AN ABSTRACT OF THE THESIS OF

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Geotextiles are synthetic fabrics which may be substituted for graded aggregate to protect ocean and coastal structures from erosion and soil instability adjacent to the structure. They are commonly used as a filter and as a structural membrane between an undisturbed sediment surface below and an erosion resistant coarse aggregate above. Geotextiles provide a cost effective alternative to graded aggregate in marine foundations. The need for rational design procedures has led to a theoretical description of the combined soil-geotextile behavior which quantifies failure potential and facilitates optimum geotextile selection. A two-dimensional analytical model has been developed for a three layered system; two different soils separated by a geotextile. The soil response is modeled by Biot consolidation theory and an unsteady form of Darcy's equation in which each soil is considered homogeneous, isotropic and linearly elastic. The soil layers are coupled through the geotextile which acts as an elastic permeable membrane. Soil displacements and stresses and fluid pressures and flows are determined analytically. Potential failure conditions are identified from the cyclic shear stress ratio and from a Mohr-Coulomb stress analysis.

Two series of laboratory experiments were conducted at the Oregon State University Wave Research Facility to verify the model. The large scale facility includes a wave channel which is 12 feet wide, 15 feet deep and 342 feet long. A test section 36 feet long was constructed in the wave channel and filled with approximately three feet of fine sand, a geotextile and one foot of gravel. The test section was exposed to simple harmonic and random waves with heights up to four and one-half feet and periods to eight seconds in water depths to eight feet. The pore water pressure was monitored continuously at seven to ten soil depths and three to five lateral positions and recorded on magnetic tape along with the displacement of the free surface. Four geotextile conditions were tested including woven, impermeable, semi-rigid and no geotextile. Wave-induced liquefaction was observed for a low permeability geotextile.

The experimental results verify the soil-geotextile interaction model and also provide insight into the dynamic response of horizontally layered soils. Results indicate that for the permeabilities of commonly available geotextiles that the hydraulic properties of the geotextile are dominated by the adjacent soil properties. However, clogging of the geotextile increases the potential for soil failure. The pore pressure amplitude response is frequency selective, the higher frequencies being more highly damped. For a given soil condition a "worst" wave period may exist which produces maximum failure potential. Conversely, for a given design wave, there is a "worst" combination of backfill and armor in terms of potential failure.

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bу

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OCEAN WAVE-SOIL-GEOTEXTILE INTERACTION

1.0 INTRODUCTION

Geotextiles are synthetic fabrics which may be substituted for graded aggregate to protect ocean and coastal structures from erosion and soil instability. Geotextiles are commonly used as a structural membrane and as a filter between an undisturbed sediment surface below and an erosion resistant coarse aggregate placed above. Applications in coastal engineering include: erosion protection at piers, dolphins, dikes and tidal channels; foundation stabilization under sea walls, caissons and outfalls; intermediate layers in composite breakwaters, jetties and groins; and reinforcement of buried pipeline backfill material.

Geotextile fabrics are derived from polymers which are constructed as woven, nonwoven or a combination. The mechanical and hydraulic properties of the geotextile vary with the fabric type and may be adjusted to focus on five important performance functions: drainage, filtration, reinforcement, separation and armor. In addition, a geotextile composition must be selected to provide satisfactory placement and longevity for the design life of the structure. Thus, properties such as resistance to ultraviolet deterioration, biofouling, tearing, puncturing, etc. must also be considered in the selection of the optimum geotextile. It is readily apparent that the performance functions, constructability and longevity impose a great number of constraints on the desirable fabric properties for a particular application. This problem is compounded by the recent advent of hundreds of durable and economical geotextiles suitable for both marine and terrestrial application.

1.1 Motivation

Most ocean and coastal structures require protection from erosion and soil instability effects adjacent to the structure. A common practice is to riprap the sediment surface near the structure with graded geologic materials. The geologic materials are placed in layers with the smallest in contact with the undisturbed sediment surface and with each layer increasing in size up to the final armor layer at the top. The armor layer material is selected to provide a stable surface at the design wave and current conditions. The other layer sizes are selected to minimize the exchange of geologic material between adjacent layers.

An alternative to graded riprap filters is the use of synthetic filter fabrics or geotextiles. A geotextile may replace several intermediate layers of graded materials and thereby reduce the construction costs. In the construction of deep water marine structures, the placement of graded riprap filters becomes very difficult. This difficulty may be reduced through the use of geotextiles. A third benefit of geotextiles is that they confine the movement of the soil. Buried pipelines may be held down by fabric tension.

Geotextiles provide a cost-effective alternative to graded riprap filters, are less difficult to work with in deeper water and provide an additional mode of soil stabilization. As a result, geotextiles are being used in an increasing number of marine structures. However, the use of these materials has preceded a well-defined analysis, design and construction procedures required to insure their successful performance in the field [Heerten (1981)].

This study responds to the need for a comprehensive examination of synthetic geotextile behavior in coastal and ocean engineering applications. A theoretical description of the combined wave-soil-geotextile interaction is developed which provides the framework to develop meaningful design procedures.

1.2 Scope

An analytical model is developed to quantify the response of a horizontal, three-layered soil-geotextile-soil system to wave excitation. The differential equations describe each soil layer as a homogeneous, isotropic, linearly elastic medium. The fluid flow in the interstices of the soil is described by an unsteady, compressible fluid form of Darcy's equation. The two soil layers are coupled through the geotextile which acts as an elastic permeable membrane. A general solution to the differential equations is obtained assuming simple harmonic dependence in time and the horizontal direction of surface wave propagation. This reduces the system of partial differential equations to ordinary differential equations in depth which have exponential solutions. The model is verified with experimental results. The behavior of the solution is examined for a variety of soil and geotextile characteristics.

1.3 Literature Review

Fluid flow in porous media is common to many areas of science and engineering. However, most of the literature is the result of four areas of research: ground water flow, geotechnical engineering, mechanics and ocean engineering. The systems being modeled by each discipline are similar but the relative importance of individual processes varies among the fields. In ground water problems the rate of flow may be of interest while in geotechnical engineering the soil settlement or consolidation due to the expulsion of the pore fluid is of major interest. In the mechanics literature more emphasis is placed on soil stresses and displacements while in ocean engineering wave damping and sub-bottom failures are of interest. The diversity of application has, unfortunately, fragmented the literature.

The present study, while falling in the ocean engineering category, is an attempt to draw concepts from all four disciplines to develop a physically meaningful set of defining equations with a tractable solution. An overview of the ocean engineering literature is

presented, followed by a review of geotechnical literature, a review of geotextile literature and a summary of the literature relevant to the present wave-soil interaction study.

1.3.a Ocean Engineering Literature

The interaction of water waves and the bottom has been observed in the field [Gade (1958), Bennett and Faris (1979), Bea et al. (1980)], and demonstrated in the laboratory [Nakamura et al. (1973) and Nath et al. (1977)]. Heerten (1981) suggests that significant profile changes and slope reduction of a revetment was caused by wave-induced liquefaction. Wave-induced failures associated with large storms observed in the Mississippi delta and have resulted in pipeline failures [Bea et al. (1980)]. In a soft permeable sediment excess pore water pressures are developed and the bottom deforms in response to the wave pressure. Either or both of these mechanisms may lead to a soil failure. Since energy is dissipated at the fluid-soil interface and in the soil layer, the water wave height is attenuated. This attenuation may be significant if the bottom is very soft or the wave travel distance in shallow water is long. The magnitude of the wave bottom interaction is a function of the wave conditions and the soil matrix properties. A variety of theories have been proposed within the framework of these variables; permeable or impermeable bottom, rigid or deformable soil skeleton, compressible pore fluid and the degree of wave-bottom interaction. A number of theories are categorized by these assumptions in Table 1.1.

The simplest assumptions are that the bottom is rigid, impermeable and smooth. This leads to a no wave-bottom interaction solution [Lamb (1932)]. A number of solutions have been developed which include bottom friction [Putnam and Johnson (1949), Hunt (1952, 1964), Case and Parkinson (1957), Ippen (1966), Van Dorn (1966), Johns (1968), Treloar and Bebner (1970), Mei and Liu (1973), Isaacson (1977), and Kamphus (1978)]. Wave heights are attenuated due to viscous dissipation. The impermeable soil assumption has also been applied to deformable bottoms [Mallard and Dalrymple (1977), Dawson (1978), and Dawson <u>et al</u>. (1981)]. The soil is assumed to be an elastic solid which deforms in response to wave pressures. An alternative is to treat the bottom as a viscous fluid [Gade (1958) and Dalrymple and Liu (1978)]. As in the case of the elastic solid, the bottom deforms in response to wave pressures. Viscous dissipation in the bottom fluid results in wave attenuation. Hsiao and Shemdin (1980) and MacPherson (1980) have developed solutions for a soil which is modeled as an impermeable viscoelastic medium.

A number of solutions have been developed for a porous, rigid bottom. Putnam (1949) developed a solution for the pore water velocity potential from fluid continuity and Darcy's equation. The wave and bottom were not coupled. An estimation of wave decay was made by calculating the mechanical energy dissipated in the pore fluid. Reid and Kajiura (1957) extended this analysis to include wave-bottom interaction which resulted in an exponential decay of wave height with travel distance. Pressure and vertical flux of fluid were matched at the mudline. This led to a solution in which there is a discontinuity in the horizontal component of velocity at the mudline. Hunt (1959), Murrary (1965), Liu (1973), Dalrymple (1974), McClain <u>et al</u>. (1977), and Puri (1980) have resolved this difficulty by allowing for the development of a viscous boundary layer at the mudline.

Porous rigid bottom solutions have also been developed for anisotropic soils [Sleath (1970)], turbulent flow in the bed [Massel (1976)] and a compressible pore fluid [Nakamura <u>et al</u>. (1972) and Moshagen and Torum (1975)]. The extension to anisotropic soils is useful since in most sedimentary sea beds the horizontal and vertical flow properties are different. The turbulent flow model is applicable when the sediment grain size is large and the flow is less restricted. A compressible pore fluid and an incompressible soil skeleton is usually an inappropriate assumption since the skeleton is often more deformable [Prevost et al. (1965)].

A recent series of papers stimulated by Yamamoto (1977) treat the bottom as porous and deformable. He developed a solution from the

Soil:	Imperme	able		Porous	
Skeleton:	Rigid	Deformable	Rig	id	Deformable
luid:			Compressible	Incompressible	Compressible
	Lamb (1932)	Gade (1958)	Nakamura <u>et al</u> . (1972)	Putnam (1949)	Yamamoto (1977, 1978,
	Putnam and Johnson (1949)	Mallard and Dalrymple (1977)	Moshagen and Torum (1975)	Reid and Kajiura (1957)	1981a, 1981b)
	Hunt (1952)	Dawson (1978)		Hunt (1959)	Yamanoto <u>et al</u> . (1978
	Case and Parkinson (1957)	Dalrymple and Liu (1978)		Murrary (1965)	Madsen (1973)
	Hunt (1964)	MacPherson (1980)		Sleath (1970)	Mei and Foda (1979)
	Ippen (1966)	Hsiao and Shemdin (1980)		Liu (1973)	Dalrymple and Liu (1979)
	Van Dorn (1966)	Dawson et al. (1981)		Dalrymple (1974)	Hudspeth and Patton
	Johns (1968)			Massel (1976)	(personal communica tion)
	Treloar and Brebner (1970)			Puri (1980)	Yamamoto and Suzuki
	Mei and Liu (1973)		1		(1980)
	Isaacson (1977)				Rousseau (1981)
	Kamphuis (1978)				

Table 1.1. Categorization of ocean engineering wave-bottom interaction literature

quasi-static theory of consolidation proposed by Biot (1941). It is assumed that the soil skeleton behaves as a linearly elastic medium and that the fluid flow is modeled by Darcy's equation. The inertia terms are neglected in the stress equilibrium equations. The continuity or storage equation was taken from Verruijt (1969) and accounts for the partial saturation of the pore fluid. The theory predicted stresses, displacements and pore pressures for an infinitely thick soil deposit in which the water waves were decoupled from the soil response. Depth profiles of pressure amplitude and phase agreed with laboratory observations. Madsen (1978) developed a solution by a different mathematical approach and extended the model conceptually to anisotropic permeability and layered soils. Yamamoto (1978) extended the results of his earlier work to soil deposits of finite thickness. For soil layers of finite thickness, the permeability was shown to be more important.

Yamamoto has recently developed a multi-layered model [Yamamoto and Suzuki (1980) and Yamamoto (1981a)]. This model approximates vertically inhomogeneous soil deposits. Yamamoto has also examined the potential for sea bed liquefaction using a Mohr circle analysis. Hudspeth and Patton (personal communication) have extended the Biot theory to allow for wave-bottom interaction and the development of a bottom boundary layer. Wave height attenuation is determined for the combined effects of viscous dissipation at the mudline and wave induced flow in the sea bed. Rousseau (1981) has solved the coupled wavebottom interaction problem for a soil with anisotropic permeability.

Biot (1956a,b) extended his earlier work to include the inertia terms. The solution to these equations revealed the existence of three waves: one rotational or shear wave, and two dilational or compression waves. Dalrymple and Liu (1979) solved the coupled wave-soil problem including the inertia terms. The inertia terms were found to be unimportant, except for the case of very soft sediments in which the water wave celerity approaches the Raleigh wave speed of the sediment. Noting that one of the dilational waves is rapidly attenuated, Mei and Foda (1979) developed a boundary layer type formulation. Outside the boundary layer there is little relative motion between the

fluid and soil and the inertia terms are unimportant. The approximate solution was within five percent of the Yamamoto <u>et al</u>. (1978) results. Yamamoto (1981b) has also developed a solution to the Biot equations including the inertia terms and internal Columb friction. This solution agreed well with field measurements.

1.3.b Geotechnical Literature

Geotechnical engineers have also studied the wave-soil interaction phenomenon. Primarily, two aspects of wave-soil interaction have been analyzed: 1) wave-induced slope instability and 2) wave-induced liquefaction. For the slope stability analyses a failure surface is constructed and the load is prescribed as a combination of the static overburden and the dynamic wave pressure [e.g., Henkel (1970)]. For the wave-induced liquefaction models, concepts are drawn from earthquake engineering and the development of excess pore water pressure due to cyclic stressing of the soil [Seed et al. (1976)]. Terzaghi's one-dimensional consolidation equation [Terzaghi and Peck (1967)] is time-averaged over one wave period and a semi-empirical pore pressure source term is included to account for the pore water pressure accumulation due to the cyclic stressing of the soil [Finn et al. (1977), Rahman et al. (1977), Seed and Rahman (1978), Finn et al. (1980)]. The random sea surface is reduced to a simple periodic loading by estimating the equivalent number of cycles associated with each loading. As the pore pressure accumulates a liquefaction failure is predicted.

1.3.c Geotextile Literature

The geotextile literature identifies a variety of applications: highway construction, erosion control, soil stabilization, drainage and ocean engineering. However, the vast majority of the literature is related to highway engineering. In ocean engineering the first geotextile applications were in coastal protection on sand beaches [Agerschon (1961) and Crowell (1963)]. The geotextiles were placed beneath an armor layer to prevent washout of the underlying beach

sands. Cathage Mills, a major manufacturer of geotextiles, identified a variety of applications in ocean engineering including revetments, seawalls, bulkheads, groins and jetties [Barrett (1963)]. A number of coastal structures using filter fabrics are discussed by Barrett (1966) suggesting that geotextiles were becoming an integral component in many coastal construction projects. Other marine experiences with geotextiles are reported by Lee (1972), Dunham and Barrett (1974), DeMent (1978), Welsh and Koerner (1979), and Heerten (1981). Heerten also identifies a lack of technical recommendations and testing regulations for specific applications of geotextiles in marine structures. He presents a technique for selecting fabrics on the basis of permeability and soil separation. An excellent bibliography of geotextile properties and all areas of geotextile applications by J.R. Bell is given in a Transportation Research Circular (1979). This circular also identifies literature related to soil-geotextile interaction models.

Broms (1977) showed that geotextile layers in soils increase the lateral strength analytically and experimentally. Several models have been developed which indicate that geotextiles increase the bearing capacity of soils [e.g., Nieuwenhuis (1977) and Jessberger (1977)]. However, the geotextile must be very strong to perform this function. A number of finite element numerical models have been developed to analyze the states of stress in soil-geotextile systems [Al-Hussaini and Johnson (1977), Bell <u>et al.(1977)</u> and Barvashov and Fedorovsky (1977)]. The pretension in the geotextile increases stability, but this tension must be large.

Most of the soil-geotextile models are for static conditions in foundations or highway engineering. No models have been developed addressing the dynamic, marine application of this investigation.

1.3.d Relevant Literature Synopsis

The Biot consolidation equations [Biot (1941)] coupled with the storage equation [Verruijt (1969)] provide the best description of wave-induced soil response [Yamamoto (1981b)]. The inertia terms may be neglected as they have little influence except for very soft muds

[Dalrymple and Liu (1979)]. The equations presented in Yamamoto (1977) are appropriate for the present study. The coupling of the soil layers is conceptually similar to that suggested by Madsen (1978), Yamamoto and Suzuki (1980) and Yamamoto (1981a) except that the influence of the geotextile must also be considered. Rather than considering the geotextile as a fabric element as in the finite element soil-geotextile models, the fabric is modeled as a thin permeable, elastic membrane.

1.4 Geotextile Properties

The development of geotextiles and their engineering applications has occurred very rapidly within the past 15 years. Initial applications were primarily terrestrial but marine applications are becoming increasingly more common. This rapid development has led to confusion with regard to design procedures and geotextile properties. These problems are particularly apparent in the marine environment due to the limited field experience. These problems are further complicated by the large number of commercially available geotextiles.

To help remedy this situation the Federal Highway Administration awarded a contract to Hicks and Bell at Oregon State University to develop test methods and use criteria for geotextiles. In an interim report, Bell and Hicks (1980) categorize fabrics by construction method: woven, knitted, nonwoven, combinations and special. Woven geotextiles tend to have high strengths, high moduli and low strain at failure. The single strand fabrics have simple pore structures and are less susceptible to swelling in water than multiple strand fabrics. Knitted geotextiles may be constructed of either single or multiple strand fabrics. These fabrics tend to be less expensive than woven geotextiles and may be knitted into tubes or sacks. Nonwoven fabrics encompass a number of construction methods: needle punching, heat bonding and resin bonding. Nonwoven tend to be less expensive than woven geotextiles and have lower strengths. Combination fabrics are combinations of the above techniques. A typical example is a light weight needle punch in combination with a stronger woven backing or scrim. Special geotextiles include construction methods not outlined

above. An example of this type is an extruded plastic mesh.

Most geotextiles are formed from polyester or polypropylene fibers. However, the individual fabric hydraulic and mechanical properties are highly variable due to the different construction techniques. Important properties include pore size, permeability, elastic modulus, strength, friction and tear and puncture resistance. Pore size is important for determining the separation capabilities of the fabric and the potential for clogging. The geotextile permeability determines the drainage condition. In general, a drained condition is desired to allow for the release of pore water pressure. Modulus and strength indicate the stretching of the fabric and the ultimate failure. If the friction between the soil and geotextile is large, then the fabric may increase structural strength. Tear and puncture resistance are important during construction when the geotextile may be exposed to very high concentrated loads such as in the placement of riprap.

Geotextile physical properties employed in this study are permittivity, elasticity and in situ fabric tension. The permittivity is a single hydraulic fabric parameter which indicates the effectiveness of pressure transmission through the geotextile. It incorporates both the permeability and the fabric thickness.

2.0 DEFINING EQUATIONS

The physical system under consideration in this study is two horizontal layers of soil separated by a geotextile. The dynamic response of this system to ocean waves is to be modeled. The model will be used to predict states of soil stress and identify potential failure conditions as a function of wave, soil and geotextile conditions. Biot (1941) developed a set of equations describing the three-dimensional consolidation of a poro-elastic soil subjected to a time varying load. The Biot equations are used to model the dynamic response of the soil skeleton. The pore water pressure is modeled by the storage equation [Verruijt (1969)]. This system of equations provides information on soil displacements and stresses and on fluid flows and pressure.

2.1 Elastic Soil Skeleton

The Biot equations are derived by substituting stress expressed as a function of displacement through Hooke's Law into the equations of stress equilibrium. Important assumptions are that the soil is linearly elastic, that the soil inertia is small, and that the body forces are small. A short derivation of the Biot equations is presented for completeness.

The convention for identifying stresses is shown in Figure 2.1. A stress on a positive face acting in a positive direction is considered positive. A stress on a negative face acting in a negative direction is also considered positive. Therefore, the convention that tension is positive is being used. Stresses are excess values in that they are the stress levels above static conditions.

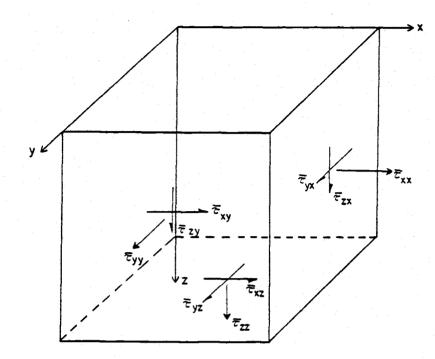


Figure 2.1. Definition sketch for the coordinate system and stress notation.

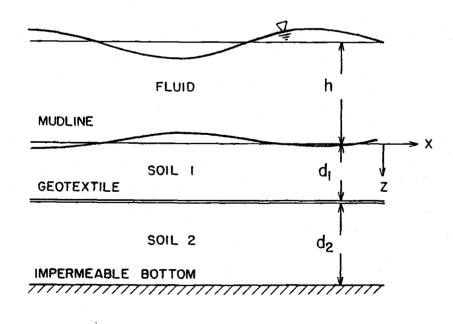


Figure 2.2. Soil layer definition sketch

The components of the total stress tensor, $\overline{\tau}_{ij},$ are denoted by

$$\tau_{ij} = \begin{bmatrix} \overline{\tau}_{xx} & \overline{\tau}_{xy} & \overline{\tau}_{xz} \\ \overline{\tau}_{yx} & \overline{\tau}_{yy} & \overline{\tau}_{yz} \\ \overline{\tau}_{zx} & \overline{\tau}_{zy} & \overline{\tau}_{zz} \end{bmatrix}$$
(2.1.1)

Columns represent surface faces and rows indicate stress directions. Assuming that the elemental volume shown in Figure 2.1 is small and that the volume is in equilibrium, taking moments about each axis yields

$$\overline{\tau}_{ij} = \overline{\tau}_{ji}$$
(2.1.2)

Since the stress tensor is symmetric, the following notation is adopted

	$\overline{\sigma}_{x} \overline{\tau}_{z} \overline{\tau}_{y}$
τ _{ij} =	$\overline{\tau}_z \ \overline{\sigma}_y \ \overline{\tau}_x$
	$\overline{\tau}_y \overline{\tau}_x \overline{\sigma}_z$

The total stress may be decomposed as

$\overline{\sigma}_{\mathbf{x}} = \sigma_{\mathbf{x}} - \mathbf{p} \tag{2}$.1.4a)
$\overline{\sigma}_{y} = \sigma_{y} - p \tag{2}$.1.4b)
$\overline{\sigma}_{z} = \sigma_{z} - p \tag{2}$.1.4c)
$\overline{\tau}_{x} = \tau_{x} $ (2)	.1.4d)
$\overline{\tau}_{y} = \tau_{y} \tag{2}$.1.4e)
$\overline{\tau}_{z} = \tau_{z} $ (2)	.1.4f)

(2.1.3)

in which σ_x, σ_y and σ_z are the x, y and z components of the effective normal stress, respectively, τ_x, τ_y and τ_z are the components of the shear stress and p is fluid pressure.

The sum of the forces in each direction is equal to the product of mass and acceleration of the elemental volume in that direction. Expanding the stresses in a Taylor series, evaluating forces as the product of the stress with the area it acts over and retaining first order terms gives the equations of stress equilibrium. If the inertia is small and body forces are separated as a static load, the dynamic equations are given by

$$\frac{\partial \sigma_{\mathbf{x}}}{\partial \mathbf{x}} + \frac{\partial \tau_{\mathbf{z}}}{\partial \mathbf{y}} + \frac{\partial \tau_{\mathbf{y}}}{\partial \mathbf{z}} = \frac{\partial p}{\partial \mathbf{x}}$$
(2.1.5a)
$$\frac{\partial \tau_{\mathbf{z}}}{\partial \mathbf{x}} + \frac{\partial \sigma_{\mathbf{y}}}{\partial \mathbf{y}} + \frac{\partial \tau_{\mathbf{x}}}{\partial \mathbf{z}} = \frac{\partial p}{\partial \mathbf{y}}$$
(2.1.5b)
$$\frac{\partial \tau_{\mathbf{y}}}{\partial \mathbf{x}} + \frac{\partial \tau_{\mathbf{x}}}{\partial \mathbf{y}} + \frac{\partial \sigma_{\mathbf{z}}}{\partial \mathbf{z}} = \frac{\partial p}{\partial \mathbf{z}}$$
(2.1.5c)

The strains in the soil are, by definition, gradients of the soil displacements. Defining ξ , χ and ζ as the components of soil displacement in the x, y, and z directions, respectively, then the strains are given as

$e_x = \frac{\partial \xi}{\partial x}$	(2.1.6a)
$e_y = \frac{\partial \chi}{\partial y}$	(2.1.6b)
$e_z = \frac{\partial \zeta}{\partial z}$	(2.1.6c)
$\gamma_{\chi} = 1/2 \left(\frac{\partial \zeta}{\partial y} + \frac{\partial \chi}{\partial z}\right)$	(2.1.6d)
$\gamma_y = 1/2 \left(\frac{\partial \zeta}{\partial x} + \frac{\partial \xi}{\partial z}\right)$	(2.1.6e)
$\gamma_z = 1/2 \left(\frac{\partial \chi}{\partial x} + \frac{\partial \xi}{\partial y}\right)$	(2.1.6f)

in which e_x , e_y and e_z are the components of normal strain and γ_x , γ_y and γ_z are the shear strains. Only the linear terms in the strain tensor have been retained which requires that the strains are small. For small

strains and displacements the soil is assumed to be linearly elastic and obey Hooke's Law. Hooke's Law relates strains to longitudinal and lateral stresses according to

$e_x = [\sigma_x - v(\sigma_y + \sigma_z)]/E$	(2.1.7a)
$\mathbf{e}_{\mathbf{y}} = [\sigma_{\mathbf{y}} - \nu(\sigma_{\mathbf{x}} + \sigma_{\mathbf{z}})]/\mathbf{E}$	(2.1.7b)
$e_z = [\sigma_z - v(\sigma_x + \sigma_y)]/E$	(2.1.7c)
$\gamma_{\rm X} = \tau_{\rm X} / (2G)$	(2.1.7d)
$\gamma_y = \tau_y / (2G)$	(2.1.7e)
$\gamma_z = \tau_z / (2G)$	(2.1.7f)

in which E is Young's modulus, G is the shear modulus and ν is Poisson's ratio. Symmetry in isotropic materials assures that normal stresses produce only normal strains [equations (2.1.7a-2.1.7c)] and that shear stresses produce only shear strains [equations (2.1.7d-2.1.7f)]. The relationship between E and G is

$$G = \frac{E}{2(\nu+1)}$$
 (2.1.8)

Hooke's Law may also be inverted to express stresses as functions of strains according to

 $\sigma_{x} = 2G(e_{x} + \frac{v\varepsilon}{1-2v})$ (2.1.9a) $\sigma_y = 2G(e_y + \frac{\nabla \varepsilon}{1 - 2\nu})$ (2.1.9b) $\sigma_{z} = 2G(e_{z} + \frac{v\varepsilon}{1-2v})$ (2.1.9c) $\tau_x = 2G\gamma_x$ (2.1.9d) $\tau_y = 2G\gamma_y$ (2.1.9e) $\tau_{\tau} = 2G\gamma_{\tau}$

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(2.1.9f)

in which

$$\varepsilon = \mathbf{e}_{\mathbf{x}} + \mathbf{e}_{\mathbf{y}} + \mathbf{e}_{\mathbf{z}} \tag{2.1.10}$$

and is termed the volume strain. Substituting the strains expressed in terms of displacements into the above form of Hooke's Law yields

$$\sigma_{x} = 2G \left[\frac{\partial \xi}{\partial x} + \frac{v}{1 - 2v} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z} \right) \right]$$
(2.1.11a)

$$\sigma_{\mathbf{y}} = 2G \left[\frac{\partial \chi}{\partial \mathbf{y}} + \frac{\nu}{1 - 2\nu} \left(\frac{\partial \xi}{\partial \mathbf{x}} + \frac{\partial \chi}{\partial \mathbf{y}} + \frac{\partial \zeta}{\partial \mathbf{z}}\right)\right]$$
(2.1.11b)

$$\sigma_{z} = 2G \left[\frac{\partial \zeta}{\partial z} + \frac{\nu}{1 - 2\nu} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z}\right)\right]$$
(2.1.11c)

$$\tau_{\mathbf{X}} = G(\frac{\partial \chi}{\partial z} + \frac{\partial \zeta}{\partial y})$$
(2.1.11d)

$$r_y = G(\frac{\partial \zeta}{\partial x} + \frac{\partial \xi}{\partial z})$$
 (2.1.11e)

$$t_{z} = G(\frac{\partial \chi}{\partial x} + \frac{\partial \chi}{\partial y})$$
(2.1.11f)

Using these relationships, the equations of equilibrium may be written in terms of the displacements

$$G\nabla^2 \xi + \frac{G}{1-2\nu} \frac{\partial}{\partial x} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z} \right) = \frac{\partial p}{\partial x}$$
 (2.1.12a)

$$G\nabla^2 \chi + \frac{G}{1-2\nu} \frac{\partial}{\partial y} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z} \right) = \frac{\partial p}{\partial y}$$
 (2.1.12b)

$$G\nabla^2 \zeta + \frac{G}{1-2\nu} \frac{\partial}{\partial z} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z} \right) = \frac{\partial p}{\partial z}$$
 (2.1.12c)

in which ∇^2 is the LaPlacian operator defined in Cartesian coordinates as

$$\nabla^{2}(\cdot) \equiv \frac{\partial^{2}(\cdot)}{\partial x^{2}} + \frac{\partial^{2}(\cdot)}{\partial y^{2}} + \frac{\partial^{2}(\cdot)}{\partial z^{2}}$$
(2.1.13)

Equations (2.1.12a), (2.1.12b) and (2.1.12c) define the response of the soil skeleton. The equation for pore pressure must now be derived.

2.2 Storage Equation

The relationship between an elemental volume change and the fluid pressure is modeled by the storage equation [Verruijt (1969)]. The porous media is assumed to consist of three components: 1) soil grains, 2) pore liquid and 3) pore gas. Properties which are related to each of these components are denoted by subscript A, B and C, respectively. The relative mass of each fraction, ψ , in a fixed volume is

$\psi_{A} = (1-n)\rho_{A}$		(2.2.la)
$\psi_{B} = nS\rho_{B}$	• • • • • • • •	(2.2.1b)
$\psi_{\rm C} = n(1-S)\rho_{\rm C}$		(2.2.1c)

in which n is the porosity, S is the degree of saturation and ρ is the density of each fraction. The time rate of change of each component of the relative mass in a fixed volume must be balanced by the mass flux of that fraction across the boundaries of the volume, i.e., each component of the relative mass must satisfy conservation of mass.

$$\frac{\partial}{\partial t} \left[(1-n)\rho_A \right] + \nabla \cdot \left[(1-n)\rho_A \vec{v}_A \right] = 0 \qquad (2.2.2a)$$

$$\frac{\partial}{\partial t} \left[n S \rho_{B} \right] + \nabla \cdot \left[n S \rho_{B} \vec{v}_{B} \right] = 0$$
 (2.2.2b)

$$\frac{\partial}{\partial t} \left[n(1-S)\rho_{\hat{C}} \right] + \nabla \cdot \left[n(1-S)\rho_{\hat{C}} \quad \vec{v}_{\hat{C}} \right] = 0$$
 (2.2.2c)

in which \vec{v} is the vector velocity of each component and $\nabla \cdot (\cdot)$ is the divergence operator.

Assuming that the grains are incompressible (not the soil skeleton) relative to the fluids, that the liquid is only slightly compressible and that the gas is ideal and obeys Boyles Law, the equations of state are given as

ρ_{A} = constant	(2.2.3a)
$\rho_{\rm B} = \rho_{\rm o} e^{\beta \rm P}$	(2.2.3b)
$\rho_{\rm C} = \rho_{\rm g} \frac{\rm p}{\rm p_{\rm g}}$	(2.2.3c)

where ρ_0 and ρ_g are reference densities, p_g is a reference pressure and β is the liquid compressibility which is a function of the degree of saturation.

