

AN ABSTRACT OF THE THESIS OF

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A microprogramming teaching tool was designed and implemented. This tool was based on the Am 2900 bit-slice microprocessor family. It provides tools for understanding software development for a simple bit-slice microprocessor.

A
Microprogramming Learning
System

by

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A MICROPROGRAMMING LEARNING SYSTEM

CHAPTER I

INTRODUCTION

Microprogramming is taught in senior level computer architecture classes at Oregon State University. In an effort to provide a practical example of microprogramming the design of a microprogramming teaching tool was undertaken.

To be useful in a lab situation, a microprogramming teaching tool must have the following characteristics:

1. Be simple to use.
2. Allow students to write and run their own microprograms.
3. Demonstrate the advantages and disadvantages of microprocessing.
4. Be practical to use to assign lab projects.

The Am 2900 Evaluation and Learning Kit was selected as the basis for the design of the microprogramming teaching tool. It had the following useful characteristics:

1. It was designed to demonstrate microprogramming techniques.
2. It could be used to load and run user microprograms.

¹Donated to OSU by Advanced Micro Devices, Inc.

3. It was simple to modify if necessary.

The Am 2900 kit also had a number of disadvantages as follows:

1. It was tedious to use due to a slow and complicated program loading technique.
2. It was difficult to observe the flow of program execution due to a limited number of output indicator lights.

Thus while the kit was an excellent demonstration tool, it was not a practical lab instrument.

To make the kit useful for lab applications it was necessary to interface it with an external system. The external system would have to be able to simplify the program loading and data output procedures. Most main-frame, personal computers and development systems would be able to satisfy these requirements. The AMC System 29 was selected for the task. It was a microprogramming development system upon which future development in the microprogramming area was planned. It was also a system which would allow the greatest flexibility for expansion of the Am 2900 kit, beyond the modifications done in this project.

At the time of the conception of this project, it was decided to allow users of the combined system the option of using the AM 2900 kit independently or with the System 29.

CHAPTER II

BACKGROUND INFORMATION

Microprogramming

The technique of microprogramming involves using microwords or microinstructions to run various devices within a microprocessor. A microword consists of a number of bits broken down into fields. Each field consists of the control bits required to run each device, an example of which is given in Figure 1. In the example a 010 (binary) in the ALU field would cause the ALU to do a S-R operation.

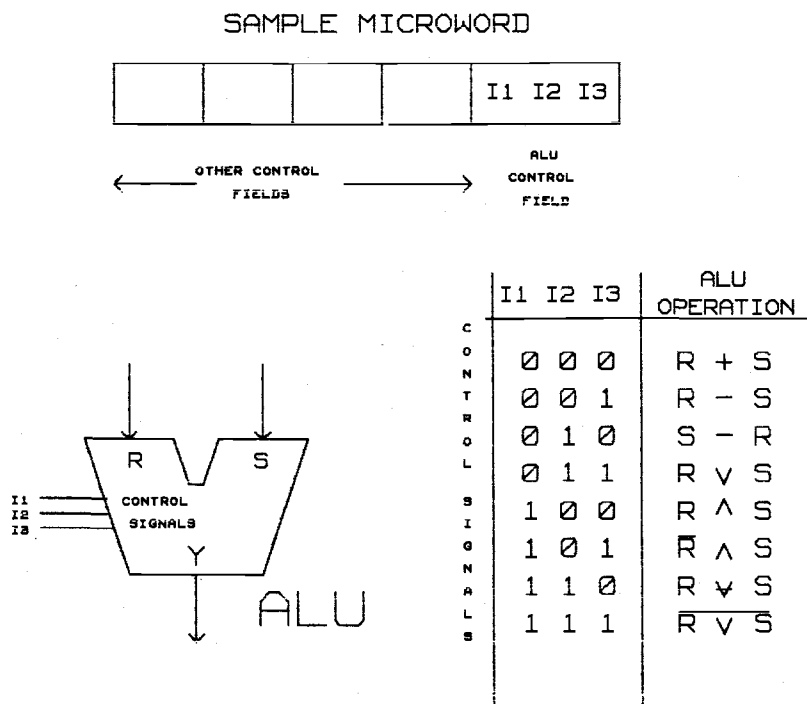


Fig. 1. ALU Control.

A microprocessor with a large number of devices will require more fields and consequently a longer microword than a microprocessor with less devices. One of the fields within a microword is the next address field. This field is used with an address decoder or microsequencer to select the next microword to be executed. Microsequencers allow conditional and unconditional microword branching and subroutine calls. Microwords are stored in memory referred to as the microprogramming memory.

The Am 2900 Evaluation and Learning Kit

The Am 2900 kit is composed of an Am 2901 bit-slice microprocessor, an Am 2909 microprogram sequencer, registers, multiplexers (muxes) and several memories (see Figure 2). Each microprogram word on the kit consists of 32 bits which are broken down into 8 fields (see Figure 3). Sixteen microwords can be loaded and stored in the microprogram memory. These sixteen locations in memory are addressed by a four bit address from the Am 2909 sequencer.

Loading of the sixteen words is done through toggle switches which:

1. Select the address of the memory word to be loaded.
2. Set the data which is to be loaded.
3. Activate the load signal which writes the data into the memory.

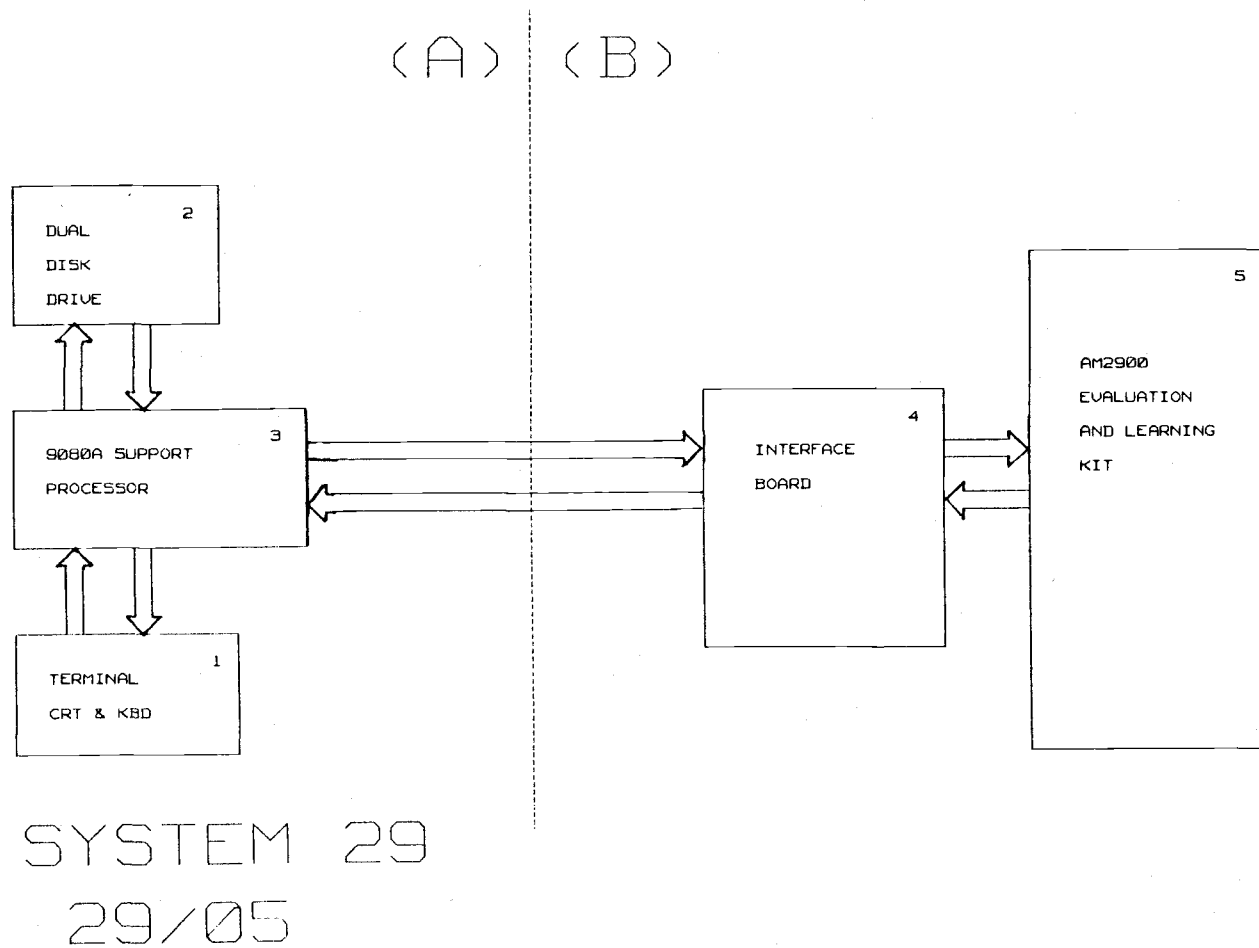


Fig. 2. Block diagram of Am 2900 Evaluation and Learning Kit.

| | | | | | | | | |
|------------------------------------|-------------------|--------------------------|-------------------------|-------------------------|----------------|------|-----|-----|
| RAM & MUX SELECT (FIELD NO.) | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| BIT NUMBER | 31-28 | 27-24 | 23-20 | 19-16 | 15-12 | 11-8 | 7-4 | 3-0 |
| FIELD DEFINITION | BRANCH ADDRESS | NEXT INST. CONTROL | ALU DEST. CONTROL | ALU SOURCE SELECT | ALU CONTROL | A | B | D |

Fig. 3. Am 2900 microprogram word.

