AN ABSTRACT OF THE THESIS OF

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Title: THE EFFICIENCY OF SMOOTH GOODNESS-OF-FIT TESTS
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Donald A. Pierce

Neyman (1939) obtained a quadratic score statistic for testing simple goodness-of-fit hypotheses in a family of "smooth" alternatives. Javitz (1975) and Thomas and Pierce (1977) described the appropriate quadratic score statistic for composite goodness-of-fit hypotheses against "smooth" alternatives. These statistics, $\psi_k^2$ and $\psi_k^2(\lambda_0)$, are described and matrices needed for their application to some examples are calculated. The possibility of applying the procedures to testing multivariate normality is considered and difficulties are seen to arise.

Noncentrality parameters for power calculations are derived, and a measure of asymptotic relative efficiency of the smooth tests with other tests based on quadratic score statistics is derived. This permits comparison of the smooth tests with $\chi^2$ goodness-of-fit tests of the Pearson type as well as locally best tests for parametric alternatives. For the examples considered the smooth tests for composite hypotheses are seen to perform better than the $\chi^2$ tests and,
while still giving protection against a wide range of alternatives, to be at least moderately efficient with respect to tests for parametric departures.

The Appendix contains a summary of the asymptotic distribution theory of $\psi_k^2$ and $\psi_k^2(\hat{\lambda}_0)$ and discussion of some optimality properties of the tests.
THE EFFICIENCY OF SMOOTH GOODNESS-OF-FIT TESTS

by

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This thesis is dedicated by my parents in recognition of their immeasurable loving impact on my life.
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THE EFFICIENCY OF SMOOTH GOODNESS-OF-FIT TESTS

I. INTRODUCTION

I.1. Goodness-of-Fit Tests

The application of any statistical procedure presupposes some model describing the observed phenomena. A simple and widely utilized type of model is the specification of a probability distribution for some appropriate random variable. Such a model might completely specify a single distribution or might encompass a family of probability laws which contains the correct but unknown distribution. The value of a statistical procedure in a given problem (as measured by its power, efficiency, etc.) depends on how nearly the unknown true probability law matches that the statistician assumed to be true in applying the procedure. Clearly, it is a problem of some importance to be able to evaluate how well a set of data agrees with the hypothesized probability distribution or class of distributions, i.e., to be able to test the goodness of fit of a distribution (or family) to a data set.

The development of goodness-of-fit tests has occurred throughout this century, and the statistician now has available a wide variety of different procedures. For example, Pearson's $\chi^2$, as well as the Kolmogorov-Smirnov, Cramér-von Mises, Anderson-Darling,
Watson, and other criteria are all appropriate for an arbitrary simple
goodness-of-fit hypothesis. In most applications, however, the
hypothesis is composite. Typically, it places the distribution in a
class of probability laws indexed by unknown and unspecified param-
eter values. A common procedure is to replace the unknown
"nuisance" parameter values by estimates and calculate Pearson's $\chi^2$
statistic, which is taken to have a $\chi^2$ distribution with degrees of
freedom reduced by one for each parameter estimated. However, with
commonly used estimators of the nuisance parameter, the statistic is
no longer asymptotically distributed as $\chi^2$; see Chernoff and
Lehmann (1954) or Kendall and Stuart (1973; Sections 30. 11-30. 19).
Lilliefors (1967, 1969), Durbin (1975), and Margolin and Maurer(1976)
have considered the use of Kolmogorov-Smirnov statistics for com-
posite hypotheses, especially in the cases of normality and exponen-
tiality. Pearson and Hartley (1972; Table 54) give percentage points
for several statistics in testing normality and exponentiality with
unknown parameters.

Because of the central role it plays in many statistical models,
the normal distribution has received special attention in the develop-
ment of goodness-of-fit tests. For example, tests based on the
sample skewness and kurtosis and the Shapiro-Wilk test are appropri-
ate for testing normality, as are, of course, all those tests applicable
to arbitrary continuous distributions. For discussion of testing for

Many goodness-of-fit tests, including several mentioned above, share the characteristic of giving moderate protection against many alternatives at the expense of not giving very good protection against any particular alternative, which might be acceptable if one has no idea of the type of alternative likely to be encountered. Very often, however, some class of alternatives can be identified. In this case, one might be able to embed the null distribution (or class) in a parametric family in such a way that the goodness-of-fit hypothesis corresponds to a hypothesis about certain parameter values. So, for example, can one consider the hypothesis that a Weibull shape parameter is unity to be a hypothesis of goodness of fit of the exponential distribution. In this manner, one can often construct a test which has very good power against the parametric alternatives, although one must often sacrifice power against alternatives outside the given class.

It is a general rule that, as the class of alternatives increases, the power of tests designed for the class tends to decrease for individual alternatives, and this is exemplified in the discussion above: parametric tests have good power in relatively small classes of
parametric alternatives, while the tests which seek to protect against all alternatives tend to have low power overall. The desire to find a compromise, a procedure which has reasonably good power over a relatively wide class of alternatives, leads to the smooth goodness-of-fit tests of Neyman and Barton. These tests are obtained by embedding the null density or class of densities in an exponential family containing the null density or class, which then corresponds to a hypothesis on the exponential family parameters, and also containing alternatives which are only slight or "smooth" departures from the null case. In this paper, the smooth goodness-of-fit tests are described in detail, and they are compared, chiefly in terms of efficiency, with procedures having wide-spread, moderate power, and with parametric procedures having highly focused power.

I.2. Preview

Smooth goodness-of-fit tests are neither well-known nor widely used. For this reason the derivation of the tests for simple and composite hypotheses is presented in Chapter II. The details of the asymptotic distribution theory and optimality properties are postponed to the Appendix. The application of smooth goodness-of-fit tests to the multivariate normal case is also considered.

The comparisons of smooth tests with certain other parametric tests, in terms of power and efficiency, reduce to comparisons of
noncentral $\chi^2$ distributions with, in general, differing noncentrality parameters and degrees of freedom. Such comparisons not only provide a means for evaluating the smooth tests, but also aid in the selection of the order or degrees of freedom of the test. The derivations of the noncentrality parameters and measures of efficiency are contained in Chapter III, along with calculations for several examples.

Chapter IV consists of discussion of the results of Chapter III and some concluding remarks.
II. SMOOTH GOODNESS-OF-FIT TESTS

II. 1. Quadratic Score Statistics

Neyman's smooth goodness-of-fit test is obtained by embedding the distribution specified by the null hypothesis in a parametric class indexed by a vector parameter $\theta$ and then testing the hypothesis $H_0: \theta = 0$, which is equivalent to the original goodness-of-fit hypothesis. The test of $\theta$ is based on the quadratic score statistic, which is particularly convenient for the smooth test. In this section, the quadratic score statistics are discussed in general. Details of the asymptotic theory and optimality properties are left to the Appendix. In the subsequent sections of this chapter these results are applied to smooth goodness-of-fit tests and several important examples are considered.

Let $X_1, \ldots, X_n$ denote a random sample from a distribution with density function $g(x|\theta)$, where $\theta \in \mathbb{R}^k$. It is desired to test $H_0: \theta = 0$. Suppressing the dependence on the observed $x_1, \ldots, x_n$, let $l.(\theta)$ denote the log likelihood of $\theta$ given $x_1, \ldots, x_n$, i.e.,

$$l.(\theta) = \sum_{i=1}^{n} \ln g(x_i|\theta).$$

The subscripted dot will always denote summation over the $n$ observations. For $j = 1, \ldots, k$ we define the efficient scores for the
ith observation

\[ U_{\theta_j}^{(i)} = U_{\theta_j}^{(i)}(0) = \frac{\partial \ln g(x_{ij} | \theta)}{\partial \theta_j} \bigg|_{\theta=0} \]

and

\[ U_{\theta_j} = U_{\theta_j}(0) = \sum_{i=1}^{n} U_{\theta_j}^{(i)}. \]

Finally, denote the vector of efficient scores by

\[ U_{\theta} = U_{\theta}(0) = \left[U_{\theta_1}, \ldots, U_{\theta_k}\right]. \]

Under suitable regularity conditions on the density \( g(x | \theta) \)

\[ E_0 U_{\theta_j} = \int U_{\theta_j} g(x | \theta=0)dx = 0 \]

\[ i_{\theta_j \theta_j} = i_{\theta_j \theta_j}(0) = \text{Var}_0 U_{\theta_j} < \infty \]

for \( j = 1, \ldots, k \), from which it follows that

\[ i_{\theta_j \theta_l} = i_{\theta_j \theta_l}(0) = \text{Cov}_0(U_{\theta_j}, U_{\theta_l}) < \infty. \]

Let the information matrix be denoted
then the covariance matrix of $U_\theta$ is given by

$$i_{\theta\theta} = n \, i_{\theta\theta}.$$  

In most cases of practical interest, $i_{\theta\theta}$ will be nonsingular; indeed this will be true for the goodness-of-fit statistics to be considered below. If, however, $i_{\theta\theta}$ is found to be singular, one can often reparameterize to a parameter, perhaps of lower dimension, for which the information matrix is nonsingular. Since $U_\theta^{(1)}, \ldots, U_\theta^{(n)}$ are independently and identically distributed random vectors with finite second moments, it follows by a multivariate central limit theorem, for example, Anderson (1958; Theorem 4.2.3), that $n^{-1/2}U_\theta$ is asymptotically distributed as normal with mean vector 0 and covariance matrix $i_{\theta\theta}$. Thus the quadratic score statistic

$$W_u = U_\theta' i_{\theta\theta}^{-1} U_\theta$$

is asymptotically distributed as $\chi^2_k$.

Rao (1948) suggested the use of $W_u$ for testing the simple hypothesis $H_0: \theta = 0$. In fact, $W_u$ is asymptotically equivalent to Wald's statistic, $\hat{\theta}' i_{\theta\theta}(\hat{\theta}) \hat{\theta}$, and to the likelihood ratio statistic,
$2[\ell(\hat{\theta})-\ell(0)]$, under standard regularity conditions; refer, for example, to Cox and Hinkley (1974; 9.3(ii)). Here $\hat{\theta}$ denotes the maximum likelihood estimator of $\theta$. Because of this equivalence, the quadratic score statistic inherits the optimality properties verified by Wald (1943) for the other two statistics; refer to the Appendix. In addition $W_u$ is often easier to calculate than either alternative statistic since, unlike the other two, $W_u$ does not require the evaluation of $\hat{\theta}$. In the goodness-of-fit tests to be considered below, the parameter $\theta$ is of little direct interest, and the simplicity of $W_u$ far outweighs any desire to estimate $\theta$.

The utility of $W_u$ for testing $H_0: \theta = 0$ arises from the fact that for $\theta^* \text{ near } \theta = 0$,

$$E_{\theta^*}U_{\theta^*} = i_{\theta^*}$$

$$\text{Var}_{\theta^*}U_{\theta^*} = i_{\theta^*}$$

so that for large $n$

$$n^{-1/2}U_{\theta^*} \sim N_k(n^{1/2}i_{\theta^*}, i_{\theta^*})$$

where $Z \sim L$ means that $Z$ is approximately distributed as $L$, in which case,

$$W_u = U_{\theta^*}^{-1}i_{\theta^*}U_{\theta^*} \sim \chi^2_k, \delta(\theta^*)$$
where the noncentrality parameter is given by

\[(1.1) \quad \delta(\theta^*) = (n_i\theta^*)'(n_i\theta^*)^{-1}(n_i\theta^*) = n\theta^*i_{\theta^*}.\]

Of course, simple hypotheses rarely arise in practical situations, so a generalization of the results above to composite hypotheses is imperative. Rao (1948), Bartlett (1953), and Neyman (1959) each suggested the suitable modification of \( W_u \) which will be described below. Suppose now that \( X_1, \ldots, X_n \) constitute a random sample from a distribution with density \( g(x|\theta, \lambda) \), where \( \theta \in \mathbb{R}^k \) is the parameter of interest, as before, while \( \lambda \in \mathbb{R}^s \) is a nuisance parameter. It is desired to test \( H_0 : \theta = 0 \), leaving \( \lambda \) unspecified. The likelihood is now a function of both \( \theta \) and \( \lambda \) for the observed \( X_1, \ldots, X_n \), and the efficient scores are also: we now consider \( U_{\theta}(0, \lambda) \) and \( U_{\lambda}(0, \lambda) \), where the \( \lambda \)-scores are defined in the same manner as the \( \theta \)-scores. In addition, we deal with a partitioned covariance matrix:

\[
\text{Cov}_{0, \lambda} \begin{bmatrix} U_{\theta}(0, \lambda) \\ U_{\lambda}(0, \lambda) \end{bmatrix} = \begin{bmatrix} i_{\theta\theta}(0, \lambda) & i_{\theta\lambda}(0, \lambda) \\ i_{\lambda\theta}(0, \lambda) & i_{\lambda\lambda}(0, \lambda) \end{bmatrix}.
\]

We can define adjusted \( \theta \)-scores by
Notice that \( U_\theta | \lambda (0, \lambda) \) represents the residuals from the regression of \( U_\theta (0, \lambda) \) on \( U_\lambda (0, \lambda) \), i.e., that part of \( U_\theta (0, \lambda) \) which is "free of" or orthogonal to \( U_\lambda (0, \lambda) \). Similarly the adjusted information matrix is given by

\[
i_\theta \theta | \lambda (0, \lambda) = \text{Cov}_0, \lambda U_\theta | \lambda (0, \lambda)
= i_\theta \theta (0, \lambda) - i_\theta \lambda (0, \lambda) i_\lambda^{-1} \lambda (0, \lambda) i_\lambda \theta (0, \lambda).
\]

Following results in the Appendix, we consider a statistic

\[
W_u (\lambda) = U_\theta | \lambda (0, \lambda) i_\theta^{-1} \theta | \lambda (0, \lambda) U_\theta | \lambda (0, \lambda).
\]

The dependence on the unknown \( \lambda \) is removed, and a practical statistic thereby obtained, by replacing \( \lambda \) with an estimator \( \hat{\lambda} \) which is guaranteed to be sufficiently close to \( \lambda \) in a probabilistic sense. Under regularity conditions on \( g(x | \theta, \lambda) \), the maximum likelihood estimator of \( \lambda \) under \( H_0 : \theta = 0 \), say \( \hat{\lambda}_0 \), may be used, in which case

\[
U_\theta | \lambda (0, \hat{\lambda}_0) = U_\theta (0, \hat{\lambda}_0)
\]

and the test of \( \theta \) may be based on
\[ W_u = W_{u_0} = U\theta(0, \hat{\lambda}_0) = U\theta|_{\hat{\theta}}(0, \hat{\lambda}_0) I_{\theta\theta}^{-1}(0, \hat{\lambda}_0) U\theta(0, \hat{\lambda}_0). \]

Moran (1970) demonstrated the asymptotic equivalence of \( W_{u_0} \) to Wald's statistic, \( \hat{\theta}'I_{\theta\theta}|_{\hat{\theta}}(\hat{\theta}, \hat{\lambda}) \hat{\theta} \), and to the likelihood ratio statistic, \( 2[\ell(\hat{\theta}, \hat{\lambda}) - \ell(0, \hat{\lambda}_0)] \), under regularity conditions. Here \( (\hat{\theta}, \hat{\lambda}) \) is the unrestricted joint maximum likelihood estimator. Wald (1943) demonstrated the asymptotic equivalence of the latter two statistics, as well as several optimality properties which are inherited by the quadratic score statistic \( W_{u_0} \).

As for the test of a simple hypothesis, \( W_{u_0} \) is distributed as \( \chi^2_k \) under the null hypothesis. And for \( \theta^* \) near \( 0 \), if \( U_{\theta}(0, \lambda) \) and \( U_{\lambda}(0, \lambda) \) have finite variances, then for large \( n \)

\[ n^{-1/2} U_{\theta|\lambda}(0, \hat{\lambda}_0) \overset{d}{\rightarrow} N_k(0, \lambda^*(\theta^*, \lambda) \theta^* I_{\theta\theta}|_{\theta} \lambda(0, \lambda)), \]

so that

\[ W_{u_0} \hat{\lambda}_0 \overset{d}{\rightarrow} \chi^2_k \delta(\theta^*|\lambda) \]

where

\[ \delta(\theta^*|\lambda) = n\theta^* I_{\theta\theta}|_{\theta} \lambda(0, \lambda) \theta^* \]

(1.2) For a more detailed discussion, refer to the Appendix. See also Neyman (1959) or Bhat and Nagnur (1965).
II. 2. Smooth Goodness-of-Fit Test: Simple Hypothesis

Neyman (1937) proposed what he referred to as the smooth goodness-of-fit test for a simple hypothesis. The procedure attempts to draw a compromise between the overall low power of omnibus tests and the highly focused power of parametric tests by establishing a reasonably rich family of parametric alternatives. The alternative densities are considered to be "smooth" departures from the null density in the sense that they remain close to the null density and cross it no more than a few times.

The alternatives are defined as follows. Suppose that under the null hypothesis, the distribution of a random variable $X$ has density function $f(x)$. Let $F(x) = \int_{-\infty}^{x} f(u)du$ denote the cumulative distribution function of $X$. Then it is well known that if $f$ is the true density, then the random variable $Y = F(X)$ is uniformly distributed on the interval $[0, 1]$. Neyman considered a class of alternatives for which the densities of $Y$, indexed by a vector parameter $\theta = (\theta_1, \ldots, \theta_k)' \in \mathbb{R}^k$, are given by

$$h(y|\theta) = \exp \left\{ \sum_{i=1}^{k} \theta_i y^i - K(\theta) \right\}, \quad 0 \leq y \leq 1.$$  

Here the normalizing constant is
The corresponding densities for $X$ are given by

$$
g(x | \theta) = f(x) \exp \left\{ \sum_{i=1}^{k} \theta_i y_i \right\}
$$

(2.1)

and the hypothesis that the true density is $f$ corresponds to $H_0 : \theta = 0$. In fact, Neyman's model was parameterized in terms of modified Legendre polynomials in $y = F(x)$ in order to capitalize on the orthogonality of the efficient scores and obtain a statistic which is simply a sum of squares. However, the simplification obtained is of little value when calculations may be readily computerized, so the current parameterization will be employed, since it leads to clearer derivations.

Since $Y^* = \bar{F}(X) = 1 - F(X)$ is uniformly distributed on $(0, 1)$ as well as $Y$ when $F$ is the correct cumulative distribution function, the alternatives (2.1) could be written with $\bar{F}$ in place of $F$. This corresponds to a nonsingular linear transformation on the parameter space and leaves the goodness-of-fit tests to be described below unchanged. Some simplification of the test statistic may thereby be obtained; for example, the negative exponential distribution has

$$\bar{F}(x) = e^{-x}.$$
Barton (1953) proposed a system of alternatives which are first
order approximations of (2.1):

\[ g^*(x | \theta) = f(x) \left\{ 1 + \sum_{i=1}^{k} \theta_i \pi_i[F(x)] \right\} \]

where \( \pi_i(y) \) denotes the \( i \)th order modified Legendre polynomial
in \( y \). While this system provides some simplifications over
Neyman's, it imposes constraints on the \( \theta \)'s, and we shall retain
Neyman's parameterization.

From (2.1) it is easy to see that the alternatives are indeed
smooth, in the sense described by Neyman, so long as \( \theta \) is reason-
ably near 0 and \( k \) is not too large. In addition, even by taking
\( k \) no greater than three or four one expects to obtain a rich family
of alternatives. Neyman (1937; Fig. 4) illustrates two particular
alternatives to normality. Figures 1 through 4 of this paper show how
the Neyman alternatives with \( k = 2 \) depart from normality in four
different "directions": when \( \theta_2 = 0, \theta_1 = 0, \theta_1 = \theta_2, \) and \( \theta_1 = -\theta_2 \).

Figures 5 through 8 show the same departures from the negative
exponential distribution. In each figure, the null density is repre-
sented by a dashed curve, while the alternatives, corresponding to
\( \theta \)-values of \( \pm 0.2, \pm 0.4, \) and \( \pm 0.6 \), are represented by solid curves.

As a step in deriving the quadratic score statistic to test the
goodness-of-fit hypothesis \( H_0 : \theta = 0 \), note that from Lehmann
Figure 1. Neyman alternatives to normality:
\[ g(x | \theta_1, \theta_2) \]
\[ \theta_1 = -0.6(0.2) \cdot 0.6, \quad \theta_2 = 0. \]
Figure 2. Neyman alternatives to normality:
\[ \theta_1 = 0, \theta_2 = -0.6(0.2)0.6. \]
Figure 3. Neyman alternatives to normality:
\[ \theta_1 = \theta_2 = -0.6(0.2)0.6.\]
Figure 4. Neyman alternatives to normality:
\[ \theta_1 = -\theta_2 = -0.6(0.2)0.6. \]
Figure 5. Neyman alternatives to exponentiality:
\[ \theta_1 = -0.6(0.2)0.6, \quad \theta_2 = 0. \]
Figure 6. Neyman alternatives to exponentiality:
\( \theta_1 = 0, \theta_2 = -0.6(0.2)0.6. \)
Figure 7. Neyman alternatives to exponentiality:
\[ \theta_1 = \theta_2 = -0.6(0.2)0.6. \]
Figure 8. Neyman alternatives to exponentiality:

\[ \theta_1 = -\theta_2 = -0.6(0.2)0.6. \]
(1959; Theorem 9, p. 52)

$$\frac{\partial}{\partial \theta_j} \int_0^1 \exp \left\{ \sum_{i=1}^{k} \theta_i y^i \right\} dy = \int_0^1 y^j \exp \left\{ \sum_{i=1}^{k} \theta_i y^i \right\} dy$$

so

$$\frac{\partial}{\partial \theta_j} K(\theta) \big|_{\theta=0} = \int_0^1 y^j dy / \exp \{ K(0) \} = (j+1)^{-1}.$$ 

Since the log likelihood for $\theta$ is

$$f(\theta) = \ln f(x) + \sum_{i=1}^{k} \theta_i F_i(x) - K(\theta),$$

it follows that the efficient score for $\theta_j$ is

$$U_{\theta_j} = U_{\theta_j}(0) = F^j(x) - (j+1)^{-1}.$$ 

The information matrix is easily calculated since

$$\text{Cov}_0(U_{\theta_j}, U_{\theta_k}) = E_0[\mathbf{F}^j(X)\mathbf{F}^k(X)] - (j+1)^{-1}(j+1)^{-1}$$

$$= (j+k+1)^{-1} - (j+1)^{-1}(j+1)^{-1}$$

$$= jk(j+k+1)^{-1}(j+1)^{-1}(j+1)^{-1}.$$ 

For $k$ up to four, the information matrix is just the $k \times k$ upper left submatrix of
Since the calculations essentially involve only the moments of 
\( Y = F(X) \), the distribution of which is uniform on \([0, 1]\) for any 
\( F \), the information matrix is the same regardless of the null distribution, and may be denoted simply \( i_{\theta \theta} \). For \( k \) up to four, \( i_{\theta \theta}^{-1} \) is given below:

\[
\begin{bmatrix}
1 & 1 & 3 & 1 \\
12 & 12 & 40 & 15 \\
4 & 1 & 8 \\
45 & 12 & 105 \\
9 & 3 \\
112 & 40 \\
16 \\
225
\end{bmatrix}
\]

(2.3)

\[
i_{\theta \theta} = 
\begin{bmatrix}
12 \\
180 \\
1200 \\
-2700 \\
1680 \\
6480 \\
-4200 \\
2800
\end{bmatrix}
\]

\[
i_{\theta \theta}^{-1} = 
\begin{bmatrix}
12 \\
-180 \\
180 \\
192 \\
-180
\end{bmatrix}
\]

\[
\begin{align*}
k &= 1 \\
& \quad i_{\theta \theta}^{-1} = [12] \\
k &= 2 \\
& \quad i_{\theta \theta}^{-1} = 
\begin{bmatrix}
192 & -180 \\
-180 & 180
\end{bmatrix}
\end{align*}
\]

\[
\begin{align*}
k &= 3 \\
& \quad i_{\theta \theta}^{-1} = 
\begin{bmatrix}
1200 & -2700 & 1680 \\
6480 & -4200 & \\
2800
\end{bmatrix}
\end{align*}
\]
\[ k = 4 \]

\[
\begin{align*}
\hat{\Theta}^{-1} &= \\
&= \begin{bmatrix}
4800 & -18900 & 26880 & -12600 \\
79380 & -117600 & 56700 \\
179200 & -88200 \\
44100
\end{bmatrix}
\end{align*}
\]

Also

\[
U' \hat{\Theta} = \left[ \sum_{i=1}^{n} F(x_i) - \frac{n}{2}, \ldots, \sum_{i=1}^{n} F^k(x_i) - \frac{n}{k+1} \right],
\]

so the quadratic score statistic

\[
\psi^2_k = W_u = U' \hat{\Theta}^{-1} U' \hat{\Theta}
\]

is easily calculated. The symbol \( \psi^2_k \) originated by Neyman, serves to emphasize \( k \), the order or degrees of freedom of the test, and will be used in this paper.