If the volume of air in the water is small, then the velocity of the pore gas will be the same as the pore liquid. Employing this assumption and the equations of state, the conservation of mass equations may be written

$$\frac{\partial n}{\partial t} + \vec{v}_{A} \cdot \nabla n - (1-n) \nabla \cdot \vec{v}_{A} = 0 \qquad (2.2.4a)$$

$$\frac{1}{n} \frac{\partial n}{\partial t} + \frac{1}{S} \frac{\partial S}{\partial t} + \beta \frac{\partial p}{\partial t} + \nabla \cdot \vec{v}_{B} + \frac{\nabla(\rho_{B}Sn) \cdot \vec{v}_{B}}{\rho_{B}Sn} = 0 \qquad (2.2.4b)$$

$$\frac{1}{n} \frac{\partial n}{\partial t} - \frac{1}{(1-S)} \frac{\partial S}{\partial t} + \frac{1}{p} \frac{\partial p}{\partial t} + \nabla \cdot \vec{v}_{C} + \frac{\nabla[\rho_{C}(1-S)n] \cdot \vec{v}_{B}}{\rho_{C}(1-S)n} = 0 \qquad (2.2.4c)$$

in which $\nabla(\cdot)$ is the gradient operator. Elimination of the $\frac{\partial S}{\partial t}$ term from equations (2.2.4b) and (2.2.4c) gives

$$\frac{1}{n}\frac{\partial n}{\partial t} + \frac{1 - S + S\beta p}{p} \quad \frac{\partial p}{\partial t} + \nabla \cdot \vec{v}_{B} + (\frac{1}{n}\nabla n + \frac{1 - S + S\beta p}{p}\nabla p) \cdot \vec{v}_{B} = 0 \quad (2.2.5)$$

The fluid discharge velocity (relative to the soil) is given by Darcy's equation for small relative pore fluid velocities. Previous applications of Biot's theory to the wave-soil problem have ignored the effect of pore water acceleration in Darcy's equation. However, Sollitt and Cross (1972) and Hannoura and McCorquodale (1978) have shown this effect may be significant for unsteady flows in coarse aggregate. A more complete, but linearized, form of the equation of motion of the pore fluid is

$$(1+C_m) \frac{\partial}{\partial t} \vec{q} = -\frac{n}{\rho} \nabla p - \frac{gn}{\hat{\kappa}} \vec{q}$$
 (2.2.6)

in which C_m is an inertial coefficient, \vec{q} is the two-dimensional vector discharge velocity and \hat{K} is the steady permeability. The wave-induced flows are periodic in x and t and therefore

$$\vec{q}(x,z,t) = \vec{Q}(z) e^{i(\lambda x - \omega t)}$$
 (2.2.7)

Substituting this periodic form of the discharge velocity into equation (2.2.6) yields

$$\left[\frac{-i\omega(1+C_m)}{gn} + \frac{1}{\tilde{\kappa}}\right] \vec{q} = -\frac{1}{\rho g} \nabla p \qquad (2.2.8)$$

Defining an apparent unsteady permeability, K, as

$$\frac{1}{K} = \frac{1}{\hat{K}} - \frac{i\omega(1+C_m)}{gn}$$
(2.2.9)

the equation of motion yields an unsteady form for Darcy's equation

$$\vec{q} = -\frac{K}{\rho g} \quad \nabla p \tag{2.2.10}$$

Taking the divergence of equation (2.2.10) yields

$$\frac{\kappa}{\rho_{B}g} \nabla^{2} \mathbf{p} = - (\vec{\mathbf{v}}_{B} - \vec{\mathbf{v}}_{A}) \cdot \nabla (Sn) - Sn \nabla \cdot (\vec{\mathbf{v}}_{B} - \vec{\mathbf{v}}_{A}) + \frac{\beta \kappa}{\rho_{B}g} \nabla \mathbf{p} \cdot \nabla \mathbf{p}$$
(2.2.11)

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Eliminating $\nabla \cdot \vec{v}_B$ between equations (2.2.5) and (2.2.11) and using equation (2.2.4b) to eliminate S $\frac{\partial n}{\partial t}$ gives

$$\frac{K}{\rho_{B}g} \nabla^{2}p = S \nabla \cdot \vec{v}_{A} + Sn(\frac{1-S+S\beta p}{p}) \frac{\partial p}{\partial t} + n \vec{v}_{A} \cdot \nabla S$$

$$+ n \vec{v}_{B} \cdot [-\nabla S + S(\frac{1-S+S\beta p}{p})\nabla p] \qquad (2.2.12)$$

$$+ \frac{K\beta}{\rho_{B}g} \nabla p \cdot \nabla p$$

It has been assumed that the volume of air in the water is small and therefore, $S \approx 1$. Since pure water is nearly incompressible, $p\beta <<1$. It has also been assumed that the soil skeleton deformations are small and second order terms were neglected. Adhering to the same order of approximation, second order terms are also neglected in the storage equation. Equation (2.2.12), for these assumptions, is

$$\frac{K}{\rho_{\rm B}g} \nabla^2 p = \nabla \cdot \vec{v}_{\rm A} + n\beta' \frac{\partial p}{\partial t}$$
(2.2.13)

in which

$$\beta' = \beta + \frac{1-S}{p}$$
 (2.2.14)

For wave-induced pressure fluctuations in soils the pressure in equation (2.2.14) may be approximated by the absolute static pressure, P_S . The combined air-water compressibility, β' , is given by

$$\beta' = \frac{1}{K_W} + \frac{1-S}{P_S}$$
(2.2.15)

in which K_W is the bulk modulus of elasticity of pure water. Noting that the divergence of \vec{v}_A is equivalent to the time rate of change of ε , the final form of the storage equation is

$$\frac{K}{\gamma} \nabla^2 p = \frac{\partial}{\partial t} \left(\frac{\partial \xi}{\partial x} + \frac{\partial \chi}{\partial y} + \frac{\partial \zeta}{\partial z} \right) + n\beta' \frac{\partial p}{\partial t}$$
(2.2.16)

in which γ is the weight of density of the fluid, not to be confused with the shear strains, γ_x , γ_y and γ_z , in equations (2.1.7d-2.1.7f). The first term in equation (2.2.16) models the pressure response in a rigid soil matrix, the second term accounts for the soil matrix deformation and the third term includes the pore fluid compressibility.

2.3 Boundary Conditions

In two dimensions the Biot consolidation equations are second order in three variables: ξ , ζ and p. If a simple harmonic solution is required in x and t, then six boundary conditions are required for the z dependence in each soil layer. For two soil layers separated by a geotextile, as shown in Figure 2.2, 12 boundary conditions are required; three at the mudline, three at the impermeable bottom and six at the geotextile.

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2.3.a Mudline Boundary Conditions

At the mudline the pore fluid pressure is matched with the dynamic component of the wave-induced pressure. The dynamic pressure is periodic in the direction of wave propagation, x, and in time, t. The pressure boundary condition is given by

$$p_1(x,0,t) = p_0 e^{i(\lambda x - \omega t)}$$
 (2.3.a.1)

in which i is the square root of -1, λ is the wave number, ω is the radian wave frequency and p_0 is the amplitude of the wave-induced bottom pressure. Subscripts 1 and 2 denote values in the upper and lower soil layers, respectively. The component of pressure due to the elevation changes of the mudline are very small and are therefore neglected.

Also at the mudline, the vertical component of effective stress vanishes

$$\sigma_{z1} (x,0,t) = 0 \tag{2.3.a.2}$$

and the horizontal shear stress on the bottom due to flow in the fluid layer is balanced by the shear stress in the soil. The shear stress is conventionally expressed proportional to the velocity squared, however, using Lorentz principle of equivalent work [Lorentz (1926)], a linear stress which dissipates the same amount of energy per wave period is given by

$$\tau_1(x,0,t) = \frac{8}{3\pi} \rho C_D u_0^2 e^{i(\lambda x - \omega t)}$$
(2.3.a.3)

in which π is a numerical constant, C_D is a drag coefficient of order 0.01, ρ is the fluid density and u_0 is the amplitude of the near bottom horizontal velocity. As with the pore pressure, stresses associated with the small displacement of the mudline are small and are neglected.

2.3.b Geotextile Boundary Conditions

Geotextiles usually have rough surfaces or pores which provide a no-slip surface between the fabric and the soil. Also, the fabric is thin so that no gradients in fabric extension occur across the thickness of the fabric. Therefore, the horizontal and vertical components of displacement are matched across the geotextile.

$$\xi_1(x,d_1,t) = \xi_2(x,d_1,t)$$
 (2.3.b.1a)
 $\zeta_1(x,d_1,t) = \zeta_2(x,d_1,t)$ (2.3.b.1b)

Both the mechanical and the hydraulic behavior of the geotextile must be determined to quantify its effect on the adjacent soil layers. The mechanical behavior of the geotextile may be idealized as a membrane in tension. For the two-dimensional Biot problem, the state of stress in the geotextile is described by the one-dimensional wave equation [Hildebrand (1964)]

$$\hat{T} \frac{\partial^2}{\partial x^2} \mu + (\frac{\partial}{\partial x} \hat{T}) (\frac{\partial}{\partial x} \mu) + f = 0$$
 (2.3.b.2)

in which T is the tension per unit width in the geotextile, μ is the vertical geotextile displacement and f is the normal stress. The second term in equation (2.3.b.2) is negligible if the horizontal gradients are small. As an alternative, the gradient of the tension may be approximated by a spring constant, K_S. The normal stress on the geotextile is the result of the total vertical stresses in the adjacent soil layers. The vertical displacements of the soil layers are continuous across the geotextile and therefore equal to the fabric displacement. Balancing vertical forces across the geotextile, equation (2.3.b.2) may be written

$$(1-n_{1}) \sigma_{z1}(x,d_{1},t) + n_{1}p_{1}(x,d_{1},t) = (1-n_{2}) \sigma_{z2}(x,d_{1},t) + n_{2}p_{2}(x,d_{1},t) + (\hat{T} \frac{\partial^{2}}{\partial x^{2}} + K_{S} \frac{\partial}{\partial x}) \zeta_{2}(x,d_{1},t)$$
(2.3.b.3)

The elasticity of the geotextile also resists horizontal displacement. Balancing horizontal forces across the geotextile yields

$$\tau_1(x,d_1,t) = \tau_2(x,d_1,t) + K_S \frac{\partial}{\partial x} \xi_2(x,d_1,t) \qquad (2.3.b.4)$$

The volume of water for thin fabrics in the pore spaces of the geotextile remains approximately constant. Therefore, by conservation of mass, the vertical volume flow of water must match across the fabric. From Darcy's equation

$$\frac{\partial}{\partial z} p_1(x,d_1,t) = \frac{K_2}{K_1} \frac{\partial}{\partial z} p_2(x,d_1,t) \qquad (2.3.b.5)$$

in which K_1 and K_2 are the permeabilities of soil layers 1 and 2, respectively.

The hydraulic behavior of the geotextile is characterized by the fluid energy dissipated in the flow through the fabric. From the energy equation, the pressure drop across the geotextile is due to a head loss in the geotextile. An estimate of this pressure drop is obtained from Darcy's equation and conservation of mass between the fabric and the lower soil layer

$$\frac{K_{f}}{\gamma} \frac{\Delta p}{\Delta z_{f}} = \frac{K_{2}}{\gamma} \frac{\partial}{\partial z} p_{2}(x,d_{1},t) \qquad (2.3.b.6)$$

in which K_f is the fabric permeability, Δp is the pressure drop across the fabric and Δz_f is the fabric thickness. Defining the permittivity C_p , as

$$C_{\ell} = \frac{\Delta z_{f}}{K_{f}}$$
(2.3.b.7)

the energy equation across the fabric yields

$$p_1(x,d_1,t) = p_2(x,d_1,t) - C_{\ell}K_2 \frac{\partial}{\partial z} p_2(x,d_1,t)$$
 (2.3.b.8)

2.3.c Impermeable Bottom Boundary Conditions

At the rigid impermeable bottom there is no vertical flow of pore fluid.

$$\frac{\partial}{\partial z} p_2(x, d_1 + d_2, t) = 0$$
 (2.3.c.1)

Also at this boundary there is no vertical displacement.

$$\zeta_2(x,d_1+d_2,t) = 0$$
 (2.3.c.2)

The impermeable bottom may be clay or rock in the field or wood or concrete in the laboratory. For field conditions, due to the interlocking between the soil grains and the bottom, a no horizontal displacement boundary condition may be appropriate. However, for smooth bottom surfaces in the laboratory a limited amount of slip may occur. Therefore, a boundary condition which will allow for partial slip is employed.

$$\alpha[\xi_{2}(x,d_{1}+d_{2},t] + (1-\alpha)(d_{1}+d_{2}) \frac{\partial}{\partial z} [\xi_{2}(x,d_{1}+d_{2},t)] = 0 \qquad (2.3.c.3)$$

This allows for the full range of slip conditions as a function of the constant, $\boldsymbol{\alpha}.$

$\alpha = 0$	free slip	(2.3.c.4a)
0 < α < 1	partial slip	(2.3.c.4b)
$\alpha = 1$	no slip	(2.3.c.4c)

The gradient term, with $\alpha = 0$, assures that the free slip boundary condition is allowed to penetrate to the full depth of the bottom layer.

3.0 SOLUTIONS TO THE BIOT EQUATIONS

The Biot consolidation equations provide a very general description of dynamic soil response. It

is of interest to note that a number of simplified methods developed for analyzing pore pressure response in marine soils are based on reduced forms of the Biot equations. An examination of the "unseen" assumptions in the aforementioned methods provides insight into their range of validity or application. Two such examples, the earthquake consolidation equation and the potential pressure model, are examined before developing solutions to the full set of Biot equations.

3.1 Earthquake Consolidation Equation Model

The solutions developed by Yamamoto (1977) and others (see Table 1.1) for the Biot consolidation equations are strictly periodic in time. However, it has been observed that soils subjected to simple periodic cyclic loading may not respond in a strictly periodic sense. The mean excess pore water pressure in a loose saturated silt or fine sand may increase with the number of cyclic loads [Seed and Lee (1966), Seed et al. (1978)].

These soils exhibit a tendency for volume reduction when cyclically loaded. As the volume decreases, the excess pore water pressure increases. If the accumulation of pore pressure per cycle of loading exceeds the dissipation by drainage a net accumulation results. The pore pressure may increase to the point that most of the overburden is carried by the fluid and grain effective stress is very small. Since water is incapable of supporting substantial shear stresses, an increase in the applied load may result in a soil failure. Such a failure has been termed liquefaction because the soil behaves as a liquid. Liquefaction due to cyclic earthquake loading has been well documented [Seed and Idriss (1967)]. This problem has been analyzed by earthquake engineers using a modified form of Terzaghi's one-dimensional consolidation equation [Terzaghi and Peck (1967)]. More recently this technique has been applied to model the response of marine soils due to the cyclic loading of water waves [Finn, <u>et al</u>. (1977), Rahman, <u>et al</u>. (1977), Seed Rahman (1978), Finn, <u>et al</u>. (1980)]. The derivation of the consolidation equation is not based on the Biot equations and the resulting boundary value problem is solved numerically although for simple cases analytic solutions are possible.

The three-dimensional Biot consolidation equations were derived in Chapter 2. The earthquake consolidation equation may be derived from equations (2.1.39), (2.1.40), (2.1.41) and (2.2.12) by seeking a one-dimensional solution. That is, all gradients with respect to the x and y coordinate directions are assumed to be zero. The resulting equations are

$$G \frac{2-2\nu}{1-2\nu} \frac{\partial^2 \zeta}{\partial z^2} = \frac{\partial p}{\partial z}$$
(3.1.1a)

$$\frac{K}{\gamma} \frac{\partial^2 p}{\partial z^2} = \frac{\partial^2 \zeta}{\partial z \partial t} + n \beta' \frac{\partial p}{\partial t}$$
(3.1.1b)

Differentiating equation (3.1.1a) with respect to t and equation (3.1.1b) with respect to z and eliminating ζ from equation (3.1.1b) yields

$$\frac{\partial^2 \mathbf{p}}{\partial z \partial t} = c \frac{\partial^3 \mathbf{p}}{\partial z^3}$$
(3.1.2)

in which

$$c = \frac{GK}{\gamma} \frac{(2-2\nu)}{(1-2\nu) + (2-2\nu)n\beta'G}$$
(3.1.3)

and is termed the coefficient of consolidation. Integrating with respect to z yields the earthquake consolidation equation

$$\frac{\partial p}{\partial t} = c \frac{\partial^2 p}{\partial z^2} + s \qquad (3.1.4)$$

in which s is an integration constant in z, functioning as a pore pressure source term and may be time dependent. However, for generality (and

because of the form of the source term used by earthquake engineers) s will be considered a function of time and depth in each soil layer. The pressure is composed of a fluctuating component (in time) and a mean drift component. The mean drift or pore pressure accumulation may be more clearly examined by removing the fluctuating component by time averaging over one wave period. The mean pore pressure accumulation, \overline{p} , is given by

$$\overline{p} = \frac{1}{T} \int_{t}^{t+T} pdt \qquad (3.1.5)$$

The boundary value problem for the pore pressure accumulation for a homogenous soil of thickness, d, over an impermeable bed material is given by

- $\frac{\partial \overline{p}}{\partial t} = c \frac{\partial^2 \overline{p}}{\partial z^2} + s \qquad (3.1.6a)$
- $\overline{p}(0,t) = 0$ (3.1.6b)
- $\frac{\partial}{\partial z} \overline{p} (d, z) = 0$ (3.1.6c)

$$\overline{p}(z,0) = f(z)$$
 (3.1.6d)

in which f(z) is the initial vertical profile of the pore water pressure. The pore pressure at the mudline time-averages out. Therefore, the pore pressure is only driven by the source term. An eigenseries solution to this problem obtained by separation of variables and application of the boundary conditions is given by

$$p = \sum_{n=1}^{\infty} \frac{2}{d} e^{-c\kappa_n^2 t} \{ \int_{0}^{t} e^{c\kappa_n^2 \tau} [\int_{0}^{d} s(z,t) \sin(\kappa_n z) dz] d\tau \}$$

$$x \sin(\kappa_n z) \qquad (3.1.7)$$

in which the eigenvalues are given by

$$\kappa_n = \frac{2n-1}{2} \frac{\pi}{d}$$
 (3.1.8)

This solution applies for an arbitrary pore water pressure source term. For the solution to be physically meaningful an analytic expression for the source term must be determined. The laboratory results of De Alba, Chan and Seed (1975) relate the development of pore water pressure to the number of load cycles in simple shear. This relationship is given by

$$\frac{p_{g}}{\sigma_{0}^{\prime}} = \frac{1}{2} + \frac{1}{\pi} \sin^{-1} \left[2\left(\frac{N}{N_{\ell}}\right)^{1/\alpha} - 1\right]$$
(3.1.9)

in which \overline{p}_{g} is the pore water pressure generated due to the cyclic loading, σ'_{0} is the effective overburden stress corresponding to static conditions, N is the number of cyclic loadings, N_L is the number of cycles to liquefaction, and α is a shape factor. This family of curves is shown in Figure 3.1 as a function of α . Seed, <u>et al.</u> (1975) suggest using a value of $\alpha = 0.7$ for which there is a somewhat linear relationship between the pore pressure ratio $\overline{p}_{g}/\sigma'_{0}$ and the cyclic ratio N/N_L (the dashed line in Figure 3.1). For a linear relationship

$$\overline{p}_{g} = \sigma_{0}' \frac{N}{N_{\ell}}$$
(3.1.10)

The pore pressure source term in equation (3.1.6a) is given by Seed, et al. (1974) as

$$s = \frac{\partial}{\partial t} \left(\sigma'_{0} \frac{N}{N_{\ell}} \right)$$
(3.1.11)

The effective overburden stress is

$$\sigma_0' = \gamma_B z'$$
 (3.1.12)

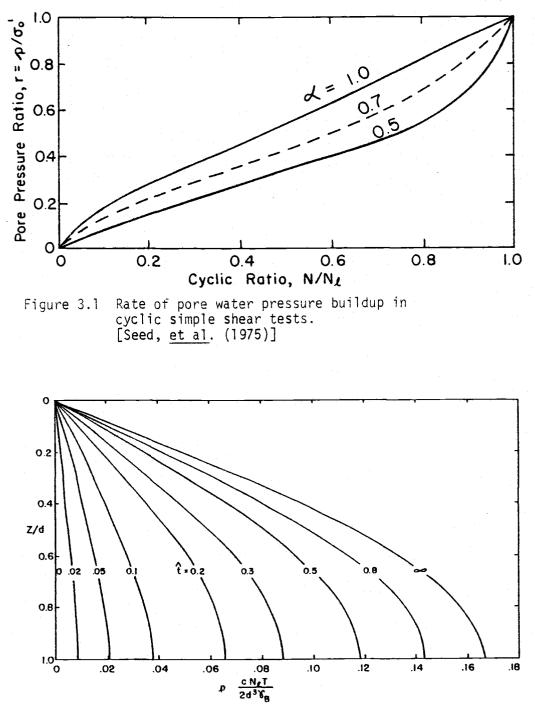


Figure 3.2 Dimensionless pore water pressure accumulation profiles.

31.

and the cyclic ratio as a continuous function of time is given by

$$\frac{N}{N_{\rho}} = \frac{t}{N_{\rho}T}$$
(3.1.13)

in which t is time and T is the wave period. Therefore, the pore pressure source term is given by

$$s = \frac{\gamma_B}{N_{\ell}T} z \qquad (3.1.14)$$

For this source term, the solution to the earthquake consolidation equation given by equation (3.1.7) is

$$\overline{p} = \sum_{n=1}^{\infty} - \frac{(-1)^n}{\kappa_n} \frac{2\gamma_B}{cdN_\ell T} (1 - e^{-c\kappa_n^2 t}) \sin(\kappa_n z)$$
(3.1.15)

It is convenient to express the pressure in a dimensionless form by introducing the following variables

> $\hat{z} = z/d$ (3.1.16a) $\hat{t} = t(c/d^{2})$ (3.1.16b) $\hat{\kappa}_{n} = \frac{2n-1}{2} \pi$ (3.1.16c) $\hat{p} = \overline{p} \quad \frac{cN_{\ell}T}{2d^{3}\gamma_{B}}$ (3.1.16d)

A dimensionless solution, which applies for all soils and wave conditions, is

$$\hat{p} = \sum_{n=1}^{\infty} - \frac{(-1)}{\hat{\kappa}_n^4} (1 - e^{-\hat{\kappa}_n^2} \hat{t}) \sin(\hat{\kappa}_n \hat{z})$$
(3.1.17)

Dimensionless vertical pressure profiles are shown in Figure 3.2 as a function of dimensionless time. These profiles apply for all soils that have a tendency for volume reduction and pore pressure accumulation when cyclically loaded. The pressure scaling term in equation (3.1.16d) contains fluid properties, flow properties, static and dynamic soil properties, geometric and wave properties.

The one-dimensional earthquake consolidation equation provides information on the accumulation of pore pressure not revealed by other solutions of the Biot equations. However, by itself this approach may not provide adequate pore water pressure information to predict failure. Specifically, if the periodic pore pressure amplitude is large a failure would be observed before the accumulated pressure reaches a failure level. This type of failure is shown in Figure 3.3. Instantaneous or momentary failures occur before the mean drift failure. Even for rapid pore pressure accumulation, complete failure may be preceded by momentary failures associated with the periodic component of pore water pressure. If design estimates are based only on the earthquake consolidation equation, failure may be observed in the field before the predicted number of cycles.

This failure mechanism suggests a coupling of the earthquake consolidation equation to determine mean pore pressure accumulation with the two-dimensional periodic solutions to the Biot equations for the cyclic pore pressure. Such a model is an anticipated extension of the present study.

3.2 Potential Pressure Model

Moshagen and Torum (1975) developed a two-dimensional heat equation for modeling wave-induced pressures in marine soils. This equation is a simplified form of the Biot equations for compressible pore fluid but an incompressible or rigid soil skeleton. The resulting equation is

$$\frac{K}{\gamma} \nabla^2 p = n\beta' \frac{\partial p}{\partial t}$$
(3.2.1)

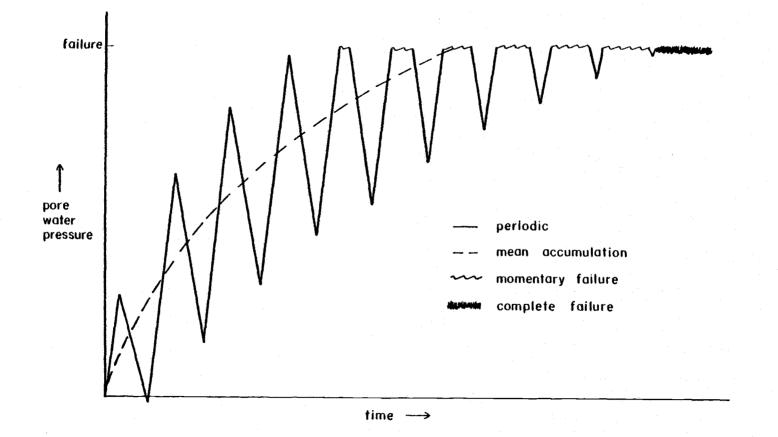


Figure 3.3 Idealized wave-induced soil failure due to periodic and mean accumulation of pore water pressure.

The assumption that the fluid is more compressible than the skeleton is physically unrealistic for most saturated marine soils [Prevost, Eide and Anderson (1975)]. A more physically consistent assumption is that the pore fluid is also incompressible. This yields the potential pressure model.

$$\nabla^2 \mathbf{p} = \mathbf{0} \tag{3.2.2}$$

A number of investigators have examined soil response to waves by assuming that the field equation for pressure is LaPlace's equation [cf. Putnam (1974), Reid and Kajura (1957), Hunt (1959), Murray (1965) Liu (1973), Dalrymple (1974), McClain, <u>et al.</u> (1977), Puri (1980)]. The most common derivation of this relationship is from Darcy's equations for horizontal and vertical flow.

$$u = -\frac{K}{\gamma} \frac{\partial p}{\partial x}$$
(3.2.3a)
$$w = -\frac{K}{\gamma} \frac{\partial p}{\partial z}$$
(3.2.3b)

Taking the derivative of equation (3.2.3a) with respect to x and the derivative of equation (3.2.3b) with respect to z and adding, for a homogeneous soil and assuming continuity, yields

 $\nabla^2 \mathbf{p} = \mathbf{0} \tag{3.2.4}$

It is interesting to note that the equation for the pressure is independent of the soil properties. Relative soil properties are introduced through the boundary conditions.

The boundary conditions for pressure for a three layered system, two soils separated by a geotextile, as shown in Figure 2.2, are given by equations (2.3a.1), (2.3b.3), (2.3b.6) and 2.3c.1). They correspond to pressure matching at the mudline, fluid continuity and a pressure head loss at the geotextile and a no flow bottom boundary condition, respectively. For these boundary conditions, a solution obtained by separation of variables to equation (3.2.4) is

$$p_1 = p_0 [ch (\lambda z) + R2 sh (\lambda z)] e^{i(\lambda x - \omega t)}$$
 (3.2.5a)

$$p_2 = p_0 \frac{\kappa_1}{\kappa_2} R1[1+R2 th (\lambda d_1)][ch (\lambda z)-th(\lambda \overline{d})sh(\lambda z)]e^{i(\lambda x-\omega t)}$$
(3.2.5b)

in which

$$R1 = \frac{K_2}{K_1} \left[1 - th(\lambda d_1) th(\lambda \overline{d}) + R3 \right]^{-1}$$
(3.2.6a)

$$R2 = \frac{R1[th(\lambda d_1) - th(\lambda \overline{d})] - th(\lambda d_1)}{1 - R1th(\lambda d_1)[th(\lambda d_1) - th(\lambda \overline{d})]}$$
(3.2.6b)

$$R3 = K_2 C_{\ell} [th(\lambda d_1) - th(\lambda \overline{d})] \lambda \qquad (3.2.6c)$$

$$\vec{d} = d_1 + d_2$$
 (3.2.6d)

and p_1 is the pore pressure in soil layer 1 and p_2 is the pore pressure in layer 2. Vertical profiles of the pressure amplitude are shown in Figure 3.4 for a test condition of one foot of pea gravel above three feet of silt separated by a very permeable fabric. This configuration approximately corresponds to the laboratory conditions for several of the experiments. Stream function [Dean (1974)] wave cases 5B, 7B and 8B for a water depth of eight feet are shown. The wave heights and periods for these wave cases are summarized in Table 4.4. Figure 3.4 indicates that the decay of pressure response with depth is exponential [in accordance with equations (3.2.5a) and (3.2.5b)] and that the shorter wave lengths are more highly damped.

The potential pressure model provides reasonable estimates of pore pressure for sands [Liu (personal communication)] which are relatively permeable and stiff. However, no information on the phase shift with depth is obtained from this solution.

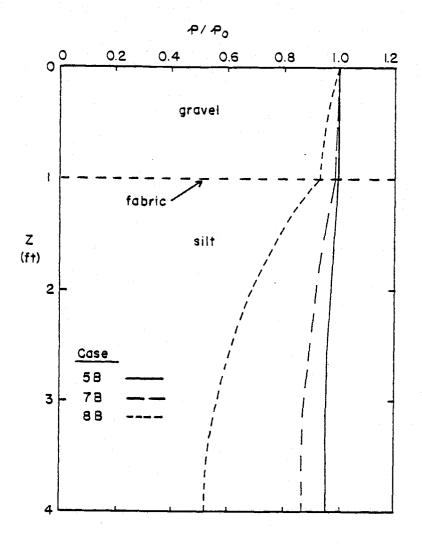


Figure 3.4 Vertical pore water pressure profiles from the potential pressure model for stream function wave cases 5B, 7B and 8B.

3.3 Periodic, Two-Dimensional Biot Model

The most general analytic solutions to the Biot equations for wave-induced marine soil response have considered a periodic, twodimensional case [eg. Yamamoto (1977)]. If the solution is assumed to be periodic in x and t, with the same frequencies as the wave, the Biot equations (2.1.12a), (2.1.12c) and (2.2.16) reduce to the matrix form

$$\begin{pmatrix} (D^2 - \frac{2-2\nu}{1-2\nu} \lambda^2) & (\frac{i\lambda}{1-2\nu} D) & (-i\frac{\lambda}{G}) \\ (\frac{i\lambda}{2-2\nu} D) & (D^2 - \frac{1-2\nu}{2-2\nu} \lambda^2) & (-\frac{1}{G} \frac{1-2\nu}{2-2\nu} D) \\ (-\frac{\gamma}{K} \lambda \omega) & (i\frac{\gamma}{K} \omega D) & [D^2 + (i\frac{\gamma}{K} \omega n\beta' \lambda^2)] \\ \end{pmatrix}$$

in which

$$D(\cdot) \equiv \frac{d}{dz} (\cdot)$$
 (3.3.2)

The existence of a non-trivial solution requires that the determinant of the coefficient matrix vanish [Wylie (1975)]. The eigenvalues corresponding to the roots are

$$\lambda_{1} = \pm \lambda \qquad (3.3.3a)$$

$$\lambda_{2} = \pm \lambda \qquad (3.3.3b)$$

$$\lambda_{3} = \pm \lambda^{\prime} = \left[\lambda^{2} - i \frac{\gamma}{K} \quad \frac{\omega}{G} \left(n\beta^{\prime}G + \frac{1-2\nu}{2-2\nu}\right)\right]^{1/2} \qquad (3.3.3c)$$

With the eigenvalues known, general solutions for horizontal displacement, vertical displacement and pressure in the two soil layers are

$$\xi_{1} = [a_{1} \operatorname{ch}(\lambda z) + a_{2} \operatorname{sh}(\lambda z) + a_{3} z \operatorname{ch}(\lambda z) + a_{4} z \operatorname{sh}(\lambda z) + a_{5} \operatorname{ch}(\lambda'_{1} z)$$

$$+ a_{6} \operatorname{sh}(\lambda'_{1} z)]e^{i(\lambda x - \omega t)} \qquad (3.3.4a)$$

$$z_{1} = [b_{1} \operatorname{ch}(\lambda z) + b_{2} \operatorname{sh}(\lambda z) + b_{3} z \operatorname{ch}(\lambda z) + b_{4} z \operatorname{sh}(\lambda z) + b_{5} \operatorname{ch}(\lambda' z)$$

+ $b_{6} \operatorname{sh}(\lambda' z)]e^{i(\lambda x - \omega t)}$ (3.3.4b)

$$p_{1} = [c_{1} ch(\lambda z) + c_{2} sh(\lambda z) + c_{3} z ch(\lambda z) + c_{4} z sh(\lambda z) + c_{5} ch(\lambda'_{1} z)$$
$$+ c_{6} sh(\lambda'_{1} z)]e^{i(\lambda x - \omega t)}$$
(3.3.4c)

$$\xi_{2} = [a_{7} ch(\lambda z) + a_{8} sh(\lambda z) + a_{9} z ch(\lambda z) + a_{10} z sh(\lambda z) + a_{11} ch(\lambda z' z) + a_{12} sh(\lambda z' z)]e^{i(\lambda x - \omega t)}$$
(3.3.4d)

$$\zeta_{2} = [b_{7} \operatorname{ch}(\lambda z) + b_{8} \operatorname{sh}(\lambda z) + b_{9} z \operatorname{ch}(\lambda z) + b_{10} z \operatorname{sh}(\lambda z) + b_{11} \operatorname{ch}(\lambda z' z) + b_{12} \operatorname{sh}(\lambda z' z)]e^{i(\lambda x - \omega t)}$$
(3.3.4e)

$$p_{2} = [c_{7} ch(\lambda z) + c_{8} sh(\lambda z) + c_{9} z ch(\lambda z) + c_{10} z sh(\lambda z) + c_{11} ch(\lambda z' z) + c_{12} sh(\lambda z' z)]e^{i(\lambda z - \omega t)}$$
(3.3.4f)

in which the subscripts on $\xi,\ \zeta$ and p refer to the soil layer.