Run modes are selected through toggle switches as well. A user may run the kit with the Single Step Switch or an external clock.

Operation of the kit may be observed from four indicator light emitting diodes (LED's). The LED's may be used to read outputs from both the 2901 and the 2909 as well as some of the other registers.

Two other sets of LED's allow the user to examine the microword memory and the pipeline register contents, (see Figure 2).

The pipeline register is a device used to speed up processing time by reducing the amount of time the system has to wait to fetch the next instruction. Microinstructions being executed are in the pipeline register. Thus while all the ALU functions and other micro-operations are being carried out, the next address can be decoded and the new microinstruction can be made ready at the inputs of the pipeline register. Thus when the present microinstruction has been executed, the next microinstruction has already been fetched and can be loaded and executed immediately.

Further details about microprogramming can be obtained from White, Bit-slice Design: Controllers and ALUs, and Sieworek, Bell, and Newell, Computer Structures: Principles and Examples and Mick and Brick Bit-slice Microprocessor Design.

Using the Am 2900 Kit

Once the user has developed a microprogram it can be loaded into memory using the three sets of input switches and a number of control switches (see Figure 2).

The RAM and Mux Select Switches. These three switches allow access to the eight different fields of the microprogram word. These switches are needed because the kit has only four data LED's, four pipeline LED's and four microprogram word LED's. Thus to view all 32 bits of each of the above registers it is necessary to view them four bits at a time. Since only four data switches are supplied it is also necessary to load the microprogram word in fields of four bits at a time. The RAM and Mux Select Switches allow the selection of these fields.

The Memory Address Switches. These four switches are used to address the sixteen microwords in the kit's microprogram memory.

The Memory Data Switches. These four switches² are set to the bit configuration that is to be loaded into the presently addressed microinstructions field³ at the presently addressed memory location⁴.

²The Memory Data Switches are set to opposite polarity due to the fact that the RAM used in the kit inverts data from input to output.

³selected using the RAM and Mux Switches

⁴selected using the Memory Address Switches

The Memory Load Switch. This momentary switch loads data into the microprogram memory.

The Run/ Load Switch. This toggle switch is used to select the mode of the processor. In Load mode, the data and address switches may be used to load (i.e. program) the RAM. In Run mode, the Memory Load Switch is inhibited and programs in memory can be run using the Single Step Clock Switch or the clock pulse input.

The Single Step Clock Switch. This momentary switch is used to apply a debounced clock pulse to all the clocked devices in the kit. This switch is also used to fill the pipeline register with the first microword. This is important because should the user attempt to run a program with random values in the pipeline register it will be impossible to guess which instruction will be fetched next. This switch is inhibited when the Single Step/ Pulse Generator Select Switch is set to Pulse Generator.

The Single Step/ Pulse Generator Select Switch. This toggle switch is used to decide if the kit will be run by the Single Step Clock Switch or an external pulse generator.

Summary. To use the kit the user sets the control toggle switches to Load mode and then stores a program into the 16 word RAM. With the address of the start location stored in the Memory Address Switches, the user

fills the pipeline register with the first microinstruction to be executed. Finally the user runs the program in Run mode using a clock pulse or the Single Step Switch.

Further operation details may be obtained from The Am 2900 Learning and Evaluation Kit, User's Manual.

The System 29 Advanced Microprogramming Development System

The System 29 (29/05) consists of two main parts. The first part of the system is called the Microprogrammed System (MPS), the second part is called the System Support Processor (SSP). Both parts are housed in the System Mainframe.

The MPS consists of hardware required for microprogramming development. The MPS was not used in this project.

The SSP consists of a CPU card and a RAM card. The processor on the CPU card is an Am 9080A microprocessor which can run four RS232 serial I/O ports, three 8-bit parallel ports, a dual disk drive, a CRT, and various other peripherals. The CPU can also run the MPS part of the system if a user wishes.

Through the SSP, a user may run the entire system. CP/M is available to run on the Am 9080A. CP/M utilities include an Assembler, a Dynamic Debugging Technique routine and a Context Editor.

Additional System 29 details may be obtained from the AMDOS System 29 Users' Manual.

CHAPTER III
HARDWARE AND SOFTWARE
CONSIDERATIONS AND DECISIONS

System Overview

Figure 4 is the block diagram of the main parts of the completed system. The area under (A) is the System 29 (29/05)⁵ development system. It includes:

1. a terminal (CRT and keyboard)
2. a dual floppy disk drive
3. the 9080A system support processor.

The units under (B) include:

4. The interface between the Am 2900 and 29/05, which consists of muxes, latches, drivers, and receivers.
5. The Am 2900 kit which has been modified to run with the 29/05.

Am 2900 Kit Inputs

The 2900 kit, is set up with sets of switches which are used for addressing and data input. The interface board uses the switches on the kit and the outputs of the 29/05 as the two inputs to a bank of 2:1 multiplexers.

⁵Note System 29 and 29/05 are used interchangeably within this text.

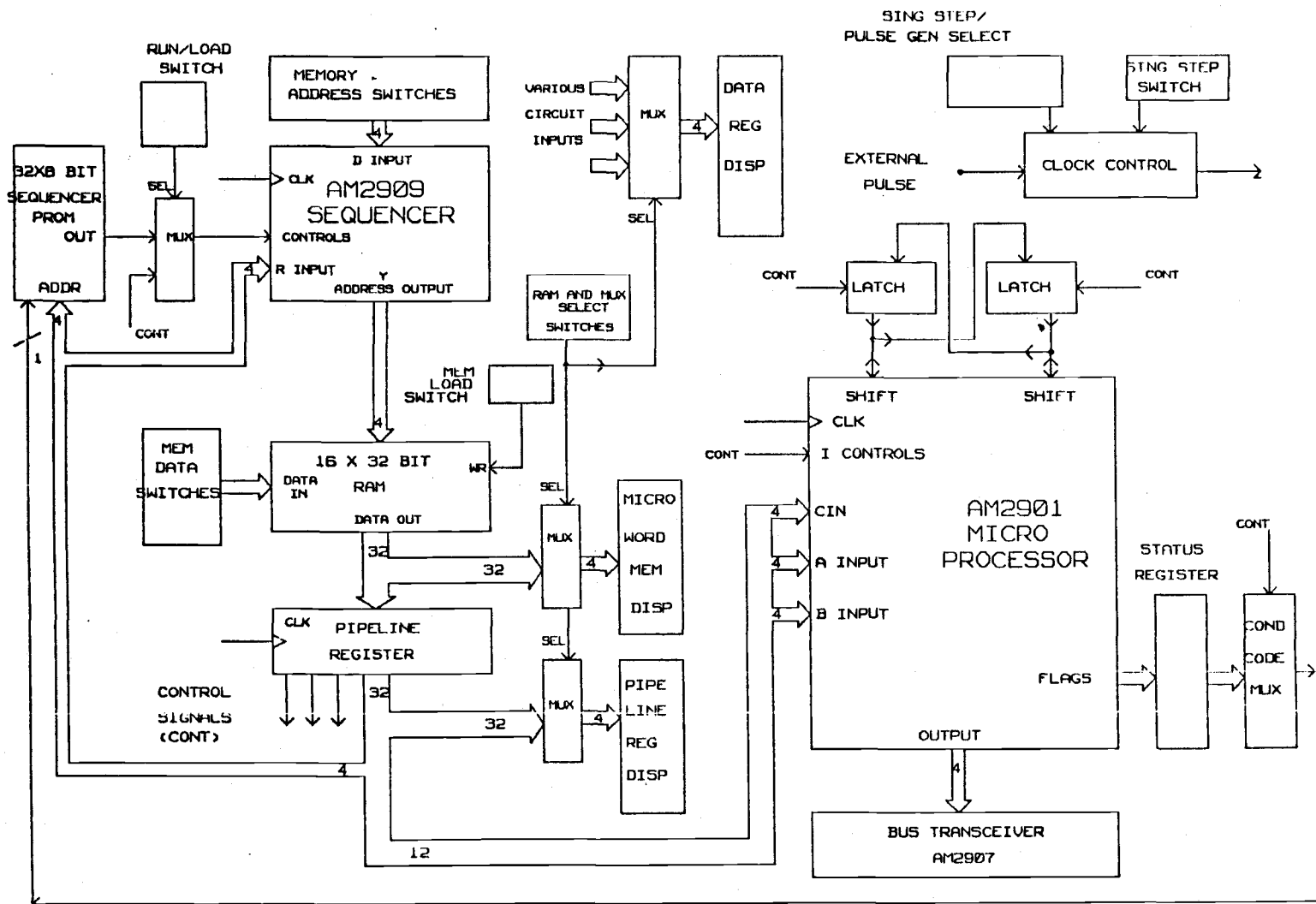


Fig. 4. Basic block diagram of the Am 2900 Microprogramming Learning System.

