	.147±.032	119±12.5
	512**	.511	-78	.129	93
	256	.426±.336	-73±15.6	.070±.044	110±14.7
Oct 23	1024	.265	-8	.054	92
(2:38)	512	.267±.009	-6.7± 2.9	.056±.003	94± 1.5
	512**	.392	-6.7	.065	84
	256	.267±.019	-7± 4.3	.055±.010	91± 7.2
Oct 24	1024	1.04	-31	.063	79
(14:47)	512	1.03±.010	-31± 2.6	.059±.008	80± 1.5
	512**	.736	-56	.070	78
	256	1.03±.030	-31± 4.3	.055±.003	81± 1.9
Oct 25	1024	.242	198	.072	89
(6:51)	512	.249±.031	199±10.8	.068±.001	89± 3.0
	512**	.212	250	.080	98
	256	.250±.031	197±13.5	.066±.019	91± 2.1
Oct 25	1024	.421	-17	.047	97
(10:52)	512	.418±.011	-17± 1.1	.045±.002	96± 4.4
	512**	.468	193	.043	72
	256	.424±.006	-16± 2.2	.044±.007	96± 4.7

** data measured from meter 25

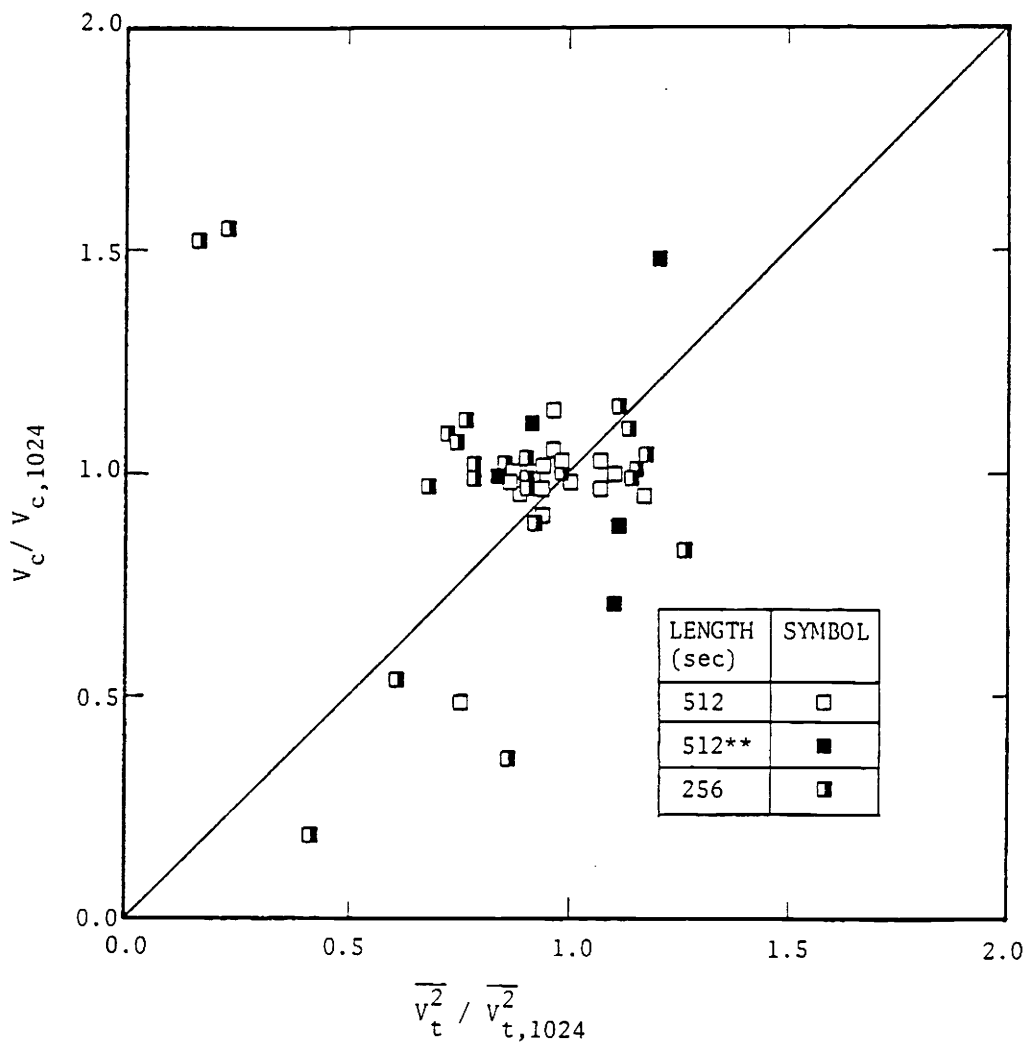


FIG. 4.2 Plot of dimensionless parameters $\frac{\overline{v_t^2}}{\overline{v_{t,1024}^2}}$ versus $\frac{v_c}{v_{c,1024}}$
 ** meter 25 data

cate ratios approaching three. This condition implies a strong, short term unsteady current occurring at the depth of meter 25 during this particular measuring period.

It is surprising that almost all ratios of $E_{\text{total}}/E_{\text{total},1024}$ and $E_p/E_{p,1024}$ of the central 256 second records differ significantly from

TABLE 4.5 Comparison of ratios $E_{total}/E_{total,1024}$ and $E_p/E_{p,1024}$

Year: <u>1982</u>		Meter No. <u>43</u>					
Date, (init. time)	Length (sec)	S/D ₁	S/D ₁	S/D ₂	S/D ₂	GEO.	GEO.
		$\frac{E_{total}}{E_{total,1024}}$	$\frac{E_p}{E_{p,1024}}$	$\frac{E_{total}}{E_{total,1024}}$	$\frac{E_p}{E_{p,1024}}$	$\frac{E_{total}}{E_{total,1024}}$	$\frac{E_p}{E_{p,1024}}$
Oct 21 (10:28)	512	.86±.18	.80±.25	.91±.21	.80±.11	.92±.08	.65±.14
	512**	.97	.55	1.56	1.45	.97	.96
	256	.74	.35	1.02	.48	.83	.36
Oct 23 (2:38)	512	1.08±.34	.93±.10	.95±.40	.95±.10	1.07±.18	.98±.10
	512**	.91	1.02	1.62	1.18	1.00	1.12
	256	3.50	1.50	2.50	1.13	3.40	2.40
Oct 24 (14:47)	512	.93±.08	.94±.08	.92±.01	.95±.11	.93±.01	.94±.13
	512**	1.05	1.09	1.56	2.00	1.03	1.08
	256	1.08	.88	1.10	.93	1.03	.89
Oct 25 (6:51)	512	1.12±.19	.96±.08	1.16±.18	.93±.06	1.03±.08	.94±.06
	512**	1.22	1.17	1.64	1.47	1.14	1.10
	256	.63	.16	.61	.18	.61	.13
Oct 25 (10:52)	512	1.09±.19	1.27±.30	1.00±.13	1.16±.27	1.13±.21	1.29±.31
	512**	2.70	2.60	3.96	3.80	2.40	2.30
	256	2.30	.92	1.64	.87	2.00	1.15

** data measured from meter 25

the means of the related ratios for 512 second records. This result is presented graphically as a plot of $E_{total}/E_{total,1024}$ versus $E_p/E_{p,1024}$ in Fig. 4.3. The standard deviations for each 512 second sample in Table 4.5 are relatively small value implying approximately stationary processes for this record length.

Numerical stability studies in both the time and frequency domains

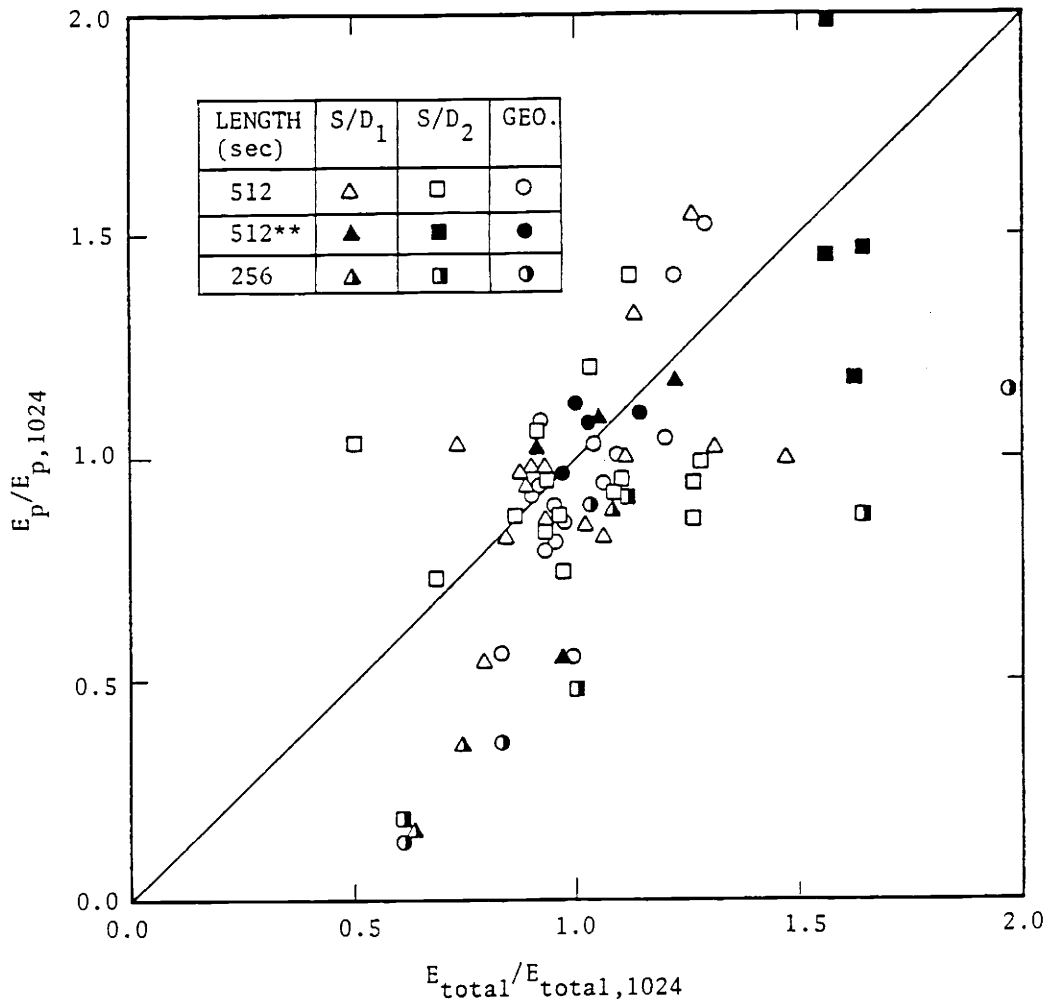


FIG. 4.3 Plot of dimensionless parameters $\frac{E_{total}}{E_{total,1024}}$ vs $\frac{E_p}{E_{p,1024}}$
 ** meter 25 data

show that wave property statistics estimated from a record length of 512 seconds are more reliable, less variable than those estimated from a record length of 256 seconds. Since 1024 second records are not generally available from the field measurements in this research project, 512 second data sets are selected as the optimum record length.

4.4 Comparisons of Results from Alternative Directional Spectrum Solution Methods

In this section, directional wave properties from the five data sets identified in Section 4.3 will be analyzed further to compare the behavior of the Stochastic/Deterministic one and double angle mode and geometric methods utilized in directional spectra analysis. This will be accomplished by comparing nearly simultaneous water surface spectrum predictions from two different current meters. These results will also be used as examples to compare wave property statistics in the time and frequency domains. Then, graphical examples of directional spectra output based on real ocean measured data will be presented for both smoothed spectra and proposed spectra.

4.4.1 Direct Comparison of Selected Numerical Results

Although the geometric approach has been shown to be theoretically superior to the Sto./Det. approach in Chapter 2, it is appropriate to compare numerical results to see if one method provides superior computations as well. This comparison will be facilitated by examining water surface spectrum predictions from two current meters separated by a ten foot vertical distance. One dimensional frequency spectra, critical spreading parameters and main propagation directions will be compared.

The same five data sets used in the numerical stability study in Section 4.3 will be the analyzed again. However, results from the data sets of October 21 with initial time 10:28 and of October 25 with initial time 10:52 are of less interest due to the previously mentioned small wave energy levels and unusual short duration unsteady currents, respectively. The ratios of total energy, $E_{total}/E_{total,1024}$, and peak energy, $E_p/E_{p,1024}$, for sample lengths of 512 seconds in Table 4.5 provide us with a comparison of one-dimensional spectrum results. Recall that the 512 second records were determined to be superior in Section 4.3. The results for meter 43 (upper meter) are presented in the first

row of each data set. The results from meter 25 (lower meter) are presented in the second row and identified with a double asterisk. The results from both meters should indicate the same one-dimensional spectrum estimates at the water surface because the same phenomenon is being sampled at different depths. The superior method should be indicated by the smallest difference between meters. An interpretation of the data from October 23, 24, and 25 (6:51) reveals that the double angle mode solution of the stochastic/deterministic approach has the greatest differences between meters (<110%), the geometric approach has the smallest differences between meters (<17%), and the one angle mode solution of the stochastic/deterministic approach has an intermediate difference between meters (<31%). One could conclude that the geometric approach provides more reliable predictions of the water surface one-dimensional spectrum.

The directional wave properties used to compare the three methods are the critical spreading parameter, s_c , and the main direction, ϕ_{main} , of the five data sets. The mean and standard deviation are calculated for these parameters for a sample length of 512 seconds, measured by meter 43, and are presented in Table 4.6. Also, values of s_c and ϕ_{main} for sample record lengths of 512 seconds from meter 25 are presented in Table 4.6. Results from data sets of October 21 and 25 (10:52) are ignored in this comparison. For the remaining data sets, the maximum difference in main direction evaluated from separate current meters for methods S/D_1 , S/D_2 , and GEO. are 22° , 29° , and 18° , respectively (October 23 data set). The maximum difference in critical spreading parameters for methods S/D_1 , S/D_2 , and GEO. are 9.2, 11.0, and 6.7, respectively. One could conclude that the geometric approach provides more consistent predictions of directional information than the stochastic/deterministic approaches.

Figure 4.4 shows the variation of s_c versus ϕ_{main} for the individual data sets (in Table 4.3 and Table B.2). No significant pattern is revealed in this figure. In order to see whether these critical spreading parameters occur at consistent frequencies, values of s_c

TABLE 4.6 Comparison of s_c and ϕ_{main}

Year: <u>1982</u>		Meter No. <u>43</u>					
Date, (init. time)	Length (sec)	S/D ₁ s_c	S/D ₁ ϕ_{main} (o)	S/D ₂ s_c	S/D ₂ ϕ_{main} (o)	GEO. s_c	GEO. ϕ_{main} (o)
Oct 21	1024	39.0	64	91.0	67	5.5	56
(10:28)	512	9.7±6.6	64±11	27.0±21.	74±19	5.3±1.5	63±15
	512**	28.0	41	27.0	65	10.0	58
Oct 23	1024	29.0	92	32.0	99	7.6	90
(2:38)	512	10.0±2.6	95± 7	10.3±2.1	101± 9	4.7±0.6	90± 6
	512**	14.0	73	10.0	72	8.0	72
Oct 24	1024	12.0	75	16.0	77	3.8	73
(14:47)	512	15.6±2.1	74±11	13.3±3.2	74±11	3.3±0.3	72±13
	512**	7.0	66	9.0	65	10.0	67
Oct 25	1024	20.0	84	32.0	89	4.6	87
(6:51)	512	14.7±6.4	85± 2	20.0±2.6	95± 6	4.6±0.7	87± 2
	512**	5.5	73	9.0	78	5.2	71
Oct 25	1024	20.0	90	33.0	93	5.4	90
(10:52)	512	22.0±5.5	90± 1	16.7±5.5	100±10	4.0±1.7	85± 5
	512**	43.0	81	31.0	82	23.0	76

** data measured from meter 25

versus f_c are plotted in Fig.4.5. Ignoring the data of October 21 and 25 (10:52), the maximum difference in f_c for methods S/D₁, S/D₂, and GEO. are .004 (Hz), .007 (Hz), and .002 (Hz), respectively. Therefore, less variability appears in the results of the geometric approach.

It should be pointed out that significant differences in values of E_{total} , E_p , s_c and ϕ_{main} occur when comparing the results of one method

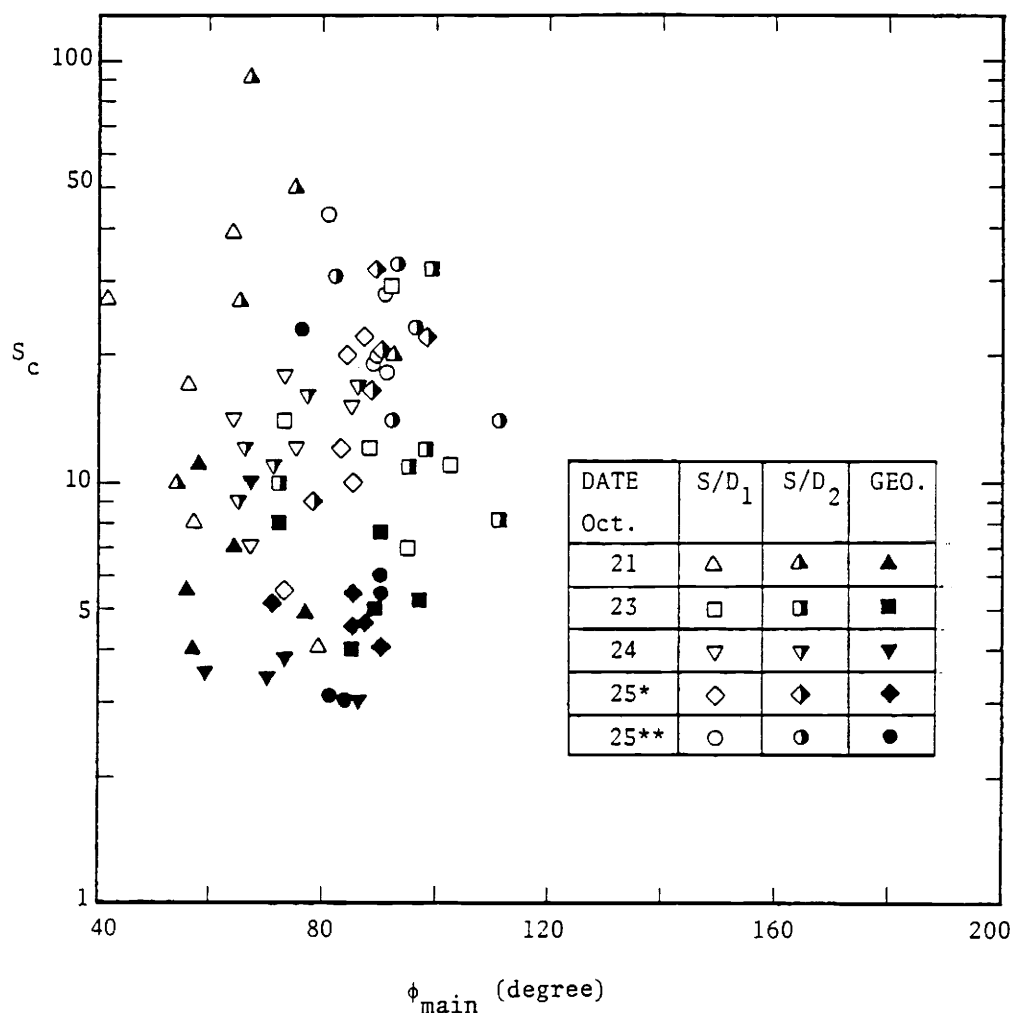


FIG. 4.4 Plot of s_c versus ϕ_{main} , * 6:51 data set, ** 10:52 data set

to the other. Hence, solutions obtained from one method cannot be used to approximate solutions obtained from another method. This is illustrated in Table 4.7 where a list of mean and standard deviation values for parameters E_{total} , E_p , s_c , and ϕ_{main} are presented for data sets from October 23, 24, and 25 (6:51). The standard deviations reflect differences between three 512 second records, analyzed from the first half, last half, and second and third quarters of a 1024 second record. Note how relative means for the same sample vary from one method to another. The parameters E_{total} and E_p solved from S/D_1 differ from the

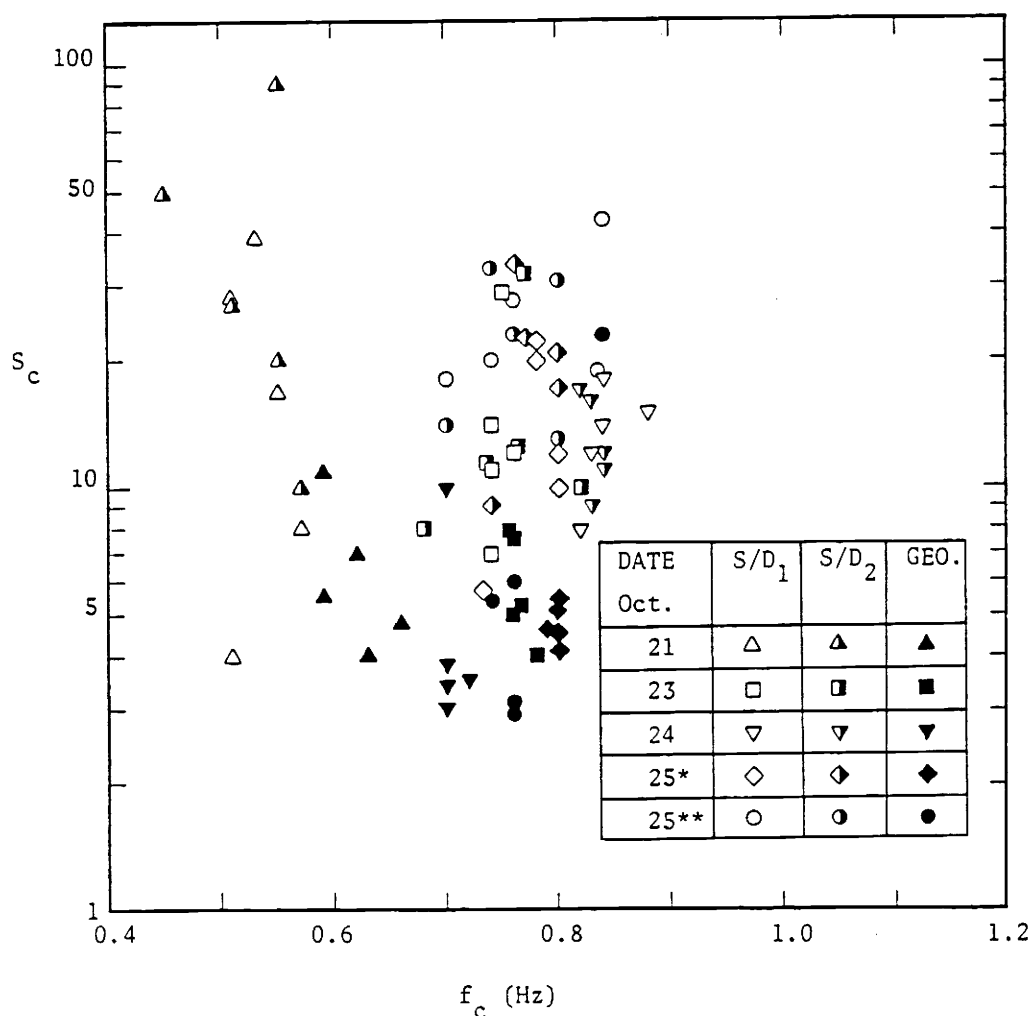


FIG. 4.5 Plot of s_c versus f_c , * 6:51 data set, ** 10:52 data set

results of the GEO. method by 16% and 23%, or less. The values of E_{total} and E_p solved from S/D_2 are much smaller than those solved from either S/D_1 or GEO. The means of ϕ_{main} for the same sample are scattered with respect to the three methods. The maximum deviation about the mean of ϕ_{main} for the same sample is 11° (October 23, data). The values of s_c solved from S/D_1 are fairly consistent with those solved from S/D_2 ; the maximum deviation about the mean being approximately five. The values of s_c solved from GEO. are much smaller than those solved from S/D_1 and S/D_2 ; this is illustrated in Figs. 4.4 and 4.5.

TABLE 4.7 The mean and standard deviation of E_{total} , E_p , s_c , and ϕ_{main}

Year: <u>1982</u>		Length: <u>512</u> (sec)		Meter No. <u>43</u>	
Date, (init. time)		S/D ₁	S/D ₂	GEO.	
Oct 23	E_{total} (ft ²)	1.08±.34	.60±.25	1.10±.12	
(2:38)	E_p (ft ² s)	43.0±4.3	42.0±4.0	46.0±4.6	
	s_c	10.0±2.6	10.3±2.1	4.7±0.6	
	ϕ_{main} (o)	95.0±7.0	101.±9.0	90.0±6.0	
Oct 24	E_{total} (ft ²)	1.23±.11	.82±.01	1.43±.02	
(14:47)	E_p (ft ² s)	56.0±4.6	34.0±4.0	69.0±9.5	
	s_c	15.6±2.1	13.3±3.2	3.3±0.3	
	ϕ_{main} (o)	74.0±11.	74.0±11.	72.0±13.	
Oct 25	E_{total} (ft ²)	1.76±.30	1.39±.21	1.78±.14	
(6:51)	E_p (ft ² s)	96.0±9.3	75.0±4.5	102.±6.0	
	s_c	14.7±6.4	20.0±2.6	4.6±0.7	
	ϕ_{main} (o)	85.0±2.0	95.0±6.0	87.0±2.0	

The average critical spreading parameters solved from S/D₁ and S/D₂ for these three consecutive days' data are 13.5 and 14.5, respectively. However, the average value solved from GEO. is 4.2. Figure 2.5 indicates that smaller values of the spreading parameter, s , associated with the geometric method will yield broader directional spreading than that indicated by the stochastic/deterministic method. One may conclude from these results that computations from the geometric method are more consistent and, therefore, are superior in terms of reliability. Furthermore, if the geometric method is "correct", then significant errors may be associated with the stochastic/deterministic method. However, this analysis does not establish which method best approximates the actual, unknown, directional spectrum.

4.4.2 Directional Wave Properties Estimated in the Time and Frequency Domains

If one has records of water surface elevation, one can directly evaluate total water surface wave energy densities from both time and frequency domains and immediately compare the results. However, with a current meter based measurement system, this comparison can only be done by evaluating subsurface mean square velocities, $\overline{V_t^2}$ and $\overline{V_f^2}$, as indicated by Eqs.(3.6) and (4.5), respectively. Similarly, directional properties must be compared utilizing subsurface time and frequency information.

According to Eq.(3.7-1), the accuracy of evaluating the main direction, $\overline{\phi}$, in the time domain is very much dependent on one's ability to guess the general direction of wave propagation. Our measurement system is located three miles offshore and all waves are assumed to propagate towards the coastline. A normal projection to the coastline is equal to 120° , relative to magnetic north. Hence, any velocity vector directed beyond $120^\circ \pm 90^\circ$ is assumed to correspond to a wave trough and is corrected by 180° . Since a perfect guess of this general propagation direction is nearly impossible, considerable differences may occur between the time domain main direction, $\overline{\phi}$, and the frequency domain main direction, ϕ_{main} . The main direction, ϕ_{main} , evaluated in the frequency domain is not affected by this directional ambiguity because pressure frequency components resolve troughs from crests in both the S/D_1 and GEO. methods. However, the estimation of ϕ_{main} in S/D_2 which excludes pressure data, may experience this direction ambiguity unless the pressure data is used to reference directions, in accordance with the discussion of Eq.(2.40-2).

The data sets identified in Table 4.5 have been analyzed to yield $\overline{\phi}$ and ϕ_{main} . These are plotted on a scatter diagram in Fig. 4.6. The poor correlation of the October 21, data is because the wave heights were very low so the direction computations are limited by the resolving powers of the instrument and are subject to contamination by slight

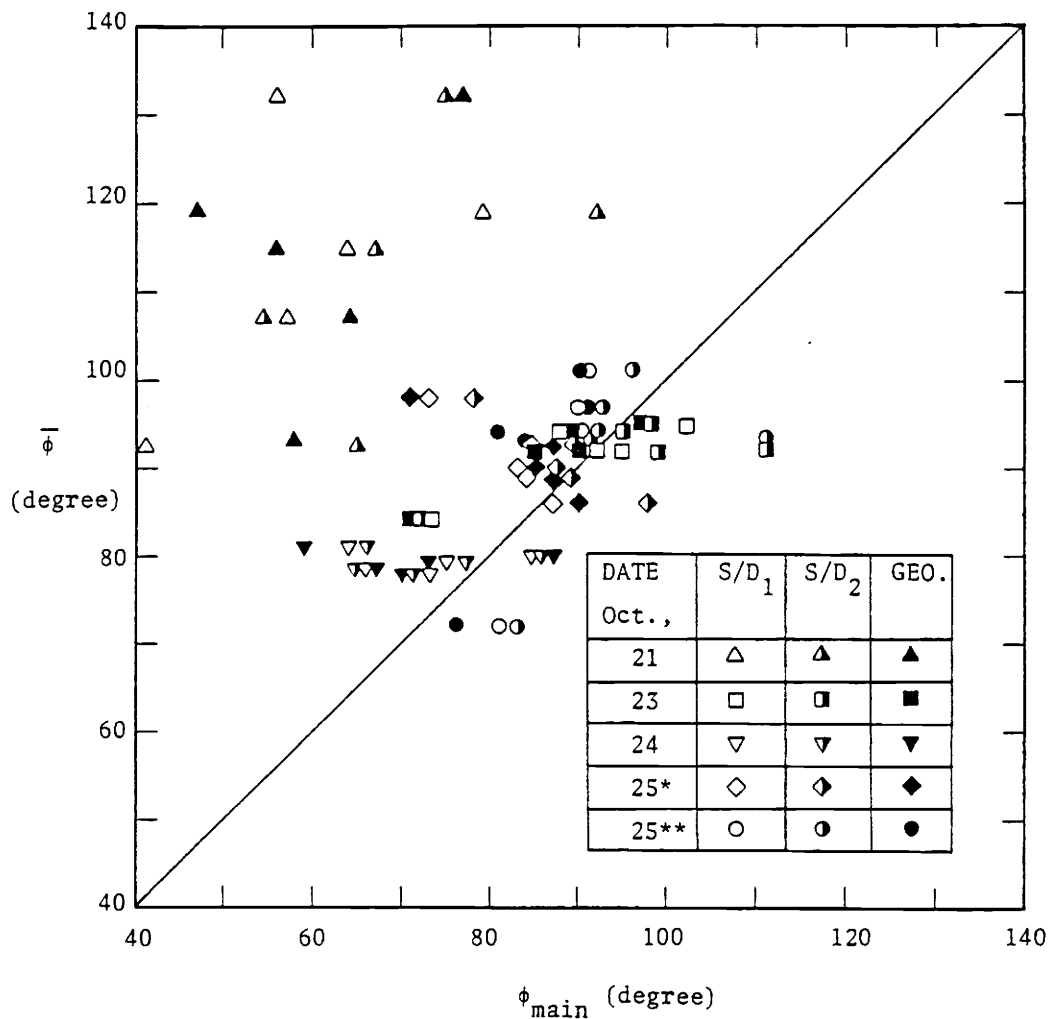


FIG. 4.6 Plot of main directions $\bar{\phi}$ versus ϕ_{main}

electro-mechanical and/or hydraulic disturbances. On October 21, the main direction estimated from the frequency domain, ϕ_{main} , is about 65 which is considerably different from the estimated shoreward direction of 120°. Less scatter is seen in Fig. 4.6 for the data of October 23, where ϕ_{main} is about 95°, and the maximum difference between $\bar{\phi}$ and ϕ_{main} is 12°.

The mean square velocities, $\overline{V_t^2}$ and $\overline{V_f^2}$, for the same five data sets are plotted in Fig. 4.7. The energy estimates of the method S/D₂ use

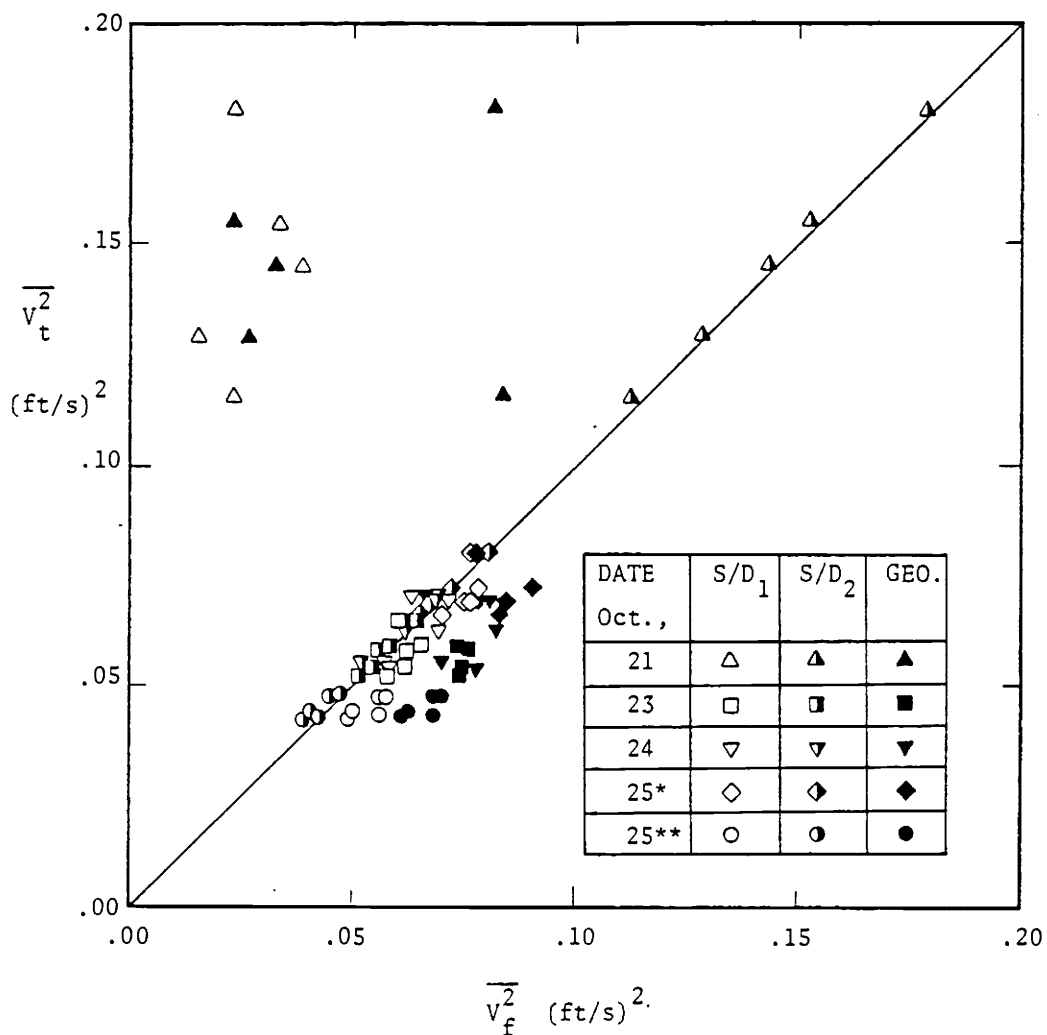


FIG. 4.7 Plot of mean square velocities $\overline{V_t^2}$ versus $\overline{V_f^2}$

Fourier coefficients which are directly transformed from the time series of measured wave properties. Consequently, the total energy density estimated from the frequency domain corresponds closely to the energy density estimated from the time domain except for the truncated high frequency components exceeding the deep water condition. Hence, all points based on S/D_2 fall along a 45° line in Fig. 4.7. The data of October 21 are extremely scattered again due to low wave conditions. The remaining four data sets correlate more closely in Fig. 4.7. However, differences between $\overline{V_t^2}$ and $\overline{V_f^2}$ can be significant for either the S/D_1 or GEO. methods.

The mean square velocity evaluated from the time domain generally under estimates the same quantity from the frequency domain by up to 14% for the S/D_1 method and 40% for the GEO. method. To explain this difference, two subsurface velocity fluctuations due to water surface wavelet pairs solved in a frequency interval are represented here in accordance with Eq.(2.69) from the GEO. method.

$$u_n(t) = A(\sigma_n) \cos(\sigma_n t - \theta_{an}) \cos \phi_{an} + B(\sigma_n) \cos(\sigma_n t - \theta_{bn}) \cos \phi_{bn}$$

$$v_n(t) = A(\sigma_n) \cos(\sigma_n t - \theta_{an}) \sin \phi_{bn} + B(\sigma_n) \cos(\sigma_n t - \theta_{bn}) \sin \phi_{bn}$$

where $\sigma_n = 2\pi f_n$. The mean square velocity evaluated for this frequency σ_n is

$$\begin{aligned} \overline{V_n^2(t)} &= \overline{u_n^2(t) + v_n^2(t)} \\ &= \frac{1}{2} [A^2(\sigma_n) + B^2(\sigma_n)] + A(\sigma_n) B(\sigma_n) \cos(\theta_{an} - \theta_{bn}) \cos(\phi_{an} - \phi_{bn}) \end{aligned} \quad (4.5)$$

The frequency domain velocity energy density for the $A(\sigma_n)$ and $B(\sigma_n)$ wavelets in each frequency interval is simply

$$\frac{[A^2(\sigma_n) + B^2(\sigma_n)]}{2}$$

Equation (4.5) demonstrates that the mean square velocity in the time domain can not, in general, be equal to the velocity energy density in the frequency domain. However, for the stochastic/deterministic approach, $\theta_{an} - \theta_{bn} = 90^\circ$ and the cross product term in Eq.(4.5) vanishes,

yielding an identity between the time and frequency domains. This solution is appropriate for the S/D_2 approach which utilizes only velocity data. However, the S/D_1 approach modifies the velocity amplitudes $A(\sigma_n)$ and $B(\sigma_n)$ with pressure data, violating the equality suggested by Eq. (4.5). Furthermore, it has been observed in this study that the two directions, ϕ_{an} and ϕ_{bn} , solved from the GEO. approach are highly correlated and the difference between the two directions is usually smaller than 90° . Also, the difference between two phases, θ_{an} and θ_{bn} , solved from the GEO. approach at each frequency is often larger than 90° . Therefore, the cross product term in Eq. (4.5) is negative and the mean square velocity in the time domain is reduced relative to the velocity energy density in the frequency domain. Consequently, $\overline{V_f^2}$ exceeds $\overline{V_t^2}$ for the geometric approach. This behavior is substantiated in Fig. 4.7.

4.4.3 Selection of Significant Data Sets

Utilizing a low energy content wave property record may confuse the interpretation of wave spectrum behavior, as shown for the data of October 21 in Section 4.4.1 and Section 4.4.2. Wave property measurements containing high wave energy, implying a significant wave state, are preferred in directional spectrum analysis. The parameter utilized to characterize significant data sets is the time domain mean square velocity, $\overline{V_t^2}$. Although $\overline{V_t^2}$ is not equal to $\overline{V_f^2}$, both quantities are proportional to the total wave energy content. Also $\overline{V_t^2}$ is the only parameter which can be simply calculated from velocity records in the time domain and associated with total wave energy content. For samples of October 1982, measured by meter 25, and March 1983 (see Table 4.1), 25% of each months samples with the highest $\overline{V_t^2}$ values are selected for spectral analysis. For samples of August 1982, the root mean square value of $\overline{V_t^2}$ shows a low average energy content for the entire month, $\overline{V_{rms}^2} = 0.017 \text{ (ft/s)}^2$. Consequently, only the highest 10% of $\overline{V_t^2}$ values are utilized for spectral analysis in August 1982. For samples of October 1982, the sample population is so small that all 11 samples are

used in spectral analysis.

Tabular summaries of E_{total} and $\overline{V_t^2}$ obtained from samples of significant data sets in October 1983 (meter 25) and March 1983 are presented in Table 4.8. These samples are thought to have sufficiently large energy densities to relate E_{total} to $\overline{V_t^2}$. The tabular results suggest that $\overline{V_t^2}$ can be an appropriate indicator for the total wave energy content. Figure 4.8 shows a plot of E_{total} versus $\overline{V_t^2}/\overline{V_{\text{rms}}^2}$ for the significant data sets of October 1982 and March 1983.