There are 36 integration constants but only 12 boundary conditions (see section 2.3). This suggests that 24 of the constants are not independent. This dependency may be determined by substituting the general solutions into the governing equations (3.3.1) and collecting

like terms in $ch(\lambda z)$, $sh(\lambda z)$, etc. The resulting system of equations can be solved to yield the vertical displacement and pressure integration constants as functions of the horizontal displacement constants. These relationships are

 $b_1 = -ia_2 + iAl a_3$ (3.3.5a)

 $b_2 = -ia_1 + iA1 a_4$ (3.3.5b)

- $b_3 = -i a_4$ (3.3.5c)
- $b_4 = -i a_3$ (3.3.5d)
- $b_5 = -i \frac{\lambda' 1}{\lambda} a_6$ (3.3.5e)
- $b_6 = -i \frac{\lambda' 1}{\lambda} a_5 \qquad (3.3.5f)$
- $b_7 = -i a_8 + iBl a_{11}$ (3.3.5g)
- $b_8 = -i a_7 + iB1 a_{10}$ (3.3.5h)
- $b_g = -i a_{10}$ (3.3.5i)
- $b_{10} = -i a_9$ (3.3.5j)
- $b_{11} = -i \frac{\lambda' 2}{\lambda} a_{12} \qquad (3.3.5k)$
- $b_{12} = -i \frac{\lambda' 2}{\lambda} a_{11}$ (3.3.51)
- $c_1 = -i A2 a_4$ (3.3.5m)
- $c_2 = -i \ A2 \ a_3$ (3.3.5n) $c_3 = 0$ (3.3.5o)

	c = 0		41
	c ₄ = 0		(3.3.5p)
	$c_5 = -A3 a_5$		(3.3.5q)
	$c_6 = -A3 a_6$		(3.3.5r)
	c ₇ = -i B2 a ₁₀		(3.3.5s)
	c ₈ = −i B2 a ₉		(3.3.5t)
	c ₉ = 0		(3.3.5u)
	c ₁₀ = 0		(3.3.5v)
	$c_{11} = -B3 a_{11}$		(3.3.5w)
	$c_{12} = -B3 a_{12}$		(3.3.5x)
in which	A1 = $\frac{1}{\lambda}$ $\frac{1+C1}{1+C1}$ $(3-4v_1)$		(3.3.6a)
	$A2 = \frac{2G_1}{1+C1}$		(3.3.6b)
	A3 = $\frac{\gamma}{K_1} = \frac{\omega}{\lambda} [1+C1(2-2v_1)]$]	(3.3.6c)
	$C1 = \frac{n_{1\beta}' 1^{G_{1}}}{1 - 2\nu_{1}}$		(3.3.6d)
	B1 = $\frac{1}{\lambda}$ $\frac{1+C2(3-4v_2)}{1+C2}$		(3.3.6e)
	$B2 = \frac{2G_2}{1+C2}$		(3.3.6f)

B3 =
$$\frac{\lambda}{K_2} \frac{\omega}{\lambda} [1+C2(2-2\nu_2)]$$
 (3.3.6g)
C2 = $\frac{n_2 \beta_2' G_2}{1-2\nu_2}$ (3.3.6h)

and the subscripts on v, G, K, n and β refer to the soil layer. The 12 boundary conditions are now imposed to determine the remaining 12 unknown horizontal displacement integration constants. The resulting system of 12 simultaneous equations is solved numerically.

$$-i A2 a_4 - A3 a_5 = p_0$$
 (3.3.7a)

$$a_1 + \frac{(1-\nu_1)(1-\lambda A1)}{\lambda(1-2\nu_1)} a_4 + \frac{(1-\nu_1)\lambda'_1^2 - \nu_1\lambda^2}{\lambda^2(1-2\nu_1)} a_5 = 0$$
 (3.3.7b)

$$2\lambda a_2 + (1 - \lambda A_1) a_3 + 2\lambda'_1 a_6 = \frac{1}{G_1} \frac{8}{3\pi} \rho c_f u_0^2$$
 (3.3.7c)

$$a_{1} + th(\lambda d_{1}) a_{2} + d_{1} a_{3} + d_{1} th(\lambda d_{1}) a_{4} + \frac{ch(\lambda'_{1}d_{1})}{ch(\lambda d_{1})} a_{5}$$

$$+ \frac{sh(\lambda'_{1}d_{1})}{ch(\lambda d_{1})} a_{6} - a_{7} - th(\lambda d_{1})a_{8} \qquad (3.3.7d)$$

$$- d_{1} a_{9} + d_{1} th(\lambda d_{1}) a_{10} - \frac{ch(\lambda'_{2}d_{1})}{ch(\lambda d_{1})} a_{11}$$

$$- \frac{sh(\lambda'_{2}d_{1})}{ch(\lambda d_{1})} a_{12} = 0$$

$$th(\lambda d_{1}) a_{1} + a_{2} + [d_{1} th(\lambda d_{1}) - AI] a_{3} + [d_{1} - AI th(\lambda d_{1})] a_{4}$$

$$+ \frac{\lambda'}{\lambda} \frac{sh(\lambda' d_{1})}{ch(\lambda d_{1})} a_{5} + \frac{\lambda'}{\lambda} \frac{ch(\lambda' d_{1})}{ch(\lambda d_{1})} a_{6}$$

$$- th(\lambda d_{1}) a_{7} - a_{8} - [d_{1} th \lambda d_{1} - BI] a_{9} \qquad (3.3.7e)$$

$$- [d_{1} - B_{1} th(\lambda d_{1})] a_{10} - \frac{\lambda'}{\lambda} \frac{sh(\lambda' 2d_{1})}{ch(d_{1})} a_{11}$$

$$- \frac{\lambda'}{\lambda} \frac{ch(\lambda' 2d_{1})}{ch(\lambda d_{2})} a_{12} = 0$$

$$-a_{1} - th(\lambda d_{1}) a_{2} + \{ \frac{1-\nu_{1}}{1-2\nu_{1}} (A1 - \frac{1}{\lambda}) th(\lambda d_{1}) - d_{1} \} - \frac{n_{1}A_{2}th(\lambda d_{1})}{2\lambda G_{1}(1-n_{1})} a_{3}$$

+ {[
$$\frac{1-v_1}{1-2v_1}$$
 (A1- $\frac{1}{\lambda}$) - d₁ th(λ d₁)] - $\frac{n_1A_2}{2\lambda G_1(1-n_1)}$ a₄

+
$$\left[\frac{\nu_{1}\lambda^{2}-(1-\nu_{1})\lambda'_{1}}{\lambda^{2}(1-2\nu_{1})}-\frac{n_{1}A_{3}}{i2\lambda G_{1}(1-n_{1})}\right]\frac{ch(\lambda'_{1}d_{1})}{ch(\lambda d_{1})}a_{5}+$$

+
$$\left[\frac{\nu_1 \lambda^2 - (1 - \nu_1) \lambda'_1^2}{\lambda^2 (1 - 2\nu_1)} - \frac{n_1 A_3}{i2\lambda G_1 (1 - n_1)}\right] \frac{sh(\lambda'_1 d_1)}{ch(\lambda d_1)} a_6$$
 (3.3.7f)

$$\begin{aligned} &+\left[\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} + \overline{\Phi} \ th(\lambda d_{1})\right]a_{7} + \left[\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \ th\lambda d_{1} + \overline{\Phi}\right]a_{8} \end{aligned} \tag{3.3.7f} \\ &= \left(\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \left[\frac{1-\nu_{2}}{1-2\nu_{2}} \left(B1 - \frac{1}{\lambda}\right) \ th(\lambda d_{1}) - d_{1}\right] - \frac{n_{2}B_{2}}{2\lambda G_{1}} \ th(\lambda d_{1}) \\ &+ \left[\overline{\Phi}B1 - \overline{\Phi}d_{1} \ th(\lambda d_{1})\right] a_{9} \end{aligned} \\ &= \left(\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \left[\frac{1-\nu_{2}}{1-2\nu_{2}} \left(B1 - \frac{1}{\lambda}\right) - d_{1} \ th(\lambda d_{1})\right] - \frac{n_{2}B_{2}}{2\lambda G_{1} \left(1-n_{1}\right)} \end{aligned} \\ &+ \left[\overline{\Phi}B1 - \overline{\Phi}d_{1} \ th(\lambda d_{1})\right] a_{9} \end{aligned} \\ &= \left(\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \left[\frac{1-\nu_{2}}{1-2\nu_{2}} \left(B1 - \frac{1}{\lambda}\right) - d_{1} \ th(\lambda d_{1})\right] - \frac{n_{2}B_{2}}{2\lambda G_{1} \left(1-n_{1}\right)} \end{aligned} \\ &+ \left[\overline{\Phi}B1 \ th(\lambda d_{1}) - d_{1}\overline{\Phi}\right]\right) a_{10} \\ &- \left[\left(\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \quad \frac{\nu_{2}\lambda^{2} - \left(1-\nu_{2}\right)\lambda^{2} \frac{2}{2}}{\lambda^{2} \left(1-2\nu_{2}\right)} - \frac{n_{2}B_{3}}{12\lambda G_{1} \left(1-n_{1}\right)}\right] \frac{ch(\lambda^{2}_{2}d_{1})}{ch(\lambda d_{1})} \\ &- \overline{\Phi} \quad \frac{\lambda^{2}}{\lambda} \quad \frac{sh(\lambda^{2}_{2}d_{1})}{ch(\lambda d_{1})} a_{11} \\ &+ \left(\left[\frac{1-n_{2}}{1-n_{1}} \quad \frac{G_{2}}{G_{1}} \quad \frac{\nu_{2}\lambda^{2} - \left(1-\nu_{2}\right)\lambda^{2} \frac{2}{2}}{\lambda^{2} \left(1-2\nu_{2}\right)} - \frac{n_{2}B_{2}}{12\lambda G_{1} \left(1-n_{1}\right)}\right] \frac{sh(\lambda^{2}_{2}d_{1})}{ch(\lambda d_{1})} \\ &- \overline{\Phi} \quad \frac{\lambda^{2}}{\lambda} \quad \frac{ch(\lambda^{2}_{2}d_{1})}{ch(\lambda d_{1})} a_{12} = 0 \end{aligned}$$

$$\begin{aligned} & \overset{45}{\text{th}(\lambda d_{1}) a_{1} + a_{2} + \left[\frac{1-\lambda A1}{2\lambda}\right] + d_{1} \text{th}(\lambda d_{1})\right] a_{3} + \left[\frac{1-\lambda A1}{2\lambda}\right] \text{th}(\lambda d_{1}) + d_{1}\right] a_{4} \\ & + \frac{\lambda^{\prime}}{\lambda} - \frac{\text{sh}(\lambda^{\prime}_{1} d_{1})}{\text{ch}(\lambda d_{1})} a_{5} + \frac{\lambda^{\prime}}{\lambda} - \frac{\text{ch}(\lambda^{\prime}_{1} d_{1})}{\text{ch}(\lambda d_{1})} a_{6} \\ & - \frac{G_{2}}{G_{1}} \left(1 + \frac{\lambda K_{5}}{G_{2}}\right) \text{th}(\lambda d_{1}) a_{7} - \frac{G_{2}}{G_{1}} \left(1 + \frac{\lambda K_{5}}{G_{2}}\right) a_{8} \\ & - \frac{G_{2}}{G_{1}} \left(\frac{1-\lambda B1}{2\lambda} + d_{1} \text{th}(\lambda d_{1})\right) + \frac{K_{5}}{G_{2}} \left[1 + \lambda d_{1} \text{th}(\lambda d_{1})\right] \right] a_{9} \\ & - \frac{G_{2}}{G_{1}} \left(\frac{\lambda^{\prime}}{2\lambda} + \frac{\lambda^{\prime}}{2\lambda}\right) \frac{\text{sh}(\lambda^{\prime} 2d_{1})}{\text{ch}(\lambda d_{1})} a_{11} \\ & - \frac{G_{2}}{G_{1}} \left(\frac{\lambda^{\prime}}{2} + \frac{\lambda^{\prime}}{G_{2}}\right) \frac{\text{sh}(\lambda^{\prime} 2d_{1})}{\text{ch}(\lambda d_{1})} a_{12} = 0 \\ & - \text{i } A2 \text{ th}(\lambda d_{1}) a_{3} - \text{i} A2 a_{4} - A3 \frac{\text{ch}(\lambda^{\prime} 1d_{1})}{\text{ch}(\lambda d_{1})} a_{10} \\ & + \text{i } B2\left[\text{th}(\lambda d_{1}) - \lambda K_{2}C_{2}\right] a_{9} + \text{i} B2\left[1 - \lambda K_{2}C_{2} \text{th}(\lambda d_{1})\right] a_{10} \\ & + \text{B3 } \left[\frac{\text{ch}(\lambda^{\prime} 2d_{1})}{\text{ch}(\lambda d_{1})} - \lambda^{\prime} 2K_{2}C_{2} \frac{\text{ch}(\lambda^{\prime} 2d_{1})}{\text{ch}(\lambda d_{1})}\right] a_{12} = 0 \end{aligned}$$

-i A2
$$a_3$$
 - i A2 th(λd_1) a_4 - $\frac{\lambda'_1}{\lambda}$ A3 $\frac{\operatorname{sh}(\lambda'_1d_1)}{\operatorname{ch}(\lambda d_1)}$ a_5 - $\frac{\lambda'_1}{\lambda}$ A3 $\frac{\operatorname{ch}(\lambda'_1d_1)}{\operatorname{ch}(\lambda d_1)}$ a_6

+
$$i \frac{K_2}{K_1} B^2 a_g + i \frac{K_2}{K_1} B^2 th(\lambda d_1) a_{10} + \frac{K_2}{K_1} \frac{\lambda' 2}{\lambda} B^3 \frac{sh(\lambda' 2^{d_1})}{ch(\lambda d_1)} a_{11}$$
 (3.3.7i)
+ $\frac{K_2}{K_1} \frac{\lambda' 2}{\lambda} \frac{ch(\lambda' 2^{d_1})}{ch(\lambda d_1)} a_{12} = 0$

$$[\alpha + (1-\alpha) \lambda \overline{d} th(\lambda \overline{d})] a_7 + [\alpha th(\lambda \overline{d}) + (1-\alpha)\lambda \overline{d}] a_8$$

$$+ \{\alpha \overline{d} + (1-\alpha) \overline{d}[1 + \lambda \overline{d} th(\lambda \overline{d})]\} a_9 + \{\alpha \overline{d} th(\lambda \overline{d}) + (1-\alpha) \overline{d} [th(\lambda \overline{d}) - \lambda \overline{d}]\} a_{10}$$

$$(3.3.7j)$$

$$+ \left[\alpha \frac{\operatorname{ch}(\lambda' 2^{\overline{d}})}{\operatorname{ch}(\lambda \overline{d})} + (1-\alpha) \lambda' 2^{\overline{d}} \frac{\operatorname{sh}(\lambda' 2^{\overline{d}})}{\operatorname{ch} \lambda \overline{d}}\right] a_{11}$$

$$+ \left[\alpha \frac{\operatorname{sh}(\lambda' 2^{\overline{d}})}{\operatorname{ch}(\lambda \overline{d})} + (1-\alpha)\lambda' 2^{\overline{d}} \frac{\operatorname{ch}(\lambda' 2^{\overline{d}})}{\operatorname{ch}(\lambda \overline{d})}\right] a_{12} = 0$$

$$th(\lambda \overline{d}) = a_7 + a_8 - [B1 - \overline{d}th(\lambda \overline{d})] = a_9 - [B1th(\lambda \overline{d}) - \overline{d}] = a_{10}$$

$$+ \frac{\lambda'_2}{\lambda} \frac{sh(\lambda'_2 \overline{d})}{ch(\lambda \overline{d})} = a_{11} + \frac{\lambda'_2}{\lambda} \frac{ch(\lambda'_2 \overline{d})}{ch(\lambda \overline{d})} = a_{12} = 0$$
(3.3.7k)

i B2
$$a_9$$
 + iB2 th($\lambda \overline{d}$) a_{10} + B3 $\frac{\lambda'_2}{\lambda}$ $\frac{sh(\lambda'_2\overline{d})}{ch(\lambda \overline{d})}$ a_{11}

+ B3
$$\frac{\lambda'_2}{\lambda} = \frac{ch(\lambda'_2\overline{d})}{ch(\lambda\overline{d})} a_{12} = 0$$

in which

$$\overline{\phi} = \frac{-T\lambda + iK_s}{2G_1(1-n_1)}$$
(3.3.8)

3.3.a Computer Program

Although the solution to the Biot equations is analytic, the actual numerical computation requires the use of the computer. The horizontal displacement integration constants are determined from equations (3.3.7a)-(3.3.71) using the International Mathematics and Science Library subroutine LEQT2C. The remaining integration constants for vertical displacement and pressure are determined by back substitution into equations (3.3.5a)-(3.3.5x). Stresses are calculated from equations (2.1.11a), (2.1.11c) and (2.1.11e). Fluid flows are determined from equation (2.2.7). The shear stress ratio, r, is defined as the ratio of the maximum shear stress, $\tau_{\rm m}$, to the effective overburden, $\sigma_{\rm o}^{\rm c}$, and is useful for identifying potential soil failure conditions.

$$r = \frac{\tau_m}{\sigma_0^{\prime}}$$
(3.3.9)

in which $\boldsymbol{\tau}_{m}$ is given by [Jumikis (1969)]

$$\tau_{\rm m} = \left[\left(\frac{\sigma_{\rm z} - \sigma_{\rm x}}{2} \right)^2 - \tau^2 \right]^{1/2}$$
(3.3.10)

47

(3.3.71)

Another parameter useful for identifying potential failure conditions is the shear stress angle, ϕ [Jumikis (1969)].

$$\phi = \tan^{-1} \qquad \frac{\tau_{m}^{2}}{(\frac{\sigma_{x} + \sigma_{z}}{2} + \tau_{m})} \qquad (3.3.11)$$
(3.3.11)

The computer program gives both dimensional and dimensionless results. The scaling used for each variable is listed in Table 3.1.

Table 3.1 Non-dimensionalizing scaling factors.

Variable	Scaling
ξ	Lp _o /G ₁
ζ	Lp _o /G ₁
р	р _о
σ _x	р _о
σ _z	р _о
τ	р _о
u	Kp _o /γL
W	Kp _o /γL Kp _o /γL
Z	L

A listing of the computer program is given in Appendix B.

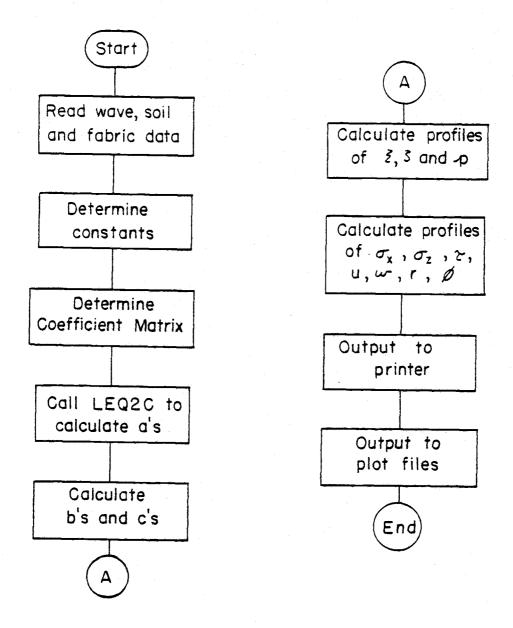


Figure 3.5 Computer program block diagram.

4.0 ANALYTICAL SOLUTION BEHAVIOR

The response of the soil-geotextile system to waves is not readily apparent from the analytical solution. Therefore, the general solution behavior and response to changes in wave and soil properties are examined. These responses are first presented for a single soil layer. An examination of this simplified case provides insight into the more complex case: two different soils separated by a "non-transparent" geotextile. For a three layered system examined at the end of this chapter, it is shown that the relative properties of the soils also influence the response.

4.1 Single Soil Layer Response

The dynamic response of a single, homogeneous soil layer may be examined using the soil-geotextile interaction model. This is the case for which both soils have identical properties and the geotextile does not resist displacement or fluid flow. A single soil layer 40 feet thick is examined. The specific wave and soil characteristics are listed in Table 4.1 and are denoted as the case A condition. This soil is generally described as a coarse sand [Creager <u>et al.</u> (1955)].

Table 4.1. Case A wave and soil conditions.

$G = 10^6 \text{ lb/ft}^2$	$\gamma_B = 60 \text{ lb/ft}^3$	H = 19.8 ft
v = 0.33	d = 40 ft	T = 10 s
n = 0.40	$\alpha = 1.0$	h = 50 ft
K = 0.01 ft/s		

The vertical profiles of displacements, stresses and flows are shown in Figures 4.1 - 4.3. The dimensionless depth is the depth scaled by the wave length.

The amplitudes of the displacements tend to decrease with depth. For the case A conditions the maximum horizontal and vertical displacements are 4.4×10^{-3} ft and 1.3×10^{-3} ft, respectively. The maximum horizontal displacement may occur at intermediate depths. However, the maximum vertical displacement always occurs at the mudline. For this case, no-slip bottom boundary conditions were imposed so both components of displacement vanish at the lower boundary of the soil layer.

The pore water pressure also decreases with depth for this case. However, for certain wave-soil conditions the pressure may increase near the impermeable bottom boundary. For this case, and in general, there is little phase shift with depth.

The stress profiles for this case are typical for a single soil layer system. The horizontal effective stress is a maximum at the mudline and has a large phase shift near the bottom boundary. The vertical effective stress is zero at the mudline as specified by the boundary condition and attains a maximum at intermediate depths. The shear stress increases approximately linearly with depth.

The horizontal velocity is proportional to the pressure because of the periodicity assumption in x. Therefore, the form of the horizontal discharge velocity is similar to the pore pressure profile. The vertical discharge velocity decreases almost linearly from a maximum at the mudline to zero at the bottom impermeable boundary.

The cyclic shear stress ratio is commonly used by earthquake engineers in estimating soil failure. Values larger than 0.25 for a drained soil indicate a potential failure condition. For this case, failure would be anticipated in the upper 5 or 6 feet of soil.

Another indicator of failure conditions is the shear stress angle. For cohesionless soils such as silts, sands and gravels, if this angle is exceeded the soil will fail. Failure is predicted for the upper 2 feet of soil. It is of interest to note that even though the maximum displacements are small (approximately 1/20 and 1/60 in.

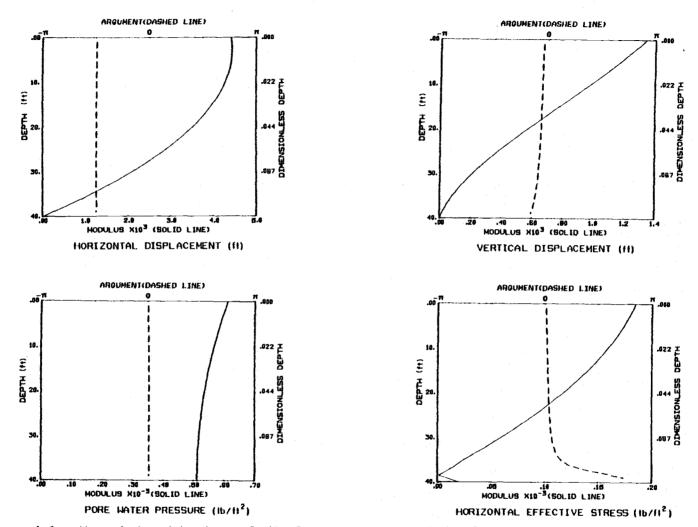


Figure 4.1. Wave-induced horizontal displacement, vertical displacement, excess pore water pressure and horizontal effective stress for the case A conditions.

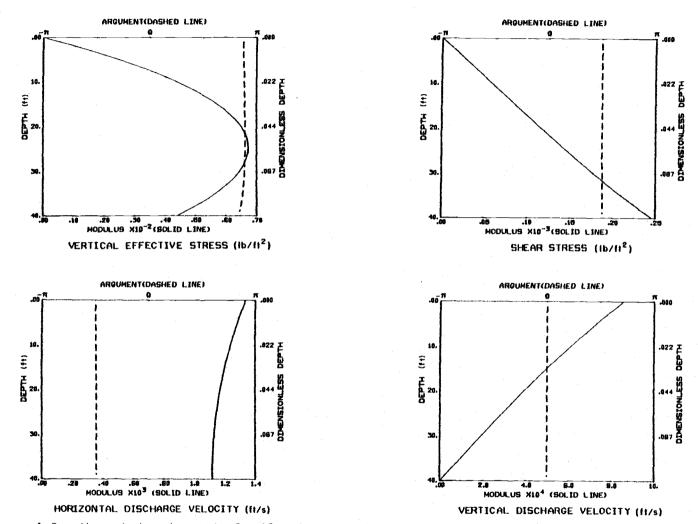


Figure 4.2. Wave-induced vertical effective stress, shear stress, horizontal discharge velocity and vertical discharge velocity for the case A conditions.

5 S

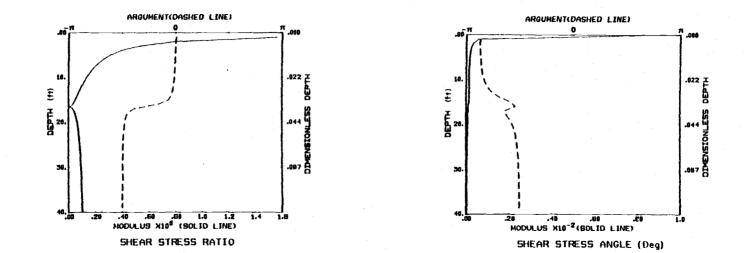


Figure 4.3. Wave-induced shear stress ratio and shear stress angle for the case A conditions.

for the horizontal and vertical, respectively) that failures may occur.

The amplitude of the pore pressure response is frequency selective, the higher frequencies being more highly damped. This response is shown in Figure 4.4 for the case A conditions but allowing the wave period to vary. The soil acts as a low pass filter preferentially removing the higher frquencies. This behavior is characterized by a frequency and depth dependent transfer function. For a single soil layer of thickness, d, the transfer function for dimensionless pressure from the potential pressure model, T, is

$$T = \frac{ch^2 \left[\lambda(d-z)\right]}{ch^2 \left(\lambda d\right)}$$
(4.1.1)

This transfer function is shown in Figure 4.5 for the case A conditions. The higher frequencies are very highly damped. The frequency dependency is also given as a function of d/L which is a common scaling. The depth of the soil may be classified as shallow, intermediate or deep with respect to the wave length by examining the asymptotic behavior of the transfer function. These domains are labeled using the same criteria as used in linear wave theory. For a shallow soil the amplitude of the dynamic pore water pressure is constant with depth, for a deep soil the dependency is exponential and for an intermediate depth soil the dependency is hyperbolic.

The magnitudes of the maximum soil displacements and of the maximum shear stress are also frequency selective. Both components of displacement have a critical frequency at which a maximum occurs. For the case A conditions, the maximum horizontal and vertical displacements and shear stress occur at approximately 12, 8 and 11 seconds, respectively, as shown in Figure 4.6.

The magnitudes of the maximum soil displacements are inversely related to the shear modulus, the stiffer soils being more resistant to displacement. This dependency is shown in Figure 4.7 for the case A conditions, but with variable shear modulus. For these conditions, the displacements are approximately linear functions of the modulus. It is also shown that for values of the modulus greater than 10^{10} lb/ft² the stresses are constant.

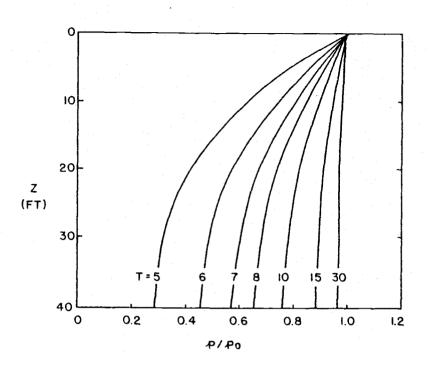


Figure 4.4. Frequency dependency of pore water pressure profiles for the case A conditions.

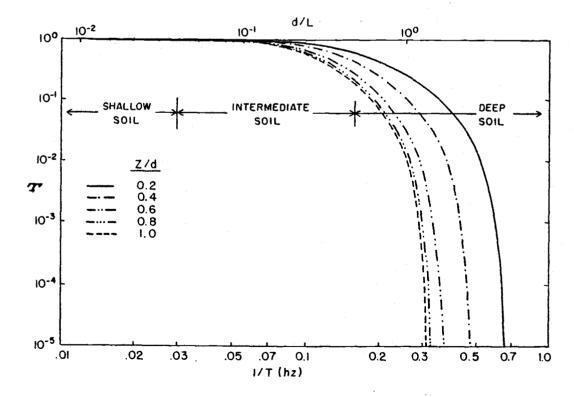


Figure 4.5. Transfer function for the dimensionless pore water pressure from the potential pressure model.

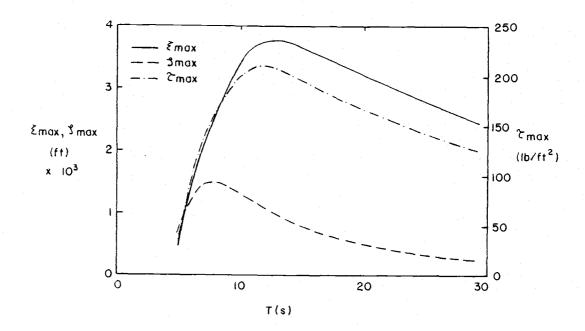


Figure 4.6. Frequency dependency of the maximum displacements and shear stress for the case A conditions.

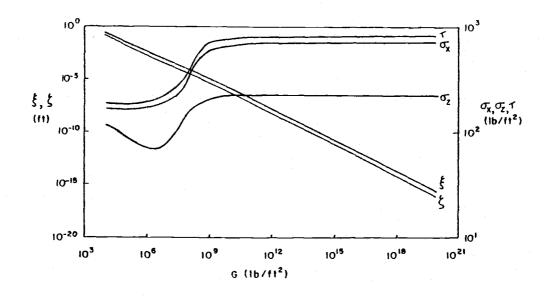


Figure 4.7. Maximum displacements and stresses as a function of the shear modulus for the case A conditions.

The magnitudes of the displacements are a function of the degree of slip at the bottom. The maximum horizontal and vertical displacements and the horizontal displacement at the bottom are shown in Figure 4.8 as a function of the degree of slip for the case A conditions. Free slip corresponds to $\alpha = 0$ and no slip corresponds to $\alpha = 1$. In the field, the impermeable bottom boundary (clay, rock, etc.) may interlock with the soil restricting the soil motion. However, in the laboratory the impermeable bottom may be wood or smooth concrete which provides little resistance to horizontal soil displacement. In this case, the form and magnitude of the soil displacements (and the associated stresses) are dependent on the empirical coefficient, α . The value of α must be determined from experiments. However, this determination is difficult to make if the only measurements are the pore pressure profiles because the pore pressure is relatively insensitive to this coefficient (see Figure 4.9).

The degree of saturation of the pore water has a major effect on the pore pressure response. Air is much more compressible than pure water so even small amounts influence the response. Pore water pressure profiles are shown in Figure 4.10 for the case A conditions as a function of the degree of saturation. The air easily compresses when the soil deforms so the responses are not transmitted as efficiently down through the soil column. However, the displacements near the mudline tend to be larger (see Figure 4.11). An increase in the volume of air in the pore water results in an increase in failure potential.

Pore water pressure profiles are shown in Figure 4.12 for the case A conditions with variable soil depth. For shallow soils (d/L < 0.05) the response is nearly constant in z. For deep soils (d/L > 0.5) the decay with depth is exponential. The magnitudes of the displacements and shear are also a function of the soil layer thickness. Figure 4.13 indicates that for the case A conditions a maximum failure potential occurs for a soil depth which is approximately 15% of the wave length.

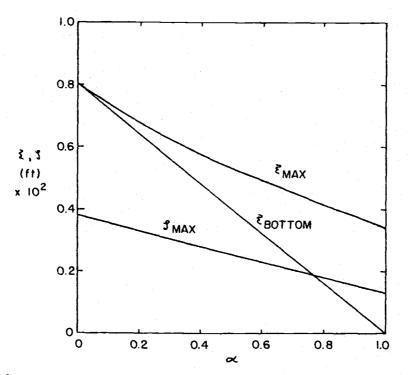


Figure 4.8. Maximum displacements as a function of the degree of bottom slip for the case A conditions.

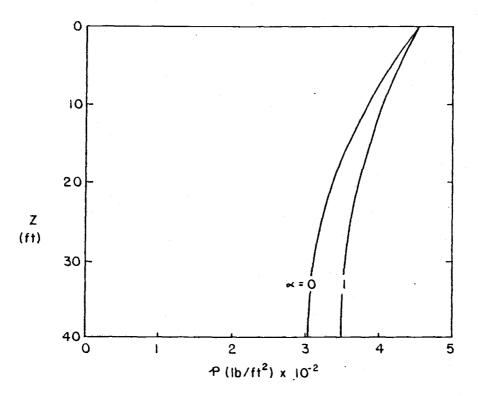


Figure 4.9. Pore water pressure profiles as a function of the degree of bottom slip for the case A conditions.

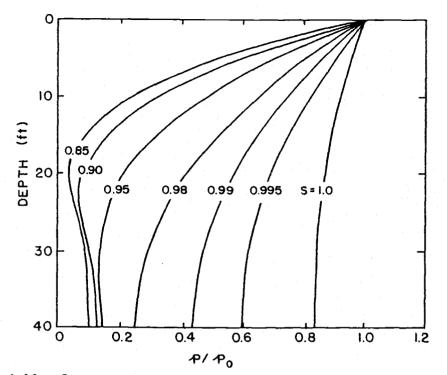


Figure 4.10. Pore water pressure profiles as a function of the degree of saturation for the case A conditions.