The multiplexer outputs then go to the inputs of the 2900 processor. This is shown diagrammatically in Figure 5. Thus a user can decide which inputs to use for the 2900 processor. A switch on the interface board allows the user to select the source he wishes.

An attempt was made to wire the system without cutting traces. However, after examining the Am 2900 circuitry, it was obvious that to make the system stable and reliable, traces would have to be cut before external connections could be made. A detailed description of these connections are given in the Appendix.

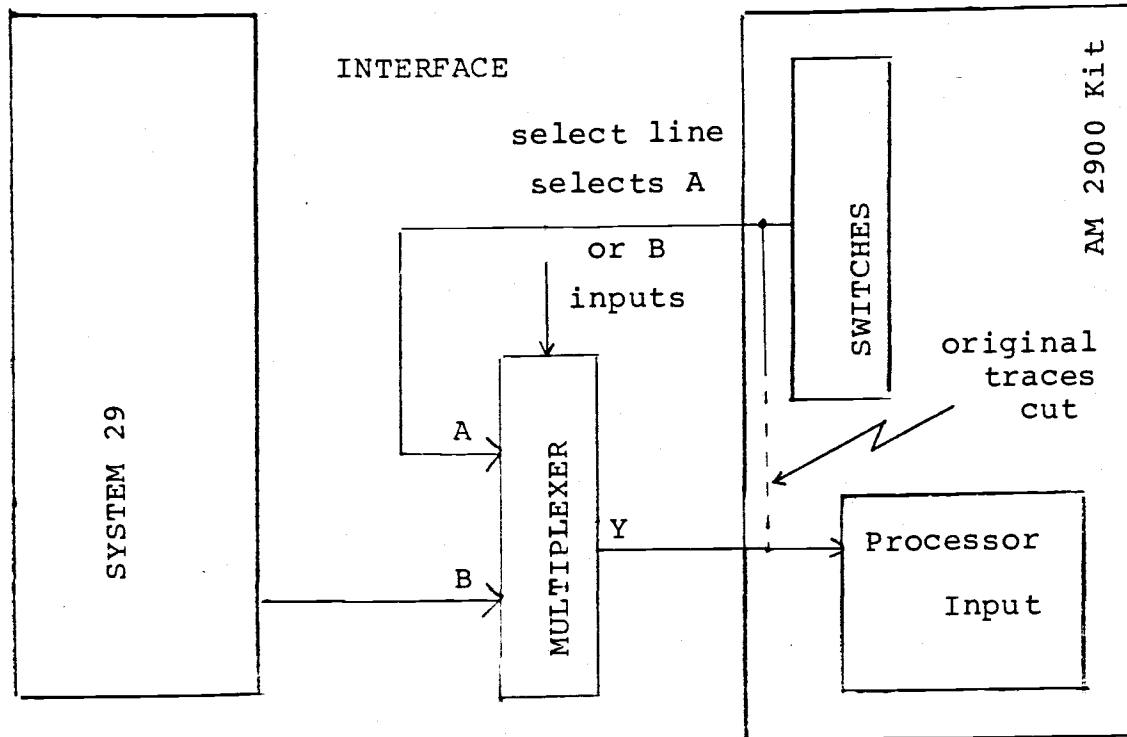


Fig. 5. Multiplexer input detail.

Am 2900 Kit Output

The method of output to the interface board was simple since it was possible to tap into the display outputs, just prior to the LED's of the 2900 kit as shown in Figure 6. Loading was not a concern due to the short distance the signals needed to be carried between the Am 2900 and the interface board.

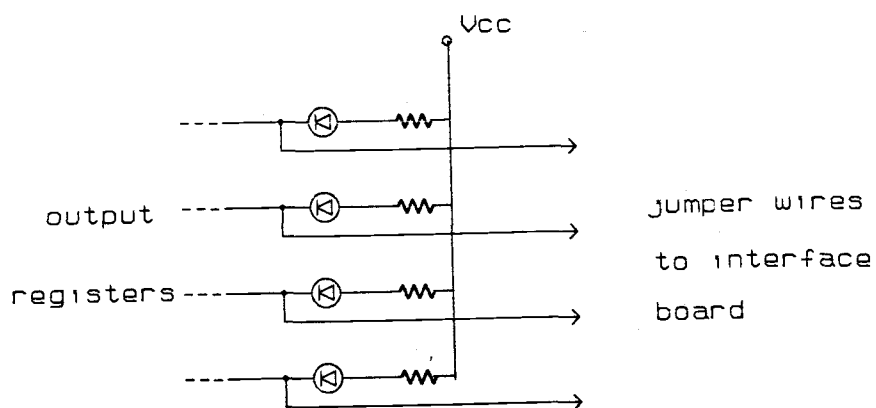


Fig. 6. Am 2900 output connection to Interface Board.

System 29 Input and Output

After the kit's method of output and input had been decided upon it was necessary to decide on the method of input and output on the 29/05. It was decided to use the three 8-bit bidirectional parallel ports on the 9080A processor board (see Figure 7).

Each of these ports can be configured as either inputs or outputs. Their configuration is decided by the following two factors:

1. How the ports are addressed from the 9080A, i.e. whether an OUT (port address) command or an IN (port address) is used.
2. Whether receivers or drivers are inserted into the optional sockets as shown in Figure 4.

Thus by putting drivers on all the ports that are to be outputs and using the OUT (port address) command, an output port configuration is determined. Likewise using receivers and the IN (port address) command an input port configuration is determined.

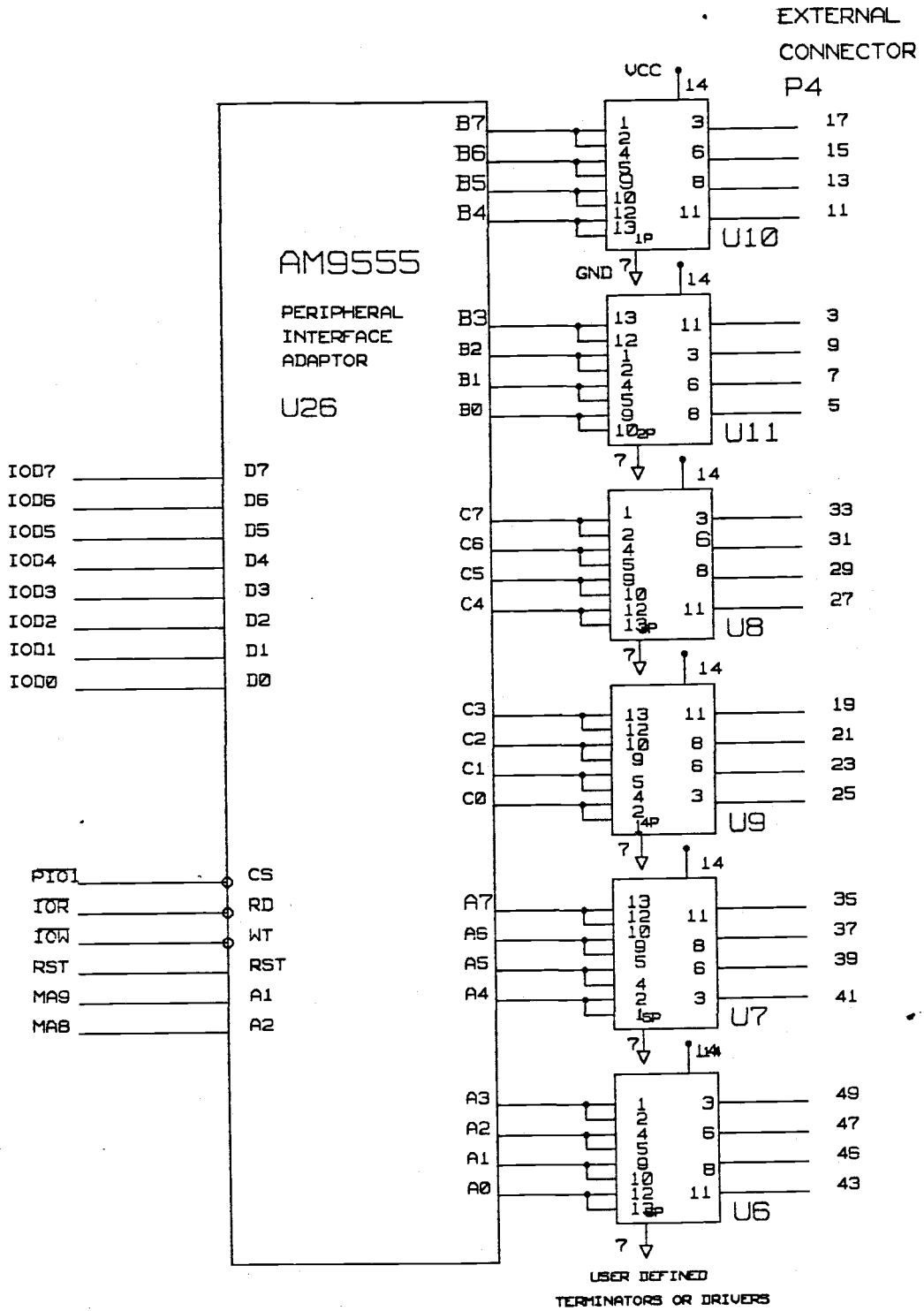


Fig. 7. System 29 parallel ports.