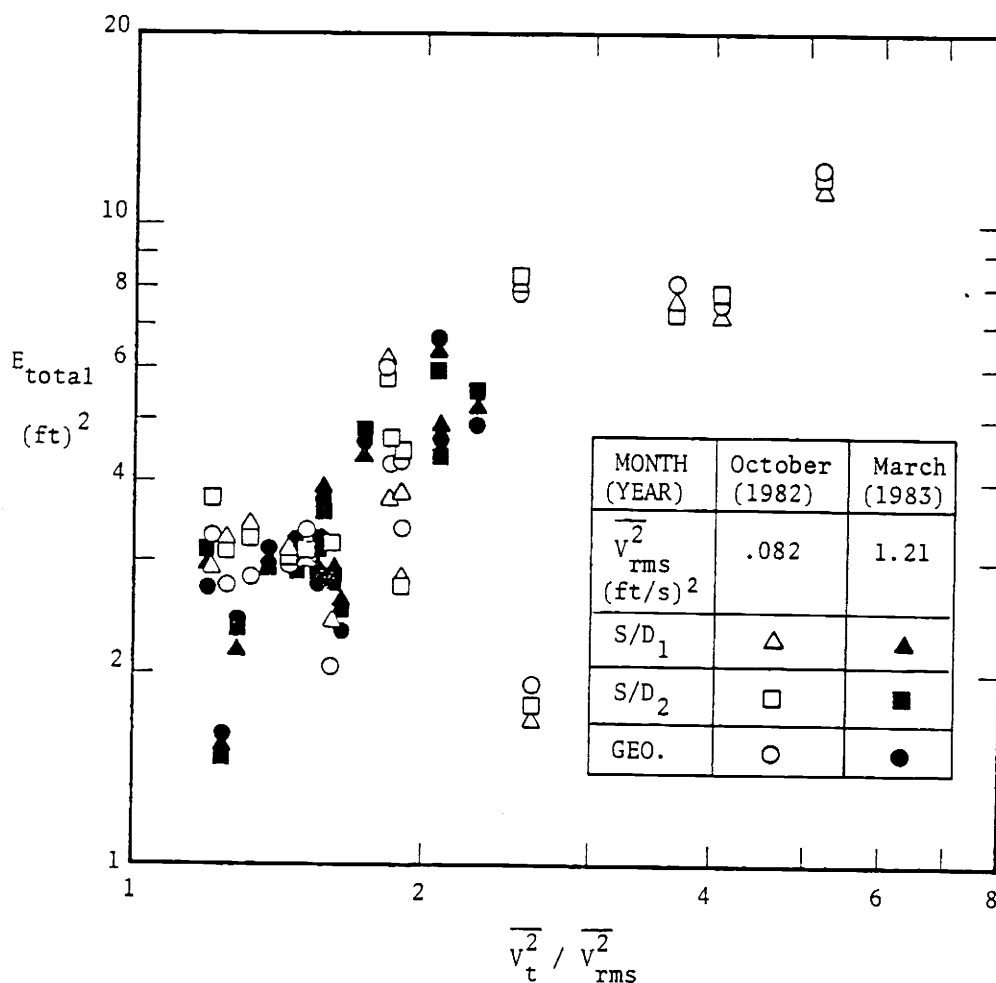


FIG. 4.8 Plot of E_{total} versus $\overline{V_t^2}/\overline{V_{\text{rms}}^2}$

TABLE 4.8 Tabular summary of E_{total} and $\overline{V_t^2}$ Month: March Year: 1983 Meter No. 26

Date	Init. time	GEO.	S/D ₁	S/D ₂	$\overline{V_t^2}$ (ft/s) ²	
		E_{total} (ft ²)	E_{total} (ft ²)	E_{total} (ft ²)		
	24	7:42	2.73	3.00	3.05	1.455
	24	13:34	4.87	5.27	5.42	2.753
	24	16:30	2.33	2.65	2.61	1.971
	24	19:26	3.14	2.96	2.87	1.776
	24	22:22	4.67	4.68	4.58	2.532
	25	1:18	3.73	3.79	3.67	1.905
	25	4:14	1.58	1.54	1.48	1.496
	25	7:10	2.74	2.87	2.76	1.917
	25	10:06	3.11	3.07	3.03	1.660
	25	13:02	3.18	3.13	3.10	1.894
	25	15:02	2.73	2.80	2.78	1.946
	25	18:54	2.43	2.19	2.39	1.560
	27	3:10	4.61	4.59	4.76	2.086
	27	6:06	6.49	6.48	5.97	2.525

Month: October Year: 1982 Meter No. 25

Date	Init. time	GEO.	S/D ₁	S/D ₂	$\overline{V_t^2}$ (ft/s) ²	
		E_{total} (ft ²)	E_{total} (ft ²)	E_{total} (ft ²)		
	21	10:26	.08	.10	.11	.129
	22	2:30	6.03	5.92	4.51	.151
	24	2:42	2.74	3.23	3.12	.104
	26	2:54	2.83	3.41	3.24	.110
	26	6:55	8.11	7.70	7.65	.300
	26	10:56	7.54	7.47	7.78	.331
	26	14:57	12.2	11.6	12.0	.425
	27	3:00	4.38	3.82	4.26	.155
	27	7:01	8.00	8.08	8.28	.205
	27	11:02	1.92	1.75	1.82	.215
	28	19:10	2.03	2.42	3.20	.131
	28	23:11	3.34	3.02	3.13	.124
	29	3:12	3.37	2.73	2.72	.156
	29	7:13	3.29	2.91	3.76	.099
	29	11:14	3.00	2.28	3.14	.118
	31	19:28	4.29	3.78	4.70	.152

In Fig. 4.8, the increase of $\overline{v_t^2}/\overline{v_{rms}^2}$ is monotonic with E_{total} for all three applied methods. Figure 4.8 also indicates how the total energy densities of the sample vary from one method to the other. The maximum difference in E_{total} between the GEO. and S/D₁ methods is 22%, between the GEO. and S/D₂ methods is 55%, and between the S/D₁ and S/D₂ methods is 33%. Therefore, the one-dimensional spectrum may vary significantly depending on the method of analysis. Since the one-dimensional spectrum is a fundamental quantity in directional spectrum analysis, the appropriate method of analysis should be carefully chosen. The geometric method has been shown to be theoretically more satisfying and numerically more stable when compared to the other two methods. Consequently, the geometric method is regarded as a standard for comparing the results of other methods in the following sections.

4.4.4 Graphical presentation and Comparison of Directional Wave Spectrum Outputs

The computer system utilized in this study is equipped with a Tektronix, Model No. 4631, Hard Copy Unit, providing a variety of graphical outputs in response to user specified options in the directional spectrum software. A typical example of the available graphical outputs from a geometric method of analysis of the October 26, 1982, data set is shown in Figures 4.9 and 4.10. Each figure is composed of six sub-graphs. In Fig. 4.9, from left to right and from top to bottom, the sub-graphs include a proposed directional wave spectrum (plotted from the empirical equations representing the JONSWAP spectrum, spreading parameter and central angle), a smoothed directional wave spectrum, a one-dimensional wave spectrum, the distribution pattern of the spreading parameter, the frequency spectrum of the dominant (main) direction and the directional spectrum of the dominant (peak) frequency. In Fig. 4.10, from left to right and from top to bottom, the sub-graphs are a proposed directional velocity spectrum (plotted from the empirical equations), a smoothed directional velocity spectrum, a one-dimensional velocity spectrum, the distribution of central direction, the frequency velocity spectrum of the dominant direction and the direc-

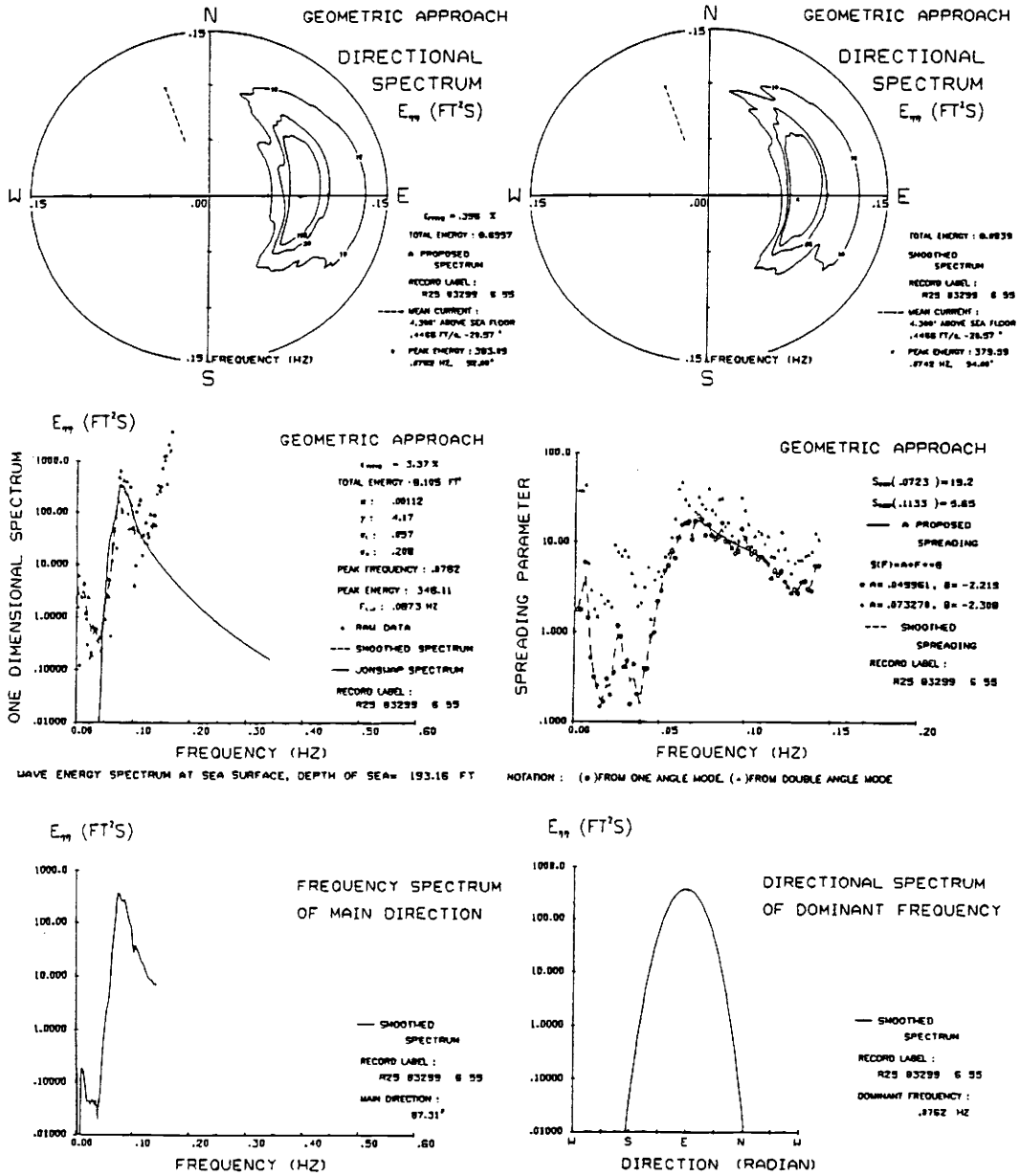


FIG. 4.9 Results of directional wave spectrum from the geometric approach

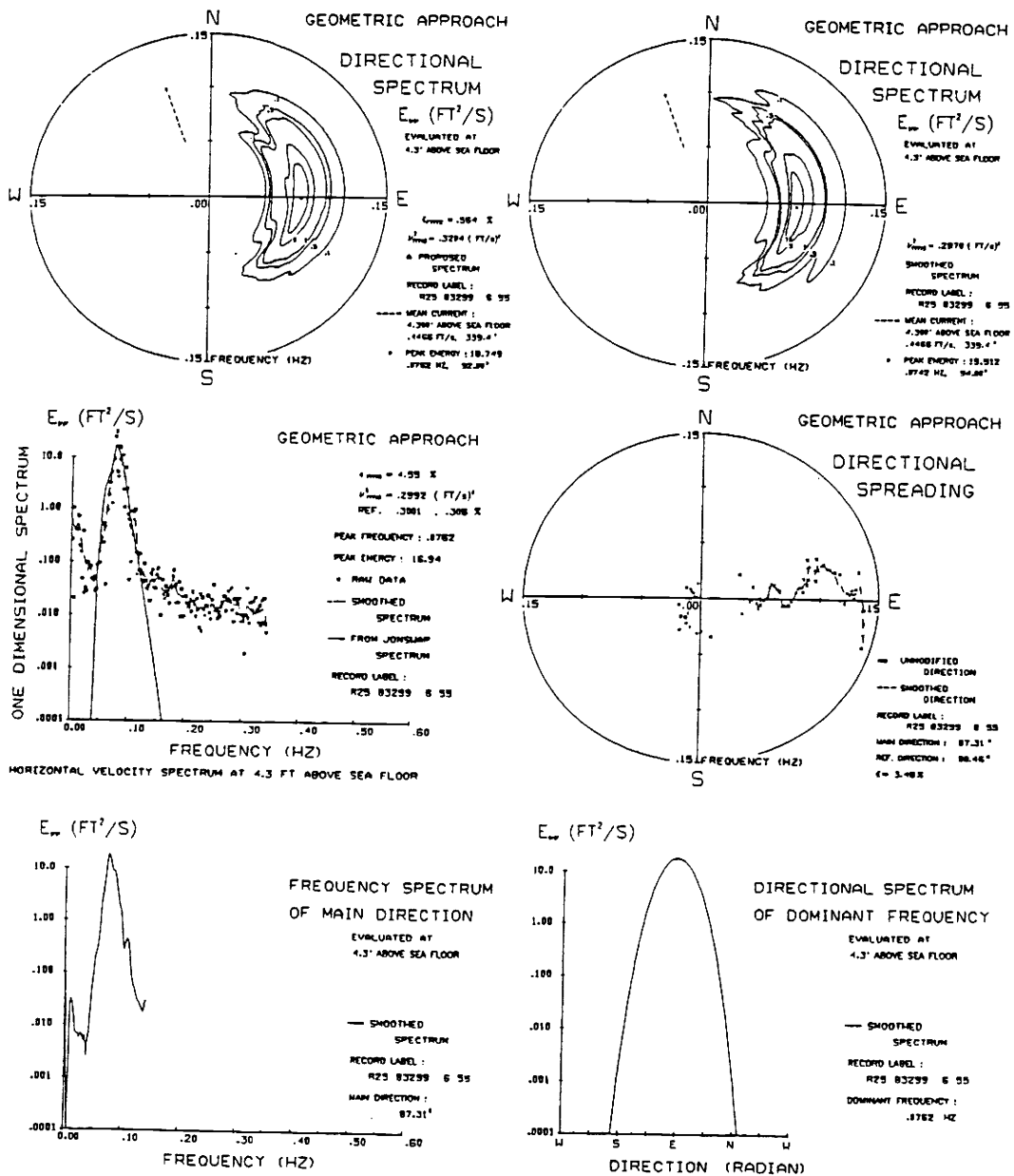


FIG. 4.10 Results of directional velocity spectrum from the geometric approach

tional velocity spectrum of the dominant frequency.

To examine the difference between the proposed directional spectrum and the smoothed raw data spectrum, the smoothed central angles (not the empirical central angle function) are utilized in the proposed directional spectrum in both Figs. 4.9 and 4.10. The error associated with the proposed models of the one-dimensional and the directional spectra compared to the smoothed raw data spectra have been evaluated in a root mean square sense, as specified in Eqs.(3.14) and (3.25), respectively. The errors as well as the total energy estimates are evaluated in a discrete form with a fundamental directional interval of 1° and a fundamental frequency interval identical to that used in the FFT calculations. The errors are discussed later in this section.

The distribution of the spreading parameter with respect to frequency shows a maximum, s_c , near the spectral peak of the one-dimensional spectrum with decreasing values on both sides of s_c . One may notice that the spreading parameter maintains high values for a finite low frequency interval and then decreases rapidly to relatively low values at much lower frequencies. A decrease in the spreading parameter at low frequencies implies increased spreading of low frequency waves. This is contrary to what one would expect for waves coming from a single storm source. That is, long waves are relatively resistant to the dispersive effects of cross winds and currents, therefore, it is anticipated that low frequency waves are unidirectional. Accordingly, higher values of the spreading parameter should be associated with low frequency waves generated from the same origin. Evidently real ocean waves include low frequency waves arriving from a variety of sources, propagating in a variety of directions. The energy density levels at low frequencies are quite small so the absolute value of the spreading parameter in this frequency range does not significantly affect the overall energy distribution, evaluated in a mean square error sense.

The empirical equation for the spreading parameter utilized in the proposed directional spectra in both Figs. 4.9 and 4.10 has been

defined as a power function, as indicated in Eq.(3.15), for values to the right of s_c and a constant, as indicated in Eq.(3.16), for values to the left of s_c . Normally, the spreading parameter power function to the right of s_c covers an interval from the critical point, f_c , to the deep water frequency, indicated in Eq.(3.23). However, if the energy density drops by more than an order of magnitude prior to the deep water frequency, then the spreading parameter formula is evaluated over an abbreviated frequency range corresponding to the first relative minimum observed in the smoothed spreading parameter. The raw data one-dimensional spectrum (Fig. 4.9) indicates high energy density values at frequencies beyond the deep water wave condition. This occurs because a finite amount of energy remains in the velocity spectrum at high frequencies (Fig. 4.10) due to instrument noise. Then the inverse transfer function, Eq.(2.11) becomes very large at high frequencies, causing the calculated water surface elevation spectrum to become proportionately large. Clearly, this is a result of the numerical procedure, not an indication of wave activity at the water surface. Consequently, raw data beyond the deep water frequency should be ignored.

The graphical outputs from the same sample utilizing the S/D_1 and S/D_2 methods are shown in Figs. 4.11, 4.12, 4.13 and 4.14. The spreading parameter distribution from S/D_1 is closely related to the distribution from S/D_2 except at low frequencies where long wave effects become significant. However, both distribution curves of the spreading parameter solved from S/D_1 and S/D_2 differ greatly from the one solved from GEO.

A tabular summary comparing the three methods for the October 26 data is presented in Table 4.9. Results include total energy estimated from the smoothed and proposed directional spectra, spectral peak values, five JONSWAP parameters, two parameters of the spreading parameter power function to the right of s_c , and main directions evaluated in the time and frequency domains. According to Table 4.9, the root mean square errors for the proposed directional water surface elevation

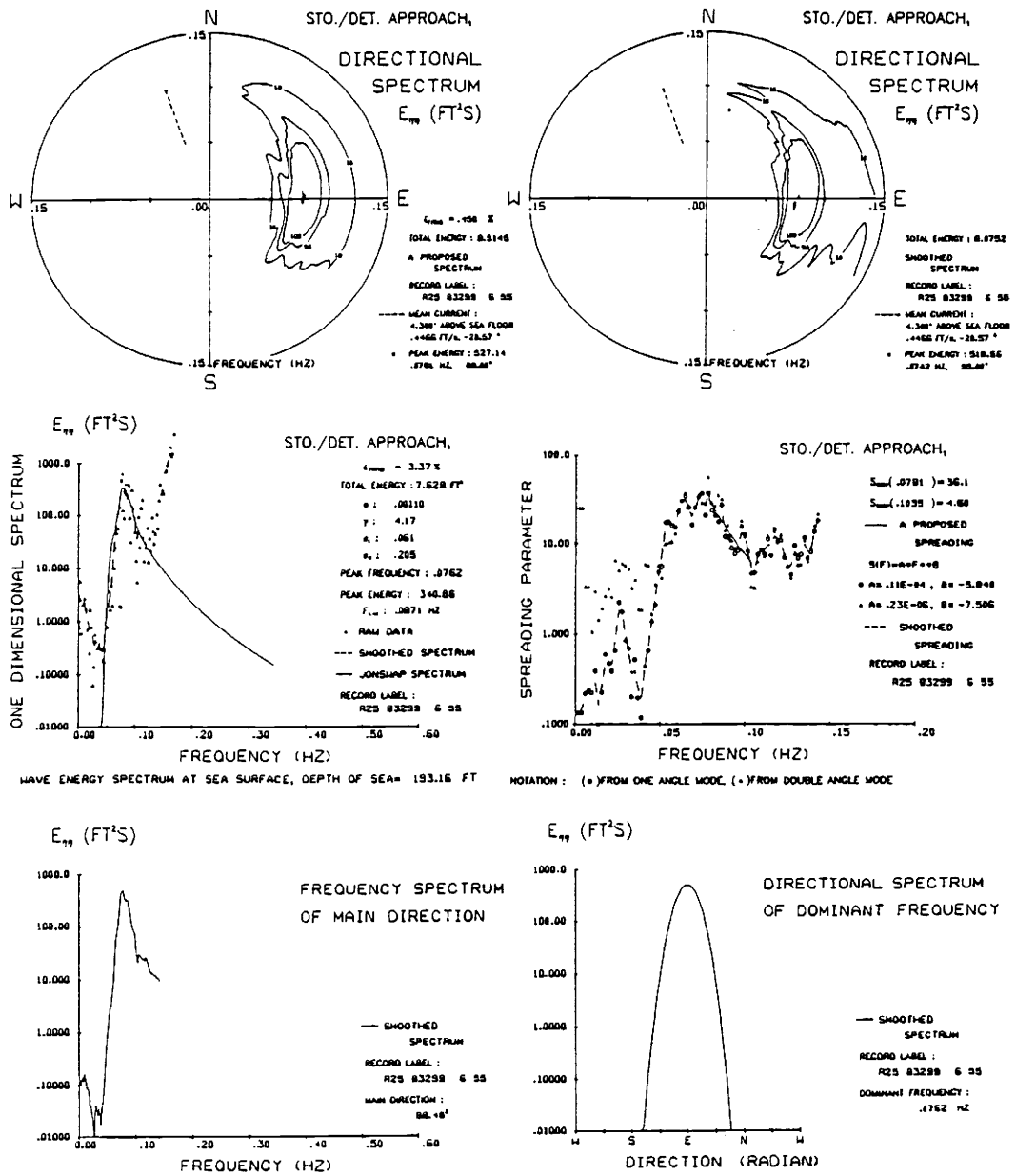


FIG. 4.11 Results of directional wave spectrum from the stochastic/deterministic approach one angle mode solution

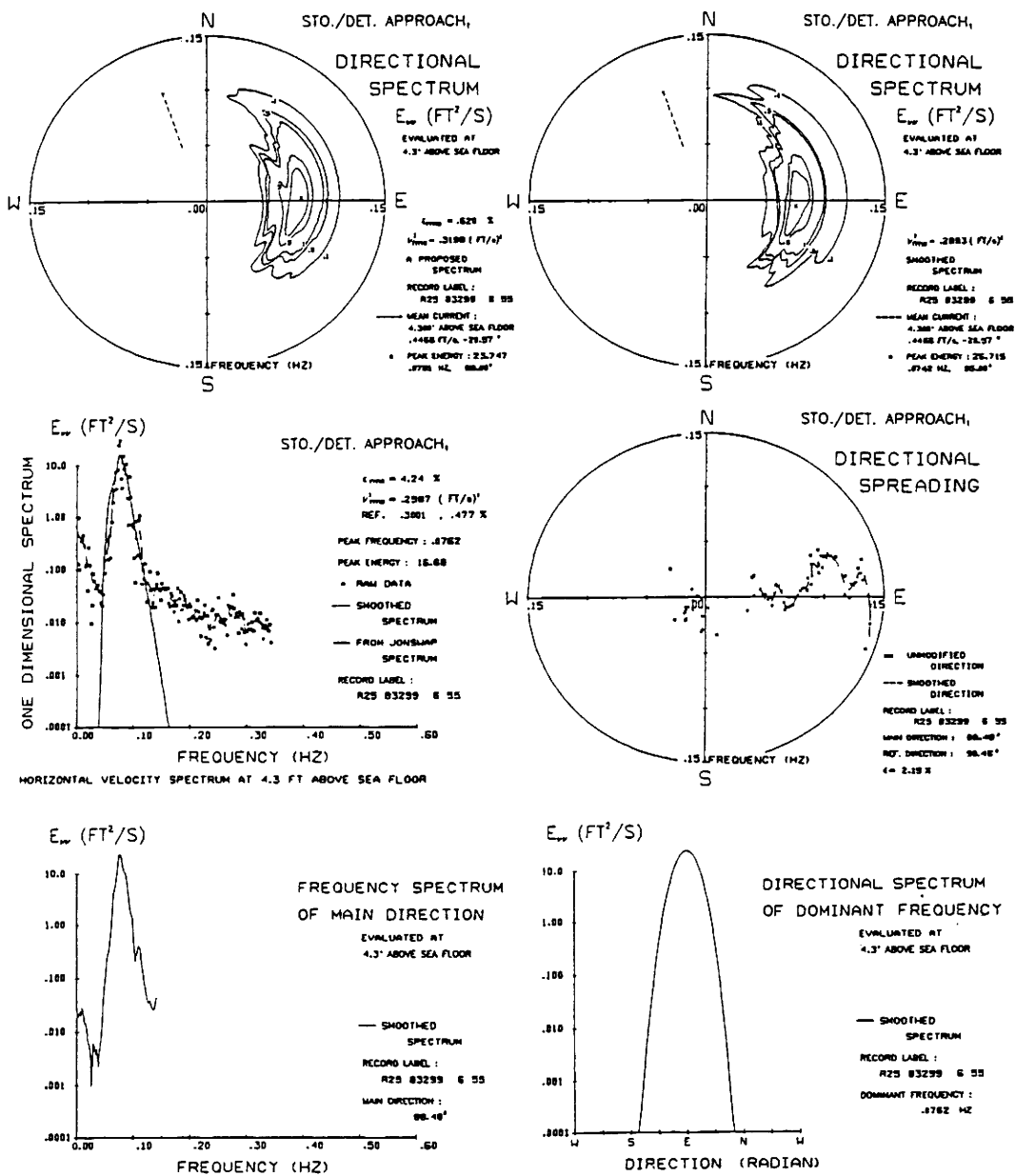


FIG. 4.12 Results of directional velocity spectrum from the stochastic/deterministic approach one angle mode solution

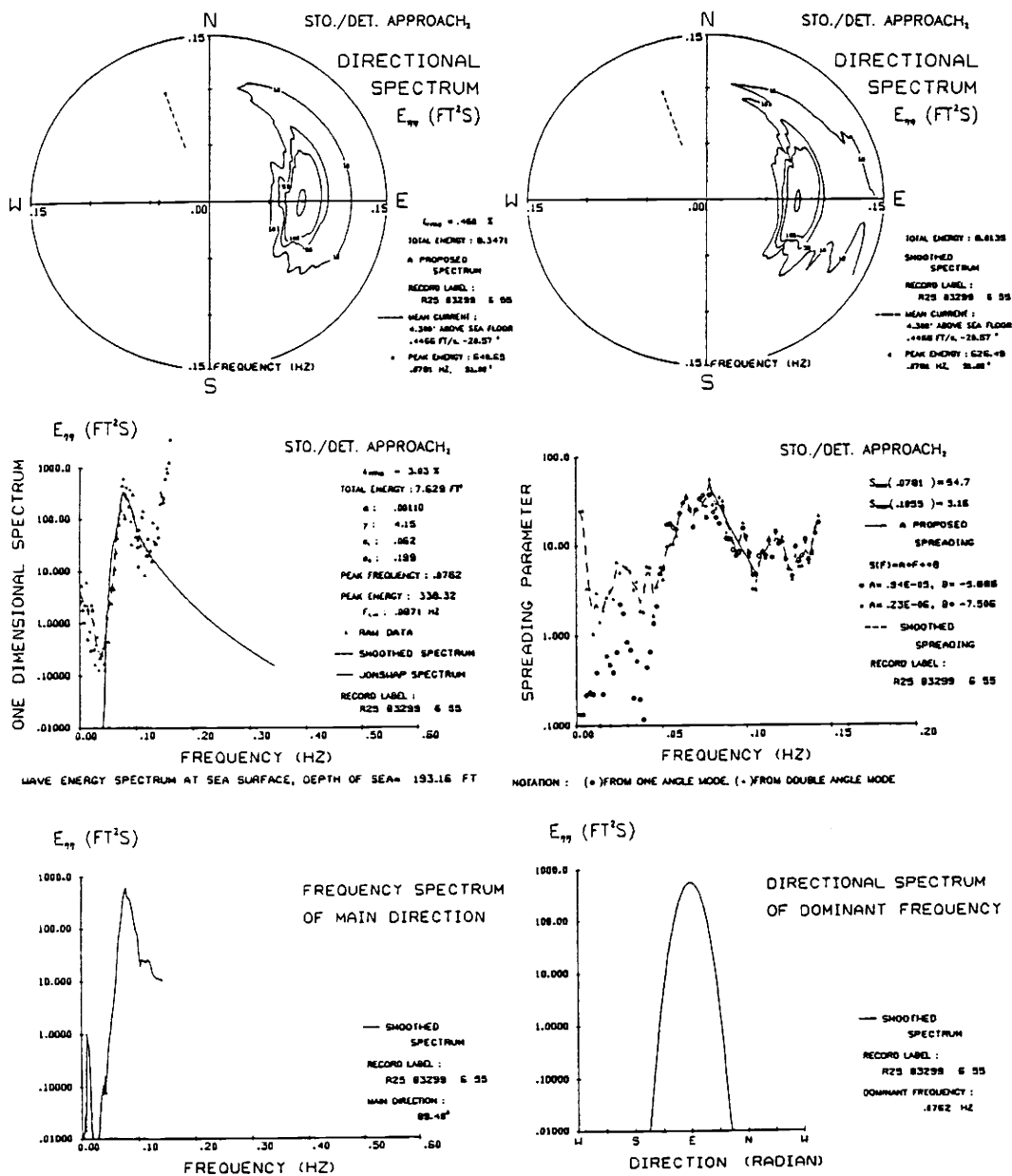


FIG. 4.13 Results of directional wave spectrum from the stochastic/deterministic approach double angle mode solution

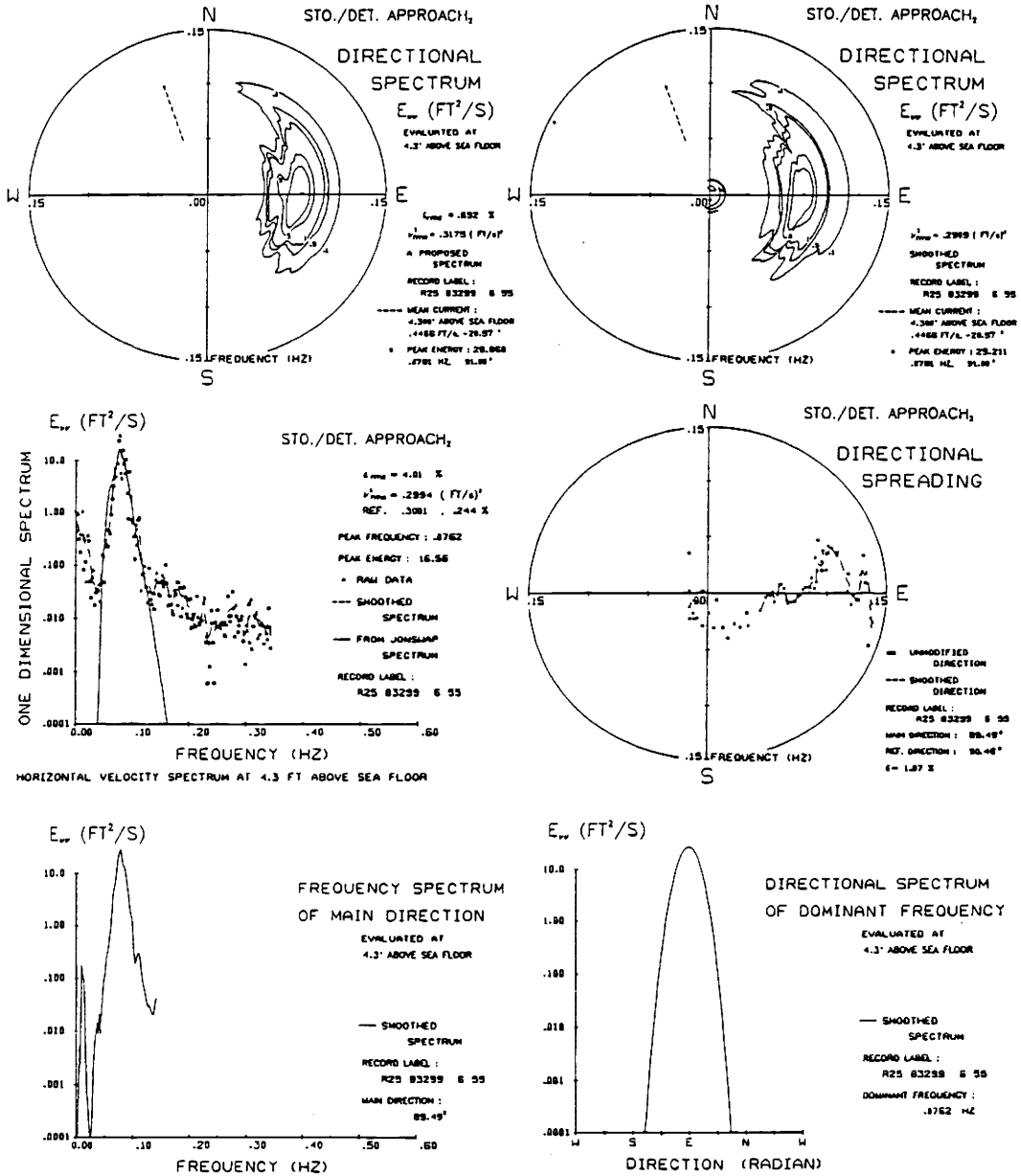


FIG. 4.14 Results of directional velocity spectrum from the stochastic/deterministic approach double angle mode solution

TABLE 4.9 Directional spectra summary

Date: Oct 26, 1982 Init. time: 6:55 Water depth: 193.2 (ft)
 Mean current(4.3 ft above bottom): .45 (ft/s), -20.6 (o) $\overline{V_t^2} = \underline{.30 (ft/s)^2}$, $\overline{\phi} = \underline{90.5 (o)}$

ONE DIMENSIONAL WATER SURFACE WAVE ENERGY SPECTRUM

	smoothed spectrum	JONSWAP spectrum								
	E_{total} (ft ²)	E_{total} (ft ²)	E_p (ft ² /s)	f_p (Hz)	$10^3 \alpha$	γ	σ_L	σ_R	ϵ_{rms} (%)	$f_{1,-1}$ (Hz)
GEO.	8.094	8.11	346	.0762	1.12	4.17	.057	.208	3.37	.0873
S/D ₁	8.075	7.63	341	.0762	1.10	4.17	.061	.205	3.37	.0871
S/D ₂	8.014	7.63	338	.0762	1.10	4.15	.062	.199	3.03	.0871

PROPOSED DIRECTIONAL WATER SURFACE WAVE ENERGY SPECTRUM

	E_{total} (ft ²)	E_p (ft ² /s)	f_p (Hz)	ϕ_p (o)	ϵ_{rms} (%)	ϕ_{main} (o)	s_c	f_c (Hz)	A_R	B_R
GEO.	8.656	383	.0762	92	.40	87.3	19.2	.0723	.50 10 ⁻⁴	-2.219
S/D ₁	8.514	527	.0781	89	.45	88.5	36.1	.0781	.11 10 ⁻⁶	-5.840
S/D ₂	8.347	641	.0781	91	.46	89.5	54.7	.0781	.23 10 ⁻⁶	-7.506

	<u>SMOOTHED</u> $E_{VV}(f)$	<u>PROPOSED</u> $E_{VV}(f)$				<u>PROPOSED</u> $E_{VV}(f, \phi)$				
	E_{total} (ft/s) ²	E_{total} (ft/s) ²	E_p (ft ² /s)	f_p (Hz)	ϵ_{rms} (%)	E_{total} (ft/s) ²	E_p (ft ² /s)	f_p (Hz)	ϕ_p (o)	ϵ_{rms} (%)
GEO.	.287	.299	16.9	.0762	4.6	.320	18.7	.0762	92	.56
S/D ₁	.289	.299	16.7	.0762	4.2	.320	23.7	.0781	89	.62
S/D ₂	.291	.299	16.6	.0762	4.0	.318	28.9	.0781	91	.69

spectrum or velocity spectrum are small, less than 1%, for all three solution methods. Also, the root mean square errors associated with the proposed one-dimensional spectra are all less than 5%. However, the total energy densities estimated from the proposed water surface elevation spectrum and velocity spectrum may have errors up to 6% and 10%, respectively, of the smoothed directional wave spectrum and velocity spectrum.

Differences between the two-sided spreading parameter power function and one-sided power function are illustrated in Fig. 4.15. Alternative spreading function formulae are discussed in Section 3.4.2. The spreading parameter distributions are shown in the lower right hand corner of the figure. Water surface elevation directional spectra are presented on the left, velocity directional spectra are presented on the right. Smoothed raw data results appear in the center row while the one-sided and two-sided spreading function results are presented in the first and third rows, respectively. Smoothed raw data central angle distributions rather than empirical distributions were utilized for the proposed directional spectra in Fig. 4.15. A summary of total energy densities estimated from the smoothed directional spectra and from the alternative proposed directional spectra are tabulated in Table 4.10. Root mean square errors associated with alternative spreading functions are also listed. Both graphical and tabular results

TABLE 4.10 Total energy densities and root mean square errors of directional spectra for alternative spreading function representations

	smoothed spectra	proposed spectra			
		$s_{1\text{-side}}^*$		$s_{2\text{-side}}^{**}$	
	E_{total}	E_{total}	$\epsilon_{\text{rms},2\text{-D}}$	E_{total}	$\epsilon_{\text{rms},2\text{-D}}$
$E(f,\phi)$	8.094 (ft ²)	8.656	.40	8.655	.39
$E_{\sqrt{V}}(f,\phi)$.2870 (ft/s) ²	0.320	.56	0.320	.53
* $A_L=15.340$, $B_L=0.000$, $A_R=.050$, $B_R=-2.22$					
** $A_L=.23 \times 10^7$, $B_L=4.435$, $A_R=.050$, $B_R=-2.22$					

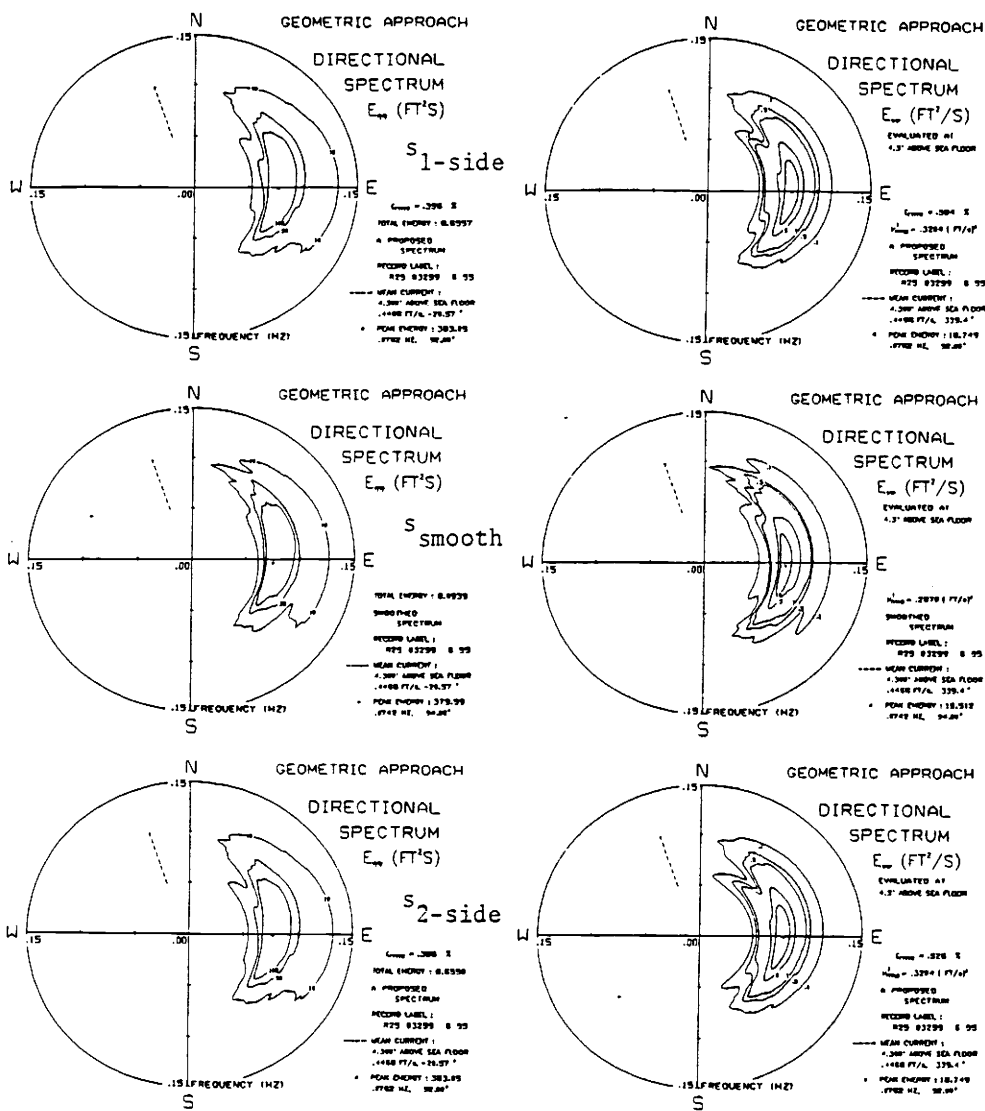
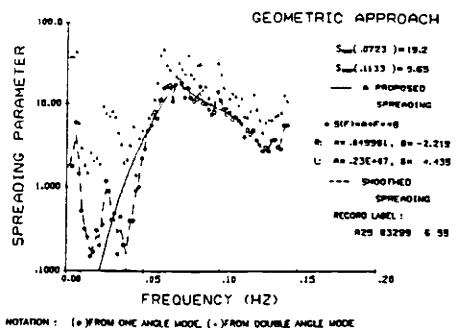


FIG. 4.15 Comparison of directional spectra for alternative spreading function representations



NOTATION : (o) FROM ONE ANGLE MODE, (-) FROM DOUBLE ANGLE MODE

indicate little difference between the one-sided and two-sided spreading functions in the proposed directional spectrum models.