The selection of \( k \) immediately presents itself as a crucial problem in the application of the smooth goodness-of-fit test. In accordance with the general rule mentioned above, it is necessary to seek a compromise between the rich class of alternatives provided by a large value of \( k \) and the better power characteristics provided by a small value of \( k \). Neyman (1937) and Pearson (1938) pointed out that for \( k^* \leq k_1 < k_2 \), the \( k_2 \)-order test will be less sensitive than
the $k_1$-order test against alternatives which are modeled by the polynomial of order $k^*$ in (2.1). Moreover, the test based on $\psi_k^2$ will have no power against departures of $\theta_k$ from 0 when $k' > k$. Neyman based these comments on an examination of the asymptotic power function, which he showed by a direct argument to be of the noncentral $\chi^2$ form with noncentrality parameter given by (1.1). Of course, to insure a test of the desired size, $k$ must be selected independently of the data, and in the absence of special knowledge about a particular problem, Neyman recommended that $k$ generally need not be greater than four. However, the results of the following chapter will suggest that one might do better to use a smaller value of $k$.

Pearson (1938) noted the asymptotic equivalence of Neyman's smooth goodness-of-fit test to the likelihood ratio test. Neyman (1937) showed that the smooth test had, locally and asymptotically, the property later defined by Wald (1943) to be "uniformly best constant power" on the contours defined by setting the noncentrality parameter equal to a constant; i.e., asymptotically the test is locally uniformly most powerful among all tests of $H_0: \theta = 0$ which have power functions depending on $\theta$ only through $\delta(\theta) = n^{\theta' \theta} \theta$. Because of its asymptotic $\chi^2$ distribution, the test is consistent and therefore asymptotically unbiased. In fact, for $k = 1$, the test is asymptotically uniformly most powerful among all unbiased tests for $H_0: \theta_1 = 0;$
see, for example, Lehmann (1959; Section 4.2).

David (1939) calculated exact moments for $\psi_1^2$ and $\psi_2^2$, and Barton (1953), using these, fitted Pearson curves and an Edgeworth expansion to approximate the distributions of $\psi_1^2$ and $\psi_1$, respectively, in addition to calculating the exact distribution of $\psi_1^2$. Based on these he tabulated exact and approximate critical points for $\psi_1^2$ when $n$ is small; refer to his Table II. Barton (1955) also attempted to generalize the smooth goodness-of-fit test to grouped and discrete data.

II.3. Smooth Goodness-of-Fit Test: Composite Hypothesis

Barton (1956), Javitz (1975), and Thomas and Pierce (1977) considered generalizations of Neyman’s smooth test to the more useful case of a composite null hypothesis. Suppose we wish to test whether the distribution of $X$ has density $f(x|\lambda)$, where $\lambda \in \mathbb{R}^s$ is to be left unspecified. For example, we might wish to determine if $X$ is normally distributed, regardless of the values of the mean and variance. As before, we consider the class of alternatives with densities

$$g(x|\theta, \lambda) = f(x|\lambda) \exp \left\{ \sum_{i=1}^{k} \theta_i F_i(x|\lambda) - K(\theta) \right\},$$

where $F(x|\lambda)$ is the cumulative distribution function for $X$ under
\[ \lambda. \text{ The normalizing constant } K(\theta) \text{ is free of } \lambda \text{ since, substituting } \\
y = F(x|\lambda) \text{ for any } \lambda, \]

\[ K(\theta) = \ln \left[ \int_{-\infty}^{\infty} f(x|\lambda) \exp \left\{ \sum_{i=1}^{k} \theta_i F_i(x|\lambda) \right\} \, dx \right] \]

\[ = \ln \left[ \int_{-\infty}^{\infty} \exp \left\{ \sum_{i=1}^{k} \theta_i y^i \right\} \, dy \right]. \]

Proceeding as in the previous section we find that \( \psi_k^2 \) is a function of \( \lambda \). Barton's procedure was to substitute an estimate of \( \lambda \) in the statistic, which then was, he showed, distributed as a linear combination of \( \chi^2 \) random variables. As an alternative to this rather complicated criterion, Javitz and, independently, Thomas and Pierce, proposed using the quadratic score statistic as described in the first section of this chapter. Thus the test is based on

\[ (3.1) \quad \psi_k^2(\hat{\lambda}_0) = W_u(\hat{\lambda}_0) = U'_{\theta}(0, \hat{\lambda}_0) \mathbf{i}_{\hat{\theta}}^{-1} U_{\theta}(0, \hat{\lambda}_0) \]

where

\[ U_{\theta}(0, \hat{\lambda}_0) = \begin{bmatrix} \sum_{i=1}^{n} F(x_i|\hat{\lambda}_0) - \frac{n}{2}, \ldots, \sum_{i=1}^{n} F^{k}(x_i|\hat{\lambda}_0) - \frac{n}{k+1} \end{bmatrix}^t \]

and

\[ \mathbf{i}_{\hat{\theta}} = n[i_{\theta_0}(0, \hat{\lambda}_0) - i_{\theta_0}(0, \hat{\lambda}_0) i_{\lambda}(0, \hat{\lambda}_0) i_{\lambda}(0, \hat{\lambda}_0)] \]
Here $\hat{\lambda}_0$ is the maximum likelihood estimator of $\lambda$ under the null hypothesis $H_0: \theta = 0$. Recall from Section 1 of this chapter that if $\hat{\lambda}$ is a consistent estimator, not necessarily the maximum likelihood estimator, then the adjusted efficient score vector

$$U_{\theta}(0, \hat{\lambda}) = U_{\theta}(0, \hat{\lambda}) - i_{\theta\lambda}(0, \hat{\lambda}) \lambda^{-1}_{\lambda\lambda}(0, \hat{\lambda}) U_{\lambda}(0, \hat{\lambda})$$

should be used in (3.1) in place of $U_{\theta}(0, \hat{\lambda}_0)$.

It is an identity of linear algebra that, dropping the arguments $(0, \hat{\lambda}_0)$,

$$i^{-1}_{\theta\theta|\lambda} = (i_{\theta\theta} - i_{\theta\theta} i_{\lambda\lambda} i_{\lambda\theta})^{-1}$$

$$= i^{-1}_{\theta\theta} + i^{-1}_{\theta\theta} i_{\lambda\lambda} (i_{\lambda\lambda} - i_{\lambda\theta} i_{\theta\theta} i_{\lambda\theta})^{-1} i_{\lambda\theta} i_{\theta\theta}^{-1}$$

see, for example, Rao (1973; p. 33, problem 2.7). Thus the quadratic score statistic is just Barton's statistic plus a term to correct for the estimation of $\lambda$.

It will be seen in the examples below that $i_{\theta\theta|\lambda}(0, \lambda)$ is independent of $\lambda$ in each case considered. This greatly simplifies computation of the statistic, since then the matrix of the quadratic form depends only on the null distribution, and not at all on the data. This is easily shown to be true in general for location-scale families, with $f(x|\mu, \sigma) = \sigma^{-1} f[(x-\mu)/\sigma | 0, 1]$, and for shape-scale families, with $f(x|\tau, \sigma) = \tau x^{\tau-1} \sigma^{-\tau} f[(x/\sigma)^\tau | 1, 1]$. As mentioned in Section 2 of this
chapter, since the calculation of moments of the θ-scores involves essentially only the uniformly distributed random variables, 

\[ Y = F(X|\lambda) \] in this case, the information matrix \( i_{\theta\theta} \) is the same for any \( F \) and any \( \lambda \), and is given by (2.3). In addition, since

\[ \ln g(x|\theta,\lambda) = \ln f(x|\lambda) + \sum_{i=1}^{k} \theta_i F^i(x|\lambda) - K(\theta), \]

the vector of efficient scores for \( \lambda \), obtained by differentiating and then evaluating at \( \theta = 0 \), and \( i_{\lambda\lambda} \), the covariance matrix, are the same for the Neyman family of densities \( g(x|\theta,\lambda) \) as for the parametric family of densities \( f(x|\lambda) \). Finally, notice that

\[ i_{\theta i,\lambda j} = -E_{0,\lambda}[\theta^2 \ln g(X|0,\lambda)/\theta_i \theta_j] = -E[\theta F^i(X|\lambda)/\theta_j]. \]

From Section 1 of this chapter we know that, asymptotically, \( \psi^2_k(\lambda|0) \) is distributed as \( \chi^2_k, \delta(\theta|\lambda) \) where

\[ \delta(\theta|\lambda) = n \theta' i_{\theta\theta}|_{(0,\lambda) \theta}, \]

for local alternatives. The comments in Section 2 of this chapter regarding the selection of \( k \) apply in this case as well. To compromise between the effects of selecting a high or low value of \( k \), one might be guided by considerations of efficiency, as in the following chapter.
II. 4. Calculation of $i_{\theta \theta}^{-1} \lambda$ for Examples

A. Normal Distribution

In this case the density is well-known:

$$f(x|\mu, \sigma) = \sigma^{-1} (2\pi)^{-1/2} \exp\left\{-(x-\mu)^2/2\sigma^2\right\}.$$  

We take $\lambda = (\mu, \sigma)'$. Then

$$U_{\mu}(0, \lambda) = (x-\mu)\sigma^{-2}$$
$$U_{\sigma}(0, \lambda) = (x-\mu)^2 \sigma^{-3} - \sigma^{-1}$$

and

$$i_{\lambda\lambda} = \sigma^{-2} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

Moreover, from Barton (1953; Table X), it follows that, for $k$ up to four,

$$i_{\theta\theta} = \sigma^{-1} \begin{bmatrix} \frac{1}{2\pi 1/2} & 0 \\ \frac{1}{2\pi 1/2} & \frac{\sqrt{3}}{6\pi} \\ \frac{3S_3 + 18\pi}{40\pi 3/2} & \frac{\sqrt{3}}{4\pi} \\ \frac{3S_3 + 8\pi}{20\pi 3/2} & \frac{\sqrt{3} (S_4 + 8\pi)}{28\pi 2} \end{bmatrix}$$
where

\[ S_3 = 10 \arcsin\left(\frac{1}{3}\right) - \pi = 0.256776441 \]
\[ S_4 = 14 \arcsin\left(\frac{1}{4}\right) - \pi = 0.395930917. \]

So, for \( k \) up to four, recalling that \( i_{\theta\theta} \) is given by (2.3),

\[
i_{\theta\theta}|\lambda = i_{\theta\theta} - i_{\theta\lambda} i_{\lambda\lambda}^{-1} i_{\lambda\theta} = \\
\begin{bmatrix}
3.755862 & 3.755862 & 2.404642 & 1.053422 \\
5.089701 & 4.405401 & 3.225992 & \\
4.632428 & 4.116791 & \\
4.211002 & 
\end{bmatrix} \times 10^{-3}.
\]

For any \( k, \) \( i_{\theta\theta}|\lambda \) is just the inverse of the upper left \( k \times k \) submatrix of \( i_{\theta\theta}|\lambda \) given above. These inverses are listed in Table 1. Of course the noncentrality parameter \( \delta(\theta|\lambda) = n\theta' i_{\theta\theta}|\lambda \theta \) is calculated from the submatrix from \( i_{\theta\theta}|\lambda \) of the appropriate order.

**B. Exponential Distribution**

The density is \( f(x|\lambda) = \lambda^{-1} \exp\{ -x/\lambda \} \), where the nuisance parameter is \( \lambda \), the scale parameter. We have

\[ U_{\lambda}(0,\lambda) = \lambda^{-2}(x-\lambda) \]

so
Table 1. Matrices $i_{\theta \theta}^{-1}$ for testing normality.

<table>
<thead>
<tr>
<th>k = 1</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>266.2504789951</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>k = 2</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>$1015.965828673$</td>
<td>-749.7153496774</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>-749.7153496774</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>k = 3</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>$9072.727318174$</td>
<td>-14806.08191679</td>
<td>9370.911044737</td>
<td></td>
</tr>
<tr>
<td></td>
<td>25273.39540729</td>
<td>-16349.1200384</td>
<td></td>
</tr>
<tr>
<td></td>
<td>10899.41335893</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>k = 4</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>$23058.98126537$</td>
<td>-66471.72954001</td>
<td>84729.69856163</td>
<td>-37679.39415895</td>
</tr>
<tr>
<td></td>
<td>216127.8696941</td>
<td>-294726.7739746</td>
<td>139188.8284477</td>
</tr>
<tr>
<td></td>
<td>416937.1470859</td>
<td>-203018.8690217</td>
<td></td>
</tr>
<tr>
<td></td>
<td>101509.43559</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>


Recall from Section 2 that it is sometimes convenient to use $\bar{F}(x)$ in place of $F(x)$, so we take

$$U_{\theta i}(0, \lambda) = \bar{F}^i(x | \lambda) - (i+1)^{-1} = e^{-ix/\lambda} - (i+1)^{-1}.$$ 

Thus

$$\Cov(U_{\theta i}, U_{\theta j} | 0, \lambda) = \int_0^\infty \frac{x e^{-ix/\lambda}}{\lambda^2 (i+1)} \left( \frac{1}{\lambda} e^{-x/\lambda} \right) dx - \frac{1}{\lambda(i+1)}$$

$$= \frac{1}{\lambda^2 (i+1)} \int_0^\infty \frac{x}{\lambda} e^{-i+1)}x/\lambda dx - \frac{1}{\lambda(i+1)}$$

$$= \frac{1}{\lambda^2 (i+1)} \times \frac{\lambda}{i+1} - \frac{1}{\lambda(i+1)} = -\frac{1}{\lambda} \frac{i}{(i+1)^2}.$$ 

Thus, for $k$ up to four,

$$i_{\theta \lambda}(0, \lambda) = \lambda^{-1} \left[ -\frac{1}{4}, -\frac{2}{9}, -\frac{3}{16}, -\frac{4}{25} \right]$$

and

$$i_{\theta \theta | \lambda} = \begin{bmatrix}
\frac{1}{48} & \frac{1}{36} & \frac{9}{320} & \frac{2}{75} \\
\frac{16}{405} & \frac{1}{24} & \frac{64}{1575} \\
\frac{81}{1792} & \frac{9}{200} \\
\frac{256}{5625}
\end{bmatrix}.$$ 

The inverses of $i_{\theta \theta | \lambda}$ for $k$ up to four are given in Table 2.
### Table 2. Matrices $i_{00}^{-1}$ for testing exponentiality.

| $k = 1$ | 48 |
| $k = 2$ | 768  
|         | -540 |
|         | 405  |
| $k = 3$ | 4800  
|         | -8100  
|         | 4480  |
|         | 14580  
|         | -8400  |
|         | 4977.7 |
| $k = 4$ | 19200  
|         | -56700  
|         | 71680  
|         | -31500  |
|         | 178605  
|         | -235200  
|         | 106312.5 |
|         | 193137.7  
|         | 147000  |
|         | 68906.25 |

### C. Weibull Distribution

For the density $f(x | \tau, \sigma) = \tau x^{\tau - 1} \sigma^{-\tau} \exp\{-x/\sigma\}$ we have for

$\lambda = (\tau, \sigma)'$

$$U_{\tau}(0, \lambda) = \tau^{-1} + [1 -(x/\sigma)^{\tau}] \ln(x/\sigma)$$

$$U_{\sigma}(0, \lambda) = \tau \sigma^{-1} [(x/\sigma)^{\tau} - 1].$$

From
\[ \frac{\partial^2 l(\tau, \sigma)}{\partial \tau^2} = -\tau^{-2} - (x/\sigma)^T \ln^2 (x/\sigma) = -\tau^{-2} \{ 1 + (x/\sigma)^T \ln^2 [(x/\sigma)^T] \} \]

it follows that, letting \( y = (x/\sigma)^T \),

\[ i_{\tau \tau} = E(-\frac{\partial^2 l}{\partial \tau^2} | \tau, \sigma) = \tau^{-2} + \tau^{-2} \int_0^\infty y(\ln y)^2 e^{-y} dy \]

\[ = \tau^{-2} [1 + \Gamma''(2)] = 1.828681 \tau^{-2}. \]

Also, since

\[ \frac{\partial^2 l(\tau, \sigma)}{\partial \sigma^2} = \tau \sigma^{-2} - \tau(\tau + 1) \sigma^{-2} (x/\sigma)^T \]

we have

\[ i_{\sigma \sigma} = \tau(\tau + 1) \sigma^{-2} E[(X/\sigma)^T | \tau, \sigma] - \tau \sigma^{-2} = \tau(\tau + 1) \sigma^{-2} E(X | 1, 1) - \tau \sigma^{-2} \]

\[ = \tau \sigma^{-2}. \]

And from

\[ \frac{\partial^2 l(\tau, \sigma)}{\partial \tau \partial \sigma} = -\sigma^{-1} + \sigma^{-1} (x/\sigma)^T + \tau \sigma^{-1} (x/\sigma)^T \ln(x/\sigma) \]

it follows that

\[ i_{\tau \sigma} = \sigma^{-1} - \sigma^{-1} E[(X/\sigma)^T | \tau, \sigma] - \sigma^{-1} E\{ (X/\sigma)^T \ln[(X/\sigma)^T] | \tau, \sigma \} \]

\[ = \sigma^{-1} - \sigma^{-1} E(X | 1, 1) - \sigma^{-1} E(X \ln X | 1, 1) \]

\[ = -\sigma^{-1} \int_0^\infty x(\ln x)e^{-x}dx = -\sigma^{-1}(1 - \gamma) \]

where \( \gamma = 0.577216... \) is Euler's constant. So
\[ i_{\tau \sigma} = -0.422784\sigma^{-1} \]

and

\[ i_{\lambda \lambda} = \begin{bmatrix} 1.828681\tau^{-2} & -0.422784\sigma^{-1} \\ \tau^2\sigma^{-2} & -2 \end{bmatrix}. \]

As for the negative exponential, it is convenient to write the Neyman alternatives in terms of \( \bar{F}(x) = \exp\{-x/\sigma\} \), so we have

\[ U_{\theta_1}(0, \lambda) = \exp\{-i(x/\sigma)^T\} \cdot (i+1)^{-1}. \]

Therefore, letting \( y = (x/\sigma)^T \),

\[ i_{\theta_1, \sigma} = \text{Cov}[U_{\theta_1}(0, \lambda), U_{\sigma}(0, \lambda) | 0, \lambda] \]

\[ = E[\exp\{-i(X/\sigma)^T\} \tau^{-1}(X/\sigma)^T | 0, \lambda] - \tau^{-1}(i+1)^{-1} \]

\[ = \tau^{-1} \int_0^\infty ye^{-(i+1)y} dy - \tau^{-1}(i+1)^{-1} = -\tau^{-1}i(i+1)^{-2}. \]

Also, letting \( u = (i+1)y \)

\[ i_{\theta_1, \tau} = \text{Cov}[U_{\theta_1}(0, \lambda), U_{\tau}(0, \lambda) | 0, \lambda] \]

\[ = E[\exp\{-i(X/\sigma)^T\} \ln(X/\sigma) | 0, \lambda] \]

\[ - E[\exp\{-i(X/\sigma)^T\}(X/\sigma)^T \ln(X/\sigma) | 0, \lambda] + \tau^{-1}(i+1)^{-1} = \]
\[= \tau^{-1} \int_0^\infty e^{-(i+1)y} \ln y \, dy - \tau^{-1} \int_0^\infty ye^{-(i+1)y} \ln y \, dy + \tau^{-1}(i+1)^{-1} \]
\[= \tau^{-1}(i+1)^{-1} \left\{ \int_0^\infty \left[ \ln u - \ln(i+1) \right] e^{-u} \, du \right. \]
\[\left. - \int_0^\infty u(i+1)\left[ \ln u - \ln(i+1) \right] e^{-u} \, du + 1 \right\} \]
\[= \tau^{-1}(i+1)^{-1}\{-\gamma \ln(i+1)-(i+1)^{-1}[1-\gamma \ln(i+1)]+1\} \]
\[= i[1-\gamma \ln(i+1)]\tau^{-1}(i+1)^{-2}. \]

So

\[
\begin{bmatrix}
    -0.067591/\tau & -\tau/4\sigma \\
    -0.150184/\tau & -2\tau/9\sigma \\
    -0.180658/\tau & -3\tau/16\sigma \\
    -0.189865/\tau & -4\tau/25\sigma \\
\end{bmatrix}
\]

and

\[
\begin{bmatrix}
    2.641897 & 2.145342 & 0.833043 & -0.371844 \\
    3.390813 & 3.213743 & 2.539434 \\
    4.259354 & 4.439160 \\
    5.327499
\end{bmatrix} \times 10^{-3}
\]

For \( k \) up to four, \( \mathbf{1}_{\mathbf{0}\theta|\lambda}^{-1} \) is given in Table 3.
Table 3. Matrices \( \mathbf{\theta}^{-1} \mathbf{\lambda} \) for testing the Weibull distribution.

<table>
<thead>
<tr>
<th>k = 1</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>378.515892</td>
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</table>

<table>
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<th>k = 2</th>
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</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>\begin{bmatrix} 778.479599 &amp; -492.538214 \ 606.539764 \end{bmatrix}</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>k = 3</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>\begin{bmatrix} 10276.398086 &amp; -16135.879709 &amp; 10164.895656 \ 26371.567486 &amp; -16741.871835 \ 10878.710303 \end{bmatrix}</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>k = 4</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>\begin{bmatrix} 19600.422408 &amp; -54730.219668 &amp; 67235.294397 &amp; -28568.029642 \ 186122.660513 &amp; -252969.738092 &amp; 118249.825381 \ 360194.660129 &amp; -174858.922126 \ 87530.050266 \end{bmatrix}</td>
</tr>
</tbody>
</table>
II. 5. The Possibility of a Smooth Test for Multivariate Normality

One attractive feature of the Neyman smooth test is its potential for applications to problems beyond the standard goodness-of-fit test. Thomas (1977) considers smooth goodness-of-fit tests for censored data. Javitz (1975) considered smooth tests for independence and equality of distributions, as well as a smooth test for bivariate goodness of fit. Almost all widely used multivariate techniques are based on the assumption of multivariate normality, which therefore has been the focus of nearly all the attention given to multivariate goodness-of-fit tests. Several goodness-of-fit procedures have been discussed by Hensler, Mehrota, and Michalek (1977), Kowalski (1970), Malkovich and Afifi (1973), and Mardia (1974); see also the reviews of Andrews, Gnanadesikan, and Warner (1973) or Gnanadesikan (1977).