Interface Methods

There were two choices for running the interface between the two systems; the first was to run the system as it was intended to run, i.e. to use the 29/05 outputs to simulate the 2900's switches. The other choice was to reconfigure the system and run it synchronously. The latter method would mean that the address would have to be present at a certain time 't'. At 't + τ ' the data would be expected. Then once the data was present it could be loaded at the next pulse 't + 2 τ '. This would of course involve timing restrictions, a clock pulse and a lot of extra timing logic. As a consequence it was decided instead to use the 29/05 to simulate the 2900 kit's switches. Also by using software to raise and lower the signal at one of the 29/05's output ports, the Single Step Clock Switch could be simulated. This avoided the necessity of using an external clock pulse to run the kit. This method though slower than the synchronous method is fast enough such that the time penalty is of no consequence and is unnoticed by the user.

Am 2900 Kit Load and Single Step Clock Pulses

The Load and Single Step Clock pulses on the 2900 are activated with momentary switches and each of these are used with a debouncer (an Am 9314). To avoid signal problems inputs to the interface board were taken by

bypassing the debouncer as shown in Figure 8. In this way one is able to mux in and choose whichever inputs are desired to run the board (i.e. the kit's switches or the 29/05).

The 29/05 Bidirectional Port Drivers and Receivers

In deciding to use the 29/05's I/O ports, the selection of which ports to use as inputs and outputs had to be made. Furthermore, the method of driving the output ports and receiving the input signal had to be determined.

These I/O ports have configurations like NAND gates as shown in Figure 7. Due to the inability to locate drivers and receivers with the right configurations, the concept of an external adapter board for the 29/05 I/O was researched. This adaptor would consist of MC1488 drivers and MC1489 receivers. However this was discarded in favor of a simpler solution.

It was determined that regular TTL gates would have the capability to drive a 10-foot twisted pair cable needed to carry signals between the interface board and the 29/05. Thus 7400 NAND gates were used as drivers on the output ports and standard resistor pack were used for receivers on the input ports.

I/O Configurations and Connectors

Thus all the I/O and most of the format decisions

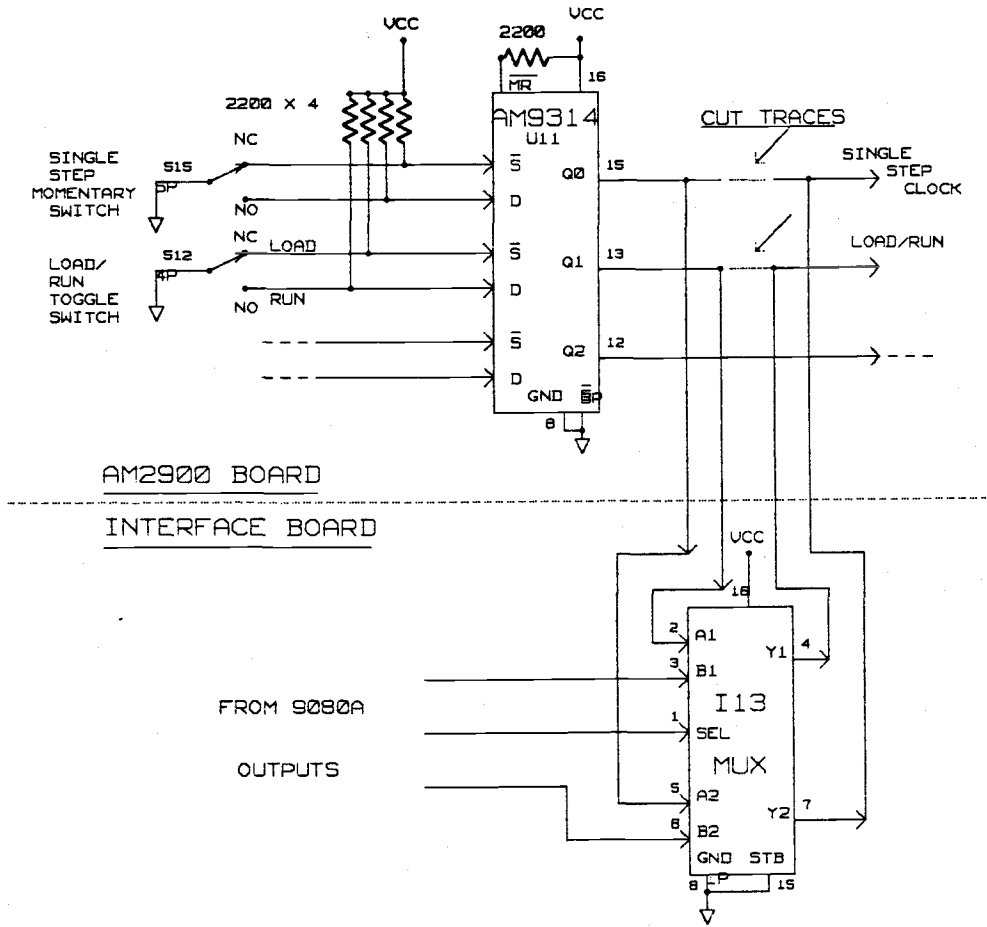


Fig. 8. Single step and load/run connections.

were made. What remained was the actual configuration of the I/O ports themselves, i.e. which ports would be used as outputs and which as inputs. To decide on a configuration it was necessary to determine how the signals were going to be routed to the 10 foot cable. The 29/05 uses a 50 pin edge connector and ribbon cable to route the 24 parallel port I/O signals (3 ports X 8 bits) to a DB25 pin connector on the frame. Every alternate line on the edge connector is grounded. Unfortunately a lot of the DB25 pins are also grounded, and only port A and two lines of port C are actually connected to the DB25 connector. The other signal lines were unconnected. By determining which connector pins were unused and by using jumper wires to connect the I/O port lines to these pins, all necessary signals were routed to the connector without any traces being cut.

Am 2900 Kit I/O Requirements

The kit requires:

- a. 4 data inputs
- b. 4 address inputs
- c. 3 Mux/ RAM select inputs
- d. 1 Single Step Clock Pulse signal
- e. 1 Memory Load signal
- f. 1 Load/ Run selection input

- g. 1 Clock Pulse/ Single Step selection input
- h. 4 data outputs
- i. 4 pipeline register outputs
- j. 4 microword memory register outputs

The above totals 15 input signals and 12 output signals. However, if the data needed can be latched in at the 2900 kit's input, all the lines will not have to be used simultaneously. This method is shown in Figure 9, the Interface Block Diagram. This bus-like structure enables each I/O line to be used for more than one input signal.

Am 29/05 Port Configurations

The 29/05 ports were broken down into input and output as follows:

- Port A -- output from 29/05 to 2900 used for Data, Address, etc.
- Port B -- output from 29/05 to 2900, used for control signals, clock pulses to latches, memory loads, etc.
- Port C -- input to 29/05 from 2900, used for reading data register contents, pipeline register contents, and memory contents.

Rather than using all eight output lines of Port B, Port B was used to run a 3-8 decoder (a 74LS138). This required only three lines from Port B (B_0 to B_2). By using Port B as a control port, data from Port A can be clocked into the desired latches.

Through the decoder, Port B is also used to run the

Single Step Clock Pulse and the Memory Load Pulse⁶.

The three output registers are muxed⁷ to the lowest significant nibble of Port C. The selection of sources for the mux is made with lines B₅ and B₄ of Port B.

This resulted in the input/output configuration shown in Table 3.1 and the block diagram shown in Figure 9.

The Interface Board

The interface board was wired using wirewrap methods, that being the easiest to debug and modify. The board was designed to be as physically modular as possible, i.e. it can be disconnected from the 2900 kit for testing or modifying. This also allows the entire system to be moved without breaking wires or loosening connections.

A schematic of all connections is included in the Appendix.

Software Decisions

Having decided on the hardware options, the software

⁶ The Single Step/ Pulse Generator Switch does not need to be accessed by the 29/05. The user must make sure it remains in the Single Step position whenever using the simulation program.

⁷ By using a mux to select a source it was possible to reduce the number of 29/05 input lines needed and thus use the DB25 connector with its limited number of pins.