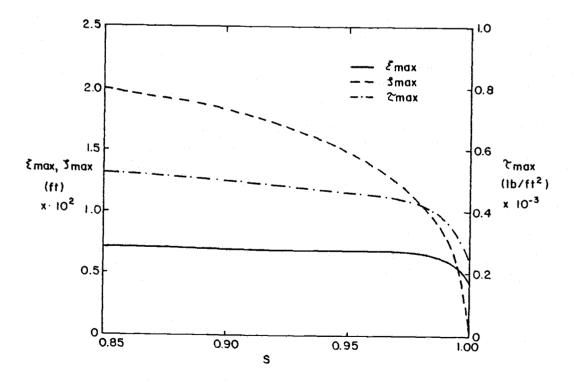


Figure 4.11. Maximum displacements and shear stress as a function of the degree of saturation for the case A conditions.

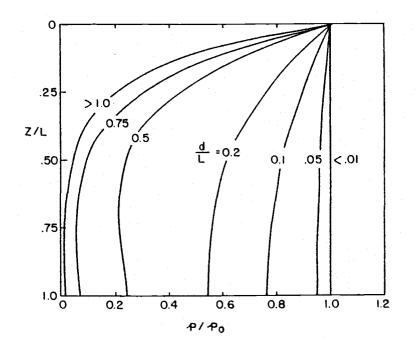


Figure 4.12. Pore water pressure profiles as a function of the soil thickness for the case A conditions.

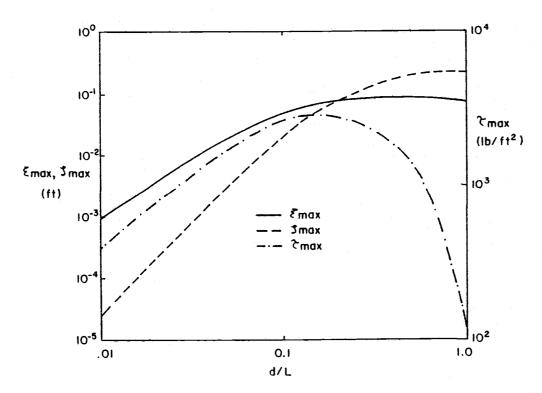


Figure 4.13. Maximum displacements and shear stress as a function of the soil thickness for the case A conditions.

4.2 Two Soil Layer Response

The general responses of a two soil layer system are similar to the one layer system but are complicated by the geotextile properties and the coupling of the two soil layers. A three layered system (two identical soil layers separated by a geotextile) with geometry similar to the conditions tested in the wave channel is examined in detail. These conditions are denoted as the case B conditions and are summarized in Table 4.2. The soils may again be described as a coarse sand.

				and the second
${\tt G}_1$	= 2.5 x 10^5 1b/ft ²	G2	= 2.5 x 10^5 lb/ft ²	H = 2.03 ft
v ₁	= 0.33	ν 2	= 0.33	T = 1.77 s
n_1	= 0.4	n ₂	= 0.4	h = 8.0 ft
К1	= 0.01 ft/s	K ₂	= 0.01 ft/s	$\alpha = 1.0$
γ _{B1}	= 50 lb/ft	γ _{B2}	= 50 lb/ft	
d_1	= 1.0 ft	d ₂	= 3.0 ft	

Table 4.2. Case B wave and soil conditions.

The fluid energy dissipated in the geotextile is characterized by the permittivity. This coefficient is primarily a function of the fabric permeability. Pore water pressure profiles are shown in Figure 4.14 for the case B conditions as a function of the geotextile permeability for a geotextile with a thickness of 0.01 ft. The fabric location is shown by the hashed line. When the geotextile permeability is of the same order or greater than the soil permeability, the fabric is transparent. As the geotextile permeability decreases the transmission of pressure is significantly reduced. The resulting displacements and shear stress are shown in Figure 4.15. Decreasing geotextile permeability results in a decreased failure potential from the cyclic stresses. However, as the permeability of the geotextile

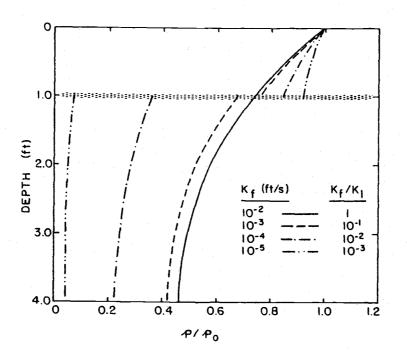


Figure 4.14. Pore water pressure profiles as a function of the geotextile permeability for the case B conditions.

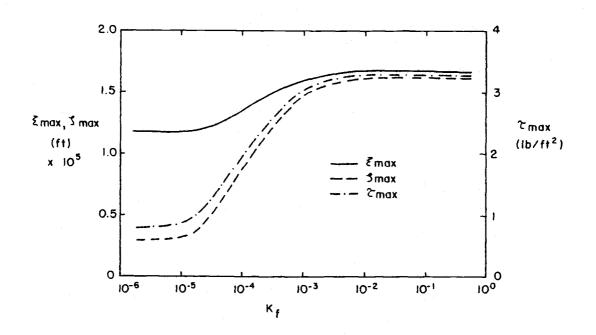


Figure 4.15. Maximum displacements and shear as a function of the geotextile permeability for the case B conditions.

decreases the failure potential due to the accumulation of pore water pressure increases significantly. A low permeability fabric is an undrained condition and the accumulating pore pressure is unable to dissipate. If the permeability of the geotextile is of the same order or greater than that of the adjacent soils the geotextile permeability will have little or no influence on the soil response. Most commercially available geotextiles are more permeable than sands and silts and therefore are transparent in the transmission of pressure. However, the geotextile pores can clog with soil particles which reduces the fabric permeability. A clogged geotextile is more susceptible to a pore water pressure accumulation failure.

The geotextile permeability may be defined to include the effect of the fluid acceleration in the same way unsteady soil permeabilities were defined. The imaginary portion of the permeability indicates the importance of the acceleration. For a physically realistic values for the inertial coefficient, C_m , the imaginary portion of the geotextile permeability has no influence on the soil response. The sensitivity to the inertial coefficient has been examined for the range $-6 < C_m < 6$. No discernible change in soil response was noted.

The solution is also influenced by the ratio of the soil permeabilities. Pore water pressure profiles are shown in Figures 4.16 for the case B conditions with variable K_1 . The pressure response in the lower layer is decreased as the upper layer becomes less permeable. Figure 4.17 shows the maximum displacements and shear. When the permeabilities are within an order of magnitude of each other the solution is sensitive to changes in the relative permeability. However, as the difference in permeability exceeds an order of magnitude, equilibrium values are quickly reached which are associated with the less permeable layer. Figures 4.18 and 4.19 are similar to Figures 4.17 and 4.18 except K_2 is held constant and K_1 is allowed to vary. It is of interest to note that for a relative permeability of approximately 10, a maximum pore water pressure profile results. This maximum is also observed in the horizontal displacement and shear stress. This corresponds to a worst combination of grain sizes in terms of failure potential. The permeabilities for this worst case (for the case B

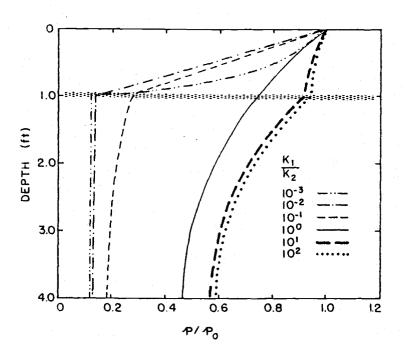


Figure 4.16. Pore water pressure profiles as a function of the relative permeability for the case B conditions $(K_2 = 0.01 \text{ ft/s}).$

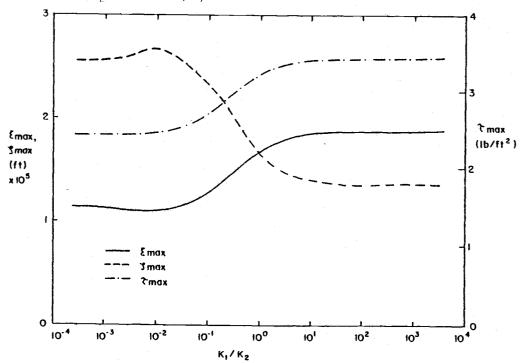


Figure 4.17. Maximum displacements and stresses as a function of the relative permeability for the case B conditions $(K_2 = 0.01 \text{ ft/s}).$

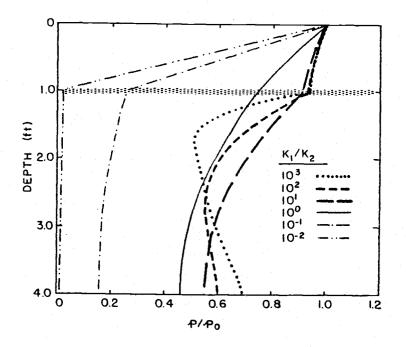


Figure 4.18. Pore water pressure profiles as a function of the relative permeability for the case B conditions $(K_1 = 0.01 \text{ ft/s}).$

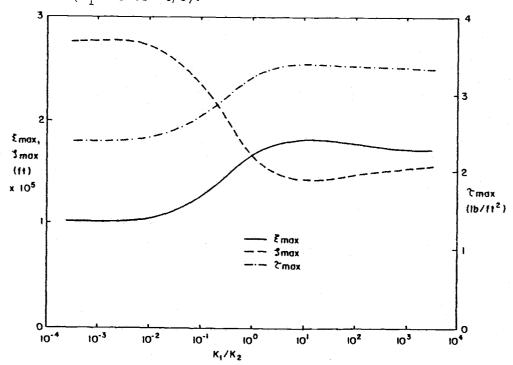


Figure 4.19. Maximum displacements and shear stress as a function of the relative permeability for the case B conditions $(K_1 = 0.01 \text{ ft/s}).$

conditions) are representative of a gravel covering a coarse sand.

The imaginary portion of the soil permeability has a minor influence on the soil response. Hannoura and McCorquodale (1978) present experimental results that indicate the inertia coefficient for coarse granular media is between -6 and 6. The pressure profiles for this range of inertia coefficient are not influenced by the acceleration. The influence on the magnitude of the displacements and stresses is also very small for the test wave and soil conditions. However, the relative importance of the inertial term is given by ω C_m k/gn. For most marine soils, the added mass and porosity show little variation. Therefore, the inertial term is primarily a function of the soil permeability and the wave frequency; high permeability (associated with larger sediment size) and higher wave frequency tending to increase the relative importance. For the case B conditions this coefficient has a value near 10⁻⁴, while for gravel it is near 10⁻² and for riprap it may approach unity.

The mechanical properties of the geotextile are described in terms of the elasticity and tension. The elasticity has little influence on the pore water pressure; less than 2% decrease for very stiff fabrics. However, the maximum displacements and shear stress are dependent on the elasticity (see Figure 4.21). The primary influence on the vertical displacement and shear stress occurs for very compliant geotextiles while the influence on the horizontal displacement is a maximum as the geotextile elasticity approaches the shear modulus of the soil. As with the elasticity, the pore water pressure profiles are only weakly dependent on the geotextile tension. The maximum change occurs for fabric tensions less than 100 lb/ft. Figure 4.21 shows that pretensioning the geotextile to 100 lb/ft for the case B condition results in a 30% reduction in shear stress.

It was shown in Figure 4.10 that the degree of saturation of the pore water influences the soil response. In a marine sediment, biological activity or chemical decomposition of organics may produce gas. The influence of these bio-chemical processes on the soil pressure response is shown in Figure 4.22 for the case B conditions with variable saturation in the upper layer. The soil response is a

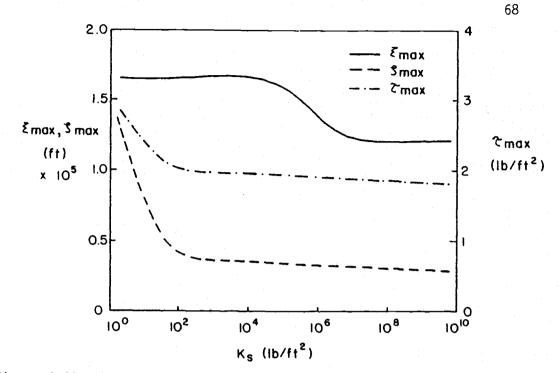


Figure 4.20. Maximum displacements and shear stress as a function of geotextile elasticity for the case B conditions.

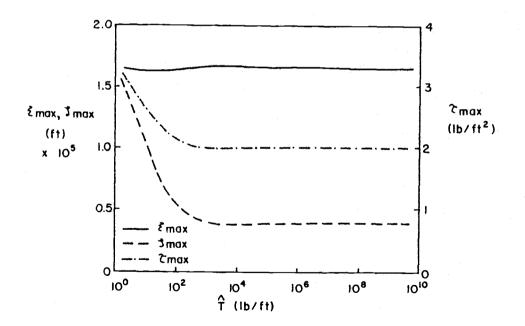


Figure 4.21. Maximum displacements and shear stress as a function of the geotextile tension for the case B conditions.

function of the degree of saturation in the upper layer, but the influence on the pressure profile is small even for a large variation in saturation. However, the shear stress increases in the upper layer in response to increasing gas content in the pore water. The sensitivity of both the shear stress and pore water pressure responses increase as the thickness of the organic layer increases.

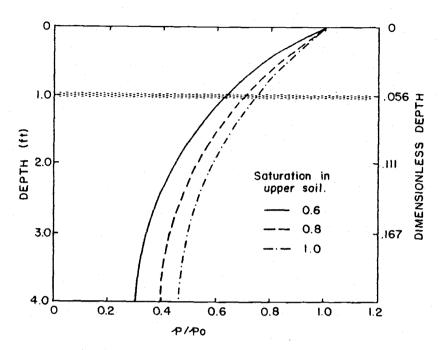


Figure 4.22. Pore water pressure profiles as a function of the degree of saturation of the upper layer for the case B conditions.

5.0 EXPERIMENTAL RESULTS

Two series of laboratory experiments were conducted at the Oregon State University Wave Research Facility (WRF) during the spring of 1980 and 1981. In both cases the pore pressure response was measured in a three layered system; two different soils separated by a geotextile. However, in the first series of experiments only the periodic responses were measured while in the second series of experiments both the periodic and mean change in pore water pressure were monitored.

5.1 Laboratory Setup

5.1.a Oregon State University Wave Research Facility

The WRF is a large scale open air wave channel 12 feet wide, 15 feet deep and 342 feet long. The hinged wave board is driven by an MTS servo hydraulic piston. The facility is capable of producing simple periodic waves with periods exceeding eight seconds and heights to five feet. Random waves can also be generated using the on-site PDP 11 computer to generate the wave spectrum and transfer function for the board motion. Wave heights are measured with a sonic surface profiler. The wave energy is dissipated through breaking on a concrete beach with slope 1:12.

5.1.b Test Section

A test section 36 feet long was constructed in the wave channel. The determination of the optimum test section length for minimum end wall effects is discussed in Appendix C. The four foot deep, four foot wide section was constructed of 3/4 inch plyboard reinforced with 2 x 4 studs. The side walls were braced to the wave channel walls and the bottom was attached to the channel bottom. Wood to wood connections

were glued and screwed and the entire section was treated with a water sealer. The test section is shown in place in Figure 5.1 before the addition of the soil layers.

The volume between the wave tank walls and the test section was filled with gravel to provide extra stability and prevent deflection of the side walls during the cyclic wave loading. A typical cross section of the test section is shown in Figure 5.2.

A uniform gravel ($D_{50} = 10.5 \text{ mm}$) was selected as the upper soil layer material. The gravel provides good transmission of the pore pressure to the geotextile while also providing a stable surface under the test wave conditions. A uniform, fine, clean sand ($D_{50} = 0.2 \text{ mm}$) was selected for the lower layer. Such a material demonstrates a potential for liquefaction [Seed and Idriss (1967)]. Accurate determination of the physical properties of the two soils is important when comparing the analytical model with the experimental observations. These properties are summarized in Table 5.1 and Figures 5.3 and 5.4.

Table 5.1. Test section upper layer soil properties.

 $\gamma_{B1} = 58.6 \text{ lb/ft}^3$ $K_1 = 0.059 \text{ ft/s}$ $G_1 = 4.0 \times 10^5 \text{ lb/ft}^2$ $\nu_1 = 0.35$ $n_1 = 0.465$

The two soil layers were separated by a geotextile. Four geotextile conditions were tested; woven, impermeable, semi-rigid and no geotextile. Typical geotextiles are shown in Figures 5.5, 5.6, 5.7 and 5.8.

Important geotextile physical properties for the analytical model include: tension, elasticity, permeability and thickness. The perme-

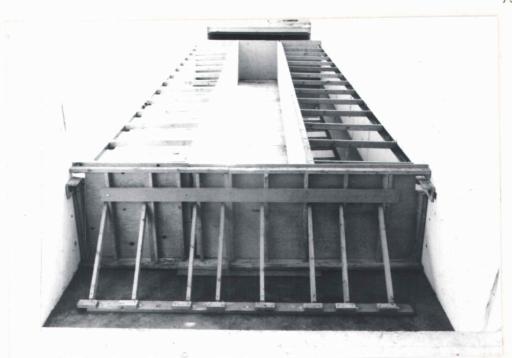


Figure 5.1. In place photograph of the test section before the addition of the soil layers.

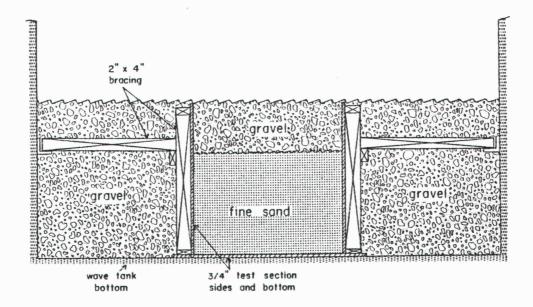


Figure 5.2. Typical cross-section of the test section.

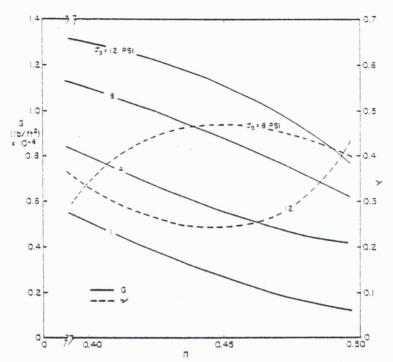


Figure 5.3. Shear modulus and Poisson's ratio in the lower soil layer as a function of porosity for different confining pressures.

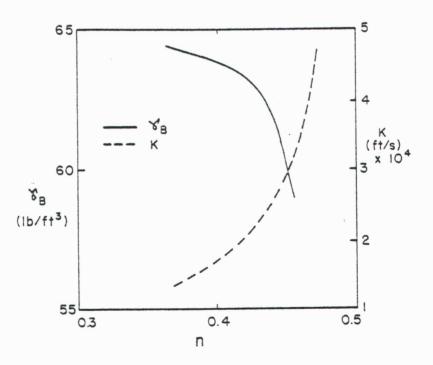


Figure 5.4. Bouyant weight and permeability of the lower soil layer as a function of porosity.

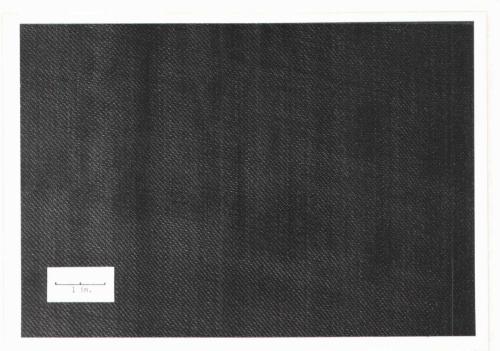


Figure 5.5. Monofilament woven geotextile (Polyfilter GB, Carthage Mills).



Figure 5.6. Needle punch nonwoven geotextile (Bidim C42. Monsanto).



Figure 5.7. Heat bonded nonwoven geotextile (Typar, Dupont).

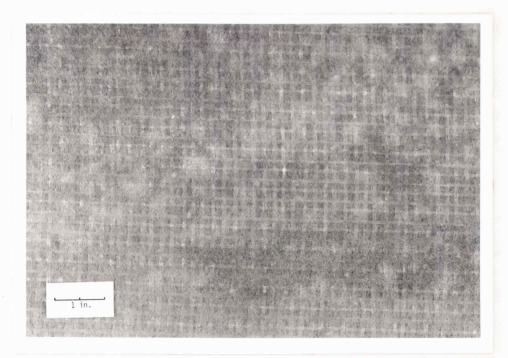


Figure 5.8. Combination woven/nonwoven geotextile (Terrafix 500N, Terrafix)

ability and thickness may be combined into a single term, the permittivity. Properties for several fabrics are listed in Table 5.2. The values for elasticity are only approximate values because the stress-strain behavior of geotextiles is very non-linear.

Geotextile	Permeability (ft/s)	Thickness (in)	Elasticity (1b/ft ²)
Polyfilter GB	0.059	0.025	2040
Bidim C42	0.130	0.180	5280
Typar	0.004	0.015	12000
Terrafix 500 N	0.118	0.175	12000

Table 5.2 Geotextile properties.

The uniform preparation of the lower soil is an important aspect of the experiments to insure repeatability. The soil was first completely fluidized by injecting a high pressure water jet into the sand. The "fluidizer", an inverted tee shaped manifold [see Nath et al. (1977)] was moved through the soil at one foot intervals. In the 1980 experiments the soil was reconsolidated by moving a hinged metal flap activated by a concrete vibrator through the bed at one foot intervals. This left the soil in a relatively dense state. The following year the soil was slightly consolidated by manually vibrating vertical rods at a specific number of locations. This left the soil in a uniform condition very near liquefaction. A gravel overburden of approximately 60 lb/ft² was then added and the soil was allowed to consolidate for 24 hours. During this period the soil consolidated from n = 0.460 to a more stable value of n = 0.425. This second consolidation technique was more consistent from test to test than the hinged flap concrete vibrator method. Thielen (1981) provides a detailed description of the bed preparation techniques.

The lower soil layer porosities for the 1980 tests are summarized in Table 5.3. The 1981 tests showed little variation.

Table	5.3.	Lower	soj]	layer	porosities	for	the	1980
		tests.						

Geotextile	<u>n</u>	σ
woven	0.430	0.000
semi-rigid	0.480	0.000
impermeable	0.418	0.005
no fabric	0.457	0.015

The average porosity for all tests was 0.442 with a standard deviation of 0.023 or about 5% of the mean. Because of this small variation, a single set of soil parameters is used to describe the lower soil for all tests. These properties are summarized in Table 5.4.

Table 5.4. Mean lower soil layer properties.

 $Y_{B2} = 61.7 \text{ lb/ft}$ $K_2 = 2.6 \times 10^{-4} \text{ ft/s}$ $G_2 = 3.0 \times 10^5 \text{ lb/ft}^2$ $v_2 = 0.374$ $n_2 = 0.442$

In both series of experiments the pore water pressure was monitored to reveal the dynamic response of the soil-geotextile system to ocean waves. The 1980 tests were designed to examine the periodic pore water responses only, while in the 1981 tests both the periodic response and mean accumulation of pore pressure was monitored. The periodic responses were used to verify the Biot model and the accumulation measurements were compared with the earthquake consolidation equation predictions [Thielen (1981)]. Thielen (1981) also includes an analysis of the random waves and more information on the laboratory experiments.

5.1.c Pressure Transducers

The response of the soil-geotextile system was examined by measuring the dynamic pore pressure response in the soil. Nine pressure transducers (Druck model PDCR10) were mounted in the side wall of the test section in the 1980 experiments and 14 in the 1981 experiments. Carborundum filter stones were placed between the soil and transducers in flush mounting aluminum brackets. This prevented soil from clogging the pressure transducers. The stones were boiled for 20 minutes to remove air and were always kept underwater. A small amount of air in the stones significantly changes the dynamic response of the transducers due to the compressibility of air.

Most of the transducers were placed to measure the vertical profile of the pressure. However, two transducers in the 1980 experiments and four in the 1981 experiments were placed off this vertical profile to insure that the central location of the test section was homogeneous and free from end effects. The locations of the pressure transducers are summarized in Table 5.5.

The transducers were calibrated by raising the still water level in the wave channel and the response was nearly linear at one volt per psi of static pressure. The calibrations were checked before and after each sequence of runs. No DC drift was observed as a function of time.

5.2 Laboratory Measurements

The free surface profiles and the pore pressure response were recorded for different wave and geotextile conditions. The simple periodic waves tested corresponded to Dean's stream function cases [Dean (1974)]. These waves are summarized in Tables 5.6 and 5.7 for the two water depths examined, four and eight feet, respectively.

<u></u>					
	1	980	1981		
Transducer	x(ft)	z(ft)	x(ft)	z(ft)	
1	0.00	4.00	0.00	3.44	
2	0.00	3.76	0.00	2.77	
3	0.00	2.21	0.00	1.85	
4	0.00	1.45	0.00	1.60	
5	0.00	1.17	0.00	1.35	
6	0.00	0.54	0.00	1.10	
7	0.00	0.00	0.00	0.85	
8	-6.00	2.21	0.00	0.62	
9	6.00	2.21	0.00	0.36	
10			0.00	0.00	
11			-10.00	1.60	
12			-4.67	1.60	
13			4.67	1.60	
14			10.00	1.60	

Table 5.5. Pressure transducer locations

Table 5.6. Simple periodic waves tested for a water depth of four feet.

Wave Case	T (sec)	<u>H (ft)</u>
7A	1.98	0.64
7B	1.98	1.26
7C	1.98	1.88
6A	2.80	0.74
6B	2.80	1.46
5A	3.95	0.78
5B	3.95	1.54
4A	6.25	0.78
4B	6.25	1.58

Wave Case	T (sec)	<u>H (ft)</u>
8A	1.77	0.68
8B	1.77	1.36
8C	1.77	2.03
7A	2.80	1.28
7B	2.80	2.52
7C	2.80	3.76
6A	3.95	1.47
6B	3.95	2.92
6C	3.95	4.40
5A	5.59	1.55
5B	5.59	3.07
4A	8.84	1.56

Table 5.7. Simple periodic waves tested for a water depth of eight feet.

The physical significance of the Dean's stream function wave cases is shown in Figure 5.9. In the stream function wave case designation the number indicates the relative depth and the letter, the percent of the breaking wave height. The waves utilized in the tests span the range of intermediate waves.

The free surface elevation and pressure transducer outputs were recorded on magnetic analog tape as a function of time. The 1980 results were transcribed on strip charts and visually read. The 1981 results were digitally recorded and analyzed by the computer. Both sets of measurements are summarized in Appendix D.

The dynamic wave-induced pressure at the mudline drives the soilgeotextile system. Therefore, an accurate measurement of this value is important. It is also the amplitude of the dynamic pressure at the mudline which is used to nondimensionalize the analytic solutions. There is some scatter in this measurement which is propagated through the nondimensionalizing. These errors vary from 2% to 8% of the mean

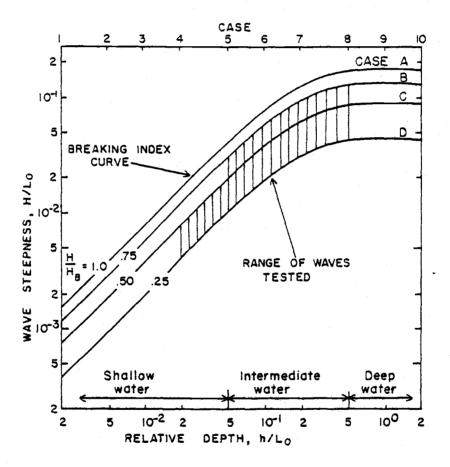


Figure 5.9. Definition diagram for Dean's stream function wave cases [from Dean (1974)].

mudline pressure amplitudes for the various wave cases. This error primarily results from small variations in the simulation of test waves for a given stream function case. However, the nondimensional pressure is not very sensitive to the magnitude of the mudline pressure and the theoretical solution to the pressure ratio is amplitude independent.

5.3 Comparison of Theory and Observations

The soil-geotextile system is driven by the wave-induced pressure at the mudline. (The wave-induced fluid shear stress at the mudline also drives the soil system but this stress is approximately five orders of magnitude less than the pressure and is negligible.) The pore pressure response in the soil is therefore linear in the pressure amplitude at the mudline. Pressure profiles scaled by the mudline pressure amplitude would then be expected to be independent of wave steepness. This result was confirmed by the laboratory measurements. Figure 5.10 shows the dimensionless measured soil pressure response for wave cases 8A, 8B and 8C. Each case is the average of the four no geotextile runs for the 1980 experiments.

A surprising observation is that the geotextile properties have very little influence on the cyclic pore water response. This lack of dependency on the geotextile properties is shown in Figure 5.11. The dimensionless pressure profile is similar for a no geotextile, an impermeable geotextile, a semi-rigid geotextile and a woven geotextile. Each data point is the average of wave cases 8A, 8B and 8C for a given geotextile condition.

Theory and measurements are compared in Figures 5.12 and 5.13 for the no geotextile condition. Theoretical results for both the free slip and no slip bottom conditions are shown. For the smooth laboratory test section, the free slip condition provides the best predicted response. In general the agreement with theory is good suggesting that the soil response is well modeled by Biot consolidation theory and that the soil-geotextile-soil model is valid for layered soils.

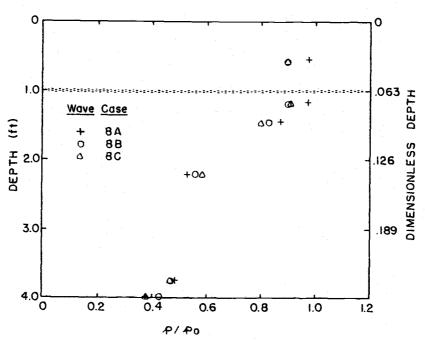


Figure 5.10. Dimensionless measured pore water pressure profiles for stream function wave cases 8A, 8B and 8C.

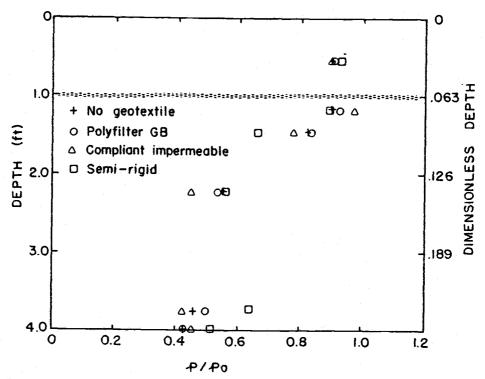


Figure 5.11. Average dimensionless measured pore water pressure profiles for stream function wave cases 8A, 8B and 8C as a function of geotextile conditions.

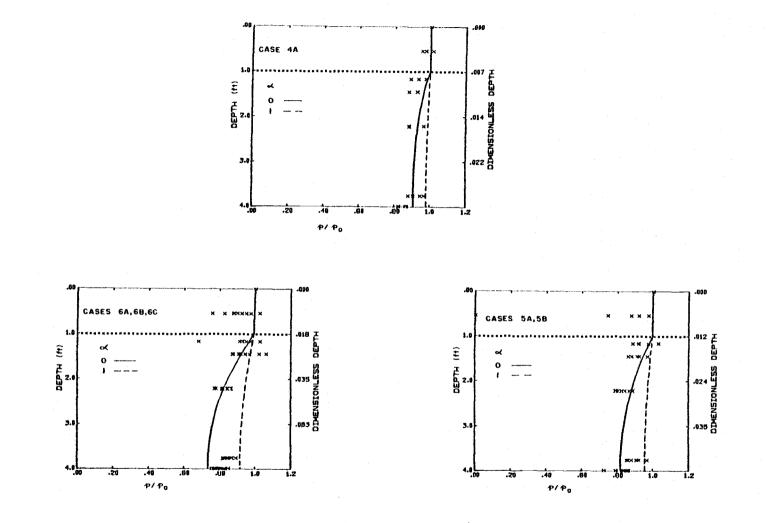
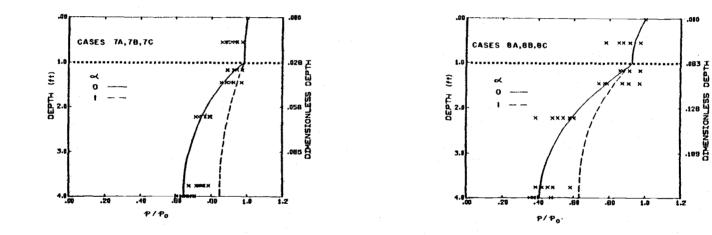
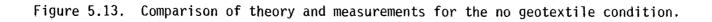


Figure 5.12. Comparison of theory and measurements for the no geotextile condition.





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Theory and measurements are compared in Figures 5.14 and 5.15 for the Polyfilter GB geotextile. Again the agreement is good. The lack of dependency of the pore water pressure profiles on the geotextile properties (see Figure 5.11) is also revealed by the analytic solution. Most commercially available geotextiles are relatively permeable and do not induce a pressure drop. Geotextile elasticity is generally low so little resistance to displacement is developed. Finally, fabrics are usually placed rather loosely so that there is no tension. This leads to the conclusion that most geotextiles will appear to be transparent having little or no influence on the cyclic soil response, other than maintaining the interface between the soil layers.