For simplicity of exposition, we will consider the case of bivariate normality. Further generalization to the $p$-variate normal distribution will then be obvious. Moreover, we will consider first the composite null hypothesis that $(X_1, X_2)$ has a bivariate normal distribution with the nuisance parameter $\lambda' = (\mu_1, \mu_2, \sigma_1, \sigma_2, \rho)$ unknown, where $\rho$ denotes the correlation coefficient of $X_1$ and $X_2$. Let $\phi_2(x_1, x_2 | \lambda)$ denote the joint density.
\[
\phi_2(x_1, x_2 | \lambda) = (2\pi)^{-1} \sigma_1^{-1} \sigma_2^{-1} (1 - \rho^2)^{-1/2} 
\times \exp\left\{ -\frac{1}{2(1 - \rho^2)} \left[ \left( \frac{x_1 - \mu_1}{\sigma_1} \right)^2 - 2\rho \left( \frac{x_1 - \mu_1}{\sigma_1} \right) \left( \frac{x_2 - \mu_2}{\sigma_2} \right) + \left( \frac{x_2 - \mu_2}{\sigma_2} \right)^2 \right] \right\}
\]

and let the marginal probability transform of \( X_i \) be denoted by \( Y_i = \phi[(X_i - \mu_i)/\sigma_i] \) for \( i = 1, 2 \). We consider the family of smooth alternative densities

\[(5.1) \quad g(x_1, x_2 | \theta, \lambda) = \phi_2(x_1, x_2 | \lambda) \exp\{P_k(\theta, y_1, y_2) - K(\theta)\}\]

where \( P_k \) is a polynomial of degree \( k \) with coefficients given by \( \theta \), and \( K(\theta) \) is the usual normalizing constant. For example, taking \( k = 2 \) and letting \( \theta^i = (\theta_{10}, \theta_{20}, \theta_{01}, \theta_{02}, \theta_{11}) \) we have

\[(5.2) \quad P_k(\theta, y_1, y_2) = \theta_{10}y_1 + \theta_{20}y_1^2 + \theta_{01}y_2 + \theta_{02}y_2^2 + \theta_{11}y_1y_2.\]

Javitz (1975) parameterized the alternatives (5.1) in terms of the modified Legendre polynomials in \( y_1 \) and in \( y_2 \), but that corresponds simply to a linear transformation on the parameter space so long as \( k \) is fixed.

Javitz mistakenly asserts that, under the null hypothesis, which may now be written \( H_0 : \theta = 0 \), the joint distribution of \( (Y_1, Y_2) \) is
uniform on the unit interval. This implies that $Y_1$ and $Y_2$ are independent, which is clearly true if and only if $\rho = 0$. In general, however, the joint density of $(Y_1, Y_2)$ is

\begin{equation}
(5.3) \quad h(y_1, y_2 | \lambda) = (1 - \rho^2)^{-1/2} \exp\left\{ - \frac{\rho}{2(1 - \rho^2)} [\rho z_1^2 - 2z_1 z_2 + \rho z_2^2] \right\}
\end{equation}

where $z_i = \Phi^{-1}(y_i)$. The alternative densities (5.1) are given in terms of the $y$'s by

$$h^*(y_1, y_2 | \theta, \lambda) = h(y_1, y_2 | \lambda) \exp\{P_k(\theta, y_1, y_2) - K(\theta)\}.$$ 

So, although the null distribution of the $Y$'s is no longer uniform, as in the univariate case, it is still true that the alternatives are smooth departures: the log-likelihood ratio

$$\ln\left\{ \frac{h^*(y_1, y_2 | \theta, \lambda)}{h^*(y_1, y_2 | 0, \lambda)} \right\}$$

is simply a polynomial in the $y$'s.

The fact that the probability integral transformation in the univariate case produces a random variable with a uniform distribution on $(0, 1)$ provides a major simplification for the smooth test: as noted before, $\theta_\theta$ depends on neither the null hypothesis nor on $\lambda$, and is very easily calculated from the moments of the uniform distribution. From (5.3) we see that this simplification no longer occurs in the multivariate case, at least when $\rho \neq 0$. In fact, if $E[T(Z) | \mu, \sigma^2]$ denotes the expectation of $T(Z)$ when $Z \sim N(\mu, \sigma^2)$, then
\[
E\{\Phi^i_1 \Phi^j_2 | \lambda\} = E\{\Phi^i_1(Z_1)E[\Phi^j_2(Z_2)| \rho Z_1, 1-\rho^2] | 0,1}\]

for \(i, j \geq 1\), and therefore

\[
i_{ij} \theta_{\ell m} (\rho) = E\{\Phi^{i+\ell}_1(Z_1)E[\Phi^{j+m}_2(Z_2)| \rho Z_1, 1-\rho^2] | 0,1\}
- E\{\Phi^i_1(Z_1)E[\Phi^j_2(Z_2)| \rho Z_1, 1-\rho^2] | 0,1\}
\times E\{\Phi^\ell_1(Z_1)E[\Phi^m_2(Z_2)| \rho Z_1, 1-\rho^2] | 0,1\}.
\]

For \(\rho = 0\), each conditional expectation is just a constant and

\[
(i_{ij} \theta_{\ell m}) (0) = (i+\ell+1)^{-1}(j+m+1)^{-1} - (i+1)^{-1}(j+1)^{-1}(\ell+1)^{-1}(m+1)^{-1}.
\]

We consider a test of the null hypothesis that \((X_1, X_2)\) has a bivariate normal distribution with \(\lambda^* = (\mu_1, \mu_2, \sigma_1, \sigma_2)\) unknown and with \(\rho = 0\). We do not consider departures in \(\rho\) but rather smooth departures \((5.1)\), with \(k = 2\) for clarity. From \((5.2)\) it may be seen that the smooth test statistic \(\psi_{2}^2(\lambda^*)\) will have five rather than two degrees of freedom. Let

\[
U'(\lambda^*) = [U_{00}(\lambda^*), U_{01}(\lambda^*), U_{02}(\lambda^*), U_{20}(\lambda^*), U_{10}(\lambda^*), U_{11}(\lambda^*)]
\]
\[
\begin{bmatrix}
\Phi\left( \frac{X_1 - \mu_1}{\sigma_1} \right) - \frac{1}{2} \Phi^2\left( \frac{X_1 - \mu_1}{\sigma_1} \right) - \frac{1}{3} & \Phi\left( \frac{X_2 - \mu_2}{\sigma_2} \right) - \frac{1}{2} \Phi^2\left( \frac{X_2 - \mu_2}{\sigma_2} \right) - \frac{1}{3} \\
\Phi\left( \frac{X_1 - \mu_1}{\sigma_1} \right) \Phi\left( \frac{X_2 - \mu_2}{\sigma_2} \right) - \frac{1}{4} & \Phi\left( \frac{X_2 - \mu_2}{\sigma_2} \right) - \frac{1}{2} \Phi^2\left( \frac{X_2 - \mu_2}{\sigma_2} \right) - \frac{1}{3}
\end{bmatrix}
\]

Then from (5.4),

\[
i_{\theta} = \text{Cov}(U_{\theta}(\lambda^*), \theta = 0, \lambda^*)
\]

\[
= \begin{bmatrix}
\frac{1}{12} & \frac{1}{12} & 0 & 0 & \frac{1}{24} \\
\frac{4}{45} & 0 & 0 & \frac{1}{24} \\
\frac{1}{12} & \frac{1}{12} & \frac{1}{24} \\
\frac{4}{45} & \frac{1}{24} \\
\frac{7}{144}
\end{bmatrix}
\]

Now because of the independence of \( X_1 \) and \( X_2 \) under the null hypothesis, the null density factors:

\[
\phi_2(x_1, x_2 | \lambda^*) = \phi(x_1 | \mu_1, \sigma_1) \phi(x_2 | \mu_2, \sigma_2)
\]

So the efficient scores for the components of \( \lambda^* \) and their covariances may be taken from Section 4A. Moreover, scores relating to \( X_1 \) are uncorrelated with those relating to \( X_2 \) when \( H_0 \) is true, so from (4.1)
\[ i_{\lambda^* \lambda^*}(\lambda^*) = \text{diag}(\sigma_1^{-2}, 2\sigma_1^{-2}, \sigma_2^{-2}, 2\sigma_2^{-2}) \].

Again, since \( X_1 \) and \( X_2 \) are independent by assumption, it follows that

\[
i_{\mu_1 \theta 0m} = i_{\sigma_1 \theta 0m} = i_{\mu_2 \theta m0} = i_{\sigma_2 \theta m0} = 0
\]

for \( m = 1, 2 \). And since expressions involving only \( X_1 \) or \( X_2 \) depend only on the marginal distributions, the covariances may also be taken directly from Section 4A. Finally, again by independence,

\[
i_{\mu_1 \theta 11}(\lambda^*) = \mathbb{E}\left\{ \Phi\left( \frac{X_1 - \mu_1}{\sigma_1} \right) \Phi\left( \frac{X_2 - \mu_2}{\sigma_2} \right) \mid \lambda^* \right\}
\]

\[
= i_{\mu_1 \theta 10}(\lambda^*) \mathbb{E}\left\{ \Phi\left( \frac{X_2 - \mu_2}{\sigma_2} \right) \mid \lambda^* \right\}
\]

\[
= i_{\mu_1 \theta 10}(\lambda^*) / 2
\]

with analogous expressions for the rest of \( i_{\lambda^* \theta 11}(\lambda^*) \). Thus we have
and

\[
\begin{bmatrix}
\frac{1}{2\pi} & 0 & 0 & 0 \\
0 & \frac{1}{2\pi} & 0 & 0 \\
0 & 0 & \frac{1}{6\pi} & 0 \\
0 & 0 & 0 & \frac{1}{6\pi}
\end{bmatrix}
\]

\[i\theta \lambda^*(\lambda^*) = \begin{bmatrix}
\frac{1}{2\pi} & 0 & 0 & 0 \\
0 & \frac{1}{2\pi} & 0 & 0 \\
0 & 0 & \frac{1}{6\pi} & 0 \\
0 & 0 & 0 & \frac{1}{6\pi}
\end{bmatrix}
\]

Numerically,

\[
(\pi - 3)/12\pi = 0.003756
\]

\[
(\pi - 3)/24\pi = 0.001878
\]

\[
(32\pi^2 - 90\pi - 15)/360\pi^2 = 0.005090
\]

\[
(7\pi - 18)/144\pi = 0.008822.
\]
So

\[
\begin{bmatrix}
A & -B & 36 & 0 & -72 \\
B & 0 & 0 & 0 & \\
A & -B & -72 & \\
B & 0 & \\
& 144
\end{bmatrix}
\]

(5.5)

where

\[
A = \frac{(454\pi^3 - 1098\pi^2 - 720\pi + 105)}{(2\pi^3 - 6\pi^2 - 15\pi + 45)}
\]

\[= 1051.965825\]

\[
B = \frac{360\pi^2}{(2\pi^2 - 15)} = 749.715349.
\]

From (5.4) and (5.5) we obtain the quadratic score statistic

(5.6)

\[
\psi_2(\hat{\lambda^*}) = n^{-1}U_0^{-1}(\hat{\lambda^*})i^{-1}_0\theta|\lambda U_0^{-1}(\hat{\lambda^*})
\]

where

\[
\hat{\lambda^*}_0 = (\bar{x}_1, \bar{x}_2, s_1, s_2)
\]

is the maximum likelihood estimator of \(\lambda^*\).

It is extremely important to note that (5.6) is only appropriate for testing that \(X_1\) and \(X_2\) are independently distributed with a bivariate normal distribution relative to a fixed, known coordinate system. To paraphrase Gnanadesikan (1977; Section 5.4.2), the test presupposes a total commitment to the given coordinate system:
interest must be completely confined to the observed coordinates.

For example, suppose a new pair of coordinate axes is obtained by a rigid rotation through angle \( \eta \). Let \( V = (v_1, v_2)' \) denote the new coordinates of the point with original coordinates \( X = (x_1, x_2) \), i.e.,

\[
V = A \eta X = \begin{bmatrix}
\cos \eta & \sin \eta \\
-\sin \eta & \cos \eta
\end{bmatrix} X.
\]

The use of \( \psi_2(\lambda^*) \) defined in (5.6) is based on the assumption that \( X_1 \) and \( X_2 \) are independent:

\[
\text{Cov}(X \mid \lambda^*) = D_X = \text{diag}(\sigma_1^2, \sigma_2^2)
\]

where \( \sigma_1^2 \) and \( \sigma_2^2 \) are unknown. But

\[
\text{Cov}(V \mid \lambda^*) = A \eta D_X A' \eta = \begin{bmatrix}
\sigma_1^2 \cos^2 \eta + \sigma_2^2 \sin^2 \eta & (\sigma_2^2 - \sigma_1^2) \cos \eta \sin \eta \\
(\sigma_2^2 - \sigma_1^2) \cos \eta \sin \eta & \sigma_2^2 \cos^2 \eta + \sigma_1^2 \sin^2 \eta
\end{bmatrix}.
\]

Thus \( V_1 \) and \( V_2 \) are uncorrelated if and only if \( \sigma_1^2 = \sigma_2^2 \) or \( \eta = N\pi/2 \) for some integer \( N \), and in general \( \psi_2(\lambda^*) \) is not appropriate for data \( V \) obtained from the original \( X \). This lack of invariance, which is related to the difficulty of assuming \( \rho \) is unknown, is a major drawback to the use of the smooth test statistic for multivariate normality, and arises from the use of the marginal probability integral transformations. The problem of testing the
composite hypothesis of normality remains invariant under location and scale changes, rotations, and reflections. However, the smooth test statistics based on the marginal \( Y's \) are only location and scale invariant. Further work in this area may be possible. For example, correlated data might be orthogonalized by regressing \( X_2 \) on \( X_1 \) and then testing \( X_1 \) and the residuals, or by transforming the data to its principal components.
III. POWER AND EFFICIENCY

III.1. Introduction

In most practical applications, Neyman's smooth test will be utilized to test a composite hypothesis about a parameter vector of dimension greater than unity. In such a situation one does not expect to find a procedure with any strong optimality properties, such as the property of being uniformly most powerful. Nevertheless, by virtue of being asymptotically equivalent to the likelihood ratio, Neyman's test does have the optimality properties described by Neyman (1959) and Wald (1943); refer to Chapter II and the Appendix.

When the selection of a test procedure is not dictated by any compelling optimality considerations, one is led to comparison of power functions and to measures such as relative efficiency in evaluating the available procedures. In the case of the smooth goodness-of-fit test this will assist the statistician in answering two closely related questions. How well do the smooth tests compare with the other omnibus tests, on the one hand, and with the parametric tests, on the other? In addition, what value of $k$ is best, and will one choice for $k$ serve in general?

The information about a test's performance is contained in its power functions. In Section 2 the power of the smooth goodness-of-fit tests against departures in various "directions" from the null
hypothesis is discussed. Sections 3, 4, and 5 contain examples of calculations described in Section 2. Of course, it is awkward to try to compare procedures in terms of entire power functions, so we seek summary measures which are algebraically simpler and conceptually more concise. In Section 6 it is seen that asymptotic relative efficiency provides such a measure which is suitable for comparing smooth tests with other parametric tests based on quadratic score statistics. Section 7 describes such a comparison of the smooth tests with the omnibus Pearson's $\chi^2$ test and a generalization.

III. 2. The Power of Smooth Goodness-of-Fit Tests

Neyman (1937) derived directly the asymptotic noncentral $\chi^2$ distribution of $\psi_k^2$ under local alternatives, when testing a simple goodness-of-fit hypothesis. In Chapter II this result, as well as the analogous result for a composite hypothesis, was seen to be a special case of general results for quadratic score statistics. Simply stated, the noncentrality parameter is a quadratic form in $\theta$, the vector parameter indexing the smooth departures from the null density, given by (II. 1.1) and (II. 1.2) for simple and composite hypotheses, respectively. Neyman (1937) and Javitz (1975) examine the noncentrality parameter of $\psi_k^2$ when the smooth alternatives are of various orders other than $k$. Barton (1953) derived a formula giving the exact power of $\psi_k^2$ for any $n$ when the alternatives are of the form
(II.2.2), however the expression is dismayinglingly complicated: a polynomial of order \( n \) in the \( \theta \)'s.

It is of interest to consider the power of the smooth tests against alternatives other than those for which the tests were designed. Hamdan (1962) calculated the noncentrality parameter when the smooth test of the simple hypothesis of standard normality is applied and the true distribution is \( N(\mu, 1) \) for \( \mu = 0.05(0.05)0.20 \).

Javitz (1975) considered the power of the smooth test against composite, "non-smooth" alternatives. He also obtained empirical powers for tests of the normal, beta, gamma, and Poisson distributions by computer simulation. He considered \( \psi_k(\lambda, 0) \) for \( k = 2, 3, 4 \) as well as Pearson's \( \chi^2 \) and in each case the alternatives were mixtures of densities of the null family with alterations in parameter values. In addition he estimated the power of the tests of normality when the distribution is in fact a standard Cauchy or a Gamma \((4, 2)\). These latter results are reproduced in Table 4. The six entries in each column are based on one set of 100 samples of the indicated size and are therefore correlated. Critical levels were taken from the theoretical asymptotic \( \chi_k^2 \) distribution for \( \psi_k(\lambda, 0) \), and, as in its common usage, the Pearson \( \chi^2 \) statistics were also taken to have \( \chi^2 \) distributions. Kang (1977) obtained empirical powers of several tests of normality: \( \psi_k(\lambda, 0) \) for \( k = 1, \ldots, 4 \), as well as the omnibus \( \chi^2 \) and Kolmogorov-Smirnov tests and the tests for normality
Table 4. Empirical powers of tests for normality (Javitz, 1975).

<table>
<thead>
<tr>
<th>Alternative:</th>
<th>Gamma (4, 2)</th>
<th>Cauchy</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>n: 50 100 150</td>
<td></td>
</tr>
<tr>
<td>Test Statistic</td>
<td></td>
<td>Cauchy</td>
</tr>
<tr>
<td>( \psi_2^{L_0} )</td>
<td>33 65 86</td>
<td>91 100</td>
</tr>
<tr>
<td>( \psi_3^{L_0} )</td>
<td>31 55 72</td>
<td>90 99</td>
</tr>
<tr>
<td>( \psi_4^{L_0} )</td>
<td>32 53 78</td>
<td>90 99</td>
</tr>
<tr>
<td>( \chi^2 (20% / cell) )</td>
<td>21 28 44</td>
<td>86 98</td>
</tr>
<tr>
<td>( \chi^2 (10% / cell) )</td>
<td>25 29 47</td>
<td>79 96</td>
</tr>
<tr>
<td>( \chi^2 (5% / cell) )</td>
<td>25 26 40</td>
<td>76 91</td>
</tr>
</tbody>
</table>

Note: entries are percentages rounded to the nearest digit; tests are at \( \alpha = 0.10 \); all powers against Cauchy are 100% for \( n \geq 75 \).
based on $b_1$ and $b_2$, and the Shapiro-Wilk statistic. He considered several alternatives from among those used by Shapiro, Wilk and Chen (1968), including the Weibull with scale parameter 2 (denoted W2), standard Laplace (Lap.), standard logistic (Log.), extreme value with parameters 0 and 0.5 (EV(.5)), and double $\chi^2$ with parameter -0.5 (D(-0.5)). This last density is proportional to $\exp\{-x^4\}$ and therefore has light tails relative to the normal density. He first estimated the critical value of the statistics from 2000 trials for each statistic at each sample size. The powers relative to these empirical critical values were then estimated from 2000 trials for W2 and Lap. and 1000 trials for the rest, at each sample size. The results are shown in Table 5. The smooth tests with $k = 1$ and 2 are seen to perform very well, having maximum power in half of the cases. Notice that the smooth tests dominate the Pearson's $\chi^2$ and Kolmogorov-Smirnov tests. The power of $\psi_2(\lambda_0)$ is never more than 8% below the maximum power, and the smooth tests with one or two degrees of freedom perform as well as or better than procedures specifically designed for testing normality, at least for the alternatives considered.

In the remainder of this section we consider the power of the smooth tests against parametric departures from the null density. Suppose we have a family of densities $f(x|\beta)$, indexed by a scalar parameter $\beta$, which contains the null density $f(x) = f(x|\beta = 0)$. 
<table>
<thead>
<tr>
<th>Alternative:</th>
<th>$W_2$</th>
<th>Lap.</th>
<th>Log.</th>
<th>$EV(.5)$</th>
<th>$D(-.5)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$n$:</td>
<td>20</td>
<td>50</td>
<td>20</td>
<td>50</td>
<td>20</td>
</tr>
<tr>
<td>Test Statistic</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$\psi_1^2(\lambda_0^0)$</td>
<td>26*</td>
<td>55</td>
<td>29</td>
<td>31</td>
<td>18</td>
</tr>
<tr>
<td>$\psi_2^2(\lambda_0^0)$</td>
<td>22</td>
<td>52</td>
<td>39*</td>
<td>69*</td>
<td>21</td>
</tr>
<tr>
<td>$\psi_3^2(\lambda_0^0)$</td>
<td>18</td>
<td>42</td>
<td>38</td>
<td>66</td>
<td>20</td>
</tr>
<tr>
<td>$\psi_4^2(\lambda_0^0)$</td>
<td>20</td>
<td>40</td>
<td>39</td>
<td>66</td>
<td>21</td>
</tr>
<tr>
<td>$\chi^2_2$</td>
<td>12</td>
<td>--</td>
<td>25</td>
<td>--</td>
<td>13</td>
</tr>
<tr>
<td>$\chi^7_2$</td>
<td>--</td>
<td>23</td>
<td>--</td>
<td>38</td>
<td>--</td>
</tr>
<tr>
<td>$D$</td>
<td>18</td>
<td>34</td>
<td>31</td>
<td>54</td>
<td>15</td>
</tr>
<tr>
<td>$b_1$</td>
<td>24</td>
<td>52</td>
<td>34</td>
<td>43</td>
<td>21*</td>
</tr>
<tr>
<td>$b_2$</td>
<td>15</td>
<td>21</td>
<td>35</td>
<td>61</td>
<td>18</td>
</tr>
<tr>
<td>$W$</td>
<td>25</td>
<td>58*</td>
<td>35</td>
<td>50</td>
<td>19</td>
</tr>
</tbody>
</table>

Note: entries are percentages rounded to nearest digit; tests are at $\alpha = 0.10$; $D =$ Kolmogorov-Smirnov, $W =$ Shapiro-Wilk; maximum power in each column denoted by asterisk.
Here \( \beta \) is not a nuisance parameter, and should one be required, we consider densities \( f(x|\beta, \lambda) \) with the null densities given by \( f(x|\lambda) = f(x|\beta = 0, \lambda) \). First, however, we consider the case of a simple hypothesis. Let \( U_{\beta} \) denote the efficient score for \( \beta \):

\[
U_{\beta} = U_{\beta}(0) = \left[ \partial \ln f(x|\beta) / \partial \beta \right]_{\beta=0}.
\]

The locally best test for \( H_0 : \beta = 0 \) is based on the asymptotic normal distribution of \( n^{1/2} U_{\beta} \); see, for example, Cox and Hinkley (1974; Section 4.8).

We assume that \( \psi_k^2 \) for some \( k \) is used to test the goodness-of-fit of the density \( f(x) = f(x|0) \) when in fact the departure is in the "\( \beta \) direction". Consider the family of densities which includes both smooth alternatives as well as \( \beta \)-departures from \( f(x|0) \):

\[
g(x|\theta, \beta) = f(x|\beta) \exp \left\{ \sum_{i=1}^{k} \theta_i F_i(x|0) - K(\theta, \beta) \right\}.
\]

Here \( K(\theta, \beta) \) is simply the normalizing constant, and clearly \( K(0, \beta) = 0 \) identically in \( \beta \). The use of the smooth test of \( H_0 : \theta = 0 \) is of course based on the assumption that \( \beta = 0 \). Proceeding as before we find that

\[
U_{\theta}(\theta=0, \beta=0) = \begin{bmatrix}
F(x|0) - 1/2 \\
\vdots \\
F^k(x|0) - (k+1)^{-1}
\end{bmatrix}.
\]
Also

\[ U_\beta (\theta = 0, \beta = 0) = U_\beta, \]

that is, the \( \beta \)-score for the larger family is just the same as the \( \beta \)-score for the parametric family of densities \( f(x | \beta) \). So we may denote the scores by \( U_\theta \) and \( U_\beta \) without ambiguity. The covariance matrix of the vector of scores \( [U'_\theta, U'_\beta]' \) may be partitioned in an obvious fashion as

\[
\begin{bmatrix}
  i_{\theta \theta} & i_{\theta \beta} \\
  i_{\beta \theta} & i_{\beta \beta}
\end{bmatrix}
\]

(2.1)

Here \( i_{\theta \theta} \) is the same as before, given by (II.2.3), and \( i_{\beta \beta} \) is just the information about \( \beta \) contained in \( x \), relative to the family \( f(x | \beta) \). If this quantity is finite, since \( i_{\theta \theta} \) is finite for all \( j \), it follows that \( i_{\beta \beta} = \text{Cov}[i(x | 0), U_\beta | \theta = 0, \beta = 0] \) is also finite for all \( j \).