The main direction, ϕ_{main} , and the third-order polynomial function, ϕ_{poly} , are considered as alternatives in the proposed directional spectrum model. The two-sided spreading parameter power functions are utilized in comparing the two models. The resulting graphical outputs are shown in Fig. 4.16. The central angle distribution with respect to frequency appears in the lower right hand corner of the figure; both raw data and the polynomial function are shown. The geometric approach is used to solve for water surface elevation directional spectra on the left and velocity directional spectra on the right. The smoothed raw data is graphed in the center row while the results for the proposed central angle represented as a constant, ϕ_{main} , appear in the top row and the polynomial function results appear in the bottom row. Both functions smooth the results relative to the raw data. The ϕ_{main} results are symmetric about a constant ϕ_{main} . The polynomial central angle results are symmetric about a central angle which varies with frequency, providing a more realistic appearance to the directional spectra. However, root mean square errors associated with both methods, tabulated in Table 4.11, are less than 1%. The polynomial central angle results are somewhat better than the constant central angle results and should be used for improved graphical presentations. However, a constant central

TABLE 4.11 Total energy densities and root mean square errors of directional spectra for alternative central angle representations

	smoothed spectra	proposed spectra			
		ϕ_{main}^*		ϕ_{poly}^{**}	
	E_{total}	E_{total}	$\epsilon_{\text{rms},2-D}$	E_{total}	$\epsilon_{\text{rms},2-D}$
$E(f, \phi)$	8.094 (ft ²)	8.695	.68	8.652	.52
$E_{\sqrt{V}}(f, \phi)$	0.287 (ft/s) ²	0.320	.73	0.320	.59
** $\phi_{\text{main}} = 87.31$					
** $\phi_{\text{poly}} = 90.00 + 1419.6f_n - 28536.8f_n^2 + 128392.0f_n^3$					

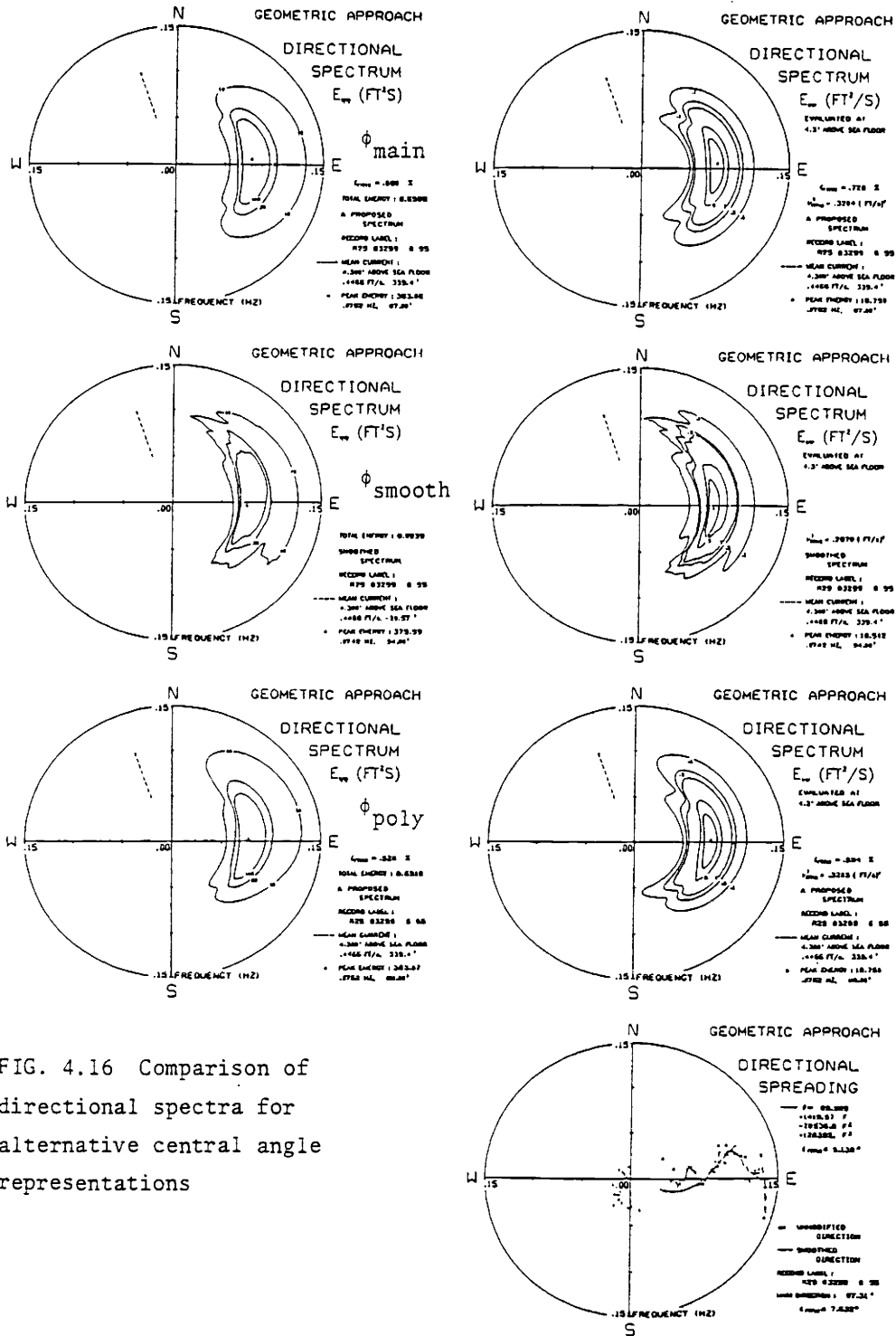


FIG. 4.16 Comparison of directional spectra for alternative central angle representations

angle equal to ϕ_{main} appears to provide a satisfactory representation of directional spectrum energy density.

4.5 Parametric Analysis

Empirical equations have been proposed to represent the water surface elevation directional spectrum as discussed in Section 3.4. The directional spectrum is summarized by Eq.(3.24), the latter requiring frequency dependent relationships for the one-dimensional frequency spectrum, the spreading parameter and the central angle of wave propagation. The one-dimensional frequency spectrum is represented by the five parameter JONSWAP spectrum, defined in Eq.(3.13). The frequency dependent spreading parameter is defined by a two-sided exponential relationship in Eq.(3.15). A polynomial form for the frequency dependent central angle of wave propagation is defined in Eq.(3.17). Ten wave records with the highest energy levels were selected to analyze via the geometric method to obtain least squares best fit values to the empirical parameters. The results are summarized in Table 4.12, along with root mean square errors between the empirical directional spectra and the smoothed raw data spectra. Note that all errors are less than 2%, indicating that the empirical formulae can provide reasonable precision as well as efficiency in quantifying directional spectrum properties.

All significant data sets identified in Section 4.4.3 have been analyzed via the geometric method to obtain abbreviated versions of the least squares best fit empirical parameters. The abbreviated empirical formulations use the one-sided spreading parameter, Eqs.(3.15) and (3.16), and a constant central angle equal to ϕ_{main} , (Eq. 3.20). Results are tabulated in Table 4.13. Again, root mean square errors for the empirical spectra are less than 2% relative to the smoothed raw data spectra, suggesting that the abbreviated empirical formulations are also quite useful for quantifying wave directional spectrum properties.

In Table 4.13 the average values and standard deviations of the

TABLE 4.12 Empirical directional water surface elevation spectrum
summary for ten high energy data sets

Date	Init. time	Depth (ft)	f_p (Hz)	$10^4 \alpha$	γ	σ_L	σ_R	A_L	B_L	f_c (Hz)	A_R	B_R	ϕ_{main} (°)	$10^{-1}c_0$	$10^{-2}c_1$	$10^{-3}c_2$	$10^{-4}c_3$	$\epsilon_{rms,2-D}$ (%)
8/ 5/82	20:11	179.5	.088	6.40	4.37	.037	.101	$.126 \times 10^4$	1.22	.074	$.770 \times 10^{-1}$	-2.02	80.9	9.0	-12.13	20.20	-8.47	.85
10/24/82	6:45	185.9	.082	5.53	4.07	.033	.030	$.720 \times 10^6$	3.55	.069	$.512 \times 10^{-2}$	-2.41	71.9	9.0	-14.43	38.52	-28.31	1.39
10/25/82	6:51	185.8	.078	4.60	3.70	.019	.028	$.300 \times 10^8$	5.53	.064	$.357 \times 10^{-5}$	-5.44	87.0	9.0	-19.54	57.29	-41.16	1.58
10/26/82	6:55	193.2	.076	11.2	4.17	.057	.208	$.230 \times 10^7$	4.44	.072	$.500 \times 10^{-1}$	-2.22	87.3	9.0	14.20	-28.54	12.84	.52
10/26/82	14:57	192.2	.084	22.0	4.00	.225	.189	$.360 \times 10^{12}$	9.08	.078	$.170 \times 10^{-2}$	-3.81	98.3	9.0	-5.00	19.57	-14.72	.57
10/27/82	7:01	192.9	.088	30.0	4.38	.050	.048	$.400 \times 10^5$	2.87	.076	$.314 \times 10^{-3}$	-4.44	104.7	9.0	-15.37	47.06	-31.27	.64
3/24/83	13:34	56.52	.059	3.50	3.98	.048	.058	$.660 \times 10^9$	5.56	.062	$.700 \times 10^{-4}$	-5.25	98.1	9.0	6.75	-13.01	6.70	1.38
3/25/83	1:18	58.73	.064	3.84	2.93	.070	.086	$.280 \times 10^{11}$	7.19	.064	$.800 \times 10^{-7}$	-7.51	96.0	9.0	4.46	-7.88	3.74	.76
3/25/83	13:02	57.58	.072	1.38	11.4	.210	.167	$.120 \times 10^{10}$	6.24	.057	$.184 \times 10^0$	-1.80	91.8	9.0	.71	-2.71	2.40	1.57
3/27/83	3:10	57.82	.072	7.70	2.68	.088	.103	$.700 \times 10^6$	3.19	.068	$.105 \times 10^{-5}$	-6.64	95.7	9.0	6.75	-9.03	1.87	.67

TABLE 4.13 Empirical directional water surface elevation spectrum
summary for all significant data sets

Month: August Year: 1982 Meter No. 24 Meter height above bottom: 4.3 (ft)

Date	Init. time	Depth (ft)	f_p (Hz)	$10^4 \alpha$	γ	σ_L	σ_R	θ_{main} (°)	Λ_L ($B_L=0$)	f_c (Hz)	Λ_R	B_R	$\epsilon_{rms, 2-D}$ (%)
5	8:11	177.4	.0703	.181	4.14	.080	.108	78.5	5.15	.0684	$.116 \times 10^{-2}$	-3.17	.75
6	4:11	180.3	.0644	.017	7.35*	.123	.125	81.0	11.57	.0664	$.227 \times 10^{-1}$	-8.28	.54
6	20:11	179.5	.0879	6.40	4.37	.037	.101	80.9	13.26	.0742	$.770 \times 10^{-1}$	-2.02	.86
7	0:11	182.0	.0938	7.55	4.17	.055	.048	75.2	11.95	.0801	$.153 \times 10^{-3}$	-2.68	.97
9	8:11	178.4	.0918	1.99	6.07	.251	.095	96.9	13.56	.0762	$.850 \times 10^{-9}$	-3.80	.64
9	12:11	179.7	.0957	5.65	3.92	.068	.056	92.8	19.38	.0957	$.401 \times 10^{-8}$	-10.53	1.19
13	0:11	178.5	.0644	.025	3.97	.090	.059	83.3	4.94	.0840	$.688 \times 10^{-8}$	-8.28	.97
Average			.0812		4.44	.100	.085	84.1		.0778		-5.54	
±Std.Dev.			±.0142		±.81	±.072	±.030	±7.86		±.0101		±4.00	

* not include in average

Month: October Year: 1982 Meter No. 25 Meter height above bottom: 4.3 (ft)

21	10:26	192.0	.0586	.072	3.57	.060	.043	46.8	29.40	.0508	$.277 \times 10^{-9}$	-7.01	.72
22	2:30	193.2	.0938	31.4	3.65	.048	.058	14.0	6.33	.0879	$.154 \times 10^{-1}$	-6.26	.56
24	2:42	191.6	.0859	8.60	3.95	.132	.076	58.3	13.84	.0703	$.140^{-5}$	-1.77	.60
26	2:54	190.8	.0918	4.50	10.29*	.193	.117	71.0	9.08	.0742	$.290 \times 10^{-5}$	-3.98	.71
26	6:55	193.2	.0762	11.2	4.17	.057	.208	87.3	15.34	.0723	$.050^{-10}$	-2.22	.68
26	10:56	193.1	.0703	6.01	4.52	.061	.517	87.2	38.21	.0664	$.361 \times 10^{-2}$	-8.55	.95
26	14:57	192.2	.0840	22.0	4.00	.225	.189	98.3	25.33	.0781	$.170 \times 10^{-5}$	-3.81	.65
27	3:00	190.6	.0879	19.6	3.66	.045	.059	108.1	11.68	.0879	$.450 \times 10^{-5}$	-4.18	.69
27	7:01	192.9	.0879	30.0	4.38	.050	.048	104.7	23.32	.0781	$.314 \times 10^{-5}$	-4.44	.67
27	11:02	200.3	.0840	3.30	4.43	.040	.423	106.9	7.06	.0820	$.630 \times 10^{-7}$	-3.77	.58
28	19:10	202.0	.0898	10.0	4.35	.036	.022	95.4	2.45	.0742	$.132 \times 10^{-2}$	-5.59	.66
28	23:11	200.9	.0879	13.9	3.51	.045	.051	96.1	2.60	.0762	$.880 \times 10^{-6}$	-2.25	.48
29	3:12	200.0	.0859	13.0	3.80	.044	.058	89.4	2.75	.0762	$.170 \times 10^{-2}$	-4.82	.44
29	7:13	201.8	.0977	14.7	5.84	.087	.062	77.6	2.70	.0898	$.690 \times 10^{-8}$	-2.52	.51
29	11:14	203.7	.0859	9.80	4.06	.068	.053	80.0	4.85	.0703	$.848 \times 10^{-1}$	-5.90	.72
31	19:28	198.7	.0859	5.70	8.97*	.125	.134	123.0	10.07	.0723	$.845 \times 10^{-1}$	-1.86	.75
Average			.0846		4.14	.082	.132	84.0		.0752		-3.96	
±Std.Dev.			±.0094		±.59	±.057	±.143	±26.8		±.0095		±2.10	

* not include in average

TABLE 4.13 (continued) Empirical directional water surface elevation spectrum summary for all significant data sets

Month: October Year: 1982 Meter No. 43 Meter height above bottom: 14. (ft)

Date	Init. time	Depth (ft)	f_p (Hz)	$10^4 \alpha$	γ	σ_L	σ_R	ϕ_{main} (°)	Λ_L ($B_L=0$)	F_c (Hz)	Λ_R	B_R	$\epsilon_{rms, 2-D}$ (%)
19	18:18	182.9	.0840	.130	21.33*	.195	.049	82.8	3.01	.0781	$.790 \times 10^{-13}$	-10.50	.65
21	2:26	185.8	.0927	1.10	2.78	.027	.016	88.1	2.15	.0518	.172	-.888	.59
21	10:28	184.5	.0586	.062	3.77	.059	.043	88.0	2.43	.0566	$.720 \times 10^{-7}$	-4.47	.93
21	18:30	184.4	.0811	.120	9.46*	.041	.115	60.6	3.24	.0576	$.440 \times 10^{-13}$	-4.77	1.86
23	2:38	184.9	.0859	4.28	4.50	.025	.040	90.4	4.76	.0762	$.730 \times 10^{-10}$	-10.53	.89
23	14:41	186.4	.0937	.780	20.78*	.100	.105	59.0	2.49	.0790	$.104 \times 10^{-2}$	-8.55	1.14
24	6:45	185.9	.0820	5.53	4.07	.033	.030	71.9	2.87	.0693	$.512 \times 10^{-6}$	-2.41	1.31
24	14:47	185.6	.0840	.760	21.00*	.145	.066	70.2	3.28	.0723	$.290 \times 10^{-9}$	-4.47	.74
25	2:50	183.7	.0830	5.40	3.91	.019	.026	92.7	3.04	.0811	$.760 \times 10^{-7}$	-7.01	.56
25	6:51	185.8	.0781	4.60	3.70	.019	.028	87.0	9.70	.0644	$.357 \times 10^{-2}$	-5.44	1.54
25	10:52	185.2	.0742	1.39	4.10	.044	.043	90.3	3.41	.0664	$.171 \times 10^{-2}$	-2.84	.48
Average			.0816		3.83	.063	.051	80.1		.0679		-5.62	
±Std.Dev.			±.0095		±.53	±.057	±.032	±12.4		±.0101		±3.05	

* not include in average

Month: March Year: 1983 Meter No. 26 Meter height above bottom: 4.3 (ft)

24	7:42	61.25	.0586	1.68	4.38	.063	.090	89.1	24.53	.0547	$.670 \times 10^{-2}$	-2.86	1.32
24	13:34	56.52	.0586	3.50	3.98	.048	.058	98.1	132.1	.0625	$.700 \times 10^{-10}$	-5.25	1.05
24	16:30	57.14	.0644	2.81	2.99	.044	.044	102.4	50.91	.0625	$.606 \times 10^{-2}$	-8.28	.83
24	19:26	59.91	.0625	2.86	2.88	.059	.094	95.5	35.41	.0606	$.575 \times 10^{-5}$	-3.15	.92
24	22:22	60.45	.0645	3.48	4.06	.076	.164	94.0	44.50	.0645	$.633 \times 10^{-9}$	-4.11	.68
25	1:18	58.73	.0645	3.84	2.93	.070	.086	96.0	63.47	.0644	$.800 \times 10^{-1}$	-7.51	.76
25	4:14	58.85	.0644	1.32	4.06	.069	.114	90.4	19.89	.0606	$.331 \times 10^{-9}$	-2.32	.83
25	7:10	61.00	.0664	3.33	3.99	.047	.073	92.6	36.49	.0703	$.115 \times 10^{-1}$	-8.28	.94
25	10:06	60.87	.0684	3.10	4.05	.080	.118	94.3	25.94	.0664	$.548 \times 10^{-1}$	-2.31	.57
25	13:02	57.58	.0723	1.38	11.35*	.210	.167	91.8	29.17	.0566	.184	-1.80	1.54
25	15:02	55.96	.0762	5.20	3.95	.072	.058	97.3	24.08	.0742	.147	-2.00	.58
25	18:54	58.63	.0723	2.66	4.26	.083	.201	99.6	22.26	.0684	.777	-1.29	.71
27	3:10	57.82	.0723	7.70	2.68	.088	.103	95.7	51.34	.0684	$.105 \times 10^{-7}$	-6.64	.86
27	6:06	58.02	.0742	11.7	3.85	.055	.065	88.5	19.45	.0703	.667	-1.31	1.57
Average			.0670		3.70	.076	.102	94.7		.0646		-4.08	
±Std.Dev.			±.0057		±.59	±.041	±.046	±4.0		±.0055		±2.61	

* not include in average

JONSWAP parameters have been evaluated for the significant seasonal data sets. These average values do not reflect the mean JONSWAP parameter values obtained during the Joint North Sea Wave Project ($\gamma=3.3$, $\sigma_L=.07$, $\sigma_R=.09$) (Hasselmann et al., 1975). This is because the referenced JONSWAP values were evaluated under well-behaved wind conditions, implying the existence of a single or dominant wind fetch and duration. It is generally believed that a dominant storm will generate a wave spectrum with a single spectral peak. The JONSWAP spectrum appears to be able to represent a large range of single-peaked spectral shapes. However many wave spectra evaluated in the present study have two or more spectral peaks, implying the presence of waves from two or more storm sources. The JONSWAP spectrum may not be precisely applicable to those spectra which contain two or more peaks, consequently the resulting JONSWAP parameters deviate from standard values.

The average values of B_R from the significant seasonal data sets in Table 4.13 are not equal to -2.7 as suggested by Eq.(2.43-1). Also, the standard deviations of these average values are large, contradicting the existence of a single constant power as shown in Eq.(2.43-1). However, this variability in B_R may be due to the superposition of many wave systems generated from many storms. To substantiate this hypothesis, parameter values from single peaked spectra are examined.

An examination of the graphs of one-dimensional frequency spectra from the available significant data sets reveals very few single peaked spectra. As a compromise, single storm wave spectra have been approximated as those with low secondary peaks at higher frequencies. It is reasoned that relatively small, secondary peaks may be generated by local winds or nonlinear wave interactions. The effects of the secondary peak have been minimized by terminating the analysis of spectral properties at a frequency less than that associated with the secondary peak.

Spectral properties of the dominant peak have been evaluated via the S/D_1 , S/D_2 and GEO. methods for the appropriate significant seasonal data sets. Tabular summaries of spectral properties E_{total} , E_p , f_p ,

TABLE 4.14 Numerical behavior of directional wave properties
 — GEOMETRIC APPROACH

Date	Init. time	E_{total} (ft ²)	E_p (ft ² s)	f_p (Hz)	$10^4 \alpha$	γ	σ_L	σ_R	$f_{1,-1}$ (Hz)	$10^8 \Lambda_R$	B_R	$10^8 \Lambda_{Ro}$	Λ_{R1}
3/27/83	6:06	6.488	382.5	.0742	11.7	3.85	.055	.065	.0852	4.356	-8.275	2.426	29.94
10/27/82	7:01	5.406	476.9	.0879	32.8	4.00	.048	.047	.1010	1.940	-8.275	1.123	3.262
3/27/83	3:10	3.288	199.0	.0723	33.0	3.48	.088	.104	.0833	1.388	-8.275	.7686	11.53
3/25/83	1:18	2.909	192.0	.0644	3.86	2.91	.070	.088	.0746	.9970	-8.275	.5377	20.64
10/26/82	10:56	2.894	302.1	.0703	8.20	3.33	.056	.047	.0816	.4420	-8.55	.5043	8.95
10/26/82	6:55	2.660	346.1	.0762	9.78	4.77	.061	.108	.0860	.7170	-8.275	.4019	4.58
3/25/83	7:10	2.244	195.8	.0664	3.32	4.00	.047	.067	.0765	.0031	-10.525	.7580	23.40
10/29/82	3:12	1.678	201.3	.0860	13.1	3.79	.044	.047	.0994	.1810	-8.55	.2046	.679
10/25/82	2:50	1.396	102.8	.0830	5.44	3.91	.019	.026	.0982	.1660	-8.55	.6795	.694
10/24/82	6:45	1.025	115.2	.0820	5.49	4.10	.033	.030	.0959	8.640	-7.012	.2093	.948
10/25/82	6:51	.8441	110.2	.0781	4.34	3.88	.019	.031	.0924	.3400	-8.275	.1916	3.15
10/27/82	11:02	.7871	66.18	.0840	3.24	4.48	.041	.081	.0961	.0033	-10.525	.4968	2.20
10/25/82	10:52	.4011	43.46	.0781	1.67	3.97	.044	.062	.0897	1.623	-7.506	.1287	1.02
8/ 5/82	8:11	.1530	8.286	.0703	.180	4.14	.078	.108	.0793	.0633	-8.55	.0723	1.64
10/21/82	10:26	.0639	7.108	.0586	.074	3.47	.059	.043	.0680	.0857	-8.275	.0452	3.82
10/21/82	18:30	.0527	6.180	.0810	.330	3.43	.026	.047	.0953	.0866	-8.55	.0982	.470
10/21/82	10:28	.0505	9.055	.0586	.076	4.31	.023	.032	.0691	.0141	-8.55	.0141	1.192
10/21/82	2:26	.0253	3.424	.0586	.030	4.18	.038	.045	.0682	.0118	-8.55	.0136	.949
Average						3.89	.048	.060			-8.52		
±Std.Dev.						±.44	±.020	±.027			±.83		

TABLE 4.15 Numerical behavior of directional wave properties

— STO./DET. APPROACH₁

Date	Init. time	E _{total} (ft ²)	E _p (ft ² s)	f _p (Hz)	10 ⁴ α	γ	σ _L	σ _R	f _{1,-1} (Hz)	10 ⁸ A _R	B _R	10 ⁸ A _{Ro}	A _{R1}
3/27/83	6:06	6.482	380.0	.0742	11.7	3.84	.055	.067	.0852	.0254	-10.525	4.923	60.60
10/27/82	7:01	5.886	483.7	.0879	3.41	3.91	.048	.045	.1010	4.900	-8.275	2.835	8.240
10/26/82	6:55	4.284	340.8	.0762	12.1	3.81	.060	.073	.0872	.0075	-10.525	1.378	13.95
10/26/82	10:56	4.243	295.8	.0703	8.30	3.22	.056	.044	.0818	1.480	-8.550	1.690	29.54
3/27/83	3:10	3.828	197.7	.0703	6.42	2.78	.066	.144	.0815	8.213	-8.275	4.519	81.16
10/22/82	2:30	3.779	298.4	.0938	32.3	3.52	.048	.051	.1083	5.905	-8.275	3.467	5.57
3/25/83	1:18	3.343	191.5	.0644	3.73	3.00	.072	.094	.0744	3.280	-8.275	1.770	69.50
3/25/83	7:10	2.273	197.3	.0664	3.30	4.06	.048	.069	.0764	1.130	-8.55	1.294	40.40
3/25/83	10:06	2.220	160.5	.0683	3.11	4.05	.077	.110	.0773	1.945	-8.275	1.063	29.90
3/25/83	15:58	2.149	155.0	.0762	5.25	3.98	.073	.062	.0865	.0075	-10.525	1.377	14.90
3/24/83	19:26	1.917	168.2	.0625	3.04	2.77	.062	.094	.0727	4.780	-7.506	.3038	14.40
10/28/82	23:11	1.913	166.2	.0879	11.6	3.95	.049	.050	.1012	.5750	-8.55	.6493	1.86
10/25/82	10:52	.3822	40.85	.0781	1.63	3.83	.047	.054	.0897	8.978	-7.506	.7120	5.67
10/19/82	18:18	.1513	10.35	.0840	.510	4.45	.136	.021	.0925	2.480	-7.888	.5446	3.34
8/ 5/82	8:11	.1465	8.846	.0703	.175	4.56	.083	.079	.0788	.1600	-8.55	.1827	4.37
10/21/82	10:26	.0596	7.194	.0586	.076	3.45	.059	.046	.0679	.0172	-8.55	.0198	1.68
10/21/82	10:28	.0503	8.468	.0586	.073	4.24	.022	.032	.0692	.0322	-8.55	.0371	2.69
Average						3.73	.062	.067			-8.66		
±Std.Dev.						±.53	±.024	±.030			±.95		

TABLE 4.16 Numerical behavior of directional wave properties
 — STO./DET. APPROACH₂

Date	Init. time	E _{total} (ft ²)	E _p (ft ² s)	f _p (Hz)	10 ⁴ α	γ	σ _L	σ _R	f _{1,-1} (Hz)	10 ⁸ A _R	B _R	10 ⁸ A _{Ro}	A _{R1}
10/26/82	6:55	4.603	338.3	.0762	12.0	3.80	.061	.079	.0871	3.230	-8.275	1.810	17.90
10/27/82	7:01	4.404	496.5	.0879	35.1	3.90	.052	.044	.1010	3.970	-8.275	2.297	6.67
3/27/83	3:10	4.197	201.7	.0703	6.72	2.71	.068	.146	.0816	9.850	-8.275	5.420	28.20
10/22/82	2:30	3.337	225.8	.0939	21.7	3.96	.055	.053	.1073	5.905	-8.275	3.467	6.04
3/25/83	1:18	3.165	184.0	.0644	3.66	2.94	.072	.093	.0744	3.620	-8.275	1.953	76.00
3/24/83	19:26	2.927	162.3	.0625	2.91	2.83	.059	.094	.0727	.6340	-8.275	.3398	16.10
3/24/83	16:30	2.606	140.3	.0644	2.81	2.92	.093	.046	.0742	.5280	-8.55	.6056	24.30
3/25/83	10:06	2.197	157.4	.0683	3.05	4.05	.079	.111	.0773	12.55	-7.506	.8805	24.70
10/29/82	3:12	2.132	152.8	.0762	5.18	3.98	.073	.063	.0865	1.200	-8.55	1.365	14.81
10/28/82	23:11	1.973	164.3	.0860	12.4	3.27	.039	.038	.1006	.1810	-8.55	.2647	.614
10/27/82	11:02	1.736	160.3	.0879	13.4	3.30	.045	.044	.1023	3.070	-8.275	1.776	4.626
10/25/82/	6:51	.9898	76.21	.0840	3.77	4.44	.040	.090	.0962	.0270	-10.525	4.071	17.97
10/25/82	10:52	.5860	79.96	.0781	3.30	3.70	.019	.028	.0926	.9380	-8.55	1.066	6.489
10/19/82	18:18	.3978	2.904	.0781	.890	4.98	.072	.093	.0876	.9830	-8.275	.5540	5.387
8/ 5/82	8:11	.1358	7.485	.0703	.167	4.06	.083	.086	.0794	.6510	-8.55	.7423	16.68
10/21/82	10:28	.0348	6.512	.0586	.061	3.90	.024	.031	.0694	.0740	-8.55	.0853	6.038
Average						3.67	.058	.071			-8.47		
±Std.Dev.						±.63	±.021	±.033			±.60		

α , γ , σ_L , σ_R , $f_{1,-1}$, A_R and B_R are expressed in Tables 4.14, 15, 16. In these tables, the samples are ordered from large values of E_{total} to small values. Average values and standard deviations are calculated for γ , σ_L , σ_R , and B_R , for each method of analysis. A list of these average values and standard deviations appears in Table 4.17.

TABLE 4.17 Means and Standard Deviations of Parameters

$\gamma, \sigma_L, \sigma_R, B_R$				
Method	γ	σ_L	σ_R	B_R
GEO.	$3.89 \pm .44$	$.048 \pm .02$	$.060 \pm .027$	$-8.52 \pm .83$
S/D ₁	$3.73 \pm .53$	$.062 \pm .024$	$.067 \pm .030$	$-8.66 \pm .95$
S/D ₂	$3.67 \pm .63$	$.058 \pm .021$	$.071 \pm .033$	$-8.47 \pm .060$

The mean JONSWAP parameters obtained here are somewhat different from those obtained from the North Sea Project (Hasselmann et al., 1975). This may be due to meteorological and oceanographical conditions which are unique to the two different ocean systems. Nevertheless, the JONSWAP spectrum parameter mean values expressed in Table 4.17 for the geometric approach are deemed most appropriate to model one-dimensional frequency spectra for single storm wave systems in the offshore Coos Bay, Oregon, area.

Averages of B_R obtained from the various methods are relatively consistent and all have small standard deviations. Thus, a constant value of -8.5, from the geometric method, is proposed for the power in Eq.(2.43-1), instead of a value of -2.7 which was utilized by S.E. Sand (1979). Hence, Eq.(2.43-1) because

$$s_e(f_n) = A_{R1} \left(\frac{f_n}{f_{1,-1}} \right)^{-8.5} \quad (4.6)$$

An alternative form for the right side spreading parameter function is proposed as

$$s_e(f_n) = A_{R0} (f_n)^{-8.5} \quad (4.7)$$

The parameters A_{R1} and A_{Ro} are calculated relative to this constant value for B_R by a regression procedure which evaluates the spreading parameter at the peak frequency utilizing Eq.(3.15) and then returns the values A_{R1} and A_{Ro} utilizing Eqs.(4.6) and (4.7), respectively. Choosing the spreading parameter at the peak frequency, f_p , rather than at the critical frequency, f_c , is thought to be a more significant value for regressing A_{R1} and A_{Ro} . The regressed values of A_{R1} and A_{Ro} are also expressed in Tables 4.14, 15, 16 for each method.

Both parameters A_{Ro} and A_{R1} tend to decrease with decreasing E_{total} and E_p . The statistical correlations among these parameters are calculated and expressed in Table 4.18. The tabular results demonstrate that the parameters E_{total} and A_{Ro} have the highest positive correlation, a value of unity being a perfect correlation.

TABLE 4.18 Correlations among parameters E_{total} , E_p , A_{Ro} , A_{R1}

	GEO.		S/D ₁		S/D ₂	
	A_{Ro}	A_{R1}	A_{Ro}	A_{R1}	A_{Ro}	A_{R1}
E_{total}	.85	.64	.78	.39	.44	.39
E_p	.68	.46	.67	.30	.31	.06

A graph of E_{total} versus A_{Ro} is presented in Figure 4.17, including results obtained from the GEO., S/D₁, S/D₂ methods. The points associated with S/D₂ are more scattered. The points associated with both the GEO. and S/D₁ methods are more well behaved and may be approximated by straight lines in Figure 4.17. The function

$$A_{Ro} = C(E_{total})^D \quad (4.8)$$

indicates a straight line on log-log scaled paper and is utilized here to present an empirical relationship between A_{Ro} and E_{total} . Parameters C and D of Eq.(4.8) are determined utilizing a least square best fit

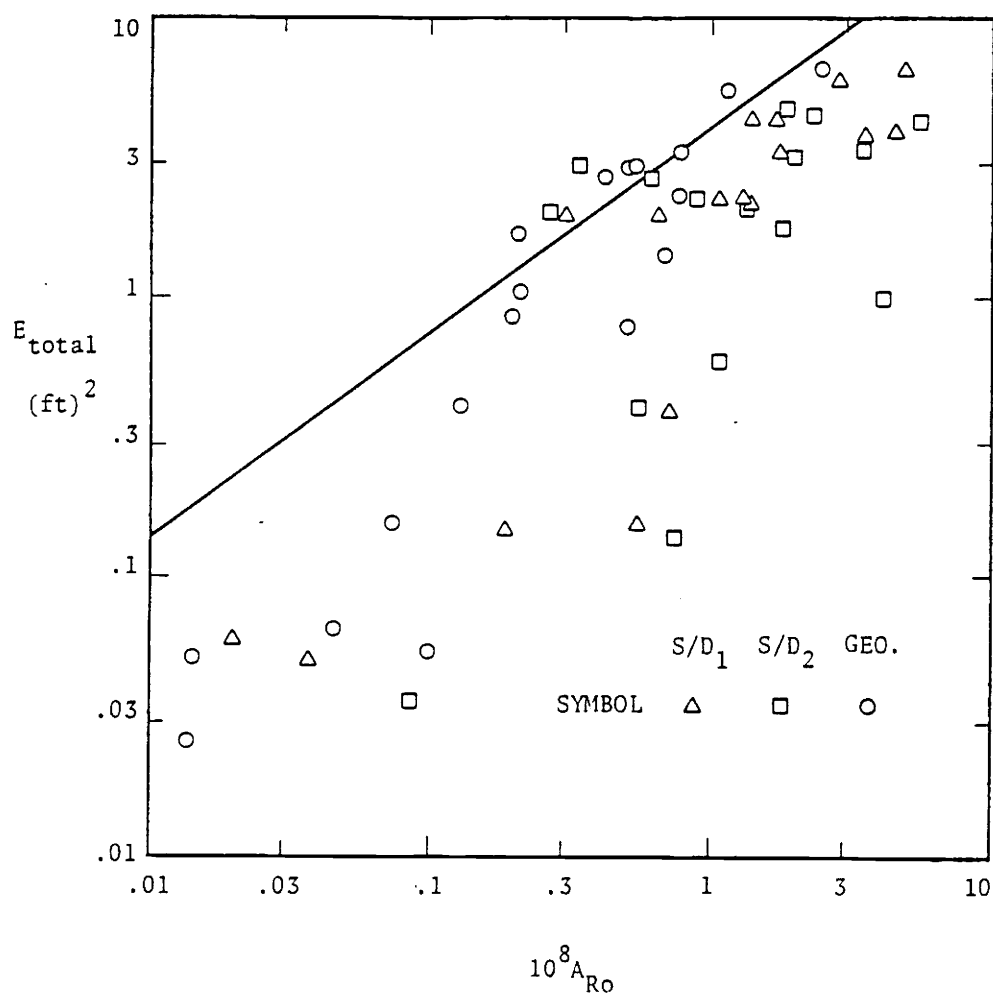


FIG. 4.17 Correlation study of E_{total} and A_{Ro}

procedure which is similar to the one used in determining the parameters A_{R} and B_{R} for the spreading parameter power function expressed by Eq.(3.15). The resulting parameters for the three methods of analysis provide the following equations

TABLE 4.19 Empirical spreading parameter coefficient equations

Method	Equation	Correlation
GEO.	$A_{\text{Ro}} = 1.5 \cdot 10^{-9} (E_{\text{total}})^{1.396}$.85
S/D ₁	$A_{\text{Ro}} = 5.1 \cdot 10^{-9} (E_{\text{total}})^{1.131}$.78
S/D ₂	$A_{\text{Ro}} = 1.24 \cdot 10^{-8} (E_{\text{total}})^{.47}$.44

where E_{total} is the total wave energy density with a unit of ft^2 . The equation for the geometric approach is graphed through the data in Fig. 4.17.

The proposed spreading parameter function of Eq.(4.7) may now be, expressed empirically as

$$s_e(f_n) = C(E_{\text{total}})^D (f_n)^{-8.5} \quad (4.9)$$

However, Eq.(4.9) is suitable only for wave systems generated by a single storm event in the region offshore of Coos Bay, Oregon.

The main direction of wave propagation is shown to vary from 80° in October to 95° in March; see Table 4.13. One may use these seasonal-ly variable values to approximate the central angle of wave propagation in Eq.(3.20). Also, the mean JONSWAP parameters from Table 4.17 may be used to approximate the frequency spectrum shape. The total spectral energy, E_{total} , and peak frequency, f_p , may be obtained from traditional hindcasting procedures for a specific design storm wind velocity, fetch and duration. With E_{total} and f_p known, along with the results of Table 4.17, the JONSWAP spectrum is specified. Similarly, the spreading parameter is specified by Eq.(4.9). Now one can predict the water surface elevation directional spectrum for offshore Coos Bay, Oregon by substituting these specific results into Eq.(3.24).

4.6 Directional Wave Simulation Study

Random wave simulation produces wave property records directly from a designed wave spectrum, called a target spectrum. Only the statistics of the wave property can be reproduced, not the originally measured records. That is, the wave properties are reproduced in a statistical sense by utilizing the wave simulation method (Borgman, 1969).

The concept of a directional wave simulation algorithm comes from

a physical interpretation of the directional spectrum as discussed in Section 2.2. An infinitesimal amplitude wavelet may be thought of as contributing energy to a small interval of frequency and direction. The entire spectrum can then be thought of as the sum of the contributions from a large number of wavelets. Each of these wavelets may have its amplitude evaluated from Eq.(2.51), or

$$a_{mn} = \sqrt{2E(f_n, \phi_m) \Delta f_n \Delta \phi_m} \quad (4.10)$$

where a_{mn} denotes the amplitude of a wavelet within a frequency interval Δf_n and a direction interval $\Delta \phi_m$. More specifically, a wavelet which has an amplitude a_{mn} is regarded as an independent small wave with wave frequency f_n and propagation direction ϕ_m . The surface wave profile then may be represented by the sum of those small, independent wavelets, or

$$\eta(x, y, t) = \sum_{n=1}^N \sum_{m=1}^M a_{mn} \cos(k_n x \cos \phi_m + k_n y \sin \phi_m - 2\pi f_n t + \theta_{mn}) \quad (4.11)$$

Since each small wave is assumed to be independent of others, the phase θ_{mn} is assumed to be uniformly and randomly distributed over the interval $(0, 2\pi)$. Hence, various other wave properties can be described simply by transferring Eq.(4.11) to the desired wave properties in accordance with linear wave theory.

Wave simulation from a one-dimensional frequency spectrum is a simplified model of directional wave simulation. By dropping out the direction index and symbols from Eqs.(4.10) and (4.11), a wave simulation model associated with the frequency spectrum is obtained.

The validity of a wave simulation model is usually tested by evaluating a spectrum from the simulated wave properties and comparing the results with the target spectrum. The wave simulation model associated with a frequency spectrum usually has no difficulty returning the spectral properties of the target spectrum. However, the results obtained from directional wave simulation are usually poorly correlated with

the target directional spectrum. The main reason is that the phases of individual wave frequency components can be nicely described as random variables. However, phases of waves with the same frequency but different directions may not be appropriately represented by a uniform distribution over the interval $(0, 2\pi)$, that is, wave directional components of the same frequency may have related phases.

Poor results from directional wave simulation have been obtained by many investigators in the past. A procedure utilized to improve directional wave simulation results is to look the mean values and standard deviations of spectral properties of many simulation runs. Since each run of many simulations is assumed to be independent of other runs, the mean values and standard deviations of wave properties of many runs allow one to identify the intervals in which the theoretically true values are most likely located. This procedure is referred as the Maximum Likelihood Method in statistics (Goda, 1981).

In order to see how directional wave simulation results vary with respect to individual methods of analysis a target directional spectrum is utilized here to generate 15 subsurface pressure and velocity records which are then analyzed by the computational system. The resulting mean values and standard deviations of E_{total} , E_p , $\epsilon_{rms,1-D}$, JONSWAP parameters, $f_{1,-1}$, s_c , f_c , B_L , B_R , ϕ_{main} and ϵ_{rms,ϕ_0} are expressed in Table 4.20. The same information for the target directional wave spectrum is also indicated in Table 4.20, providing a constant spreading parameter, $.9s_c$, for values to the left of s_c and a constant direction, 15° , for all central angles.

One may notice that the mean values of E_{total} , E_p , α and s_c obtained from S/D_1 and S/D_2 are considerably larger than the values assigned to the target spectrum. Also the standard deviations are much larger those obtained from GEO. For other parameters expressed in Table 4.20 the related mean values and standard deviations are approximately equal for all methods. Nevertheless, the geometric approach produces less biased means, smaller standard deviations, and smaller errors.

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TABLE 4.20 Maximum likelihood resolution of directional wave simulation

		Sample population: <u>15</u>					Water Depth: <u>63.36</u> (ft)			
Target spectrum	E_{total} (ft^2)	E_p (ft^2s)	f_p (Hz)	α	γ	σ_L	σ_R	$\epsilon_{rms,1-D}$	$f_{1,-1}$ (Hz)	
Target spectrum	5.636	279.9	.0703	.00062	4.08	.081	.095	0.00	.0793	
GEO.	6.325 ± 2.184	307.3 ± 117.1	.0721 $\pm .0033$.00079 $\pm .00031$	4.05 $\pm .68$.088 $\pm .067$.071 $\pm .036$	6.85 ± 2.68	.0798 $\pm .0037$	
S/D ₁	6.733 ± 2.841	360.1 ± 163.0	.0703 $\pm .0036$.00084 $\pm .00036$	3.92 $\pm .65$.069 $\pm .066$.090 $\pm .090$	7.54 ± 2.19	.0785 $\pm .0031$	
S/D ₂	6.707 ± 2.807	338.5 ± 178.5	.0706 $\pm .0038$.00085 $\pm .00037$	3.94 $\pm .80$.074 $\pm .064$.087 $\pm .088$	7.46 ± 2.42	.0785 $\pm .0029$	
Target spectrum	A_L	B_L	s_c	f_c (Hz)	A_R	B_R	ϕ_{main} (o)	ϵ_{rms,ϕ_o} (o)		
Target spectrum	48.7	.0	54.1	.0742	.00115	-4.136	15.0	0.0		
GEO.	10977 ± 20298	.0177 ± 1.851	55.3 ± 17.2	.0752 $\pm .0043$.110 $\pm .417$	-4.859 ± 2.338	15.5 ± 4.1	3.42 ± 1.30		
S/D ₁	3753780 ± 14528176	.0477 ± 1.480	95.3 ± 67.3	.0719 $\pm .0059$.045 $\pm .142$	-4.686 ± 2.128	15.1 ± 4.2	3.53 ± 1.46		
S/D ₂	3753780 ± 14528176	.0480 ± 1.478	89.9 ± 68.3	.0721 $\pm .0064$.033 $\pm .108$	-4.852 ± 2.057	15.1 ± 4.3	4.13 ± 1.37		

The mean values of A_L , A_R differ significantly from the target values in Table 4.20. This is because slight changes in B_L or B_R cause considerable changes in A_L or A_R . It should be noted that resulting mean values of B_R for all three methods do not differ appreciably from B_R of the target spectrum. This suggests that the simulated distribution curves of the spreading parameter to the right of s_c approximately parallel the distribution curves of the target spectrum spreading parameter. Also, small mean values of B_L for all three methods imply that the simulated spreading parameters to the left of s_c can be approximately represented by constant values. However, the simulated distribution curves of spreading parameters obtained from both S/D_1 and S/D_2 are very biased relative to the target spectrum distribution curve. This is indicated by the resulting critical spreading parameters, s_c , which differ from the target s_c by approximately 40%. Also, the standard deviations are about 75% of the means for the S/D_1 and S/D_2 methods. The critical spreading parameter, s_c , from the geometric approach, however, differs from the target s_c by 2% and has a standard deviation of about 30% of the mean s_c .

It is concluded that wave simulation results do not validate any method. However, the geometric method yields the smallest errors for wave simulation tests examined in this study.