The permittivity of a geotextile may be measured in the laboratory by inducing a cyclic pressure differential across the fabric and measuring the gradients and head loss. Such a test for the compliant impermeable geotextile indicated a permittivity much more transparent to the transmission of pressure than would have been anticiapted based on the permeability. The apparent permeability is due to the dynamic deflection of the loose membrane and is approximately equal to 10^{-4} ft/s. Employing this result, the theory and measurements are compared in Figures 5.16 and 5.17 for the impermeable geotextile.

The fourth geotextile tested was an impermeable semi-rigid condition imposed by sandwiching a plastic sheet between two layers of quarter-inch plyboard. Theory and measurements are compared in Figures 5.18 and 5.19. As anticipated from the discussion of geotextile mechanical properties in Chapter 4, the geotextile stiffness has little influence on the pore water pressure profiles. The elasticity and effective permeability were taken as 10^4 lb/ft² and 10^{-4} ft/s, respectively.

The preceeding comparisons of theory and measurements are based on the 1980 experiments. The pore pressure responses in the 1981 experiments were very similar, except that the gravel upper layer was only five inches thick rather than one foot as in the 1980 experiments. The influence of a reduced armor layer overburden is shown in Figure 5.20 for approximately the experimental conditions and a case 7B wave. The maximum displacements and shear stress are also a function of the armor

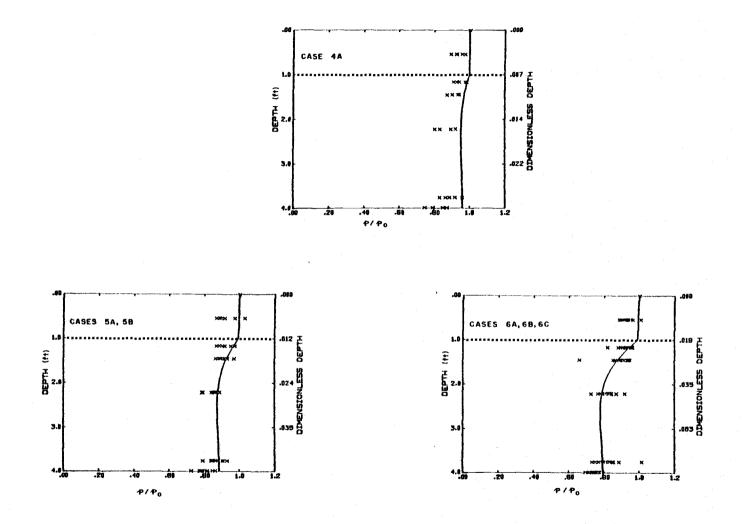
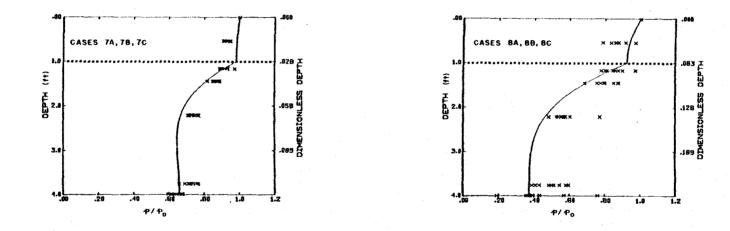
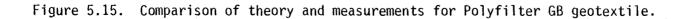


Figure 5.14. Comparison of theory and measurements for Polyfilter GB geotextile.





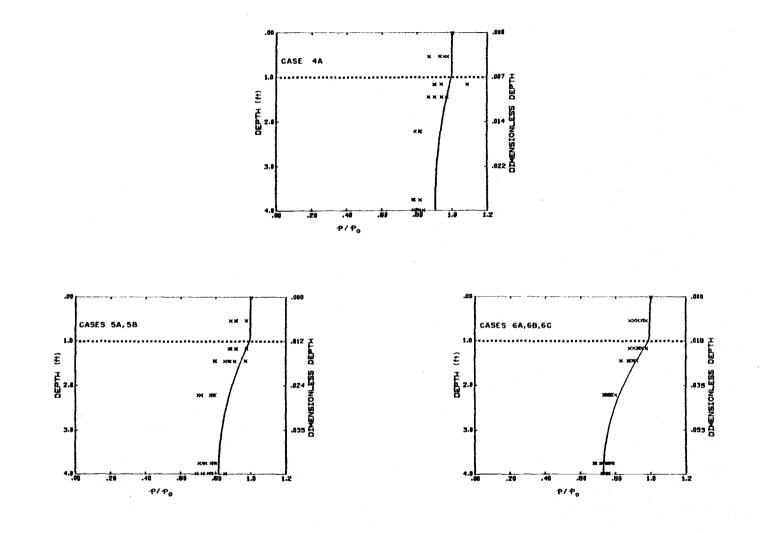
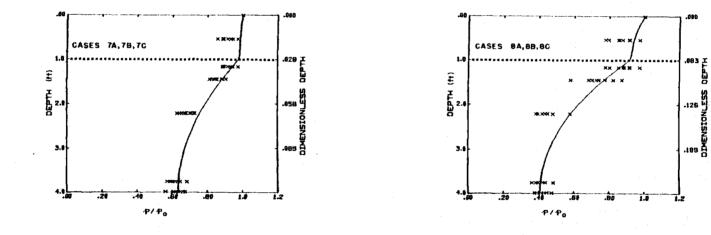


Figure 5.16. Comparison of theory and measurements for the compliant impermeable geotextile.





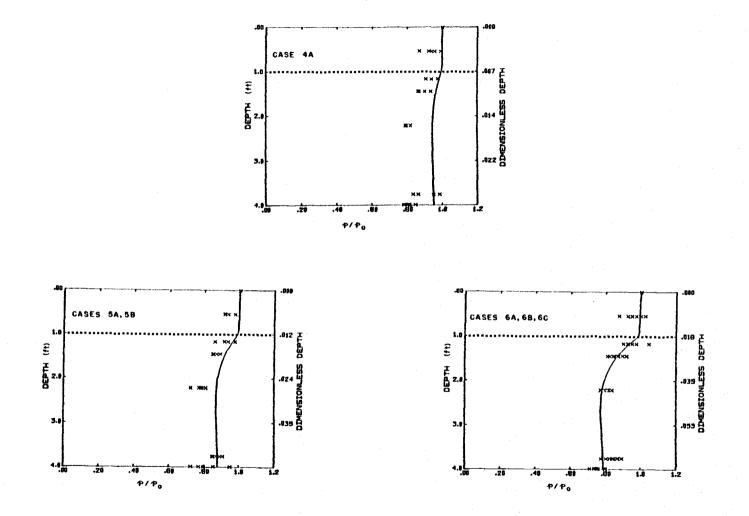
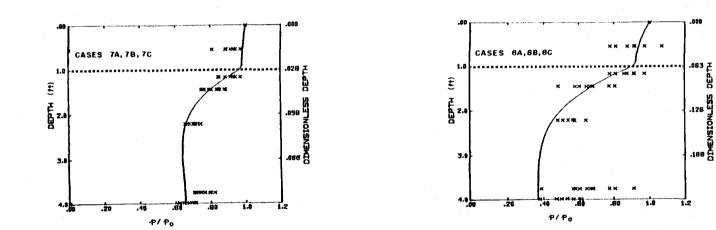
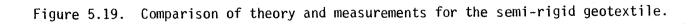


Figure 5.18. Comparison of theory and measurements for the semi-rigid geotextile.





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thickness as shown in Figure 4.21. For these wave and soil conditions a maximum failure potential (as discussed in Chapter 4 and depicted in Figure 4.3) occurs at an armor thickness of approximately two feet.

5.4 Wave-Induced Failure

There were two potential modes of soil failure: momentary failure associated with the cyclic stresses and complete failure associated with the accumulation of pore water pressure. In the 1980 series of experiments neither type of failure was observed. In this series of experiments the change in pressure amplitude in one hour of testing was less than 0.1% of the initial values for eight time series measurements. This change is less than the experimental error. The 1981 experiments were designed to monitor both the mean accumulation of pressure and the dynamic response. There was a general tendency for both the cyclic pore pressure amplitude and the mean pressure to decrease with time. Decreases in amplitude ranged from 0.2% to 4.5% of the inital value in 100 waves for the different tests. The mean pore water pressure decreased from 0.0% to 1.7%. Again, this represents a relatively small change but suggests that cyclic stressing associated with waves may slowly consolidate the soil and increase the stability. An exception to this general trend was observed for an impermeable geotextile. In this run complete failure occurred. The mean pore pressure rapidly accumulated during the first several stress cycles until the effective stress went to zero (see Figure 5.22). The response of the liquefied soil was similar to a dense viscous liquid. This response continued until there was a structural failure associated with the geotextile and the excess pore pressure was released. The geotextile is shown in place before and after this run in Figures 5.23 and 5.24. The settlement at the geotextile boundaries was approximately eight inches and occurred immediately upon the release of the pore water pressure.

Although this type of failure was observed only once, it does document wave-induced liquefaction. Complete soil failure due to liquefaction should therefore be anticipated in the field, but is like-

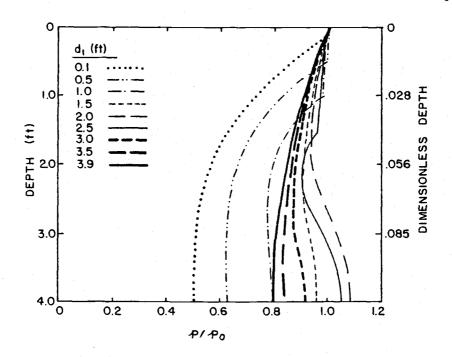


Figure 5.20. Pore water pressure profiles as a function of the armor layer thickness for approximately the experimental conditions and wave case 7B.

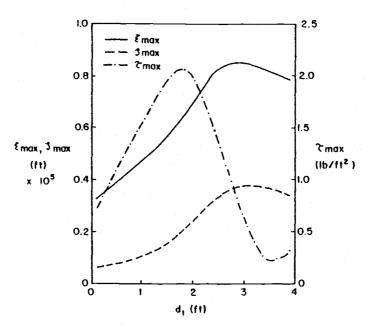


Figure 5.21. Maximum displacements and shear stress as a function of the armor layer thickness for approximately the experimental conditions and wave case 7B.

ly to occur infrequently. A more common failure is associated with the presence of a structure. For such foundation failures, the soil does not need to completely liquefy, only experience a decrease in strength. Several failures of this type were identified in Chapter 1.

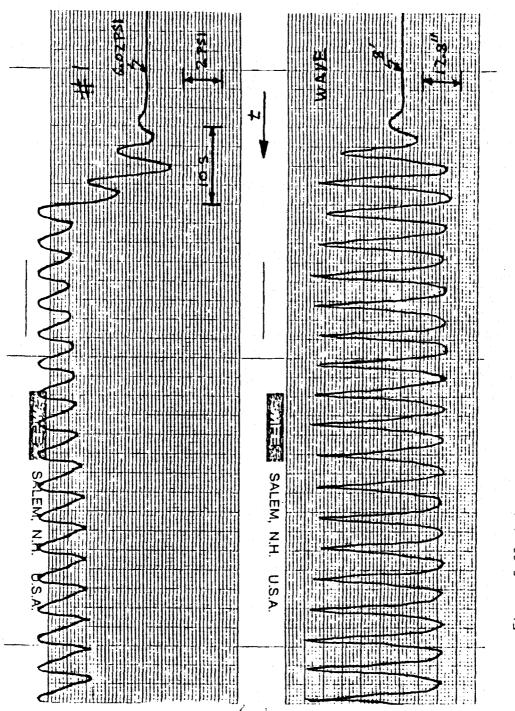


Figure 5.22 Laboratory measurements of wave-induced liquefaction.



Figure 5.23. Geotextile before failure.

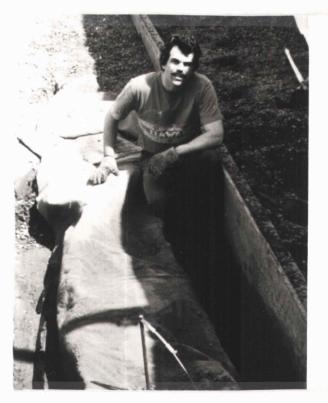


Figure 5.24. Geotextile after failure.

6.0 CONCLUSIONS

6.1 Summary

An analtyical model is developed to quantify the response of a horizontal, three-layered soil-geotextile-soil system to wave excitation. The theory is based on the Biot consolidation equations in which each soil layer is modeled as a homogeneous, isotropic, linearly elastic medium. The fluid flow in the interstices of the soil is described by an unsteady, compressible fluid form of Darcy's equation. The two soils are coupled through the geotextile which acts as an elastic permeable membrane. A general solution is obtained to the differential equations by seeking solutions with a simple harmonic dependence in time and in the direction of surface wave propagation. The solution is given as a 12 x 12 complex matrix which is solved numerically.

It is also shown that two other common methods for modeling wavesoil interaction, the potential pressure model and the earthquake consolidation equation, are simplifications of the Biot model. These models provide insight into the response of marine soils to ocean waves. The earthquake consolidation equation yields information on the mean accumulation of pore water pressure not revealed by the periodic Biot equation solution.

An examination of the Biot solution behavior indicates that:

- 1) the most important soil property is the permeability,
- 2) the pore water pressure profiles are very sensitive to the degree of saturation,
- 3) the soil response is frequency selective,
- soil stability may be slightly increased by pretensioning the geotextile.

Two series of laboratory experiments were conducted at the Oregon State University Wave Research Facility. In both cases the pore water

pressure was monitored in the soil and recorded as a function of time. These data, which are among the first to be taken in a large wave facility, are used to verify the theoretical model. A second result of the experiments is the documentation of a wave-induced liquefaction failure. Some investigators have expressed doubt about the actual occurrence of such failures.

6.2 Applications

The theoretical description of the combined soil-geotextile response to waves provides the basis for rational design procedures and geotextile selection. A fundamental consideration in the selection of a geotextile is the influence of the fabric hydraulic and mechanical properties on the dynamic response of the soil. In general, for commercially available geotextiles, this influence is very small. The fabric appears to be transparent; its main function being separation of the two soil layers. Exceptions to this are:

- When the geotextile becomes clogged with soil particles and the permeability is significantly reduced. This results in an undrained boundary condition which is much more susceptible to a liquefaction type failure due to the mean accumulation of pore water pressure.
- 2) When the geotextile is pretensioned. For the wave and soil conditions examined in Chapter 4, a pretensioning of approximately 100 lb/ft resulted in a 30% reduction in maximum shear stresses.

The theoretical model also predicts the dynamic response as a function of the soil properties. Results indicate that the relative permeability of the two soil layers is important. For a given design condition, a worst combination of geologic materials exists in terms of potential soil failure. The model may be used to select the optimum armor layer thickness for a given set of material properties. The soilgeotextile model may be used to model the response of a single homogeneous soil layer or a vertically inhomogeneous deposit, the vertical inhomogeneities being approximated by homogeneous horizontal layers.

6.3 Future Research

The development and verification of the wave-soil-geotextile interaction model provides the theoretical foundation for the analysis of a number of other wave-soil interaction problems. Among these are:

- The response of marine soils to random waves. The Biot consolidation equations are linear. Therefore, the solutions for the soil resonse at each frequency in the wave spectrum may be superimposed to yield the total response.
- 2) Soil stability on sloping beaches or structures. The down slope component of the weight tends to reduce the stability of the soil or armor. Mathematically, this is a difficult physical system to analyze because the coordinate system is not separable. However, several options are available. A solution may be sought be expanding the equations in terms of a small slope parameter or slope dependent soil parameters may be developed (e.g., a reduced sediment density).
- 3) Influence of standing waves. Standing waves frequently occur near large structures such as breakwaters and jetties, near beaches and in a wave tank. For a perfect standing wave, stationary regions with large soil responses would be associated with the antinodes of the standing waves. These areas may require additional protection due to the locally large erosive and soil destabilizing forces. Again, because the Biot equations are linear, superposition of two progressive waves may be used to model a standing wave.
- 4) Mean accumulation of pore water pressure. The solution developed to the Biot equations is strictly periodic in time while the solution to the earthquake consolidation equation provides no information on the dynamic response. A coupling of these two models would provide a more complete description of the wave-soil interaction process.

The periodic solution oscillates around the mean drift solution. The coupling is accomplished in the evaluation of the failure indicators, the shear stress ratio and the shear stress angle.

- 5) Buried pipe stability. Buoyant buried pipe lines may float to the surface during periods of reduced soil strength associated with periods of high wave activity. For small diameter pipes, the presence of the pipe may have a minor influence on the stress field. However, for larger diameter pipes, soil-structure interaction must be considered. A geotextile may reduce the failure potential by acting as a membrane in tension holding the pipeline down.
- 6) Wave-soil-structure interaction. The presence of a structure changes the wave field, possibly producing a standing wave as discussed above. A more accurate description of the fluid motion and resulting pressure distribution on the bottom may be obtained by solving the wave-structure interaction problem. The resulting bottom pressure is periodic in time but not space. Again, because the Biot equations are linear, the pressure distribution may be represented as a Fourier series, a solution obtained for each spatial frequency component and the complete solution obtained through superposition.

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APPENDIX A

List of Notations

a _n ;n=1,12	horizontal displacement integration constants
A1,A2,A3	Biot solution constants in soil layer 1
b _n ;n=1,12	vertical displacement integration constants
B1,B2,B3	Biot solution constants in soil layer 2
с	coefficient of consolidation
c _n ;n=1,12	pressure integration constants
CD	drag coefficient
Cf	friction coefficient
Cl	permittivity
° C _m	inertial coefficient
d,d ₁ ,d ₂	soil layer thicknesses
d	total thickness of both layers
e _x ,e _y ,e _z	normal strains
Ε	Young's modulus
g	accerlation due to gravity
G	shear modulus
h	water depth
Н	wave height
i	square root of -1
К	unsteady permeability
Kf	geotextile permeability
K _S	geotextile elasticity
Kw	bulk modulus of pure water

ĥ	steady permeability
l	length of text section
L	wave length
n	porosity
N	number of cyclic loadings
NR	number of cyclic loadings to liquefaction
p	excess pore water pressure
pg	reference pressure
pg	pore water pressure generation term
P _O	amplitude of dynamic wave-induced mudline pressure
P _S	hydrostatic pressure
p	dimensionless time-averaged pressure in earthquake equation
q	vector discharge velocity
đ -	vertical dependency of vector discharge velocity
r	shear stress ratio
r _e	relative error due to end conditions
R1,R2,R3	constants in potential pressure solution
S	pressure source term
S	degree of saturation
t	time
î	dimensionless time in earthquake equation
T	wave period
τ.	geotextile tension
T	potential pressure model transfer function

u	horizontal discharge velocity (relative to soil)
u _O	amplitude of near bottom fluid velocity
$\vec{v}_{A}, \vec{v}_{B}, \vec{v}_{C}$	vector velocities of solids, liquid and gas
W	vertical discharge velocity (relative to soil)
x	coordinate in direction of wave propagation
У	coordinate along wave crest
Z	vertical coordinate down from mudline
2 ·	dimensionless depth in earthquake equation
α	bottom slip parameter
α	pore pressure accumulation shape factor
β	liquid compressibility
β'	combined liquid-gas compressibility
γ	weight density of fluid
Υ _B	buoyant weight density of soil
Yx,Yy,Yz	shear strains
∆p	pressure drop across geotextile
∆zf	geotextile thickness
ε	volume strain
ζ	vertical displacement of soil
^к n	eignevalue in potential pressure model
[~] n	dimensionless eigenvalue in potential pressure model
λ	radian wave number
λľ	eigenvalue in Biot model
μ	geotextile displacement
ν	Poisson's ratio

ξ	horizontal displacement of soil
π	numerical constant (3.14159)
ρ	fluid density
ρ _A ,ρ _B ,ρ _C	densities of solids, liquid and gas
٥ , ٥ g	reference densities
σ _x ,σ _y ,σ _z	effective normal stresses
$\overline{\sigma}_{x}, \overline{\sigma}_{y}, \overline{\sigma}_{z}$	total normal stresses
σ ₀ '	effective overburden stress
τ	shear stress
Tij	total shear stress
τ _m	maximum shear stress
φ	shear stress angle
$\overline{\phi}$	geotextile mechanical property coefficient
χ	laterial displacement of soil
ΨΑ,ΨΒ,ΨC	relative mass of solids, liquid and gas
ω	radian wave frequency
$D(\cdot)$	vertical gradient operator
⊽(・)	gradient operator
$\nabla \cdot (\cdot)$	divergence operator
_⊽ 2	La Placian operator
(•)	time-averaged
(\cdot)	vector
$(\cdot)_1$	soil layer 1
(•) ₂	soil layer 2
(·) _{max}	maximum value in vertical profile

APPENDIX B

Computer Programs

B.1 Program GEOTEX

	PROGRAM GEOTEX (INPUT, TARES=INPUT, OUT PUT, TARES=OUT PUT,
	.DATA, TAPE7=DATA, CPRINT, TAPE == OPPINT, OPLOT, TAPE == OPLCT)
_ C *	· · ·
	REAL NU1.NU2.N1.N2.K1.K2.KF.LENGTH
	COMPLEX C1.C2.XLP1.XLP2.XP9.XP91.Xkp2.13.07 Complex HLL.STRFCH.XD14.DU42.DU42.
	COMPLEX FERO, A, E3, E4, E7, E3, 50, 510
	OIMENSION IDENT(15),7(42),F1(42),F2(42)
	COMPLEX Q(12,12),F1(12),F2(12),P3(12)
	COMPLEX S(12),CHECK(12),WK(12),WA(163)
	COMPLEX U(42), H(42), P(42), SIGX(42), SIG7(42), TAU(42)
	COMPLEX FVX(42),FV7(42),S3R(42),PHI(42) COMPLEX DUDX(42),DHT7(42),DMDY(42),DMD7(42)
	COMPLEX DPDX(42)+DPD7(42)+TAUM4X(42)
	COMPLEX SS(42), VS(42), FF(42)
C.+	
_ <u>C</u> =	***************************************
_0* _0*	THOUT HARTARIES
0.+	INPUT VAPIAELES.
- <u>0</u> +	HEACEP CARD
C*	FORMAT (15A4)
C.	IDENT(I) - DATA FILE TOFNTIFICATION
C* C*	
0.* 0.*	HAVE PARAMETEPS FCPMAT(8610.4)
Č*	LENGTH - WAV= L=NGTH
0*	PERIOD - WAVE PERIOD
C.	DEPTH - WATER DEPTH
<u>C</u> *	HEIGHT - WAVE HEIGHT
C.♥ C.♥	- PO - WAVE PRESSURE AMPLITUDE FOW - FLUTD DENSITY
Č*	FON - FLUID DENSITY G - ACCELERATION DUE TO GRAVITY
Ċ.*	CF - BCITOM FRIGTION OUSFRICIENT
C.+	
С* С*	SOIL PARAMETERS (1 CARD PER LAYER)
C.	FORMAT(8610.4) F1.62 - SHEAF MODULUS
Č.	NU1+NU2 - PCISSON'S PATIO
C.₹	N1.N2 - PCEOSITY
C*	SAT1.SAT2 - DEGRES OF SATURATION
C* ℃*	GAMMA1. GAMMA2 - PUCYANT WEIGHT
is≖ ij≢	C1.02 - SCIL LAYER THTOKNESS K1.K2 - PERMHADTLITY
Č+	K1,K2 - PERMEAGILITY CM1,CM2 - ACCED MASS COFFFICIENT
C.■	
€₹	GECTEXTILE PARAMETERS
C*	FORMAT(4610.4)
C* C*	GD - GEOTEXTILE ELASTICITY TEN - GEOTEXTILE TENSION
0+	TEN - GECTEXTILE TENSTON DZE - GECTEXTTLE THTOKNESS
Č*	KE - GECTEXTILE OCCMEADILITY
C *	
0*	INTERNAL PARAMETERS
C.+ C.+	FORMAT(1X+11.5X F10.7) NONDIM - DIMENSIONAL/DIMENSIONALCOC DEST DEAMERED
G*	シー・シート こうかんしゃ かんしん 手がいたい とうかん たいしょう からせい 日本 日本 日本
Č.₩	NONDINES OIMENSIONLESS PLOTS NONDINES OIMENSIONLESS PLOTS
9 ₹	ALP + POTTOM OLIP PARAMETER
¢*	The state of the

₽₹ 0<ALP<1 INTERMEDIATE Ċ+ ALP=1 NO SUIP Ç# 0#4 C.# Ç.# INPUT DATA C.. C.+ HEADER CAPD READ(7,50) (IDENT(I), I=1,15) 50 FORMAT (1X.1544) C¥ WAVE PARAMETERS C * READ(7,100) LENGTH. PERICD. DEPTH, HE IGHT. PD. PON. G.CF 100 FORMAT(8610.4) C.* C * SOIL PARAMETERS PEAD(7,200)61,NU1,N1,SAT1.GAMMA1.01,K1.CM1 200 FORMAT(8610.4) READ(7,200) G2, NU2, N2, SAT2, GAMMA2, D2, K2, CM2 C* С. GEOTEXTILE PARAMETERS PEAD(7.400) GE.TEN.DZE.KE 400 FORMAT (4610.4) C * C* INTERNAL PARAMETERS READ(7,450)NONDIN,ALP 450 FORMAT(1X, 11, 5X, F10, 7) C * C * * ********* C.* Č* PPINT INPUT DATA C * WRITE(8,480) 480 FORMAT(1H1///) WFITE(8,520) WPITE(8,510) WPITE(8,500) 500 FORMAT(10X, "* SOIL-GECTEXTILE INTERACTION MODEL *") HFITE(8,510) 510 FORMAT(10X,"*",35X,"*") WFITE(8,520) 520 FORMAT (10X, 37 ("*")) WRITE(8,550)(IDENT(I),I=1,15) 550 FORMAT(//5X, "IDENTIFICATION: ".1544//) WPITE(8+600) 600 FORMAT(5X ."WAVE FORAMETERS"/) WPITE(8,700)LENGTH, PEFTOD.DEPTH.HEIGHT.P0, POW.G, CF 700 FORMAT(10X, "LENGTH", 16X, 015.4/10X."PERIOD". 16X, 015.4/ .10X, "WATER CEPTH".11X, G15.4/10X. "MAVE HEIGHT".11X, G15.4/ .10X, "PRESSURE AMPLITUNE", 4X. 615. 47 .10X, "FLUID DENSITY".9X, G15.4/15X. "GRAVITY". .15X .615.4/10X . "BCTTOM FRICTION" .7X.615.4//) WPITE(8,800) 800 FORMAT(5X,"SOIL FARAMETERS") WRITE(8,900) 900 FORMAT(40X, "LAYER 1",17X, "LAYER 2"/) WPITE(8.1000)61.62.NU1.NU2.N1.N2 1000 FORMAT(10X, "SHEAF MODULUS", 3X.615.4.5%,615.4/ .10X. "POISSON'S PATIO",7X,615.4,5X.615.4/ .10X, "POROSITY".14%,615.4,5%,615.4) WEITE(8.1100)SAT1.SAT2.GAMMA1.GAMMA2 1100 FORMAT(10X, "DEGREE OF SITURATION". 27.615.4.5%,615.4/ .10X, "RUOYANT WEICHT", AY. 615.4.5X, 615.4) WRITE(8,1200)01.02.K1.K2.011.032 1200 FORMAT (10X, "THICKNEDS", 13X, 615, 4, 5%, 615, 4/ .10X, "PERMEARTLITY", 10X, 615.4.5X, 615.4/

```
.10X, "ADCEE MASS", 12X, 615, 4, 5X, 615, 4//)
       WPITE(8,1300)
  1300 FORMAT(5X,"GEOTEXTILE FARAMETERS"/)
       WPITE(8,1400)GE, TEN, DZE, KF
  1490 FORMAT(10X, "ELASTICITY", 12X, 615.4/
      .10X. "TENSION", 15X.615.4/
.10X. "THICKNESS".13X.615.4/
      .10X, "PERMEARILITY". 10X, G15.4/)
C.*
C***
            *****************************
C+
C*
       PPOGRAM VARIABLES
C *
C*
         ZERO
                       - COMPLEX 0.0
С.
         Δ
                       - SART (-1.0)
C.*
         F
                       - PADIAN WAVE FREDHENCY
ņ.
                       - FLUID COMPRESSIBILITY
         RETA1.BETA2
C *
         XKP1, XKP2
                       - UNSTEADY PERMEANTLITY
Č.#
         Хt
                       - FIRST ETGENVALUE (SAME IN BOTH LAYERS
C*
                         AND IS EQUAL TO THE WAVE NUMBERT
C *
         XLP1+XLPZ
                       - SECOND EIGENVALUES FOR LAYERS 1 AND 2
C*
         9(I,J)
                       + COEFFICIENT MATPIX
C.*
         SIT
                       - FORCING VECTOR
C*
         R1(I)
                       - HORIZONTAL DISPLACEMENT CONSTANTS
C *
         R2(I)
                       - VERTICAL DISPLACEMENT CONSTANTS
C*
         R3(I)
                       - PRESSURE CONSTANTS
C *
         U(I)
                       - HORIZONTAL DISPLACEMENT
C*
         W(T)
                       - VERTICAL DISPLACEMENT
C*
         0(I)
                       - PRESSURE
C.*
         FVX(I)
                       - HORIZONTAL FLUID VELOCITY
C*
         FVZ(I)
                       - VERTICAL FLUID VELOCITY
°C*
         STRECH
                       - MECHANICAL GENTEXTILS PROPERTY
C.*
         HLL
                       - HEAD LOSSINTMENSIONS OF LENGTH)
Č*
         Uð
                       - NEAP EDITOM WATER PARTICLE VELOCITY
C *
Q#
                        PRESSURE, STRESS AND SHEAR ARE NON-
C..
                        DIMENSIONALIZED AY PO.
C.*
                        DISPLACEMENTS ARE NON-DIMENSIONALIZED
C*
                        PY POTLENGTHICL.
¢*
                        FLUID VELOCITIES ARE NON-DIMENSIONALIZED
C *
                        EY XKP1*P0/(LENGTN*POW*G)
C *
C**
C *
C*
      CONSTANTS
      PI=3.14159
      A=(0.0,1.0)
      ZER0=(0.0.0.0)
      F=2.0*PI/PEFIDD
      UD=0.5*HFIGHT*PEFIOD/(LENGTH*COSH(2.0*PT*DEPTH/LENGTH))
      COMP=2.1859
      IF(G.GT.12.0)COMF=4.55E7
      PATH=101330.0
      IF(G.GT.12.0)PATH=2116.8
      SET 41=1.0/COMP+(1.0-SAT1)/(90W*G*(DEPTH+0.5*01)+PAT H)
      BETA2=1.0/COMP+(1.0-SAT2)/(FON+G*(0)PTH+01+0.5+02)+PATM)
      XKP1=1.0/(1.0/V1-(4*F)/(G*H1)-(A*F*CM1)/(G*H1))
      XKP2=1.0/(1.0/K2-(A*F)/(G*N2)-(4*F*CM2)/(G*N2))
C.*
C*
C*
      EIGENVALUES
      XL=2.0*PI/LENGTH
      AX=N1+BETA1+G1
```

```
BX=N2*BETA2*G2
      C1= (A*RCH*G*F)/(XKP1*G1)*(AX+(1.0-2.0*NU1)/
     .(2.0-2.0*NU1))
      C2= (4*ROW*G*F1/(XKP2*G2)*(8X+(1.0-2.0*NU2)/
      .(2.0-2.0*NU2))
      XLP1=CSQRT(XL=XL-C1)
      XLP2=CSORT (XL+XL-C2)
C*
C*
      MORE CONSTANTS
      C3=1.0-NU1
      C4=1.0-2.0*NU1
      C5=1.0-NU2
      C5=1.0-2.0*NU2
      DB=01+02
      STRECH#+TEN#XL#XL#A#XL#GF
      IF(KF.E0.0.0)KF=1.0E-50
      HLL=DZF *XKP2/KF
      E1=COSH(XL+D1)
     ~E2=TANH (XL+01)
      E3=0.5*(CEXP(XLP1*01)+CEXP(-XLP1*01))
      E4=0.5*(CEXP(XLP1*D1)-CEXP(-XLP1*D1))
      E5=COSH (XL+DB)
      ES=TANH(XL+D8)
      E7=0.5*(CEXF(XLP2*D1)+CEXP(+XLP2*D1))
      EA=0.5*(CEXP(XLP2*D1)-CEXP(-XLP2*D1))
      E9=0.5* (CEXP(XUP2+08)+CEXP(-XUP2+n8)).
      E10=0.5*(CEXP(XLF2*DP)+CEXP(+XLP2*DA))
      A1=(1.0/XL)*(1.0+AX*(3.0-4.0*NU1)/C4)/(1.0+AX/C4)
      B1=(1.0/XL)*(1.0+PX*(3.0-4.0*NU2)/C6)/(1.0+BX/C6)
      A2=(2.0*F1)/(1.0+AX/C4)
      B2= (2+0+G2) / (1+0+BX/C6)
      A3= (ROW *C*F)/(XL *XKP1) * (AX+1.0)
      93=(ROW*G*F)/(XL*XKP2)*(9X+1.0)
C *
C***
    **********************
C *
C *
      COEFFICIENT MATRIX
C+
      7(1,1)
              = ZEPO
              = ZERO
      0(1,2)
              = ZERO
      9(1,3)
      17(1.4)
              = -4=42
      9(1.5)
              = -43
      0(1.6)
              ≈ ZERO
      9(1,7)
              = ZERO
      Q(1,8)
              = ZEPO
      0(1,9)
              = ZEPO
      9(1.10) = 75RC
      0(1,11) = ZEFO
      9(1,12) = 7ER0
C*
      9(2,1)
              = 1.0
      0(5.5)
              = ZEPC
      Q(2,3)
              = Z2R0
              = 03/04*(1.0-XL*A1)/XL
      0 (2,4)
      312.51
              = (03*XLF1*XLP1-NU1*XL*XL)/(XL*XL*04)
      (2.6)
              = ZERO
      9 (2 .7)
              = 7FRC
      0(2.8)
              = 7550
      0(2,9)
              = 7390
      P(2,10) = 7ER0
      0(2,11) = ZEP0
      0(2.12) = 7590
```