Under regularity conditions on the family of densities \( f(x | \beta) \)--see the Appendix--the approximate large-sample distribution of the efficient score vector is given by

\[
n^{-1/2} \begin{bmatrix} U'_\theta \\ U'_\beta \end{bmatrix} \sim N_{k+1}(0, \begin{bmatrix} i_{\theta \theta} & i_{\theta \beta} \\
  i_{\beta \theta} & i_{\beta \beta}\end{bmatrix}^{1/2} \begin{bmatrix} \theta^* \\ \beta^* \end{bmatrix}, \begin{bmatrix} i_{\theta \theta} & i_{\theta \beta} \\
  i_{\beta \theta} & i_{\beta \beta}\end{bmatrix}^{1/2})
\]

for \( (\theta^*, \beta^*) \) near \( (0, 0) \). So the marginal distribution of the
\( \theta \)-scores, when there is a "pure" \( \beta \) departure, is approximately given by
\[
n^{-1/2} U_{\theta} \sim N_k(n^{1/2} i_{\theta \beta} \beta^*; i_{\theta \theta}).
\]

Therefore the noncentrality parameter for the test based on \( \psi_k^2 \) under a local alternative of the \( f(x|\beta) \) type, is

\[
(2.2) \quad \delta(\beta^*) = n(i_{\theta \beta} \beta^*)^{-1} i_{\theta \theta} (i_{\theta \beta} \beta^*) = n(\beta^*)^2 i_{\beta} i_{\theta \theta} i_{\beta} = n(\beta^*)^2 i_{\beta} R_{\theta, \beta}^2
\]

where \( R_{\theta, \beta}^2 = i_{\beta} i_{\theta \theta} i_{\beta} / i_{\beta} \) is well known to be the squared multiple correlation coefficient of the scores \( U_{\theta 1}, \ldots, U_{\theta k} \) with \( U_{\beta} \) under the null hypothesis; see, for example, Anderson (1958, p. 32).

Equation (2.2) is intuitively quite appealing. If we suppose that \( n \) has a fixed, large value, since \( i_{\beta} \) is constant, the rate at which the power increases with \( (\beta^*)^2 \) depends on how closely the linear span of \( \{U_{\theta 1}, \ldots, U_{\theta k}\} \) comes to containing \( U_{\beta} \). If the \( \theta \)-scores are all orthogonal to (uncorrelated with) \( U_{\beta} \), then \( R_{\theta, \beta}^2 = 0 \) and the smooth test has, locally, no power against departures in the \( \beta \) direction. At the other extreme, if \( U_{\beta} \) is in the span of \( \{U_{\theta 1}, \ldots, U_{\theta k}\} \) then \( R_{\theta, \beta}^2 = 1 \). But \( n^2 i_{\beta} \) is the noncentrality parameter for the locally best test of \( H_0: \beta = 0 \) for the
family of densities \( f(x | \beta) \), under local departures. Of course if \( k = 1 \), then \( R_{\theta, \beta}^2 = 1 \) if and only if \( U_\beta \sim U_\theta \), in which case \( \psi_1^2 \) is exactly the quadratic score statistic for testing \( H_0 : \beta = 0 \), so the two tests must have identical power. But if \( k > 1 \), then the alternative distributions are

\[
\psi_k^2 \sim \chi_k^2, n\beta_i^2, \beta^2
\]

and

\[
W_u = U_\beta^2 / i, \beta^2 \sim \chi_1^2, n\beta_i^2, \beta^2
\]

which implies that \( W_u \) is locally more powerful than \( \psi_k^2 \), since the noncentral \( \chi^2 \) distributions are stochastically increasing in their degrees of freedom for any fixed value of their noncentrality parameter. Heuristically, \( \psi_k^2 \) is indeed giving protection in the right direction, but is losing power in other directions when \( k > 1 \). Correction for unequal degrees of freedom will be discussed at more length in Section 6.

Before calculating some example values of \( R_{\theta, \beta}^2 \), we consider the more important case of composite hypotheses. The development follows closely that given above and therefore will only be outlined.

We begin with a family of densities \( f(x | \beta, \lambda) \) where \( \lambda \in \mathbb{R}^s \) is a nuisance parameter. The \( \beta \)-score is then
\[ U_\beta(0, \lambda) = \left[ \ln f(x|\beta, \lambda) / \ln \beta \right]_{\beta=0, \lambda}. \]

Analogously, the \( \lambda \)-score is given by

\[ U_\lambda(0, \lambda) = \left[ \ln f(x|\beta, \lambda) / \ln \lambda \right]_{\beta=0, \lambda} \]

and

\[ U_\lambda(0, \lambda) = [U_{\lambda_1}(0, \lambda), \ldots, U_{\lambda_s}(0, \lambda)]'. \]

Consider the density functions

\[ g(x|\theta, \beta, \lambda) = f(x|\beta, \lambda) \exp \left\{ \sum_{i=1}^{k} \theta_i F_i(x|0, \lambda) - K(\theta, \beta, \lambda) \right\}. \]

Clearly \( K(0, \beta, \lambda) = 0 \) identically in \( \beta \) and \( \lambda \), and \( K(\theta, 0, \lambda) \) is constant in \( \lambda \). As before

\[ U_\theta(\theta=0, \beta=0, \lambda) = \begin{bmatrix} F(x|0, \lambda)-1/2 \\ \vdots \\ F^k(x|0, \lambda)-(k+1)^{-1} \end{bmatrix} \]

and

\[ U_\beta(\theta=0, \beta=0, \lambda) = U_\beta(0, \lambda). \]

That is, the \( \beta \)-score for the larger family of densities is just the \( \beta \)-score for the parametric family \( f(x|\beta, \lambda) \). Similarly,

\[ U_\lambda(\theta=0, \beta=0, \lambda) = U_\lambda(0, \lambda). \]
The overall information matrix may be written in partitioned form as

\[
\begin{bmatrix}
  i_{\theta \theta} & i_{\theta \beta} & i_{\theta \lambda} \\
  i_{\beta \theta} & i_{\beta \beta} & i_{\beta \lambda} \\
  i_{\lambda \theta} & i_{\lambda \beta} & i_{\lambda \lambda}
\end{bmatrix}
\]

(2.3)

where \( i_{\beta \beta} \) and \( i_{\lambda \lambda} \) are the information matrices for the smaller parametric families of densities \( f(x|\beta, \lambda) \) and \( f(x|0, \lambda) \), respectively. The possible dependence of some entries of (2.3) on \( \lambda \) has been suppressed in the notation. As usual \( i_{\theta \theta} = i_{\theta \theta}(\theta=0, \beta=0, \lambda) \) is constant in \( \beta \) and \( \lambda \), and is given by (II. 2.3). The remaining parts of (2.3) may depend on \( \lambda \). However, in the examples to be considered below, the more important adjusted covariance matrices are free of \( \lambda \). In the case that \( i_{\theta \beta} \) and \( i_{\beta \beta} \) are independent of \( \lambda \), the upper left portion of (2.3) is just the same as (2.1).

Now we consider the adjusted \( \theta \)- and \( \beta \)-scores

\[
U_{\theta|\lambda}(\lambda) = U_{\theta|\lambda}(0, 0, \lambda) = U_{\theta}(0, 0, \lambda) - i_{\theta \lambda} i_{\lambda \lambda}^{-1} U_{\lambda}(\lambda),
\]

and

\[
U_{\beta|\lambda}(\lambda) = U_{\beta}(0, \lambda) - i_{\beta \lambda} i_{\lambda \lambda}^{-1} U_{\lambda}(\lambda),
\]

for which the covariance matrix may be written
where

\[ i_{\theta \theta} | \lambda = i_{\theta \theta} - i_{\theta \lambda} i_{\lambda \lambda} i_{\lambda \theta} \]

as before, and

\[ i_{\theta \beta} | \lambda = i_{\theta \beta} - i_{\theta \lambda} i_{\lambda \lambda} i_{\lambda \beta} \]

\[ i_{\beta \beta} | \lambda = i_{\beta \beta} - i_{\beta \lambda} i_{\lambda \lambda} i_{\lambda \beta} \]

Under regularity conditions discussed in the Appendix it follows that for large \( n \)

\[
n^{-1/2} \begin{bmatrix} U_{\theta} | \lambda \left( \lambda \right) \\ U_{\beta} | \lambda \left( \lambda \right) \end{bmatrix} \approx \mathcal{N}_{k+1} \left( \begin{bmatrix} i_{\theta \theta} | \lambda \\ i_{\theta \beta} | \lambda \end{bmatrix}, \begin{bmatrix} i_{\theta \theta} | \lambda & i_{\theta \beta} | \lambda \\ i_{\theta \beta} | \lambda & i_{\beta \beta} | \lambda \end{bmatrix} \right) \]

when \( (\theta^*, \beta^*) \) is near \( (0, 0) \). Thus the marginal distribution of the adjusted \( \theta \)-scores under a \( \beta \) departure is approximately given by

\[
n^{-1/2} U_{\theta} | \lambda \left( \lambda \right) \approx \mathcal{N}_{k} \left( n^{1/2} i_{\theta \beta} | \lambda \left( \beta^* \right), i_{\theta \theta} | \lambda \right), \]

and the noncentrality parameter for the test based on \( \psi_k^{2}(\lambda_0) \) is, for small \( \beta^* \), large \( n \), and an appropriate \( \lambda_0 \).
\begin{equation}
\delta(\beta^*|\lambda) = n(\iota_0\beta|\lambda \beta^*)' i^{-1} \iota_0 \theta |\lambda (\iota_0 \beta |\lambda \beta^*)
\end{equation}

\[ = n(\beta^*)^2 i_\beta \theta |\lambda i_\theta \theta |\lambda i_\theta \beta |\lambda \]

\[ = n(\beta^*)^2 i_\beta \beta |\lambda R^2_{\theta, \beta |\lambda} \]

where

\[ R^2_{\theta, \beta |\lambda} = i_\beta \theta |\lambda i^{-1}_\theta \theta |\lambda i_\theta \beta |\lambda / i_\beta \beta |\lambda \]

is, by analogy with $R^2_{\theta, \beta |\lambda}$, the natural way to define the squared partial multiple correlation coefficient of the scores $U_{\theta_1}(\lambda), \ldots, U_{\theta_k}(\lambda)$ with $U_\beta(\lambda)$, adjusting for $U_\lambda(\lambda)$, when $X$ has density $f(x|0, \lambda)$. In other words, $R^2_{\theta, \beta |\lambda}$ is the multiple correlation of $U_{\theta_1}(\lambda), \ldots, U_{\theta_k}(\lambda)$ with $U_\beta(\lambda)$, the parts of the $\theta$- and $\beta$-scores which are orthogonal to, or "free of," $U_\lambda(\lambda)$.

Notice the similarity of (2.4) to (2.2), and recall that $n(\beta^*)^2 i_\beta \beta |\lambda$ is the local noncentrality parameter for $W^A_\lambda(\lambda_0)$, the generalization of the locally best test of $H_0: \beta = 0$ for the family of densities $f(x|\beta)$ to the test of $H_0: \beta = 0$, $\lambda$ unknown, for the family of densities $f(x|\beta, \lambda)$. As before, if $R^2_{\theta, \beta |\lambda} = 1$ and $k = 1$, then this test is equivalent to the smooth test based on $\psi^A_1(\lambda_0)$. However, for $k > 1$, $\psi^A_k(\lambda_0)$ will be less powerful than $W^A_\lambda(\lambda_0)$. This suggests also that if $R^2_{\theta, \beta |\lambda}$ increases slowly with $k$, then the power of the smooth test will decrease as $k$ increases.
Before proceeding to the calculation of some exemplary multiple correlation coefficients, we comment on the restriction to scalar \( \beta \). The densities \( g(x | \theta, \beta) \) and \( g(x | \theta, \beta, \lambda) \) were introduced in order to permit the calculation of powers and efficiencies of tests against certain departures from the null density. They are not intended to be models for the behavior of observable phenomena, so the additional richness of the class of densities provided by a vector \( \beta \) is of no value in that regard. And in thinking of power properties of a test, it is perhaps most useful to think in terms of one "direction" at a time. For the local departures being considered here, a departure along a straight line from the origin in the parameter space suffices for this, and this can be modeled as an alternative in a scalar parameter, after a reparameterization, if necessary.

III.3. Multiple Correlations for Tests of the Exponential Distribution: Weibull Departures

We consider applying a smooth test for exponential goodness of fit when the alternative is in fact a Weibull distribution. The approach of Section 2 applies directly in this case. The Weibull densities may be written

\[
f(x | \beta, \lambda) = \lambda^{-1}(x / \lambda)^{\beta - 1} \exp\{- (x / \lambda)^\beta\}
\]

for \( x, \beta, \lambda > 0 \). Suppose first that the scale parameter is known:
we take it to be $\lambda = 1$ without loss of generality. Thus we are
testing the null hypothesis that the density is $f(x) = \exp(-x)$. Now the
necessary matrices are obtained by easy modifications of the results
of Section II. 4. C with $\lambda = \sigma, \beta = \tau$. Thus

\[
i_{\theta \beta} = 1.828681
\]

\[
i_{\theta, j} \beta = j[1 - \gamma \ln(j+1)]/(j+1)^2
\]

where $\gamma = 0.577216\ldots$ is Euler's constant. Numerically then, for
$k$ up to 4,

\[
i_{\theta \beta} = \begin{bmatrix}
-0.067591 \\
-0.150184 \\
-0.180658 \\
-0.189865
\end{bmatrix}.
\]

Taking $i_{\theta \theta}^{-1}$ from Section II. 2, the squared multiple correlation
coefficients $R^2_{\theta_1 \ldots \theta_k \beta} = i_{\theta \theta}^{-1} i_{\theta \beta} i_{\beta \beta} / i_{\beta \beta}$ are calculated and listed
in Table 6a.

For testing the composite hypothesis that $X$ has an exponen-
tial distribution with unspecified scale parameter $\lambda$, we have

\[
i_{\lambda \lambda}(\lambda) = \lambda^{-2}
\]

\[
i_{\beta \lambda}(\lambda) = -(1 - \gamma)/\lambda = -0.422784\lambda^{-1}
\]

\[
i_{\lambda \theta}(\lambda) = [-1/4\lambda, -2/9\lambda, -3/16\lambda, -4/25\lambda].
\]
\[ i_\beta \beta | \lambda = 1.644934 \]

\[
\begin{pmatrix}
-0.173287 \\
-0.244136 \\
-0.259930 \\
-0.257510
\end{pmatrix}
\]

\[ i_\theta \beta | \lambda = \begin{pmatrix} \end{pmatrix} \]

Table 6. Multiple correlations for Weibull departures from the exponential distribution.

<table>
<thead>
<tr>
<th>k</th>
<th>( R^2_{\theta_1 \ldots \theta_k, \beta} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>a. Simple hypothesis</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.030</td>
</tr>
<tr>
<td>2</td>
<td>0.703</td>
</tr>
<tr>
<td>3</td>
<td>0.729</td>
</tr>
<tr>
<td>4</td>
<td>0.860</td>
</tr>
</tbody>
</table>

| b. Composite hypothesis (\( \lambda = \) scale parameter) |                                             |
| 1   | 0.876                                    |
| 2   | 0.918                                    |
| 3   | 0.965                                    |
| 4   | 0.972                                    |

For \( k \) up to 4, \( i_\theta^{-1} | \lambda \) may be found in Table 2, so the squared partial multiple correlation coefficients

\[ R^2_{\theta_1 \ldots \theta_k, \beta | \lambda} = i_\beta \theta | \lambda i_\theta \theta | \lambda i_\theta \beta | \lambda i_\beta \beta | \lambda \] can be calculated, and are listed in Table 6b. Notice that in each case, \( R^2_{\theta, \beta} < R^2_{\theta_1 \ldots \theta_k, \beta | \lambda} \). For
The difference is quite extreme, the squared correlations being 0.030 and 0.876, respectively. In Section 6 it will be seen that this implies that $\psi_1^2$ is much less efficient for testing the simple hypothesis of exponential goodness of fit than $\psi_1^2(\lambda_0)$ is for testing the composite hypothesis. The difference in correlations is vividly illustrated in Figures 9 and 10. The first shows the standardized score functions

$$U_{\theta_1 | \theta_1}^{-1/2} = (y - \frac{1}{2})/0.288675$$

$$U_{\beta | \beta}^{-1/2} = [1 +(1 + \ln y)\ln(-\ln y)]/1.352293$$

and the second shows

$$-U_{\lambda_1 | \lambda_1}^{-1/2} = [-y + \frac{1}{4} \ln y + \frac{3}{4}]/0.144338$$

$$U_{\beta | \beta}^{-1/2} = [2 - \gamma + (1 + \ln y)\ln(-\ln y) + (1-\gamma)\ln y]/1.282550.$$ 

Notice that the score functions are given in terms of $y = \bar{F}(x | \lambda) = \exp(-x/\lambda)$. The standardization and the use of $-U_{\theta_1 | \lambda}$ have no effect on the correlations, but make the curves more readily comparable.
Figure 9. Neyman and Weibull scores for tests of simple exponentiality.
Figure 10. Neyman and Weibull scores for tests of composite exponentiality.
III. 4. Multiple Correlations for Tests of the Exponential Distribution: Gamma Departures

We proceed as in the previous section. The Gamma densities are given by

\[ f(x | \beta, \lambda) = \lambda^{-1} \left[ \Gamma(\beta) \right]^{-1} (x / \lambda)^{\beta-1} \exp(-x / \lambda) \]

for \( x, \beta, \lambda > 0 \). Assume first we are testing a simple hypothesis of exponential goodness of fit: without loss of generality we take \( \lambda = 1 \).

Now

\[ U_{\beta} (\beta=1) = -\psi(1) + \ln x = \gamma + \ln x \]

where \( \psi(\beta) = \partial \ln \Gamma(\beta) / \partial \beta \) and \( \psi(1) = -\gamma = -0.577216... \) is the negative of Euler's constant. Since

\[ \partial^2 \ln f(x | \beta, 1) / \partial \beta^2 = -\psi'(\beta) \]

it follows that

\[ i_{\theta \beta} = -\mathbb{E} \{ \partial^2 \ln f(x | \beta, 1) / \partial \beta^2 \}_\beta=1 = \psi'(1) = 1.644934. \]

Also since \( U_{\theta j} = \exp(-jx) - (j+1)^{-1} \)

\[ i_{\theta j, \beta} = \int_0^{\infty} (\ln x) \exp\{- (j+1)x\} dx + \gamma / (j+1) \]

\[ = -[\ln(j+1)] / (j+1) \]
or, numerically, for $k$ up to 4,

$$i_{\theta \beta} = \begin{bmatrix} -0.346574 \\ -0.366204 \\ -0.346574 \\ -0.321888 \end{bmatrix}.$$

With $i^{-1} \theta \theta$ from Section II.2, the squared multiple correlation coefficients $R_{\theta_1 \ldots \theta_k, \beta}^2$ are calculated and listed in Table 7a.

**Table 7. Multiple correlations for Gamma departures from the exponential distribution.**

<table>
<thead>
<tr>
<th>$k$</th>
<th>$R_{\theta_1 \ldots \theta_k, \beta}^2$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>a.</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.876</td>
</tr>
<tr>
<td>2</td>
<td>0.918</td>
</tr>
<tr>
<td>3</td>
<td>0.965</td>
</tr>
<tr>
<td>4</td>
<td>0.972</td>
</tr>
<tr>
<td>b.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.694</td>
</tr>
<tr>
<td>2</td>
<td>0.840</td>
</tr>
<tr>
<td>3</td>
<td>0.910</td>
</tr>
<tr>
<td>4</td>
<td>0.938</td>
</tr>
</tbody>
</table>
For the test of the composite hypothesis that \( X \) has an exponential distribution with unknown scale parameter, it is easily seen that \( i_{\beta\beta} \) and \( i_{\theta\beta} \) are the same as above. Moreover, since

\[
U_\lambda(\lambda) = (x-\lambda)/\lambda^2
\]

is distributed under \( H_0 \) the same as for Weibull departures in Section 3, it is easy to see that \( i_{\lambda\lambda} \) and \( i_{\theta\lambda} \) are the same as in Section 3. Also \( i_{\beta\lambda} = \lambda^{-1} \). So we may calculate the adjusted covariance matrices

\[
i_{\beta\beta} | \lambda = 0.644934
\]

and

\[
i_{\theta\beta} | \lambda = \begin{bmatrix}
-0.096574 \\
-0.143982 \\
-0.159070 \\
-0.161888
\end{bmatrix}
\]

Finally, \( i_{\theta\theta}^{-1} \) is given in Table 2 for \( k \) up to 4, so the squared partial multiple correlation coefficients may be calculated. These are listed in Table 7b. Two features of this table are notable. First, the multiple correlations for a Gamma departure from the simple hypothesis are the same as the partial multiple correlations for the Weibull departure from the composite hypothesis. Second, unlike the previous
example, \( R_{\theta_1 \ldots \theta_k, \beta|\lambda}^2 < R_{\theta_1 \ldots \theta_k, \beta}^2 \) for each \( k \).

III.5. Multiple Correlations for Tests of Normality: Skewness and Kurtosis Departures

In this example we depart somewhat from the situations of the previous sections, however the essential results are not altered. We seek to obtain the noncentrality parameters of the smooth tests for normality when the alternatives differ in skewness or kurtosis. Let 
\[
\phi(x) = (2\pi)^{-1/2} \exp\left(-\frac{x^2}{2}\right)
\]
be the standard normal density, and consider the functions

\[
(5.1) \quad h(x|\beta_1, \beta_2) = \phi(x) \left\{ 1 + \beta_1 H_3(x) / 6 + (\beta_2 - 3) H_4(x) / 24 \right\}
\]

where
\[
H_3(x) = x^3 - 3x \\
H_4(x) = x^4 - 6x^2 + 3
\]

are the third and fourth order Hermite polynomials, respectively.

The function \( h \) is very nearly a probability density: it integrates to unity for all values of \( \beta_1 \) and \( \beta_2 \), however if \( (\beta_1, \beta_2) \neq (0, 3) \), then \( h(x|\beta_1, \beta_2) < 0 \) for some values of \( x \). But for \( (\beta_1, \beta_2) \) near \( (0, 3) \), the region in which \( h \) is negative has very low probability under the null density \( \phi(x) \), so we will deal with \( h \) as if it were a probability density since we are concerned with local departures.
The alternatives (5.1) are in the spirit of (II.2.2) proposed by Barton (1953) and are simply truncated Gram-Charlier expansions of Type A; see, for example, Kendall and Stuart (1969; Sections 6.14-6.16).