Table 3.1. Table of I/O signals.

Inputs to Interface Board from 9080

| 2900 Signal Name | 29/05 Signal Name | Edge Conn. | DB25 Pin No. | Jumper Pin No. | Color |
|---------------------|-----------------------|---------------|-----------------------------------|-------------------|-------------|
| GND 0 | GND A ₀ | 1 43 | P ₁₅ P ₁ | J4-2 J4-3 | Red Blue |
| DATA BUS 1 | A ₁ | 45 | P ₂ | J4-4 | Grn |
| DATA BUS 2 | A ₂ | 47 | P ₃ | J4-5 | Org |
| DATA BUS 3 | A ₃ | 49 | P ₄ | J4-6 | Yellow |
| DATA BUS 4 | A ₄ | 41 | P ₅ | J4-7 | Brown |
| DATA BUS 5 | A ₅ | 39 | P ₆ | J4-8 | Violet |
| DATA BUS 6 | A ₆ | 37 | P ₇ | J4-9 | w/Blk |
| DATA BUS 7 | A ₇ | 35 | P ₈ | unused | |
| CONTROL 0 | B ₀ | 5 | P ₁₈ | J4-11 | w/Blue |
| CONTROL 1 | B ₁ | 7 | P ₁₉ | J4-12 | w/Grn |
| CONTROL 2 | B ₂ | 9 | P ₂₀ | J4-13 | w/Org |
| UNUSED | B ₃ | 3 | P ₂₁ | unused | |
| MUX SELECT 1 | B ₄ | 11 | P ₂₂ | J4-15 | w/Brn |
| MUX SELECT 2 | B ₅ | 13 | P ₂₃ | J4-16 | w/Vio |
| UNUSED | B ₆ | 15 | N/C | unused | |
| UNUSED | B ₇ | 17 | N/C | unused | |

Outputs from Interface to 9080

| | | | | | |
|--------------|----------------|----|-----------------|------|------|
| OUTPUT BUS 0 | C ₀ | 25 | P ₁₃ | J5-1 | Blk |
| OUTPUT BUS 1 | C ₁ | 23 | P ₂₄ | J5-2 | Red |
| OUTPUT BUS 2 | C ₂ | 21 | P ₂₅ | J5-3 | Blue |
| OUTPUT BUS 3 | C ₃ | 19 | P ₁₄ | J5-4 | Grn |
| UNUSED | C ₇ | 33 | P ₁₇ | N/C | |
| GND | GND | | P ₉ | GND | |
| GND | GND | | P ₁₀ | GND | |
| GND | GND | | P ₁₁ | GND | |
| GND | GND | | P ₁₂ | GND | |
| GND | GND | | P ₁₆ | GND | |

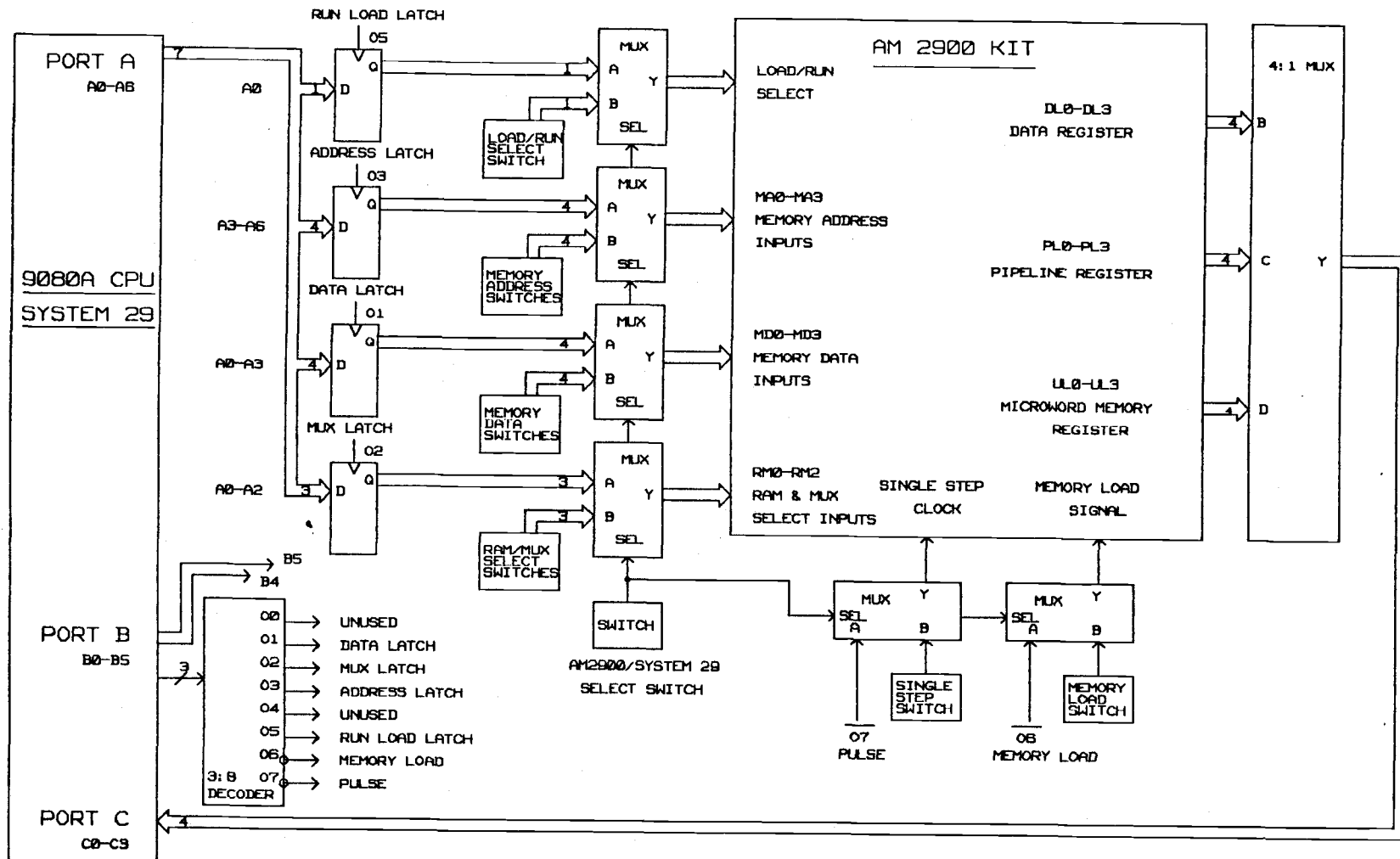


Fig. 9. Interface Block Diagram.

decisions had to be made.

The main subroutines for each operation, e.g. loading, reading, etc. are simple and are explained below.

Loading a nibble of data into memory

Below is a detailed example of a microprogram memory load subroutine. It is suggested that the reader follow these steps while referring to Figure 9, the Interface Block Diagram.

This subroutine loads one nibble (field) of a microword at a time. Field 3 of the microword⁸ is used for this example, i.e. the ALU function and the Am 2901 carry input.

A few assumptions are made in this example:

1. The address of the microword is located in the register called ADDR.
2. The data to be loaded is located in the register addressed as DATA.

⁸ Selected by using the RAM and mux select as listed on page 3-4 of the Am 2900 manual.

Assembly Listing of Program

LOAD\$NIBBLE:

```

MVI A, 01H      ; Put the 2900 into Load mode by sending
OUT PORT$A     ; out a 1 to Port A (bit A0) and
                ; then latch this into the 1 bit latch.
MVI A, 05H      ; This is done by sending out a
                ; 10 (binary) to Port B which
OUT PORT$B     ; will send a high signal out
                ; line O5 (Run/ Load Latch).
MVI A, 00H      ; The line O5 is lowered to simulate a
OUT PORT$B     ; single clock pulse.

LDA ADDR       ; Load in the 4 bit address.
RLC            ; Move the address to bits A6-A3 as
RLC            ; these are the output lines connected to
                ; the address mux on the
RLC            ; interface board.
ORI 03H        ; OR in the RAM/ Mux Select choice.
                ; This results in a 7 bit address as
                ; shown in Figure 10.
OUT PORT$A     ; now send this address out PORT$A,
MVI A, 03H     ; latch in the Address and then latch in
OUT PORT$B     ; the RAM/ Mux Select. This is done
                ; using lines O3 and O2 respectively.

MVI A, 02H     ;
OUT PORT$B     ;

LDA DATA     ; Send
OUT PORT$A     ; the data out port A in bits A0-A3.

MVI A, 01H     ; And in the same way latch the data in
OUT PORT$B     ; using the line O1.
MVI A, 06H     ; Now that the address and data are in
OUT PORT$B     ; send out a memory load pulse. This is
MVI A, 00H     ; done using O6.
OUT PORT$B     ; Lower the signal to simulate a single
                ; pulse.