5. CONCLUSIONS

5.1 Summary

This study has examined directional wave spectrum analysis based upon a single point measurement system. The input data required for spectral analysis are simultaneous records of wave-induced dynamic pressure and horizontal orbital velocity. The directional spectrum estimate is obtained by expanding the one-dimensional frequency spectrum into a two-dimensional spectrum by means of an angular distribution function. This angular distribution function is usually normalized, single-peaked, and symmetric with respect to a central direction. The angular distribution function utilized in this study is a square-cosine-power function. The power is called the spreading parameter and a main direction associated with the peak at each frequency is called the central angle of propagation. Both the spreading parameter and central angle may vary with frequency. The directional wave spectrum is simply expressed as a product of the one-dimensional frequency spectrum and the normalized angular distribution function. Hence, directional wave spectrum analysis reduces to an evaluation of the one-dimensional frequency spectrum, spreading parameter and central angle of wave propagation.

Two previously developed methods, stochastic and deterministic approaches, have been reviewed and restudied. By expressing an estimation to the one-dimensional frequency spectrum in a more general sense, the two methods are shown to yield identical solutions to the directional wave spectrum. In order to improve directional resolutions obtained from the combined stochastic/deterministic approach, a new method, the geometric approach, has been developed as part of this research effort. The geometric approach matches Fourier transformed wave properties to frequency dependent wavelet pairs in each frequency interval. The amplitude, direction and phase of each wavelet are uniquely specified by equating kinematic and dynamic properties for each frequency component. Wavelets evaluated in each

frequency interval do not have an artificially imposed phase constraint in the geometric approach as they have in the stochastic/deterministic approach, providing a more realistic model to represent the directional properties of ocean random waves.

Inspection of directional properties obtained from real ocean data reveals that numerically more stable results are obtained from the geometric approach than from the stochastic/deterministic approach. Directional behavior based upon an analysis of simulated data also indicate that improved results are obtained from the geometric approach.

5.2 Conclusions

Several conclusions relating to this work are summarized in the following paragraphs.

(1) The principle of the wavelet concept in both the geometric approach and the stochastic/deterministic approach is that the propagating directions and amplitudes can be solved by matching velocities and/or pressures for wavelets in each frequency interval. The wavelet amplitudes are then used to estimate the directional distribution of wave energy density in each frequency interval. As a result, a finite number of wavelets solved in a frequency interval are used to estimate the behavior of a continuous distribution of wavelets in that frequency interval. One would expect that the directional properties obtained from the one angle mode solutions would be more accurate than those obtained from the double angle mode solutions. However, directional properties obtained from both the one angle mode and double angle mode solutions are fairly consistent with one another for either the geometric approach or stochastic/deterministic approach as observed in this research.

(2) Estimating the main propagating direction, $\bar{\phi}$, from velocity

records in the time domain is complicated by not knowing if a specific velocity measurement is associated with a wave trough or crest. However, this same calculation in the frequency domain can utilize pressure measurements to circumvent this difficulty.

(3) The variance of a time series of wave-induced horizontal velocity, $\overline{V_t^2}$, is identical to the sum of all frequency components of the horizontal velocity spectrum, $\overline{V_f^2}$, from a stochastic/deterministic approach, Double Angle Mode solution, as indicated by Parseval's theorem. However, $\overline{V_t^2}$ is not identical to $\overline{V_f^2}$ for both the stochastic/deterministic approach one angle mode solution and the geometric approach. However, the geometric approach does precisely observe the kinematic and dynamic relationships required to obtain the correct velocity and pressure spectra.

(4) A record length of 512 seconds, digitized every second, was found as an optimum size for directional spectrum input data. Results obtained from consecutively recorded samples of 512 seconds in length show a gradual variation in spectral property, indicating a non-stationary process.

(5) An empirical directional spectrum formula has been proposed which utilizes a JONSWAP one-dimensional frequency spectrum, a cosine squared spreading function, a spreading parameter which is inversely proportional to a power of frequency, and a central angle of wave propagation which is represented by a third-order polynomial function of frequency. Parameters evaluated from a least squares best fit procedure provide directional spectrum predictions with root mean square errors less than 2% of the smoothed raw data spectrum.

(6) The mean JONSWAP parameters obtained here, $\gamma=3.9$, $\sigma_L=.048$, $\sigma_R=.06$, from a geometric approach are based on a single peaked spectrum approximation. The standard deviations of these mean JONSWAP parameters are small, suggesting that they should be appropriate for

characterizing spectra at the measurement site located offshore of Coos Bay, Oregon. This spectrum has a sharper peak than that associated with North Sea waves.

5.3 Future Studies

Further studies related to this work are suggested as follows:

(1) Discrepancies between frequency and time domain variances for directional wave properties need to be resolved theoretically and numerically.

(2) Alternative angular distribution functions should be proposed based upon dimensional analysis of real ocean wave data.

(3) More high quality, simultaneous wave measurements are required to check the repeatability of various directional spectrum calculations.

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APPENDICES

Appendix A - Summary of Least Square Analysis

A.1 JONSWAP Spectrum

$$E_J(f_n) = \frac{\alpha g^2}{(2\pi)^4 f_n^5} \gamma^\beta \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] \quad (\text{A.1})$$

where

$$\beta = \exp\left[-\frac{(f_n - f_p)^2}{2\sigma_{LR}^2 f_p^2}\right]$$

$$\sigma_{LR} = \begin{cases} \sigma_L, & \text{for } f_n < f_p \\ \sigma_R, & \text{for } f_n > f_p \end{cases} \quad n = 1, 2, \dots, n_p, \dots, N'$$

n_p = index of frequency at maximum $E(f_n)$

f_p = frequency at maximum $E(f_n)$

The parameters are determined by minimizing the root-mean-square error $\epsilon_{\text{rms},1-D}$, defined in Eq.(3.14), between the actual one-dimensional frequency spectrum $E(f_n)$ and the proposed JONSWAP spectrum $E_J(f_n)$. Taking the derivatives of $\epsilon_{\text{rms},1-D}$ with respect to α , γ , σ_L , σ_R and equating them to zero, four equations can be obtained and expressed as follows:

$$\alpha \sum_{n=1}^{N'} \frac{g^2 \gamma^{2\beta}}{(2\pi)^4 f_n^{10}} \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] = \sum_{n=1}^{N'} E(f_n) \frac{\gamma^\beta}{f_n^5} \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] \quad (\text{A.2})$$

$$\alpha \sum_{n=1}^{N'} \frac{g^2 \beta \gamma^{2\beta-1}}{(2\pi)^4 f_n^{10}} \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] = \sum_{n=1}^{N'} E(f_n) \frac{\beta \gamma^{\beta-1}}{f_n^5} \exp\left[-\frac{5}{4}\left(\frac{f_p}{f_n}\right)^4\right] \quad (\text{A.3})$$

$$\begin{aligned} \alpha \sum_{n=1}^{n_p} \frac{g_{L}^2 \beta_L \gamma_L^{2\beta_L}}{(2\pi)^4 f_n^{10}} (f_n - f_p)^2 \exp\left[-\frac{5}{2} \left(\frac{f_p}{f_n}\right)^4\right] \\ = \sum_{n=1}^{n_p} E(f_n) \frac{\beta_L \gamma_L^{\beta_L}}{f_n^5} (f_n - f_p)^2 \exp\left[-\frac{5}{4} \left(\frac{f_p}{f_n}\right)^4\right] \end{aligned} \quad (\text{A.4})$$

$$\begin{aligned} \alpha \sum_{n=n_p}^{N'} \frac{g_R^2 \beta_R \gamma_R^{2\beta_R}}{(2\pi)^4 f_n^{10}} (f_n - f_p)^2 \exp\left[-\frac{5}{2} \left(\frac{f_p}{f_n}\right)^4\right] \\ = \sum_{n=n_p}^{N'} E(f_n) \frac{\beta_R \gamma_R^{\beta_R}}{f_n^5} (f_n - f_p)^2 \exp\left[-\frac{5}{4} \left(\frac{f_p}{f_n}\right)^4\right] \end{aligned} \quad (\text{A.5})$$

In order to solve these non-linear equations, a numerical iteration procedure is utilized. The spectral peak is previously known and provided by the actual spectrum. Thus

$$\gamma = \frac{(2\pi)^4 f_p^2}{\alpha g^2} \exp\left(\frac{5}{4}\right) E(f_p) \quad (\text{A.6})$$

To start the numerical iteration, initial conditions are assigned, by experience, as

$$\alpha=4, \quad .004 \leq \sigma_L \leq 4, \quad .004 \leq \sigma_R \leq 4 \quad (\text{A.7})$$

The initial value γ is evaluated by Eq.(A.6). Then, σ_L and σ_R are calculated from Eqs.(A.4) and (A.5), respectively, utilizing the Bisection method. The Bisection method is a procedure which is used to approximate a root of the function $F(x)$ in a known interval. Suppose that $F(x)$ has a unique root between x_1 and x_2 , there must exist the relationship $F(x_1)F(x_2) < 0$. Let $x_0 = (x_1 + x_2)/2$; if $F(x_1)F(x_0) < 0$, there must be a root between x_1 and x_0 . Otherwise, if $F(x_1)F(x_0) > 0$, there must be a root between x_2 and x_0 . Thus, one may reiterate the procedure until the resulting root converges in a satisfactorily small interval.

By using σ_L and σ_R solved from the Bisection method, two solutions of α can be obtained from Eqs.(A.2) and (A.3), respectively. Taking the average of the two values of α and replacing this average value into Eq.(A.6), one may evaluate a new γ . Therefore, one may reiterate the entire procedure until an acceptable closure error is obtained.

A.2 Two Parameter Power Function of Spreading Parameter

$$s_e(f_n) = A_{LR} f_n^{B_{LR}} \quad (A.8)$$

where

$$(A_{LR}, B_{LR}) = \begin{cases} (A_L, B_L), & \text{for } f_n < f_c \\ (A_R, B_R), & \text{for } f_n > f_c \end{cases} \quad n = 1, 2, \dots, n_c, \dots, N'$$

n_c = index of frequency at maximum $s(f_n)$

The parameters defined in Eq.(A.8) are determined by minimizing the root-mean-square error between the actual spreading parameter $s(f_n)$ and the proposed spreading parameter function $s_e(f_n)$. This root-mean-square error is defined as

$$\epsilon_{rms,s} = \frac{\sqrt{\sum_{n=n_1}^{n_2} [s_e(f_n) - s(f_n)]^2}}{\sum_{n=n_1}^{n_2} s(f_n)} \quad (A.9)$$

where

$n_1, n_2 = 1, n_c$ to the left of the critical point

$n_1, n_2 = n_c, N'$ to the right of the critical point

Taking the derivatives of $\epsilon_{rms,s}$ with respect to A_{LR} , B_{LR} and equating them to zero, two equations can be obtained and expressed as follows:

$$A_{LR} = \sum_{n=n_1}^{n_2} s(f_n) f_n^{B_{LR}} / \sum_{n=n_1}^{n_2} f_n^{2B_{LR}} \quad (A.10)$$

$$A_{LR} = \sum_{n=n_1}^{n_2} s(f_n) f_n^{B_{LR} \ln(f_n)} / \sum_{n=n_1}^{n_2} f_n^{2B_{LR} \ln(f_n)} \quad (A.11)$$

By equating Eq.(A.10) to Eq.(A.11), the Bisection method can be again employed to solve B_{LR} . Then, A_{LR} can be obtained by replacing the resulting B_{LR} into either Eq.(A.10) or Eq.(A.11). The initial condition for B_{LR} is

$$-40 < \underline{B}_R < -0.1, \quad -40 < \underline{B}_L < 40 \quad (A.12)$$

A.3 Third-order Polynomial Function of Central Angle

$$\phi_{oe}(f_n) = c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3 \quad (A.13)$$

The parameters in Eq.(A.13) can be determined by minimizing the root-mean-square error ϵ_{rms, ϕ_o} , defined in Eq.(3.21), with respect to each of c_0 , c_1 , c_2 and c_3 . That is,

$$\sum_{n=1}^{N'} [c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3] E(f_n) = \sum_{n=1}^{N'} \phi_o(f_n) E(f_n) \quad (A.14)$$

$$\sum_{n=1}^{N'} [c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3] f_n E(f_n) = \sum_{n=1}^{N'} \phi_o(f_n) f_n E(f_n) \quad (A.15)$$

$$\sum_{n=1}^{N'} [c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3] f_n^2 E(f_n) = \sum_{n=1}^{N'} \phi_o(f_n) f_n^2 E(f_n) \quad (A.16)$$

$$\sum_{n=1}^{N'} [c_0 + c_1 f_n + c_2 f_n^2 + c_3 f_n^3] f_n^3 E(f_n) = \sum_{n=1}^{N'} \phi_o(f_n) f_n^3 E(f_n) \quad (A.17)$$

The parameters, c_0 , c_1 , c_2 , and c_3 , can be then solved from these four linear equations.

Appendix B - Statistics of Ocean Waves Evaluated in the Time
and Frequency Domains

B.1 Statistics Evaluated in the Time Domain

TABLE B.1 Summary of statistics evaluated in the time domain

Date: <u>October 23, 1982</u>						Meter No. <u>43</u>					
Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$	Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$
(sec)		(ft/s)	(o)	(ft/s) ²	(o)	(sec)		(ft/s)	(o)	(ft/s) ²	(o)
1024	2:38	.265	-8	.054	92	256	2:38	.283	-9	.040	88
512	2:38	.273	-5	.053	92	256	2:42	.265	-2	.061	95
512*	2:42	.272	-5	.058	94	256*	2:44	.276	-4	.062	97
512	2:46	.256	-10	.058	95	256	2:46	.277	-7	.063	96
512**	2:36	.392	-67	.065	84	256	2:50	.235	-13	.050	80

* central section of 1024 seconds

** data measured from meter 25

TABLE B.1 (continued) Summary of statistics evaluated
in the time domain

Date: <u>October 24, 1982</u>						Meter No. <u>43</u>					
Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$	Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$
(sec)		(ft/s)	(o)	(ft/s) ²	(o)	(sec)		(ft/s)	(o)	(ft/s) ²	(o)
1024	14:47	1.04	-31	.063	79	256	14:47	1.07	-39	.057	80
512	14:47	1.04	-34	.069	78	256	14:51	1.01	-29	.057	79
512*	14:51	1.02	-30	.054	81	256*	14:53	1.00	-29	.056	80
512	14:55	1.04	-29	.055	80	256	14:55	1.03	-30	.056	80
512**	14:45	.736	-56	.070	78	256	14:59	1.06	-30	.049	84

* central section of 1024 seconds

** data measured from meter 25

TABLE B.1 (continued) Summary of statistics evaluated
in the time domain

Date: <u>October 25, 1982</u>						Meter No. <u>43</u>					
Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$	Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$
(sec)		(ft/s)	(o)	(ft/s) ²	(o)	(sec)		(ft/s)	(o)	(ft/s) ²	(o)
1024	6:51	.242	198	.072	89	256	6:51	.202	174	.091	91
512	6:51	.216	187	.067	86	256	6:55	.235	195	.049	88
512*	6:55	.253	202	.069	90	256*	6:57	.261	201	.054	93
512	6:59	.277	208	.069	92	256	6:59	.272	207	.055	93
512**	6:49	.212	250	.080	98	256	7:03	.278	206	.080	90

* central section of 1024 seconds

** data measured from meter 25

TABLE B.1 (continued) Summary of statistics evaluated
in the time domain

Date: <u>October 25, 1982</u>						Meter No. <u>43</u>					
Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$	Length	Init. Time	V_c	ϕ_c	$\overline{V_t^2}$	$\overline{\phi}$
(sec)		(ft/s)	(o)	(ft/s) ²	(o)	(sec)		(ft/s)	(o)	(ft/s) ²	(o)
1024	10:52	.421	-17	.047	97	256	10:52	.428	-17	.043	93
512	10:52	.431	-16	.044	94	256	10:56	.431	-15	.046	92
512*	10:56	.421	-16	.043	93	256*	10:58	.424	-15	.040	96
512	11:00	.414	-18	.047	101	256	11:00	.419	-15	.037	95
512	10:50	.468	193	.043	72	256	11:04	.417	-20	.054	104

* central section of 1024 seconds

** data measured from meter 25

B.2 Statistics Evaluated in the Frequency Domain

TABLE B.2 Summary of statistics evaluated in the frequency domain

Date: <u>October 23, 1982</u>		Meter No. <u>43</u>							
Length	Init. Time	E_{total}	E_p	f_p	$f_{l,-1}$	s_c	f_c	ϕ_{main}	$\overline{V_f^2}$
.(sec)		(ft ²)	(ft ² s)	(Hz)	(Hz)		(Hz)	(°)	(ft/s) ²
<u>STO./DET. APPROACH₁</u>									
1024	2:38	1.00	46	.077	.088	29	.075	92	.061
512	2:38	1.47	46	.088	.101	7	.074	95	.057
512*	2:42	.84	38	.076	.087	12	.076	88	.065
512	2:46	.93	45	.076	.087	11	.074	102	.062
512**	2:36	.91	47	.078	.088	14	.074	73	.060
256*	2:44	3.49	69	.094	.114	8	.078	93	.051
<u>STO./DET. APPROACH₂</u>									
1024	2:38	.63	44	.077	.088	32	.076	99	.054
512	2:38	.32	46	.080	.091	8	.068	111	.053
512*	2:42	.80	38	.078	.091	11	.074	95	.058
512	2:46	.69	42	.076	.086	12	.076	98	.058
512**	2:36	1.02	52	.078	.089	10	.082	72	.064
256*	2:44	1.56	50	.082	.091	10	.078	114	.062
<u>GEOMETRIC APPROACH</u>									
1024	2:38	1.03	48	.077	.089	7.6	.076	90	.075
512	2:38	1.24	49	.080	.093	4.0	.078	85	.074
512*	2:42	1.00	41	.076	.088	5.0	.076	89	.073
512	2:46	1.07	49	.076	.088	5.2	.076	97	.074
512**	2:36	1.01	53	.078	.088	8.0	.076	72	.063
256*	2:44	3.52	112	.094	.114	3.5	.078	95	.055

* central section of 1024 seconds, ** data measured from meter 25

TABLE B.2 (continued) Summary of statistics evaluated
in the frequency domain

Date: <u>October 24, 1982</u>		Meter No. <u>43</u>							
Length	Init. Time	E_{total}	E_p	f_p	$f_{1,-1}$	s_c	f_c	ϕ_{main}	$\overline{V_f^2}$
(sec)		(ft ²)	(ft ² s)	(Hz)	(Hz)		(Hz)	(o)	(ft/s) ²
<u>STO./DET. APPROACH₁</u>									
1024	14:47	1.32	60	.084	.084	12	.083	75	.069
512	14:47	1.19	59	.086	.088	18	.084	73	.071
512*	14:51	1.35	51	.084	.093	14	.084	64	.058
512	14:55	1.15	59	.084	.089	15	.088	85	.056
512**	14:45	1.39	66	.086	.092	7	.084	66	.063
256*	14:53	1.43	53	.082	.092	37	.082	64	.064
<u>STO./DET. APPROACH₂</u>									
1024	14:47	.89	36	.084	.083	16	.083	77	.063
512	14:47	.81	38	.086	.089	11	.084	71	.068
512*	14:51	.83	30	.084	.093	12	.084	66	.054
512	14:55	.83	34	.084	.091	17	.082	86	.054
512**	14:45	1.39	71	.086	.092	9	.086	65	.069
256*	14:53	.98	33	.082	.092	25	.082	64	.056
<u>GEOMETRIC APPROACH</u>									
1024	14:47	1.54	73	.084	.086	3.8	.070	73	.082
512	14:47	1.42	69	.086	.089	3.4	.070	70	.080
512*	14:51	1.46	59	.084	.094	3.5	.072	59	.074
512	14:55	1.42	78	.084	.090	3.0	.070	86	.077
512**	14:45	1.60	78	.084	.088	10.	.070	67	.068
256*	14:53	1.60	65	.082	.092	3.6	.070	65	.067

* central section of 1024 seconds, ** data measured from meter 25

TABLE B.2 (continued) Summary of statistics evaluated
in the frequency domain

Date: <u>October 25, 1982</u>		Meter No. <u>43</u>							
Length	Init. Time	E_{total}	E_p	f_p	$f_{1,-1}$	s_c	f_c	ϕ_{main}	$\overline{V_f^2}$
(sec)		(ft ²)	(ft ² s)	(Hz)	(Hz)		(Hz)	(°)	(ft/s) ²
<u>STO./DET. APPROACH₁</u>									
1024	6:51	1.57	97	.078	.093	20	.078	84	.078
512	6:51	1.46	85	.078	.091	22	.078	87	.070
512*	6:55	1.75	100	.088	.092	12	.080	83	.076
512	6:59	2.06	102	.088	.098	10	.080	85	.075
512**	6:49	1.91	116	.078	.091	5.5	.078	73	.077
256*	6:57	.99	17	.090	.104	41	.059	97	.060
<u>STO./DET. APPROACH₂</u>									
1024	6:51	1.19	80	.078	.092	32	.077	89	.072
512	6:51	1.14	70	.078	.090	22	.078	98	.067
512*	6:55	1.50	75	.088	.097	17	.080	87	.067
512	6:59	1.52	79	.088	.098	21	.080	90	.070
512**	6:49	1.95	117	.078	.091	9	.078	78	.080
256*	6:57	.72	14	.078	.094	42	.059	98	.052
<u>GEOMETRIC APPROACH</u>									
1024	6:51	1.72	108	.078	.092	4.6	.079	87	.090
512	6:51	1.63	96	.078	.091	4.1	.080	90	.082
512*	6:55	1.82	102	.088	.092	5.4	.080	85	.084
512	6:59	1.90	108	.088	.092	4.5	.080	87	.081
512**	6:49	1.97	117	.078	.091	5.2	.080	71	.078
256*	6:57	1.05	14	.066	.081	8.0	.066	95	.067

* central section of 1024 seconds, ** data measured from meter 25

Appendix C - Computer Program Listing

C.1 Pre-calculation: Program PRECAL

```

PROGRAM PRECAL(INPUT,OUTPUT,DATA1,DATA2,DATA3,TAPE4=DATA1,TAPE5=
1 DATA2,TAPE10=DATA3)
C ---THIS PROGRAM IS USED TO CALCULATE FOURIER COEFFICIENTS OF WAVE DATA THROUGH FFT---
C ---NOTICE THAT THE DISTANCE FROM METERS TO WATER SURFACE SHOULD BE LESS THEN 220 FT---
C ---ALWAYS CHECK THE INPUT FORMAT FOR [DATA1] BEFORE DEBUGGING THE PROGRAM---
C ---[DATA1] IS USED TO INPUT ORIGINAL FILTERED TAPE RECORDER DATA---
C ---[DATA2] IS USED TO OUTPUT FREQUENCY DOMAIN DATA FROM FFT CALCULATION---
C ---[DATA3] IS USED TO INPUT OR OUTPUT WAVE INDUCED VELOCITIES AND DYNAMIC PRESSURE---
C ---REMARK [A] IS USED FOR INPUT FILE WITHOUT H1 VALUE(USUALLY 81 DATA)---
C ---REMARK [B] IS USED FOR INPUT FILE WITH H1 VALUE(USUALLY 82,83 DATA)---
C CHARACTER DATE*75
CHARACTER*10 M(4)
DIMENSION RECORD(3300),V(1100),D(1100),P(1100)
DIMENSION PR(512),VB(512),DB(512)
DATA VI,DI,PI,DEGREE/.0,.0,.0,57.29578/
DATA M(1),M(3)/'R', ' 83'/
C ***** [B]
C ---PART I: INPUT INFORMATION FOR RIGHT PROGRAM--- *
C *****
C PRINT 1000
C1000 FORMAT(/"-----CHECK IF THE INPUT FORMAT FOR [DATA1] IS CORRECT,
C 1/"-----INPUT DATE AND TIME INFORMATION (FORMAT IS A75).")
C READ(4,1005) DATE
C1005 FORMAT(A75)
C *****
C ---PART II: READ DATA OF VELOCITY,DIRECTION AND PRESSURE--- *
C *****
C PRINT 1019
C1019 FORMAT(1X/"-----INPUT 0 IF [DATA1] IS READY FOR INPUT."/ "-----OR
C 1 INPUT 1 IF [DATA3] IS READY FOR INPUT.")
C READ*,K
C
C IF(K.EQ.0) THEN
C PRINT 1017
C1017 FORMAT(/"-----INPUT H1(FT): DISTANCE FROM CURRENTMETER TO FLOOR.") [A]
C READ*,H1 [A]
C PRINT 1002
C1002 FORMAT(1X/"-----THE RECORD IS DIGITIZED AT EVERY ONE SECONDD."
C 1/"-----INPUT THE LENGTH OF RECORD IN SECONDD (FORMAT IS I3).")
C READ*,LL
C PRINT 1004,LL
C1004 FORMAT(1X/"-----RECORD LENGTH=",I5,1X,"SECONDD.")
C ---NOTE THAT FOUR CONTINUOUS DATA FORMATED IN ONE LINE IN REFILED MAGNETIC TAPE---
C ---DIRECTION IS IN CLOCKWISE COORDINATE WITH NORTH BEING ZERO---
L1=LL*3
C READ(6,1003) M(1),M(2),M(3),DEPTH,M(4),(RECORD(I),I=1,L1) [A]
C1003 FORMAT(3X,A1,1X,A2,4X,A3/37X,FB.2/18X,A9,2X,3(4F7.2,2X)/(29X,3 [A]
C 1(4F7.2,2X))) [A]
C READ(6,1003) M(2),H1,DEPTH,M(4),(RECORD(I),I=1,L1) [B]
1003 FORMAT(/22X,A2,13X,FB.2,20X,FB.2/4X,A9,2X,2(4F7.2,2X),4FB.3 [B]
1/(15X,2(4F7.2,2X),4FB.3)) [B]
I1=1
I2=I1+3
L2=LL*2-8
DO 1006 J=0,L2,8
DO 1007 I=1,I2
V(I)=RECORD(I+J)
D(I)=RECORD(I+J+4)
C ---V(I): WAVE INDUCED PARTICLE VELOCITIES(CM/S)---
C ---D(I): DIRECTION OF PARTICLE VELOCITIES(DEGREE)---
RADIAN=(90-D(I))*0.017453293
C ---WHERE 0.017453293=3.141592654/180, CHANGING DEGREE TO RADIAN---
D(I)=V(I)*SIN(RADIAN)
V(I)=V(I)*COS(RADIAN)
C ---V(I) BECOMES VELOCITY IN X DIRECTION (+EAST & -WEST)---
C ---D(I) BECOMES VELOCITY IN Y DIRECTION (+NORTH & -SOUTH)---
P(I)=RECORD(I+J+8)
C ---P(I): WAVE INDUCED DYNAMIC PRESSURE(PHI)---
VI=VI+V(I)
DI=DI+D(I)
PI=PI+P(I)
1007 CONTINUE
I1=I
I2=I1+3
1006 CONTINUE

```

```

VI=VI/LL
DI=DI/LL
PI=PI/LL
M2=PI*2.25
H0=H2+3.4167
IF(ABS(H0-H1).GT.5.0) PRINT*, 'CHECK H1'
IF(H0+4.3.GT.DEPTH) DEPTH=H0+4.3
H1=DEPTH-H0
H2=H1+3.4167
C DEPTH=(VI*VI+DI*DI+12.9*PI)*0.174375+H2
C ---ABOVE EQUATION CAN NOT BE USED TO COMPUTE DEPTH SINCE CURRENT OF SURFACE IS UNKNOWN---
C DEPTH=(DEPTH+4.5+PI*2.25+H2)/2.
C ---THE NUMBER 4.5 FT APPEARED ABOVE IS THE SENSOR LOCATED ON THE BOTTON OF BOAT---
C ---WHERE 2.25 IS CONTANT TO CONVERT PRESSURE(PST) TO DEPTH(FT)---
VI=VI*.3937
DI=DI*.3937
SUM=.0
C=.0
CC=.0
WRITE(+,1013)
1013 FORMAT(1X/'=====GUESS & INPUT A MAIN DIRECTION (DEGREE, 0=NORTH)*
1/' OF WAVE PROPAGATION.}')
READ=,ANGLE
ANGLE=90.-ANGLE
DD 1008 I=1,LL
V(I)=V(I)*.3937-VI
D(I)=D(I)*.3937-DI
C ---SUBTRACT CURRENT FROM VELOCITY DATA, V(I) & D(I) BECOME WAVE INDUCED VELOCITIES---
C ---CHANGING UNIT OF VELOCITY FROM (CM/S) TO (IN/S)---
ALL=V(I)*V(I)+D(I)*D(I)
SUM=SUM+ALL
R=SQR(ALL)
TEMP=ATAN2(D(I),V(I))*DEGREE
H0=ABS(TEMP-ANGLE)
IF(H0.GT.90..AND.H0.LT.270.) THEN
IF(ABS(TEMP+180.-ANGLE).LT.90.) THEN
TEMP=TEMP+180.
ELSE
TEMP=TEMP-180.
END IF
ELSE IF(H0.GE.270.) THEN
IF(ANGLE.GT.90.) TEMP=TEMP+360.
IF(ANGLE.LE.-90.) TEMP=TEMP-360.
END IF
C=C+B*TEMP
CC=CC+B
P(I)=P(I)-PI
C ---P(I) BECOMES WAVE INDUCED DYNAMIC PRESSURE (PSI)---
1008 CONTINUE
SUM=SUM/LL/144.
CC=90.-C/CC
VI=VI/12.
DI=DI/12.
C=SQR(VI*VI+DI*DI)/12.
DI=90.-ATAN2(DI,VI)*DEGREE
PRINT 1014, M(1),M(2),M(3),M(4),H1,H2,DEPTH,C,DI,PI,CC,SUM
1014 FORMAT(1X/'-----BURST METER NUMBER AND RECORD DATE FOR FILE DATA="
1,A1,A2,A3,A9," /"-----CURRENTMETER IS",F6.1," (FT) ABOVE SEA FLOO
1R." /"-----PRESSURE GAGE IS",F6.1," (FT) ABOVE SEA FLOOR." /
1 "-----WATER DEPTH FROM SEA BOTTON TO SVL IS",F7.2,"(FT)."/
1 "*****MAGNITUDE OF MEAN CURRENT=",F9.4," (FT/S)."/
1 "*****DIRECTION OF MEAN CURRENT=",F9.4," (DEGREE, 0=NRTH)."/
1 "*****AVERAGE PRESSURE IN THE RECORDS=",F9.4," (PSI)."/
1 "*****WEIGHTED MEAN DIRECTION=",F9.4," (DEGREE, 0=NORTH)."/
1 "VARIANCE OF HORI. VELOCITY(U/O CURRENT)=",F9.4," (FT/S)**2")
VI=C
C END IF
C
C *****
C ---PART III: RUNNING FFT TECHNIQUE AMONG DIFFERENT WAVE PROPERTIES---
C *****
C PRINT 1018
C1018 FORMAT(1X/'-----THE FFT APPLIED LATER WILL BE BASED ON 2 ALGORITHM
C 1./"-----INPUT N PREPARED FOR APPLING FFT LATER (FORMAT IS FREE*).
C 1/"-----REQUIRE THAT N=2**IP IS THE LEAST VALUE THAT IS GE. TO THE
C 1 DATA PERIOD." / "-----FOR EXAMPLE: DATA PERIOD=250 POINTS, N=2**8
C 1=256 POINTS (MAX. N=2**9=512 POINTS).")
C READ=,N
C N=LL
C N=256
C IF(ABS(S12-LL).LT.50) N=512
C IF(ABS(1024-LL).LT.50) N=1024
C ---THE CHARACTERS "IP" INDICATES "POWER" OF BASE 2---
C
C IF(K.EQ.0) THEN

```

```

      IF(N.LE.LL) GO TO 1023
      L1=LL+1
      DO 1024 I=L1,N
      V(I)=0.0
      D(I)=0.0
1024 P(I)=0.0
1023 CONTINUE
C   WRITE(10,1015) M(1),M(2),M(3),M(4),DEPTH,VI,DI,PI,(V(I),D(I),P(I)
C   1,I=1,N)
C1015 FORMAT(1X/A1,A2,A3,A9,4F8.3/(9(F11.7,2X)))
C
C   ELSE
C   READ(10,1021)M(1),M(2),M1,DEPTH,VI,DI,PI,CC,SUM,(V(I),D(I),P(I)
C   1,I=1,N)
C1021 FORMAT(1X/A10,A5,7F9.4/(9(F11.7,2X)))
C   END IF
C
      CALL ORBIT(P,PB,N)
      CALL ORBIT(V,VB,N)
      CALL ORBIT(D,DB,N)
      NH=N/2
      K=0
      NHO=NH/1.2
      FREQ2=SQRT(2.5/(DEPTH-H1))
C --- IN A DISTANCE 'DEPTH-H1' BELOW WATER SURFACE, ONE MAY SENSE 4.32
C OF WAVE MOTION AT SURFACE IN ACCORDANCE WITH LINEAR WAVE THEORY---
      IF(FREQ2.GT..5) PRINT*, 'CHECK DEEP'
      L3=FREQ2*FLOAT(N)
      IF(NHO.LT.L3) NHO=L3
      IF(NHO.GT.NH) NHO=NH
      IF(K.EQ.0) WRITE(8,1020)N,NHO,M(1),M(2),M(3),M(4),H1,DEPTH,VI,DI,
      IP1,CC,SUM,(P(I),PB(I),V(I),VB(I),D(I),DB(I),I=1,NHO)
C   IF(K.EQ.1) WRITE(8,1022)N,NHO,M(1),M(2),M1,DEPTH,VI,DI,PI,CC,SUM
C   1,(P(I),PB(I),V(I),VB(I),D(I),DB(I),I=1,NHO)
1020 FORMAT(1X/2I5/A1,A2,A3,A9,7F9.4/(10E12.6))
C1022 FORMAT(1X/2I5/A10,A5,7F9.4/(10E12.6))
C   PRINT 1001,DATE
C1001 FORMAT(1X/'*****DATE AND TIME= ',A/)
      STOP
      END
C
C *****
C ---PART X: COLLECTION OF SUBROUTINES AND BLOCK DATA--- *
C *****
      SUBROUTINE ORBIT(T1,T2,N)
      DIMENSION T1(N),T2(N)
      COMPLEX X(2048)
      DO 10 I=1,N
10 X(I)=CMPLX(T1(I),.0)
      CALL COOLEY(X,N,1,1)
      NH=N/2
      DO 20 I=1,NH
      NN=N-I+1
      T1(I)=2.*REAL(X(NN))
20 T2(I)=2.*AINAG(X(NN))
      RETURN
      END
C
      SUBROUTINE COOLEY(X,N,INV,KIND)
C ---COOLEY-TUKEY METHOD BASE 2 FFT ALGORITHM; FROM R.K.BTNE & L.ENOCHSON---
C ---"APPLIED TIME SERIES ANALYSIS: BASIC TECHNIQUES"(1978) V.1 PP.246-254---
C ---N: N=2**IF, NUMBER OF COMPLEX VALUES FOR RUNNING FFT BASED ON 2 ALGORITHM---
C ---INV: EQUALED 1 FOR FORWARD FFT, EQUALED -1 FOR INVERSE FFT---
C ---KIND: EQUALED 1 FOR FIRST KIND TYPE, EQUALED 3 FOR THIRD KIND TYPE---
C ---X(I) IS A COMPLEX VARIABLE ARRAY USED TO INPUT & OUTPUT FFT INFORMATION---
      DIMENSION X(N),CS(2),MSK(13)
      COMPLEX X,CXCS,HOLD,XA
      EQUIVALENCE (CXCS,CS)
      IF(KIND.EQ.3) KIND=-1
      IN=N
      DO 5 I=2,15
      IN=IN/2
      IF(IN.LE.2) GO TO 10
5 CONTINUE
10 IP=1
      ZZ=-6.283185306*INV/FLOAT(N)
      HSK(1)=N/2
      DO 15 I=2,IP
15 HSK(I)=HSK(I-1)/2
      NN=N
      MM=2
      DO 45 LAYER=1,IP
      NN=NN/2
      II=NN
      ---INITIAL NU=0 HERE---

```

```

DO 20 J=1,NN
II=II+1
IJ=II-NN
XA=X(II)
X(II)=X(IJ)-XA
20 X(IJ)=X(IJ)+XA
DO 25 LOC=2,IP
LL=-MSK(LOC)
IF(LL) 30,35,25
25 NU=LL
30 NU=MSK(LOC)
GO TO 40
35 NU=MSK(LOC+1)
40 DO 400 I=3,MM,2
II=NN+I
U=FLOAT(NU)*ZZ
CS(1)=COS(U)
CS(2)=SIN(U)
DO 200 J=1,NN
II=II+1
IJ=II-NN
XA=CXCS*X(II)
X(II)=X(IJ)-XA
200 X(IJ)=X(IJ)+XA
DO 250 LOC=2,IP
LL=NU-MSK(LOC)
IF(LL) 300,350,250
250 NU=LL
300 NU=MSK(LOC)+NU
GO TO 400
350 NU=MSK(LOC+1)
400 CONTINUE
45 MM=MM+2
NU=0
DO 80 I=1,N
NU1=NU+1
HOLD=X(NU1)
IF(NU1-I) 60,53,50
50 X(NU1)=X(I)
IF(INV.EQ.KIND) X(NU1)=X(I)/FLOAT(N)
55 X(I)=HOLD
IF(INV.EQ.KIND) X(I)=HOLD/FLOAT(N)
60 DO 65 LOC=1,IP
LL=NU-MSK(LOC)
IF(LL) 70,75,65
65 NU=LL
70 NU=MSK(LOC)+NU
GO TO 80
75 NU=MSK(LOC+1)
80 CONTINUE
RETURN
END
EOI ENCOUNTERED.