Taking \( h \) as a density, the moments of \( X \) are

\[
E(X \mid \beta_1, \beta_2) = 0
\]
\[
E(X^2 \mid \beta_1, \beta_2) = \text{Var}(X \mid \beta_1, \beta_2) = 1
\]
\[
E(X^3 \mid \beta_1, \beta_2) = \text{Skew}(X \mid \beta_1, \beta_2) = \beta_1
\]
\[
E(X^4 \mid \beta_1, \beta_2) = \text{Kurt}(X \mid \beta_1, \beta_2) = \beta_2.
\]

There are, of course, alterations in the higher moments as well but these serve to index the departures of interest. The score functions for \( \beta_1 \) and \( \beta_2 \) are easily seen to be

\[
U_{\beta_1} = H_3(x)/6 = (x^3 - 3x)/6
\]
\[
U_{\beta_2} = H_4(x)/24 = (x^4 - 6x^2 + 3)/24.
\]

From well-known properties of Hermite polynomials it follows that

\[
(5.2) \quad i\beta_1 \beta_1 = 1/6
\]
\[
i\beta_2 \beta_2 = 1/24.
\]

To compute \( i \theta \beta_1 \) and \( i \theta \beta_2 \) we employ Table X in Barton (1953)
and after some calculation find that for \( k \) up to 4

\[
\begin{align*}
i_{\theta_1} & = \begin{bmatrix}
-1/24\pi^{1/2} \\
-1/24\pi^{1/2} \\
\{-3(S_3 + 18\pi) + 10\sqrt{2}\}/480\pi^{3/2} \\
\{-3(S_3 + 8\pi) + 10\sqrt{2}\}/240\pi^{3/2}
\end{bmatrix} \\
\end{align*}
\]

(5.3)

and

\[
\begin{align*}
i_{\theta_2} & = \begin{bmatrix}
0 \\
-5\sqrt{3}/432\pi \\
-5\sqrt{3}/288\pi \\
\{-\sqrt{3}(25S_4 + 200\pi) + 21\sqrt{5}\}/10080\pi^2
\end{bmatrix}
\end{align*}
\]

(5.4)

where

\[
S_3 = 10 \arcsin(1/3) - \pi = 0.256776441
\]

\[
S_4 = 14 \arcsin(1/4) - \pi = 0.395930917.
\]

Numerically,

\[
\begin{align*}
i_{\theta_1} & = \begin{bmatrix}
-0.023507899 \\
-0.023507899 \\
-0.016154184 \\
-0.008800469
\end{bmatrix}
\end{align*}
\]

(5.5)

and
With these and with \( i_{\Theta} \) from Section II. 2 we can calculate

\[
R^2_{\Theta j} = \frac{i_{\Theta j}^{-1} \beta_j i_{\Theta j}^{-1} / \beta_j \beta_j}{i_{\Theta j}^{-1} \beta_j i_{\Theta j}^{-1}} \text{ for } j = 1, 2.
\]

These multiple correlation coefficients are displayed in Table 8a. Since \( R^2_{\Theta 1, \Theta 2} = 0 \), we see that \( \psi_1 \) has no power against departures from normality which affect the kurtosis but not the symmetry of the distribution. This is not surprising, since \( U_{\Theta 1} = \phi(x) - \frac{1}{2} \) is an odd function of \( x \), while the kurtosis score \( U_{\Theta 2} = H_4(x)/24 = (x^4 - 6x^2 + 3)/24 \) is an even function.

Notice also that the multiple correlation does not increase if

\[
U_{\Theta 3} = \phi^3(x) - \frac{1}{4}
\]

is added to \( U_{\Theta 1} \) and \( U_{\Theta 2} \). Unfortunately this does not bear a simple interpretation: if \( U_{\Theta 3} \) and \( U_{\Theta 2} \) are regressed on \( U_{\Theta 1} \) and \( U_{\Theta 2} \), the two residual functions are

\[
\phi^3(x) - \frac{5}{2} \phi^2(x) + \frac{3}{5} \phi(x) + \frac{17}{60}
\]

and

\[
\frac{1}{24} H_4(x) + \frac{25\sqrt{3}}{36\pi} (3 \phi^2(x) - 3 \phi(x) + \frac{1}{2})
\]

which can easily be shown to be uncorrelated, but these functions have
no apparent significant interpretation. Similar behavior is seen in values of \( R^2_{\theta, \beta_1} \).

The results given above for the standard normal distribution apply to any simple hypothesis of normality, for if \( \mu \) and \( \sigma^2 \) are known, the observations can be standardized. Now suppose we must test a composite hypothesis of normality with \( \lambda = (\mu, \sigma)^T \) unknown. Analogous to (5.1) we consider densities

\[(5.7) \quad h(x \mid \beta_1, \beta_2, \lambda) = \sigma^{-1} \phi(z) \left\{ 1 + \beta_1 H_3(z) / 6 + (\beta_2 - 3) H_4(z) / 24 \right\} \]

where \( z = (x - \mu) / \sigma \). Now \( i_{\beta_1} \beta_1 (\lambda) \), \( i_{\beta_2} \beta_2 (\lambda) \), \( i_{\theta_1} \theta_1 (\lambda) \), and \( i_{\theta_2} \theta_2 (\lambda) \) are all independent of \( \lambda \), and are just the same as given in (5.2) - (5.6). Also, \( i_{\lambda \lambda} \lambda (\lambda) \) and \( i_{\theta \lambda} \lambda (\lambda) \) are given by (II.4.1) and (II.4.2), respectively. Finally, since Hermite polynomials of different orders are uncorrelated, we find that \( i_{\beta_1} \lambda (\lambda) = i_{\beta_2} \lambda (\lambda) = [0, 0] \). From this last fact, for \( j = 1, 2 \)

\[
i_{\theta_j} \lambda = i_{\theta_j} \lambda - i_{\theta \lambda} i_{\lambda \lambda} (\lambda) i_{\lambda \beta_j} = i_{\theta_j} \lambda \]

\[
i_{\beta_j} \beta_j \lambda = i_{\beta_j} \beta_j - i_{\beta_j \lambda} i_{\lambda \lambda} (\lambda) i_{\lambda \beta_j} = i_{\beta_j} \beta_j \]

Taking \( i_{\theta \theta}^{-1} \lambda \) from Table 1 we can compute

\[
R^2_{\theta_1 \ldots \theta_k, \beta_j \lambda} = i_{\beta_j \theta \theta}^{-1} i_{\theta \lambda} i_{\lambda \beta_j} / i_{\beta_j} \beta_j \]
for \( k = 1, \ldots, 4 \) and \( j = 1, 2 \). These values are shown in Table 8b.

Notice that \( R_{\theta_1 \theta_2}^2 |_{\lambda} = 0 \) and that while the correlation coefficients are much higher than for the simple hypothesis, they still exhibit the behavior of increasing only with even or odd \( k \).

Table 8. Multiple correlations for skewness and kurtosis departures from the normal distribution.

<table>
<thead>
<tr>
<th>( k )</th>
<th>( R_{\theta_1 \theta_k \beta_1}^2 )</th>
<th>( R_{\theta_1 \theta_k \beta_2}^2 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>a. Simple hypothesis</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.040</td>
<td>0.000</td>
</tr>
<tr>
<td>2</td>
<td>0.040</td>
<td>0.176</td>
</tr>
<tr>
<td>3</td>
<td>0.460</td>
<td>0.176</td>
</tr>
<tr>
<td>4</td>
<td>0.460</td>
<td>0.296</td>
</tr>
</tbody>
</table>

| \( R_{\theta_1 \theta_k \beta_1}^2 |_{\lambda} \) | \( R_{\theta_1 \theta_k \beta_2}^2 |_{\lambda} \) |
|-----------------|-----------------|
| b. Composite hypothesis | | |
| (\( \lambda = (\mu, \sigma)' \)) | | |
| 1 | 0.883 | 0.000 |
| 2 | 0.883 | 0.733 |
| 3 | 0.996 | 0.733 |
| 4 | 0.996 | 0.863 |

When the noncentrality parameter is the same, the test with more degrees of freedom will have less power than the test with fewer degrees of freedom. So, for example, in testing for normality, \( \psi_1^2 \) has better power than \( \psi_2^2 \) against local departures in \( \beta_1 \). If the noncentrality parameter increases with \( k \), it becomes a question of whether that increase is sufficient to overcome the loss in power incurred by the increase of \( k \). The problem of adjusting for unequal
degrees of freedom will be explored more carefully in the following section.

III. 5. Asymptotic Relative Efficiency of the Smooth Tests

Pitman's measure of asymptotic relative efficiency is a very useful tool for comparing statistical tests of hypotheses. Briefly, the efficiency is the ratio of the sample sizes required by the two procedures in question in order to insure that they have equal power at each point in a sequence of alternatives converging to the hypothesized law. This is typically done by showing that the power functions of the two tests are asymptotically of the same form, say $G(\cdot)$, but with different arguments, say $G(u_1)$ and $G(u_2)$, where the $u$'s depend on sample sizes, alternative parameter values, etc. The limiting ratio of the sample sizes which insures the equality of the $u$'s in the limit is then taken to be the asymptotic relative efficiency. This is the outline of an argument available in detail in Noether (1955) or Kendall and Stuart (1973; Sections 25.5-6). Very often the test statistics are asymptotically normal, so that $G(\cdot)$ has the same form for both tests, however the same argument applies if the test statistics asymptotically have $\chi^2$ distributions with the same degrees of freedom. In this case, the asymptotic relative efficiency can be shown to be the ratio of the two noncentrality parameters. This was shown by Hannan (1956). Hájek and Šidák (1967) use this as
the definition of the asymptotic relative efficiency of two tests based on asymptotically $\chi^2$ statistics with equal degrees of freedom. However the argument does not apply to $\chi^2$ statistics with unequal degrees of freedom, since the power functions have different forms, say $G_1$ and $G_2$, and equating the arguments of the two functions no longer insures equal power. This point was apparently overlooked by Kendall and Stuart (1973; Section 25.15). Hamdan (1964) computed the Pitman efficiency of a smooth test based on Walsh functions relative to Neyman's smooth test with the same degrees of freedom for a simple hypothesis of normality when the alternative is a shift in the mean.

Blomqvist (1950) defined the relative efficiency of two tests to be the limiting ratio of sample sizes required to insure that the asymptotic power functions have equal slopes at the value specified by the null hypothesis. Noether (1955) showed that under weak conditions this is equivalent to Pitman's measure of efficiency; see also Kendall and Stuart (1973; Section 25.8). Shirahata (1976) redefined the local asymptotic efficiency of Hájek and Šidák (1967) as the slope of the power function at the origin. In his Theorem 5.1 he then showed the following. Suppose two test statistics of $H_0: \delta = 0$, $T_1$ and $T_2$, are asymptotically distributed as $\chi^2_{k_1, c_1 \delta^2}$ and $\chi^2_{k_2, c_2 \delta^2}$, respectively. Then for tests of size $\alpha$, the local asymptotic relative efficiency of the first test to the second is
(6.1) \[ e(T_1, T_2; \alpha) = \frac{c}{c_2} \frac{1 - \alpha - \text{Pr}\{\chi_{k+2}^2 \leq \chi_k^2 (1-\alpha)\}}{1 - \alpha - \text{Pr}\{\chi_{k+2}^2 \leq \chi_k^2 (1-\alpha)\}} \]

This is just the ratio of slopes of the power functions where, for convenience, we may think of differentiating with respect to \( \delta^2 \). The local asymptotic relative efficiency is the product of the ratio of noncentrality parameters with a term which adjusts for the unequal degrees of freedom. Note that this measure of efficiency depends on \( \alpha \), the size of the test. For reference, values of 

\[ 1 - \alpha - \text{Pr}\{\chi_{k+2}^2 \leq \chi_k^2 (1-\alpha)\} \]

are tabulated in Table 9 for various \( k \) and \( \alpha \).

Table 9. Values of \( 1 - \alpha - \text{Pr}\{\chi_{k+2}^2 \leq \chi_k^2 (1-\alpha)\} \).

<table>
<thead>
<tr>
<th>( k )</th>
<th>( \alpha = 0.10 )</th>
<th>( \alpha = 0.05 )</th>
<th>( \alpha = 0.01 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.339</td>
<td>0.229</td>
<td>0.075</td>
</tr>
<tr>
<td>2</td>
<td>0.230</td>
<td>0.150</td>
<td>0.046</td>
</tr>
<tr>
<td>3</td>
<td>0.183</td>
<td>0.117</td>
<td>0.035</td>
</tr>
<tr>
<td>4</td>
<td>0.155</td>
<td>0.098</td>
<td>0.029</td>
</tr>
<tr>
<td>5</td>
<td>0.136</td>
<td>0.086</td>
<td>0.025</td>
</tr>
<tr>
<td>6</td>
<td>0.123</td>
<td>0.077</td>
<td>0.022</td>
</tr>
<tr>
<td>7</td>
<td>0.112</td>
<td>0.070</td>
<td>0.020</td>
</tr>
<tr>
<td>8</td>
<td>0.104</td>
<td>0.065</td>
<td>0.019</td>
</tr>
<tr>
<td>9</td>
<td>0.098</td>
<td>0.060</td>
<td>0.017</td>
</tr>
<tr>
<td>10</td>
<td>0.092</td>
<td>0.057</td>
<td>0.016</td>
</tr>
<tr>
<td>11</td>
<td>0.087</td>
<td>0.054</td>
<td>0.015</td>
</tr>
<tr>
<td>12</td>
<td>0.083</td>
<td>0.051</td>
<td>0.014</td>
</tr>
<tr>
<td>13</td>
<td>0.079</td>
<td>0.049</td>
<td>0.014</td>
</tr>
<tr>
<td>14</td>
<td>0.076</td>
<td>0.047</td>
<td>0.013</td>
</tr>
</tbody>
</table>
The evaluation of (6.1) is convenient and illuminating for the comparison of smooth tests with the quadratic score statistic test for some parametric departure as described in Section 2. Testing, for example, a simple hypothesis, we have

\[ \psi_k^2 \overset{\sim}{\sim} \chi_k^2, n\beta^2_i \beta \beta R^2_{\theta \theta} \]

\[ W_u \overset{\sim}{\sim} \chi_1^2, n\beta^2_i \beta \beta \]

so that

\[
(6.2) \quad e(\psi_k^2, W_u; \alpha) = R^2_{\theta \theta} \frac{1 - \alpha - \Pr \{ \chi_k^{2} \leq \chi_k^{2}(1 - \alpha) \}}{1 - \alpha - \Pr \{ \chi_3^{2} \leq \chi_1^{2}(1 - \alpha) \}}.
\]

Similarly, for a composite hypothesis,

\[
(6.3) \quad e(\psi_k^2 \Lambda_0, W_u \Lambda_0; \alpha) = R^2_{\theta \theta} |\lambda| \frac{1 - \alpha - \Pr \{ \chi_k^{2} \leq \chi_k^{2}(1 - \alpha) \}}{1 - \alpha - \Pr \{ \chi_3^{2} \leq \chi_1^{2}(1 - \alpha) \}}.
\]

Formulas (6.2) and (6.3) make explicit the trade-off that takes place as one increases \( k \), the order of the smooth test. As \( k \) increases, so does \( R^2_{\theta \theta} \) or \( R^2_{\theta \theta} |\lambda| \) and hence so does the non-centrality parameter. At the same time, however, increasing the degrees of freedom tends to reduce power, and this is reflected in the term \( 1 - \alpha - \Pr \{ \chi_k^{2} \leq \chi_k^{2}(1 - \alpha) \} \). One can expect the efficiency to
first increase with \( k \), and then decrease. By selecting the \( k \) which maximizes (6.2) or (6.3), one selects the best smooth test, in terms of efficiency, for the alternative under consideration. Notice that (6.2) and (6.3) represent a generalization of the result of van Eeden (1963) who related Pitman efficiency to the correlation of test statistics. The efficiencies (6.2) and (6.3) for the examples previously considered are listed in Table 10.

To obtain a measure of efficiency which does not depend on the size of the test, \( \alpha \), Shirahata (1976) considers

\[
e(T_1, T_2) = \lim_{\alpha \to 0} e(T_1, T_2; \alpha)
\]

and shows that, following the notation of (6.1),

\[
e(T_1, T_2) = \frac{c_1}{c_2} \times \frac{k_2}{k_1}
\]

an expression reminiscent of Kendall and Stuart's (1973) equation (25.64). However, \( e(T_1, T_2; \alpha) \) seems to be a more suitable measure of efficiency for two reasons. First, the ratio of the terms

\[1 - \alpha - \Pr\{\chi_{k+2}^2 \leq \chi_k^2(1-\alpha)\}\]

when the two degrees of freedom, \( k_1 \) and \( k_2 \), are fixed is fairly stable as \( \alpha \) varies between 0.01 and 0.10, the range of typical test sizes. Second, the values of the ratio on that range are closer to each other than to the limiting value
Table 10. Local asymptotic relative efficiencies ($\alpha = 0.10$).

<table>
<thead>
<tr>
<th>k</th>
<th>$e(\psi_k^2, W_u; .10)$</th>
<th>$e(\psi_k^2(\lambda_0), W_u(\lambda_0); .10)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>a. Normal distribution: skewness departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.040</td>
<td>0.883</td>
</tr>
<tr>
<td>2</td>
<td>0.027</td>
<td>0.599</td>
</tr>
<tr>
<td>3</td>
<td>0.248</td>
<td>0.538</td>
</tr>
<tr>
<td>4</td>
<td>0.210</td>
<td>0.455</td>
</tr>
<tr>
<td>b. Normal distribution: kurtosis departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.000</td>
<td>0.000</td>
</tr>
<tr>
<td>2</td>
<td>0.119</td>
<td>0.497</td>
</tr>
<tr>
<td>3</td>
<td>0.095</td>
<td>0.396</td>
</tr>
<tr>
<td>4</td>
<td>0.135</td>
<td>0.395</td>
</tr>
<tr>
<td>c. Exponential distribution: Weibull departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.030</td>
<td>0.876</td>
</tr>
<tr>
<td>2</td>
<td>0.477</td>
<td>0.623</td>
</tr>
<tr>
<td>3</td>
<td>0.394</td>
<td>0.521</td>
</tr>
<tr>
<td>4</td>
<td>0.393</td>
<td>0.444</td>
</tr>
<tr>
<td>d. Exponential distribution: gamma departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>0.876</td>
<td>0.694</td>
</tr>
<tr>
<td>2</td>
<td>0.623</td>
<td>0.570</td>
</tr>
<tr>
<td>3</td>
<td>0.521</td>
<td>0.491</td>
</tr>
<tr>
<td>4</td>
<td>0.444</td>
<td>0.429</td>
</tr>
</tbody>
</table>
For example, with $k_1 = 1$, $k_2 = 5$, the value of the ratio is 2.49, 2.66, and 3.00 for $\alpha = 0.1$, 0.05, and 0.01, respectively, while the limiting value is $k_2/k_1 = 5.00$.

It is often of interest to compare the behavior of tests in regions of moderate power, and this leads to a third measure of efficiency. Let $\delta(k, \alpha, \pi)$ denote the value of the noncentrality parameter necessary for a size-$\alpha$ test based on a $\chi^2$ statistic with $k$ degrees of freedom to have power $\pi$. For the smooth tests and the parametric tests, we have seen that these may be written

$$\delta(k, \alpha, \pi) = n \beta R^2 \theta_1 \cdots \theta_k, \beta^2(\alpha, \pi)$$

$$\delta(1, \alpha, \pi) = n \beta \beta^2(\alpha, \pi)$$

for $\psi_k^2$ and $W_u$, respectively. Notice that $\alpha$ and $\pi$ enter the expressions only through $\beta$. For moderate values of $\pi$, say, for example, $\pi = 0.5$, the consistency of $\chi^2$ tests insures that power $\pi$ may be attained locally if $n$ is sufficiently large. Now for $\alpha$ and $\pi$ fixed, in order to insure that power $\pi$ is achieved by both tests at the same value of $\beta^2(\alpha, \pi)$ we must have

$$\delta(k, \alpha, \pi)/n \beta R^2 \theta_1 \cdots \theta_k, \beta = \delta(1, \alpha, \pi)/n \beta \beta$$

or
\[
\frac{n_2}{n_1} = \frac{R_{21} \ldots R_{2k}}{\theta_1 \ldots \theta_k} \delta(1, \alpha, \pi)
\]

where \(n_1, n_2\) are the sample sizes for \(\psi_k^2\) and \(W_u\), respectively. So it is natural to define a moderate-power relative efficiency of \(\psi^2_k\) to \(W_u\), for \(\alpha\) and \(\pi\) given, by the asymptotic ratio of sample sizes:

\[
e(\psi^2_k, W_u; \alpha, \pi) = \frac{R_{21} \ldots R_{2k}}{\theta_1 \ldots \theta_k} \delta(1, \alpha, \pi)
\]

Values of the noncentrality parameters \(\delta(k, \alpha, \pi)\) are tabulated in, for example, Pearson and Hartley (1972; Table 25). More extensive tables, based on work by G. E. Hayman, Z. Govindarajulu, and F. C. Leone, are reproduced in Harter and Owen (1970). From these tables it may be seen that \(\delta(k, \alpha, \pi)\) increases with the degrees of freedom, \(k\), when \(\alpha\) and \(\pi\) are fixed. The generalization of (6.5) to tests of composite hypotheses is obvious. Investigation of these efficiencies will not be pursued at length since the measure depends on both \(\alpha\) and \(\pi\), however Table 11 lists values of \(e(\psi_k^2(X), W_u(X); .10, .5)\) for tests of the normal and exponential distributions. Notice that the entries in Table 11 are roughly comparable to, and never less than, the corresponding entries in Table 10.

It is of interest to note that each of the three measures of efficiency (6.2), (6.4), and (6.5), or its obvious generalization to
composite hypotheses, is of the form

\[ e = R^2(k)g(k) \]

where \( g(k) \) is a decreasing function in \( k \) which depends on the measure of efficiency being used and represents the "cost" of increasing the degrees of freedom, which must be balanced against the gain in \( R^2(k) \).

Table 11. Moderate-power efficiencies of smooth tests for composite hypotheses (\( \alpha = 0.1, \pi = 0.5 \)).

<table>
<thead>
<tr>
<th>k</th>
<th>( \beta_1 ) Departure</th>
<th>( \beta_2 ) Departure</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.883</td>
<td>0.000</td>
</tr>
<tr>
<td>2</td>
<td>0.671</td>
<td>0.557</td>
</tr>
<tr>
<td>3</td>
<td>0.644</td>
<td>0.474</td>
</tr>
<tr>
<td>4</td>
<td>0.574</td>
<td>0.497</td>
</tr>
</tbody>
</table>

Weibull Departure | Gamma Departure

<table>
<thead>
<tr>
<th>k</th>
<th>( \beta_1 ) Departure</th>
<th>( \beta_2 ) Departure</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.876</td>
<td>0.694</td>
</tr>
<tr>
<td>2</td>
<td>0.697</td>
<td>0.638</td>
</tr>
<tr>
<td>3</td>
<td>0.624</td>
<td>0.588</td>
</tr>
<tr>
<td>4</td>
<td>0.560</td>
<td>0.540</td>
</tr>
</tbody>
</table>

Clearly, one is not restricted to comparing only smooth tests with parametric tests by the means described above. Suppose one considers testing the hypothesis by means of another quadratic score statistic \( \phi_m^2 \) with \( m \) degrees of freedom based on the \( m \)-dimensional score vector \( U_\omega \). The parameter \( \omega \) might, for
example, arise by embedding the null density in a family indexed by $\omega$ in a manner analogous to the formation of the Neyman-type smooth alternatives. Following the derivation above we could calculate the efficiency (6.2) for the parametric $\beta$ departure: with obvious notation,

$$e(\phi_m^2, W_u; \alpha) = R^2_{\omega_1 \cdots \omega_m} \frac{\beta^{1-\alpha-\Pr\{X_m^2 \leq \chi_m^2(1-\alpha)\}}}{\beta^{1-\alpha-\Pr\{X^2 \leq \chi_1^2(1-\alpha)\}}}.$$  

Then the relative efficiency of the size-$\alpha$ test based on $\phi_m^2$ to the test based on $\psi_k^2$, with respect to $\beta$-departures, is

$$e(\phi_m^2, \psi_k^2; \alpha) = e(\phi_m^2, W_u; \alpha)/e(\psi_k^2, W_u; \alpha)$$

$$= \frac{R^2_{\omega_1 \cdots \omega_m} \beta^{1-\alpha-\Pr\{X_m^2 \leq \chi_m^2(1-\alpha)\}}}{R^2_{\theta_1 \cdots \theta_k} \beta^{1-\alpha-\Pr\{X_k^2 \leq \chi_k^2(1-\alpha)\}}}.$$  

With the usual modification, (6.7) can be applied to tests of composite hypotheses.