= ZEPO		
-		
-		
= 1.8		
= E2		
= -A1+F2+D1		
= (XLP1/XL)*E4/E1		
≠ -E2		
= -1.0		
= -01*E2+81		
. = 81*E2-01		
= -(XLP2/XL)*E8/E1		
= - (XLP2/XL)*E7/81		
= E2		
= 1.0		
= 1.0/(2.0*XL)-A1/2.0+01*52		
= {1+0+XL#A1}/{2+0#XL}#E2+01		
= (XLP1/XL)*E4/E1		
= (XLP1/XL)*E3/E1		
= -62/61*(1.0+XL*GE/62)		
= -G2/51*(1.0/(2.0*XL)-91/2.0+01*22		
+GE/G2*(1.0+XL*D1*E2))		
= -G2/G1*{(1,G-XL*31)/(2,G*XL)*E2+01		
+GE/G2*(E2+XL*01))		
= -G2/G1*(XLP2/XL+XLP2*GE/G2)*57/F1		
= 1.0		
= E2		
<pre>= 01*F2+(1.0+XL*A1)*03/(04*XL)+N1*A2/</pre>		
<pre>= 01*F2+(1.0+XL*A1)*C3/(C4*XL)+N1*A2/ = ((C3*XLP1*XLP1+NU1*XL*XL)/(XL*XL*C4 E3/E1</pre>		4***2)
	<pre>= 1.0 = 01*E2-A1 = -A1*F2+D1 = (XLP1/XL)*E4/E1 = (XLP1/XL)*E3/E1 = e2 = -1.0 = -01*E2+A1 = -(XLP2/XL)*E3/E1 = -(XLP2/XL)*E3/E1 = -(XLP2/XL)*E3/E1 = -(XLP2/XL)*E3/E1 = -(XLP2/XL)*E3/E1 = (XLP2/XL)*E3/E1 = (XLP2/XL)*E3/E1 = (XLP1/XL)*E3/E1 = (XLP1/XL)*E3/E1 = -62/G1*E2*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(1.0+XL*GE/G2) = -62/G1*(XLP2/XL+XLP2*GE/G2)*E3/E1 = -62/G1*(XLP2/XL+XLP2*GE/G2)*E3/E1 = -62/G1*(XLP2/XL+XLP2*GE/G2)*E3/E1 = -62/G1*(XLP2/XL+XLP2*GE/G2)*E3/E1 = -62/G1*(1.0-N1)*G1) *XL*G1*(1.0-N1)*G1)</pre>	<pre>= 2.0*XL = -(XL*A1-1.0) 77EPO 77EPO 2 2.0*XLF1 77EPO 77</pre>

	0(7,6) =	Q(7+5)+E4/E3
	Q(7,7) =	- (RT1+STRECH*E2)
	Q(7,8) =	- (RT1*E2+STRECH)
	0(7,9) =	(RT1*(C5/(XL*C6)*(XL*B1-1.0)*F2+D1)
	•	-N2*R2*F2/RT2+STRFCH*(B1-01*F2))
	0(7,10) =	RT1*(05/(XL*06)*(XL*31-1.0)-01*52)
	•	-N2*P2/FT2+STRECH*(91*E2-01)
	0(7,11) =	(RT1*NU2*XL*XL+05*XLP2*XLP2)/(XL*XL*06)
		-12*83/(A*PT2)*F7/E1-STRECH*XLP2/XL*E8/51
	0(7,12) =	(RT1*(NU2*XL*XL-C5*XLP2*XLP2)/(XL*XL*C6)
		-N2+B3/(A+FT2))+EA/51-STRECH+XLP2/XL+E7/61
C.+	•	THE BOATA PIED COVEL STREEPERAL COVEL
•	Q(8.+1) =	7270
	· -	ZERO
		A+E2
		A~EZ A
		43/A2*E3/E1
		43/A2*E4/E1
		ZERO
		ZERO
		-A+P?/A2+(E2+XL+(-HLL))
		-4*82/42*(1.0+XL*(~HLL)*52)
		+83/A2*(E7/E1+XLP2*(~HLL)*E8/E1)
	0(8,12) =	-P3/A2*(E8/E1+XLP2*(-HLL)*E7/E1)
C.+		
	Q(9,1) =	ZERO
	Q(3,2) =	ZERO
	0(9,3) =	- Δ
	0(9,4) =	-A*E2
	0(9,5) =	-A3/42*(XLP1/XL)*E4/E1
	Q(9,6) =	-43/42*(XLP1/XL)*E3/E1
	0(9,7) =	ZEFO
		75 R0
		XKP2/XKP1*A*82/A2
		XKP2/XKP1*A*82/A2*E2
		XKP2/XKP1+R3/A2+(XLP2/XL)+E8/F1
		XKP2/XKP1+83/A2+(XLP2/XL)+E7/21
C#		SAMERAR & GOVAE CALLERALY LIVET
	Q(10,1) =	75 20
		ZEPO
		ZERO
	-	ZERO ZERO
	Q(10,6) =	
		ALP+(1.0+ALP)+XL*NP+56
		ALP*E6+(1.0-ALP)*XL*NA
		ALP+98+(1.0-4LP)*98*(1.0+XL*98**6)
		4LP*78*56+(1.0-4LP)*78*(56+XL*78)
		ALP*E9/E5+(1.0-ALP)*XLP2*08*E10/55
	((10,12)=	ALP*F10/E5+(1.0-ALF)*XLP2*09*E3/E5
C*		
	Q(11,1) =	
	0(11,2) =	
	9(11,3) =	
	0(11,4) =	ZERO
	Q(11,5) =	ZERO
	0(11,6) =	ZERO
	0(11.7) =	-E6
	Q(11,8) =	-1.0
	0(11,3) =	B1-0 ⁿ *E6
		B1+EA-DB
		- (XL92/XL)*E10/55
		- (XLP2/XL)*E9/85

```
C.
       Q(12,1) = ZEP0
       0(12,2) = ZEPO
       0(12.3) = ZERG
       0(12,4) = ZERO
       0(12,5) = ZERO
       Q(12,6) = ZEP0
       Q(12,7) = ZERO
       0(12,8) = 7580
       Q(12, 9) = -\Delta
       Q(12,10) = -4 + E5
       Q(12,11) = - (XLP2/XL)+93/92+810/85
       0(12+12)= - (XLP2/XL)+83/P2+E9/E5
C₽
C= #
             ***********************
Č*
Č+
c*
       WRITE COEFFICIENT MATFIX
C*
       WRITE(8,480)
       WRITE(8,1500)
 1500 FORMAT(/20X."COEFFICIENT MATRIX"//)
       00 1600I=1,12
       WRITE(8,1700) (REAL(0(I,J)), J=1.12)
 1600 WRITE(8+1300)(41MAG(0(1+J))+J=1+12)
 1700 FORMAT(2X,12E10.3)
 1800 FORMAT(2X.12F10.3/)
C#
C * *
                      **************
C.
C.
       FORCING VECTOR
C =
       S(1) = CMPLX(P0.0.0)
       S(2) = ZEPO
       XX=(1.0/G1)*(8.0/(3.0*PI)*ROW*CF*00*00)
       S(3) = CMPLX(XX, 0.0)
       S(4) = 7ERO
       3(5) = ZERO
       S(5) = ZERO
       S(7) = 7ERO
       S(8) = ZEPO
       5(9) = 7ERO
       S(10) = ZERO
       S(11)= 7ER0
       S(12) = ZEPO
C#
Ĉ#
       WPITE FORCING VECTOR
       WRITE(8,480)
       WFITE (8,1900)
 1900 FORMAT (///10X, "FORCING VECTOR"//)
       DO 2000I=1,12
 2000 WRITE(8,2100)REAL(S(1)),41MAG(5(1))
 2100 FORMAT(2X,2E15.5)
C*
       WRITE CONSTANTS
       WPT TE (8+2102)
 2102 FORMAT (//10X, "CONSTANTS" //)
       WRITE(R.2104)XL, FFAL (XUP1), PEAL (XUP2), AIMAG(XUP1), AIMAG(XUP2)
 2104 FORMAT (5%, "XL", AX, E15, 6/5%, ")L01", 6%, F15, 8, 5%, "XL02", 6%, 515, 8/
     .15X .815 .8.15X.715.9)
 WPITE(8,2106)41.E1.42.P2.P2AL(47).REAL(87).ALMAG(43).AIMAG(43).
2106 FORMAT(5X,"A1".AX.E15.8.EX,"P1".AX.E15.8/CX."A2".AX.E15.8,
.5X."P2".8X.E15.8/5X."A3".3Y.E15.8.5X."B3".AX.E15.3/
     +15X +E15 +8 +15X +815 +8)
```

```
Appendix B (continued)
            WPITE(8,2109)HLL
       2108 FORMAT(5X, "HLL", 7X, E15.8, 157, E15.8)
      C+
     č*
      C*
            159=0
            CALL LE02010,12,12,5,1,12,0,WA, HK, [EP)
      C*
      C *
      Č*
      Č*
            CHECK GOEFFICIENT MATRIX
      C*
            00 2109I=1,12
       2109 R1(I)=S(I)
            DO 2112I=1,12
            SUM=ZERO
            DO 2110J=1,12
       2110 SUM=SUM+0(I,J) *R1(J)
       2112 CHECK(I) = 3UM
            WRITE(8,2114)
       2114 FORMAT(///IDX,"CCEFFICIENT MATRIX CHECK"//)
            00 2116I=1,12
       2116 WRITE(8,2118)CHECK(I)
       2118 FORMAT (2X, 2E15.5)
      C*
      C*
            VERTICAL DISPLACEMENT INTERPATION CONSTANTS
            R2(1) =-A*R1(2)+A*A1*R1(3)
            R2(2) =-A*R1(1)+A*A1*F1(4)
            R2(3) =+A*R1(4)
            R2(4) = -A^*R1(3)
            R2(5) =+A*XLP1/XL*R1(6)
            R2(5) =-A*XLP1/XL*R1(5)
            R2(7) =-A*R1(8)+A*81*R1(9)
            R2(8) =-A*R1(7)+A*B1*P1(10)
            R2(9) =-4*R1(10)
            R2(10) = -A*R1(9)
            R2(11)=-A*XLP2/XL*R1(12)
            R2(12) = -A*XLP2/XL*R1(11)
     C*
C*
            PRESSURE INTEGRATION CONSTANTS
            R3(1) =- A* 42* F1(4)
            R3(2) =-A*A2*F1(3)
            P3(3) =ZER0
            R3(4) =ZEPO
            R3(5) =-A3*R1(5)
            R3(6) =-A3+R1(6)
            R3(7) =-A*32*R1(10)
            R3(8) =-A*B2*P1(9)
            P3(9) =ZERO
            R3(19)=7EP0
            R3(11)=-83*R1(11)
            P3(12)=-B3*P1(12)
     C*
      C.
            WEITE INTEGRATION CONSTANTS
      C.*
            WPITE(8,480)
            WFITE(8,2120)
       2120 FORMAT(20X, "INTEGRATICN CONSTANTS"//)
            WPITE(8,2130)
       2130 FORMAT(6X, "HOFTZONTAL DISPLACEMENT", 3X, "VERTICAL GISPLACENEUT",
           .11X, "PRESSURE"/)
            WRITE(8,2140)
       2140 FORMATICX, 3 (7X, "REAL", 5X, "IMAGINA PY ")/)
```

```
Appendix B (continued)
             DO 2150I=1,12
       2150 WPITE(8,2160)REAL(R1(I)), ATMAG(R1(I)), REAL(P2(I)), ATMAG(P2(I)),
            .REAL(R3(I)),AIMAG(R3(I))
       2160 FORMAT (2X, 3 (2X, 2E12. 5)/)
      C*
      C*
              COMPUTATION DEPTHS
      C*
             NZ=40
             07=08/NZ
             NZF =01/08*NZ+1.5
             1179=N7+2
             L=1
             DO 2200I=1,N7P
             IF(I.GT.NZF)L=2
       2200 Z(I)=0Z*(I-L)
      C *
      Č*
             HORIZONTAL DISPLACEMENT
      C *
             CALL FUNC (XL, XLP1, XLP2, Z, P1, N7F, N7P, U)
             XDIM=LENGTH*PO/G1
             WRITE(8,440)
             WPITE(8.2600)
       2600 FORMAT(//2X, "HORIZONTAL DISPLACEMENTS"//)
             CALL OUT1(Z,U,N7P,XDIM)
      C*
      C*
             VERTICAL DISPLACEMENT
      C*
            CALL FUNC(XL,XLP1,XLP2,Z.R2,NZF,NZP,W)
             HRITE(8,480)
             WRITE(8,2800)
       2800 FORMAT(//2X, "VERTICAL DISPLACEMENTS"//)
             CALL OUT1(Z.W.NZF.XDIM)
      C*
      C*
             PRESSURE
      C.*
             CALL FUNCIAL, XLP1, XLP2, Z, R3, NZF, NZP, P)
             XDIM=P0
             HPITE(8,480)
             WPITE(8,3000)
       3000 FORMAT(//2X, "PPESSURE"//)
             CALL OUT1 (Z.P.NZP.XDIM)
      C*
      C+
             HORIZONTAL AND VERTICAL GRADIENTS
      C*
            L=0
             XP=XLP1
            00 3010I=1.NZP
             DPDX(I) = 4*XL*F(I)
             DUDX(I)=A*XL*U(I)
             D H D X (I) = A + X L + W (I)
             IF(I.GT.NZE)L=6
             IF(I.GT.N7F)XP=XLP2
             D=7(I)
             OPD7(I)=XL*(%3(L+1)*SINH(XL*D)+R3(L+2)*DOSH(XL*D))+
            .XP# {0.5+(CEXP(XP*0)-CEXP(-XP*0))*P3(L+5)+
            +8+5*(CEXP(XP*0)+CEXP(+XP*0))***(L+5))
             0007(I) =xL*(F1(L+1)*SINH(XL*D)+P1(L+2)*003H(XL*D)+
            .P1(L+3)*(COSH(XL*D)/XL+0*SINH(XL*O))+
            .R1(L+4)*(SINH(XL*D)/XL+D*COSH(XL*D)))+
            •XP*(R1(L+5)*0.5*(CEXP(XP*D) -CEXP(-KP*D))+
            .R1(L+6)*0.5*(CFXF(XP*C)+CEXP(-XP*C)))
       3010 DW0 Z(I) =XL* (P2(L+1) *SINH(XL*D) +P2(L+2)*005H(XL*D) +
            .R2(L+3)*(COSH(XL*P)/XL+0*SINH(XL*O))+
```

	• R2(L+4) * (SINH(XL+D)/XL+D*COSH(XL+D)) +
	• XP* (R2(L+5)*0•3*(CEXP(XP*D)+CEXP(-XP*D))* • R2(L+6)*0•5*(CEXP(XF*D)+CEXP(-XP*D))
C.	• R2(L+0)*U+5*(LEXF(X+*U)+LEXP(=XP*()))
Č*	FLUID VELCCITY
č•	
Č+	DISCHARGE VELOCITY
Č,	DISCOMMOC ACCOLL
· ·	00 3100 I=1, NZF
	XY=XKP1
	IF(I.GT.NZF)XY=XKP2
	FVX(I) = -XY/(FOW+C) + DPCX(I)
	FV2(1)=-XY/(POW+C)+0P02(1)
3100	CONTINUE
	XDIH=(XKP1+P0/LENGTH)
	WRITE(8,480)
	WRITE(8.3200)
3200	FORMAT(//2X,"HORIZONTAL DISCHARGE VELOCITY"/
	2X, "(RELATIVE TO THE SCIL MATRIX)"//)
	XDIM=PO*XKP1/(LENGTH*FOW*G)
	CALL OUT1(Z,FVX,N7P.X0IM)
	WRITE(8,480)
	WRITE(8,3300)
3300	FORMAT(//2X, "VERTICAL DISCHARGE VELOCITY"/
	.2X, "(RELATIVE TO THE SCIL MATRIX)"//)
	CALL OUT1(Z,FVZ,NZP,XDIM)
C*	
C*	STRAINS
C.*	
C *	VOLUME STRAIN
	00 3552 I=1, N7P
3552	VS(I)=DUDX(I)+DWD7(I)
	XOIM=P0/G1
	WPITE(8,400)
	WRITE(8+3554)
3554	FORMAT(//2X, "VOLLHE STRAIN"//)
	CALL OUT1(Z, VS, NZP, XDIM)
C*	
C*	
C*	
	DO 3556I=1,N7P
3556	SS(I)=DUDZ(I)+DWCX(I)
	WRITE(0,480)
7550	WRITE(8,3558)
3228	FORMAT(//2X,"SHEAP STRAIN"//)
C+	CALL OUT1(Z,SS.NZP,XDIM)
-	SEEPAGE VELOCITY
-C*	SEEPAGE VELOUIT
C*	00 3400 I=1, NZP
	XN=N1
	IF(I.GT.NZF)XN=N2
	FVX (I) = (1.9/XN) + FVX (I)
3400	
2400	WEITE(8,480)
	WRITE(8,3500)
3500	FORMAT(//2X,"HORIZONTAL SEEPAGE VELOCITY"/
	.2X. "(RELATIVE TO THE SCIL MATEIX)"//)
	XDIM=PO *XKP1/(LENGTH*CCN*G)
	CALL OUT1 (Z.FVX.N7P.XCI4)
	WRTTE(A,440)
	WRITE(8,3550)
3550	

```
.2X. "(RELATIVE TO THE SCIL MATRIX) "//)
       CALL OUT1(Z.FVZ,N7P,X01H)
       XN=N1
       00 35501=1,NZP
       IF(I.GT.NZF)XN=N2
       FVX(I)=FVX(I)+XN
 3560 FVZ(I)=FV7(I)*XN
¢*
C.#
       STRESS AND SHEAP
C+
       XDIM=P0
       G=G1
       XNU=NU1
       00 3600I=1,NZP
       IF(I.GT.NZF)G=G2
       IF(I.GT.NZF)XNU=NU2
       SIGX(I)=2.0*G/(1.0-2.0*XNU)*((1.0-XNU)*DUDX(I)+
      .XNU *OWD7(1))
       SIG7(I) =2.0*G/(1.0-2.0*XNU)*((1.0-XNU)*DHD7(I)+
      .XNU*DUDX(T))
 3600 TAU(I)=G*(DUD7(I)+OWDX(I))
       XDIM=P0
       WRITE(8.480)
       WPITE(8,3700)
 3700 FORMAT(//2X, "HORIZONTAL EFFECTIVE STRESS"//)
       CALL OUT1 (Z.SIGX.NZP.XDIM)
       WRITE(8,480)
       WPITE(8,3800)
 3800 FORMAT(//2X, "VERTICAL EFFECTIVE STRESS"//)
      CALL OUTI(Z.SIGZ.NZP.XDIM)
      WRITE(8.480)
      WFITE(8.3900)
 3900 FORMAT (//2X . "SHEAP"//)
      CALL OUTI(Z.TAU.N7P, XCIM)
C*
¢*
      SHEAR STRESS ANGLE
ċ*
      WPITE(8,440)
 HPITE(8,3902)
3902 FORMAT(//2X,"SHEAR STRESS ANGLE"//)
      00 3904 I=1.NZP
      TAUMAX(I)=CSOPT(((SIG7(I)-SIGX(I))*0.5)**2+TAU(I)**2)
      DUM1=(SIGX(I)+SIGZ(I))*0.5
      DUM2=TAUMAX(I)/((DUM1+TAUMAX(J))*(DUM1-TAUMAX(I)))
      DUM3= (A+DUM2) / (A-DUM2)
      DUM4=CARS (DUM3)
      DUMS=REAL (DUM3)
      DUM6=AIMAC(DUM3)
      IFIDUM5.ED.9.0 .AND. CUMF.GT.0.010047=30.0
      IF(DUM5.EQ.0.0 .AND. DUMF.LT.0.0) DUM7=-90.0
      IF(DUM5.E0.0.0 .AND. 6045.E0.8.0) 0047=9.0
IF(DUM5.E0.0.0) 60 TO 3903
      DUM7=ATAN2(DUM6, DUM5)
 3903 CONTINUE
 3904 PHI (I) = (ALOG (DUH4) + A*OU'17)*0.5*A*(180./PT)
      XDIM=(1.0.0.0)
      CALL OUTIEZ, PHI.NZP, X0JH)
C*
С
     SHEAF STRESS PATIC
Č+
      WRITE(8.480)
      WRITE(8.3918)
 3910 FORMATE//2X, "SHEAF STRESS PATTO"//)
```

```
00 39201=2,NZP
       IF(I.LE.NZF)SSR(I)=TAUMAX(I)/(7(I)*GAMMA1)
      IF(I.GT.NZF)SSP(I)=TAUMAX([)/(7(N7F)*GAMMA1+(Z(I)-Z(N2F))*
     . GAHMA21
 3920 CONTINUE
      SSR (1) = 7ER0
      CALL OUT1 (Z,SSP, NZP, XDIM)
C.
C*
      OUTPUT TO GRAPHICS
C *
C *
      IIDPTH=0
      XDIM=CMPLX(1.0.0.0)
      IF(NONDIM.EQ.0)XCIM=LENGTH*P0/51
      CALL SCALE(U,FF,XDIM,NZP)
      CALL ARGMOD (FF.F1.F2.NZP)
      CALL OUTPLT (LENGTH, IDENT, NZF, NZP, YOIH, 1, IIDPTH, 7, F1, F2)
      CALL SCALE(W.FF.XDIM,NZP)
      CALL ARGMOD(FF, F1, F2, N7P)
      CALL OUTPLT(LENGTH, IDENT, NZF, NZP, XOIM, 2, IIOPTH, 7, F1, F2)
      IF (NCNDIM.E0.0) XDIM=PO
      CALL SCALE(P,FF,XDIM,NZP)
      CALL ARGMOD(FF.F1.F2.N7P)
      CALL OUTPLT (LENGTH. IDENT, NZF, NZP, XOIM, 3, TIMPTH, Z, F1, F2)
      CALL SCALE(SIGX, FE, XDIM, N7P)
      CALL ARGHOD(FF,F1,F2,NZP)
      CALL OUTPLT (LENGTH, IDENT, NZF, NZP, XDIM, 4, IJD PTH, Z, F1, F2)
      CALL SCALE(SIG7, FF, XDIM, N7P)
      CALL ARGMOD(FF.F1.F2.N7P)
      CALL OUTPLT (LENGTH, IDENT, NZF, N7P, XDIM, 5, IJO PTH, Z, F1, F2)
      CALL SCALE (TAU, FF, XDIM, N7P)
      CALL ARGMOD(FF,F1,F2,NZP)
      CALL OUTPLT(LENGTH, IDENT, NZF, NZP, XDIM, 6, TIDPTH, Z, F1, F2)
      IF (NONDIM.E0.0) XDIM=PG/G1
      CALL SCALE(VS, FF, XD IM, N7P)
      CALL ARGMOD (FF.F1.F2.NZP)
      CALL OUTPLT(LENGTH.IDENT,NZF,NZP,YDIM.7.IIDFTH.7.F1.F2)
      CALL SCALE(SS,FF,XDIM,NZP)
      CALL APGMOD(FF,F1,F2,NZP)
      CALL OUTPLT (LENGTH, IDENT, NZE, NZE, XDIM, 8, IIOPTH, 7, F1, F2)
      IF(NONDIN.E.O.O)XDIM=XKP1*P0/(LENGTH*ROW*G)
      CALL SCALE(FVX.FF.XDIM,N7P)
      CALL APGMOD(FF.F1,F2,NZP)
      CALL OUTPLT(LENGTH, IDENT, NZF, NZF, XOIM, 9, IIOPTH, 7, F1, F2)
      CALL SCALE(EV7, FE, XDIM, N7P)
      CALL ARGMOD(FF,F1,F2,N7P)
      CALL OUTPLT(LENGTH, IDENT, NZF, NZP, XOIM, 10, ITOPTH, 7, F1, F1)
      00 39701=1,N7P
       XN = N1
       IF(I.GT.NZF)XN=N2
      FVX(I)=FVX(I)/XN
 3970 FV2(I)=FV2(I)/XN
      CALL SCALE (FVX.FF.XDIM.NZP)
       CALL ARGMOD(FF+F1+F2,NZP)
       CALL OUTPLT (LENGTH, IDENT, NZF, HZP, XNIM, 11, IINPTH, 7, F1, F2)
      CALL SCALE(FV7.FF,X0IM,N7P)
       CALL ARGHOD (FF,F1,F2,NZP)
      CALL OUTPLT(LENGTH, IDENT, NZF, NZP, XDIM, 12, IIDPTH, 7, F1, F2)
      XOIH=(1.0.0.0)
      CALL SCALE(SSF.FF.X0 TM.NZP)
CALL ARGHOD(FF.F1.F2.NZP)
      CALL OUTPLT(LENGTH, ICENT, NZE, N7P, XOTM, 17, IIOPTH, 7, F1, F2)
       CALL SCALF(PHI, FF, KOTM, N7P)
```

```
CALL ARGMOD (FF.F1.F2,NZP)
       CALL OUTPLT (LENGTH, IDENT, N7F, N7P, XDIM, 14, IIDPTH, 7, F1, F2)
C*
C.*
 4000 CONTINUE
       END
C*
Č+++
           **********
C#
       SUBFOUTINE FUNC(XL,XLP1,XLP2,7,R,NZF,NZP,X)
       COMPLEX P (42) , X (42)
      DIMENSION Z (42)
      COMPLEX XP, XLP1, XLP2
      L=0
       XP=XLP1
       00 100I=1,NZP
      IF(I.GT.N7F)L=6
       IF(I.GT.NZF)XP=XLP2
      0=2(I)
  100 X(I)=R(L+1)*COSH(XL*D)+R(L+2)*SINH(XL*D)+P(L+3)*D*CCSH(XL*D)+
     +R(L+4)*D*SINH(XL*D)+R(L+5)*0.5*(CEXP(XP*D)+CEXP(-XP*D))+
     .R(L+6)*0.5*(CEXP(XP*0)-CEXP(-XP*0))
      RETURN
      END
C*
Ċ*
            **************
C *
      SUBROUTINE OUT1(7,X,N7F,XDIM)
      COMPLEX X(42), XDIM, FF(42)
      DIMENSION 2 (42) . X400 (42) . XAF6 (42) . FFM00 (42) . FFAR6 (42)
      WRITE(8,50)XDIM
   50 FORMAT(4X, "NCN-DIMENSICNALIZED BY", 2015.5/)
      WRITE(8,100)
  100 FORMAT(10X."7".12X, "REAL", 9X, "IMAGINAPY", 7X, "PODULUS",
9X, "PHASE", 6X, "DIMENSIONLEST", 2X, "DIMENSIONLESS"/)
      CALL APGMOD (X, XMCD, XARG, NZP)
      CALL SCALF (X.FF.XDIM.NZP)
      CALL ARGHOD (FF. FFMOD. FFAFG. N7P)
      00 2001=1.NZP
      H=Z(I)
      F1=PEAL(X(I))
      F2=AIMAG(X(I))
      F3=XM00(I)
      F4=XARG(I)
      F5=FFM00(I)
      FF=FFARG(I)
  200 WPITE(8,300)H.F1,F2,F3,F4,F5.F6
  300 FORMAT(F15.5.3F15.5.F15.5.E15.5.F15.5)
      RETURN
      END
C*
C *
               Č*
      SUBFOUTINE OUTPLT(XL. IDENT, "7F, N7P, XDIM, IFUNCT, IIDPTH.7, F1, F2)
      DIMENSION IF (14.8) (DENT(15) (F1(42) (F2(42))7(42)
      COMPLEX XHIM
C*
      DATA (IF(1+I)+I=1+8)/4H
                                    .4HHDST.4HZONT.4HAL D.
     .4HISPL,4HACEM.4HENT .4H
      DATA (IF(2,1),T=1,8)/4H
                                    .4H VER, GHTICA, GHL DE.
     .4HSPLA.4HCEME.4HNT .4H
                                    1
      DATA (IF (3, I) . T=1,8)/4H
                                    ,4H PD.4HE W.4HATEP.
     . 4H PRE. 4HRSUR, 4HE
                           .44
      DATA (IF(4,1),1=1,8)/4H HO.4HEI70.4HMTAL.4H EFF.
```

• 4HECTI, 4HVE S.4HTRES, 4HS /	
DATA(IF(5,1),I=1,8)/4H V,4HERTI,4HCAL ,4HEFFE.	
• 4HCTIV. 4HE ST.4HFESS.4H /	
DATA(IF(6,I),I=1,8)/4H ,4H ,4H SH,4HEAR ,	
.4HSTRE.4HSS .4H .4H /	
DATA(IF(7,I),I=1,8)/4H .4H .4H VOL,4HUME,	
4HSTRA-4HIN -4H -4H /	
DATA (IF(9,I),I=1,8)/4H ,4H ,4H SH,4HEAR , 4HSTRA.4HIN .4H .4H /	
DATA (IF(9,I),I=1,8)/4H HOR,4HIZON,4HTAL ,4HDISC. .4HHARG,4HE VE,4HLOCI,4HTY /	
DATA (IF(10,I),I=1,3)/4H VE,4HRTIC,4HAL D,4HISCH.	
.4HARGE.4H VEL.4HCGIT.4HY /	
DATA (IF(11,I),I=1,3)/4H - H0,4HRI70,4HNTAL,4H SEF,	
.4HPAGE.4H VEL.4HCCIT.4HY /	
DATA (IF(12,I),I=1,8)/4H V,4HEFTI,4HCAL,4HSEEP,	
.4HAGE .4HVELO.4HCITY.4H	
DATA (IF(13,1), I=1,8)/4H ,4H S,4HHEAR,4H STP.	
.4HESS .4HRATI,4HC .4H /	
DATA(IF(14, I), I=1, 8) / 4H , 4H S, 4HHFAR, 4H STR,	
. 4HESS . 4HANGL, 4HE .4H /	
DATA DEPTH 15HDEFTH1	
DATA IMOD /4HMOD /	
DATA IARG /4HAPG /	
C*	
IF(IIDPTH.EQ.1)GC TC 450	
IIDPTH=1	
WRITE(9,100)(IDENT(I),I=1,15)	
100 FORMAT(1X,1544)	
WRITE(9,200)N7F,N7P	
200 FORMAT(2X,12,6X,12)	
WRITE(9,300) 05 PTH, XL	
300 FORMAT(1X,45,2F12.5)	
W4ITE(9,400)(Z(I),I=1,NZP)	
400 FORMAT(1X,612.5)	
450 CONTINUE WPITE(9,500)(IF(IFUNCT,I),I=1,8).XDIM	
500 FORMAT(1X,844/1X,2615,5)	
WRITE (9,600) IMOD.IARG	
600 FORMAT (7X, A4, 12X, A4)	
00 7001=1,NZP	
700 WRITE(9,800)F1(I),F2(I)	
800 FORMAT (1X+2G15.5)	
RETURN	
END	
C.*	
- C * * * * * * * * * * * * * * * * * *	٠
C*	
SUBPOUTINE ARGMOC(F, FMOD, FAFG, NZP)	
DIMENSION F(42), FMOD(42), FAFF(42)	
COMPLEX F	
00 100I=1,N7P	
A1=FFAL(F(I))	
A2 = A IMAG (F(I))	
FMOD(I)=\$0RT(A1**2+A2**2) IF(A1.E0.0.0 .AND. A2.GT.0.0)TEST=30.0	
IF(A1.E0.0.0.0 .ANC. A2.UT.0.0) TEST=+90.0	
IF(A1.E0.0.0 ANC. A2.E0.0.0)7537=0.0	
IF (A1.E0.0.0) GO TO SO	
THS TEATANZ LAZ . GIT PS Z. ZYE	
TEST=ATAN2(A2.A1)*57.296 50 CONTINUE	
50 CONTINUE	

ENO C* C* SUBFOUTINE SCALE(X,F,X0IM,N7P) COMPLEX X,F,X0IM DIMENSION X(42),F(42) DO 100I=1,N7P 100 F(I)=X(I)/X0IM RETURN ENO