```

C.2 Directional Spectrum Estimation:

the stochastic/deterministic approach, Program STOCH

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PROGRAM STOCH(INPUT,OUTPUT,DATA2,DATA4,TAPE4=DATA2,TAPE5=DATA4)
C ---CAUTION: BEFORE RUNNING THIS PROGRAM, 'LIBRARY(COHPLOT)' & 'SETTL(100)' MUST BE CALLED---
C ---CAUTION: FFT POINTS M.LE.1024, CHANGE DIR. IF ONE INCREASES N---
C ---CAUTION: 0 DIRECTS TOWARD TO EAST FOR HATH, BUT TO NORTH FOR OUTPUT---
C ---[DATA2] IS USED TO INPUT FORWARD FFT DATA, COMPUTED FROM <FUNDA>---
C ---[DATA4] ARE USED TO COLLECT DESIRED OUTPUT FROM FORMATED <TAPE5>---
CHARACTER*10 LX(2),LY(2),LX1(2),LY1(2),LX2(2),LY2(2),ST(2),LX21
CHARACTER*3 LX3,LY3,LX4,LY4,LX10,LY10,LX18,LZ,LZ1,LZ2,LZ4,LZ5
CHARACTER*10 LX5(2),LY5(2),LX6,LX6(2),LX7,LX7(2),LX11(2),LY14(3)
CHARACTER*10 LX8,LY8(3),LX9,LY9,H(2),LX15,LY15,LX16,LY16,LY21(2)
CHARACTER*10 LX14,LY11(2),LX12(3),LY12(3),LX13(2),LY13(3),LX25(3)
CHARACTER*10 LX17,LY17(7),LY18(2),LX19(2),LY19,LX20(3),LY20(3)
CHARACTER*10 LZ3(2),LX22,LY22(2),LX23,LY23(2),LX24,LY24(3),LY25(2)
CHARACTER*10 LX26,LZ6,LZ7,LZ8,LZ9,LZ10,LX30,ST2(2)
DIMENSION P(720),PB(720),V(720),VB(720),D(720),DB(720)
DIMENSION T33(720),T12(720),RECORD(720),B1(720),D2(720),FS(100)
DIMENSION S1(720),S2(720),VIA(720),VIB(720),V2A(720),V2B(720)
DIMENSION XX(7,14,2),YY(7,14,2),IX(7),XL(10),YL(10),IK3(4),A(4,5)
COMMON /DATA10/ FREQ(720),T13(720),T23(720),UP(720),UK(720),FREQ1
1,FREQ2,ALFA,GA,PEAK,LL,IPEAK,IPPEAK,IPEAK,K,A1,ICPEAK,L1
DATA LX,LY,LX18//FREQUENCY', '(HZ)', 'E'>MTH <(F', 'T'2S)', 'C2'//
DATA LX1,LY1//E1>MTH I<', '(FT'2/S)', 'SPREADING', 'PARAMETER'//
DATA LX2,LY2//RECORD LAB', 'EL >.<', 'E1>P79 I<', '(FT'2S)'//
DATA LX3,LX4,LY3,LY4,LX14,LZ//E', 'U', 'M', 'S', 'FROM', '100'//
DATA LX5,LX6,LX7//DIRECTIONA', 'L', 'SPECTRUM', 'UNMODIFIED'//
DATA LY5,LX13//WAVE ENERB', 'T SPECTRUM', 'AT SEA SU', 'RFACE, DEP',
1 'TH OF SEA', ' FT', 'FT'>S<', ' ' '0'//
DATA LY6,LX12//HORIZONTAL', ' AMPLITUDE', ' SPECTRUM', 'AT 4.3 FT',
1 ' ABOVE SEA', 'FLOOR', '--->+< H', 'EAN CURREN', 'T >.<'//
DATA LY7,LY12//HORIZONTAL', ' VELOCITY', 'SPECTRUM A', 'T 4.3 FT A',
1 ' BOVE SEA F', 'LOOR', ' >+< A', 'BOVE SEA F', 'LOOR'//
DATA LX8,LY8,LY22,LY25//SHOOTED', 'ONE DIMENS', 'IONAL SPEC', 'TRUM'
1, 'SPCTR?I?T(' ' )', 'S'DTE?E?P(' ' )'//
DATA LZ5,LX9,LY9,LY19//>Z', 'RAW DATA', 'JONSWAP', 'A PROPOSED'//
DATA LX10,LY10,LY13//---', 'XXX', ' ' '-----', '>+<'//
DATA LX11,LY11//PEAK FREQ', 'ENCY >.<', 'PEAK ENERB', 'Y >.<'//
DATA LX15,LX16,LY18//>A', '<.', '>R!<TL>', 'S(F)*A*F*-', 'B'//
DATA LY15,LY16,LX19//>C', '<.', '>R!<YR>', 'A', ' ' 'B'//
DATA LY14,LX17//MAIN DIREC', 'TION >.<', ' ' '0', 'C1 AND C2'//
DATA LY17//NOTATION >.', '< ( ' ) F', 'ROM ONE AN', 'GLE MODE, '
1 '( ' ) FROM B', 'OUBLE ANGL', 'E MODE'//
DATA LX20,LY20,ST//TOTAL ENER', 'GY >.<', ' FT'2', 'F?IT, 7-71'
1, '>.<', ' HZ', 'STO./DET.', 'APPROACH?1'//
DATA LZ3,LZ4,LX23,LX24,LZ2//HZ, ' ' '0', '0', '(RADIAN)'
1, '=
B(','OF'//
DATA LY23,LY24//EVALUATED', 'AT', 'DOMINANT F', 'REQUENCY >', '<'//
DATA LZ1,LX25,LZ7//500', 'REF. DIREC', 'TION >', '<' '0', 'L'>.<'//
DATA LX21,LX22,LY21//>M'2', '>RMS<', '= (' ' FT'>S<'2'//
DATA LX26,LZ6,ST2//, 'B(','R>.<', 'STO./DET.', 'APPROACH?2'//
DATA A,LZ8,LZ9,LZ10,LX30/20*.0, '3', '2', '4', '1Y!<'//
DATA CPI,DEGREE,RN,DNEAN,ESDA/3.14159265,57.29578,.0174532,.0,.0/
DATA FS/ 1.00000,1.33333,1.60000,1.82857,2.03175,2.21645,2.38695,
1 2.54608,2.69585,2.83773,2.97286,3.10212,3.22620,3.34569,3.46106,
1 3.57271,3.68097,3.78614,3.88847,3.98817,4.08545,4.18046,4.27335,
1 4.36428,4.45334,4.54066,4.62634,4.71045,4.79309,4.87433,4.95424,
1 5.03288,5.11031,5.18658,5.26175,5.33586,5.40895,5.48107,5.55225,
1 5.62253,5.69195,5.76053,5.82830,5.89529,5.96153,6.02704,6.09185,
1 6.15597,6.21943,6.28226,6.34446,6.40605,6.46706,6.52750,6.58739,
1 6.64673,6.70556,6.76386,6.82148,6.87900,6.93585,6.99224,7.04818,
1 7.10368,7.15874,7.21339,7.26763,7.32146,7.37490,7.42796,7.48064,
1 7.53295,7.58490,7.63650,7.68775,7.73866,7.78924,7.83950,7.88943,
1 7.93905,7.98836,8.03737,8.08608,8.13450,8.18263,8.23048,8.27804,
1 8.32536,8.37240,8.41917,8.46569,8.51195,8.55796,8.60372,8.64924,
1 8.69453,8.73958,8.78440,8.82899,8.87335/
DATA XL,YL/.0,.333,.5,.667,.8,.857,.889,.909,.952,.98,10*1./
DATA CPI2,VLARGE,ESDB,GA,XX/6.2831853,.0,.0,4.,196*1./
DATA IPNOV,EDEP,ADEP/0.,0.,0001/
PRINT 5040
5040 FORMAT(IX/'-----THE PROGRAM WILL FIRST COMPUTE THE INFORMATION FOR
1 SPREADING USE,/'-----THEN, IT WILL COMPUTE ONE DIMENSION CASE,/'
1'-----FINALLY IT WILL DRAW THE DIRECTIONAL SPECTRUM.')
READ(6,5068) N
5068 FORMAT(IX/IS)
NH=N/2
NH1=NH/1.45

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      READ(6,5050)M(1),M(2),H1,DEPTH,VI,DI,PI,S,SV,(P(I),PB(I),V(I),
      1 UB(I),D(I),DB(I),I=1,NH1)
5050 FORMAT(A10,A5,7F9.4/(10E12.6))
      IF(DEPTH.LT.140.) EDEP=2.
      IF(EDEP.GT.1.) ADEP=.01
      PRINT 5028
5028 FORMAT(/"====INPUT 1 WILL BE BASED ON U,V,P DATA,"
1/"====OR INPUT 2 WILL BE BASED ON U,V DATA.")
      READ=,NOTE
      NH2=NH/3.5
      NH3=NH2-3
      NH4=NH/2.5
      NMS=NH4+1
      FREQ1=1./FLOAT(N)
      PII=SQRT(VI*VI+DI*DI)
      DII=90.-ATAN2(DI,VI)*DEGREE
      IF(DII.LT..0) DII=DII+360.
C ---PII & DII ARE THE MAGNITUDE AND DIRECTION OF CURRENT AT H1(FT) ABOVE SEA FLOOR---
C .....
C ---PART IV: CALCULATE ONE DIMENSIONAL SPECTRUM---
C .....
      L1=N/32
      IF(L1.LT.4) L1=4
      FREQ2=SQRT(2.56/DEPTH)
C ---FREQUENCY FREQ2(HZ) CIRCUMSCRIBES DEEP WATER WAVES, WAVE LENGTH<2*DEPTH---
      L3=FREQ2/FREQ1
      IDEEP=L3
      ENH=FLOAT(N)/288.
C ---ENH=FLOAT(N)/144./2. COEF. USED TO COMPUTE ENERGY IN POSITIVE FREQUENCY---
C ---ALSO UNIT CHANGES FROM IN=IN TO FT=FT---
      CALL TRANS(DEPTH,H1,NH1)
C
      DO 5001 I=1,NH1
      B=SQRT(V(I)*V(I)+D(I)*D(I))
      C=SQRT(PB(I)*PB(I)+DB(I)*DB(I))
      IF(NOTE.EQ.1) THEN
      RECORD(I)=(ABS(P(I))*B+ABS(PB(I))*C)/UP(I)*ENH
C ---RECORD(I) IS EXPRESSED IN A BEST ESTIMATE IN ABOVE FORM---
C ---RECORD(I) IS RAW DATA OF I-D HORI. VELOCITY SPECTRUM @ H1(FT) ABOVE SEA FLOOR---
      V2A(I)=(B*B+C*C)*ENH
      ELSE
      RECORD(I)=(B*B+C*C)*ENH
      V2A(I)=(ABS(P(I))*B+ABS(PB(I))*C)/UP(I)*ENH
      END IF
5001 CONTINUE
      IF(NOTE.EQ.1) THEN
      CALL SMOOTH(N,T12,RECORD,NMS,0,1)
      CALL SMOOTH(N,T33,V2A,NMS,0,1)
      ELSE
      CALL SMOOTH(N,T33,RECORD,NMS,0,1)
      CALL SMOOTH(N,T12,V2A,NMS,0,1)
      END IF
      DO 5047 I=1,NMS
      IF(1.LE.L1.OR.1.GE.L3) GO TO 5027
      IF(RECORD(I).LE.VLARGE) GO TO 5027
      VLARGE=RECORD(I)
      IPEAK=I
5027 CONTINUE
      IF(NOTE.EQ.1) THEN
      B=ENH*T12(I)/RECORD(I)/UP(I)
      C=ENH*T33(I)/V2A(I)
      ELSE
      B=ENH*T12(I)/V2A(I)/UP(I)
      C=ENH*T33(I)/RECORD(I)
      END IF
      T13(I)=(V(I)*P(I)+VB(I)*PB(I))*B
      T23(I)=(D(I)*P(I)+DB(I)*PB(I))*B
      V1A(I)=(V(I)*D(I)+VB(I)*DB(I))*C
5047 V1B(I)=(V(I)*V(I)+VB(I)*VB(I)-D(I)*D(I)-DB(I)*DB(I))*C
      IF(L3.LT.NH2) L3=NH2
      IF(L3-IPEAK.GT.20) L3=IPEAK+20
C
      WRITE(*,7) H1,(RECORD(I),I=1,30)
C 7 FORMAT(1X/"-----OUTPUT VELOCITY SPECTRUM AT ",F6.1,"" ABOVE SEA FLO
C 10R,"/(9F8.3))
C .....
C ---PART V: CALCULATE SPREADING PARAMETER AND DIRECTIONAL SPREADING---
C .....
      PRINT 5014
5014 FORMAT(1X/"====INPUT 3 WILL AVERAGE THREE FREQUENCY DATA,"/
1/"====OR INPUT 4 WILL AVERAGE FOUR FREQUENCY DATA,"/
1/"====OR INPUT 5 WILL AVERAGE FIVE FREQUENCY DATA,"/
1"-----DOUBLE THE VALUE OF INPUT WILL CALCULATE BEST-FIT CURVE"/
1" OF SPREADING PARAMETER IN EITHER SIDE OF PEAK POINT.")
      READ=,INTO

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IF(INTD.GE.6) IPNOV=1
IF(INTD.GE.4) INTO=INTD/2
DO 5054 I=2,NH6
  B=T23(I)+T23(I-1)+T23(I+1)
  C=T13(I)+T13(I-1)+T13(I+1)
  TEMP=T12(I)+T12(I-1)+T12(I+1)
  BB=2.*(V1A(I)+V1A(I+1)+V1A(I-1))
  CC=V1B(I)+V1B(I+1)+V1B(I-1)
  VARY=T33(I)+T33(I-1)+T33(I+1)
  IF(INTD.EQ.4.AND.I.LT.NH6) THEN
    B=B+T23(I+2)
    C=C+T13(I+2)
    TEMP=TEMP+T12(I+2)
    BB=BB+2.*V1A(I+2)
    CC=CC+V1B(I+2)
    VARY=VARY+T33(I+2)
  ELSE IF(INTD.EQ.5.AND.I.LT.NH6.AND.I.GT.2) THEN
    B=B+T23(I+2)+T23(I-2)
    C=C+T13(I+2)+T13(I-2)
    TEMP=TEMP+T12(I+2)+T12(I-2)
    BB=BB+2.*(V1A(I+2)+V1A(I-2))
    CC=CC+V1B(I+2)+V1B(I-2)
    VARY=VARY+T33(I+2)+T33(I-2)
  END IF
  S1(I)=SQRT(B*B+C*C)/TEMP
  D1(I)=ATAN2(B,C)
  S2(I)=SQRT(BB*BB+CC*CC)/VARY
  D2(I)=ATAN2(BB,CC)/2.
  IF(ABS(D2(I)-D1(I)).LT.1.75) GO TO 5054
  IF(D2(I).LT.D1(I)) D2(I)=D2(I)+CPI
  IF(ABS(D2(I)-D1(I)).GT.1.75) D2(I)=D2(I)-CPI
5054 CONTINUE
  L2=IPEAK-L1/2
  S1(1)=S1(2)
  S2(1)=S2(2)
  D1(1)=D1(2)
  D2(1)=D2(2)
  DO 5016 J=1,NH6
    IF(S1(I).GT..999) S1(I)=.999
5016 IF(S2(I).GT..999) S2(I)=.999
  CALL PLOTYP(1)
  CALL BAUD(1200)
  CALL SIZE(7.5,5.625)
C ---THE FOLLOWING 80 LINES CAN BE DELETED IF NOT NEEDED---
C
  PRINT 5060
5060 FORMAT(/"=====INPUT THE NUMBER TO OUTPUT CORRESPONDING FIGURES,"/
  1"-----SPREADING PARAMETER 1 PROPAGATION DIRECTION - FREQUENCY,"/
  1"-----CODE=1 GIVES THE COMPARISON FROM ONE 1 DOUBLE ANGLE RESULTS,
  1"/"-----CODE=2 WILL SHOW THE FINAL SOLUTION ONLY.")
  READ*,JMODE
  IF(JMODE.EQ.2) GO TO 5061
  CALL ERASE
  CALL SCALE(25.,4.,1.1,1.,0.,-1)
  CALL AXISL(0.,-2.,0.,0.1,.05,.1,4,0,1,2,1.,1.,-1,0)
  CALL VECTORS
  CALL PLOT(.0,1.,0,0)
  CALL PLOT(.2,1.,1,0)
  CALL PLOT(.2,0.,1,0)
  CALL SYMBOL(.06,-.14,-.0,-15,15,LX)
  CALL SYMBOL(-.025,-.33,90.,-16,9,LX17)
  CALL SYMBOL(-.03,-.24,-.0,-1,68,LY17)
  CALL POINTS
  CALL PLOT(.0185,-.23,1,17)
  CALL PLOT(.107,-.23,1,3)
C ---DRAW S1 AND S2 VERSE FREQUENCY FIGURES---
  CALL LINE(FREQ,S1,17,NH6)
  CALL LINE(FREQ,S2,3,NH6)
  CALL TEXPAUS
  CALL ERASE
  CALL SCALE(4.4,4.,1.8,-9,0.,-1)
  CALL AXISL(.0,1.,.0,-.0,1.,.0,-.1,1,0,0,2,2,1.,1.,-1,0)
C ---DRAW S1-S2 PICTURE AS C1-C2 RELATION---
  DO 5044 I=L2,L3
    J=I-L2+1
    T12(J)=S1(I)
5044 T33(J)=S2(I)
  CALL POINTS
  CALL LINE(T12,T33,1,J)
  CALL LINE(XL,YL,6,10)
  CALL NUMBER(.0,1.02,-.0,.085,3,.0)
  CALL NUMBER(.333,1.02,-.0,.085,3,.5)
  CALL NUMBER(.5,1.02,-.0,.085,3,1.)
  CALL NUMBER(.667,1.02,-.0,.085,3,2.)

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CALL NUMBER(.78,1.02,.0,-.085,3,4.)
CALL SYMBOL(.909,1.02,.0,-.085,2,LZ)
CALL SYMBOL(.98,1.02,.0,-.085,2,LZ1)
CALL SYMBOL(.2,1.04,.0,-.12,1,LX6)
DO 5045 I=1,51
T12(I)=.02*FLOAT(I-1)
5045 T33(I)=6./(2.-T12(I))-3.-2.*T12(I)
CALL VECTORS
CALL LINE(T12,T33,0,51)
CALL PLOT(1.,.0,1,0)
CALL PLOT(1.,1.,0,0)
CALL PLOT(0.,1.,1,0)
CALL SYMBOL(.7,-.12,.0,-.12,2,LX17)
CALL SYMBOL(-.22,.71,.0,-.12,2,LX18)
CALL TEKPAUS
CALL ERASE
CALL SCALE(25.,.63662,1.1,1.5,0.,-CPI)
CALL AXISL(.0,-2,0.,-CPI,CPI,-CPI,.05,CPI,4,3,1,0,1.,1.,.1,0)
CALL PLOT(.0,CPI,0,0)
CALL PLOT(.2,CPI,1,0)
CALL PLOT(.2,-CPI,1,0)
CALL SYMBOL(.05,-4.1,.0,-.15,15,LX)
CALL SYMBOL(-.033,-2.4,90.,.15,11,LXS)
CALL SYMBOL(-.026,-.65,90.,.15,9,LT1)
CALL NUMBER(-.028,-3.1,.0,-.1,6,-180.0)
CALL NUMBER(-.025,-1.57,.0,-.1,5,-90.0)
CALL NUMBER(-.019,.0,.0,-.11,3,.0)
CALL NUMBER(-.025,1.55,.0,-.1,5,90.0)
CALL NUMBER(-.029,3.10,.0,-.1,6,180.0)
CALL SYMBOL(-.03,-4.8,.0,-.1,68,LY17)
CALL POINTS
CALL PLOT(.018,-4.71,1,28)
CALL PLOT(.106,-4.71,1,20)
C ---DRAW D1 AND D2 DATA SHOWING WAVE PROPAGATION DIRECTION---
CALL LINE(FREQ,D1,28,NH6)
CALL LINE(FREQ,D2,20,NH6)
CALL TEKPAUS
5061 CONTINUE
C
C
DO 5033 I=1,NH2
IF (NOTE.EQ.2) D1(I)=D2(I)
C=1.-S1(I)
UP(I)=S1(I)/C
C=1.-S2(I)
B=(1.5*S2(I)+.3)/C
5033 T13(I)=B+SQRT(B*B+2.*S2(I)/C)
C ---UP(I) AND T13(I) ARE SPREADING PARAMETERS FROM ONE AND DOUBLE ANGLE MODE---
C
IF(L3-IPEAK.LT.L1) L3=IPEAK+L1+L1/2
IF(L3.GT.NH2) L3=NH2
IDPEAK=L3-L1/2
IF(NOTE.EQ.1) VARY=UP(IDPEAK)
IF(NOTE.EQ.2) VARY=T13(IDPEAK)
DO 5049 I=IDPEAK,L3
IF(NOTE.EQ.1.AND.UP(I).GE.VARY) GO TO 5049
IF(NOTE.EQ.2.AND.T13(I).GE.VARY) GO TO 5049
IDPEAK=I
IF(NOTE.EQ.1) VARY=UP(I)
IF(NOTE.EQ.2) VARY=T13(I)
5049 CONTINUE
C
TEMP=FREQ(IDPEAK)
LL=IPEAK+L1/3
ICPEAK=L2
C ---CRITICAL FREQUENCY INDEX INDICATES HIGHEST SPREADING PARAMETER---
IF(NOTE.EQ.1) VLARGE=UP(ICPEAK)
IF(NOTE.EQ.2) VLARGE=T13(ICPEAK)
DO 5006 I=ICPEAK,LL
IF(NOTE.EQ.1.AND.UP(I).LE.VLARGE) GO TO 5006
IF(NOTE.EQ.2.AND.T13(I).LE.VLARGE) GO TO 5006
ICPEAK=I
IF(NOTE.EQ.1) VLARGE=UP(I)
IF(NOTE.EQ.2) VLARGE=T13(I)
5006 CONTINUE
PEAKF=FREQ(ICPEAK)
C
MOD=1
C
5020 X1=-5.
X2=-.1
IF(MOD.EQ.2.AND.IPNOW.EQ.1) X1=.1
IF(MOD.EQ.2.AND.IPNOW.EQ.1) X2=20.
CALL LST(FF2,X2,MOD)
5043 CALL LST(FF1,X1,MOD)

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XN=100000.*FF1*FF2
IF(XN.GT..0) THEN
X1=X1-3.
IF(MOD.EQ.2.AND.IPNOW.EQ.1.AND.X1.GT.-7.) GO TO 5063
IF(MOD.EQ.2.AND.IPNOW.EQ.1) GO TO 5080
IF(X1.GT.-40.) GO TO 5063
5080 X=.0
A1=.0
GO TO 5056
END IF
DO 5057 I=1,22
X=(X1+X2)/2.
CALL LST(FF,X,MOD)
XN=100000.*FF*FF1
IF(XN.LE..0) THEN
X2=X
FF2=FF
ELSE
X1=X
FF1=FF
END IF
IF(ABS(FF)-1.E-10) 5056,5056,5057
5057 CONTINUE
5056 IF(MOD.EQ.2) GO TO 5018
MOD=2
CALL ERASE
C *****
C ----PART VI: DRAWING APPLIED SPREADING PARAMETER IN LOG. SCALE---
C *****
IF(NOTE.EQ.1) CALL SMOOTH(N,S1,UP,NH2,ICPEAK,3)
IF(NOTE.EQ.2) CALL SMOOTH(N,S1,T13,NH2,ICPEAK,3)
CALL SCALE(25.,1.3,1.1,1.06,.0,-1.)
CALL AXISL(.0,-2,.0,-1.,2,-1.,.05,1.,4,0,1,0,1.,1.,.1,0)
DO 6069 I=1,NH2
IF(S1(I).LT..1) VB(I)=-1.
IF(WP(I).LT..1) T12(I)=-1.
IF(T13(I).LT..1) D(I)=-1.
IF(S1(I).GE..1) VB(I)=ALOG10(S1(I))
IF(T13(I).GE..1) D(I)=ALOG10(T13(I))
6069 IF(WP(I).GE..1) T12(I)=ALOG10(WP(I))
CALL POINTS
IF(IPNOW.EQ.0) THEN
CALL PLOT(.168,.53,1,27)
CALL PLOT(.168,.31,1,19)
ELSE
IF(NOTE.EQ.1) CALL PLOT(.168,.75,1,27)
IF(NOTE.EQ.2) CALL PLOT(.168,.75,1,19)
CALL SYMBEL(.16,.5,.0,.09,4,LZ6)
CALL SYMBEL(.16,.28,.0,.09,4,LZ7)
END IF
CALL POINTS
CALL PLOT(.009,-1.64,1,27)
CALL PLOT(.098,-1.64,1,19)
CALL LINE(FREQ,T12,27,NH2)
CALL LINE(FREQ,D,19,NH2)
CALL DASHES
CALL LINE(FREQ,VB,0,NH2)
CALL VECTORS
IF(X.NE.0) THEN
IF(IPNOW.EQ.0.AND.NOTE.NE.1) GO TO 5084
INTO=0
DO 6071 I=NH2,1,-1
IF(I.GE.ICPEAK) S2(I)=A1*FREQ(I)**X
6071 IF(I.LT.ICPEAK) S2(I)=.8*S2(ICPEAK)
DO 6066 I=ICPEAK,IDPEAK
J=I-ICPEAK+1
DR(J)=FREQ(I)
IF(S2(I).LT..1) VB(J)=-1.
6066 IF(S2(I).GE..1) VB(J)=ALOG10(S2(I))
CALL LINE(DB,VB,0,J)
END IF
5084 XL(1)=.17
XL(2)=.183
YL(1)=1.19
YL(2)=1.19
CALL SYMBOL(.05,-1.4,.0,.15,15,LX)
CALL SYMBOL(-.026,-.7,90.,.15,20,LY1)
CALL SYMBEL(-.038,-1.67,.0,-1.68,LY17)
CALL NUMBER(-.024,-1.03,.0,-1.6,1000)
CALL NUMBER(-.024,-.03,.0,-1.6,1000)
CALL NUMBER(-.024,.97,.0,-1.6,1000)
CALL NUMBER(-.024,1.97,.0,-1.6,1000)
IF(NOTE.EQ.1) CALL SYMBEL(.12,2.,.0,.15,20,ST)
IF(NOTE.EQ.2) CALL SYMBEL(.12,2.,.0,.15,20,ST2)
CALL SYMBEL(.173,1.64,.0,-1.07,19,LY22)

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CALL NUMBER(.185,1.64,.0,.09,6,PEAKF)
CALL NUMBER(.215,1.64,.0,.09,5,VLARGE)
CALL SYMBOL(.173,1.4,.0,.102,19,LY25)
CALL NUMBER(.185,1.4,.0,.09,6,TEMP)
CALL NUMBER(.215,1.4,.0,.09,5,VARY)
CALL SYMBOL(.191,1.16,.0,.09,10,LY19)
CALL SYMBOL(.2,.96,.0,.09,9,LY1)
CALL SYMBOL(.173,.72,.0,.09,11,LY18)
CALL SYMBOL(.173,.5,.0,.09,14,LX19)
CALL NUMBER(.179,.5,.0,.09,8,A1)
CALL NUMBER(.226,.5,.0,.09,6,X)
CALL SYMBOL(.17,.03,.0,.104,3,LX10)
CALL SYMBOL(.191,.03,.0,.09,8,LX8)
CALL SYMBOL(.2,-.17,.0,.09,9,LY1)
CALL SYMBOL(.173,-.37,.0,.09,16,LX2)
CALL SYMBOL(.187,-.57,.0,.09,15,M)
GO TO 5020
5018 CALL SYMBOL(.173,.28,.0,.09,14,LX19)
CALL NUMBER(.179,.28,.0,.09,8,A1)
CALL NUMBER(.226,.28,.0,.09,6,X)
IF(IPHOW.EQ.1.AND.X.NE.0.) THEN
II=ICPEAK-1
DO 5081 I=1,II
5081 S2(I)=A1*FREQ(I)**X
DO 5082 I=1,II
IF(S2(I).LT..1) VB(I)=-1.
5082 IF(S2(I).GE..1) VB(I)=ALOG10(S2(I))
CALL LINE(FREQ,VB,0,II)
GO TO 5083
END IF
IF(NOTE.EQ.2.AND.X.NE.0) THEN
INTD=0
DO 6051 I=NH2,1,-1
IF(I.GE.ICPEAK) S2(I)=A1*FREQ(I)**X
6051 IF(I.LT.ICPEAK) S2(I)=.8*S2(ICPEAK)
DO 6052 I=ICPEAK,1DPEAK
J=I-ICPEAK+1
DB(J)=FREQ(I)
IF(S2(I).LT..1) VB(J)=-1.
6052 IF(S2(I).GE..1) VB(J)=ALOG10(S2(I))
CALL LINE(DB,VB,0,J)
END IF
5083 CALL LINE(XL,YL,0,2)
CALL TEKPAUS
CALL ERASE
IF(INTD.NE.0) THEN
DO 6053 I=NH2,1,-1
IF(I.GE.ICPEAK) S2(I)=.00003/FREQ(I)**5
6053 IF(I.LT.ICPEAK) S2(I)=.8*S2(ICPEAK)
END IF
C *****
C ---PART VII: DRAWING APPLIED DIRECTIONAL SPREADING IN POLAR COORDINATES--- *
C *****
PRINT 303
303 FORMAT(/"====INPUT 1 WILL SET PROPOSED DIRECTION AS SMOOTHED DIRE
ION,/"====OR INPUT 2 TO SET MAIN DIRECTION IN PROPOSED SPECTRUM,
"/"====OR INPUT 3 TO SET BEST-FIT-CURVE IN PROPOSED SPECTRUM.")
READ*,JUMP
CALL ERASE
DO 6067 I=L1,NH2
ESDA=ESDA+RECORD(I)
6067 DMEAN=DMEAN+Df(I)+RECORD(I)
DDMEAN=DMEAN/ESDA
IF(JUMP.NE.2) THEN
CALL SCALE(17.4,16.,.42,.42,.0,.0)
CALL ORIGIN(3.03,2.83)
CALL POINTS
END IF
T12(1)=DDMEAN
DO 6065 I=2,NH2
IF(JUMP.NE.2) THEN
X=FREQ(I)*COS(D1(I))
Y=FREQ(I)*SIN(D1(I))
CALL PLOT(X,Y,1,1)
END IF
T12(I)=D1(I)
6065 IF(I.GT.L2.AND.ABS(T12(I)-T12(I-1)).GE..9) T12(I)=T12(I-1)
I=.7+T12(I)*.3
DMEAN=DDMEAN*DEGREE
CALL SMOOTH(N,D1,T12,NH2,0,2)
C ---WHERE D1(I) IS A SMOOTHED DIRECTIONAL SPREADING---
IF(JUMP.EQ.2) GO TO 304
IF(JUMP.EQ.3) THEN
II=IDEEP
IF(II.GT.NH3) II=NH3

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CALL SMOOTH(N,WP,RECORD,II,0,2)
DO 301 I=L1,II
A(1,1)=A(1,1)+WP(I)
BB=WP(I)*FREQ(I)
A(1,2)=A(1,2)+BB
BB=BB+FREQ(I)
A(1,3)=A(1,3)+BB
BB=BB+FREQ(I)
A(1,4)=A(1,4)+BB
BB=BB+FREQ(I)
A(2,4)=A(2,4)+BB
BB=BB+FREQ(I)
A(3,4)=A(3,4)+BB
A(4,4)=A(4,4)+BB+FREQ(I)
CC=WP(I)*(D1(I)-DDNEAN)
A(1,5)=A(1,5)+CC
CC=CC+FREQ(I)
A(2,5)=A(2,5)+CC
CC=CC+FREQ(I)
A(3,5)=A(3,5)+CC
301 A(4,5)=A(4,5)+CC+FREQ(I)
X12=A(1,1)
A(2,1)=A(1,2)
A(2,2)=A(1,3)
A(2,3)=A(1,4)
A(3,1)=A(1,3)
A(3,2)=A(2,3)
A(3,3)=A(2,4)
A(4,1)=A(1,4)
A(4,2)=A(2,4)
A(4,3)=A(3,4)
DO 405 I=1,4
DO 405 J=1,5
405 A(I,J)=A(I,J)/A(I,1)
DET=1.
DO 411 K=1,4
BIG=ABS(A(K,K))
KKK=K
DO 410 KK=K,4
IF(BIG-ABS(A(KK,K))) 409,410,410
409 BIG=ABS(A(KK,K))
KKK=K
410 CONTINUE
DO 408 JJ=K,5
BOXX=A(K, JJ)
A(K, JJ)=A(KKK, JJ)
408 A(KKK, JJ)=BOXX
DET=DET*A(K, K)
IF(DET-.0) 413,412,413
412 PRINT=, 'DET=.0'
STOP
413 K1=K+1
DO 414 J=K1,5
A(K, J)=A(K, J)/A(K, K)
IF(K-N.EQ.0) GO TO 411
DO 415 I=K1,4
415 A(I, J)=A(I, J)-A(I, K)*A(K, J)
414 CONTINUE
411 CONTINUE
XL(4)=A(4, 5)
K=4
417 SIGNN=.0
DO 416 J=K,4
416 SIGNN=SIGNN+A(K-1, J)*XL(J)
XL(K-1)=A(K-1, 5)-SIGNN
K=K-1
IF(K.EQ.1) GO TO 418
GO TO 417
418 Z1=XL(1)+DDNEAN
Z2=XL(2)
Z3=XL(3)
Z4=XL(4)
DO 302 I=1, NH2
302 D2(I)=Z1+Z2*FREQ(I)+Z3*FREQ(I)*FREQ(I)+Z4*FREQ(I)**3
C ---D2(I) IS THE BEST-FIT-CURVE FOR PROPOSED DIRECTION---
Z1=90.-Z1*DEGREE
Z2=-Z2*DEGREE
Z3=-Z3*DEGREE
Z4=-Z4*DEGREE
BB=-.0
CC=-.0
DO 305 I=L1, II
J=I-1+1
D(J)=FREQ(I)*COS(D2(I))
T33(J)=FREQ(I)*SIN(D2(I))
CC=CC*(D1(I)-DDNEAN)**2*WP(I)

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305 BB=BB+(D1(I)-D2(I))*2*UP(I)
BB=SQRT(BB/X12)*DEGREE
CC=SQRT(CC/X12)*DEGREE
XL(1)=.151
XL(2)=.148
YL(1)=.078
YL(2)=.078
CALL VECTORS
CALL LINE(D,T33,0,J)
CALL LINE(XL,YL,0,2)
CALL SYMBEL(.173,.075,.0,.105,6,LX30)
CALL NUMBER(.187,.075,.0,.08,7,Z1)
CALL SYMBEL(.2145,.065,.0,.08,1,LX)
IF(Z2.GT.0.) CALL SYMBEL(.17,.065,.0,.08,1,LZ10)
CALL NUMBER(.17,.065,.0,.08,8,Z2)
CALL SYMBEL(.2145,.055,.0,.08,1,LX)
CALL SYMBEL(.22,.058,.0,.065,1,LZ9)
IF(Z3.GT.0.) CALL SYMBEL(.17,.055,.0,.08,1,LZ10)
CALL NUMBER(.17,.055,.0,.08,8,Z3)
CALL SYMBEL(.2145,.045,.0,.08,1,LX)
CALL SYMBEL(.22,.048,.0,.065,1,LZ8)
IF(Z4.GT.0.) CALL SYMBEL(.17,.045,.0,.08,1,LZ10)
CALL NUMBER(.17,.045,.0,.08,8,Z4)
CALL SYMBEL(.173,.03,.0,.11,2,LZ5)
CALL SYMBEL(.179,.0283,.0,.09,4,LX22)
CALL SYMBEL(.195,.03,.0,.11,LX24)
CALL SYMBEL(.229,.033,.0,.05,1,LZ2)
CALL NUMBER(.2,.03,.0,.08,6,RR)
CALL SYMBEL(.173,-.145,.0,.11,2,LZ5)
CALL SYMBEL(.179,-.1467,.0,.09,4,LX22)
CALL SYMBEL(.195,-.145,.0,.11,LX24)
CALL SYMBEL(.229,-.142,.0,.05,1,LZ2)
CALL NUMBER(.2,-.145,.0,.08,6,CC)
END IF
S=90.-S
DM=90.-DMEAN
R=100.*ABS(DM-S)/S
L4=L1+L1/2
DO 6068 I=L4,NH2
II=I-L4+1
D(II)=FREQ(I)*COS(D1(I))
6068 T33(II)=FREQ(I)*SIN(D1(I))
CALL DASHES
CALL LINE(D,T33,0,II)
INTO=1
GO TO 7062
6072 CALL SYMBEL(.13,.095,.0,.18,9,LY1)
CALL SYMBEL(.15,-.0545,.0,.05,3,LY10)
CALL SYMBEL(.17,-.055,.0,.08,10,LX7)
CALL SYMBEL(.19,-.065,.0,.08,9,LX5)
CALL SYMBEL(.15,-.08,.0,.09,3,LX10)
CALL SYMBEL(.17,-.08,.0,.08,8,LX8)
CALL SYMBEL(.19,-.09,.0,.08,9,LX5)
CALL SYMBEL(.15,-.105,.0,.08,16,LX2)
CALL SYMBEL(.176,-.115,.0,.08,15,M)
CALL SYMBEL(.15,-.13,.0,.08,30,LY14)
CALL NUMBER(.215,-.13,.0,.08,6,DM)
IF(.IUMP.EQ.1) THEN
CALL SYMBEL(.15,-.145,.0,.08,29,LX25)
CALL NUMBER(.215,-.145,.0,.08,6,S)
CALL SYMBEL(.15,-.16,.0,.11,2,LZ5)
CALL SYMBEL(.155,-.16,.0,.08,10,LX24)
CALL NUMBER(.161,-.16,.0,.08,5,B)
END IF
CALL TEXPAUS
CALL ERASE
304 CONTINUE
C
IF(ABS(H1-4.3).GT.5) L5=0
DO 5043 I=1,NH1
IF(L5.EQ.0) RECORD(I)=RECORD(I)*(COSH(UK(I)*4.333)/COSH(UK(I))*
I1)**2
C ---RECORD(I) IS RAW DATA OF HORI. VELOCITY SPECTRUM @ 4.3'---
5043 DB(I)=RECORD(I)/FREQ(I)**2/39.47842
C ---39.47842=(CPI2)**2---
C ---DB(I) IS RAW DATA OF HORI. AMPLITUDE SPECTRUM @ 4.3' ABOVE SEA FLOOR---
C
DO 5041 I=1,NH1
UB(I)=DB(I)*(SINH(UK(I)*DEPTH)/COSH(UK(I)*4.333))**2
C ---VB(I) IS RAW DATA OF WAVE ENERGY SPECTRUM AT SEA SURFACE---
IF(VB(I).GE.2500.) GO TO 5042
5041 CONTINUE
C
5042 MINN=I-1

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K=MINN-1.5*L1
IF (IDEEP.GE.MINN) IDEEP=MINN
MAX=(IPEAK+K)/2
IF (MAX-IPEAK.GT.L1) MAX=IPEAK+L1
CALL SHOOTH(N,UP,UB,IDEEP,0,1)
IPEAK=IPEAK
VLARGE=UP(IPEAK)
MAX=MAX+L1/3
DO 5038 J=L2,MAX
IF (UP(J).LE.VLARGE) GO TO 5038
VLARGE=UP(J)
IPEAK=J
5038 CONTINUE
MM=K
IF (K.GT.IIPEAK*L1*2) MM=IIPEAK*L1*2.3
WRITE(*,5053) VLARGE,IPEAK,UP(MM),MM,(UP(I),I=L2,MM)
5053 FORMAT('//////////-----CHECK 1-D. WATER SURFACE ENERGY HERE, "/-----
1 INDEX OF PEAK ENERGY",F7.2," SHOW HERE IS",I3," "/-----INDEX OF
UPPER BOUND",F7.2," IS",I3," "/-----SMOOTHED ENERGY SERIES NEAR
PEAK ARE SHOWN AS FOLLOWS, "/(9F8.2))
PRINT 7067
7067 FORMAT('====INPUT NEW INDEX FOR UPPER BOUND TO CONTINUE, "/====
OR INPUT 0 TO STOP THE PROGRAM, "/====OR INPUT 1 WILL RESET INDEX
1 FOR DESIRED PEAK AND UPPER BOUND.')
READ*,MOD
IF (MOD.EQ.0) STOP
IF (MOD.EQ.1) THEN
READ*,IIPEAK,MOD
VLARGE=UP(IIPEAK)
END IF
K=MOD
XM=1.
X2=10.
PEAKF=FREQ(IIPEAK)
CALL ERASE
IF (K.LE.IIPEAK*3) PRINT*, 'IIPEAK=',IIPEAK,', K=',K
IF (K.LE.IIPEAK) STOP
C
Y=.6641874
LL=.62*IIPEAK
IF (K.GT.IIPEAK+LL) K=IIPEAK+LL
C ---LL WILL HELP AVOIDING THE OVERFLOW IN EXP---
DO 120 J=LL,K
C=EXP((PEAKF/FREQ(J))*4+1.25)*FREQ(J)**5
T13(I)=Y/C/C
120 T23(I)=UP(I)/C
P(IIPEAK)=1.
ALFA=VLARGE*PEAKF**5*3.490343/Y/GA
MM=1
130 MAX=1
160 X1=.0038
X2=4.
IF (MAX.EQ.1) CALL LSM(FF1,X1,MAX)
IF (MAX.EQ.1) B=FF1
IF (MAX.EQ.2) FF1=B
110 CALL LSM(FF2,X2,MAX)
XN=100000.*FF1*FF2
IF (XN.GT.0) THEN
X2=X2*2.
IF (X2.LE.10.) GO TO 110
PA=.0
PC=.0
ALFA=.0081
GA=1.
DO 7055 I=IIPEAK,NH1
TEMP=PEAKF/FREQ(I)
V(I)=TEMP**5*EXP(1.25*(1.-TEMP**4))*VLARGE
C ---USE P-M SPECTRUM TO EXTRAPOLATE THE TAIL OF RAW DATA OF WAVE ENERGY DENSITY---
7055 WP(I)=V(I)
DO 7056 I=1,IIPEAK
TEMP=PEAKF/FREQ(I)
A2=1.25*(1.-TEMP**4)
IF (I.GE.IPEAK) V(I)=UP(I)
IF (I.LT.IPEAK) V(I)=.0
7056 IF (I.LT.IPEAK.AND.A2.GE.-670.) V(I)=TEMP**5*EXP(A2)*VLARGE
GO TO 220
END IF
DO 140 I=1,15
X=(X1+X2)/2.
CALL LSM(FF,X,MAX)
XN=100000.*FF*FF1
IF (XN.LE.0) THEN
X2=X
FF2=FF

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ELSE
X1=X
FF1=FF
END IF
IF (ABS(FF)-1.E-8) 150,150,140
140 CONTINUE
150 IF (MAX.EQ.1) PA=X
IF (MAX.EQ.2) PC=X
MAX=MAX+1
IF (MAX.LE.2) GO TO 160
Z1=.0
Z2=.0
Z3=.0
Z4=.0
DO 170 I=LL,K
TEMP=PC
IF (I.LT.IIPEAK) TEMP=PA
P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/TEMP)**2/26.))**13
C ---WHERE .36788=1/EXP---
C=GA**P(I)
Z1=Z1+T13(I)*C*C
Z2=Z2+T23(I)*C
Z3=Z3+T13(I)*P(I)*C/C/GA
170 Z4=Z4+T23(I)*P(I)*C/GA
Z1=Z2/Z1
Z2=Z4/Z3
ALFA=(Z1+Z2)/2.
GA=VLARGE*PEAKF**5*3.490343/Y/ALFA
IF (ABS((Z1-Z2)/Z1).LE..01) GO TO 180
MM=MM+1
IF (MM.LE.15) GO TO 130
180 MAX=FLOAT(IIPEAK)*(1.+125.*PC)
DO 190 I=LL,MM1
IF (I.LE.K) V(I)=ALFA*Y/FREQ(I)**5/EXP((PEAKF/FREQ(I))**4*1.25)
!*GA**P(I)
C ---V(I) IS AN APPLIED JONSWAP SPECTRUM AT SEA SURFACE---
IF (I.GT.K.AND.I.LE.MAX) THEN
P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/PC)**2/26.))**13
V(I)=ALFA*Y/FREQ(I)**5/EXP((PEAKF/FREQ(I))**4*1.25)*GA**P(I)
END IF
IF (I.GT.MAX) V(I)=V(MAX)
190 IF (I.GT.IDEEP) UP(I)=V(I)
C ---USE JONSWAP TO EXTRAPOLATE THE TAIL PART OF RAW DATA OF WAVE ENERGY SPECTRUM---
VALUE=FLOAT(IIPEAK)*(1.-125.*PA)+1.
DO 5034 I=1,LL
A2=(PEAKF/FREQ(I))**4*1.25
IF (A2.GT.740.) THEN
V(I)=.0
ELSE
V(I)=.0
IF (I.GT.VALUE) P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/PA)**2/26.))**13
IF (I.GT.VALUE) V(I)=ALFA*Y/FREQ(I)**5/EXP(A2)*GA**P(I)
END IF
5034 CONTINUE
220 B2=.0
B3=.0
ESDB=.0
DO 7063 I=1,MM1
C IF (I.LT.IIPEAK.AND.V(I).LT.UP(I)) V(I)=UP(I)
C IF (I.LE.IIPEAK) B2(I)=V(I)
C ---B2(I) KEEPS THE ORIGINAL FRONT PART OF JONSWAP---
ESDB=ESDB+RECORD(I)
B2=B2+FREQ(I)*V(I)
7063 B3=B3+V(I)/FREQ(I)
VMS=ESDB*FREQ1
B2=SQR(B2/B3)
B=.0
DO 5065 I=L1,IDPEAK
ESDB=ESDB+V(I)
5065 B=B+(V(I)-UP(I))**2
TOT=ESDB*FREQ1
ERR1=100.*SQRT(B)/ESDB
DO 7064 I=1,MM2
IF (S1(I).GT.1000.) S1(I)=1000.
IF (S2(I).GT.1000.) S2(I)=1000.
C ---ASSURE THAT SPREADING PARAMETER WILL BE NEVER ACCESSES 50.---
IS=INT(S1(I))
IF (IS.EQ.0) THEN
T13(I)=S1(I)
ELSE
IF (IS.LT.100) T13(I)=FS(IS)+(S1(I)-IS)*(FS(IS+1)-FS(IS))
IF (IS.GE.100) T13(I)=8.87335+.022*(S1(I)-100.)
END IF
IS=INT(S2(I))