The relative efficiency in (6.7) permits us to make an interesting comparison. A test for normality with the mean and variance unknown can be based on the statistic

$$T = n\left[\frac{\hat{\sigma}^2}{\nu} + \frac{(\hat{\beta} - 3)^2}{24}\right]$$
where \( \hat{\beta}_1, \hat{\beta}_2 \) are the usual estimators of the skewness and kurtosis.

In fact this is just the quadratic score statistic for testing

\[ H_0 : \beta_1 = \beta_2 = 0 \quad \text{with} \quad \lambda = (\mu, \sigma)' \quad \text{unknown for the family of densities} \]

\[ h(x|\beta_1, \beta_2, \lambda) \]

given by (5.7). Clearly, the partial multiple correlation of \( U_{\beta_1}\lambda \) and \( U_{\beta_2}\lambda \) with \( U_{\beta_j}\lambda \) is unity for \( j = 1, 2, \) so from (6.7) we find that for a \( \beta_j \) departure

\[
e(\psi_k^2(\hat{\lambda}_0), T; \alpha) = R^2_{\theta_1 \ldots \theta_k, \beta_j|\lambda} \frac{1-\alpha \cdot \Pr\{\chi^2_{k+2} \leq \chi^2_k(1-\alpha)\}}{1-\alpha \cdot \Pr\{\chi^2_4 \leq \chi^2_2(1-\alpha)\}}
\]

For example, with \( \alpha = 0.10, \)

\[
e(\psi_k^2(\hat{\lambda}_0), T; .10) = R^2_{\theta_1 \ldots \theta_k, \beta_j|\lambda} \frac{1-\alpha \cdot \Pr\{\chi^2_{k+2} \leq \chi^2_k(1-\alpha)\}}{0.230} = \frac{1-\alpha \cdot \Pr\{\chi^2_{k+2} \leq \chi^2_k(1-\alpha)\}}{0.230}
\]

\[ = e(\psi_k^2(\hat{\lambda}_0), \lambda_{uj}(\hat{\lambda}_0); .10)(0.339) \]

\[ = 1.47e(\psi_k^2(\hat{\lambda}_0), \lambda_{uj}(\hat{\lambda}_0); .10)
\]

where \( \lambda_{uj}(\hat{\lambda}_0) \) denotes the quadratic score statistic for testing \( \beta_j, \) \( j = 1, 2. \) The efficiencies \( e(\psi_k^2(\hat{\lambda}_0), \lambda_{uj}(\hat{\lambda}_0); .10) \) are given in Tables 10a and 10b. This result once again demonstrates the effect of increasing the degrees of freedom of a test. For a \( \beta_j \) departure, \( T \) is poorer than \( \lambda_{uj}(\hat{\lambda}_0); \psi_k^2(\hat{\lambda}_0) \) is nearly 50% more efficient relative to \( T \) than to \( \lambda_{uj}(\hat{\lambda}_0). \)
III. 7. Comparison of Pearson's $\chi^2$ with the Smooth Tests

The remarks at the end of the previous section lead us to a method of determining the relative efficiency of Pearson's $\chi^2$ test with respect to the smooth goodness-of-fit tests. Pearson's $\chi^2$ test for a simple hypothesis is in fact the quadratic score statistic for a family of alternatives quite similar to the Neyman alternatives (II. 2. 1). We suppose the test to be based on $m$ intervals which partition the range of $X$ into cells of probability $1/m$. Let

$I_{m,j}(y)$ denote the indicator function of the interval $((j-1)/m, j/m)$ for $j = 1, \ldots, m-1$, that is

$$I_{m,j}(y) = \begin{cases} 1 & \text{if } (j-1)/m < y < j/m \\ 0 & \text{otherwise} \end{cases}$$

We consider the alternatives, indexed by the $(m-1)$-dimensional parameter $\omega = (\omega_1, \ldots, \omega_{m-1})'$, for the null density $f(x)$,

$$g(x|\omega) = f(x)\exp\left\{\sum_{j=1}^{m-1} \omega_j I_{m,j}(F(x)) - K(\omega)\right\}$$

where $F(x)$ is the cumulative distribution function under the null hypothesis and $K(\omega)$ is the normalizing constant. For a sample of size $n$, let $n_j$ denote the number of observations for which $(j-1)/m < F(x) < j/m$, for $j = 1, \ldots, m$, i.e., the number in the
jth cell. Then it is easy to show that, for testing \( H_0: \omega = 0 \),

\[
U'_\omega = [n_1-n/m, \ldots, n_{m-1}-n/m]
\]

and

\[
i_{\omega \omega} = m^{-2} \begin{bmatrix}
m-1 & -1 & \ldots & -1 \\
-1 & m-1 & \ldots & -1 \\
\vdots & \vdots & & \vdots \\
-1 & -1 & \ldots & m-1
\end{bmatrix}
\]

Thus

\[
i_{\omega \omega}^{-1} = m \begin{bmatrix}
2 & 1 & \ldots & 1 \\
1 & 2 & \ldots & 1 \\
\vdots & \vdots & & \vdots \\
1 & 1 & \ldots & 2
\end{bmatrix}
\]

and

\[
nU'_\omega i_{\omega \omega}^{-1} U'_\omega = \sum_{j=1}^{m} \frac{(n_j-n/m)^2}{n/m}
\]

which is, of course, Pearson's \( \chi^2 \) statistic.

Now we consider, as in Section 2, parametric alternatives to \( f(x) \) indexed by a parameter \( \beta \). To calculate powers and efficiencies of the Pearson test with respect to \( \beta \) alternatives, we must find \( i_{\omega \beta} \). But since \( U'_\omega (\omega=0, \beta=0) = I \left[ F(x | \beta=0) \right] - m^{-1} \), it follows that
for $j = 1, \ldots, m-1$. Note that typically $F^{-1}(0 | 0)$ is either 0 or $-\infty$. For the calculation of multiple correlations, we find from (7.1) and (7.2) that

$$(7.3) \quad i_{\beta} \omega_{\omega} \omega_{\omega} \omega_{\beta} = m \left\{ \sum_{j=1}^{m-1} i_{\omega}^{2} \beta + \left( \sum_{j=1}^{m-1} i_{\omega} \beta \right)^{2} \right\}$$

and

$$\sum_{j=1}^{m-1} i_{\omega} \beta = \int_{0}^{F^{-1}(0 | 0)} F^{-1}((m-1)/m | 0) \left[ \partial f(x | \beta) / \partial \beta \right]_{\beta=0} dx.$$ 

In some cases a closed expression can be found for the integral in (7.2), but numerical integration may be required. For example, for skewness or kurtosis departures from normality, it follows from

$$(3.1)$$

that

$$[\partial h(x | \beta, 3) / \partial \beta]_{\beta=0} = \frac{1}{6} H_{3}(x) \phi(x),$$

$$[\partial h(x | 0, \beta, 2) / \partial \beta]_{\beta=0} = \frac{1}{24} H_{4}(x) \phi(x).$$
Then, since

\begin{align*}
(7.4) \quad \int_{-\infty}^{a} \frac{1}{6} H_3(x) \phi(x) dx &= \frac{1-a^2}{6} \phi(a) \\

\int_{-\infty}^{a} \frac{1}{24} H_4(x) \phi(x) dx &= \frac{3a-a^2}{24} \phi(a),
\end{align*}

the covariances $i_j$ for $l = 1, 2$ given by (7.2) may be easily calculated. With these one can then calculate $R^2_{\omega_1 \cdots \omega_{m-1}, \beta_l}$ using (7.3), and then $e(\chi^2_{m-1}, W_u; \alpha)$ and $e(\chi^2_{m-1}, \psi_k; \alpha)$ using (6.2) and (6.7). These results, for $m = 3, 6, 11,$ and 15 cells, for $k = 1, \ldots, 4,$ and for $\alpha = 0.10$ are summarized in Table 12.

The relative efficiencies of the $\chi^2_{m-1}$ and $\psi_k^2$ tests may be interpreted as the ratio of the $\psi_k^2$ test sample size to the $\chi^2_{m-1}$ test sample size necessary to insure that the asymptotic power functions of the tests at $\alpha = 0.10$ have equal slope as functions of $\beta_1^2$ or $(\beta_2 - 3)^2$. Notice that for $k = 1$ and kurtosis departures, the relative efficiency is undefined since $\psi_1^2$ has asymptotically no local power against $\beta_2$.

For Weibull and Gamma departures from the exponential distribution we have

\[
[\partial f(x|\beta)/\partial \beta]_{\beta=0} = e^{-x}[1+(1-x)\ln x] \\
[\partial f(x|\beta)/\partial \beta]_{\beta=0} = e^{-x}[\gamma + \ln x],
\]
Table 12. Efficiencies of $\chi^2$ tests for normality: simple hypothesis.

<table>
<thead>
<tr>
<th>m-1</th>
<th>$R^2_{\omega_1 \ldots \omega_{m-1}, \beta_1}$</th>
<th>$R^2_{\omega_1 \ldots \omega_{m-1}, \beta_2}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>a. Multiple correlations</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.088</td>
<td>0.146</td>
</tr>
<tr>
<td>5</td>
<td>0.179</td>
<td>0.223</td>
</tr>
<tr>
<td>10</td>
<td>0.337</td>
<td>0.233</td>
</tr>
<tr>
<td>14</td>
<td>0.424</td>
<td>0.249</td>
</tr>
<tr>
<td>m-1</td>
<td>Skewness ($I = 1$)</td>
<td>Kurtosis ($I = 2$)</td>
</tr>
<tr>
<td>b. $e(\chi^2_{m-1, W_u}, 10)$ for $W_u$ based on $U$ and $\beta_f$ departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.060</td>
<td>0.099</td>
</tr>
<tr>
<td>5</td>
<td>0.072</td>
<td>0.089</td>
</tr>
<tr>
<td>10</td>
<td>0.091</td>
<td>0.063</td>
</tr>
<tr>
<td>14</td>
<td>0.095</td>
<td>0.056</td>
</tr>
<tr>
<td>m-1</td>
<td>k</td>
<td></td>
</tr>
<tr>
<td>c. $e(\chi^2_{m-1, \psi^2_k}, 10)$ for skewness departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>1.500</td>
<td>2.222</td>
</tr>
<tr>
<td>5</td>
<td>1.800</td>
<td>2.667</td>
</tr>
<tr>
<td>10</td>
<td>2.275</td>
<td>3.370</td>
</tr>
<tr>
<td>14</td>
<td>2.375</td>
<td>3.519</td>
</tr>
<tr>
<td>d. $e(\chi^2_{m-1, \psi^2_k}, 10)$ for kurtosis departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>-</td>
<td>0.832</td>
</tr>
<tr>
<td>5</td>
<td>-</td>
<td>0.748</td>
</tr>
<tr>
<td>10</td>
<td>-</td>
<td>0.529</td>
</tr>
<tr>
<td>14</td>
<td>-</td>
<td>0.471</td>
</tr>
</tbody>
</table>
respectively, where $\gamma$ is Euler's constant. The covariances (7.2) must be evaluated by numerical integration, but after that the efficiencies are calculated as before; see Table 13.

The relative efficiencies $e(\chi^2_{m-1}, \psi^2_k; 10)$ listed in Tables 12 and 13 vary over a wide range, and this suggests that consideration of the efficiencies relative to $W_u$ based on the parametric score $U_\beta$ may be more informative. So for example, while $e(\chi^2_{2}, \psi^2_{1}; 10) = 5.133$ for a Weibull departure from the exponential distribution implies that $\psi^2_1$ requires more than five times as many observations as $\chi^2_2$ to insure comparable local asymptotic power, it is perhaps more instructive to note that neither test is highly efficient relative to the quadratic score statistic test based on the Weibull score. From Tables 13b and 10c the efficiencies of $\chi^2_2$ and $\psi^2_1$ relative to $W_u$ are seen to be 0.154 and 0.030, respectively.

Unfortunately the straightforward analysis described above does not carry over to the more practical case of composite goodness-of-fit hypotheses. The most widely used procedure consists of calculating Pearson's $\chi^2$ statistic with the nuisance parameter, say $\lambda \in \mathbb{R}^s$, replaced by an estimate, often the maximum likelihood estimator $\hat{\lambda}_0$. The resulting "Chernoff-Lehmann" $\chi^2_{CL}(\hat{\lambda}_0)$, if based on $m$ cells, is taken to have a $\chi^2_{m-s-1}$ distribution, although Chernoff and Lehmann (1954) showed that $\chi^2_{CL}(\hat{\lambda}_0)$ is distributed as
Table 13. Efficiencies of $\chi^2$ tests for the exponential distribution: simple hypothesis.

<table>
<thead>
<tr>
<th>m-1</th>
<th>Weibull</th>
<th>Gamma</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>a. Multiple correlations $R^2_{\omega_1 \ldots \omega_{m-1}, \beta}$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.227</td>
<td>0.729</td>
</tr>
<tr>
<td>5</td>
<td>0.514</td>
<td>0.873</td>
</tr>
<tr>
<td>10</td>
<td>0.691</td>
<td>0.934</td>
</tr>
<tr>
<td>14</td>
<td>0.758</td>
<td>0.952</td>
</tr>
<tr>
<td>b. $e(\chi^2_{m-1}, W_u; .10)$ for $W_u$ based on $U_\beta$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.154</td>
<td>0.495</td>
</tr>
<tr>
<td>5</td>
<td>0.206</td>
<td>0.350</td>
</tr>
<tr>
<td>10</td>
<td>0.188</td>
<td>0.253</td>
</tr>
<tr>
<td>14</td>
<td>0.170</td>
<td>0.213</td>
</tr>
<tr>
<td>c. $e(\chi^2_{m-1}, \psi_k^2; .10)$ for Weibull departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>5.133</td>
<td>0.323</td>
</tr>
<tr>
<td>5</td>
<td>6.867</td>
<td>0.432</td>
</tr>
<tr>
<td>10</td>
<td>6.267</td>
<td>0.394</td>
</tr>
<tr>
<td>14</td>
<td>5.667</td>
<td>0.356</td>
</tr>
<tr>
<td>d. $e(\chi^2_{m-1}, \psi_k^2; .10)$ for gamma departure</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.565</td>
<td>0.795</td>
</tr>
<tr>
<td>5</td>
<td>0.400</td>
<td>0.562</td>
</tr>
<tr>
<td>10</td>
<td>0.289</td>
<td>0.406</td>
</tr>
<tr>
<td>14</td>
<td>0.243</td>
<td>0.342</td>
</tr>
</tbody>
</table>
\[
\sum_{j=1}^{m-s-1} Z_j^2 + \sum_{j=m-s}^{m-1} \alpha_j Z_j^2
\]

where \( Z_1, \ldots, Z_{m-1} \) are independently distributed as \( N(0,1) \), and \( 0 \leq \alpha_j \leq 1 \) for \( j = m-s, \ldots, m-1 \). See also Watson (1959). In terms of the notation of this thesis,

\[
\chi^2_{CL}(\hat{\lambda}_0) = U_i^\omega (\hat{\lambda}_0) i_{\omega \omega}^{-1} U_{\omega} (\hat{\lambda}_0).
\]

Thus the "wrong" covariance matrix has been used, and the statistic is not asymptotically distributed as \( \chi^2 \). The correct quadratic score statistic

\[
\chi^2_{K}(\hat{\lambda}_0) = U_i^\omega (\hat{\lambda}_0) i_{\omega \omega}^{-1} \lambda (\hat{\lambda}_0) U_{\omega} (\hat{\lambda}_0)
\]

is attributed by Moore and Spruill (1975) to the unpublished 1971 thesis of C. Khambhampati (K. C. Rao); see also Rao and Robson (1974).

From the results of Section II.1, this statistic will have the asymptotic \( \chi^2_{m-1} \) distribution, however it is no longer a simple sum of squares.

The comparisons of Pearson's \( \chi^2_{m-1} \) and \( \psi^2_k \) for simple hypotheses can easily be generalized, by using partial multiple correlation coefficients, to handle \( \chi^2_{K}(\hat{\lambda}_0) \) and \( \psi^2_k(\hat{\lambda}_0) \). Although it would be of interest to compare \( \psi^2_k(\hat{\lambda}_0) \) with the widely used \( \chi^2_{CL}(\hat{\lambda}_0) \), this is not possible by the means presented in this paper.
Nevertheless it is of value to compare \( \psi_k^2(\lambda_0) \) with the statistic that should be used, in order to see how well \( \psi_k^2(\lambda_0) \) performs. It should be noted that simulation results of Rao and Robson (1974) and Kang (1977) show that for testing normality, \( \chi_k^2(\lambda_0) \) has consistently greater power than \( \chi_{CL}^2(\lambda_0) \) against a wide range of alternatives, and Spruill (1976) showed that the approximate Bahadur efficiency of \( \chi_k^2(\lambda_0) \) is not less than that of \( \chi_{CL}^2(\lambda_0) \).

The calculations proceed as usual. For example, for testing normality, for the density (5.7) the nuisance parameter scores, where \( \lambda' = (\mu, \sigma) \), are

\[
U_\mu(0, \lambda) = \frac{(x-\mu)}{\sigma}^2 \sigma^{-1} H_1[(x-\mu)/\sigma] \\
U_\sigma(0, \lambda) = \frac{(x-\mu)}{\sigma}^3 \sigma^{-1} = \sigma^{-1} H_2[(x-\mu)/\sigma]
\]

where \( H_1(z) = z \) and \( H_2(z) = z^2 - 1 \) are the first two Hermite polynomials. Also

\[
U_{\beta_1}(0, \lambda) = \frac{H_3[(x-\mu)/\sigma]}{6} \\
U_{\beta_2}(0, \lambda) = \frac{H_4[(x-\mu)/\sigma]}{24}
\]

and, since Hermite polynomials are uncorrelated, it follows that

\[
\begin{bmatrix}
i_{\beta\beta} & i_{\beta\lambda} \\
i_{\lambda\beta} & i_{\lambda\lambda} \\
\end{bmatrix} = \text{diag}(1/6, 1/24, 1/\sigma^2, 2/\sigma^2).
\]
Thus

\[ i_{\beta \beta} | \lambda = i_{\beta \beta} = \text{diag}(1/6, 1/24) \]
\[ i_{\omega \beta} | \lambda = i_{\omega \beta} \]

Also, (7.2) generalizes readily to

\[ i_{\omega \beta} (\lambda) = \int F^{-1}(j/m \mid 0, \lambda) U_{\beta I} (0, \lambda) f(x \mid 0, \lambda) dx \]
\[ F^{-1}[(j-1)/m \mid 0, \lambda] \]

and

\[ i_{\omega \lambda} (\lambda) = \int F^{-1}(j/m \mid 0, \lambda) U_{\lambda I} (0, \lambda) f(x \mid 0, \lambda) dx \]
\[ F^{-1}[(j-1)/m \mid 0, \lambda] \]

For the normal example, it follows easily that \( i_{\omega \beta} \) is the same as for the simple hypothesis (i.e. is free of \( \lambda \)) and the matrix \( i_{\omega \lambda} \) may be calculated directly since

\[ \int_{-\infty}^{a} \sigma^{-1} H_1(x) \phi(x) dx = -\sigma^{-1} \phi(a) \]
\[ \int_{-\infty}^{a} \sigma^{-1} H_2(x) \phi(x) dx = -a \sigma^{-1} \phi(a). \]

As usual, \( i_{\omega \omega} \) does not depend on \( \lambda \). So \( i_{\omega \omega} | \lambda \) can be calculated, and then
These squared partial multiple correlation coefficients, along with several efficiencies, are presented in Table 14. The efficiencies of \( \chi_k^2(\lambda_0) \) relative to \( \psi_k^2(\lambda_0) \) are uniformly rather low for \( k \leq 4 \) and are quite stable in comparison to the entries of Table 12. Notice that for a kurtosis alternative the efficiency with respect to \( \psi_1^2(\lambda_0) \) is not defined, that statistic having, asymptotically, no local power. Since the entries increase in \( k \), the low order smooth tests are recommended.

For Weibull and gamma departures from the exponential distribution, the calculations are somewhat simplified by the fact that \( i_{\omega \beta} \) is obtained by multiplying the matrix obtained for the simple hypothesis by \( \lambda^{-1} \), where \( \lambda \) as usual denotes the nuisance scale parameter. Moreover, since \( U_\lambda(\lambda) = \lambda^{-1}[(x/\lambda)-1] \) is the same for both the Weibull and gamma cases, and since covariances are calculated under the null exponential distribution, it follows that

\[
R^2_{\omega_1 \ldots \omega_{m-1}, \beta_1 | \lambda} = 6 \beta_1 \omega \omega | \lambda \omega | \beta_1 \]

\[
R^2_{\omega_1 \ldots \omega_{m-1}, \beta_2 | \lambda} = 24 \beta_2 \omega \omega | \lambda \omega | \beta_1 \]

\[
\chi_k^2(\lambda_0) \quad \text{relative to} \quad \psi_k^2(\lambda_0)
\]

\[
\text{i}_{\omega \beta} = \int_{F^{-1}[(j-1)/m|0, \lambda]}^{F^{-1}(j/m|0, \lambda)} \lambda^{-1}[(x/\lambda)-1] \exp(-x/\lambda) \, dx
\]

\[
= \lambda^{-1} \left\{ \left( \frac{m-j}{m} \right) \ln\left( \frac{m-j}{m} \right) - \left( \frac{m-j-1}{m} \right) \ln\left( \frac{m-j-1}{m} \right) \right\}
\]
Table 14. Efficiencies of $\chi^2$ tests for normality: composite hypothesis.

| m-1 | $R^2_{\omega_1 \ldots \omega_{m-1}, \beta_1 | \lambda}$ | $R^2_{\omega_1 \ldots \omega_{m-1}, \beta_2 | \lambda}$ |
|------|-------------------------------------------------|-------------------------------------------------|
|      |                                                 |                                                 |
| a. Multiple correlations ($\lambda^t = (\mu, \sigma)$) |                                                 |                                                 |
| 2    | 0.424                                          | 0.187                                          |
| 5    | 0.643                                          | 0.471                                          |
| 10   | 0.786                                          | 0.654                                          |
| 14   | 0.840                                          | 0.726                                          |
| b. $e(\chi^2_{K \lambda_0}, W_u (\lambda_0); \cdot 10)$ for $W_u (\lambda_0)$ based on $U \beta_l (\lambda_0)$ and $\beta_l$ departure |                                                 |                                                 |
| 2    | 0.288                                          | 0.127                                          |
| 5    | 0.258                                          | 0.189                                          |
| 10   | 0.213                                          | 0.177                                          |
| 14   | 0.188                                          | 0.163                                          |
| c. $e(\chi^2_{K \lambda_0}, \psi^2_{k \lambda_0}; \cdot 10)$ for skewness departure |                                                 |                                                 |
| 2    | 0.326                                          | 0.481                                          | 0.535                                          | 0.633 |
| 5    | 0.292                                          | 0.431                                          | 0.480                                          | 0.567 |
| 10   | 0.241                                          | 0.356                                          | 0.396                                          | 0.468 |
| 14   | 0.213                                          | 0.314                                          | 0.349                                          | 0.413 |
| d. $e(\chi^2_{K \lambda_0}, \psi^2_{k \lambda_0}; \cdot 10)$ for kurtosis departure |                                                 |                                                 |
| 2    | -                                              | 0.256                                          | 0.321                                          | 0.322 |
| 5    | -                                              | 0.380                                          | 0.477                                          | 0.478 |
| 10   | -                                              | 0.356                                          | 0.447                                          | 0.448 |
| 14   | -                                              | 0.328                                          | 0.412                                          | 0.413 |
applies in both cases. The other matrices needed have been calculated in Sections 3 and 4. The partial multiple correlations and efficiencies calculated from these are presented in Table 15. As for the normal case, \( \bar{\chi}_K^2(\lambda_0) \) uniformly dominates \( \bar{\chi}_K^2(\lambda_0) \) in terms of relative efficiency, and low values of \( k \) are preferred.
Table 15. Efficiencies of $\chi^2$ tests for the exponential distribution: composite hypothesis.