```

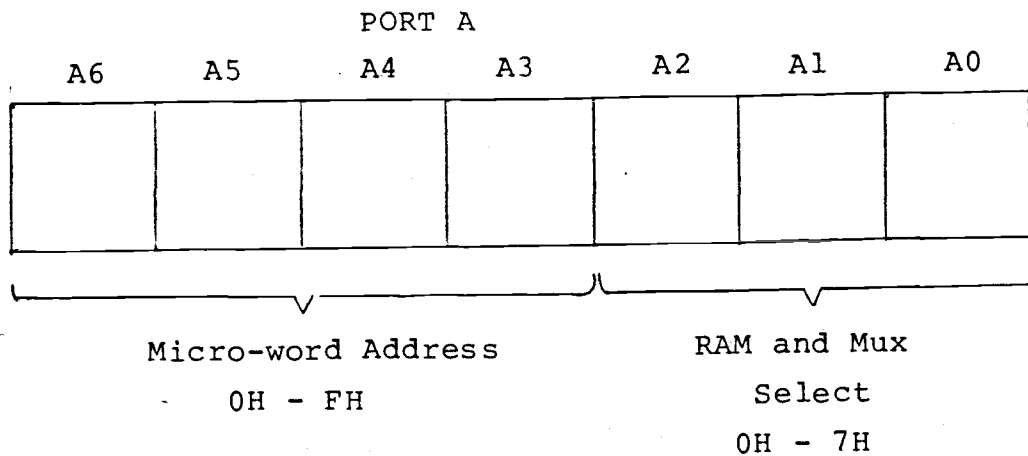


Fig. 10. Effective 7 bit address for a microword field.

Thus the microword can be loaded for all 8 RAM and mux locations (from 0 to 7).

Reading a nibble of data

To read the Am 2900 kit's outputs it is necessary to select which register to read with the control signals of Port B see Table 3.2 below. Then using the IN PORT\$C command on the 9080A the 4 bit data can be loaded through Port C into the LSN of the 9080A accumulator (see Figure 9).

Table 3.2. Control Signals for Port C source.

| B ₅ | B ₄ | Data on Port C bits C ₀ -C ₄ |
|----------------|----------------|--|
| 0 | 0 | N/C |
| 0 | 1 | Data Register D ₀ -D ₃ |
| 1 | 0 | Pipeline Register P ₀ -P ₃ |
| 1 | 1 | Microword Memory Register M ₀ -M ₃ |

Running a program

In running a program on the 2900 kit the kit is first put into run mode and line O₇ is used as a Single Step Clock input. Software is used to create the pulse.

The Simulation Monitor

The simulation monitor is the software that controls the system and simulates the Am 2900 kit switches. All user input and output through the terminal is handled by the monitor using CP/M utilities. The user's input is decoded by the monitor and the appropriate load, read or run subroutine is executed.

All software is written in assembly language and is listed in the Appendix.

CHAPTER IV
USING THE AM 2900
MICROPROGRAMMING LEARNING SYSTEM

Using the Am 2900 with the 29/05

To use the simulation program:

1. Turn on the power switches on the CRT, disk drive, processor and Am 2900 kit.
2. Set the Am 2900 Single Step/ Pulse Generator Select Switch to Single Step.
3. Set the 29/05 - Am 2900 Select Switch on the Interface Board to 29/05.
4. Hit the reset button on the 29/05 processor.
5. Insert the "Am 2900 Simulation" disk into Drive A.

The system will boot up with a request for the date. Once this has been entered the system will return with a CP/M prompt:

A>

The user then types in the simulation program name and enters the simulation monitor⁹.

A> **AM2900** <cr>

⁹For clarity, input typed by the user is shown in bold face type with <cr> representing a carriage return.

The system responds with the monitor title and the simulation prompt:

and the user may then enter any command as follows.

a) Loading microword with data. The L (Load) command:

```

-L3 <cr> / L for Load, 3 for
          / location 3 onwards.
3-AF011001 56A23101 <cr> / System shows original
          / data, user enters new
          / data.
4-ACE611AF <space> <cr> / Old data is left
          / unchanged.
5-4653ABCD <cr> / Exit Load mode.
- / System prompt.

```

The microword is displayed highest significant nibble first. The user will need to refer to the Am 2900 user's manual for microprogramming details.

b) Reading registers and data. The X (Examine) command.

```

-XD <cr> / Examine data register.
D-ABCDEF12 / System responds with
           / the 8 data nibbles.
           / Note the lowest
           / significant nibble is
           / the currently addressed
           / memory location.
-XM <cr> / Examine presently
         / addressed microword.
M-12345678 / System responds with
           / 8 microword nibbles.
-XP <cr> / Examine present
         / pipeline register
         / contents.
P-54321ACE / System responds with 8
           / pipeline nibbles.

```

```

-X <cr>                / Examine all output
                        / registers

D-12345678      P-9ABCDEF0      M-1A2B3C4D

                        / System responds with
                        / contents of all three
                        / output registers.
-                / System prompt.

```

c) Running the program, the G (Go) command¹⁰.

```

-G3,F <cr>            / G for go, 3 for start
                      / location F for
                      / breakpoint11
3=D-54002192      P-21000000      M-F1000000
2=D-AA65430F      P-F1000000      M-F1000000

```

System responds by running program from location 3 outputting address of the location, 8 data nibbles, 8 microword nibbles and 8 pipeline register nibbles at each step (most significant nibble first). User can break program at any time by hitting any key on the console.

d) The S (Single Step) command¹⁰.

```

-S2 <cr>            / S for single step,
                    / 2 for start location.
2=D-ABCDEFO      P-18675309      M-54002192

```

System responds by running program from location 2 outputting as above the address of the location, 8 data

¹⁰The G and S commands are executed in Run mode. Should the user wish to execute commands in the Load mode (certain examples in the Am 2900 kit user's manual do this) it is suggested that he do so using the Am 2900 kit independently of the 29/05.

¹¹The microword at the breakpoint is not executed. The contents of the output registers at this point may be viewed by using the X command.

nibbles, 8 microword nibbles and 8 pipeline register nibbles (most significant nibble first). User continues single stepping by hitting Carriage Return. To exit single step mode the user hits any other key before Carriage Return.

e) The E (Exit) command.

```
-E <cr>           / E for Exit  
A>                / System returns to CP/M
```

f) Errors -- any undefined inputs will cause the system to respond with a bell and a '?'. The system then returns with a prompt for the next command.

Running the Am 2900 Kit Independently of the 29/05

Power up the 2900 kit and the interface board, set Am 2900 - 29/05 switch to Am 2900. Now the switches on the kit will be used as the input to the Am 2900 kit with no interference from the 29/05 development system.

CHAPTER V

CONCLUSION AND FUTURE EXPANSION SUGGESTIONS

The Am 2900 kit is an effective bit-slice demonstration utensil, yet the author feels that AMD should have added external I/O capabilities. This could be in the form of a bus, which would enable the kit to be used for more than just demonstration. Had these interface options been present, kit users would have been able to see some real world applications of bit-slice.

The Am 2900 kit is already very useful for understanding the intricacies of microprogramming. However, it is very tedious to program and if it were to be used as a teaching tool, students could easily get confused by the technicalities of its use. The end effect is that more time is spent wrestling with the methods of loading a program than the actual details of microprogramming.

The objective of this work was to interface the kit with a development system and make a system that would be simple to program, and practical to use for class projects. This goal has been achieved and the modified kit proved to be more versatile and convenient to use. Students may now load, debug, run and most importantly watch the flow of an executing program while on line. Observing the flow of an executing program is vital to the total understanding of any system, especially one as complex as a microprogrammed

microprocessor. Prior to the modifications, a student would have found this almost impossible to do, due to the limited display capabilities of the kit.

Much can be done to extend the present project and all software has been written to allow for the ease of modification or extension.

The following are a few possible ideas for future students:

1. Write software that will break down the 2900 microword into its separate fields and actually list what action is taking place. The user will then be able to decode and debug the microword while on-line.
2. Write software that will allow 2900 programs of longer than 16 microwords. What is envisioned is that the user writes in a program of any length. The 29/05 then loads a page of 16 words. When the page of microinstructions has been executed the 29/05 will automatically load in the next page and so on until the entire program has been run. Users will be limited to branching within the current page, unless a system of branching outside each page is developed. This would not be too complicated as all that would be needed is

to add an extra nibble¹² to each microword which would be the branch page number. On every branch instruction the 29/05 then halts Am 2900 execution and checks if the branch is in the current page or not. If it is not in the current page the 29/05 loads the branch page next and continues processing from there.

3. Add more data and pipeline LED's on the interface board so that a user may see all 32 data pipeline or memory word bits at a single glance.
4. Use the bit-slice capabilities of the Am 2901 to expand the ALU length of the Am 2900 kit to an 8 or 16 bit microprocessor.

¹²This nibble would not be loaded into the Am 2900 microword memory but would be stored and used by the 29/05 for branching.