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      IF(IS.EQ.0) THEN
        T23(I)=S2(I)
      ELSE
        IF(IS.LT.100) T23(I)=FS(IS)+(S2(I)-IS)*(FS(IS+1)-FS(IS))
        IF(IS.GE.100) T23(I)=8.87335+.022*(S2(I)-100.)
      END IF
7064 CONTINUE
C ---T13 & T23 REPRESENT G(5)*CPI AS SHOWN IN THEORETICAL SOLUTION---
C *****
C ---PART VIII: DRAWING ONE DIMENSIONAL KINEMATIC SPECTRUM IN LOG. SCALE--- *
C *****
      PRINT 5032
      READ*,MODE
C ---MODE=1 : WILL CALCULATE HORIZONTAL VELOCITY SPECTRUM AT 4.3 FT ABOVE SEA BUTTOM---
C ---MODE=2 : WILL CALCULATE HORIZONTAL AMPLITUDE SPECTRUM AT 4.3 FT ABOVE SEA BUTTOM---
C ---MODE=3 : WILL CALCULATE WAVE ENERGY SPECTRUM AT SEA SURFACE---
      IF(MODE.EQ.4) GO TO 7072
C
C ---ONCE CALCULATION THROUGH THIS LINE WILL DISCONNECT WITH ABOVE PART---
C
5048 PRINT 5035
5035 FORMAT(/// "====INPUT 1 TO DRAW ONE DIMENSIONAL SPECTRUM,"/"====
10R INPUT 2 TO DRAW DIRECTIONAL SPECTRUM.")
      READ*,JMODE
      IF(JMODE.EQ.2) THEN
        IF(MODE.EQ.3) GO TO 5046
        GO TO 5052
      END IF
      CALL ERASE
C
      IF(MODE.NE.3) GO TO 5029
      CALL SCALE(.76,1.1,1.,0,-2.)
      CALL AXISL(.0,.6,.0,-2.,3,-2.,1,1.,0,1,0,1.,1.,.1,0)
      CALL SYMBOL(-1,-3.08,.0,.1,60,LY5)
      CALL NUMBER(.579,-3.08,.0,.1,7,DEPTH)
      CALL SYMBOL(-.05,3.65,.0,.18,17,LY2)
      DO 5037 J=1,NINM
        IF(VB(J).LT..01) T12(J)=-2.
5037 IF(VB(J).GE..01) T12(J)=ALOG10(VB(J))
        CALL POINTS
        CALL LINE(FREQ,T12,19,MINM)
        CALL PLOT(.47,-.19,1,19)
5046 DO 5036 J=1,NH1
        PB(J)=UP(J)
        IF(JMODE.EQ.1) THEN
          IF(PB(J).LT..01.AND.J.LE.IDEEP) T12(J)=-2.
          IF(PB(J).GE..01.AND.J.LE.IDEEP) T12(J)=ALOG10(PB(J))
          IF(V(J).LT..01) T33(J)=-2.
          IF(V(J).GE..01) T33(J)=ALOG10(V(J))
        END IF
5036 P(J)=V(J)
        IF(JMODE.EQ.2) GO TO 7060
        PEAKF=FREQ(IPEAK)
        VLARGE=V(IPEAK)
        XL(1)=.452
        XL(2)=.482
        YL(1)=-1.
        YL(2)=-1.
        CALL VECTORS
        CALL LINE(XL,YL,0,2)
        CALL LINE(FREQ,T33,0,NH1)
        CALL DASHES
        CALL LINE(FREQ,T12,0,IDEEP)
        CALL SYMBOL(-.1,-2.,90.,.15,24,LYB)
        CALL SYMBOL(.18,-2.68,.0,.15,15,LX)
        CALL NUMBER(-.088,2.95,.0,.1,7,1000.0)
        CALL NUMBER(-.088,1.95,.0,.1,7,100.00)
        CALL NUMBER(-.088,.95,.0,.1,7,10.000)
        CALL NUMBER(-.088,-.05,.0,.1,7,1.0000)
        CALL NUMBER(-.088,-1.05,.0,.1,7,0.1000)
        CALL NUMBER(-.088,-2.05,.0,.1,7,0.0100)
        IF(NOTE.EQ.1) CALL SYMBOL(.36,3.3,.0,.15,20,ST)
        IF(NOTE.EQ.2) CALL SYMBOL(.36,3.3,.0,.15,20,ST2)
        CALL SYMBOL(.5,2.86,.0,.11,2,LZ5)
        CALL SYMBOL(.511,2.83,.0,.08,4,LX22)
        CALL SYMBOL(.555,2.86,.0,.09,10,LX24)
        CALL NUMBER(.57,2.86,.0,.088,5,ERR1)
        CALL SYMBOL(.46,2.5,.0,.09,29,LX20)
        CALL NUMBER(.583,2.5,.0,.09,6,TOT)
        CALL SYMBOL(.5,2.14,.0,.09,7,LX15)
        CALL NUMBER(.545,2.14,.0,.09,7,ALFA)
        CALL SYMBOL(.5,1.82,.0,.09,7,LY15)
        CALL NUMBER(.545,1.82,.0,.09,5,GA)

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CALL SYMBEL(.5,1.5,.0,.09,10,LX16)
CALL NUMBER(.545,1.5,.0,.09,5,PA)
CALL SYMBEL(.5,1.18,.0,.09,10,LY16)
CALL NUMBER(.545,1.18,.0,.09,5,PC)
CALL SYMBEL(.46,.84,.0,.09,18,LX11)
CALL NUMBER(.615,.84,.0,.09,6,PEAKF)
CALL SYMBEL(.46,.44,.0,.09,15,LY11)
CALL NUMBER(.59,.44,.0,.09,7,VLARGE)
CALL SYMBEL(.5,.14,.0,.09,27,LY20)
CALL NUMBER(.546,.14,.0,.09,6,R2)
CALL SYMBOL(.495,-.26,.0,.09,9,LX9)
CALL SYMBOL(.45,-.66,.0,.09,3,LX10)
CALL SYMBOL(.495,-.66,.0,.09,8,LX8)
CALL SYMBOL(.605,-.66,.0,.09,8,LX6)
CALL SYMBOL(.495,-1.06,.0,.09,10,LY9)
CALL SYMBOL(.588,-1.06,.0,.09,8,LX6)
CALL SYMBEL(.46,-1.46,.0,.09,16,LX2)
CALL SYMBOL(.496,-1.71,.0,.09,15,M)
CALL TEKPAUS

C
IF(MODE.EQ.3) GO TO 7060
5029 CALL SCALE(8.3,.76,1.1,1,.0,0,-4.)
CALL AXIS(.0,.6,.0,-4.,1,-4.,.1,1,0,1,0,1,.1,.1,0)
IF(MODE.EQ.1) THEN
CALL SYMBOL(-.1,-5.08,.0,-.1,55,LY7)
CALL SYMBEL(-.05,1.65,.0,.18,18,LX1)
CALL SYMBEL(.504,.26,.0,.105,5,LX21)
CALL SYMBEL(.55,.25,.0,.1,20,LY21)
CALL SYMBEL(.517,.22,.0,.08,5,LX22)
CALL NUMBER(.561,.25,.0,.088,6,VMS)
B=100.*ABS(SV-VMS)/VMS
CALL SYMBOL(.504,-.05,.0,.09,4,LX25)
CALL NUMBER(.56,-.05,.0,.088,6,SV)
CALL SYMBEL(.64,-.05,.0,.1,10,LX26)
CALL NUMBER(.65,-.05,.0,.088,5,B)
ELSE
CALL SYMBOL(-.1,-5.08,.0,-.1,56,LY6)
CALL SYMBEL(-.05,1.65,.0,.18,15,LY)
END IF
5052 IF(MODE.EQ.1) CALL SMOOTH(N,PB,RECORD,NH1,0,1)
IF(MODE.EQ.2) CALL SMOOTH(N,PB,DB,NH1,0,1)
PEAKF=FREQ(IPEAK)
VLARGE=.0
DO 5031 I=1,NH1
IF(MODE.EQ.1) THEN
IF(1.LE.IPEAK)P(I)=V(I)*RECORD(I)/VB(I)
IF(1.GT.IPEAK)P(I)=V(I)*(COSH(UK(I)*4.333)+FREQ(I)*CP12/SINH(UK(I)
+DEPTH))**2
IF(JMODE.EQ.1.AND.RECORD(I).LT.ADEP) T12(I)=-4.
IF(JMODE.EQ.1.AND.RECORD(I).GE.ADEP)T12(I)=ALOG10(RECORD(I))-EDEP
ELSE
IF(1.LE.IPEAK)P(I)=V(I)*DB(I)/VB(I)
IF(1.GT.IPEAK) P(I)=V(I)*(COSH(UK(I)*4.333)/SINH(UK(I)*DEPTH))**2
IF(JMODE.EQ.1.AND.DB(I).LT.ADEP) T12(I)=-4.
IF(JMODE.EQ.1.AND.DB(I).GE.ADEP)T12(I)=ALOG10(DB(I))-EDEP
END IF
IF(JMODE.EQ.1) THEN
IF(P(I).LT.ADEP) D(I)=-4.
IF(PB(I).LT.ADEP) T33(I)=-4.
IF(P(I).GE.ADEP) D(I)=ALOG10(P(I))-EDEP
IF(PB(I).GE.ADEP) T33(I)=ALOG10(PB(I))-EDEP
END IF
IF(1.LT.L1.AND.1.GT.NHS) GO TO 5031
IF(P(I).LT.VLARGE) GO TO 5031
VLARGE=P(I)
II=I
5031 CONTINUE
PEAKF=FREQ(II)
IF(JMODE.EQ.2) GO TO 7060
IF(MODE.EQ.1) THEN
B=.0
ESDB=.0
DO 5066 J=L1,IDPEAK
ESDB=ESDB+P(I)
5066 B=B+(P(I)-PB(I))**2
ERR2=100.*SQRT(B)/ESDB
CALL SYMBEL(.504,.65,.0,.11,2,LZ5)
CALL SYMBEL(.517,.62,.0,.08,4,LX22)
CALL SYMBEL(.55,.65,.0,.1,10,LX24)
CALL NUMBER(.561,.65,.0,.088,5,ERR2)
END IF
CALL POINTS
CALL LINE(FREQ,T12,17,NH1)
CALL PLOT(.47,-1.29,1,17)

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CALL DASHES
CALL LINE(FREQ,T33,0,MH1)
XL(1)=.452
XL(2)=.482
YL(1)=-2.4
YL(2)=-2.4
CALL VECTORS
CALL LINE(XL,YL,0,2)
CALL LINE(FREQ,0,0,MH1)
CALL SYMBOL(.18,-4.,90.,.15,24,LYB)
CALL SYMBOL(.18,-4.68,0.0,0.15,15,LX)
IF(EDEF.LT.1.) CALL NUMBER(-.07,-4.05,.0,.1,6,.0001)
IF(EDEF.LT.1.) CALL NUMBER(-.07,-3.05,.0,.1,5,.001)
IF(EDEF.LT.1.) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(EDEF.LT.1.) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(EDEF.LT.1.) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(EDEF.LT.1.) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(EDEF.GE.1.) CALL NUMBER(-.07,-4.05,.0,.1,5,.010)
IF(EDEF.GE.1.) CALL NUMBER(-.07,-3.05,.0,.1,5,.100)
IF(EDEF.GE.1.) CALL NUMBER(-.07,-2.05,.0,.1,5,1.00)
IF(EDEF.GE.1.) CALL NUMBER(-.07,-1.05,.0,.1,5,10.0)
IF(EDEF.GE.1.) CALL NUMBER(-.07,-.05,.0,.1,5,100.)
IF(EDEF.GE.1.) CALL NUMBER(-.07,.95,.0,.1,6,1000.)
IF(NOTE.EQ.1) CALL SYMBEL(.36,1.3,.0,-15,20,ST)
IF(NOTE.EQ.2) CALL SYMBEL(.36,1.3,.0,-15,20,ST2)
CALL SYMBEL(.46,-.55,.0,.09,18,LX11)
CALL NUMBER(.615,-.55,.0,.09,6,PEAKF)
CALL SYMBEL(.46,-.95,.0,.09,15,LY11)
CALL NUMBER(.59,-.95,.0,.09,6,VLARGE)
CALL SYMBOL(.495,-1.35,.0,.09,9,LX9)
CALL SYMBOL(.45,-1.76,.0,.09,3,LX10)
CALL SYMBOL(.495,-1.76,.0,.09,8,LX8)
CALL SYMBOL(.54,-2.06,.0,.09,8,LX6)
CALL SYMBEL(.495,-2.46,.0,.09,4,LX14)
CALL SYMBEL(.553,-2.46,.0,.09,10,LY9)
CALL SYMBEL(.54,-2.76,.0,.09,8,LX6)
CALL SYMBEL(.46,-3.16,.0,.09,16,LX2)
CALL SYMBEL(.496,-3.46,.0,.09,15,R)
CALL TEKPAUS

C
C *****
C ---PART IX: DRAWING DIRECTIONAL SPECTRUM IN THREE DIMENSION SPACE---
C *****
C ---THIS PART WILL BE MORE FLEXIBLE AS APPLIED TO SMOOTHED DIRECTIONAL SPECTRUM---
7060 CONTINUE
C ---THE FOLLOWING 137 LINE CAN BE DELETED IF IT IS NOT INTENDED TO HAVE---
C
C
IF(MODE.EQ.2.DR.JMODE.EQ.2) GO TO 7057
BDEP=.01
IF(MODE.EQ.1.AND.DEPTH.LT.140.) BDEP=1.
CALL ERASE
IF(MODE.EQ.1) CALL SCALE(8.3,.76,1-1,1...0,-2.)
DO 7058 I=1,MH2
COSDA=COS((DPMEAN-D1(I))/2.)*2
TEMP=ALOG10(COSDA)*5(I)
IF(TEMP.GE.-120.) T12(I)=PB(I)*T13(I)/CPI+COSDA**5(I)
IF(TEMP.LT.-120.) T12(I)=PB(I)*T13(I)/CPI*1.E-120
IF(MODE.EQ.1) T12(I)=T12(I)*100.
IF(T12(I).LT.BDEP) THEN
T12(I)=-2.
ELSE
T12(I)=ALOG10(T12(I))
IF(BDEP.GE..5) T12(I)=T12(I)-2.
END IF
7058 CONTINUE
XL(1)=.498
XL(2)=.528
YL(1)=-.1
YL(2)=-.1
IF(MODE.EQ.3) THEN
CALL SYMBEL(-.05,3.65,.0,.18,17,LY2)
CALL SYMBEL(.18,-2.68,.0,.15,15,LX)
CALL NUMBER(-.088,2.95,.0,.1,7,1000.0)
CALL NUMBER(-.088,1.95,.0,.1,7,100.00)
CALL NUMBER(-.088,.95,.0,.1,7,10.000)
CALL NUMBER(-.088,-.05,.0,.1,7,1.0000)
CALL NUMBER(-.088,-1.05,.0,0.1,7,.1000)
CALL NUMBER(-.088,-2.05,.0,-1,7,0.0100)
ELSE
CALL SYMBEL(-.05,3.65,.0,.18,18,LX1)
CALL SYMBEL(.18,-2.68,.0,.15,15,LX)
IF(BDEP.LT..5) CALL NUMBER(-.07,-2.05,.0,.1,6,.0001)
IF(BDEP.LT..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.001)
IF(BDEP.LT..5) CALL NUMBER(-.07,-.05,.0,.1,5,.010)

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IF(BDEP.LT..5) CALL NUMBER(-.07,.95,.0,.1,5,.100)
IF(BDEP.LT..5) CALL NUMBER(-.07,1.95,.0,.1,5,1.00)
IF(BDEP.LT..5) CALL NUMBER(-.07,2.95,.0,.1,5,10.0)
IF(BDEP.GE..5) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(BDEP.GE..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(BDEP.GE..5) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(BDEP.GE..5) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(BDEP.GE..5) CALL NUMBER(-.07,1.95,.0,.1,5,100.)
IF(BDEP.GE..5) CALL NUMBER(-.07,2.95,.0,.1,5,1000.)
CALL SYMBOL(.504,1.67,.0,.09,12,LY23)
CALL NUMBER(.495,1.37,.0,.085,4,4.3)
CALL SYMBEL(.511,1.37,.0,.09,24,LY12)
END IF
CALL AXISL(.0,.6,.0,-2.,3.,-2.,.1,1.,1,0,1,0,1.,1.,.1,0)
CALL LINE(FREQ,T12,0,WHZ)
CALL LINE(XL,YL,0,2)
CALL SYMBOL(.393,2.6,.0,.15,9,LX)
CALL SYMBOL(.594,2.6,.0,.15,8,LX6)
CALL SYMBOL(.393,2.07,.0,.15,2,LZ2)
CALL SYMBOL(.4515,2.07,.0,.15,14,LY14)
CALL SYMBOL(.54,.04,.0,.09,8,LX8)
CALL SYMBOL(.585,-.26,.0,.09,8,LX6)
CALL SYMBEL(.504,-.66,.0,.09,16,LX2)
CALL SYMBOL(.54,-.96,.0,.09,15,M)
CALL SYMBEL(.504,-1.36,.0,.09,18,LY14)
CALL NUMBER(.585,-1.66,.0,.085,6,6M)
CALL SYMBOL(.648,-1.57,.0,.06,1,LZ4)
CALL TEKPAUS
CALL ERASE
C
IF(MODE.EQ.1) IPNOU=IPEAK
IF(MODE.EQ.3) IPNOU=IPEAK
DO 7059 I=1,120
C=FLOAT(I)*3.*RM-CPI
COSDA=COS((C-D1(IPNOU))/2.)*2
TEMP=ALOG10(COSDA)*S1(IPNOU)
IF(TEMP.GE.-120.) T12(I)=VLARGE*T13(IPNOU)/CPI+COSDA*S1(IPNOU)
IF(TEMP.LT.-120.) T12(I)=VLARGE*T13(IPNOU)/CPI+1.E-120
IF(MODE.EQ.1) T12(I)=T12(I)*100.
T33(I)=FLOAT(I)/300.
IF(T12(I).L1.RDEP) THEN
T12(I)=-2.
ELSE
T12(I)=ALOG10(T12(I))
IF(BDEP.GE..5) T12(I)=T12(I)-EDEP
END IF
7059 CONTINUE
IF(MODE.EQ.3) THEN
CALL SYMBEL(-.05,3.65,.0,.18,17,LY2)
CALL NUMBER(-.088,2.95,.0,.1,7,1000.0)
CALL NUMBER(-.088,1.95,.0,.1,7,100.00)
CALL NUMBER(-.088,.95,.0,.1,7,10.000)
CALL NUMBER(-.088,-.05,.0,.1,7,1.0000)
CALL NUMBER(-.088,-1.05,.0,0.1,7,.1000)
CALL NUMBER(-.088,-2.05,.0,.1,7,0.0100)
ELSE
CALL SYMBEL(-.05,3.65,.0,.18,18,LX1)
IF(BDEP.LT..5) CALL NUMBER(-.07,-2.05,.0,.1,6,.0001)
IF(BDEP.LT..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.001)
IF(BDEP.LT..5) CALL NUMBER(-.07,-.05,.0,.1,5,.010)
IF(BDEP.LT..5) CALL NUMBER(-.07,.95,.0,.1,5,.100)
IF(BDEP.LT..5) CALL NUMBER(-.07,1.95,.0,.1,5,1.00)
IF(BDEP.LT..5) CALL NUMBER(-.07,2.95,.0,.1,5,10.0)
IF(BDEP.GE..5) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(BDEP.GE..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(BDEP.GE..5) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(BDEP.GE..5) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(BDEP.GE..5) CALL NUMBER(-.07,1.95,.0,.1,5,100.)
IF(BDEP.GE..5) CALL NUMBER(-.07,2.95,.0,.1,6,1000.)
CALL SYMBOL(.504,1.67,.0,.09,12,LY23)
CALL NUMBER(.495,1.37,.0,.085,4,4.3)
CALL SYMBEL(.511,1.37,.0,.09,24,LY12)
END IF
CALL AXISL(.0,.4,.0,-2.,3.,-2.,.05,1.,1,0,0,0,1.,1.,.1,0)
CALL LINE(T33,T12,0,120)
CALL LINE(XL,YL,0,2)
CALL SYMBOL(-.006,-2.26,.0,.11,1,LX4)
CALL SYMBOL(.094,-2.26,.0,.11,1,LY4)
CALL SYMBOL(.194,-2.26,.0,.11,1,LX3)
CALL SYMBOL(.294,-2.26,.0,.11,1,LY3)
CALL SYMBOL(.394,-2.26,.0,.11,1,LX4)
CALL SYMBOL(.09,-2.72,.0,.15,9,LX5)
CALL SYMBOL(.294,-2.72,.0,.15,8,LX23)
CALL SYMBOL(.336,2.6,.0,.15,11,LX5)
CALL SYMBOL(.5646,2.6,.0,.15,8,LX6)

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CALL SYMBOL(.336,2.07,.0,.15,2,LZ2)
CALL SYMBOL(.3945,2.07,.0,.15,18,LY24)
CALL SYMBOL(.54,.04,.0,.09,8,LXB)
CALL SYMBOL(.585,-.26,.0,.09,8,LX6)
CALL SYMBOL(.504,-.66,.0,.09,16,LX2)
CALL SYMBOL(.54,-.96,.0,.09,15,M)
CALL SYMBOL(.504,-1.36,.0,.09,22,LY24)
CALL NUMBER(.6,-1.66,.0,.085,6,PEAKF)
CALL SYMBOL(.678,-1.66,.0,.088,2,LZ3)
CALL TEKPAUS
7057 CONTINUE
C
C
CALL ERASE
CALL SCALE(17.4,16.,.42,.42,.0,.0)
PRINT 7069
READ*, JMODE
GO TO (7068,7068,7071,7072) JMODE
7068 PRINT 7061, MODE
7061 FORMAT(IX/"====INPUT CONSTANT, CMODE, FOR RANGING THE CONTOURS."/
!"-----CMODE=1. WILL COVER 1,4,10,40,100,400,700,1000."/!"-----CMODE
! IS THE VALUE 10**INTEGER, RANGE: (1,4,10,40,100,400,700,1000)*CMODE."/!"-----FOR
! EXAMPLE: CMODE=.1 COVERS (.1,.4,1,4,10,40,100)."/!"-----GUIDE: CMODE
! =.1,1,10. RESPECT TO MODE=1,2,3. MODE="1,1," NOW.")
READ*,CMODE
PRINT 800
800 FORMAT("/"====INPUT ANGULAR INTERVAL (DEG.) FOR ITERATIVE COMPUTAT
!ION." /!"-----GUIDE: 4 FOR ROUGH DRAW, OR LESS FOR SHARP VIEW.")
READ*,NH3
VLARGE=.002+.0002*NH3
R=.0
SUM=.0
ALL=.0
PRINT 7074
7074 FORMAT(IX/"====INPUT NUMBER OF POINT-INCREMENT IN FREQUENCY INDEX
1."/!"-----E.G. INPUT 3 WILL SKIF 2 POINTS, ETC."/!"-----GUIDE: INPUT
1 1 FOR N.LE.256, INPUT (N/256)*2 FOR N.GT.256.")
READ*,NH4
FREQ2=FLOAT(NH4)*FREQ1
CALL ERASE
CALL ORIGIN(3.03,2.83)
DO 7070 I=2,NH2,NH4
IF(JMODE.EQ.1) THEN
T12(I)=T13(I)/CMODE/CP1*PB(I)
ELSE
T33(I)=T23(I)/CMODE/CP1*P(I)
IF(1.GE.L1.AND.1.LE.IDPEAK) T12(I)=T13(I)/CMODE/CP1*PB(I)
END IF
7070 CONTINUE
C ---P(I) IS THE PROPOSED JOHNSWAP SPECTRUM, AND PR(I) IS THE SMOOTHED DATA---
MIN=INT(DMEAN)-90
MAX=2*INT(DMEAN)-MIN
C
DO 7065 J=MIN,MAX,NH3
C=FLOAT(J)
BIG=C*RW
COSJ=COS(BIG)
SINJ=SIN(BIG)
ESDA=1.E-7
DO 200 JJ=1,7
200 IXY(JJ)=0
C
IF(JMODE.EQ.2.AND.JUMP.EQ.2) COSDA=COS((BIG-DMEAN)/2.)*2
DO 7066 I=2,NH2,NH4
IF(JMODE.EQ.1.OR.JUMP.EQ.1) COSDA=COS((BIG-D1(I))/2.)*2
IF(JMODE.EQ.2.AND.JUMP.EQ.3) COSDA=COS((BIG-D2(I))/2.)*2
IF(JMODE.EQ.1) THEN
TEMP=ALOG10(COSDA)*S1(I)
IF(TEMP.GE.-120.) ESDR=T12(I)*COSDA**S1(I)
IF(TEMP.LT.-120.) ESDR=T12(I)*1.E-120
ELSE
TEMP=ALOG10(COSDA)*S2(I)
IF(TEMP.GE.-120.) ESDR=T33(I)*COSDA**S2(I)
IF(TEMP.GE.-120..AND.1.GE.L1.AND.1.LE.IDPEAK) L2=10
IF(L2.EQ.10) BOXX=COS((BIG-D1(I))/2.)*2
IF(L2.EQ.10) SUM=SUM+(ESDR-T12(I)*BOXX**S1(I))*2
IF(TEMP.LT.-120.) ESDR=T33(I)*1.E-120
END IF
ALL=ALL+ESDR
IF(ESDA.LT.1..AND.ESDB.LT.1.) GO TO 7066
IF(ESDA.GT.1000..AND.ESDB.GT.1000.) GO TO 7066
IF(1.LT.IPEAK-10.OR.1.GT.IPEAK+10) GO TO 700
IF(C.LT.DMEAN-20..OR.C.GT.DMEAN+20.) GO TO 700
IF(ESDB.GT.B) THEN
R=ESDB

```

```

      L3=1
      CC=C
      END IF
C ---WHERE ESDB IS THE DISCRETE DIRECTIONAL SPECTRUM OF INTERESTED WAVE PROPERTY---
700 L00=INT(ESDA)
      L11=INT(ESDB)
      IF(L00.GE.1.AND.L00.LE.4) THEN
        L00=1
      ELSE IF(L00.GE.5.AND.L00.LE.9) THEN
        L00=2
      ELSE IF(L00.GE.10.AND.L00.LE.49) THEN
        L00=3
      ELSE IF(L00.GE.50.AND.L00.LE.99) THEN
        L00=4
      ELSE IF(L00.GE.100.AND.L00.LE.499) THEN
        L00=5
      ELSE IF(L00.GE.500.AND.L00.LE.999) THEN
        L00=6
      ELSE IF(L00.GE.1000) THEN
        L00=7
      END IF
      IF(L11.GE.1.AND.L11.LE.4) THEN
        L11=1
      ELSE IF(L11.GE.5.AND.L11.LE.9) THEN
        L11=2
      ELSE IF(L11.GE.10.AND.L11.LE.49) THEN
        L11=3
      ELSE IF(L11.GE.50.AND.L11.LE.99) THEN
        L11=4
      ELSE IF(L11.GE.100.AND.L11.LE.499) THEN
        L11=5
      ELSE IF(L11.GE.500.AND.L11.LE.999) THEN
        L11=6
      ELSE IF(L11.GE.1000) THEN
        L11=7
      END IF
      LLL=L11
      L2=1
      IF(L11-L00) 10,7066,20
10  L11=L00
      L00=LLL
      L2=0
20  L00=L00+1
      IF(L11.GT.11) L11=11
      DO 100 K=L00,L11
        IF(K.EQ.1.OR.K.EQ.3.OR.K.EQ.5.OR.K.EQ.7) KMODE=10**(K/2)
        IF(K.EQ.2.OR.K.EQ.4.OR.K.EQ.6) KMODE=5.*10**(K/2-1)
        TEMP=FREQ(I)-ABS((KMODE-ESDB)/(ESDA-ESDB))*FREQ2
        K1=IXY(K)+1
        IF(K1.GT.14) GO TO 100
        K2=1
        IF(XX(K,K1,1).NE.1.) K2=2
        XX(K,K1,K2)=TEMP*CDSJ
        YY(K,K1,K2)=TEMP*SINJ
C ---K: "MEMORY CODE" FOR TRACING THE RELATIVE CONTOURS---
C ---K1: "ORDER CODE" FOR CONNECTING PRESENT(I) & LAST(I-1)-RUN CONTOUR LOCATION---
C ---K2: "ITERATION CODE", K2=1 FOR LAST-RUN, K2=2 FOR PRESENT RUN---
        IXY(K)=K1
        IF(K2.NE.2) GO TO 100
30  XL(1)=XX(K,K1,1)
        XL(2)=XX(K,K1,2)
        YL(1)=YY(K,K1,1)
        YL(2)=YY(K,K1,2)
        X12=SQRT(XL(2)*XL(2)+YL(2)*YL(2))-SQRT(XL(1)*XL(1)+YL(1)*YL(1))
        IF(ABS(X12).LT.VLARGE) GO TO 300
        IF(X12) 40,300,50
40  DO 60 L=13,K1,-1
        XX(K,L+1,1)=XX(K,L,1)
60  YY(K,L+1,1)=YY(K,L,1)
        XX(K,K1,1)=XX(K,K1,2)
        YY(K,K1,1)=YY(K,K1,2)
        GO TO 30
50  MM=K1+1
        DO 70 II=MM,14
        XL(1)=XX(K,II,1)
        IF(XL(1).EQ.1.) GO TO 400
        YL(1)=YY(K,II,1)
        X12=SQRT(XL(2)*XL(2)+YL(2)*YL(2))-SQRT(XL(1)*XL(1)+YL(1)*YL(1))
        IF(ABS(X12).LT.VLARGE) THEN
          DO 80 LL=1,13
          XX(K,K1+LL,1)=XX(K,II+LL,1)
          YY(K,K1+LL,1)=YY(K,II+LL,1)
          IF(II+LL.GE.14) XX(K,14,1)=1.
80  IF(XX(K,K1+LL,1).EQ.1.) GO TO 300
        END IF
70  CONTINUE

```

```

GO TO 400
300 IF(L2.EQ.1) GO TO 90
    IF(1.LE.L1) GO TO 90
    L5=J-60
    L4=J-15
    NMS=J+25
    IF(L5.LT.NH3.AND.L5.GE.0) GO TO 91
    IF(L4.LT.NH3.AND.L4.GE.0) GO TO 91
    IF(NMS.LT.NH3.AND.NMS.GE.0) GO TO 91
    GO TO 90
91 VALUE=FLOAT(KHODE)*CHODE
    IF(K.EQ.2.OR.K.EQ.4.OR.K.EQ.6) IPNOW=1
    IF(IPNOW.EQ.1.AND.FREQ(1).LT..12.AND.ABS(C-D1(I)*DEGREE).LT
    1.17.) GO TO 90
    X=XL(2)-.0025
    Y=YL(2)-.0015
    Y1=YL(2)-.006
    INTO=INT(VALUE)
    IF(INTD.GE.1) THEN
        IF(INTD.EQ.1) CALL SYMBOL(X,Y,.0,.06,1,LZ)
        IF(INTD.EQ.5) CALL SYMBOL(X,Y1,.0,.06,1,LZ1)
        IF(INTD.EQ.10) CALL SYMBOL(X,Y,.0,.06,2,LZ)
        IF(INTD.EQ.50) CALL SYMBOL(X,Y1,.0,.06,2,LZ1)
        IF(INTD.EQ.100) CALL SYMBOL(X,Y,.0,.06,3,LZ)
        IF(INTD.EQ.500) CALL SYMBOL(X,Y1,.0,.06,3,LZ1)
    GO TO 400
    END IF
    NUM=INT(ABS(ALOG10(VALUE+1.2)))+3
    X=X-.001
    IF(IPNOW.EQ.1) Y=Y1
    CALL NUMBER(X,Y,.0,.06,NUM,VALUE)
    GO TO 400
90 CALL LINE(XL,YL,0,2)
400 XX(K,K1,1)=XX(K,K1,2)
    YY(K,K1,1)=YY(K,K1,2)
100 CONTINUE
7066 ESHA=ESDR
    DO 500 K=1,7
        KK=IXY(K)+1
        DO 500 K1=KK,14
            XX(K,K1,1)=1.
500 CONTINUE
7065 CONTINUE
    DO 600 K=1,7
        KK=IXY(K)
        DO 600 K1=1,KK
            XX(K,K1,1)=1.
600 CONTINUE
    INTO=2
    C=FREQ(L3)
    X=C*CCS(CC*RN)
    Y=C*SIN(CC*RN)
    CC=90.-CC
    SUM=100.*SQRT(SUM)/ALL
    ALL=ALL*FREQ2+WH4*RN*CHODE
    B=B*CHODE
    TEMP=90.-DII
    CALL SYMBOL(X,Y,.0,.05,1,LY10)
    CALL SYMBOL(.0,-.0045,TEMP,.09,25,LY13)
    CALL SYMBOL(.138,.095,0.,.18,8,LY6)
    IF(MODE.EQ.1) THEN
        CALL SYMBOL(.158,.07,.0,.18,18,LX1)
        CALL SYMBOL(.168,-.038,.0,.105,5,LX21)
        CALL SYMBOL(.172,-.04,.0,.08,4,LX22)
        CALL SYMBOL(.184,-.038,.0,.08,20,LY21)
        CALL NUMBER(.19,-.038,.0,.08,6,ALL)
    END IF
    IF(MODE.EQ.2) CALL SYMBOL(.158,.07,.0,.18,15,LY)
    IF(MODE.EQ.3) THEN
        CALL SYMBOL(.158,.07,.0,.18,17,LY2)
        CALL SYMBOL(.168,-.038,.0,.08,15,LX20)
        CALL NUMBER(.222,-.038,.0,.08,7,ALL)
    ELSE
        CALL SYMBOL(.165,.053,.0,.08,12,LY23)
        CALL SYMBOL(.167,.041,.0,.08,25,LY12)
        CALL NUMBER(.16,.041,.0,.077,4,4.3)
    END IF
7062 CALL AXISL(-.15,.15,0.,-.15,-.15,0.,.05,0,0,0,1.,1.,.1,0)
    CALL CIRCLE(0.,0.,90.,.15,.15,.1)
    CALL CIRCLE(0.,0.,98.,180.,.15,.15,.1)
    CALL CIRCLE(0.,0.,185.,261.,.15,.15,.1)
    CALL CIRCLE(0.,0.,290.,353.,.15,.15,.1)
    CALL SYMBOL(.159,-.006,.0,.2,1,LX3)
    CALL SYMBOL(-.168,-.006,.0,.2,1,LX4)
    CALL SYMBOL(-.0038,-.158,0.,.2,1,LY3)
    CALL SYMBOL(-.0038,-.171,0.,.2,1,LY4)

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CALL SYMBOL(.11,.12,0.,.18,11,LX5)
CALL NUMBER(.131,-.01,0.,.1,4,.15)
CALL NUMBER(-.157,-.01,0.,.1,4,.15)
CALL NUMBER(-.022,-.01,0.,.107,4,.00)
CALL NUMBER(-.024,-.145,0.,.1,4,.15)
CALL NUMBER(-.024,-.150,0.,.1,4,.15)
CALL SYMBOL(.0043,-.151,0.,.1,14,LX)
IF(NOTE.EQ.1) CALL SYMREL(.08,.158,.0.,.15,20,ST)
IF(NOTE.EQ.2) CALL SYMREL(.08,.158,.0.,.15,20,ST2)
IF(INTD.EQ.1) GO TO 6072
IF(JMODE.EQ.1) THEN
CALL SYMBOL(.168,-.055,.0.,.08,8,LXB)
ELSE
CALL SYMREL(.18,-.021,.0.,.11,2,LZ5)
CALL SYMREL(.184,-.023,.0.,.08,4,LX22)
CALL SYMREL(.201,-.021,.0.,.09,10,LX24)
CALL NUMBER(.205,-.021,.0.,.08,5,SUM)
CALL SYMBOL(.168,-.055,.0.,.08,10,LY19)
END IF
CALL SYMBOL(.19,-.065,.0.,.08,8,LX6)
CALL SYMREL(.1418,-.1058,.0.,.08,25,LX12)
CALL SYMREL(.1789,-.1166,.0.,.08,25,LX12)
CALL NUMBER(.1645,-.1166,.0.,.075,6,H1)
CALL SYMREL(.194,-.1276,.0.,.08,19,LX13)
CALL NUMBER(.1653,-.1276,.0.,.075,6,PII)
CALL NUMBER(.215,-.1276,.0.,.075,6,DII)
CALL SYMBOL(.154,-.1422,.0.,.05,1,LY10)
CALL SYMREL(.168,-.1426,.0.,.08,15,LY11)
CALL NUMBER(.219,-.1426,.0.,.08,7,B)
CALL NUMBER(.1653,-.1536,.0.,.075,6,C)
CALL NUMBER(.212,-.1536,.0.,.075,6,CC)
CALL SYMREL(.194,-.1536,.0.,.08,15,LZ3)
CALL SYMREL(.168,-.08,.0.,.08,16,LX2)
CALL SYMBOL(.18,-.0908,.0.,.08,15,A)
CALL TEKPAUS
CALL ERASE
PRINT 7069
7069 FORMAT(/"=====")
1 / /"====INPUT 1 TO DRAW AN SMOOTHED SPECTRUM,/"====OR
1 INPUT 2 TO DRAW A PROPOSED SPECTRUM,/"====OR INPUT 3 TO EXECUTE
1 THE PROGRAM IN OTHER MODE." /"====OR INPUT 4 TO TERMINATE THE
1 EXECUTION OF THIS PROGRAM.")
READ*, JMODE
GO TO (7068,7068,7071,7072) JMODE
7071 PRINT 5032
5032 FORMAT(/"=====")
1 / /"====INPUT MODE CODE,/"----MODE=1 RUN A HORIZONTAL
1 VELOCITY SPECTRUM (4.3' ABOVE SEA FLOOR)"/"----MODE=2 RUN A HORI
1 ZONTAL AMPLITUDE SPECTRUM (4.3' ABOVE SEA FLOOR)"/ "----MODE=3 WI
1 LL RUN A WAVE ENERGY SPECTRUM AT SEA SURFACE, /"----MODE=4 WILL
1 TERMINATE THE PROGRAM.")
READ*, MODE
IF(MODE.NE.4) GO TO 5048
STOP
7072 END
C
C *****
C ---PART X: COLLECTION OF SUBROUTINES AND BLOCK DATA---
C *****
SUBROUTINE TRANS(DEPTH,H1,MH)
COMMON /DATA10/ FREQ(720),T13(720),T23(720),UP(720),WK(720),FREQ1
1,FREQ2,ALFA,GA,PEAKF,LL,IPEAK,IPPEAK,IPEAK,K,A1,ICPEAK,L1
FREQ3=FREQ2/6.
C ---FREQ3(HZ) CIRCUMSCRIBES SHALLOW WATERWAVES---
WK(MH+1)=.1
H2=H1+3.4167
C ---3.4167(FT) IS THE DISTANCE BETWEEN CURRENT-METER AND PRESSURE GAUGE---
DD 130 J=MH,1,-1
FREQ(I)=FREQ(I)*FREQ1
IF(FREQ(I).GT.FREQ2) THEN
WK(I)=FREQ(I)*FREQ(I)+1.2270286
C ---1.2270286=(CPI2)**2/32.174---
WP(I)=.0058855*COSH(WK(I)*H2)/COSH(WK(I)*H1)/FREQ(I)
C ---.0058855=(UNIT WEIGHT OF SEA WATER)/CPI2*(64./12**3 PSI)/CPI2---
ELSE IF(FREQ(I).LE.FREQ3) THEN
WK(I)=FREQ(I)*SQRT(1.2270286/DEPTH)
WP(I)=.0058855*WK(I)*DEPTH/FREQ(I)
ELSE
C ---CONSIDER THE INTERMEDIATE WATER CONDITION---
XX=WK(I+1)*DEPTH
WH=FREQ(I)*FREQ(I)*DEPTH+1.2270286
TANHH=TANH(XX)
DO 170 J=1,10
DH=(WH-XX*TANHH)/(TANHH*XX/COSH(XX)**2)
XX=DH*XX
TANHH=TANH(XX)
IF(ABS(DH/XX).LT..005) GO TO 150

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170 CONTINUE
150 UK(I)=XX/DEPTH
    UK(I)=XX/DEPTH
    UF(I)=.0058855*TANH(COSH(UK(I)*H2)/COSH(UK(I)*H1)/FREQ(I)
    END IF
130 CONTINUE
    RETURN
    END

C
    SUBROUTINE SMOOTH(NN,S2,S1,MH,ICPEAK,MOD)
    DIMENSION S1(MH),S2(MH)
C ---USING BARTLETT WINDOW: I=2H/3, BASEWIDTH=2/H (HZ)-----
C   N(SEC)   N(SEC)   D.O.F.   80% C.I.
C   256      128      6         (.58)(2.6)
C   512      128      12        (.65)(1.8)
C   1024     128      24        (.72)(1.5)
    IF(NN.GE.1024) MOD=4
    S2(1)=(S1(1)+S1(2))/2.
    S2(MH)=(S1(MH-1)+S1(MH))/2.
    GO TO (5,20,40,70) MOD
5  S2(2)=(S1(1)+S1(3))/3.25+S1(2)/2.6
    S2(3)=(S1(2)+S1(4))/3.25+S1(3)/2.6
    NS=MH-3
    IF(NN.EQ.512) THEN
    DO 10 I=4,NS
10  S2(I)=(S1(I-3)+S1(I+3))/36.+(S1(I-2)+S1(I+2))/9.+(S1(I-1)+S1(I+1))
    /4.5+S1(I)/3.6
    S2(NS+1)=(S1(NS)+S1(NS+2))/3.25+S1(NS+1)/2.6
    S2(MH-1)=(S1(MH-2)+S1(MH))/3.25+S1(MH-1)/2.6
    ELSE
    NS=MH-1
    DO 11 I=2,NS
11  S2(I)=(S1(I-1)+S1(I+1))/4.5+S1(I)/1.8
    END IF
    RETURN
20  NS=MH-1
    DO 30 I=2,NS
30  S2(I)=S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2
    RETURN
40  NS=ICPEAK-1
    DO 50 I=2,NS
50  S2(I)=S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2
    NS=ICPEAK+1
    II=MH-1
    DO 60 I=NS,II
60  S2(I)=S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2
    S2(ICPEAK)=S1(ICPEAK)
    RETURN
70  S2(2)=(S1(1)+S1(3))/3.05+S1(2)/2.9
    S2(3)=(S1(1)+S1(5))/5.625+(S1(2)+S1(4))/4.737+S1(3)/4.5
    S2(4)=(S1(2)+S1(6))/5.625+(S1(3)+S1(5))/4.737+S1(4)/4.5
    S2(5)=(S1(3)+S1(7))/5.625+(S1(4)+S1(6))/4.737+S1(5)/4.5
    S2(6)=(S1(4)+S1(8))/5.625+(S1(5)+S1(7))/4.737+S1(6)/4.5
    NS=MH-6
    DO 80 I=7,NS
80  S2(I)=(S1(I-6)+S1(I+6))*0.125+(S1(I-5)+S1(I+5))*0.306+
    1(S1(I-4)+S1(I+4))*0.562+(S1(I-3)+S1(I+3))*0.853+
    1(S1(I-2)+S1(I+2))*1.123+(S1(I-1)+S1(I+1))*1.318+S1(I)*1.1388
    S2(NS+1)=(S1(NS-1)+S1(NS+3))/5.625+(S1(NS)+S1(NS+2))/4.737
    +S1(NS+1)/4.5
    S2(NS+2)=(S1(NS)+S1(NS+4))/5.625+(S1(NS+1)+S1(NS+3))/4.737
    +S1(NS+2)/4.5
    S2(NS+3)=(S1(NS+1)+S1(NS+5))/5.625+(S1(NS+2)+S1(NS+4))/4.737
    +S1(NS+3)/4.5
    S2(NS+4)=(S1(NS+2)+S1(MH))/5.625+(S1(NS+3)+S1(NS+5))/4.737
    +S1(NS+4)/4.5
    S2(NS+5)=(S1(NS+4)+S1(MH))/3.05+S1(NS+5)/2.9
    RETURN
    END