<table>
<thead>
<tr>
<th>m-1</th>
<th>Weibull</th>
<th>Gamma</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>a. Multiple correlations $R^2_{\omega_1 \ldots \omega_m-1, \beta</td>
<td>\lambda}$ ($\lambda$ = scale parameter)</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.580</td>
<td>0.454</td>
</tr>
<tr>
<td>5</td>
<td>0.811</td>
<td>0.718</td>
</tr>
<tr>
<td>10</td>
<td>0.906</td>
<td>0.846</td>
</tr>
<tr>
<td>14</td>
<td>0.937</td>
<td>0.887</td>
</tr>
</tbody>
</table>

b. $e(\chi^2_{\lambda_0; \beta; \lambda_0; \lambda_0})$ for $W_{\beta}(\lambda_0)$ based on $U_{\beta}(\lambda_0)$

<table>
<thead>
<tr>
<th>m-1</th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>0.394</td>
<td>0.308</td>
</tr>
<tr>
<td>5</td>
<td>0.325</td>
<td>0.288</td>
</tr>
<tr>
<td>10</td>
<td>0.246</td>
<td>0.230</td>
</tr>
<tr>
<td>14</td>
<td>0.210</td>
<td>0.199</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$m$-1</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>c. $e(\chi^2_{\lambda_0; \beta; \lambda_0; \lambda_0})$ for Weibull departures</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>0.450</td>
<td>0.632</td>
<td>0.756</td>
<td>0.887</td>
</tr>
<tr>
<td>5</td>
<td>0.371</td>
<td>0.522</td>
<td>0.624</td>
<td>0.732</td>
</tr>
<tr>
<td>10</td>
<td>0.281</td>
<td>0.395</td>
<td>0.472</td>
<td>0.554</td>
</tr>
<tr>
<td>14</td>
<td>0.240</td>
<td>0.337</td>
<td>0.403</td>
<td>0.473</td>
</tr>
</tbody>
</table>

d. $e(\chi^2_{\lambda_0; \beta; \lambda_0; \lambda_0})$ for gamma departures

<table>
<thead>
<tr>
<th>m-1</th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>0.444</td>
<td>0.540</td>
<td>0.627</td>
<td>0.718</td>
</tr>
<tr>
<td>5</td>
<td>0.415</td>
<td>0.505</td>
<td>0.587</td>
<td>0.671</td>
</tr>
<tr>
<td>10</td>
<td>0.331</td>
<td>0.404</td>
<td>0.468</td>
<td>0.536</td>
</tr>
<tr>
<td>14</td>
<td>0.287</td>
<td>0.349</td>
<td>0.405</td>
<td>0.464</td>
</tr>
</tbody>
</table>
IV. CONCLUSIONS

IV. 1. Discussion of the Smooth Tests

In Section III. 1 two questions were posed regarding the smooth goodness-of-fit tests: how do they perform relative to other tests, and what choice of $k$ is best? The results of the previous chapter provide us with partial answers to both questions. In the comments that follow, attention will be restricted to the more useful case of composite goodness-of-fit hypotheses, rather than simple hypotheses. Moreover, the conclusions strictly apply to tests for the normal and exponential distributions, since these are the only cases investigated in depth in this paper.

How does $\psi^2_k(\lambda_0^\lambda)$ compare with other goodness-of-fit statistics? Tables 4 and 5 show that, for a wide range of alternatives to normality, a smooth test of some order has at least as much power as the Chernoff-Lehmann $\chi^2$ and Kolmogorov-Smirnov tests, and most often the smooth test has substantially greater power. Moreover, Tables 14c, 14d, 15c, and 15d show that the smooth tests of orders one through four are uniformly more efficient locally against the departures considered than $\chi^2_k(\lambda_0^\lambda)$ for a wide range of degrees of freedom. Thus it appears that the smooth tests are perhaps to be preferred to the other omnibus tests.
The situation for comparing the smooth tests to parametric tests with highly focused power is not quite so clear. For simple hypotheses, \( W_u \) represents the locally best test. For composite hypotheses, however, \( W_u(\lambda_0) \) is in general not locally best or even locally best among similar tests; see Cox and Hinkley (1974, p. 146). 

\( W_u(\lambda_0) \) does have the optimality properties described by Wald (1943) and Roussas (1972), as discussed in the Appendix, and is optimal in the class \( C(\alpha) \) of tests described by Neyman (1959). Nevertheless, Tables 10 and 11 show that \( \psi_k^2(\lambda_0) \) is always at least moderately efficient locally relative to the statistic \( W_u(\lambda_0) \) appropriate to the alternative distributions in question. Since the power of a particular \( W_u(\lambda_0) \) may be very poor for some other alternative— for example, the skewness test for normality has, locally, no power against kurtosis departures and vice versa, since \( i \beta_1 \beta_2 = 0 \)—the smooth test is preferred on the basis of giving better protection against a wider range of alternatives.

How should \( k \) be chosen? Neyman (1937) felt that \( k \) need not be taken greater than four in most practical problems, but clearly warned that this was not a mathematical result. The evidence in the present work suggests that a value of two or perhaps even one may serve very adequately. Table 5 strongly supports the use of \( k = 2 \) for testing normality, and this is born out by the efficiencies in Table 10 and 11. Although \( \psi_2^2(\lambda_0) \) is somewhat less efficient
(both locally and at moderate power) than $\psi_1^2(\lambda_0)$ for skewness departures, $\psi_2^2(\lambda_0)$ is preferred since $\psi_1^2(\lambda_0)$ provides no protection against heavy- or light-tailed alternatives. Tables 10 and 11 also support the use of $\psi_1^2(\lambda_0)$ for the exponential distribution. This conclusion would be much stronger, however, if a larger class of alternatives was considered.

IV. 2. Discussion of the $\chi^2$ Tests

The results of Section III. 7 permit us to extend the discussion above to the $\chi^2$ tests of goodness of fit. The tables in that section provide further evidence of a fact already widely known: Pearson's $\chi^2$ (and its proper generalization $\chi_k^2(\lambda_0)$) have relatively little power against any particular alternative. In addition, however, Tables 14b and 15b may aid in the selection of $m$, the number of cells on which the test is based. This problem, which is analogous to the problem of selecting $k$ in the smooth test, has received wide attention. Mann and Wald (1942) based the choice of $m$ on the sample size and size of the test, but Williams (1950) suggested that their solution could be safely halved. For further discussion see Dahiya and Gurland (1973) and Hamdan (1963). The efficiencies in Tables 14 and 15 suggest that the degrees of freedom should be rather smaller: perhaps less than ten as a general rule. Since these efficiencies change rather slowly as the degrees of freedom vary, an
exact determination of the number of cells does not seem necessary.
If the ranges of best efficiencies with respect to different alternatives
roughly coincide, which Tables 14b and 15b show to be the case for
the normal and exponential cases, then the choice of a suitable range
of degrees of freedom on the basis of efficiency is straightforward.
That the selection of the number of cells can possibly depend on the
alternative distribution may, however, make efficiency-based choice
either more or less worthwhile than a choice which ignores the
alternative, depending on the statistician’s level of knowledge of
possible alternatives.
BIBLIOGRAPHY


APPENDIX
APPENDIX

This appendix contains a discussion of the asymptotic distributional and optimality theory of tests of simple and composite hypotheses based on quadratic score statistics, with special reference to smooth goodness-of-fit tests. First the asymptotic equivalence of the quadratic score statistics with likelihood ratio and Wald's statistics is considered. Little mathematical detail is provided at this point. Sets of regularity conditions for simple and composite hypotheses are then listed, expressed in a general terminology, followed by a discussion of the distributional and optimality results they guarantee. Finally, simplifications and restatements of the regularity conditions suitable for smooth goodness-of-fit tests are presented.

Rao (1948) suggested the use of quadratic score statistics for testing simple and composite hypotheses. We consider \( H_0 : \theta = \theta_0 \) in either case, with \( \lambda \) denoting the nuisance parameter for composite \( H_0 \). Bartlett (1953) employed the statistic to obtain confidence regions for \( \theta \) in the presence of an unknown \( \lambda \). Neyman (1959) gave a detailed derivation of the statistic for composite \( H_0 \), as well as an optimality property, to be mentioned below, for the case of real-valued \( \theta \), and Bhat and Nagnur (1965) generalized that work to deal with vector-valued \( \theta \).
A test of \( H_0 : \theta = \theta_0 \) can also be based on the likelihood ratio statistic or on Wald's statistic, the latter, due to Wald (1943), being a quadratic form in \( (\hat{\theta} - \theta_0) \) with a \( \chi^2 \) distribution, where \( \hat{\theta} \) denotes the maximum likelihood estimator of \( \theta \). Let \( W \) and \( W_e \), respectively, denote the two test statistics in the case of a simple hypothesis, and \( W(\hat{\lambda}_0) \) and \( W_e(\hat{\lambda}_0) \) the same for a composite hypothesis; this notation is due to Cox and Hinkley (1974; Section 9.3). Wald (1943; Section 13) demonstrated the asymptotic equivalence of tests based on \( W(\hat{\lambda}_0) \) and \( W_e(\hat{\lambda}_0) \) under regularity conditions. In fact, under regularity conditions the quadratic score statistic, \( W_u \) or \( W_u(\hat{\lambda}_0) \), is asymptotically equivalent to \( W \) and \( W_e \) or \( W(\hat{\lambda}_0) \) and \( W_e(\hat{\lambda}_0) \), as the case may be; see, for example Cox and Hinkley (1974; Section 9.3), Moran (1970), or Javitz (1975; Section 13).

Peers (1971) considered approximations of the power functions of \( W \), \( W_e \), and \( W_u \) and found that none of the statistics dominated either of the others, even when the approximate distributions of the statistics are improved by the inclusion of terms of higher order. The following outline of a proof of the asymptotic equivalence of \( W(\hat{\lambda}_0) \) and \( W_u(\hat{\lambda}_0) \) will ignore questions of regularity conditions. Consider a family of densities \( g(x | \theta, \lambda) \) and the composite hypothesis \( H_0 : \theta = \theta_0 \), where \( \lambda \) is unknown. Let
\[ \ell_1(\theta, \lambda) = \sum_{i=1}^{n} \ln g(X_i | \theta, \lambda). \]

The unrestricted joint maximum likelihood estimator is denoted \( \hat{\theta}, \hat{\lambda} \), while \( \hat{\lambda}_0 \) is the maximum likelihood estimator of \( \lambda \) under the assumption \( H_0 : \theta = \theta_0 \). Then

\[ \begin{align*} \frac{1}{2} W(\hat{\lambda}_0) &= \ell_1(\hat{\theta}, \hat{\lambda}) - \ell_1(\theta_0, \hat{\lambda}_0) \\ &= [\ell_1(\hat{\theta}, \hat{\lambda}) - \ell_1(\theta_0, \lambda)] - [\ell_1(\theta_0, \hat{\lambda}_0) - \ell_1(\theta_0, \lambda)] \end{align*} \]

where \( \lambda \) denotes the true, unknown value of the nuisance parameter.

We suppose \( \theta \in \mathbb{R}^k \) and \( \lambda \in \mathbb{R}^s \) and let

\[ \begin{align*} U_{i}(\theta^*, \lambda^*) &= \left[ \frac{\partial \ell_1(\theta, \lambda)}{\partial \theta} \right]_{\theta^*, \lambda^*} \\ U_{j}(\theta^*, \lambda^*) &= \left[ \frac{\partial \ell_1(\theta, \lambda)}{\partial \lambda} \right]_{\theta^*, \lambda^*} \end{align*} \]

for \( i = 1, \ldots, k \) and \( j = 1, \ldots, s \). The score vectors are then

\[ \begin{align*} U_{\theta}(\theta, \lambda) &= [U_{\theta_1}(\theta, \lambda), \ldots, U_{\theta_k}(\theta, \lambda)]' \\ U_{\lambda}(\theta, \lambda) &= [U_{\lambda_1}(\theta, \lambda), \ldots, U_{\lambda_s}(\theta, \lambda)]' \end{align*} \]

The information matrix, with obvious partitioning, may be written
Approximating each term in brackets in (A.1) to first order we obtain,
suppressing the dependence on \((\theta, \lambda)\)

\[
W(\hat{\lambda}_0) = \left[ U_\theta^t, U_\lambda^t \right] \begin{bmatrix} i_{\theta \theta}(\theta, \lambda) & i_{\theta \lambda}(\theta, \lambda) \\ i_{\lambda \theta}(\theta, \lambda) & i_{\lambda \lambda}(\theta, \lambda) \end{bmatrix}^{-1} \begin{bmatrix} U_\theta^t \\ U_\lambda^t \end{bmatrix} - U_\lambda^t i_{\lambda \lambda}^{-1} U_\lambda^t \]

The first quadratic form in (A.2) may be written in terms of
\(T[U_\theta^t, U_\lambda^t]^t\) rather than \([U_\theta^t, U_\lambda^t]^t\), and an efficacious choice of
\(T\) can lead to a simpler expression for the right-hand side. We take

\[
T = \begin{bmatrix} I_k & -i_{\theta \lambda} \lambda^{-1} \\ 0 & I_s \end{bmatrix}
\]

where \(I_k\) denotes the \(k \times k\) identity matrix. Let

\[
\begin{bmatrix} U_\theta^t | \lambda \\ U_\lambda \end{bmatrix} = T \begin{bmatrix} U_\theta \\ U_\lambda \end{bmatrix}
\]

so that \(U_\theta^t | \lambda = U_\theta - i_{\theta \lambda} \lambda^{-1} U_\lambda\) and

\[
\text{Cov}_{\theta_0, \lambda} \begin{bmatrix} U_\theta^t | \lambda \\ U_\lambda \end{bmatrix} = \begin{bmatrix} i_{\theta \theta} & 0 \\ 0 & i_{\lambda \lambda} \end{bmatrix}
\]
where

\begin{equation}
L_0(X) = \theta(X)
\end{equation}

Substituting into (A. 2) we then find that

\begin{equation}
W(X) = U_\theta(X)
\end{equation}

which is just the desired approximate equivalence, when \( \lambda \) on the right-hand side is replaced by \( \hat{\lambda}_0 \).

By considering the residuals, \( U_\theta(X) \), from the regression of \( U_\theta(X) \) on \( U_\lambda(X) \), we use only that part of the \( \theta \)-scores which are orthogonal to the \( \lambda \)-scores. Another way of viewing the test is as an approximately similar test. This follows from the asymptotic normality of the efficient score vectors, from which \( [U_\theta(X), U_\lambda(X)]' \) is approximately sufficient for \( (\theta, \lambda) \), and \( U_\lambda(X) \) is approximately a complete sufficient statistic for \( \lambda \) under \( H_0 \); see, for example, Cox and Hinkley (1974; Section 9.2v). Thus the test for \( H_0: \theta = \theta_0 \) should be based on the conditional distribution of \( U_\theta(X) \) given \( U_\lambda(X) \), which is approximately

\begin{equation}
N_k(i_\theta(X), i_\lambda(X) U_\lambda(X), i_\theta(X), i_\lambda(X))^{-1}.
\end{equation}

The removal of the unknown true value of \( \lambda \) from the right-hand side of (A. 5) is a crucial step in obtaining a usable statistic. To eliminate the dependence of the quadratic score statistic on \( \lambda \), the
unknown parameter value is replaced by an estimate \( \hat{\lambda}_0 \) which is guaranteed to be "close" to the true value. Then, under regularity conditions, the statistic evaluated at \( (\theta_0, \hat{\lambda}_0) \) is asymptotically equivalent to the same evaluated at \( (\theta_0, \lambda) \) as in (A.2), thus providing a usable test statistic. Neyman (1959) showed that weak root-n consistency of the estimator provides such a result. Consider a sequence \( \{\hat{\lambda}_j(n)\} \) of estimators for the jth component of \( \lambda \).

\( \{\hat{\lambda}_j(n)\} \) is said to be root-n consistent if, for all \( \theta \) and \( \lambda \),

\[
\lim_{n \to \infty} \frac{1}{\sqrt{n}} |\hat{\lambda}_j(n) - \lambda_j| = 0
\]

remains bounded in probability as \( n \to \infty \), and is said to be locally root-n consistent if there exists a nonzero \( A_j \in \mathbb{R}^k \) such that, for all \( \theta \) and \( \lambda \),

\[
\lim_{n \to \infty} \frac{1}{\sqrt{n}} |\hat{\lambda}_j(n) - \lambda_j - A_j(\theta - \theta_0)| = 0
\]

remains bounded in probability as \( n \to \infty \). Finally if \( \{\hat{\lambda}_j(n)\} \) is a sequence of componentwise (locally) root-n consistent estimators, and if for every \( a \in \mathbb{R}^s \) such that \( a'a > 0 \), the assumption that \( \theta = \theta_0 \) implies that \( \lim_{n \to \infty} a'(\hat{\lambda}_j(n) - \lambda) \) does not tend in probability to zero, then \( \{\hat{\lambda}_j(n)\} \) is said to be weakly root-n consistent. Notice that a sufficient condition for weak root-n consistency is that the joint limiting distribution of \( n^{1/2}(\hat{\lambda}_j(n) - \lambda) \) be nondegenerate, which is true of maximum likelihood estimators under standard regularity conditions.

Neyman (1959; Theorem 1) and Bhat and Nagnur (1965; Equation (2.9)) show that

\[
(A.6) \quad i^{-1/2} \left( \theta_0, \hat{\lambda}_j(n) \right) U_\theta | \hat{\lambda}_j(n) - \lambda_j | \left( \theta_0, \lambda \right) \rightarrow 0
\]
if \( \{X(n)_0\} \) is a weakly root-n consistent estimator, under the assumption that
\[
\left( \begin{array}{c}
-1/2 \\
0
\end{array} \right) \lambda (\theta_0, \lambda) \mathcal{U}_\theta \lambda (\theta_0, \lambda)
\] is a normed Cramer function.

This argument is essentially reproduced by Javitz (1975), and the following discussion of conditions under which quadratic score statistics have asymptotic \( \chi^2 \) distributions and provide optimal tests is derived from the work of Roussas (1972) and of Javitz.

We now consider sets of regularity conditions under which distributional and optimality results may be obtained, chiefly by means of arguments based on contiguous probability measures. The conditions will be expressed in a general notation, and later will be applied to smooth tests of both simple and composite hypotheses. We begin with the sample space \( (\mathbb{R}, \mathcal{B} (\mathbb{R})) \), where \( \mathcal{B} (\mathcal{A}) \) in general denotes the \( \sigma \)-field of Lebesgue measurable subsets of \( \mathcal{A} \), for a subset of some finite dimensional Euclidean space. On \( (\mathbb{R}, \mathcal{B} (\mathbb{R})) \) is a family \( \{P(\xi); \xi \in \Xi \} \) of probability measures indexed by a vector parameter \( \xi \) ranging over a bounded parameter set \( \Xi \subset \mathbb{R}^k \). Further, we assume that each \( P(\xi) \) is absolutely continuous with respect to Lebesgue measure \( \mu \), and let \( g(x|\xi) = \frac{dP(\xi)}{d\mu} \) for all \( \xi \in \Xi \). For each \( \xi \), we then can define the infinite product probability space \( (\mathbb{R}^\infty, \mathcal{B}^\infty (\mathbb{R}), P^\infty (\xi)) \) corresponding to the infinite sequence \( \{X_1, X_2, \ldots\} \) of independent, identically distributed \( X \)'s, and let \( P^{(n)}(\xi) \) denote the restriction of \( P^\infty (\xi) \) to the sub-\( \sigma \)-field of \( \mathcal{B}^\infty (\mathbb{R}) \) generated by \( \{X_1, \ldots, X_n\} \) for \( n = 1, 2, \ldots \).
We first consider regularity conditions for a simple hypothesis. For notational consistency we let \( \theta = \xi \), \( \Theta = \Xi \). The regularity conditions are listed below.

[S1] The probability measures \( P(\theta) \) are mutually absolutely continuous for \( \theta \in \Theta \).

[S2] For all \( \theta \in \Theta \) and for \( j = 1, \ldots, k \), \( U_{\theta_{j}}(\theta) \) exists and is continuous in \( \theta \).

[S3] For all \( \theta \in \Theta \) and for \( j = 1, \ldots, k \), \( \mathbb{E}[U_{\theta_{j}}^{2}(\theta) \mid \theta] < \infty \).

[S4] For all \( \theta \in \Theta \) and for \( j = 1, \ldots, k \) there exist a neighborhood \( \mathcal{N}_{j}(\theta) \) containing \( \theta \) and a function \( H_{j}(x \mid \theta) \) such that for all \( \theta^{*} \in \mathcal{N}_{j}(\theta) \)

\[
|U_{\theta_{j}}(\theta^{*}) - U_{\theta_{j}}(\theta)| \leq H_{j}(x \mid \theta) \quad \text{a.e.} \quad P(\theta)
\]

and such that \( \mathbb{E}[H_{j}^{2}(x \mid \theta) \mid \theta] < \infty \).

[S5] \( U_{\theta}(\theta) \) is \( \overline{B}(\mathbb{R}) \times \overline{B}(\Theta) \)-measurable.

[S6] \( i_{\theta}(\theta) \) is positive definite for all \( \theta \in \Theta \).

[S7] For each fixed \( \theta_{0} \in \Theta \), \( [g(x \mid \theta^{*}) / g(x \mid \theta)] \), considered as a function of \( x \) and \( \theta^{*} \), is \( \overline{B}(\mathbb{R}) \times \overline{B}(\Theta) \)-measurable.

Conditions [S5]-[S7] are simply restatements of (A2')(ii)-(A2')(iv) in Roussas (1972; page 46). Also, [S1] implies Roussas' (A1').

Finally, from Lind and Roussas (1972; Theorem 2.2), it follows that [S2]-[S4] imply Roussas' (A2')(i). Thus [S1]-[S7] give us Roussas'
(A1') and (A2') and therefore by his Theorems 4.2 and 4.6 (page 54) we can conclude that

\[ \mathcal{L} \left[ n^{-1/2} U_{\theta}(\theta) \mid P^{(n)}(\theta) \right] \rightarrow N_k(0, i_{\theta \theta}(\theta)) \]

for all \( \theta \in \Theta \), and for \( \theta^{(n)} = \theta + n^{-1/2} h \) where \( h \in \mathbb{R}^k \),

\[ \mathcal{L} \left[ n^{-1/2} U_{\theta}(\theta) \mid P^{(n)}(\theta^{(n)}) \right] \rightarrow N_k(i_{\theta \theta}(\theta)h, i_{\theta \theta}(\theta)) \]

and therefore

\[ \mathcal{L} \left[ W_u \mid P^{(n)}(\theta) \right] \rightarrow \chi^2_k \]

\[ \mathcal{L} \left[ W_u \mid P^{(n)}(\theta^{(n)}) \right] \rightarrow \chi^2_k, \delta(\theta) \]

where \( \delta(\theta) = h' i_{\theta \theta}(\theta)h \). In addition, under (A1') and (A2') of Roussas, three optimality properties of the test based on \( W_u \) are obtained. These will be discussed in detail following the presentation of regularity conditions for composite hypotheses. At the end of this appendix it will be seen that [S1]-[S7] are satisfied by the smooth goodness-of-fit test for any simple hypothesis specifying a continuous distribution.

We now turn our attention to composite hypotheses. Let \( \theta \in \Theta \) be as before and take \( \lambda \in \Lambda \) to be the nuisance parameter, where \( \Lambda \subseteq \mathbb{R}^s \). Now \( \xi = (\theta', \lambda)' \) and \( \Xi = \Theta \times \Lambda \). The regularity conditions are now listed.
[C1] The probability measures $P(\theta, \lambda)$ are mutually absolutely continuous for $(\theta', \lambda')' \in \Theta \times \Lambda$.

[C2] The density $g(x|\theta, \lambda)$ is $\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\Theta \times \Lambda)$-measurable.

[C3] For all $(\theta', \lambda')' \in \Theta \times \Lambda$, the first and second partial derivatives of $g(x|\theta, \lambda)$ with respect to all combinations of $\theta_1, \ldots, \theta_k, \lambda_1, \ldots, \lambda_s$, evaluated at any $(\theta', \lambda')'$ exist and are finite, and all the first partial derivatives are $\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\Theta \times \Lambda)$-measurable and continuous in $(\theta', \lambda')$.