B.2 Program PLOTT

```
PROGRAM PLOTT (INPLT, TAPE5=INPUT, OUTPUT, TAPE6=OUTPUT,
   .SOILIN, TAPE7=SOILIN, TAPE10=0)
    DIMENSION IF(8), IDENT(15), IPLOTS(24), Z(42), F1(42), F2(42)
    DIMENSION ZD(41), FD(41), FF1(42), FF2(42)
    COMPLEX XOIN
    READ(7, 100) (IDENT(I), I=1, 15)
100 FORMAT(1X,15A4)
    READ(7,200)NZF,NZP
200 FORMAT(2X+12+6X+12)
    READ(7,230) DEPTH.XL
230 FORMAT(1X, 45, 612.5)
    READ(7,250)(Z(I),I=1,NZP)
250 FORMAT(1X,G12.5)
    NZPM1=NZP-1
    DD 2601=1,NZPM1
    II=I
    IF (I.GT.NZF) II=I+1
260 F1(I)=Z(II)
    F1(NZP) = Z(NZP)
    D0 2701=1.NZP
    II=NZP+1-I
270 Z(1)=F1(II)
300 FORMAT(1X, #ENTER TOTAL NUMBER OF FLOTS DESIRED#)
400 FORMAT(1X, #ENTER CODES FOR DESIRED PLOTS#//
   .1X, #HORIZONTAL DISPLACEMENT
                                         1 1/
   .1≯.≠VERTICAL DISPLACEMENT
                                         2 $1
                                         3 $)
   .1X. PORE WATER PRESSURE
500 FORMAT(1x, #HORIZONTAL EFFECTIVE STRESS
                                                 4 11
   .1X.≠VERTICAL EFFECTIVE STRESS
                                         5 1/
   .1X, #SHEAR STRESS
                                         6 21
   .1X, ≠VOLUME STRAIN
                                         7 11
   .1X, #SHEAR STRAIN
                                         8
                                           21
600 FORMAT(1X, #HORIZONTAL DISCHARGE VELOCITY
                                                 9 $/
   .1x. #VERTICAL DISCHARGE VELOCITY
                                        10 #/
   .1X, #HORIZONTAL SEEPAGE VELOCITY
                                        11 #/
   .1X. #VERTICAL SEEPAGE VELOCITY
                                        12 #/
   .1X. #SHEAR STRESS RATIO
                                        13 #/
   .1X, #SHEAR STRESS ANGLE
                                        1427
520 FORMAT(1X, #PHASE PLOTS+ (YES=1, NO=0)#)
    WRITE(6,300)
    READ *. NPLOTS
    WRITE (6,400)
    WRITE(6,500)
    WRITE(6,600)
    READ *, (IPLOTS(I),I=1, NFLOTS)
    WRITE (6,620)
    READ *, IPHASE
    WRITE(6,640)
640 FORMAT(1X. #FABRIC LOCATION SHOWN+ (YES=1.NO=0) #)
    READ *,LINE1
    NN = 1
    DO 1100N=1,14
    REA0(7,700) (IF(I),I=1,8), XDIM
700 FORMAT(1X,844/1X,2615.5)
    READ(7,750) IMOD, IARG
750 FORMAT(7X,A4,12X,A4)
    00 8001=1.NZP
800 READ(7,900)FF1(1),FF2(1)
900 FORMAT(1X,2G15.5)
    IF(IPLOTS(NN) .NE. N)GO TO 1000
```

```
Appendix B (continued)
             NN = NN + 1
             DO 9201=1.NZP
             II = I + 1
             IF(I.GT.NZF)II=I
             F1(II)=FF1(I)
         920 F2(11)=FF2(1)
             F1(1)=FF1(1)
             F2(1)=FF2(1)
             WRITE(6,950)IDENT,XDIM
         950 FORMAT(1X,15A4/,1X,2G15.5)
             CALL PLINOD (RUN, CASE, NZF, NZP, IF, DEPTH,
            .Z,F1,F2,IPHASE,LINE1,N,XL)
        1000 CONTINUE
        1100 CONTINUE
             END
             SUBROUTINE PLINCU (RUN, CASE, NZF, NZP, IF, DEPTH, Z, F1, F2,
            . IPHASE, LINE 1, NSSR, XL)
             DIHENSION F02(39),Z02(39),F01(40),Z01(40),F0(41),Z0(41)
             DIMENSION DOT1(491,0072(49)
             DIMENSION IF (8), Z(42), F1(42), F2(42), XLABZ(5), XLABF(10)
             DIMENSION XLAUZD(10)
             WIDTH=5.5
             HEIGHT=4.5
             CALL PLOTYPE(1)
             CALL TKTYPE(4010)
CALL BAUD(1200)
             CALL SIZE (WIDTH+2.0, HEIGHT+2.0)
             FMIN=0.0
             FMAX=F1(1)
             00 1001=1,NZP
         108 IF(F1(I).GT.FNAX)FMAX=F1(I)
             00 120I=1.50
             IEXPN=I-1
             IF(FHAX.LT.1.0) IEXPN=-IEXPN
             TEST=10.0**IEXPN
             IFIIEXPN.LT.0 .AND. TEST.LE.FMAXIGO TO 130
             IF(IEXPN.GT.0. AND. TEST.GE.FNAX)GO TO 130
             IF(FHAX.GE.1.0 .AND. FHAX.LE.10.0)GD TO 130
         120 CONTINUE
         130 CONTINUE
             00 1401=1.NZP
         140 F1(I)=F1(I)/10.0**IEXPN
             FMAX=FMAX/10.0**IEXPN
             EXPN=-IEXPN
             CALL RANGE (FMIN, FMAX, 5, FLOW, FHIGH, DIST)
             CALL RANGE(0.0,Z(1),4,ZLOW,ZHIGH,ZDIST)
             FFACT=WIDTH/FHIGH
              ZFACT=HEIGHT/Z(1)
             CALL SCALE(FFACT, ZFACT, 0.6, 1.0, FLOW, Z (NZP))
             DO 150180X=1.3
             CALL PLOT(FLOW,Z(NZP),0,0)
             CALL PLOT(FLOW,Z(1),1,0)
              CALL PLOT(FHIGH,Z(1),1,0)
             GALL PLOTIFHIGH, Z (NZP) , 1,0)
             CALL PLCT (FLOW, Z (NZP), 1,0)
         150 CONTINUE
       C *
              DL - HASH MARK LENGTH
              01=0.04
              NF=FHIGH/DIST-0.5
              DZ=Z(NZP)+OL
              00 2001=1,NF
              CALL PLOT(FLOW+I*CIST,Z(NZP),0,0)
              CALL PLOT(FLOW+I*DIST, DZ, 1,0)
         200 CONTINUE
              DZ=Z(1)-CL
              DIST2=DIST
```

	IF(IPHASE.EQ.1)DIST2=FHIGH/4.0
	IF(IPHASE.EQ.1)NF=3
	00 300I=1,NF
	CALL PLOT(FLOW+I*CIST2,Z(1),0,0)
300	CALL PLOT(FLOW+DIST2+I,0Z,1,0)
	$DZ = Z(1)/4 \cdot 0$
	OL=OL +F HIGH/Z(1)
	DF=FLOH+OL
	00 400I=1.3
	CALL PLOT(FLOW, Z(NZP) + I + 0Z, 0, 0)
400	CALL PLCT(OF+Z(NZP)+T*OZ+1+0)
	DF=FHIGH-OL
	NR=Z(1)/ZDIST-0.5
	D0 500I=1.NR
	CALL PLOT(FHIGH,Z(NZP)+I*ZDIST.0.0)
500	CALL PLOT(DF,Z(NZP)+I*ZDIST,1,0)
	D0 600I=1.5
600	XLABZ(I)=Z(1)-(I-1)+OZ
000	
	NF=FHIGH/OIST+1.5
	D0 700I=1,NF
	XLA8F(I)=(I-1)*0IST
C+	DS - LABLE CHARAGTER SIZE
	OS=0.0125*FHIGH
	DSF=0.0375+Z(1)
	DO 800I=1.5
80.0	CALL NUMBER (FLOW-6. 0+05, Z(NZP) + (I-1) + CZ-05F/4., 0.0.0.1.4. XLABZ(I))
	NRP1=NR+1
82 U	xLARZO(I)=(I-1)*ZOIST/XL
	00 840I=1,NRP1
84 0	CALL NUMEER(FHIGF+05/2.0.2(1)-(I-1)+20IST-05F/4.0.
	.0.0,0.1,5,XL48ZO(I))
	00 900I=1,NF
90.0	CALL NUMBER (FLOW-3.0+DS+(I-1)+DIST.Z(NZP)-DSF.0.0.0.0.1.4.XLABF(I))
	ENCODE (25,920,LABLE1)
920	FORMAT(#MODULUS X10 (SOLID LINE)#)
	CALL SYMBOL (FHIGH/2.0-23.0+05,Z(NZP)-2.5+05F,0.0.0.12,25,LABLE1)
	ENCODE(19,930,LAPLE3)
430	FORMAT(#DIMENSIONLESS DEPTH#)
	CALL SYMBOL (FHIGH+10.5+DS.Z(1)/2.0-7.5+DSF.90.0.0.12.19.LABLE3)
	IF(EXPN.GE.U.0)ISP=-1
	IF(EXPN.GE.10.0)ISP=-2
	IF(EXPN.LT.0.0)ISP=-2
	IF(EXPN.LE10.0) ISP=-3
	CALL NUMBER (FHIGH/2.0-2.2 "05.Z (NZP)-2.0*05F.0.0.0.10.15P.EXPN)
	ENCODE(21,940,LABLE2)
94.1	FORMAT(#ARGUMENT(DASHED LINE)#)
,,,,	CALL SYMBOL (FLON-6.0+DS,Z(1)/2.0-1.8+DSF,90.0.0.12,5,DEPTH)
	IF (IPHASE.EQ. 1) CALL SYNBOL (FHIGH/2. 0-18.0 *05, Z(1) +2.1*05F.0.0.
	.0.12,21,LABLE2)
	IF(NSSR_NE_13)G0 TO 960
	NZPM2=NZP-2
	00 950I=1,NZPM2
	II=I+2
	ZC1(I)=Z(II)
95 ()	FD1(I)=F1(II)
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	GALL LINE(F01,201,0,NZP M2)
~ ~ ~	GO TO 970
39 U	CONTINUE
	CALL LINE(F1,Z,O,NZP)
970	CONTINUE
	IF(IPHASE.EQ.0) GO TO 1500
	XP=FLDW-0.2+0S

```
YP=Z(1)+05F/2.0
      CALL SYMBEL (XP. YP.0.0,0.14,3,3HA>P)
      CALL SYMEEL (XP-1.85*05, YP,0.0,0.1, 3, 3H<v-)
      XP=FHIGH-OS
      CALL SYMBEL (XP, YP,0.0,0.14,3,3HA>P)
      XP=FHIGH/2.0-DS
      CALL SYMBEL (XP, YP, 0.0, 0.12, 3, 3HA>0)
C+
      DO 14001=1.NZP
 1400 F2(I)=(F2(I)+180.0)/360.0*FHIGH
C *
      IF (NSSR. NE. 13) GO TO 1480
      NZPH3=NZP-3
      CALL DASHES
      0014601=1.NZPM3
      II=I+2
      F02(I)=F2(II)
 1460 Z02(I)=Z(II)
      CALL LINE(FC2.ZC2.0.NZPM3)
      GO TO 1490
 1480 CONTINUE
      NZPM1=NZP-1
      DO 14501=1.NZPM1
      ZD(I) = Z(I)
 1450 FD(I)=F2(I)
      CALL DASHES
      CALL LINE(FC, Z0,0+NZPM1)
 1490 CONTINUE
 1500 CONTINUE
      IF(LINE1.E0.0)G0 TO 1560
      D0 15501=1,49
      XZ=(FLOAT (NZP)-FLCAT (NZF) +0.5)/FLCAT (NZP) +2(1)
      DOT1(I)=(FHIGH-FLOW)*(I)/50.0
 1550 DOT2(1)=XZ
      CALL PLOTIFLOW, XZ.0.0)
      GALL POINTS
      CALL LINE(DOT1, COT2,1,49)
1560 CONTINUE
      DS=1.5*0S
      00 1600II=1,8
      CALL SYMBOL (FHIGH/2.0-25.0*0S+(II-1)*6.38*0S,Z(NZP)-5.0*
     .DSF,0.0,0.15,4,IF(II))
 1600 CONTINUE
      CALL BELL
     CALL PLOTEND
      RETURN
     END
```

APPENDIX C

Determination of Test Section Length

The ends of the test section are no flow boundaries which are not included in the formulation of the Biot model. It is therefore necessary to examine the region of influence of this boundary. Laboratory measurements are only valid outside of this region. The longer the test section, the less the influence on the measurements made near the centerline. However, each increase in the length of the test section of three feet results in an additional four cubic yards of soil. It is therefore desirable to estimate an optimum test section length which minimizes both the volume of soil and the end effects.

To estimate the region of influence two, one-layer potential pressure models were developed; one for a test section of infinite length and the other for a test section of finite length. The boundary value problem for the infinite length test section is

$\nabla^2 p = 0$	(C.1a)
$p(x,z,t) = p^{*}(z) \cos(\lambda x - \omega t)$	(C.1b)
$p^{*}(0) = p_{0}$	(C.1c)
$\frac{d}{dz} p^*(d) = 0$	(C.1d)

A solution to this problem is

$$p = p_0 \frac{ch[\lambda(d-z)]}{ch(\lambda d)} cos(\lambda x - \omega t)$$
(C.2)

The boundary value problem for the finite length test section is given by

$$\nabla^2 p = 0$$
 (C.2a)
 $p(x,z,t) = p^*(x,z) \cos(\omega t)$ (C.2b)

$$\frac{\partial}{\partial x} p^*(0,z) = 0 \tag{C.2c}$$

$$\frac{\partial}{\partial x} p^{\star}(\ell, z) = 0$$
 (C.2d)

$$p^{*}(x,0) = p_{0} \cos(\lambda x)$$
 (C.2e)

$$\frac{\partial}{\partial z} p^{\star} (x,d) = 0$$
 (C.2f)

in which $\boldsymbol{\ell}$ is the length of the test section. A solution to this problem is

$$p = p_0 \sum_{n=0}^{\infty} \alpha_n \operatorname{ch}[\kappa_n (d-z)] \cos(\kappa_n x) \cos(\omega t)$$
 (C.3)

in which

$$\alpha_{n} = \frac{(-1)^{n} \lambda \kappa_{n} \sin(\kappa_{n} \ell)}{2\pi \operatorname{ch}(\kappa_{n} d) (\lambda^{2} - \kappa_{n}^{2})} ; \quad \lambda^{2} \neq \kappa_{n}^{2}$$
(C.4)

and

$$\kappa_n = \frac{n \pi}{2}$$
(C.5)

The relative error due to the end conditions, $\mathbf{r}_{e},$ is

$$r_{e} = 1 - \sum_{n=0}^{\infty} \frac{(-1)^{n} \lambda \kappa_{n} \sin(\lambda \ell)}{\pi (\lambda^{2} - \kappa_{n}^{2})} \frac{ch (\lambda d)}{ch(\kappa_{n} d)} \frac{ch[\kappa_{n}(d-z)]}{ch[\lambda(d-z)]} \frac{cos(\kappa_{n} x)}{cos(\lambda x)}$$
(C.6)

The portion of the test section in which the error is less than 5% is shown in Figure C.1 for different wave and test section lengths. The false bottom concrete plates are 12 feet long. Therefore, the

test section is most easily constructed at a multiple of 12 feet. A 36 foot test section provided an optimum between end effects and volume of soil.

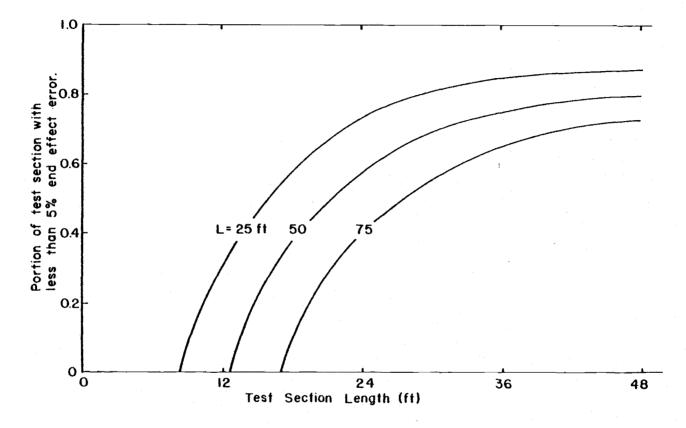


Figure C.1. Portion of the test section with less than 5% error due to the end effects as a function of different wave and test section lengths.

RUN.CASE.HEIGHT.PERIOC.DEPTH.P1 P2 Ρ3 P4 P S P6 P7 P3.FARRIC.REMARKS P.A 801 68 2.95 3.93 8.08 49.566 61.573 54.564 0.000 61.195 60.035 66.132 54.280 54.835 FAB a HEN 002 68 2.92 3.95 8.00 49.992 59.759 54.220 0.000 61.416 59.367 61.330 51.713 55.206 FAB 2 HIN 58.673 003 68 2.92 3.95 8.00 49.708 53.499 0.000 61.486 59.063 £1.955 50.979 54.835 FA3 4 HIN 804 68 2.92 3.95 8.88 49.785 59.035 54.476 0.000 61.923 59.731 62.078 54.260 55.576 FA3 8 HIN 005 68 2.92 3.95 8.00 49.148 58.673 \$3.643 0.000 59.003 61.135 59.43. 52.446 53.724 FA0 15 HIN 006 68 2.92 3.95 8.00 49.704 60.846 54.543 0.000 61.466 59.167 64.322 53.547 54.465 FAD 36 HIN 007 68 2.92 3.95 8.00 48.998 59.397 53.355 59.495 61.195 65.419 64.774 51.180 54.094 FAB 60 MIN 488 8A 0.68 1.77 8.00 .710 1.159 1.042 1.704 1.748 1.530 1.945 1.650 1.112 FAB 3.533 2.567 2.223 FAB 409 AB 1.36 1.77 8.00 1.775 1.992 2.161 3.263 3.533 4.114 010 BC 2.03 1.77 8.00 2.556 3.260 3.645 5.075 5.537 5.463 6.544 4.218 3.779 FA3 011 7A 1.28 2.80 8.00 11.362 12.894 13.050 15.661 16.173 16.335 17.950 15.991 13.857 FAB 812 75 2.52 2.80 8.00 23.008 25.956 26.222 32.193 34.240 34.819 36.648 34.035 28.159 FAB 013 70 3.76 2.80 8.00 31.955 33.755 36.771 51.308 42.854 45.896 46.620 46.945 37.051 FA3 814 64 1.44 3.95 8.08 23.576 25.352 25.235 27.907 29.869 29.137 32.909 33.008 25.936 FAB 015 68 2.92 3.95 8.00 48.288 53.079 52.490 57.280 60.175 55.274 62.452 62.349 54.094 FA8 W16 66 4.40 3.99 8.00 \$2.273 50.656 FA3 10.712 45.554 44.175 < 3. 360 23.579 16.4.45 70.053 017 5A 1.55 5.59 8.00 31.955 34.763 34.688 36.611 37.154 36.786 41.136 45.474 35.569 FAB A18 58 3.67 5.59 4.40 52.904 54.327 55. 574 \$9.455 61.559 59.362 64.696 67.117 57.635 FAB 819 4A 1.56 8.84 8.00 36.216 39.839 38.214 39.153 48.796 40.428 41.510 48.050 38.533 FA0 \$20 68 2.92 3.95 8.64 47.578 50.705 51.624 57.135 58.135 51.546 62.826 62.349 53.724 FA3 G HIN 021 68 2.92 3.95 8.00 47.152 52.922 51.423 58.885 59.446 58.639 63.574 62.349 54.094 FA9 2 NIN 822 68 2.92 3.95 8.80 48.572 51.791 53.499 58.875 59.443 58.639 63.574 64.183 54.465 FAB 4 HEN 423 68 2.92 3.95 4.00 46.572 51.791 53.643 \$9.455 60.029 58.274 63.574 64.916 54.894 FAB A HIN 024 68 2.92 3.95 0.00 48.438 52.516 53.643 59.745 60.466 58.639 63.574 64.183 54.094 FAB 15 MIN 825 68 2.92 3.95 8.08 48.288 53.355 56.730 51.429 63.200 68.466 58.639 64.183 52.612 FAB 30 MIN 826 68 2.92 3.95 8.00 48.714 53.240 53,355 59.310 £0.758 59.367 63.574 63.449 52.612 FAB 60 HIN 27 RUN MESSING 028 8A 0.68 1.77 8.00 1.420 1.987 1.442 1.450 1.457 1.821 1.878 1.834 1.112 FAB 029 88 1.36 1.77 8.00 2.130 1.811 2.163 3.263 3.643 3.278 3.748 2.934 2.594 FAB 038 AC 2.83 1.77 8.88 2.485 2.897 3.645 5.075 5.464 5,827 6.731 4.461 3.335 FA8 031 7A 1.26 2.00 8.00 18.652 11.598 11.536 13.776 15.299 14.569 15.706 16.471 14.828 FA3 032 78 2.52 2.80 0.00 22.724 26.077 27.358 30.453 35.269 33.511 33.508 35.900 26.677 FAB 033 70 3.76 2.80 8.00 21.245 36.218 37.493 44.954 46.625 48.097 52.355 46.945 38.533 FAS 034 6A 1.47 3.95 8.00 22.724 31.072 27.358 27.552 27.603 29.137 31.413 30.808 25.195 FAB 035 68 2.92 3.95 8.40 46.157 50.785 46.866 50.754 58.281 58.27% 12.272 58.681 51.871 FAB 836 60 4.48 3.95 8.00 60.160 65.192 64.891 72.506 72.851 72.843 78.532 88.687 66.692 FAB 037 SA 1.55 5.59 8.00 31.955 32,596 32.445 36.253 36.425 36.422 41.136 44.611 37.051 FA3 838 58 3.87 5.59 8.80 46.157 54.327 54.076 58.005 58.281 58.274 63.574 66.016 59.281 FAR 039 4A 1.56 8.84 8.08 36.926 36.050 39.839 39.153 40.796 40.064 43.360 47.679 40.756 FAU 040 68 2.92 3.95 8.80 46.863 50.785 49.029 58.005 61.195 61.917 67.376 62.349 55.576 FAB A MIN 50.705 841 68 2.92 3.95 8.88 48.288 51.913 58.005 58.281 58.274 64.322 62.349 51.871 FAB 2 NIN 042 6B 2.92 3.95 8.08 48.208 58.705 51.913 58.085 59.728 58.274 64.322 58.681 51.871 FAB 4 HIN 843 68 2.92 3.95 8.00 46.868 47.083 51.903 58.005 59.728 58.274 62.826 62.349 51.871 FAB A NTN 844 68 2.92 3.95 8.88 49.788 47.033 51.903 59.445 58.281 58.274 64.322 62.349 51.871 FAB 15 MIN 845 68 2.92 3.95 8.00 48.268 47.083 51.903 \$4.005 58.281 58.274 64.322 62.349 51.871 FAB 30 HIN 846 68 2.92 3.95 8.00 47.854 50.705 59.113 58.005 59.728 58.274 64.322 58.681 55.576 FAB 60 HIN 047 8A 0.68 1.77 8.00 . 355 .765 1.082 1.112 FAB 1.450 1.457 1.821 1.670 1.100 848 88 1.36 1.77 8.80 1.420 1.811 1.803 3.263 3.643 3.642 3.740 2.934 3.705 FAB 049 8C 2.03 1.77 8.08 2.485 3.260 3.605 5.075 5.464 5.463 6.357 3.705 FAB 4.034 050 78 2.52 2.00 0.00 24.144 26.801 25.843 31.903 33.511 34.965 37.396 \$4.475 28.908 FAB 051 7A 1.28 2.80 8.00 10.652 13.038 12.978 15.226 16.027 16.025 17.202 16.137 14.828 FA3 052 7C 3.76 2.80 8.00 34.086 36.218 38.935 44.954 46.625 48.876 50.859 46.945 40.015 FAS 853 6A 1.47 3.95 8.00 22.724 26.877 25.956 29.002 29.140 29.137 31.413 33.742 26.677 FA3 054 69 2.92 3.95 8.00 39.482 44.777 43.261 47.854 49.539 46.076 53.851 52.813 44.461 FAB 455 6C 4.40 3.95 8.00 56.809 61.570 61.286 72.586 72.851 72.843 18.532 77.019 66.692 FAB 856 5A 1.55 5.59 8.88 21.245 36.218 34.608 36.253 37.892 48.064 38.892 48.343 37.051 FAB 857 58 3.07 5.59 8.00 49.788 57,943 54.076 58.005 58.241 61.917 63.574 69.684 55.576 F#B \$58 4A 1.56 8.84 8.00 35.506 36.218 37.493 39.153 48.796 40.064 41.884 47.679 37.051 FAB 859 68 2.92 3.95 8.00 49.788 50.705 58.471 58.085 58/281 54.274 64.322 58.681 55.576 FAd A NEN 868 68 2.92 3.95 8.88 49.708 59.705 51.913 58.005 59.738 58.274 64.322 62.349 55.576 FA3 2 HIN 061 68 2.92 3.95 8.09 49.788 58.705 51.903 58.005 59.728 61.917 E4.322 62.349 51.871 FAB 4 HEN

APPENDIX D

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28.159 FAU 075 68 2.92 3.95 9.00 45.447 47.083 50.471 58.005 54.241 61.917 61.320 62.349 51.871 FAH 72.051 72. 443 79.953 67.464 FAB 076 66 4.46 3.95 0.00 60.360 65.192 68.496 72.506 74.532 077 5A 1.55 5.59 8.00 31.245 36.520 34.668 36.253 36.425 36.422 40.385 44.011 35.198 FAB 58.005 50.241 55.361 £3.574 66.016 57.429 FAU 074 5B 3.07 5.59 8.00 49.708 52.536 54.076 16.253 36.425 36.422 44.011 37.051 FAB 879 44 1.56 8.65 8.60 35.586 36.218 36.850 41.884 56.555 58.241 58.274 62.826 63.082 54.835 FAB A NIN 088 68 2.92 3.95 8.00 46.865 52.143 50.471 61.188 66.016 56.317 FAB 30 MIN 081 68 2.92 3.95 8.00 49.708 52.143 51.903 54.405 61.195 64.322 58.005 082 68 2.92 3.95 0.00 48.218 53.602 51.905 59.728 61.188 64.322 66.016 56.317 FAB 60 NIN 083 68 2.92 3.95 8.00 48.288 53.602 51.903 58.005 59.728 61.188 64.322 66.016 57.799 FAB 30 HIN 084 68 2.92 3.95 8.00 48.288 53.602 51.903 58.005 58.281 61.180 64.322 66.016 56.317 FAJ 120 MIN 64.322 885 68 2.92 3.95 8.08 48.268 53.602 51.903 59.445 61.195 61.108 66.016 57.799 FA9 150 HIN £4.322 086 68 2.92 3.95 8.00 48.288 53.602 51.903 58.905 59.728 61.186 63.082 57.799 FAB 180 MIN 59.721 64.549 56.317 FAB 210 MIN 887 68 2.92 3.95 8.00 48.288 53.602 51.903 58.085 58.261 62.826 888 68 2.92 3.95 8.88 48.288 52.143 51.903 59.445 61.195 61.188 €4.322 64.549 53.343 FAD 248 MIN 1.467 1.112 FAB 1.007 1.005 1.421 089 8A 0.68 1.77 8.08 .718 . 7 21 1.821 1.496 490 88 1.36 1.77 8.00 1.420 2.173 1.883 2.908 3,278 3.278 3.740 3.301 1.853 FAB 091 8C 2.03 1.77 8.68 2.485 3.268 3.605 4.356 5.100 5.827 6.357 4.034 3.705 FAG 892 7A 1.28 2.80 8.69 11.362 12.314 12.974 15.226 16.027 16.025 17.202 16.137 13.338 FA3 493 78 2.52 2.80 8.00 24.144 27.525 27.398 31.903 33.511 33.508 35.908 33.742 28.159 FAB 994 76 3.76 2.88 8.88 36.218 44.954 46.625 48.076 52.355 48.412 34.533 FAR 32.665 37.493 095 6A 1.47 3.95 8.00 26.077 25.956 27.552 27.683 29.137 31.413 32.275 26.677 FAB 22.724 096 60 2.92 3.95 0.00 46.868 51.429 57.681 56.555 58.281 58.274 62.826 62.349 48.166 FAB 897 66 4.48 3.95 8.88 56.869 61.574 61.286 68.861 69.206 72.843 74.793 77.019 62.987 FA3 098 5A 1.55 5.59 8.00 35.506 36.218 36.050 39.878 36.425 48.064 41.136 44.011 37.051 FAB 899 58 3.07 5.59 8.00 54.327 50.471 58.805 61.923 61.917 63.574 69.684 59.281 FAB 49.788 39.153 40.064 100 44 1.56 8.24 8.00 35.506 39.833 36.050 40.796 44.876 44.011 37.051 FA9 181 RANDOM WAVE 102 7A 0.64 1.58 4.80 6.526 7.285 7.649 8.965 6.968 5.147 FAB 3.551 4.346 5.047 7.968 13.776 15.299 15.297 17.950 12.470 103 78 1.26 1.58 4.00 7.101 10.094 8.151 FAB 16.071 13.338 FA9 104 7C 1.98 1.98 4.80 9.942 10.965 14.420 20.302 21.855 21.124 25.456 14.501 12.257 15.299 14.569 14.670 12.597 FAB 105 6A 0.74 2.00 4.00 9.231 10.965 16.454 106 69 1.46 2.80 4.00 19.883 22.455 24.514 29.002 30.597 32.051 34.405 28.687 23.713 FA9 107 5A 6.78 3.95 4.00 15.623 15.936 15.862 6.000 18.941 18.939 20.942 20.538 17.784 FAB 39.335 38.143 32.685 FA3 188 59 1.54 3.95 4.40 29.825 33.323 33.166 39.153 39.339 41.884 17.784 FAB 109 4A 0.78 6.25 4.00 14.202 15.936 15.462 17.401 18.941 17.482 19.446 23.473 30.282 118 48 1.54 6.25 4.00 26.984 30.423 33.353 36.425 36.422 38.892 42.544 32.685 FA3 111 8A 0.64 1.77 8.00 .718 .724 .721 1.450 1.821 1.021 1.870 1.160 1.112 PLS 112 68 1.36 1.77 8.00 1.775 1.811 2.900 4.006 4.114 2,934 2.223 PLS 1.863 3.643 113 60 2.83 1.77 8.08 2.840 2.535 2.084 4.713 5.828 5.827 6.357 4.461 2.964 PLS 14.581 16.025 17.202 15.484 13.338 PLS 114 7A 1.28 2.80 8.00 11.362 10.665 10.015 16.027 10.453 32.051 115 78 2.52 2.68 8.88 22.724 23.179 24.514 33.511 37.396 30.605 26.677 PLS 42.054 48.076 50.859 44.811 116 70 3.76 2.80 9.08 32.665 34.769 34.688 46.625 38.533 PLS 117 54 1.47 3.95 8.00 22.724 23.179 23.072 27.552 29.140 29.137 31.413 29.341 25.195 PLS 56.555 118 68 2.92 3.95 9.00 45.447 46.359 47.587 58.281 58.274 62.826 61.615 50.389 PLS 119 60 4.40 3.95 8.00 61.578 61.206 68.881 76.493 72.443 78.532 73.352 66.692 PLS 56.809 120 5A 1.55 5.59 8.00 31.955 28.974 29.561 36.253 36.425 36.422 41.136 40.343 33.346 PLS 121 58 3.07 5.59 8.00 46.157 50.705 58.471 58.754 50.201 58.274 63.574 58.681 51.871 PLS 122 4A 1.56 8.84 8.00 39.856 39.839 39.656 47.129 43.710 47.348 \$1.346 44.461 PLS 48.615 123 68 2.92 3.95 8.00 46.868 46.359 47.587 55.185 58.281 56.818 62.826 58.681 51.871 PLS 0 MIN 124 6B 2.92 3.95 8.00 45.447 46.359 47.587 55.105 58.281 58.274 61.320 58.681 51.871 PLS 2 HTN