C
    SUBROUTINE LSM(AIH,X,MAX)
    COMMON /DATA10/ FREQ(720),T13(720),T23(720),UF(720),UK(720),FREQ1
    1,FREQ2,ALFA,GA,PEAKF,LL,IPEAK,IDPEAK,IPEAK,K,A1,ICPEAK,L1
    Z1=.0
    Z2=.0
    IA=LL
    IB=K
    IF(MAX.EQ.1) IB=IPEAK
    IF(MAX.EQ.2) IA=IPEAK
    DO 10 I=IA,IB
    BATA=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/X)**2/26.))**13
    TEMP=GA**BATA
    C=BATA*TEMP*(FREQ(I)-PEAKF)**2
    Z1=Z1+T13(I)*C+TEMP
10  Z2=Z2+T23(I)*C
    AIH=ALFA*Z1-Z2
    RETURN
    END

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C
SUBROUTINE LST(AIN,X,M)
DIMENSION P(720)
COMMON /DATA10/ FREQ(720),T13(720),T23(720),UP(720),UK(720),FREQ1
1,FREQ2,ALFA,GA,PEAKF,LL,IPEAK,IDPEAK,IPEAK,K,A1,ICPEAK,L1
Z1=0.
Z2=0.
Z3=0.
Z4=0.
IF(IPEAK.EQ.0.OR.N.EQ.1) THEN
IA=ICPEAK
IR=IDPEAK
ELSE
IA=1
IR=ICPEAK
END IF
DO 10 I=1A,IR
IF(IPEAK.EQ.0) THEN
IF(N.EQ.1) P(I)=UP(I)
IF(N.EQ.2) P(I)=T13(I)
IF(P(I).GT.P(ICPEAK)) P(I)=P(ICPEAK)
ELSE IF(IPEAK.EQ.1) THEN
P(I)=UP(I)
IF(N.EQ.1.AND.P(I).GT.P(ICPEAK)) P(I)=P(ICPEAK)
ELSE
P(I)=T13(I)
IF(N.EQ.1.AND.P(I).GT.P(ICPEAK)) P(I)=P(ICPEAK)
END IF
B=FREQ(I)*X
C=B*ALOG(FREQ(I))
Z1=Z1+P(I)*B
Z2=Z2+P(I)*C
Z3=Z3+B*B
10 Z4=Z4+B*C
A1=Z1/Z3
AIN=A1-Z2/Z4
RETURN
END
EOI ENCOUNTERED.
/

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      READ(6,5050)M(1),M(2),HT,DEPTH,VI,DI,PI,S,SV,(P(I),PR(I),V(I)
1,VR(I),D(I),DR(I),I=1,NM1)
5050 FORMAT(A10,A5,2F9.4/(10E12.6))
      AA=S
      IF(DEPTH.LT.140.) EDEP=2.
      IF(EDEP.GT.1.) ADEP=.01
      NM2=NM/3.5
      NM3=NM2-3
      NM4=NM/2.5
      NM5=NM4+1
      FREQ1=1./FLOAT(N)
      PII=SQRT(VI*VI+DI*DI)
      DII=90.-ATAN2(DI,VI)*DEGREE
      IF(DII.LT..0) DII=DII+360.
C ---PII & DII ARE THE MAGNITUDE AND DIRECTION OF CURRENT AT H1(FT) ABOVE SEA FLOOR---
C *****
C ---PART IV: CALCULATE ONE DIMENSIONAL SPECTRUM---
C *****
      L1=N/32
      IF(L1.LT.4) L1=4
      FREQ2=SQRT(2.56/DEPTH)
C ---FREQUENCY FREQ2 CIRCUMSCRIBES DEEP WATER WAVES, WAVE LENGTH<2*DEPTH---
      L3=FREQ2/FREQ1
      IDEEP=L3
      ENH=FLOAT(N)/288.
C ---ENH=FLOAT(N)/144./2. : USED TO COMPUTE ENERGY IN POSITIVE FREQUENCY---
C ---ALSO THE UNIT CHANGES FROM IN*IN TO FT*FT---
      CALL TRANS(DEPTH,H1,NM1)
C
      DO 5001 I=1,NM1
      S1(I)=P(I)/UP(I)
      S2(I)=PR(I)/UP(I)
C ---UP(I) : TRANSFER PRESSURE DATA(P(SI)) @ H2' TO VELOCITY DATA(IN/S) @ H1'---
      R=(V(I)+S2(I)-VR(I))*S1(I)**2+(D(I)+S2(I)-DR(I))*S1(I)**2
      C=(V(I)+DR(I)-D(I)+VR(I))*S1(I)**2
      RR=V(I)+V(I)+D(I)+D(I)
      CC=VR(I)+VR(I)+DR(I)+DR(I)
      VALUE=ABS((R-C)/C)
      IF(VALUE.LT..07) GO TO 5010
      TEMP=(RR-R-S1(I))*S1(I)*C/(R-C)
      VARY=(CC-R-S2(I))*S2(I)*C/(R-C)
5010 T23(I)=.0
      IF(VALUE.LT..05.OR.TEMP.LT..0.OR.VARY.LT..0) T23(I)=5.
      IF(T23(I).LE.1.) THEN
      TA(I)=(S1(I)+SQRT(TEMP))/2.
      TR(I)=S1(I)-1*TA(I)
      T13(I)=(S2(I)+SQRT(VARY))/2.
      T33(I)=S2(I)-1*T13(I)
      D1(I)=(TR(I)+TR(I)+T33(I)+T33(I))*ENH
      D2(I)=(T13(I)+T13(I)+TA(I)+TA(I))*ENH
      ELSE
      TA(I)=ATAN2(D(I),V(I))
      TR(I)=ATAN2(DR(I),VR(I))
      IF(P(I).LT..0) TA(I)=TA(I)+CPI
      IF(PR(I).LT..0) TR(I)=TR(I)+CPI
      D1(I)=ABS(S1(I))*SQRT(RR)*ENH
      D2(I)=ABS(S2(I))*SQRT(CC)*ENH
      END IF
5001 RECORD(I)=D1(I)+D2(I)
C ---RECORD(I) IS RAW DATA OF 1-D HORI. VELOCITY SPECTRUM @ H1(FT) ABOVE SEA FLOOR---
      CALL SMOOTH(N,UP,RECORD,NHS,0,1)
      DO 5047 I=1,NHS
      T12(I)=UP(I)/RECORD(I)
      IF(I.LE.L1.OR.I.GE.L3) GO TO 5027
      IF(UP(I).LE.VLARGE) GO TO 5027
      VLARGE=UP(I)
      IPEAK=I
5027 CONTINUE
      IF(T23(I).GT.1.) THEN
      TEMP=D1(I)+T12(I)
      VARY=D2(I)+T12(I)
      GO TO 5005
      END IF
      DC=TA(I)
      CC=TR(I)
      DS=T13(I)
      CS=T33(I)
      TEMP=D1(I)+T12(I)
      VARY=D2(I)+T12(I)
C
      MOD=0
      MODE=0
      JMODE=0
      R=DS+CC-DC+CS
      IF(R.EQ..0) MOD=1

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IF(MOD,EO,1) GO TO 5024
A1=(DS*D(I)-DC*DR(I))/R
R1=(DS*V(I)-DC*VR(I))/R
A2=(CC*DR(I)-CS*D(I))/R
R2=(CC*VR(I)-CS*V(I))/R
IF(ABS(A1).GT.1..OR.ABS(A2).GT.1..OR.ABS(R1).GT.1..OR.ABS(
R2).GT.1.) MODE=1
IF(MOD,EO,1) GO TO 5024
TA(I)=ATAN2(A1,R1)
TB(I)=ATAN2(A2,R2)
C=CC*COS(TA(I))+DC*COS(TB(I))
5024 DC=CC
CC=S1(I)-DC
R=DS*CC-DC*CS
IF(R,EO,0) MODE=1
IF(MODE,EO,1.AND.MOD,EO,1) GO TO 5023
IF(MODE,EO,1) GO TO 5005
A1=(DS*D(I)-DC*DR(I))/R
R1=(DS*V(I)-DC*VR(I))/R
A2=(CC*DR(I)-CS*D(I))/R
R2=(CC*VR(I)-CS*V(I))/R
IF(ABS(A1).GT.1..OR.ABS(A2).GT.1..OR.ABS(R1).GT.1..OR.ABS(
R2).GT.1.) MODE=1
IF(MODE,EO,1.AND.MOD,EO,1) GO TO 5023
IF(MODE,EO,1) GO TO 5005
D1(I)=ATAN2(A1,R1)
D2(I)=ATAN2(A2,R2)
IF(MOD,EO,1) GO TO 5000
VALUE=CC*COS(D1(I))+DC*COS(D2(I))
IF(ABS(C-V(I)).LE.ABS(VALUE-V(I))) GO TO 5005
5000 TA(I)=D1(I)
TB(I)=D2(I)
TEMP=(CC*CC+CS*CS)*EMH*T12(I)
VARY=(DS*DS+DC*DC)*EMH*T12(I)
5005 P(I)=TEMP*COS(TA(I))+VARY*COS(TB(I))
PR(I)=TEMP*SIN(TA(I))+VARY*SIN(TB(I))
T33(I)=TEMP*COS(2.*TA(I))+VARY*COS(2.*TB(I))
T13(I)=TEMP*SIN(2.*TA(I))+VARY*SIN(2.*TB(I))
GO TO 5047
5023 IF(I,EO,1) THEN
P(I)=.00001
PR(I)=.00001
T33(I)=.00001
T13(I)=.00001
UP(I)=.00001
GO TO 5047
END IF
P(I)=P(I-1)
PR(I)=PR(I-1)
T33(I)=T33(I-1)
T13(I)=T13(I-1)
UP(I)=UP(I-1)
5047 CONTINUE
IF(L3.GT,NH2) L3=NH2
C WRITE(*,7) (RECORD(I),I=1,30)
C 7 FORMAT(1X/'-----OUTPUT VELOCITY SPECTRUM AT H' ABOVE SEA FLOOR,
C 1'/(9F8.3))
C *****
C ---PART V: CALCULATE SPREADING PARAMETER AND DIRECTIONAL SPREADING---
C *****
PRINT 5015
5015 FORMAT(1X/'====INPUT 3 WILL AVERAGE THREE FREQUENCY DATA./
1'====OR INPUT 4 WILL AVERAGE FOUR FREQUENCY DATA./
1'====OR INPUT 5 WILL AVERAGE FIVE FREQUENCY DATA./
1'-----DOUBLE THE VALUE OF INPUT WILL CALCULATE RESI-FIT CURVE"/
1' OF SPREADING PARAMETER IN EITHER SIDE OF PEAK POINT. ')
READ*,INT0
IF(INT0.GE,6) IFMOD=1
IF(INT0.GE,6) INTO=INT0/2
A1=P(1)+P(2)
R1=P(1)+PR(2)
A2=T33(1)+T33(2)
R2=T13(1)+T13(2)
B=UP(1)+UP(2)
D1(I)=SQRT(A1)*A1+R1*B1//R
TA(I)=ATAN2(B1,A1)
TB(I)=ATAN2(B2,A2)/2.
IF(ABS(TB(I)-TA(I)).LT,1.75) GO TO 5999
IF(B(I).LT,|A(I)|) B(I)=TR(I)+CPI
IF(ABS(TR(I)-A(I)).GT,1.75) TR(I)=TR(I)-CPI
5999 D2(I)=A2/B/COS(TR(I)+2.)
DO 5054 I=2,NH6
A1=P(I)+P(I+1)+P(I-1)
R1=PR(I)+PR(I+1)+PR(I-1)

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A2=T33(I)+T33(I+1)+T33(I-1)
B2=T13(I)+T13(I+1)+T13(I-1)
R=UP(I)+UP(I+1)+UP(I-1)
IF(INT0.EQ.4.AND.I.LT.NH6) THEN
A1=A1+P(I+2)
B1=B1+P(I+2)
A2=A2+T33(I+2)
B2=B2+T13(I+2)
R=R+UP(I+2)
ELSE IF(INT0.EQ.5.AND.I.LL.NH6.AND.I.GT.J) THEN
A1=A1+P(I-2)+P(I+2)
B1=B1+P(I-2)+P(I+2)
A2=A2+T33(I-2)+T33(I+2)
B2=B2+T13(I-2)+T13(I+2)
R=R+UP(I-2)+UP(I+2)
END IF
H1(I)=SQRT(A1+A1+B1+B1)/R
IA(I)=ATAN2(B1,A1)
TB(I)=ATAN2(B2,A2)/2.
IF(ABS(TB(I)-IA(I)).LT.1.75) GO TO 5054
IF(TB(I).LT.IA(I)) TB(I)=TB(I)+CP1
IF(ABS(TB(I)-IA(I)).GT.1.75) TB(I)=TB(I)-CP1
5054 D2(I)=A2/R/COS(TB(I)+2.)
C ---D1,IA ARE SINGLE-ANGLE MODE. D2,TB ARE DOUBLE-ANGLE MODE---
DO 5017 I=NH2,NH6
IF(D1(I).GT..999) D1(I)=.999
5017 IF(D2(I).GT..999) D2(I)=.999
KSIMU=NH2
PRINT 900
900 FORMAT(/"====INPUT 1 WILL OUTPUT DATA FOR SIMULATION USE LATER,
"/"====OR INPUT 0 WILL NOT OUTPUT DATA FOR SIMULATION USE.")
READ*,R
IF(K.EQ.1) KSIMU=NH6
DO 5051 I=1,KSIMU
IF(D1(I).GT..999) D1(I)=.999
C=1.-D1(I)
P(I)=D1(I)/C
C ---P(I) IS THE SPREADING PARAMETER CALCULATED FROM SINGLE-ANGLE MODE---
IF(D2(I).GT..999) D2(I)=.999
C=1.-D2(I)
R=1.5*D2(I)+.5/C
5051 UP(I)=R+SQRT(R+R+2.*D2(I)/C)
C ---UP(I) IS THE SPREADING PARAMETER CALCULATED FROM DOUBLE-ANGLE MODE---
C
L2=IPEAK-L1/2
IF(L3-IPEAK.LT.L1) L3=IPEAK+L1+L1/2
IF(L3.GT.NH2) L3=NH2
IDPEAK=L3-L1/2
VARY=P(IDPEAK)
DO 5049 I=IDPEAK,L3
IF(P(I).GE.VARY) GO TO 5049
IDPEAK=I
VARY=P(I)
5049 CONTINUE
C
TEMP=FREQ(IDPEAK)
LL=IPEAK+L1/3
ICPEAK=L2
C ---CRITICAL FREQUENCY INDEX INDICATES HIGHEST SPREADING PARAMETER---
VLARGE=P(ICPEAK)
DO 5006 I=ICPEAK,LL
IF(P(I).LE.VLARGE) GO TO 5006
ICPEAK=I
VLARGE=P(I)
5006 CONTINUE
PEAK=FREQ(ICPEAK)
C
CALL PLOTTYPE(1)
CALL BAUD(1200)
CALL SIZE(7.5,5.625)
C ---THE FOLLOWING 80 LINES CAN BE DELETED IF NOT NEEDED---
C
PRINT 5060
5060 FORMAT(/"====INPUT CODE NUMBER TO OUTPUT CORRESPONDING FIGURES,
"/"----SPREADING PARAMETER & PROPAGATION DIRECTION & FREQUENCY,"
"/"----CODE=1 WILL SHOW THE DETAIL COMPUTATION THROUGH FIGURES,"
"/"----CODE=2 WILL SHOW THE OPTIMAL SOLUTION ONLY.")
READ*,JMODE
IF(JMODE.EQ.2) GO TO 5061
CALL ERASE
CALL SCALE(25.,4.,1.1,1.,0.,-.1)
CALL AXISL(0.,.2,.0,1.,.0,.05,.1,4,0,1,2,1.,1.,1,0)
CALL VECTORS

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CALL PLOT(.0,1.,0,0)
CALL PLOT(.2,1.,1,0)
CALL PLOT(.2,0.,1,0)
CALL SYMBOL(.06,-.14,.0,.15,15,LX)
CALL SYMBOL(-.025,.33,90.,.16,9,LX17)
CALL SYMBOL(-.03,-.24,.0,.1,65,LY17)
CALL POINTS
CALL PLOT(.0342,-.23,1,17)
CALL PLOT(.1412,-.23,1,3)
C ---DRAW D1,D2-FREQUENCY FIGURES---
CALL LINE(FREQ,D1,17,NH6)
CALL LINE(FREQ,D2,3,NH6)
CALL TEKPAUS
CALL ERASE
CALL SCALE(4.4,4.,1.8,.9,0.,-.1)
CALL AXISL(.0,1.,.0,0,1.,.0,1.,.1,0,0,2,2,1.,1.,.1,0)
C ---DRAW D1-D2 PICTURE AS C1-C2 RELATION---
DO 5044 I=L2,L3
  J=I-L2+1
  T12(J)=D1(I)
5044 T33(J)=D2(I)
CALL POINTS
CALL LINE(T12,T33,1,J)
CALL LINE(XL,YL,0,10)
CALL NUMBER(.0,1.02,.0,.085,3,.0)
CALL NUMBER(.333,1.02,.0,.085,3,.5)
CALL NUMBER(.5,1.02,.0,.085,3,1.)
CALL NUMBER(.667,1.02,.0,.085,3,2.)
CALL NUMBER(.78,1.02,.0,.085,3,4.)
CALL SYMBOL(.989,1.02,.0,.085,2,LZ)
CALL SYMBOL(.98,1.02,.0,.085,2,LZ1)
CALL SYMBOL(.2,1.04,.0,.12,1,LX6)
DO 5045 I=1,51
  T12(I)=.02*FLOAT(I-1)
5045 T33(I)=6./(2.-T12(I))-3.-2.*T12(I)
CALL VECTORS
CALL LINE(T12,T33,0,51)
CALL PLOT(1.,.0,1,0)
CALL PLOT(1.,1.,0,0)
CALL PLOT(0.,1.,1,0)
CALL SYMBOL(-.1,-.2,.0,.12,9,LY17)
CALL SYMBOL(.7,-.12,.0,.12,2,LX17)
CALL SYMBOL(-.22,.71,.0,.12,2,LY18)
CALL TEKPAUS
CALL ERASE
CALL SCALE(25.,.63662,1.1,1.5,0.,-CPI)
CALL AXISL(.0,.2,0.,-CPI,CPI,-CPI,.05,CPI,4,3,1,0,1.,1.,.1,0)
CALL PLOT(.0,CPI,0,0)
CALL PLOT(.2,CPI,1,0)
CALL PLOT(.2,-CPI,1,0)
CALL SYMBOL(.05,-4.1,.0,.15,15,LX)
CALL SYMBOL(-.033,-2.4,90.,.15,11,LX5)
CALL SYMBOL(-.028,.65,90.,.15,9,LY1)
CALL NUMBER(-.028,-3.1,.0,.1,6,-180.0)
CALL NUMBER(-.025,-1.57,.0,.1,5,-90.0)
CALL NUMBER(-.019,.0,.0,.11,3,.0)
CALL NUMBER(-.025,1.55,.0,.1,5,90.0)
CALL NUMBER(-.029,3.10,.0,.1,6,180.0)
CALL SYMBOL(-.03,-4.8,.0,.1,65,LY17)
CALL POINTS
CALL PLOT(.0342,-4.7,1,28)
CALL PLOT(.1412,-4.7,1,20)
C ---DRAW TA,TB DATA SHOWING WAVE PROPAGATION DIRECTION---
CALL LINE(FREQ,TA,28,NH6)
CALL LINE(FREQ,TB,20,NH6)
CALL TEKPAUS
5061 CONTINUE
C
C
MOD=1
5055 X1=-5.
      X2=-.1
      IF(MOD.EQ.2.AND.IPNOW.EQ.1) X1=.1
      IF(MOD.EQ.2.AND.IPNOW.EQ.1) X2=20.
      CALL LST(FF2,X2,MOD)
5063 CALL LST(FF1,X1,MOD)
      XM=100000.*FF1*FF2
      IF(XM.GT..0) THEN
        X1=X1-3.
        IF(MOD.EQ.2.AND.IPNOW.EQ.1.AND.X1.GT.-7) GO TO 5063
        IF(MOD.EQ.2.AND.IPNOW.EQ.1) GO TO 5080
        IF(X1.GT.-40.) GO TO 5063
5080 X=.0

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A1=.0
GO TO 5056
END IF
DO 5057 I=1,22
Y=(Y1+X2)/2.
CALL LST(FF,X,MOD)
YN=100000.*FF*FF1
IF(YN.LE..0) THEN
X2=Y
FF2=FF
ELSE
Y1=X
FF1=FF
END IF
IF(ABS(FF)-1.E-10) 5056,5056,5057
5057 CONTINUE
5056 IF(MOD.GE.2) GO TO 5018
MOD=2
CALL ERASE
C *****
C ---PART VI: DRAWING APPLIED SPREADING PARAMETER IN LOG. SCALE---
C *****
CALL SMOOTH(N,S1,P,KSTIMU,ICPEAK,3)
CALL SCALE(25.,1.3,1.1,1.06,.0,-1.1)
CALL AXISL(.0,.2,.0,-1.,2.,-1.,.05,1.,4,0,1,0,1.,1.,1,0)
DO 6049 I=1,NM2
IF(S1(I).LT..1) D(I)=-1.
IF(P(I).LT..1) T12(I)=-1.
IF(UP(I).LT..1) D(I)=-1.
IF(S1(I).GE..1) VR(I)=ALOG10(S1(I))
IF(UP(I).GE..1) D(I)=ALOG10(UP(I))
6049 IF(P(I).GE..1) T12(I)=ALOG10(P(I))
CALL POINTS
IF(IPMOD.EQ.0) THEN
CALL PLOT(.168,.53,1,27)
CALL PLOT(.168,.31,1,19)
ELSE
CALL PLOT(.168,.75,1,27)
CALL SYMBL(.16,.5,.0,.09,3,LZ6)
CALL SYMBL(.16,.28,.0,.09,3,LZ7)
END IF
CALL POINTS
CALL PLOT(.009,-1.64,1,27)
CALL PLOT(.098,-1.64,1,19)
CALL LINE(FREQ,T12,27,NM2)
CALL LINE(FREQ,0,19,NM2)
CALL DASHES
CALL LINE(FREQ,0,NM2)
CALL VECTORS
IF(X.EQ..0) INT0=10
IF(INT0.NE.10) THEN
DO 6071 I=KSTIMU,1,-1
IF(I.GE.ICPEAK) S2(I)=A1*FREQ(I)*X
6071 IF(I.LT.ICPEAK) S2(I)=.9*S2(ICPEAK)
DO 6066 J=ICPEAK+1
D2(J)=FREQ(I)
IF(S2(I).LT..1) D1(J)=-1.
6066 IF(S2(I).GE..1) D1(J)=ALOG10(S2(I))
CALL LINE(D2,D1,0,J)
END IF
XL(1)=.17
XL(2)=.183
YL(1)=1.19
YL(2)=1.19
CALL SYMBOL(.05,-1.4,.0,.15,15,LY)
CALL SYMBOL(-.028,-7.90,.15,20,LY1)
CALL SYMBL(-.038,-1.67,.0,.1,6,LY17)
CALL NUMBER(-.024,-1.03,.0,.1,6,1000)
CALL NUMBER(-.024,-.03,.0,.1,6,1000)
CALL NUMBER(-.024,.97,.0,.1,6,10.00)
CALL NUMBER(-.024,1.97,.0,.1,6,100.0)
CALL SYMBOL(.12,2.,.0,.15,20,6E)
CALL SYMBL(.173,1.64,.0,.107,19,LY22)
CALL NUMBER(.185,1.64,.0,.09,6,PEAKF)
CALL NUMBER(.215,1.64,.0,.09,5,VLARGE)
CALL SYMBL(.173,1.4,.0,.102,19,LY25)
CALL NUMBER(.185,1.4,.0,.09,6,TEMP)
CALL NUMBER(.215,1.4,.0,.09,5,VART)
CALL SYMBOL(.191,1.16,.0,.09,10,LY19)
CALL SYMBL(.2,.96,.0,.09,9,LT1)
CALL SYMBL(.173,.72,.0,.09,11,LY18)
CALL SYMBL(.173,.5,.0,.09,14,LX19)

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      CALL NUMBER(.179,.5,.0,.09,8,A1)
      CALL NUMBER(.226,.5,.0,.09,6,X)
      CALL SYMBOL(.17,.03,.0,.104,3,LX10)
      CALL SYMBOL(.191,.03,.0,.09,8,LX8)
      CALL SYMBOL(.2,-.17,.0,.09,9,LY1)
      CALL SYMBOL(.173,-.37,.0,.09,16,LX2)
      CALL SYMBOL(.187,-.57,.0,.09,15,M)
      IF(IPNDW.EQ.1) IPEAK=1
C ---THIS STEP IS USED IN SUBROUTINE LST---
      GO TO 5055
5018 CALL SYMBOL(.173,.28,.0,.09,14,LX19)
      CALL NUMBER(.179,.28,.0,.09,8,A1)
      CALL NUMBER(.226,.28,.0,.09,6,X)
      IF(IPNDW.EQ.1.AND.X.NE..0) THEN
        I=ICPEAK+1
        DO 5081 I=1,I
5081 S2(I)=A1*FREQ(I)**X
        DO 5082 I=1,I
          IF(S2(I).LT..1) D1(I)=-1.
5082 IF(S2(I).GE..1) D1(I)=ALOG10(S2(I))
          CALL LINE(FREQ,D1,0,I)
          GO TO 5083
        END IF
        IF(INTO.EQ.10.AND.X.NE..0) THEN
          DO 6051 I=KSIMU,1,-1
          IF(I.GE.ICPEAK) S2(I)=A1*FREQ(I)**X
6051 IF(I.LT.ICPEAK) S2(I)=.9*S2(ICPEAK)
          DO 6052 I=ICPEAK,IPPEAK
            J=I-ICPEAK+1
            D2(J)=FREQ(I)
            IF(S2(I).LT..1) D1(J)=-1.
6052 IF(S2(I).GE..1) D1(J)=ALOG10(S2(I))
            CALL LINE(D2,D1,0,J)
          END IF
5083 CALL LINE(XL,YL,0,2)
          CALL TEKPAUS
          CALL ERASE
          IF(INTO.EQ.10.AND.X.EQ..0) THEN
            DO 6053 I=KSIMU,1,-1
            IF(I.GE.ICPEAK) S2(I)=-.00003/FREQ(I)**5
6053 IF(I.LT.ICPEAK) S2(I)=-.9*S2(ICPEAK)
          END IF
C *****
C *---PART VII: DRAWING APPLIED DIRECTIONAL SPREADING IN POLAR COORDINATES--- *
C *****
      PRINT 303
303 FORMAT(/"====INPUT 1 WILL SET PROPOSED DIRECTION AS SMOOTH DIRECT
      ION,"/"====OR INPUT 2 TO SET MAIN DIRECTION IN PROPOSED SPECTRUM,
      1"/"====OR INPUT 3 TO SET BEST-FIT-CURVE IN PROPOSED SPECTRUM.")
      READ*,JUMP
      CALL ERASE
      DO 6067 I=L1,NH2
        ESDA=ESDA+RECORD(I)
6067 DMEAN=DMEAN+TA(I)*RECORD(I)
        DMEAN=DMEAN/ESDA
        IF(JUMP.NE.2) THEN
          CALL SCALE(17.4,16.,.42,.42,.0,.0)
          CALL ORIGIN(3.03,2.83)
          CALL POINTS
          END IF
        T12(I)=DMEAN
        DO 6065 I=2,NH2
          IF(JUMP.NE.2) THEN
            X=FREQ(I)*COS(TA(I))
            Y=FREQ(I)*SIN(TA(I))
            CALL PLOT(X,Y,1,1)
          END IF
          T12(I)=TA(I)
6065 IF(1.GT.L2.AND.ABS(T12(I)-T12(I-1)).GE..9) T12(I)=T12(I-1)
          S=.7+T12(I)*.3
          DMEAN=DDMEAN+DEGREE
          CALL SMOOTH(N,D1,T12,NH2,0,2)
C ---WHERE D1(I) IS A SMOOTHED DIRECTIONAL SPREADING---
          IF(JUMP.EQ.2) GO TO 304
          IF(JUMP.EQ.3) THEN
            I1=IDEEP
            IF(I1.GT.NH3) I1=NH3
            CALL SMOOTH(N,UP,RECORD,I1,0,2)
            DO 301 J=L1,I1
              A(1,J)=A(1,J)+UP(I)
              BB=UP(I)*FREQ(I)
              A(1,2)=A(1,2)+BB
              BB=BB*FREQ(I)
              A(1,3)=A(1,3)+BB

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RR=RR+FREQ(I)
A(1,4)=A(1,4)+RR
RR=RR+FREQ(I)
A(2,4)=A(2,4)+RR
RR=RR+FREQ(I)
A(3,4)=A(3,4)+RR
A(4,4)=A(4,4)+RR+FREQ(I)
CC=UP(I)*(D1(I)-DDMEAN)
A(1,5)=A(1,5)+CC
CC=CC+FREQ(I)
A(2,5)=A(2,5)+CC
CC=CC+FREQ(I)
A(3,5)=A(3,5)+CC
301 A(4,5)=A(4,5)+CC+FREQ(I)
X12=A(1,1)
A(2,1)=A(1,2)
A(2,2)=A(1,3)
A(2,3)=A(1,4)
A(3,1)=A(1,3)
A(3,2)=A(2,3)
A(3,3)=A(2,4)
A(4,1)=A(1,4)
A(4,2)=A(2,4)
A(4,3)=A(3,4)
DO 405 I=1,4
DO 405 J=1,5
405 A(I,J)=A(I,J)/A(I,1)
DET=1.
DO 411 K=1,4
BIG=ABS(A(K,K))
KKK=K
DO 410 KK=K,A
IF (BIG-ABS(A(KK,K))) 409,410,410
409 BIG=ABS(A(KK,K))
KKK=K
410 CONTINUE
DO 408 JJ=K,5
ROXX=A(K, JJ)
A(K, JJ)=A(KKK, JJ)
408 A(KKK, JJ)=ROXX
DET=DET*A(K,K)
IF (DET=.0) 413,412,413
412 PRINT*, 'DET=.0'
STOP
413 K1=K+1
DO 414 J=K1,5
A(K, J)=A(K, J)/A(K, K)
IF (K=N.EQ.0) GO TO 411
DO 415 I=K1,4
415 A(I, J)=A(I, J)-A(I, K)*A(K, J)
414 CONTINUE
411 CONTINUE
XL(4)=A(4,5)
K=4
417 SIGNM=.0
DO 416 J=K,4
416 SIGNM=SIGNM+A(K-1, J)*XL(J)
XL(K-1)=A(K-1,5)-SIGNM
K=K-1
IF (K.EQ.1) GO TO 418
GO TO 417
418 Z1=XL(1)+DDMEAN
Z2=XL(2)
Z3=XL(3)
Z4=XL(4)
DO 302 I=1, NH2
302 D2(I)=Z1+Z2*FREQ(I)+Z3*FREQ(I)*FREQ(I)+Z4*FREQ(I)**3
C ---D2(I) IS A BEST-FIT-CURVE OF PROPOSED DIRECTION---
Z1=90.-Z1*DEGREE
Z2=-Z2*DEGREE
Z3=-Z3*DEGREE
Z4=-Z4*DEGREE
RR=.0
CC=.0
DO 305 I=L1, I1
J=I-1+1
D(I)=FREQ(I)*COS(D2(I))
T3(I)=FREQ(I)*SIN(D2(I))
CC=CC+(D1(I)-DDMEAN)**2*UP(I)
305 RR=RR+(D1(I)-D2(I))**2*UP(I)
RR=SQRT(RR/X12)*DEGREE
CC=SQRT(CC/X12)*DEGREE
XL(1)=-.151
XL(2)=-.168

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YL(1)=.078
YL(2)=.078
CALL VECTORS
CALL LINE(D,T33,0,J)
CALL LINE(XL,YL,0,2)
CALL SYMBEL(.173,.075,.0,.105,6,LX30)
CALL NUMBER(.187,.075,.0,.08,7,21)
CALL SYMBOL(.2145,.065,.0,.08,1,LX)
IF(Z2.GT.0.) CALL SYMBOL(.17,.065,.0,.08,1,LZ10)
CALL NUMBER(.17,.065,.0,.08,8,Z2)
CALL SYMBOL(.2145,.055,.0,.08,1,LX)
CALL SYMBOL(.22,.058,.0,.065,1,LZ9)
IF(Z3.GT.0.) CALL SYMBOL(.17,.055,.0,.08,1,LZ10)
CALL NUMBER(.17,.055,.0,.08,8,Z3)
CALL SYMBOL(.2145,.045,.0,.08,1,LX)
CALL SYMBOL(.22,.048,.0,.065,1,LZ8)
IF(Z4.GT.0.) CALL SYMBOL(.17,.045,.0,.08,1,LZ10)
CALL NUMBER(.17,.045,.0,.08,8,Z4)
CALL SYMBEL(.173,.03,.0,-.11,2,LZ5)
CALL SYMBEL(.179,.0283,.0,.09,4,LX22)
CALL SYMBOL(.195,.03,.0,-.1,1,LX24)
CALL SYMBOL(.229,.033,.0,-.05,1,LZ2)
CALL NUMBER(.2,.03,.0,.05,6,RR)
CALL SYMBEL(.173,-.145,.0,-.11,2,LZ5)
CALL SYMBEL(.179,-.1467,.0,.09,4,LX22)
CALL SYMBOL(.195,-.145,.0,-.1,1,LX24)
CALL SYMBOL(.229,-.142,.0,-.05,1,LZ2)
CALL NUMBER(.2,-.145,.0,.08,6,CC)
END IF
S=90.-5
DM=90.-HMEAN
R=100.*ABS(DM-S)/S
LA=L1+L1/2
DO 6068 I=L4,MH2
II=I-(L4+1)
D(II)=FREQ(I)*COS(D1(I))
6068 T33(II)=FREQ(I)*SIN(D1(I))
CALL DASMES
CALL LINE(D,T33,0,II)
INT0=1
GO TO 7062
6072 CALL SYMBOL(.13,.095,.0,-.18,9,LY1)
CALL SYMBEL(.15,-.0545,.0,.05,3,LY10)
CALL SYMBOL(.17,-.055,.0,.08,10,LX7)
CALL SYMBOL(.19,-.065,.0,.08,9,LX5)
CALL SYMBOL(.15,-.08,.0,-.09,3,LX10)
CALL SYMBOL(.17,-.08,.0,.08,8,LX8)
CALL SYMBOL(.19,-.09,.0,.08,9,LX5)
CALL SYMBEL(.15,-.105,.0,.08,16,LX2)
CALL SYMBOL(.176,-.115,.0,.08,15,M)
CALL SYMBEL(.15,-.13,.0,.08,30,LY14)
CALL NUMBER(.215,-.13,.0,.08,6,DM)
IF(JUMP.EQ.1) THEN
CALL SYMBEL(.15,-.145,.0,.08,29,LX25)
CALL NUMBER(.215,-.145,.0,.08,6,S)
CALL SYMBEL(.15,-.16,.0,-.11,2,LZ5)
CALL SYMBEL(.155,-.16,.0,.08,10,LX24)
CALL NUMBER(.161,-.16,.0,.08,5,B)
END IF
CALL TEKPAUS
CALL ERASE
304 CONTINUE
C
IF(ABS(M1-4.3).GT.5) L5=0
DO 5043 I=1,MH1
IF(L5.EQ.0) RECORD(I)=RECORD(I)*(COSH(UK(I)*4.333)/COSH(UK(I)*
MH1))**2
5043 DR(I)=RECORD(I)/FREQ(I)**2/39.47842
C ---39.47842=CPI2**2---
C ---DR(I) IS RAW DATA OF HORI. AMPLITUDE SPECTRUM @ 4.3' ABOVE SEA FLOOR---
C
DO 5041 I=1,MH1
UB(I)=DR(I)*(SINH(UK(I)*DEPTH)/COSH(UK(I)*4.333))**2
C ---UB(I) IS RAW DATA OF WAVE ENERGY SPECTRUM AT SEA SURFACE---
IF(UB(I).GE.2500.) GO TO 5042
5041 CONTINUE
C
5042 M[MN]=I-1
K=M[MN]-1.5*L1
IF(IDEEP.GE.M[MN]) IDEEP=M[MN]
MAX=(IPEAK+K)/2
IF(MAX-IPEAK.GT.L1) MAX=IPEAK+L1
CALL SMOOTH(N,UF,UB,IDEEP,0,1)
IPEAK=IPEAK

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VLARGE=UP(IPEAK)
MAX=MAX+L1/3
DO 5038 J=L2,MAX
IF(UP(J).LE.VLARGE) GO TO 5038
VLARGE=UP(J)
IPEAK=J
5038 CONTINUE
MM=K
IF(K.GT.IPEAK+L1+2) MM=IPEAK+L1+2,J
WRITE(I,5053) VLARGE,IPEAK,UP(MM),MM,(UP(I),I=L2,MM)
5053 FORMAT('////////'---CHECK 1-D. WATER SURFACE ENERGY HERE, '---
INDEX OF PEAK ENERGY',F7.2,' SHOWN HERE IS',I3,'---INDEX OF
UPPER ROUND',F7.2,' IS',I3,'---SMOOTHER ENERGY SERIES NEAR
PEAK ARE SHOWN AS FOLLOWS,',(9F8.2))
PRINT 7067
7067 FORMAT('====INPUT NEW INDEY FOR UPPER ROUND TO CONTINUE, '====
FOR INPUT 0 TO STOP THE PROGRAM, '====OR INPUT 1 WILL RESET INDEY
FOR DESIRED PEAK AND UPPER ROUND.')
READ*,MOD
IF(MOD.EQ.0) STOP
IF(MOD.EQ.1) THEN
READ*,IPEAK,MOD
VLARGE=UP(IPEAK)
END IF
K=MOD
XN=1.
X2=10.
PEAK=FREQ(IPEAK)
CALL ERASE
IF(K.LE.IPEAK+3) PRINT*, 'IPEAK=',IPEAK,', K=',K
IF(K.LE.IPEAK) STOP
C
Y=.6641874
LL=.62*IPEAK
IF(K.GT.IPEAK+LL) K=IPEAK+LL
C ---LL WILL HELP AVOIDING THE OVERFLOW IN EXP---
DO 120 I=LL,K
C=EXP((PEAK/FREQ(I))**4*1.25)*FREQ(I)**5
TA(I)=Y/C/C
120 TR(I)=UP(I)/C
P(IPEAK)=1.
ALFA=VLARGE*PEAK**5*3.490343/Y/GA
MM=1
130 MAX=1
140 X1=.0038
X2=4.
IF(MAX.EQ.1) CALL LSM(F1,X1,MAX)
IF(MAX.EQ.1) R=FF1
IF(MAX.EQ.2) FF1=K
110 CALL LSM(F2,X2,MAX)
XN=100000.*FF1*FF2
IF(XN.GT..0) THEN
X2=X2+2.
IF(X2.LE.10.) GO TO 110
PA=.0
PC=.0
ALFA=.0081
GA=1.
DO 7055 I=IPEAK,NH1
TEMP=PEAK/FREQ(I)
V(I)=TEMP**5*EXP(1.25*(1.-TEMP**4))*VLARGE
C ---USE P-K SPECTRUM TO EXTRAPOLATE THE TAIL PART OF RAW DATA OF WAVE ENERGY DENSITY---
7055 UP(I)=V(I)
DO 7056 I=1,IPEAK
TEMP=PEAK/FREQ(I)
A2=1.25*(1.-TEMP**4)
IF(I.GE.IPEAK) V(I)=UP(I)
IF(I.LT.IPEAK) V(I)=.0
IF(I.LT.IPEAK.AND.A2.GT.-670.) V(I)=TEMP**5*EXP(A2)*VLARGE
7056 CONTINUE
GO TO 220
END IF
DO 140 I=1,15
X=(X1+X2)/2.
CALL LSM(F,X,MAX)
XN=100000.*FF*FF1
IF(XN.LE..0) THEN
X2=X
FF2=FF
ELSE
X1=X
FF1=FF
END IF
IF(ABS(FF)-1.E-8) 150,150,140
140 CONTINUE