BIBLIOGRAPY

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2. "AMDOS System/ 29 Manual." Advanced Micro Devices, Inc., 1978.
3. White, Donnamaie E. Bit-Slice Design: Controllers and ALUs. Garland and STPM Press, 1981.
4. Sieworek, Bell and Newell. Computer Structures: Principles and Examples. McGraw-Hill. 1982. Chapters 11, 12, 13 and 14.
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Appendix

Table A1. Drivers and Terminators used for 9080 parallel ports.

| Port Name and bits | Configuration | Socket Number | Chip Type | Chip No. |
|-----------------------|---------------|------------------|------------------|-------------|
| A ₀₋₃ | OUTPUT | V ₆ | NAND | 7400 |
| A ₄₋₇ | OUTPUT | V ₇ | NAND | 7400 |
| B ₀₋₃ | OUTPUT | V ₁₁ | NAND | 7400 |
| B ₄₋₇ | OUTPUT | V ₁₀ | AND | 7408 |
| C ₀₋₃ | INPUT | V ₉ | Resistor pack | 221/331 |
| C ₄₋₇ | UNUSED | V ₈ | -- | -- |

Table A2. Jumper color coding/ pin outs

| Pin Number | Color |
|------------|---------------|
| 1 | Black |
| 2 | Red |
| 3 | Blue |
| 4 | Green |
| 5 | Orange |
| 6 | Yellow |
| 7 | Brown |
| 8 | Violet |
| 9 | White/ Black |
| 10 | White/ Red |
| 11 | White/ Blue |
| 12 | White/ Green |
| 13 | White/ Orange |
| 14 | White/ Yellow |
| 15 | White/ Brown |
| 16 | White/ Violet |

* refer to Figure 4.

Table A3. Jumper pin outs.

Signals from Am 2900 kit to Interface

| Jumper pin | From Switch No. | Am 2900 Signal Name |
|------------|-----------------|-----------------------------------|
| J1-1 | S ₁₁ | MAS ₃ |
| J1-2 | S ₁₀ | MAS ₂ |
| J1-3 | S ₉ | MAS ₁ |
| J1-4 | S ₈ | MAS ₀ |
| J1-5 | S ₄ | MDS ₃ |
| J1-6 | S ₅ | MDS ₂ |
| J1-7 | S ₆ | MDS ₁ |
| J1-8 | S ₇ | MDS ₀ |
| J1-9 | S ₃ | RMS ₂ |
| J1-10 | S ₂ | RMS ₁ |
| J1-11 | S ₁ | RMS ₀ |
| J1-12 | Q ₀ | single step clock switch input |
| J1-13 | Q ₁ | load/ run switch input |
| J1-14 | S ₁₄ | memory load switch input |
| J3-1 | | DL ₃ |
| J3-2 | | DL ₂ |
| J3-3 | | DL ₁ |
| J3-4 | | DL ₀ |
| J3-5 | | PL ₃ |
| J3-6 | | PL ₂ |
| J3-7 | | PL ₁ |
| J3-8 | | PL ₀ |
| J3-9 | | UL ₃ |
| J3-10 | | UL ₂ |
| J3-11 | | UL ₁ |
| J3-12 | | UL ₀ |
| J3-15 | | GND |
| J3-16 | | +5 |

Table A3. Jumper pin outs., cont.

Signals from Interface to Am 2900 kit

| Jumper Pin | Am 2900 Kit Signal Name |
|------------|-----------------------------|
| J2-1 | MA ₃ |
| J2-2 | MA ₂ |
| J2-3 | MA ₁ |
| J2-4 | MA ₀ |
| J2-5 | MD ₃ |
| J2-6 | MD ₂ |
| J2-7 | MD ₁ |
| J2-8 | MD ₀ |
| J2-9 | RM ₂ |
| J2-10 | RM ₁ |
| J2-11 | RM ₀ |
| J2-12 | single step clock signal |
| J2-13 | load/ run select signal |
| J2-14 | memory load signal |
| J2-15 | GND |
| J2-16 | GND |
| J1-15 | Vcc |
| J1-16 | Vcc |

Table A4. Inputs from 9080 to Interface Board

| DB25 | to Jumper Pin | Color | Signal Name | Edge Conn. |
|------|---------------|----------|----------------|------------|
| P1 | J4-3 | Blue | A ₀ | 43 |
| P2 | J4-4 | Green | A ₁ | 45 |
| P3 | J4-5 | Orange | A ₂ | 47 |
| P4 | J4-6 | Yellow | A ₃ | 49 |
| P5 | J4-7 | Brown | A ₄ | 41 |
| P6 | J4-8 | Violet | A ₅ | 39 |
| P7 | J4-9 | W/Black | A ₆ | 37 |
| P8 | unused | | A ₇ | 35 |
| P9 | unused | | GND | |
| P10 | unused | | GND | |
| P11 | unused | | GND | |
| P12 | unused | | GND | |
| P13 | J5-1 | Black | C ₀ | 25 |
| P14 | J5-4 | Green | C ₃ | 19 |
| P15 | J4-2 | Red | GND | |
| P16 | unused | | GND | |
| P17 | unused | | C ₇ | 33 |
| P18 | J4-11 | W/Blue | B ₀ | 5 |
| P19 | J4-12 | W/Green | B ₁ | 7 |
| P20 | J4-13 | W/Orange | B ₂ | 9 |
| P21 | unused | | B ₃ | 3 |
| P22 | J4-15 | W/Brown | B ₄ | 11 |
| P23 | J4-16 | W/Violet | B ₅ | 13 |
| P24 | J5-2 | Red | C ₁ | 23 |
| P25 | J5-3 | Blue | C ₂ | 21 |

Table A5. Table of Parts.

| Chip No. | Chip Name | Function |
|----------|-----------|-----------------------|
| I1 | 74LS138 | 1 of 8 decoder/ demux |
| I2 | 74LS 04 | Inverter |
| I3 | 74LS175 | Quad D Latch |
| I4 | 74LS175 | Quad D Latch |
| I5 | 74LS175 | Quad D Latch |
| I6 | 74 157 | Quad 2:1 Mux |
| I7 | 74 157 | Quad 2:1 Mux |
| I8 | 74 157 | Quad 2:1 Mux |
| I9 | 74LS175 | Quad D Latch |
| I10 | 74LS253 | Dual 4:1 Mux |
| I11 | 74LS253 | Dual 4:1 Mux |
| I12 | 74 00 | Two Input NAND |
| I13 | 74 157 | Quad 2:1 Mux |
| I14 | 74 00 | Two Input NAND |
| I15 | 74 00 | Two Input NAND |
| I16 | 74 00 | Two Input NAND |

Table A6. Jumper Cables

| | |
|----|---------------------------------------|
| J1 | From 2900 to Interface Board |
| J2 | From Interface Board to 2900 |
| J3 | From 2900 to Interface Board |
| J4 | From System (9080) to Interface Board |
| J5 | From Interface Board to System (9080) |