[C4] The covariance matrix

$$\text{Cov}\left\{\begin{bmatrix} U_\theta(\theta, \lambda) \\ U_\lambda(\theta, \lambda) \end{bmatrix} \right| \theta, \lambda = \begin{bmatrix} i_\theta(\theta, \lambda) & i_\theta(\theta, \lambda) \\ i_\lambda(\theta, \lambda) & i_\lambda(\theta, \lambda) \end{bmatrix}$$

is finite, positive definite, and continuous in $(\theta', \lambda')'$ for all $(\theta', \lambda')' \in \Theta \times \Lambda$.

[C5] For all $(\theta', \lambda')' \in \Theta \times \Lambda$,

$$\left\{\frac{[\partial g(x|\theta^*, \lambda^*)/\partial \theta^*]}{\partial \theta^*} / g(x|\theta, \lambda)\right\}$$

and

$$\left\{\frac{[\partial g(x|\theta^*, \lambda^*)/\partial \lambda^*]}{\partial \lambda^*} / g(x|\theta, \lambda)\right\}$$

are continuous in $(\theta^*, \lambda^*)'$, for $j = 1, \ldots, k$ and $l = 1, \ldots, s$.

[C6] For every $(\theta', \lambda')' \in \Theta \times \Lambda$ there exist a neighborhood $\mathcal{N}_1(\theta, \lambda)$ containing $(\theta', \lambda')'$ and functions $H_1,j(x|\theta, \lambda)$
and \( H^2,\ell(x|\theta,\lambda) \) such that

\[
|\frac{\partial g(x|\theta^*,\lambda^*)}{\partial \theta^*} / g(x|\theta,\lambda)| \leq \frac{H_1,\ell(x|\theta,\lambda)}{g(x|\theta,\lambda)}
\]

a.e. \( P(\theta,\lambda) \)

and

\[
|\frac{\partial g(x|\theta^*,\lambda^*)}{\partial \lambda^*} / g(x|\theta,\lambda)| \leq \frac{H_2,\ell(x|\theta,\lambda)}{g(x|\theta,\lambda)}
\]

a.e. \( P(\theta,\lambda) \)

for \( j = 1, \ldots, k \) and \( \ell = 1, \ldots, s \), and for \((\theta^*,\lambda^*)' \in \mathcal{N}_1(\theta,\lambda)\) and such that for \( m = 1, 2 \) and \( a = j \) or \( \ell \),

\[
E\{H^2_{m,a}(X|\theta,\lambda)|\theta,\lambda\} < \infty.
\]

[C7] For every \((\theta',\lambda') \in \Theta \times \Lambda\) there exist a neighborhood \( \mathcal{N}_2(\theta,\lambda) \) containing \((\theta',\lambda')\) and functions \( G_1(x|\theta,\lambda) \) and \( G_2(x|\theta,\lambda) \) such that

\[
\int_{\mathbb{R}} G_1(x|\theta,\lambda)d\mu(x) < \infty
\]

and

\[
\int_{\mathbb{R}} G_2(x|\theta,\lambda)g(x|\theta,\lambda)d\mu(x) < \infty
\]

and such that
\[
\left| \frac{\partial g(x|\theta,\lambda)}{\partial \theta^j} \right|_{\theta^*,\lambda^*} \\
\left| \frac{\partial^2 g(x|\theta,\lambda)}{\partial \theta^i \partial \theta^j} \right|_{\theta^*,\lambda^*} \\
\left| \frac{\partial^2 g(x|\theta,\lambda)}{\partial \lambda^i \partial \lambda^j} \right|_{\theta^*,\lambda^*} \right\} \leq G_1(x|\theta,\lambda)
\]

and
\[
\left| \frac{\partial \ln g(x|\theta,\lambda)}{\partial \theta^j} \right|_{\theta^*,\lambda^*} \\
\left| \frac{\partial^2 \ln g(x|\theta,\lambda)}{\partial \theta^i \partial \theta^j} \right|_{\theta^*,\lambda^*} \\
\left| \frac{\partial^2 \ln g(x|\theta,\lambda)}{\partial \lambda^i \partial \lambda^j} \right|_{\theta^*,\lambda^*} \right\} \leq G_2(x|\theta,\lambda)
\]

for all \((\theta^*,\lambda^*) \in \mathcal{N}_2(\theta,\lambda)\) and for \(i, j = 1, \ldots, k\) and \(l, m = 1, \ldots, s\).

[C8] The sequence \(\{\lambda^{(n)}_0\}\) is a system of weakly root-n consistent estimators of \(\lambda\) under \(P^{(n)}(0,\lambda)\) for all \(\lambda \in \Lambda\). Here we are tacitly assuming that the null hypothesis of interest specifies \(\theta = 0\).

It is easy to show that under these assumptions the conditions [A4.1]-[A4.8], [A5.1]-[A5.5], and [AII.1]-[AII-2] of Javitz (1975) are satisfied. Notice that [C8] makes no reference to alternative distributions \(P(\theta,\lambda)\) with \(\theta \neq 0\). Now under [C1]-[C6] we may apply
Javitz' Theorem 4.1 (page 21) to conclude that

\[ \mathcal{L} \left[ n^{-1/2} U_\theta \right|_{\lambda(0, \lambda)} P^{(n)}(\theta), \lambda \right] \rightarrow N_k(i \theta \theta|_{\lambda(0, \lambda)}, i \theta \theta|_{\lambda(0, \lambda)}) \]

under alternatives \( \theta(n) = n^{-1/2} \theta \) for some \( \theta \in \Theta \) and any \( \lambda \in \Lambda \), where \( U_\theta = U_\theta - i \theta \lambda \lambda^\top \lambda \). Moreover, under [C1]-[C8], via Javitz' Lemmas 5.1 and 5.2 (page 28) and Theorem 5.1 (page 29), we can conclude that

\[ U_\theta \right|_{\lambda(0, \lambda)} (\hat{\theta}^{(n)}) - U_\theta \right|_{\lambda(0, \lambda)} \overset{P}{\rightarrow} 0 \]

under the alternatives \( P^{(n)}(\theta(n), \lambda) \). This is the necessary analogue of (A.6). In view of [C4] it follows from the Central Limit Theorem that

\[ \mathcal{L} \left[ n^{-1/2} U_\theta \right|_{\lambda(0, \lambda)} P^{(n)}(0, \lambda) \right] \rightarrow N_k(0, i \theta \theta|_{\lambda} (\lambda)) \]

so we find that

\[ \mathcal{L} \left[ W_u(\hat{\theta}) \right|_{P^{(n)}(0, \lambda)} \right] \rightarrow \chi^2_k \]

\[ \mathcal{L} \left[ W_u(\hat{\lambda}) \right|_{P^{(n)}(\theta(n), \lambda)} \right] \rightarrow \chi^2_k, \delta(\theta|\lambda) \]

where

\[ \delta(\theta|\lambda) = \theta^\top i \theta \theta|_{\lambda(\theta, \lambda)} \theta. \]
In his proof of Theorem 4.1, Javitz (page 91) notes that his
\[ A4.1 \rightarrow A4.8 \] and \[ AII.1 \rightarrow AII.2 \] (and therefore our \[ C1 \rightarrow C6 \]) imply
that \( A1' \) and \( A2' \) of Roussas (1972; page 46) are satisfied. So, as
mentioned above for \[ S1 \rightarrow S7 \], the optimality properties of Roussas'
Theorems 2.1 (page 170), 2.2 (page 171), and 6.1 (page 191) will also
be obtained. For simple hypotheses, these theorems parallel
Theorems I-III in Wald (1943) and for composite hypotheses, they
parallel Wald's Theorems IV-VI. Of course Wald's theorems apply to
\( W_e \) and \( W_e(\hat{\lambda}_0) \), and carry over to \( W_u \) and \( W_u(\hat{\lambda}_0) \) because of
the asymptotic equivalence. The results of Roussas' three theorems
will be listed here.

To describe the optimality results we require some additional
notation, which will be very similar to that of Roussas. In the follow-
ing, \( i_{\xi,\xi}(\xi_0) \) will represent \( i_{\theta,\theta}(\theta_0) \) for simple hypotheses and
\( i_{\theta,\theta}|\lambda(\theta_0,\lambda) \) for composite hypotheses. We define the ellipsoidal
surfaces

\[
E(c) = \{ \xi \in \mathbb{R}^k \mid (\xi - \xi_0)' i_{\xi,\xi}(\xi_0)(\xi - \xi_0) = c \}
\]

for \( 0 < c \), and the function

\[
a(\xi) = \left[ |i_{\xi,\xi}(\xi_0)' (\xi - \xi_0)' i_{\xi,\xi}(\xi_0)(\xi - \xi_0)|^{1/2} \right] / \| i_{\xi,\xi}(\xi_0)(\xi - \xi_0) \|
\]

for \( \xi \in \mathbb{R}^k \setminus \{\xi_0\} \). Further we define a weight function
\[ \xi(c, \xi) = a(\xi)/A(c) \]

where \( A \) is defined by the surface integral

\[ A(c) = \int_{E(c)} a(\xi) dA. \]

Notice that \( \int_{E(c)} \xi(c, \xi) dA = 1 \) for all \( c \in (0, \infty) \). We will deal with alternatives \( \xi^{(n)} = \xi_0 + h n^{-1/2} \) for \( h \in \mathbb{R}^k \), so let

\[ E(n, c) = E(cn^{-1}) = \{ \xi \in \mathbb{R}^k | (\xi - \xi_0)'i\xi_0 (\xi - \xi_0) = cn^{-1} \} \]

and

\[ \zeta_n(c, \xi) = \zeta(cn^{-1}, \xi). \]

In the results that follow we will take \( c \in K \), a compact subset of \( (0, \infty) \), so for sufficiently large \( n \), \( E(n, c) \subset \subset \), for all \( c \in K \).

We restrict our attention to tests of \( H_0 : \xi = \xi_0 \) which depend on the data only through \( n^{-1/2} U_\theta(\xi_0) \), where \( U_\xi(\xi_0) = U_\theta(\theta_0) \) or \( U_\theta|\lambda(\theta_0, \lambda) \) as needed, and let \( \phi[n^{-1/2} U_\xi(\xi_0)] \) denote such a test: \( \phi \) gives the probability of rejecting \( H_0 \) as a function of the data through \( n^{-1/2} U_\xi(\xi_0) \). Let \( I_A(\cdot) \) denote the indicator function of the set \( A \subset \mathbb{B}^k(\mathbb{R}) \), and define

\[ \mathcal{F} = \{ \phi | \phi = I_{C^c} \} \text{ for closed, convex } C \subset \mathbb{B}^k(\mathbb{R}). \]
For the test based on $W_\lambda$ (which denotes $W_0$ or $W_{\lambda}(\lambda)$ as needed)

$$C_{W_\lambda} = \{ z \in \mathbb{R}^k \mid z'\xi_0^{-1}(\xi_0)z \leq \chi^2_k(1-\alpha) \}$$

so, clearly, for $\phi_{W_\lambda}$ defined accordingly, $\phi_{W_\lambda} \in \mathcal{F}_{\lambda}$. We also will restrict our attention to sequences of tests in $\mathcal{F}_{\lambda}$ which are asymptotically of size $\alpha$, i.e., $\{\phi_n\} \subset \mathcal{F}_{\lambda}$ for which

$$E\{\phi_n \mid \xi_0\} = E\{I_{C_n^c \mid \xi_0}\} \to \alpha$$

as $n \to \infty$. Because of the asymptotic $\chi^2$ distribution of $W_\lambda$, $\phi_{W_\lambda}$ clearly satisfies this condition.

Finally, let $\pi_n(\xi, \phi)$ denote the power of the test $\phi$ with sample size $n$, under $\xi \in \Xi$,

$$\pi_n(\xi, \phi) = E\{\phi[n^{-1/2}U_\xi(\xi_0)] \mid \xi\}$$

and for clarity let $\pi_n(\xi, W_\lambda) = \pi_n(\xi, \phi_{W_\lambda})$. Then (A1') and (A2') of Roussas (1972; page 46) imply the following results (pages 170, 171):

[R1] For any sequence of tests $\{\phi_n\} \subset \mathcal{F}_{\lambda}$ asymptotically of size $\alpha$, for an arbitrary compact set $K \subset (0, \infty)$, and for testing $H_0 : \xi = \xi_0$ against $H_1 : \xi \neq \xi_0$, we have
Under the same assumptions as [R1], we have

\[
\lim \inf_n \left\{ \inf_{c \in K} \left[ \int_{E(n, c)} \pi_n (\xi, W_u) \xi_n (c, \xi) \, dA \right. \right.
\]
\[
\left. \left. - \int_{E(n, c)} \pi_n (\xi, \phi_n) \xi_n (c, \xi) \, dA \right] \right\} \geq 0.
\]

[R2] Under the same assumptions as [R1], we have

(a) \[
\lim_{n \to \infty} \left\{ \sup_{c \in K} \left[ \sup_{\xi \in E(n, c)} \pi_n (\xi, W_u) - \inf_{\xi \in E(n, c)} \pi_n (\xi, W_u) \right] \right\} = 0
\]

and for any \( \{\phi_n\} \) as in [R1] for which \( \pi_n (\xi, \phi_n) \) satisfies

(a),

(b) \[
\lim \inf_n \left\{ \inf_{c \in K} \left[ \inf_{\xi \in E(n, c)} \left\{ \pi_n (\xi, W_u) - \pi_n (\xi, \phi_n) \right\} \right] \right\} \geq 0.
\]

These results may be roughly interpreted as follows. [R1] simply states that, approximately, \( W_u \) or \( W_u (\lambda) \) has asymptotically the best average power on the surfaces \( E(n, c) \) of tests in \( \mathcal{F} \), where the average is taken with respect to the weight function \( \xi_n \).

The first part of [R2] implies that, approximately, the power of the test based on \( W_u \) or \( W_u (\lambda) \) is asymptotically constant on the surfaces \( E(n, c) \), and the second part of [R2] implies that, approximately, \( W_u \) or \( W_u (\lambda) \) gives the test which is asymptotically most powerful among tests in \( \mathcal{F} \) with power constant on the surfaces \( E(n, c) \).
The third optimality result requires some additional notation.

We define the class of tests \( \mathcal{F}_0 \subset \mathcal{F} \) by

\[
\mathcal{F}_0 = \{ \phi \mid \phi = 1 \quad \text{for closed, convex } C \in \mathcal{B}_k(\mathbb{R}) \text{ such that } \Pr[C \mid \xi_0] = 1 - \alpha \}.
\]

This permits us to work with the envelope power function \( \pi_n(\xi, \alpha) \) defined by

\[
\pi_n(\xi, \alpha) = \sup_{\phi \in \mathcal{F}_0} \{\pi_n(\xi, \phi)\}.
\]

Using the comments above and Theorem 6.1 of Roussas (1972; page 191), it follows that (A1') and (A2') insure the following result.

\[\text{[R3]}\]

For any sequence of tests \( \{\phi_n\} \in \mathcal{F}_0 \), for an arbitrary compact set \( K \subset (0, \infty) \), and for testing \( H_0 : \xi = \xi_0 \) against \( H_1 : \xi \neq \xi_0 \), we have

\[
\limsup_n \left\{ \sup_{c \in K} \left[ \sup_{\xi \in E(n, c)} \{\pi_n(\xi, \alpha) - \pi_n(\xi, W_u)\} \right] - \sup_{\xi \in E(n, c)} \{\pi_n(\xi, \alpha) - \pi_n(\xi, \phi_n)\} \right\} \leq 0.
\]

Thus the test based on \( W_u \) or \( W_u(\lambda) \) is asymptotically most stringent in the class \( \mathcal{F}_0 \), i.e., if we call the difference between a given test's power at some \( \xi \) and \( \pi_n(\xi, \alpha) \) the shortcoming of...
the test at \( \xi \), then \( W_{\xi} \) minimizes the maximum shortcoming.

To conclude the discussion of optimality properties we note that Neyman (1959) and Bhat and Nagnur (1965) showed that the test based on \( W_{\xi}(\lambda_0) \) is locally asymptotically most powerful or stringent in the class \( C(\alpha) \) of tests; their regularity conditions are of the traditional Cramer type.

To conclude this appendix, we consider the evaluation of \([S1]-[S7]\) and \([C1]-[C8]\) for smooth goodness-of-fit tests. First we consider simple hypotheses. Since the multiplying factor

\[
\exp \left\{ \sum_{i=1}^{k} \theta_i F^i(x) - K(\theta) \right\}
\]

is strictly positive, \([S1]\) is true. Since

\[
K(\theta) = \ln \int_{0}^{1} \exp \left\{ \sum_{i=1}^{k} \theta_i y_0^i \right\} \, dy
\]

we may apply the Dominated Convergence Theorem to show that

\[
\frac{\partial g(x | \theta)}{\partial \theta_j} = F^j(x) - \frac{\partial K(\theta)}{\partial \theta_j}
\]

exists and is continuous in \( \theta \); hence \([S2]\) is true. Also, \([S3]\) is satisfied because of the boundedness of \( F \), and for \([S4]\), simply note that \( \left| U_{\theta_j}(\theta^*) - U_{\theta_j}(\theta) \right| \) is constant in \( x \). \([S6]\) follows from
simple calculations, and [S5] and [S7] may easily be seen to be true. 
Thus the regularity conditions, and therefore the asymptotic distributional and optimality theory, are always obtained for the smooth test of a simple goodness-of-fit hypothesis under smooth alternatives.

Of course the situation is more complicated for composite hypotheses. However substantial simplifications occur under the following conditions on the null family with densities
\[ \frac{dP(0, \lambda)}{d\mu} = f(x|\lambda). \]

\[ [C1'] \] The probability measures \( P(0, \lambda) \) are mutually absolutely continuous for \( \lambda \in \Lambda \).

\[ [C2'] \] \( \frac{\partial f(x|\lambda)}{\partial \lambda_t}, \frac{\partial F(x|\lambda)}{\partial \lambda_t}, \) and \( \frac{\partial^2 F(x|\lambda)}{\partial \lambda_t \partial \lambda_m} \) exist and, evaluated at any \( \lambda \in \Lambda \), are finite, for \( t, m = 1, \ldots, s \).

\[ [C3'] \] \( f(x|\lambda), F(x|\lambda), \frac{\partial f(x|\lambda)}{\partial \lambda_t}, \frac{\partial F(x|\lambda)}{\partial \lambda_t} \) are \( \mathcal{B}(\mathbb{R}) \times \mathcal{B}(\Lambda) \)-measurable and continuous in \( \lambda \), for \( t = 1, \ldots, s \).

\[ [C4'] \] For all \( \lambda \in \Lambda \) there exist a neighborhood \( \mathcal{H}(\lambda) \) containing \( \lambda \) and functions \( H_{1,t}(x|\lambda) \) and \( H_{2,t}(x|\lambda) \) such that
\[ \left| U_{t, \lambda}(x) \right| \leq H_{1,t}(x|\lambda) \quad \text{a.e. } P(0, \lambda) \]
and
\[ \left| \frac{\partial F(x|\lambda)}{\partial \lambda_t} \right|_{\lambda^*} \leq H_{2,t}(x|\lambda) \quad \text{a.e. } P(0, \lambda) \]
for all \( \lambda^* \in \mathcal{H}(\lambda) \), and such that
\[
E\left\{ H_m^2, \lambda | \lambda \right\} < \infty
\]

for \( m = 1, 2 \) and \( t = 1, \ldots, s \).

By reasoning analogous to the verification of [S1] for simple goodness-of-fit hypotheses, we find that [C2'] implies [C1]. Also [C2] follows from [C2']. The first and second partial derivatives of [C3] can all be written in terms of \( F(x|\lambda) \), \( g(x|\theta, \lambda) \), the first and second partial \( \lambda \)-derivatives of \( f \) and \( F \) and the first and second partial \( \theta \)-derivatives of \( K(\theta) \). So [C3] can be shown to be true under [C2'] and [C3']. For [C5], we have

\[
\left\{ \frac{\partial g(x|\theta^*, \lambda^*)}{\partial \theta_j^*} \right\}_{\theta^*_j, \lambda^*}/g(x|\theta, \lambda)
\]

\[
= \frac{f(x|\lambda^*)}{f(x|\lambda)} \exp \left\{ \sum_{i=1}^{k} \left[ \theta_i^* F_i(x|\lambda^*) - \theta_i F_i(x|\lambda) \right] \right\}
\]

and continuity can be obtained using [C3'] and the fact that

\[
K(\theta) = \int_{0}^{1} \exp \left\{ \sum_{i=1}^{k} \theta_i y_i \right\} \, dy.
\]

Similarly
\[
[\partial g(x|\theta^*, \lambda^*)/\partial \lambda^*]_{\theta^*, \lambda^*} / g(x|\theta, \lambda) \\
= [f(x|\lambda^*)/f(x|\lambda)] \exp \left\{ \sum_{i=1}^{k} \left[ \theta_i F_i(x|\lambda^*) - \theta_i F_i(x|\lambda) \right] - [K(\theta^*) - K(\theta)] \right\} \\
\times \left\{ \sum_{i=1}^{k} i \theta_i F_i^{i-1}(x|\lambda^*) \right\}.
\]

From this, [C3'], and the nature of \( K(\theta) \) we see that [C5] is satisfied. Moreover, with [C4'] parts of [C6] and [C7] may be satisfied. Further conditions on the null densities \( f(x|\lambda) \) might be found to bring about additional simplifications.

It should be noted that [C8] does not require \( \{\lambda^{(n)}_0\} \) to be a sequence of maximum likelihood estimators. However, as mentioned above, if \( \hat{\lambda}^{(n)}_0 \) is the maximum likelihood estimator of \( \lambda \) under the null hypothesis, and if \( n^{1/2}(\hat{\lambda}^{(n)}_0 - \lambda) \) is asymptotically normal, which happens under well-known regularity conditions, for example those of the Cramer type, then \( \{\lambda^{(n)}_0\} \) is a system of weakly root-\( n \) consistent estimators.

The null \( \chi^2 \) distribution of \( \psi^2(\lambda_0) \) can also be obtained under relatively weak assumptions. We assume that \( U_\lambda(\lambda) \) is a vector-valued Cramer function as defined by Neyman (1959). If, in addition, there exist functions \( H_\lambda(x|\lambda), H_{\ell, m}(x|\lambda), \) and \( H_{\ell, m, t}(x|\lambda) \) for all \( \lambda \in \Lambda \) and for \( \ell, m, t = 1, \ldots, s \) such that
\[ |\partial F(x | \lambda) / \partial \lambda_f | \leq H_f(x | \lambda) \]
\[ |\partial^2 F(x | \lambda) / \partial \lambda_f \partial \lambda_m | \leq H_f, m(x | \lambda) \]
\[ |\partial^3 F(x | \lambda) / \partial \lambda_f \partial \lambda_m \partial \lambda_t | \leq H_f, m, t(x | \lambda) \]

a.e. \( \mu \) and such that

\[ \mathbb{E}[H_f^3(x | \lambda) | \lambda] < \infty \]
\[ \mathbb{E}[H_f^2(x | \lambda) | \lambda] < \infty \]
\[ \mathbb{E}[H_f, m, t(x | \lambda) | \lambda] < \infty, \]

then \( U_\theta(x | \lambda) \) is also a vector-valued Cramer function, and as Neyman notes (1959; Section 8(i)), \( U_\theta | \lambda \) is therefore also a Cramer function. Finally, if \( \{\lambda^{(n)}_0\} \) is the sequence of maximum likelihood estimators and the null distributions are sufficiently regular so that \( n^{1/2} (\lambda^{(n)}_0 - \lambda) \) is asymptotically normal—see, for example, Cox and Hinkley (1974; Chapter 9)—then by Neyman (1959; Theorem 1) and the multivariate central limit theorem, the asymptotic null \( \chi^2 \) distribution is obtained.