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150 IF(MAX.EQ.1) PA=X
    IF(MAX.EQ.2) PC=X
    MAX=MAX+1
    IF(MAX.LE.2) GO TO 160
    Z1=.0
    Z2=.0
    Z3=.0
    Z4=.0
    DO 170 I=LL,K
    TEMP=PC
    IF(I.LT.IIPEAK) TEMP=PA
    P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/TEMP)**2/26.))**13
C ---WHERE .36788=1/EXP---
    C=GAMP(I)
    Z1=Z1+TA(I)*C
    Z2=Z2+TR(I)*C
    Z3=Z3+TA(I)*P(I)*C/GA
170 Z4=Z4+TR(I)*P(I)*C/GA
    Z1=Z2/Z1
    Z2=Z4/Z3
    ALFA=(Z1+Z2)/2.
    GA=VLARGE*PEAKF**5*3.490343/Y/ALFA
    IF(ABS((Z1-Z2)/Z1).LE..01) GO TO 180
    NN=NN+1
    IF(NN.LE.15) GO TO 130
180 MAX=FLOAT(IIPEAK)*(1.+125.*PC)
    DO 190 I=LL,MM1
    IF(I.LE.K) V(I)=ALFA*Y/FREQ(I)**5/EXP((PEAKF/FREQ(I))**4*1.25)
    *GAMP(I)
C ---V(I) IS AN APPLIED JONSWAP SPECTRUM AT SEA SURFACE---
    IF(I.GT.K.AND.I.LE.MAY) THEN
    P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/PC)**2/26.))**13
    V(I)=ALFA*Y/FREQ(I)**5/EXP((PEAKF/FREQ(I))**4*1.25)*GAMP(I)
    END IF
    IF(I.GT.MAX) V(I)=V(MAX)
190 IF(I.GT.IDEEP) UP(I)=V(I)
C ---USE JONSWAP TO EXTRAPULATE THE TAIL PART OF RAW DATA OF WAVE ENERGY SPECTRUM---
    VALUE=FLOAT(IIPEAK)*(1.-125.*PA)+1.
    DO 5034 I=1,LL
    A2=(PEAKF/FREQ(I))**4*1.25
    IF(A2.GT.740.) THEN
    V(I)=.0
    ELSE
    V(I)=.0
    IF(I.GT.VALUE)P(I)=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/PA)**2/26.))**13
    IF(I.GT.VALUE) V(I)=ALFA*Y/FREQ(I)**5/EXP(A2)*GAMP(I)
    END IF
5034 CONTINUE
220 B2=.0
    B3=.0
    ESDA=.0
    DO 7063 I=1,MM1
C IF(I.LT.IIPEAK.AND.V(I).LT.UP(I)) V(I)=UP(I)
C IF(I.LE.IIPEAK) D2(I)=V(I)
C ---D2(I) IS ORIGINAL FRONT PART OF JONSWAP SPECTRUM---
    ESDA=ESDA+RECORD(I)
    B2=B2+FREQ(I)*V(I)
7063 B3=B3+V(I)/FREQ(I)
    VMS=ESDA*FREQ(I)
    B2=SQRT(B2/B3)
    B=.0
    DO 5065 I=L1,IDPEAK
    ESDR=ESDR+V(I)
5065 B=B+(V(I)-UP(I))**2
    TOT=ESDR*FREQ(I)
    ERR1=100.*SQRT(B)/ESDR
    DO 7064 I=1,NSIMU
    IF(S1(I).GT.1000.) S1(I)=1000.
    IF(S2(I).GT.1000.) S2(I)=1000.
C ---ASSUME THAT SPREADING PARAMTER NEVER ACCESSES 50.---
    IS=INT(S1(I))
    IF(IS.EQ.0) THEN
    T13(I)=S1(I)
    ELSE
    IF(IS.LT.100) T13(I)=FS/IS+(S1(I)-IS)*(FS(IS+1)-FS(IS))
    IF(IS.GE.100) T13(I)=8.87335+.022*(S1(I)-100.)
    END IF
    IS=INT(S2(I))
    IF(IS.EQ.0) THEN
    T23(I)=S2(I)
    ELSE
    IF(IS.LT.100) T23(I)=FS(IS)+(S2(I)-IS)*(FS(IS+1)-FS(IS))
    IF(IS.GE.100) T23(I)=8.87335+.022*(S2(I)-100.)
    END IF
7064 CONTINUE

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CALL NUMBER(.59,.44,.0,.09,7,VLARGE)
CALL SYMBOL(.5,.14,.0,.09,27,LX20)
CALL NUMBER(.546,.14,.0,.09,6,RE)
CALL SYMBOL(.495,-.26,.0,.09,9,LX9)
CALL SYMBOL(.45,-.66,.0,.09,3,LX10)
CALL SYMBOL(.495,-.66,.0,.09,8,LX8)
CALL SYMBOL(.605,-.66,.0,.09,8,LX6)
CALL SYMBOL(.495,-1.06,.0,.09,10,LX9)
CALL SYMBOL(.588,-1.06,.0,.09,8,LX6)
CALL SYMBOL(.46,-1.46,.0,.09,16,LX2)
CALL SYMBOL(.496,-1.71,.0,.09,15,RE)
CALL TERPAUS

C
IF(MODE.EQ.3) GO TO 7060
5029 CALL SCALE(8.3,.76,1.1,1.,0.0,-4.)
CALL AXIS(.0,.6,.0,-4.,1.,-4.,.1,1.,1,0,1,0,1.,1.,.1,0)
IF(MODE.EQ.1) THEN
CALL SYMBOL(-.1,-5.08,.0,.1,55,LX7)
CALL SYMBOL(-.05,1.65,.0,.18,18,LX1)
CALL SYMBOL(.504,.26,.0,.105,5,LX21)
CALL SYMBOL(.55,.25,.0,.1,20,LX21)
CALL SYMBOL(.517,.22,.0,.08,5,LX22)
CALL NUMBER(.561,.25,.0,.088,6,UMS)
R=100.*ABS(SU-UMS)/UMS
CALL SYMBOL(.504,-.05,.0,.09,4,LX25)
CALL NUMBER(.56,-.05,.0,.088,6,SV)
CALL SYMBOL(.64,-.05,.0,.1,10,LX26)
CALL NUMBER(.65,-.05,.0,.088,5,RE)
ELSE
CALL SYMBOL(-.1,-5.08,.0,.1,56,LX6)
CALL SYMBOL(-.05,1.65,.0,.18,15,LX)
END IF
5052 IF(MODE.EQ.1) CALL SMOOTH(N,PR,RECORD,NH1,0,1)
IF(MODE.EQ.2) CALL SMOOTH(N,PR,RE,NH1,0,1)
PEAKF=FREQ(IPEAK)
VLARGE=.0
DO 5031 I=1,NH1
IF(MODE.EQ.1) THEN
IF(I.LE.IPEAK)P(I)=V(I)*RECORD(I)/VR(I)
IF(I.GT.IPEAK)P(I)=V(I)*(COSH(UK(I)*4.333)*FREQ(I)*CFI2/SINH(UK(I)
*DEPTH))**2
IF(JMODE.EQ.1.AND.RECORD(I).LT.ADEP) T12(I)=-4.
IF(JMODE.EQ.1.AND.RECORD(I).GE.ADEP)T12(I)=ALOG10(RECORD(I))-EDEP
ELSE
IF(I.LE.IPEAK)P(I)=V(I)*DR(I)/VR(I)
IF(I.GT.IPEAK) P(I)=V(I)*(COSH(UK(I)*4.333)/SINH(UK(I)*DEPTH))**2
IF(JMODE.EQ.1.AND.DR(I).LT.ADEP) T12(I)=-4.
IF(JMODE.EQ.1.AND.DR(I).GE.ADEP)T12(I)=ALOG10(DR(I))-EDEP
END IF
IF(JMODE.EQ.1) THEN
IF(P(I).LT.ADEP) D(I)=-4.
IF(PR(I).LT.ADEP) T33(I)=-4.
IF(P(I).GE.ADEP) D(I)=ALOG10(P(I))-EDEP
IF(PR(I).GE.ADEP) T33(I)=ALOG10(PR(I))-EDEP
END IF
IF(I.LT.L1.AND.I.GT.NHS) GO TO 5031
IF(P(I).LT.VLARGE) GO TO 5031
VLARGE=P(I)
I1=I
5031 CONTINUE
PEAKF=FREQ(I1)
IF(JMODE.EQ.2) GO TO 7060
IF(MODE.EQ.1) THEN
R=.0
ESDR=.0
DO 5066 I=L1,IPPEAK
ESDR=ESDR+P(I)
5066 R=R+(P(I)-PR(I))**2
ERR2=100.*SQRT(R)/ESDR
CALL SYMBOL(.504,.65,.0,.09,2,LX5)
CALL SYMBOL(.517,.62,.0,.08,4,LX22)
CALL SYMBOL(.55,.65,.0,.1,10,LX24)
CALL NUMBER(.561,.65,.0,.088,5,ERR2)
END IF
CALL POINTS
CALL LINE(FREQ,T12,17,NH1)
CALL PLOT(.47,-1.29,1,17)
CALL DASHES
CALL LINE(FREQ,T33,0,NH1)
XL(1)=.452
XL(2)=.482
YL(1)=-2.4
YL(2)=-2.4
CALL VECTORS
CALL LINE(XL,YL,0,2)
CALL LINE(FREQ,P.0,NH1)

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CALL SYMBOL(-.08,-4.,90.,.15,24,LY8)
CALL SYMBOL(.18,-4.68,0.0,0.15,15,LX)
IF(EDEP.LT.1.) CALL NUMBER(-.07,-4.05,.0,.1,6,.0001)
IF(EDEP.LT.1.) CALL NUMBER(-.07,-3.05,.0,.1,5,.001)
IF(EDEP.LT.1.) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(EDEP.LT.1.) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(EDEP.LT.1.) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(EDEP.LT.1.) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(EDEP.GE.1.) CALL NUMBER(-.07,-4.05,.0,.1,5,.010)
IF(EDEP.GE.1.) CALL NUMBER(-.07,-3.05,.0,.1,5,.100)
IF(EDEP.GE.1.) CALL NUMBER(-.07,-2.05,.0,.1,5,1.00)
IF(EDEP.GE.1.) CALL NUMBER(-.07,-1.05,.0,.1,5,10.0)
IF(EDEP.GE.1.) CALL NUMBER(-.07,-.05,.0,.1,5,100.)
IF(EDEP.GE.1.) CALL NUMBER(-.07,.95,.0,.1,6,1000.)
CALL SYMBOL(.36,1.3,.0,.15,20,GE)
CALL SYMBOL(.46,-.55,.0,.09,18,LX11)
CALL NUMBER(.615,-.55,.0,.09,6,PEANF)
CALL SYMBOL(.46,-.95,.0,.09,15,LY11)
CALL NUMBER(.59,-.95,.0,.09,6,VLARGE1)
CALL SYMBOL(.495,-1.35,.0,.09,9,LX9)
CALL SYMBOL(.45,-1.76,.0,.09,3,LX10)
CALL SYMBOL(.495,-1.76,.0,.09,8,LX8)
CALL SYMBOL(.54,-2.06,.0,.09,8,LX6)
CALL SYMBOL(.495,-2.46,.0,.09,4,LY14)
CALL SYMBOL(.553,-2.46,.0,.09,10,LY9)
CALL SYMBOL(.54,-2.76,.0,.09,8,LX6)
CALL SYMBOL(.46,-3.16,.0,.09,16,LX2)
CALL SYMBOL(.496,-3.46,.0,.09,15,M)
CALL TEKPAHS

C
C *****
C ---PART IX: DRAWING DIRECTIONAL SPECTRUM IN THREE DIMENSION SPACE--- *
C *****
C ---THIS PART WILL BE MORE FLEXIBLE AS APPLIED TO SMOOTHED DIRECTIONAL SPECTRUM---
7060 CONTINUE
C ---THE FOLLOWING 137 LINE CAN BE DELETED IF IT IS NOT INTENDED TO HAVE---
C
C
IF(MODE.EQ.2.OR.JMODE.EQ.2) GO TO 7057
RDEP=.01
IF(MODE.EQ.1.AND.DEPTH.LT.140.) RDEP=1.
CALL ERASE
IF(MODE.EQ.1) CALL SCALE(8.3,.76,1.1,1.,.0,-2.)
DO 7058 I=1,MW2
COSDA=COS((PDMEAN-B1(I))/2)**2
TEMP=ALOG10(COSDA)*S1(I)
IF(TEMP.GE.-120.) T12(I)=PR(I)*T13(I)/CPI*COSDA**S1(I)
IF(TEMP.LT.-120.) T12(I)=PR(I)*T13(I)/CPI*1.E-120
IF(MODE.EQ.1) T12(I)=T12(I)*100.
IF(T12(I).LT.RDEP) THEN
T12(I)=-2.
ELSE
T12(I)=ALOG10(T12(I))
IF(RDEP.GE..5) T12(I)=T12(I)-EDEP
END IF
7058 CONTINUE
XL(1)=.498
XL(2)=.528
YL(1)=.1
YL(2)=.1
IF(MODE.EQ.3) THEN
CALL SYMBOL(-.05,3.65,.0,.18,17,LY2)
CALL SYMBOL(.18,-2.68,.0,.15,15,LX)
CALL NUMBER(-.088,2.95,.0,.1,7,1000.0)
CALL NUMBER(-.088,1.95,.0,.1,7,100.00)
CALL NUMBER(-.088,.95,.0,.1,7,10.000)
CALL NUMBER(-.088,-.05,.0,.1,7,1.0000)
CALL NUMBER(-.088,-1.05,.0,0.1,7,.1000)
CALL NUMBER(-.088,-2.05,.0,.1,7,0.0100)
ELSE
CALL SYMBOL(-.05,3.65,.0,.18,18,LX1)
CALL SYMBOL(.18,-2.68,.0,.15,15,LX)
IF(RDEP.LT..5) CALL NUMBER(-.07,-2.05,.0,.1,6,.0001)
IF(RDEP.LT..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.001)
IF(RDEP.LT..5) CALL NUMBER(-.07,-.05,.0,.1,5,.010)
IF(RDEP.LT..5) CALL NUMBER(-.07,.95,.0,.1,5,.100)
IF(RDEP.LT..5) CALL NUMBER(-.07,1.95,.0,.1,5,1.00)
IF(RDEP.LT..5) CALL NUMBER(-.07,2.95,.0,.1,5,10.0)
IF(RDEP.GE..5) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(RDEP.GE..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(RDEP.GE..5) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(RDEP.GE..5) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(RDEP.GE..5) CALL NUMBER(-.07,1.95,.0,.1,5,100.)
IF(RDEP.GE..5) CALL NUMBER(-.07,2.95,.0,.1,6,1000.)
CALL SYMBOL(.504,1.67,.0,.09,12,LY23)

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CALL NUMBER(.495,1.37,.0,.085,4,4,3)
CALL SYMBEL(.511,1.37,.0,.09,24,LY12)
END IF
CALL AXISL(.0,.6,.0,-2.,3.,-2.,.1,1.,1,0,1,0,1.,1.,1,0)
CALL LINE(FREQ,T12,0,MH2)
CALL LINE(XL,YL,0,2)
CALL SYMBOL(.393,2.6,.0,.15,9,LX)
CALL SYMBOL(.594,2.6,.0,.15,8,LX6)
CALL SYMBOL(.393,2.07,.0,.15,2,LZ2)
CALL SYMBOL(.4515,2.07,.0,.15,14,LY14)
CALL SYMBOL(.54,.04,.0,.09,8,LX8)
CALL SYMBOL(.585,-.26,.0,.09,8,LX6)
CALL SYMBEL(.504,-.66,.0,.09,16,LX2)
CALL SYMBOL(.54,-.96,.0,.09,15,M)
CALL SYMBEL(.504,-1.36,.0,.09,18,LY14)
CALL NUMBER(.585,-1.66,.0,.085,6,DM)
CALL SYMBOL(.648,-1.57,.0,.06,1,LZ4)
CALL TEMPAUS
CALL ERASE

C
IF(MODE.EQ.1) IPNOU=IPEAK
IF(MODE.EQ.3) IPNOU=IPEAK
DO 7059 I=1,120
C=FLOAT(I)*3.*RN-CP1
COSHA=COS((C-D1(IPNOU))/2.)*2
TEMP=ALOG10(COSDA)*S(IPNOU)
IF(TEMP.GE.-120.) T12(I)=VLARGE*T13(IPNOU)/CP1+COSDA*S1(IPNOU)
IF(TEMP.LT.-120.) T12(I)=VLARGE*T13(IPNOU)/CP1*1.E-120
IF(MODE.EQ.1) T12(I)=T12(I)*100.
T33(I)=FLOAT(I)/300.
IF(T12(I).LT.BDEF) THEN
T12(I)=-2.
ELSE
T12(I)=ALOG10(T12(I))
IF(BDEF.GE..5) T12(I)=T12(I)-EDEF
END IF
7059 CONTINUE
IF(MODE.EQ.3) THEN
CALL SYMBEL(-.05,3.65,.0,.18,17,LY2)
CALL NUMBER(-.088,2.95,.0,.1,7,1000.0)
CALL NUMBER(-.088,1.95,.0,.1,7,100.00)
CALL NUMBER(-.088,.95,.0,.1,7,10.000)
CALL NUMBER(-.088,-.05,.0,.1,7,1.0000)
CALL NUMBER(-.088,-1.05,.0,0.1,7,.1000)
CALL NUMBER(-.088,-2.05,.0,.1,7,0.0100)
ELSE
CALL SYMBEL(-.05,3.65,.0,.18,18,LX1)
IF(BDEF.LT..5) CALL NUMBER(-.07,-2.05,.0,.1,5,.0001)
IF(BDEF.LT..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.001)
IF(BDEF.LT..5) CALL NUMBER(-.07,-.05,.0,.1,5,.010)
IF(BDEF.LT..5) CALL NUMBER(-.07,.95,.0,.1,5,.100)
IF(BDEF.LT..5) CALL NUMBER(-.07,1.95,.0,.1,5,1.00)
IF(BDEF.LT..5) CALL NUMBER(-.07,2.95,.0,.1,5,10.)
IF(BDEF.GE..5) CALL NUMBER(-.07,-2.05,.0,.1,5,.010)
IF(BDEF.GE..5) CALL NUMBER(-.07,-1.05,.0,.1,5,.100)
IF(BDEF.GE..5) CALL NUMBER(-.07,-.05,.0,.1,5,1.00)
IF(BDEF.GE..5) CALL NUMBER(-.07,.95,.0,.1,5,10.0)
IF(BDEF.GE..5) CALL NUMBER(-.07,1.95,.0,.1,5,100.)
IF(BDEF.GE..5) CALL NUMBER(-.07,2.95,.0,.1,6,1000.)
CALL SYMBOL(.504,1.67,.0,.09,12,LY23)
CALL NUMBER(.495,1.37,.0,.085,4,4,3)
CALL SYMBEL(.511,1.37,.0,.09,24,LY12)
END IF
CALL AXISL(.0,.4,.0,-2.,3.,-2.,.05,1.,1,0,0,0,1.,1.,1,0)
CALL LINE(T33,T12,0,120)
CALL LINE(XL,YL,0,2)
CALL SYMBOL(-.096,-2.26,.0,.11,1,LX4)
CALL SYMBOL(.094,-2.26,.0,.11,1,LX4)
CALL SYMBOL(.194,-2.26,.0,.11,1,LX3)
CALL SYMBOL(.294,-2.26,.0,.11,1,LX3)
CALL SYMBOL(.394,-2.26,.0,.11,1,LX4)
CALL SYMBOL(.09,-2.72,.0,.15,9,LX5)
CALL SYMBOL(.294,-2.72,.0,.15,8,LX23)
CALL SYMBOL(.336,2.6,.0,.15,11,LX5)
CALL SYMBOL(.5646,2.6,.0,.15,8,LX6)
CALL SYMBOL(.336,2.07,.0,.15,2,LZ2)
CALL SYMBOL(.3945,2.07,.0,.15,18,LY24)
CALL SYMBOL(.54,.04,.0,.09,8,LX8)
CALL SYMBOL(.585,-.26,.0,.09,8,LX6)
CALL SYMBEL(.504,-.66,.0,.09,16,LX2)
CALL SYMBOL(.54,-.96,.0,.09,15,M)
CALL SYMBEL(.504,-1.36,.0,.09,22,LY24)
CALL NUMBER(.6,-1.66,.0,.085,6,PEAKF)
CALL SYMBOL(.678,-1.66,.0,.088,2,LZ3)
CALL TEMPAUS
7057 CONTINUE

```



```

C
C
CALL ERASE
CALL SCALE(17.4,16.,.42,.42,.0,.0)
PRINT 7069
READ*, JMODE
GO TO (7068,7068,7071,7072) JMODE
7068 PRINT 7061, MODE
7061 FORMAT(1X/"====INPUT CONSTANT, CMODE, FOR RANGING THE CONTOURS."/
1"-----CMODE=1. WILL COVER 1,4,10,40,100,400,700,1000."/"-----CMODE
1 IS THE VALUE 10**INTEGER, RANGE: (1,4,.,.,.,1000)*CMODE."/"-----FOR
1 EXAMPLE: CMODE=.1 COVERS (.1,.4,1.4,.,.,100)."/"-----GUIDE: CMODE
1=.1,1.,10. RESPECT TO MODE=1,2,3. MODE=",11," NOW.")
READ*,CMODE
PRINT 800
800 FORMAT(1X/"====INPUT ANGULAR INTERVAL (DEG.) FOR ITERATIVE COMPUTAT
ION."/"-----GUIDE: 4 FOR ROUGH DRAW, OR LESS FOR SHARP VIEW.")
READ*,MH3
VLARGE=.002+.0002*MH3
R=.0
SUM=.0
ALL=.0
PRINT 7099
7099 FORMAT(1X/"====INPUT NUMBER OF POINT-INCREMENT IN FREQUENCY INDEY
1."/"-----E.G. INPUT 3 WILL SKIP 2 POINTS, ETC."/"-----GUIDE: INPUT
1 1 FOR N.LE.256, INPUT (N/256)*2 FOR N.GT.256.")
READ*,MHA
FREQ2=FREQ1*FLOAT(MHA)
CALL ERASE
CALL ORIGIN(3.03,2.83)
DO 7070 I=2,MH2,MHA
IF(JMODE.EQ.1) THEN
T12(I)=T13(I)/CMODE/CP1*P(I)
ELSE
T33(I)=T23(I)/CMODE/CP1*P(I)
IF(I.GE.L1.AND.I.LE.IPEAK) T12(I)=T13(I)/CMODE/CP1*P(I)
END IF
7070 CONTINUE
C ---P(I) IS THE PROPOSED JONSWAP SPECTRUM, AND PB(I) IS THE SMOOTHED DATA---
MIN=INT(DMEAN)-90
MAX=2*INT(DMEAN)-MIN
C
DO 7065 J=MIN,MAX,MH3
C=FLOAT(J)
RIG=C*RN
COSJ=COS(RIG)
SINJ=SIN(RIG)
ESDA=1.E-7
DO 200 JJ=1,7
200 IX(J)=0
C
IF(JMODE.EQ.2.AND.JUMP.EQ.2) COSDA=COS((RIG-DMEAN)/2.)*2
DO 7066 I=2,MH2,MHA
IF(JMODE.EQ.1.OR.JUMP.EQ.1) COSDA=COS((RIG-D1(I))/2.)*2
IF(JMODE.EQ.2.AND.JUMP.EQ.3) COSDA=COS((RIG-D2(I))/2.)*2
IF(JMODE.EQ.1) THEN
TEMP=ALOG10(COSDA)*S1(I)
IF(TEMP.GE.-120.) ESDR=T12(I)*COSDA**S1(I)
IF(TEMP.LT.-120.) ESDR=T12(I)*1.E-120
ELSE
TEMP=ALOG10(COSDA)*S2(I)
IF(TEMP.GE.-120.) ESDR=T33(I)*COSDA**S2(I)
IF(TEMP.GE.-120..AND.I.GE.L1.AND.I.LE.IPEAK) L2=10
IF(L2.EQ.10) RDX=COS((RIG-D1(I))/2.)*2
IF(L2.EQ.10) SUM=SUM+(ESDR-T12(I)*RDX**S1(I))*2
IF(TEMP.LT.-120.) ESDR=T33(I)*1.E-120
END IF
ALL=ALL+ESDR
IF(ESDR.LT.1..AND.ESDR.LT.1.) GO TO 7066
IF(ESDR.GT.1000..AND.ESDR.GT.1000.) GO TO 7066
IF(I.LT.IPEAK+10.OR.I.GT.IPEAK+10) GO TO 700
IF(C.LT.DMEAN-20..OR.C.GT.DMEAN+20.) GO TO 700
IF(ESDR.GT.R) THEN
R=ESDR
L3=1
CC=C
END IF
C ---WHERE ESDR IS THE DISCRETE DIRECTIONAL SPECTRUM OF INTERESTED WAVE PROPERTY---
700 L00=INT(ESDR)
L1=INT(ESDR)
IF(L00.GE.1.AND.L00.LE.4) THEN
L00=1
ELSE IF(L00.GE.5.AND.L00.LE.9) THEN
L00=2
ELSE IF(L00.GE.10.AND.L00.LE.49) THEN
L00=3

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ELSE IF(L00.GE.50.AND.L00.LE.99) THEN
L00=4
ELSE IF(L00.GE.100.AND.L00.LE.499) THEN
L00=5
ELSE IF(L00.GE.500.AND.L00.LE.999) THEN
L00=6
ELSE IF(L00.GE.1000) THEN
L00=7
END IF
IF(L11.GE.1.AND.L11.LE.4) THEN
L11=1
ELSE IF(L11.GE.5.AND.L11.LE.9) THEN
L11=2
ELSE IF(L11.GE.10.AND.L11.LE.49) THEN
L11=3
ELSE IF(L11.GE.50.AND.L11.LE.99) THEN
L11=4
ELSE IF(L11.GE.100.AND.L11.LE.499) THEN
L11=5
ELSE IF(L11.GE.500.AND.L11.LE.999) THEN
L11=6
ELSE IF(L11.GE.1000) THEN
L11=7
END IF
LLL=L11
L2=1
IF(L11-L00) 10,7066,20
10 L11=L00
L00=LLL
L2=0
20 L00=L00+1
IF(L11.GT.L11) L11=11
DO 100 K=L00,L11
IF(K.EQ.1.OR.K.EQ.3.OR.K.EQ.5.OR.K.EQ.7) KMODE=10*(K/2)
IF(K.EQ.2.OR.K.EQ.4.OR.K.EQ.6) KMODE=5.*10*(K/2-1)
TEMP=FREQ(1)-ABS((KMODE-ESDR)/(ESDA-ESDR))*FREQ2
K1=IXY(K)+1
IF(K1.GT.14) GO TO 100
K2=1
IF(XX(K,K1),ME.1.) K2=2
YY(K,K1,K2)=TEMP*COSJ
YY(K,K1,K2)=TEMP*SINJ
C ---K: "MEMORY CODE" FOR TRACING THE RELATIVE CONTOURS---
C ---K1: "ORDER CODE" FOR CONNECTING PRESENT(I) & LAST(I-1)-RUN CONTOUR LOCATION---
C ---K2: "ITERATION CODE", K2=1 FOR LAST-RUN, K2=2 FOR PRESENT RUN---
IXY(K)=K1
IF(K2.ME.2) GO TO 100
30 XL(1)=XX(K,K1,1)
XL(2)=XX(K,K1,2)
YL(1)=YY(K,K1,1)
YL(2)=YY(K,K1,2)
X12=SQRT(XL(2)*XL(2)+YL(2)*YL(2))-SQRT(XL(1)*XL(1)+YL(1)*YL(1))
IF(ABS(X12).LT.VLARGE) GO TO 300
IF(X12) 40,300,50
40 DO 60 L=1,3,K1,-1
XX(K,L+1,1)=XX(K,L,1)
60 YY(K,L+1,1)=YY(K,L,1)
XX(K,K1,1)=XX(K,K1,2)
YY(K,K1,1)=YY(K,K1,2)
GO TO 30
50 NN=K1+1
DO 70 I1=NN,14
XL(1)=XX(K,I1,1)
IF(XL(1).EQ.1.) GO TO 400
YL(1)=YY(K,I1,1)
X12=SQRT(XL(2)*XL(2)+YL(2)*YL(2))-SQRT(XL(1)*XL(1)+YL(1)*YL(1))
IF(ABS(X12).LT.VLARGE) THEN
DO 80 LL=1,13
XX(K,K1+LL,1)=XX(K,I1+LL,1)
YY(K,K1+LL,1)=YY(K,I1+LL,1)
IF(I1+LL.GE.14) XX(K,14,1)=1.
80 IF(XX(K,K1+LL,1).EQ.1.) GO TO 300
END IF
70 CONTINUE
GO TO 400
300 IF(L2.EQ.1) GO TO 90
IF(L.LE.L1) GO TO 90
L5=J-60
L4=J-15
NMS=J+25
IF(L5.LT.NM3.AND.L5.GE.0) GO TO 91
IF(L4.LT.NM3.AND.L4.GE.0) GO TO 91
IF(NMS.LT.NM3.AND.NMS.GE.0) GO TO 91
GO TO 90
91 VALUE=FLOAT(KMODE)=CHODE

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IF(K.EQ.2.OR.K.EQ.4.OR.K.EQ.6) IPMU=1
IF(IPMU.EQ.1.AND.FREQ(I).LT.12.AND.ABS(C-D(I)*DEGREE).LT
1.17.) GO TO 90
X=XL(2)-.0025
Y=YL(2)-.0015
YI=YL(2)-.006
INTO=INT(VALUE)
IF(INTO.EQ.1) THEN
IF(INTO.EQ.1) CALL SYMBOL(X,Y,.0,.06,1,LZ)
IF(INTO.EQ.5) CALL SYMBOL(X,YI,.0,.06,1,LZ1)
IF(INTO.EQ.10) CALL SYMBOL(X,YI,.0,.06,2,LZ)
IF(INTO.EQ.50) CALL SYMBOL(X,YI,.0,.06,2,LZ1)
IF(INTO.EQ.100) CALL SYMBOL(X,YI,.0,.06,3,LZ)
IF(INTO.EQ.500) CALL SYMBOL(X,YI,.0,.06,3,LZ1)
GO TO 400
END IF
NUM=INT(ABS(ALOG10(VALUE+1.2)))+3
Y=Y-.001
IF(IPMU.EQ.1) Y=Y1
CALL NUMBER(X,Y,.0,.06,NUM,VALUE)
GO TO 400
90 CALL LINE(XL,YL,0,2)
400 XX(K,K1,1)=XX(K,K1,2)
YY(K,K1,1)=YY(K,K1,2)
100 CONTINUE
7066 ESDA=ESDR
DO 500 K=1,7
KK=IXY(K)+1
DO 500 K1=KK,14
XX(K,K1,1)=1.
500 CONTINUE
7065 CONTINUE
DO 600 K=1,7
KK=IXY(K)
DO 600 K1=1,KK
XX(K,K1,1)=1.
600 CONTINUE
INTO=2
C=FREQ(L3)
X=C*COS(CC*RN)
Y=C*SIN(CC*RN)
CC=90.-CC
SUM=100.*SQRT(SUM)/ALL
ALL=ALL*FREQ2*MM4*RN*CMODE
R=R*CMODE
TEMP=90.-DII
CALL SYMBOL(X,Y,.0,.05,1,LY10)
CALL SYMBOL(.0,-.0045,TEMP,.09,25,LY13)
CALL SYMBOL(.138,.095,0.,.18,8,LX6)
IF(MODE.EQ.1) THEN
CALL SYMBOL(.158,.07,.0,.18,18,LX1)
CALL SYMBOL(.168,-.038,.0,.105,5,LX21)
CALL SYMBOL(.172,-.04,.0,.08,4,LX22)
CALL SYMBOL(.186,-.038,.0,.08,20,LY21)
CALL NUMBER(.19,-.038,.0,.08,6,ALL)
END IF
IF(MODE.EQ.2) CALL SYMBOL(.158,.07,.0,.18,15,LY)
IF(MODE.EQ.3) THEN
CALL SYMBOL(.158,.07,.0,.18,17,LY2)
CALL SYMBOL(.168,-.038,.0,.08,15,LX20)
CALL NUMBER(.222,-.038,.0,.08,7,ALL)
ELSE
CALL SYMBOL(.165,.053,.0,.08,12,LY23)
CALL SYMBOL(.167,.041,.0,.08,25,LY12)
CALL NUMBER(.16,.041,.0,.077,4,4,3)
END IF
7062 CALL AXISL(-.15,.15,0.,-.15,-.15,0.,.05,.05,0,0,0,1.,1.,.1,0)
CALL CIRCLE(0.,0,0.,90.,.15,.15,.1)
CALL CIRCLE(0.,0,99.,180.,.15,.15,.1)
CALL CIRCLE(0.,0,185.,261.,.15,.15,.1)
CALL CIRCLE(0.,0,290.,355.,.15,.15,.1)
CALL SYMBOL(.159,-.006,.0,.2,1,LX3)
CALL SYMBOL(-.168,-.006,.0,.2,1,LX4)
CALL SYMBOL(-.0038,-.158,0.,.2,1,LY3)
CALL SYMBOL(-.0038,-.171,0.,.2,1,LY4)
CALL SYMBOL(.11,.12,0.,.18,11,LX5)
CALL NUMBER(.131,-.01,0.,.1,4,.15)
CALL NUMBER(-.157,-.01,0.,.1,4,.15)
CALL NUMBER(-.022,-.01,-.0,107,4,.00)
CALL NUMBER(-.024,.145,0.,.1,4,.15)
CALL NUMBER(-.024,-.150,0.,.1,4,.15)
CALL SYMBOL(.0943,-.151,0.,.1,14,LX)
CALL SYMBOL(.08,.158,0.,.15,20,EE)
IF(INTO.EQ.1) GO TO 6072
IF(JMODE.EQ.1) THEN
CALL SYMBOL(.168,-.055,.0,.08,8,LX8)

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ELSE
CALL SYMBL(.18,-.021,.0,.11,2,LZ5)
CALL SYMBL(.184,-.023,.0,.088,4,LX22)
CALL SYMBL(.201,-.021,.0,.09,10,LX24)
CALL NUMBER(.205,-.021,.0,.08,5,SUM)
CALL SYMBL(.168,-.055,.0,.08,10,LY19)
END IF
CALL SYMBL(.19,-.065,.0,.08,8,LX6)
CALL SYMBL(.1418,-.1058,.0,.08,25,LX12)
CALL SYMBL(.1789,-.1166,.0,.08,25,LY12)
CALL NUMBER(.1645,-.1166,.0,.075,6,HI)
CALL SYMBL(.194,-.1276,.0,.08,19,LX13)
CALL NUMBER(.1653,-.1276,.0,.075,6,PII)
CALL NUMBER(.215,-.1276,.0,.075,6,DII)
CALL SYMBL(.154,-.1422,.0,.05,1,LY10)
CALL SYMBL(.168,-.1426,.0,.08,15,LY11)
CALL NUMBER(.219,-.1426,.0,.08,7,B)
CALL NUMBER(.1653,-.1536,.0,.075,6,C)
CALL NUMBER(.212,-.1536,.0,.075,6,CC)
CALL SYMBL(.194,-.1536,.0,.08,15,LZ3)
CALL SYMBL(.168,-.08,.0,.08,14,LX2)
CALL SYMBL(.18,-.0908,.0,.08,15,M)
CALL TEKPAUS
CALL ERASE
PRINT 7069
7069 FORMAT(/"=====")
1 / /"====INPUT 1 TO DRAW AN SMOOTHED SPECTRUM,"/"====OR
1 INPUT 2 TO DRAW A PROPOSED SPECTRUM,"/"====OR INPUT 3 TO EXECUTE
1 THE PROGRAM IN OTHER MODE." /"====OR INPUT 4 TO TERMINATE THE
1 EXECUTION OF THIS PROGRAM.")
READ*, JMODE
GO TO (7068,7068,7071,7072) JMODE
7071 PRINT 5032
5032 FORMAT(/"=====")
1 / /"====INPUT MODE CODE,"/"----MODE=1 RUN A HORIZONTAL
1 VELOCITY SPECTRUM (4.3' ABOVE SEA FLOOR)"/"----MODE=2 RUN A HORI
1 ZONTAL AMPLITUDE SPECTRUM (4.3' ABOVE SEA FLOOR)"/ "----MODE=3 WI
1 LL RUN A WAVE ENERGY SPECTRUM AT SEA SURFACE, "/"----MODE=4 WILL
1 TERMINATE THE PROGRAM.")
READ*, MODE
IF (MODE.NE.4) GO TO 5048
STOP
7072 END
C
C *****
C ---PART X: COLLECTION OF SUBROUTINES AND BLOCK DATA---
C *****
SUBROUTINE TRANS(DEPTH,M1,MH)
COMMON /DATA10/ FREQ(720),TA(720),TB(720),P(720),VP(720),WK(720)
1,FREQ1,FREQ2,ALFA,GA,PEAKF,LL,IPEAK,IPPEAK,IPEAK,K,A1,ICPEAK,L1
FREQ3=FREQ2/6.
C ---FREQ1(M2) CIRCUMSCRIBES SHALLOW WATER WAVES---
WK(MH+1)=.1
M2=M1+3.4167
C ---3.4167(FT) IS THE DISTANCE BETWEEN CURRENT-METER AND PRESSURE GAUGE---
DO 130 I=MH,1,-1
FREQ(I)=FLOAT(I)*FREQ1
IF (FREQ(I).GT.FREQ2) THEN
WK(I)=FREQ(I)*FREQ1*.1*2270286
C ---1.2270286=(CP12)**2/32.174---
WPI(I)=.0058855*COSH(WK(I)*M2)/COSH(WK(I)*M1)/FREQ(I)
C ---.0058855=(UNIT WEIGHT OF SEA WATER)/CP12=(64./12**3 PSI)/CP12---
ELSE IF (FREQ(I).LE.FREQ3) THEN
WK(I)=FREQ(I)*SQRT(1.2270286/DEPTH)
WPI(I)=.0058855*WK(I)*DEPTH/FREQ(I)
ELSE
C ---CONSIDER THE INTERMEDIATE WATER CONDITION---
XX=WK(I+1)*DEPTH
WPI(FREQ(I)*FREQ(I)*DEPTH*.1*2270286
TANHH=TANH(XX)
DO 170 J=1,10
DH=(WK-XX*TANHH)/(TANHH+XX/COSH(XX)**2)
YY=DH**X
TANHH=TANH(XX)
IF (ABS(DH/XX).LT..005) GO TO 150
170 CONTINUE
150 WK(I)=XX/DEPTH
WK(J)=XX/DEPTH
WPI(J)=.0058855*TANHH*COSH(WK(I)*M2)/COSH(WK(I)*M1)/FREQ(I)
END IF
130 CONTINUE
RETURN
END
C
SUBROUTINE SMOOTH(MN,S2,S1,MH,ICPEAK,MOD)
DIMENSION S1(MH),S2(MH)

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C ---USING BARTLETT WINDOW: I=2M/3, BASEWIDTH=2/M (HZ)-----
C N(SEC) M(SEC) D.O.F. 80% C.I.
C 256 128 6 (.58)(2.6)
C 512 128 12 (.65)(1.8)
C 1024 128 24 (.72)(1.5)
IF(MN.EQ.1024) MOD=4
S2(1)=(S1(1)+S1(2))/2.
S2(MH)=(S1(MH-1)+S1(MH))/2.
GO TO (5,20,40,70) MOD
5 S2(2)=(S1(1)+S1(3))/3.25+S1(2)/2.6
S2(3)=(S1(2)+S1(4))/3.25+S1(3)/2.6
NS=MH-3
IF(MN.EQ.512) THEN
DO 10 I=4,NS
10 S2(I)=(S1(I-3)+S1(I+3))/36.+(S1(I-2)+S1(I+2))/9.+(S1(I-1)+S1(I+1))
/4.5+S1(I)/3.6
S2(NS+1)=(S1(NS)+S1(NS+2))/3.25+S1(NS+1)/2.6
S2(MH-1)=(S1(MH-2)+S1(MH))/3.25+S1(MH-1)/2.6
ELSE
NS=MH-1
DO 11 I=2,NS
11 S2(I)=(S1(I-1)+S1(I+1))/4.5+S1(I)/1.8
END IF
RETURN
20 NS=MH-1
DO 30 I=2,NS
30 S2(I)=(S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2)
RETURN
40 NS=ICPEAK-1
DO 50 I=2,NS
50 S2(I)=(S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2)
NS=ICPEAK+1
II=MH-1
DO 60 I=NS,II
60 S2(I)=(S1(I-1)*.2+S1(I)*.6+S1(I+1)*.2)
S2(ICPEAK)=S1(ICPEAK)
RETURN
70 S2(2)=(S1(1)+S1(3))/3.05+S1(2)/2.9
S2(3)=(S1(1)+S1(5))/5.625+(S1(2)+S1(4))/4.737+S1(3)/4.5
S2(4)=(S1(2)+S1(6))/5.625+(S1(3)+S1(5))/4.737+S1(4)/4.5
S2(5)=(S1(3)+S1(7))/5.625+(S1(4)+S1(6))/4.737+S1(5)/4.5
S2(6)=(S1(4)+S1(8))/5.625+(S1(5)+S1(7))/4.737+S1(6)/4.5
NS=MH-6
DO 80 I=7,NS
80 S2(I)=(S1(I-6)+S1(I+6))*0.125+(S1(I-5)+S1(I+5))*0.0306+
1(S1(I-4)+S1(I+4))*0.0562+(S1(I-3)+S1(I+3))*0.0853+
1(S1(I-2)+S1(I+2))*0.1123+(S1(I-1)+S1(I+1))*0.1318+S1(I)*0.1388
S2(NS+1)=(S1(NS-1)+S1(NS+3))/5.625+(S1(NS)+S1(NS+2))/4.737
1+S1(NS+1)/4.5
S2(NS+2)=(S1(NS)+S1(NS+4))/5.625+(S1(NS+1)+S1(NS+3))/4.737
1+S1(NS+2)/4.5
S2(NS+3)=(S1(NS+1)+S1(NS+5))/5.625+(S1(NS+2)+S1(NS+4))/4.737
1+S1(NS+3)/4.5
S2(NS+4)=(S1(NS+2)+S1(MH))/5.625+(S1(NS+3)+S1(NS+5))/4.737
1+S1(NS+4)/4.5
S2(NS+5)=(S1(NS+4)+S1(MH))/3.05+S1(NS+5)/2.9
RETURN
END
C
SUBROUTINE LSM(AIN,X,MAX)
COMMON /DATA10/ FREQ(720),TA(720),TR(720),P(720),UP(720),UK(720)
1,FREQ01,FREQ02,ALFA,GA,PEAKF,LL,IPEAK,IPPEAK,IIPEAK,K,A1,ICPEAK,L1
Z1=0
Z2=0
IA=LL
IR=K
IF(MAX.EQ.1) IR=IIPEAK
IF(MAX.EQ.2) IA=IIPEAK
DO 10 I=IA,IR
DATA=(1./EXP(((FREQ(I)-PEAKF)/PEAKF/X)**2/26.))**13
TEMP=GA**DATA
C=DATA*TEMP*(FREQ(I)-PEAKF)**2
Z1=Z1+TA(I)*C*TEMP
10 Z2=Z2+TR(I)*C
AIN=ALFA*Z1-Z2
RETURN
END
C
SUBROUTINE LST(AIN,X,M)
DIMENSION PB(720)
COMMON /DATA10/ FREQ(720),TA(720),TR(720),P(720),UP(720),UK(720)
1,FREQ01,FREQ02,ALFA,GA,PEAKF,LL,IPEAK,IPPEAK,IIPEAK,K,A1,ICPEAK,L1
Z1=0.
Z2=0.
Z3=0.

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Z#=0.  
IF(I1PEAK.EQ..0) THEN  
IA=ICPEAK  
IR=IDPEAK  
ELSE  
IA=ICPEAK-L1  
IR=ICPEAK  
END IF  
DO 10 I=1A,IR  
IF(I1PEAK.EQ..0) THEN  
IF(M.EQ.1) PR(I)=P(I)  
IF(M.EQ.2) PR(I)=UP(I)  
IF(PR(I).GT.PR(ICPEAK)) PR(I)=PR(ICPEAK)  
ELSE  
PR(I)=P(I)  
END IF  
R=FRED(I)**X  
C=R*ALOG(FRED(I))  
Z1=Z1+PR(I)*R  
Z2=Z2+PR(I)*C  
Z3=Z3+R*R  
10 Z4=Z4+R*C  
A1=Z1/Z3  
A1M=A1-Z2/Z4  
RETURN  
END  
EOT ENCOUNTERED.  
/
```