Appendix D (continued

125 68 2.92 3.95 8.00 46.868 47.907 47.587 56.555 58.281 58.274 62.826 61.615 £1.871 PLS 6 HIN 48.288 49.029 58.005 59.728 61.108 63.917 63.082 51.871 PLS 4 HIN 126 68 2.92 3.95 8.00 47.807 49.629 56.555 59.728 58.274 64.322 61.615 51.871 PLS 15 HEN 127 68 2.92 3.95 8.00 48.841 47.607 \$6.555 58.281 56.414 62.826 63.082 50.389 PLS 38 MIN 128 68 2.92 3.95 8.09 46.868 47.807 49.029 64.322 50.349 PLS 60 MIN 129 68 2.92 3.95 8.00 46.868 46.359 47.587 56.555 59.728 56. 118 61.615 .710 1.457 1.874 1.100 1.112 PLS 60 HIN 138 8A 0.68 1.77 8.00 .724 1.082 1.450 1.621 2.223 PLS 60 MIN 131 48 1.36 1.77 4.00 1.775 1.811 1.843 2.900 3.643 3.278 4.114 2.190 5.983 3.301 2.594 PLS 60 HIN 132 86 2.03 1.77 8.00 2.485 2.535 2.844 4.358 5.180 5.899 10.815 14.501 12.597 PLS 60 HEN 9.942 13.141 14.570 14.569 16.454 14.670 133 74 1.28 2.68 8.00 134 78 2.52 2.80 8.90 24.144 21.731 25.956 31.903 32.054 32.051 35.990 32.275 25.195 PLS 60 NIN 42.054 49.363 42.544 37.451 PLS 60 MIN 32.665 31.472 16.050 45.168 45.163 135 70 3.76 2.80 8.80 21.731 29.917 29.341 22.231 PLS 60 HIN 136 64 1.47 3.95 8.00 22.124 23.072 27.552 29.140 27.680 137 68 2.92 3.95 8.00 45.447 44.910 47.527 53.655 58.261 56.818 61.320 60.138 48.937 PLS 68 MIN 56.809 57.944 56.279 68.981 72.951 69.201 74.793 73.352 62.987 PLS 60 MIN 138 60 4.40 3.95 8.00 41.136 48.343 37.051 PLS 60 HEN 139 5A 1.55 5.59 8.00 31.955 28.974 28.840 36.253 36.425 36.422 140 58 3.07 5.59 8.00 46.157 47.083 58.471 54.388 58.281 58.274 63.574 62.349 48.166 PL3 60 HIN 33.346 PLS 120 HIN 141 44 1.56 8.84 8.80 32.665 32.596 33.166 36.253 37.882 36.422 41.894 48.343 .741 PLS 120 HIN 1.870 .734 142 84 8.68 1.77 8.88 .721 1.065 3.278 1.821 .718 .724 3.740 2.934 1.853 PLS 128 HIN 143 88 1.36 1.77 8.08 1.775 1.449 1.803 3.082 5.100 3.276 6.357 3.668 2.964 PLS 120 HIN 144 BC 2.03 1.77 8.00 2.485 2.535 2.924 4.350 5.100 5.463 145 7A 1.28 2.80 8.00 10.652 11.536 15.226 15.299 15.297 17.202 14.678 12.597 PLS 120 HIN 10.141 26.677 PLS 120 HEN 146 78 2.52 2.80 8.80 22.724 21.731 24.154 31.178 33.511 33.508 34.485 38.604 43.504 44.811 37.051 PLS 120 MIN 147 76 3.76 2.10 4.00 31.245 38.425 36.050 46.625 46.620 49.363 148 6A 1.47 3.95 4.00 22.724 21.731 23.872 26.102 27.643 27.680 29.917 29.341 23.713 PLS 120 HIN 62.826 68.138 42.979 PLS 120 HIN 56.824 56.818 149 68 2.92 3.95 8.00 45.447 44.910 47.587 55.105 150 60 4.40 3.95 8.00 56.839 57.948 57.681 65.256 69.208 72.843 78.532 73,352 59.281 PLS 123 HIN 33.346 PLS 120 MIN 28.974 36.425 41.136 40.343 151 5A 1.55 5.59 8.00 28.485 29.848 12.628 36.422 152 59 3.07 5.54 8.88 46.157 54.380 47.083 46.866 54.638 54.632 59.834 58.681 48.166 PLS 128 MIN 153 44 1.56 8.84 8.08 34.886 32.596 33.166 37.793 39.339 40.064 41.864 40.343 37.051 PLS 120 MIN 1.100 1.879 .741 PLS 240 HIN 154 8A 0.68 1.77 8.00 .710 .724 .721 1.088 1.457 1.457 155 88 1.36 1.77 8.08 2.908 3.278 3.278 3.748 2.201 1.853 PLS 240 HIN 1.775 1.011 1. 683 4.350 5.983 3.361 2.964 PLS 240 MIN 156 AC 2.03 1.77 8.00 2.445 2.173 2.524 5.464 5.463 157 74 1.28 2.80 8.00 9.231 9.417 10.815 13.776 14.570 14.569 16.454 14.670 12.597 PLS 240 MIN 35.980 35.269 30.453 34.964 33.508 26.677 PLS 240 HIN 150 78 2.52 2.48 8.48 22.724 21.731 24.514 43.504 45.163 159 7C 3.76 2.88 8.88 32.665 38.423 36.850 46.625 58.859 44.011 34.533 PLS 240 MIN 160 6A 1.47 3.95 8.00 22.724 20.242 23.072 27.552 29.140 27.6 80 29.917 24.948 29.641 PLS 240 HIN 49.029 56.389 PLS 240 HIN 161 68 2.92 3.95 8.00 45.447 42.013 53.655 56.824 56.418 61.320 58.681 69.208 74.793 73,352 62.987 PLS 240 HIN 162 66 4.44 3.95 8.88 56.809 54.327 57.661 68.881 72.843 36.253 32.783 37.396 40.343 29.641 PLS 240 MIN 163 54 1.55 5.59 8.00 31.955 28.974 28.840 36.422 164 58 3.47 5.59 8.40 46.157 43.461 46.866 54.380 58.261 54.632 59.834 62.349 51.871 PLS 248 HIN 40.756 PLS 2.0 HIN 165 44 1.55 8.84 8.08 42.607 39.839 41.419 47.854 55.367 47.348 50.859 55.014 166 RANDON NAVE 167 8A 0.68 1.77 8.08 .718 . 124 .721 1.000 1.457 1.457 1.870 .734 1.112 PLS 480 HIN 3.740 1.534 1.853 PLS 480 HIN 168 88 1.36 1.77 8.00 1.775 1.449 3.263 3.278 1.442 3.642 169 80 2.03 1.77 8.60 4.076 PLS 490 HIN 2.485 2.535 2.884 4.350 5.100 3.463 5.963 2.934 170 7A 1.28 2.80 5.88 10.652 10.141 11.536 14.581 16.027 16.025 17.202 12.470 14.820 PLS 480 HIN 171 78 2.52 2.80 8.00 22.724 21.731 23. 172 30.453 33.511 33.508 35.900 27.874 32.605 PLS 483 HIN 172 70 3.76 2.80 8.00 31.245 28.974 33.165 42.054 45.168 46.620 49.363 36.676 44.461 PLS 483 HIN 173 6A 1.47 3.95 8.08 22.724 21.731 23.072 26.102 27.683 29.137 29.917 24.940 29.641 PLS 480 HIN 44.027 174 68 2.92 3.95 8.00 43.461 46.145 55.105 55.367 58.274 59.834 48.412 59.281 PLS 480 MIN 175 60 4.40 3.95 8.00 56.809 50.705 57.681 68.881 72.051 72.843 74.793 62.349 74.102 PLS 400 MIN 176 5A 1.55 5.59 8.00 28.405 28.974 25.840 32.628 32.783 36.422 37.396 36.676 37.051 PLS 480 MIN 54.388 12.987 PLS 488 HIN 177 58 3.87 5.59 8.80 46.157 46.866 54.638 58.274 59.834 51.346 43.461 178 44 1.56 8.84 8.00 39.339 48.756 PLS 488 HIN 34.886 32.596 33.166 36.253 40.864 41.884 37.185 179 7A 0.64 1.98 4.00 3.551 2.897 3.665 6.526 7.285 7.284 8.227 3.668 5.187 PLS 140 78 1.26 1.98 4.00 \$2.326 14.578 15.297 17.202 8.869 18.374 PLS 6.391 6.519 7.210 181 7C 1.88 1.98 4.00 17.401 21.127 24.682 11.736 15.561 PLS 7.811 7.968 8.642 21.853 182 6A 0.74 2.88 4.80 7.811 8.692 7.931 13.051 14.570 14.569 16.454 11.736 13.338 PLS 183 68 1.46 2.80 4.08 17.043 15.936 17.304 29.002 38.597 32.051 35.900 23.473 28.159 PLS 184 5A 0.78 3.95 4.00 12.978 17.484 28.942 19.266 PLS 12.782 11.590 17.401 16. 939 17.664 37.878 145 58 1.54 3.95 4.60 25.564 23.179 24.514 36.253 37.682 41.884 33.742 37.051 PLS 186 44 8.78 6.25 4.00 12.742 13.038 12.978 17.401 17.485 17.482 19.446 17.604 19.266 PLS

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107 40 1.50 6.25 4.00

24.144 21.731 24.514

1.84		0.68 1.	77	8.90	1.065	1.511	1.442	1.013	1.821	2.185	2.244	1.467	1.853 PL	,	
		1.36 1.			1.775	2.897	2.163	2.538	3.276	3.642	3.740	1.834	2.223 PL		
		2.03 1.			2.540	3.944	3.245	3.988	5.464	5.463	5.983	2.934	3.335 PL		
		1.24 2.			11.362	13.036	12.257	12.326	15.299	16.025	16.454	11.003	11.856 PL		
		2.52 2.			24.144	27.525	24.514	27.552	33.511	32.051	35.900	24.940	25.195 PL		
		3.76 2.			34.036	40.564	36.050	39.153	46.625	46.620	49.363	33.742	37.051 PL1		
194		1.47 3.			21.303	24.628	23.072	24.652	27.603	27.660	29.917	22.805	23.713 PL		
		2.92 3.			45.447	52.143	47.587	52.194	58,281	58.274	59.834	46.945	48.907 PL		
		4.40 3.				65.192	61.286	60.724	69.208	67.201	74.793	58.681	59.281 PL		
196		1.55 5.			56.809 29.825	33.320	30.282	31.983	34.968	34.965	37.396	30.001	31.123 PL		
								58.754	58.201	51.274	59.834	47.679	48.166 PLV		
		3.07 5.			46.157	54.327	46.866	37.703	39.339	39.335	41.884	33.742	35.569 PL1		
		2.92 3.			34.086	36,218		50.754	55.367	56.818	58.338	52.801	62.246 PLY		нти
					44.027		46.145		56.824	56.818	59.834	54.280	62.246 PL		MIN
		2.92 3.			44.027	49.256	47.587	50.754	58.281	58.274	61.320		63.728 PLV		MIN
		2.92 3.			45.447		48.668	52.194		58.274		54.280	65.210 PL		HIN
		2.92 3.			45.447	49.256	47.587	52.194	64.109 56.024	58.274	61.320 61.320	52.803 52.803			
		2.92 3.			45.447	50.705	47.587	53.655					65.210 PL		
		2.92 3.			45.447	50.705	47.587	53.655	56.824	54.274	59.834	52.803	66.692 PL		
		2.92 3.			45.447	50.705	49.829	53.655	58.281	58.274	59.434	46.945	63.728 PL1		
207		0.68 1.			1.065	1.067	1.982	1.450	1.821	1.457	1.870	1.100	1.482 PLY		
		1.36 1.			2.130	2.535	2.163	2,900	3.278	3.278	3.740	2.567	2.594 PL1		
		2.03 1.			3.196	3.622	3.605	4.350	5.464	5.827	6.357	3.668	5.187 PL		
210		1.28 2.			10.652	12.314	11.536	14.501	14.570	16.025	17.282	13.937	17.043 PL1		
		2.52 2.			24.144	27.525	25.956	31.903	33.511	33.508	35.900	27.874	35,569 PL		
		3.76 2.			32.665	37.666	36.850	43.584	46.625	46.620	50.459	42.544	48.987 PL1		
		1.47 3.			21.303	24.628	23.072	26.102	27.683	29.137	28.421	24.948	29.641 PLY		
		2.92 3.			45.447	50.705	47.547	52.194	55.367	56.818	56.842	52.803	62.246 PL1		
		4.40 3.			56.809	57.948	57.601	65.256	69.200	72.843	74.793	62.349	77.807 PLY		
		1.55 5.			29.825	32.596	30,262	33.353	34,968	36.422	37.396	33.00 4	40.756 PLV		
		3.07 5.			46.157	50.705	43.261	50.754	54.635	58.274	59.834	51.34E	62.987 PL1		
		1.56 8.			32.665	39.839	33.166	36.253	39.339	48.864	41.884	36.676	44.461 PL1		
		0.68 1.			1.065	1.449	1.082	1.450	1.821	1.821	2.244	1.100	1.482 PLV		
		1.36 1.			1.775	2.173	2.163	2.538	3.274	3.278	3.740	2.261	2.964 PL1		
		2.03 1.			3.196	4.346	3.245	4.350	5.464	5.827	6.357	3.668	4.446 PL1		
		1.28 2.			11.362	11.599	10.815	14.501	15.299	15.297	16.454	13.203	15.561 PL1		
		2.52 2.			0.000	26.077	24.514	30.453	30.597	33.500	35,900	27.874	35.569 PL		
		3.76 2.			0.000	36.218	36.850	48.683	46.625	45.161	50.853	36.143	48.907 PLV		
		1.47 3.			22.724	24.628	23.672	27.552	27.643	27.680	29.917	24.940	32.605 PL		
		2.92 3.			44.027	49.256	47.587	52.194	53.910	55.361	59.434	51.346	62.246 PL		
		4.40 3.			56.809	£5.192	57.601	65.256	69.298	69.241	74.793	62.349	74.102 PL		
		1.55 5.			29.825	32.596	30.202	33.353	34.968	36.422	37.396	33.004	40.756 PLV		
		3.07 5.			46.157	54.327	58.471	54.380	54.638	58.274	63.574	51.346	E6.692 PL1		
		1.56 8.			32.665	39.839	33.166	34.683	39.339	40.064	48.385	36.676	44.461 PL1		
		0.68 1.			1.065	1.449	1.882	1.008	1.457	1.021	1.674	1.467	1.482 PL1		
		1.36 1.			2.130	2.173	2.163	2.538	3.643	4.086	3.740	2.567	2.964 PL1		
233		2.03 1.			3.986	5.795	3.665	4.350	5.828	5.427	6.357	4. 834	4.817 PLV		
		1.24 2.			10.652	12.314	11.536	13.776	16.627	16.025	16.454	13.937	16.302 PL1		
		2.52 2.			24.144	27.525	24.514	29.062	32.054	33.508	34.485	27.874	35.569 PL1		
236		3.76 2.			34.016	37.666	36.050	39.153	46.625	46.628	49.363	39.610	48.987 PL		
		1.47 3.			22.724	24.628	23.072	26.102	27.683	29.137	29.917	24.948	31.123 PL		
234		2.92 3.			45.447	49.256	46.145	58.754	56.824	56.818	59.834	52.813	62.246 PL		
239		4.40 3.			56.849	61.570	57.601	£5.256	69.208	65.559	74.793	62.349	74.102 PL		
240		1.55 5.			28.405	32,596	30.202	31.903	34 - 968	32.779	29.917	33.008	40.756 PL		
		3.07 5.			46.157	58.705	43.261	54.754	54.638	54.632	59.834	47.679	62.987 PL		
		1.56 8.		B.00	34.006	36.218	34.608	37.703	39.339	40.004	43.380	.367	48.166 PL1	246	NTN -
		IDON HAV													
244		8.68 1.			.710	.724	1.062	1.008	1.021	1.821	1.670	1.100	1.482 PL1		
245		1.36 1.			1.775	2.173	1.803	1.813	3.276	3.278	3.740	2.201	2.223 PLV		
246		2.03 1.			3.196	3.622	3.245	3.625	5.828	5.463	5,983	3.301	4.076 PL		
247		1.20 2.			11.362	12.314	11.536	13.851	15.299	16.025	17.244	13.937	15.561 PL		
		2.52 2.			25.564	27.525	25.956	29.002	33.511	8.600	35.900	29.341	34.087 PL		
249		3.76 2.			24.144	34.769	25.956	29.002	33.511	29.137	35.900	27.874	35.569 PL1		
250	6A	1.47 3.	95	6.09	22.724	25.131	23.072	26.102	29.140	27.680	29,917	26.223	31.123 PL	4 8 J	WIN

251 58 2.92 3.95 8.00 44.027 50.705 46.145 49.304 55.367 56.318 58.338 51.346 E0.753 PLY 480 HIN 69.201 74.793 62.349 74.102 PLY 460 NIN 56.809 61.570 57.681 65.256 69.208 252 66 4.40 3.95 8.00 33.685 46.756 PLY 483 HIN 253 54 1.55 5.59 8.00 31.955 32.595 28.440 32.628 36.425 36.422 37.396 58.281 58.274 41.136 51.346 E2.947 PLY 444 HIN 254 58 3.07 5.59 8.00 46.157 58.705 46.866 54.380 255 4A 1.56 8.84 8.80 35.506 36.218 33.166 39.153 39.339 36.422 41.054 48.343 40.756 PLY 438 MIN 6.286 5.187 PLY 9.349 6.413 256 74 0.64 1.98 4.00 4.971 5.478 4.687 5.075 8.814 9.417 9. 173 11.238 15.663 15.297 17.576 9.536 12.597 PLY 9.231 257 78 1.26 1.98 4.00 16.302 PLY 254 76 1.88 1.98 4.00 11.362 13.838 12.974 15.226 20.398 21.853 23.914 13.203 14.570 11.856 PLY 10.094 11.601 14.569 15.786 11.736 259 64 0.74 2.08 4.80 9.942 10.141 28.159 PLY 260 68 1.46 2.88 4.88 21.393 21.731 21.638 24.652 29.140 30.594 32.909 24.948 17.484 15.939 19.446 16.137 17.784 PLY 261 54 0.74 3.95 4.00 14.202 15.936 14.420 15.951 37.882 37.878 41.864 33.742 37.051 PLY 262 58 1.54 3.95 4.88 28.485 39.423 28.840 31.903 17.950 17.604 20.749 PLY 15.951 17.484 17.482 263 44 0.78 6.28 4.00 15.623 15.936 14.420 33.508 37.396 30.868 37.051 PLV 264 48 1.58 6.25 4.00 27.044 28.974 28.840 29.002 36.425 1.870 1.482 NON 1.100 265 4A 8.68 1.77 8.00 .710 1.007 1.082 1.450 1.821 1.021 2.900 3.643 2.914 3.740 1.834 2.964 NON 266 88 1.36 1.77 8.00 1.420 1.011 1.803 4.076 NCN 5.039 5.983 3.361 267 AC 2.83 1.77 8.00 2.897 3.245 4.713 5.464 2.130 16.025 16.302 NON 268 74 1.28 2.80 8.00 11.362 12.314 12.257 15.226 15.299 16.454 13.203 34.067 NON 269 78 2.52 2.80 8.48 22.724 26.077 25.956 33.353 33.511 33.508 34.405 27.074 39.618 \$1.871 NON 36.050 44.954 46.625 45.163 49.363 274 70 3.76 2.40 8.04 34.006 36.218 271 64 1.47 3.95 8.00 24.144 24.628 24.514 27.552 27.653 26.223 29.917 27.474 31.123 NON 63.728 NON 58.338 54.280 53.904 272 68 2.92 3.95 8.80 46.868 50.705 50.471 55.105 56.824 72.851 69.201 78.532 66.016 77.807 NON 273 66 4.40 3.95 8.88 60.364 65.192 E1.286 68.881 274 5A 1.55 5.59 8.08 31.955 36.253 36.425 36.422 37.396 29.341 44.461 NON 36.218 32.445 59.934 58.281 58.274 55.814 78.397 NOH 275 58 3.17 5.59 8.80 49.700 54.327 50.471 58.805 40.343 48.166 NOH 276 44 1.56 8.84 8.80 35.506 36.218 39.656 36.253 40.068 40.064 41.136 55.361 58.338 52.403 65.210 NON a HIN 277 68 2.92 3.95 8.80 48.284 52.143 50.471 \$6.555 56.824 58.281 54.288 £5.210 HON 2 HIN 278 68 2.92 3.95 8.00 48.288 52.145 50.471 58.845 56.818 59.834 56.818 £1.328 52.803 E8.174 NON 4 NIN 279 68 2.92 3.95 8.00 48.288 52.143 51.903 58.005 58.281 58.281 56.818 61.320 52.803 68.174 NON 8 MIN 51.905 58.005 268 68 2.92 3.95 8.08 48.288 52.143 66.692 NON 281 68 2.92 3.95 8.00 48.208 52.143 51.903 58.845 58.201 56.818 61.320 54.280 15 HIN 58.281 61.320 68.174 NON 30 MIN 65.256 56.818 54.280 282 68 2.92 3.95 8.80 48.268 52.143 51.903 50.471 56.555 58.261 56.818 59.834 52.803 68.174 NON 60 NIN 243 68 2.92 3.95 0.00 48.288 52.143 244 84 8.68 1.77 8.88 .718 1.002 1.813 1.821 1.821 1.870 1.100 1.853 NON 60 HIN .724 3.335 NON 3.278 3.642 3.740 1.834 60 HIN 285 88 1.36 1.77 8.80 1.775 1.811 2.163 3.263 286 80 2.03 1.77 8.88 4.446 NON 60 HIN 5.933 2.934 2.840 2.535 3.605 5.438 5.464 5.463 14.501 14.570 13.840 15.706 13.263 16.302 NON 60 MIN 267 74 1.28 2.48 8.00 18.652 12.314 12.417 32.054 30.594 32.909 34.087 NON 68 MEN 288 78 2.52 2.60 8.00 22.724 24.628 25.956 31.943 27.074 47.425 NON 60 HIN 45.168 43.786 47.867 34.143 269 70 3.76 2.40 4.00 31.245 34.769 36.050 43.504 24.624 29.137 24.948 31.123 NON 68 HEN 290 6A 1.47 3.95 8.00 22.724 24.514 26.102 27.683 28.421 63.728 NON 60 MIN 291 68 2.92 3.95 8.00 45.447 49.256 47.541 55.105 \$5.367 53.964 58.338 49.679 69.208 50.990 67.313 62.349 77.807 NON 60 NIN 292 66 4.40 3.95 8.00 53.259 57.948 57.681 68.861 44.461 NON 60 NEN 293 54 1.55 5.59 4.00 36.218 33.166 36.253 36.425 32.779 37.396 33.008 31.245 294 58 3.07 5.59 8.08 54.327 52.273 58.005 58.281 47.348 63.574 55.815 66.692 NON 60 HEN 46.157 295 44 1.56 8.84 8.80 35.506 39.839 39.656 36,253 40.068 40.002 41.136 48.343 48.166 NON 60 MIN 1.870 1.853 NON 240 HIN 296 84 8.68 1.77 8.80 1.834 .710 .724 .721 1.458 1.821 1.321 297 88 1.36 1.77 8.00 1.420 1.811 2.161 2.988 3.274 3.642 3.745 2.201 2.964 NON 248 MIN 4.876 NON 240 MIN 298 80 2.03 1.77 8.08 2.130 2.897 3.685 4.713 5.828 5.463 5.983 3.668 299 7A 1.28 2.80 8.00 9.942 14.098 15.299 14.164 16.454 13.203 16.302 NON 240 HIN 12.257 12.314 300 79 2.52 2.80 8.00 27.394 33, 353 33.511 32.051 34.405 26.487 34.087 NON 240 HIN 24.144 24.624 45.168 47.867 36.676 51.871 NON 243 HEN 301 70 3.76 2.60 8.00 31.245 36.218 36,050 43.504 45.163 302 64 1.47 3.55 8.00 24.144 24.623 24.514 26.102 27.683 26.223 28.421 23.473 34.887 NON 240 MIN 53.984 59.834 48.412 69.656 NON 240 HIN 303 68 2.92 3.95 8.60 46.157 49.256 50.471 54.340 54.638 71.053 58.681 77.887 NON 248 HIN 304 66 4.40 3.95 8.80 56.889 61.578 57.681 68.881 69.208 69.201 0.000 39.266 36.676 44.461 NON 2.0 MIN 385 5A 1.55 5.59 0.00 33.730 36.215 32.445 36.253 38.247 306 58 3.07 5.59 8.00 57.945 54.076 58.005 61.923 61.917 67.313 55.014 66.692 NON 240 HIN 53.259 307 44 1.56 0.04 8.00 31.245 32.596 31.724 33.353 33.511 36.422 35.900 36.676 44.461 NON 248 MIN 1.870 1.482 NON 488 HIN 308 8A 0.68 1.77 8.80 1.013 1.821 1.821 .734 .710 1.037 1.012 2.964 NON 483 MIN 309 80 1.36 1.77 8.00 3.263 3.278 3.276 3.740 2.201 1.775 1.449 2.163 4.876 NON 440 HIN 310 80 2.03 1.77 8.03 2.485 2.897 3.245 4.713 5.464 5.427 6.357 2.934 12.470 311 74 1.28 2.66 0.00 11.362 11.590 12,257 15.226 15.299 15.297 17.202 16.302 NOR 430 MIN 24.887 NON 483 HIN 32.851 35.900 26.407 312 78 2.52 2.88 8.80 22.724 26.077 27.395 31.903 32.054 313 70 3.76 2.80 8.80 31.245 34.769 36,050 43.504 45.168 43.786 47.867 36.676 48.907 NON 460 HIN Appendix D (continued)

314 64 1.47 3.95 8.80 22.724 24.628 23.672 27.552 27.633 27.630 29.317 22.LCS 35.569 NON 433 MIN 315 68 2.92 3.95 8.00 44.027 47.807 47.587 53.655 53.910 52.437 54.338 48.412 66.692 NOH 410 MIN 316 6C 4.44 3.95 8.00 56.839 61.570 57.681 65.256 50.996 61.917 74.793 58.681 81.512 NON 440 MIN 117 5A 1.55 5.59 0.00 35.586 36.218 32.445 36.253 36.425 40.064 41.136 36.676 44.461 HON 488 MIN 318 50 3.07 5.59 8.00 53.259 57.948 50.471 58.005 65.566 61.917 63.574 58.681 70.397 NON 438 MIN 319 44 1.56 8.84 8.00 28.405 32.596 38.222 31.903 38.597 32.779 34.435 29.341 48.756 NON 448 MIN 328 7A 0.64 1.98 4.88 3.551 4.346 4.607 7.613 7.649 8.013 9.349 5.135 6.669 NON 321 78 1.26 1.98 4.00 6.391 7.960 9.373 14.501 15.299 14.569 17,950 8.792 12.597 NOH 9.942 10.141 12.257 19.577 19.670 19.668 22.418 13.937 17.043 104 322 70 1.84 1.96 4.80 323 64 0.74 2.40 4.00 4.521 8.642 10.094 11.601 13.113 13.112 13.4E3 11.0C3 11.856 NOM 324 68 1.46 2.88 4.88 21.303 23.179 24.514 31.903 34.968 32.851 35.900 26.4C7 28.159 NON 325 54 9.74 3.95 4.00 17.043 18.833 17.304 20.302 21.855 21.853 22.438 17.604 20.749 NON 326 58 1.54 3.95 4.00 34.046 34.769 36.050 48.603 40.796 40.792 43.383 32.275 40.015 NON 327 44 6.78 6.25 4.00 17.043 17.365 17.304 20.302 20.398 18.939 20.942 20.538 19.266 NO4 328 48 1.54 6.25 4.00 29.825 31.872 31.724 37.703 36.425 43.746 43.348 33.742 38.533 NOA

RUN.CASE.HEIGHT.PERIOD.DEPTH. P10.P9 P3 ₽2 P1.FABRIC 1 7A 1.90 7.60 8.00 26.136 26.789 26.710 25.196 24.327 23.293 22.626 20.531 20.468 20.280 GRY 2 78 2.56 2.76 8.00 34.142 35.006 34.894 32.828 31.526 30.565 29.398 27.050 26.602 26.275 GRY 3 7C 3.38 2.78 8.08 45.432 46.434 46.382 43.688 41.919 40.517 39.127 36.361 35.684 35.311 GRV 4 6A 1.34 3.96 8.08 29.016 29.066 29.972 29.166 28.565 28.024 27.630 25.663 26.336 26.163 GRY 5 68 3.03 3.98 8.08 59.328 69.664 61.041 54.972 57.972 56.764 55.937 52.891 53.385 53.174 GRY 6 6C 3.79 4.00 8.00 77.325 77.154 77.502 74.456 73.472 71.969 70.985 67.333 67.686 67.535 GRY 7 54 1.67 5.58 8.00 37.526 38.524 38.689 38.129 37.742 37.269 37.112 35.010 35.847 35.937 GRY 8 50 3.17 5.61 8.00 59.501 60.599 61.185 59.608 58.845 57.968 57.385 54.416 55.320 55.209 GRY 9 4A 1.63 8.85 8.40 42.725 43.942 44.588 44.150 43.976 43.653 43.433 40.898 42.620 42.499 GRY 10 7A 1.11 2.79 8.88 15.595 15.637 14.146 14.545 13.798 13.386 8.671 11.718 11.888 18.229 GRY 11 78 2.43 2.81 8.08 33.667 33.979 38.478 31.387 29.927 28.925 18.823 25.846 25.933 21.194 GRI 12 7C 3.58 2.85 8.00 49.291 49.645 44.717 46.037 44.173 42.488 27.773 30.693 30.300 31.175 GRY 13 64 1.36 3.94 8.00 29.434 29.748 26.999 28.758 28.124 27.624 18.227 25.283 26.160 21.478 GRY 14 68 3.69 3.54 8.00 60.653 61.112 55.638 58.904 57.593 57.251 37.187 52.681 53.164 43.123 GRY 15 6C 4.14 3.98 8.08 77.198 76.681 78.276 73.442 72.296 71.564 46.704 66.568 67.023 54.158 GRY 16 54 1.75 5.59 4.00 37.800 38.150 34.490 37.674 37.292 38.600 24.426 34.446 35.441 29.319 GRY 17 58 3.29 5.58 4.09 59.875 68.122 54.692 54.871 57.838 56.955 37.858 53.674 54.727 44.561 GRY 18 44 1.76 8.84 8.00 43.661 43.997 40.362 44.866 43.718 43.417 28.934 40.885 42.532 34.640 GRY 19 74 1.11 2.03 8.00 15.768 15.845 15.694 14.870 14.149 13.533 13.009 11.756 11.668 11.597 PLS 20 78 2.53 2.78 8.00 34.546 34.592 34.258 32.548 30.828 29.487 28.373 25.843 25.522 25.291 PLS 21 7C 3.44 2.76 8.48 44.554 44.654 45.877 42.145 48.845 38.246 37.085 34.062 33.515 33.283 PLS 22 64 1.35 3.54 4.00 28.947 29.153 29.557 24.468 28.716 26.945 26.542 24.535 25.189 24.977 PLS 23 68 3.11 4.00 8.00 59.328 59.775 60.199 58.269 56.756 55.198 54.139 58.835 51.230 51.803 PLS 24 6C 3.42 4.83 8.88 75.896 75.586 76.868 73.736 71.878 69.775 68.558 64.478 64.719 64.454 PLS 25 5A 1.73 5.58 8.00 37.526 37.668 38.412 37.426 36.873 36.187 35.949 33.665 34.436 34.641 PLS 26 58 3.12 5.68 8.00 54.648 60.010 60.896 59.460 58.107 56.537 55.721 52.215 53.047 52.996 PLS 27 44 1.65 8.84 8.80 43.776 44.879 44.728 44.115 43.766 43.281 43.045 48.473 41.951 41.983 PLS 20 74 1.14 2.79 8.00 15.898 16.147 15.703 14.754 14.307 13.871 13.744 13.097 12.258 12.293 HHT 29 78 2.57 2.76 4.40 35.122 35.618 34.888 32.719 31.835 30.767 38.594 29.029 27.193 27.077 HHT 30 7C 3,33 2.78 8.00 44.453 45.001 43.996 41.372 40.323 39.054 30.707 36.868 34.779 34.580 HHT 31 6A 1.41 3.95 8.00 30.240 30.554 -1.043 29.626 29.299 28.679 28.796 27.798 27.082 27.147 HH 32 68 3.20 3.96 8.00 60.523 61.323 61.037 59.121 50.363 57.105 57.390 55.200 53.907 54.023 HH 33 6C 3. 97 3.93 8.00 77.573 78.291 77.863 75.455 74.695 73.027 73.424 10.632 69.141 69.328 NHT 34 54 1.79 5.59 4.00 34.174 38.699 38.438 38.234 37.989 37.407 37.785 36.394 36.185 36.466 NHT 35 58 3.27 5.60 0.00 59.731 60.490 60.708 59.355 58.977 57.877 58.435 56.251 55.648 56.113 HH 36 4A 1.66 8.85 8.88 43.661 44.202 44.686 44.197 44.170 43.510 44.124 42.443 42.718 42.906 HHT 37 74 1.13 2.79 8.08 15.797 14.301 13.898 14.162 14.179 13.901 13.851 13.275 12.865 12.925 PLS 34 78 2.56 2.76 8.09 34.920 31.800 30.257 30.752 30.447 29.931 29.890 28.783 27.629 27.814 PLS 39 7C 3.22 2.75 8.00 44.136 39.481 38.501 34.937 38.645 37.754 37.851 36.398 35.099 35.201 PLS 48 64 1.17 3.98 8.00 38.018 27.318 26.962 27.419 27.672 27.364 27.639 26.841 26.667 26.768 PLS 41 69 3.20 3.95 8.00 60.552 54.885 54.822 54.969 55.299 54.757 55.278 53.531 53.289 53.598 PLS 42 66 3.96 3.96 8.00 77.227 69.696 68.268 £3.558 69.893 69.177 69.964 67.794 67.266 67.816 PLS 43 54 1.72 5.58 8.00 37.973 35.279 34.892 34.971 35.349 34.852 35.320 34.307 34.324 34.682 PLS 44 58 3.21 5.60 8.08 59.774 54.998 54.901 54.936 55.128 54.208 55.131 53.285 53.179 53.845 PLS 45 4A 1.76 8.81 8.00 44.410 42.084 42.364 41.858 42.157 41.669 42.224 40.994 41.236 41.403 PLS

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2 1981 Measurements

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APPENDIX E

English/SI Unit Conversions

Area:	$1 \text{ ft}^2 = 0.0929 \text{ m}^2$
Density:	$1 \text{slug/ft}^3 = 515.4 \text{kg/m}^3$
Force:	$1 \ 1b = 4.4483 \ N$
Length:	1 ft = 0.305 m
Mass:	1 slug = 14.60 kg
Pressure:	$1 \ 1b/ft^2 = 47.9 \ N/m^2$
Specific Weight:	$1 \ 1b/ft^3 = 157.1 \ N/m^3$
Stress:	$1 \ 1b/ft^2 = 47.9 \ N/m^2$
Velocity:	1 ft/s = 0.305 m/s
Volume:	$1 \text{ ft}^3 = 0.0283 \text{ m}^3$