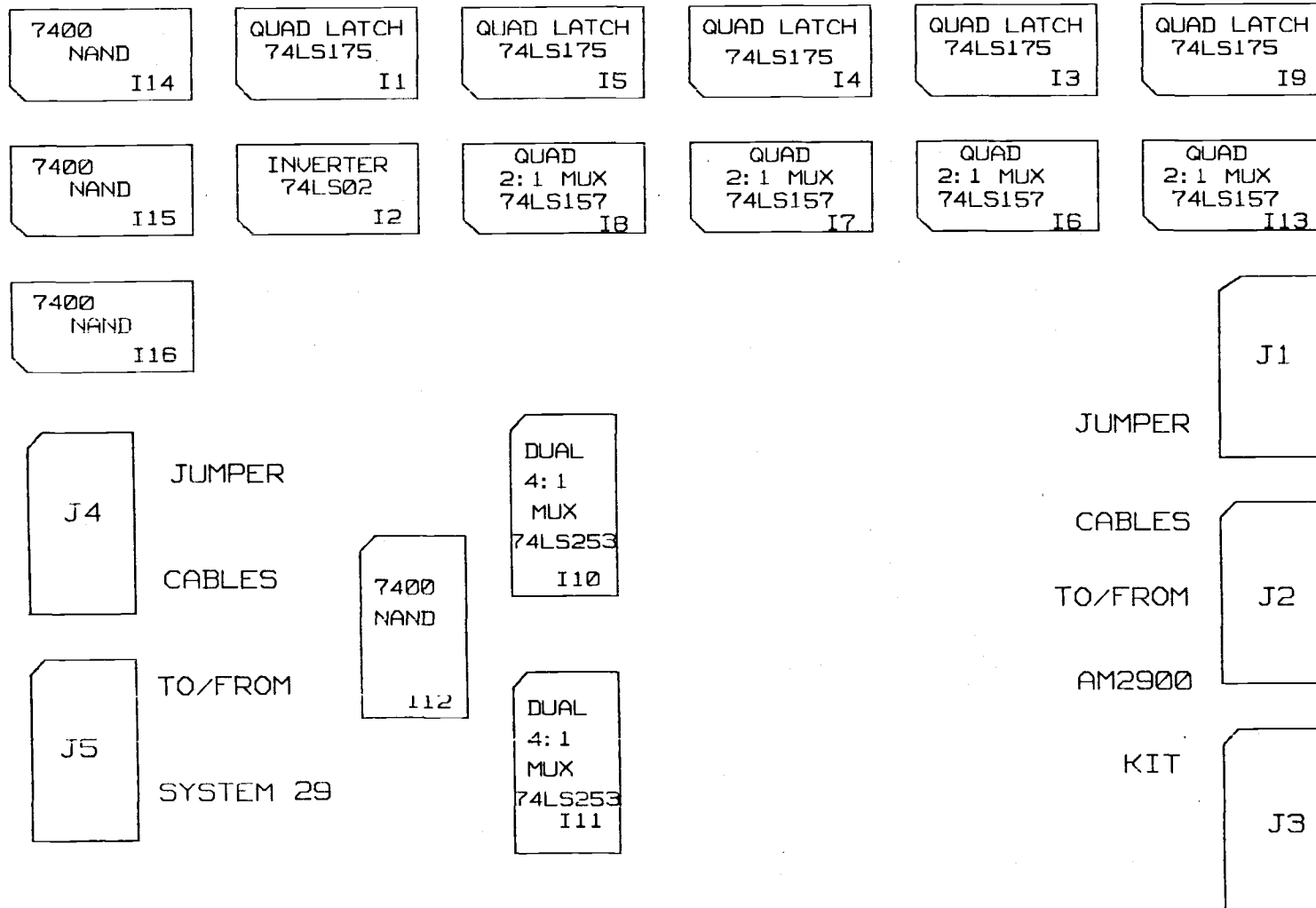


Fig. A1. Interface board layout: top view.

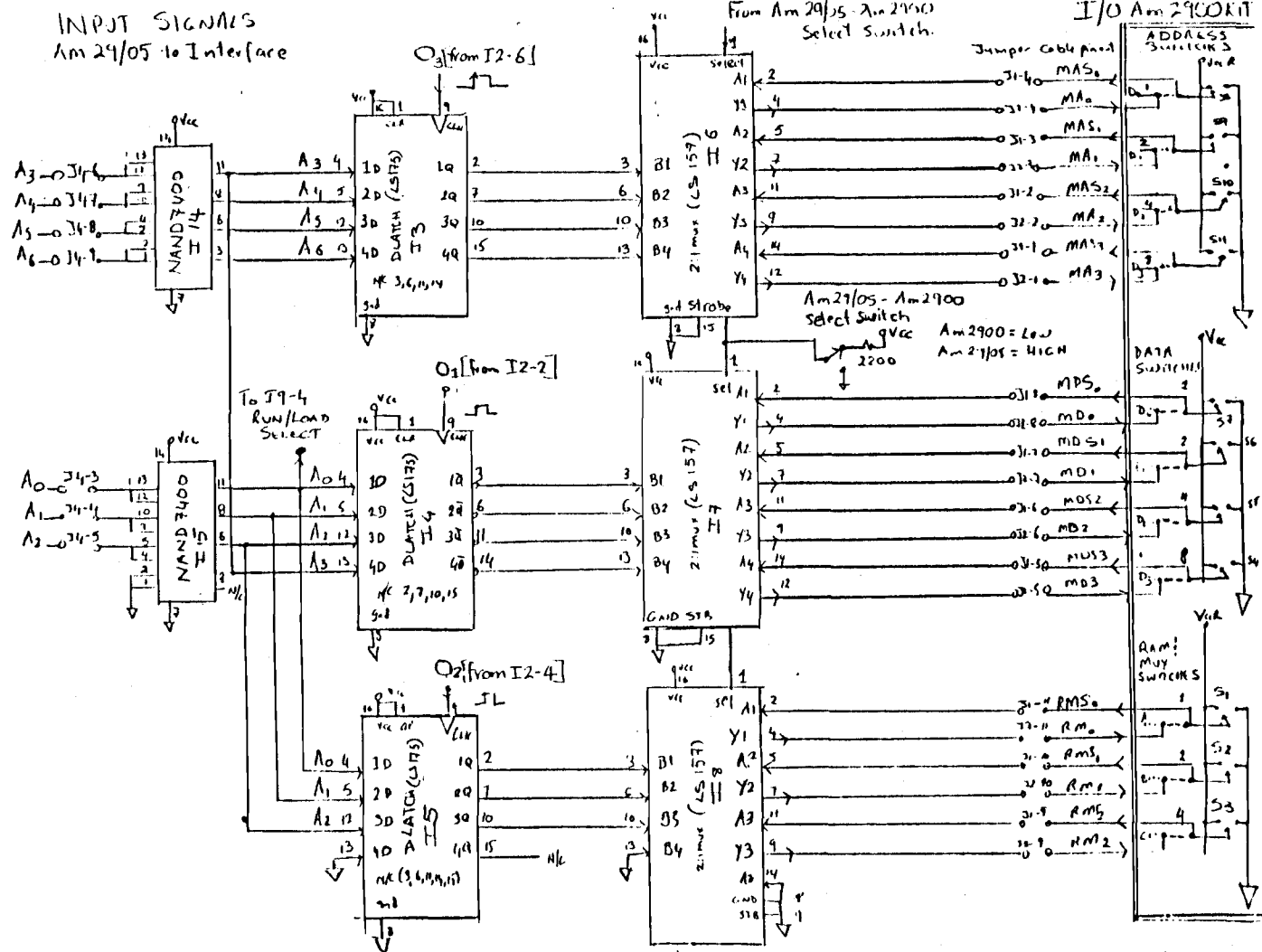


Fig. A2. Interface board schematics I.

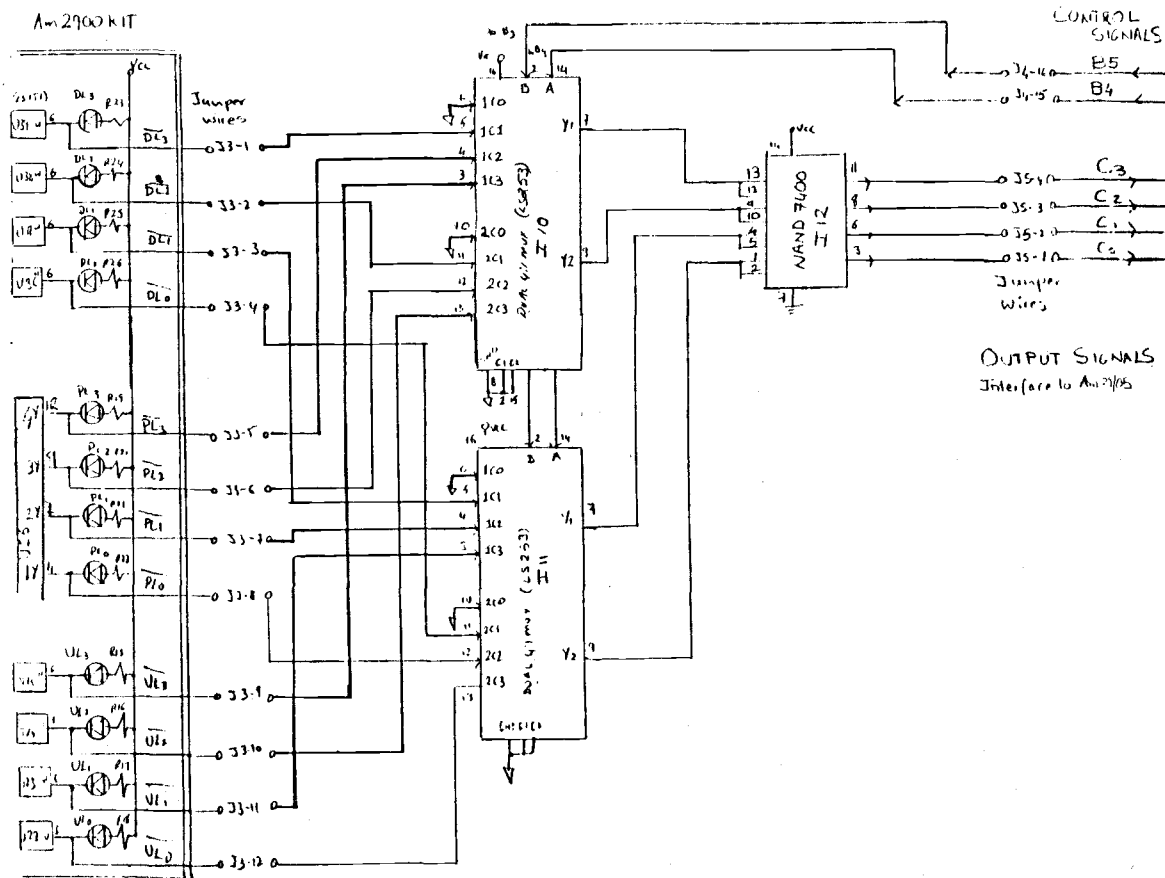


Fig. A3. Interface board schematics II.

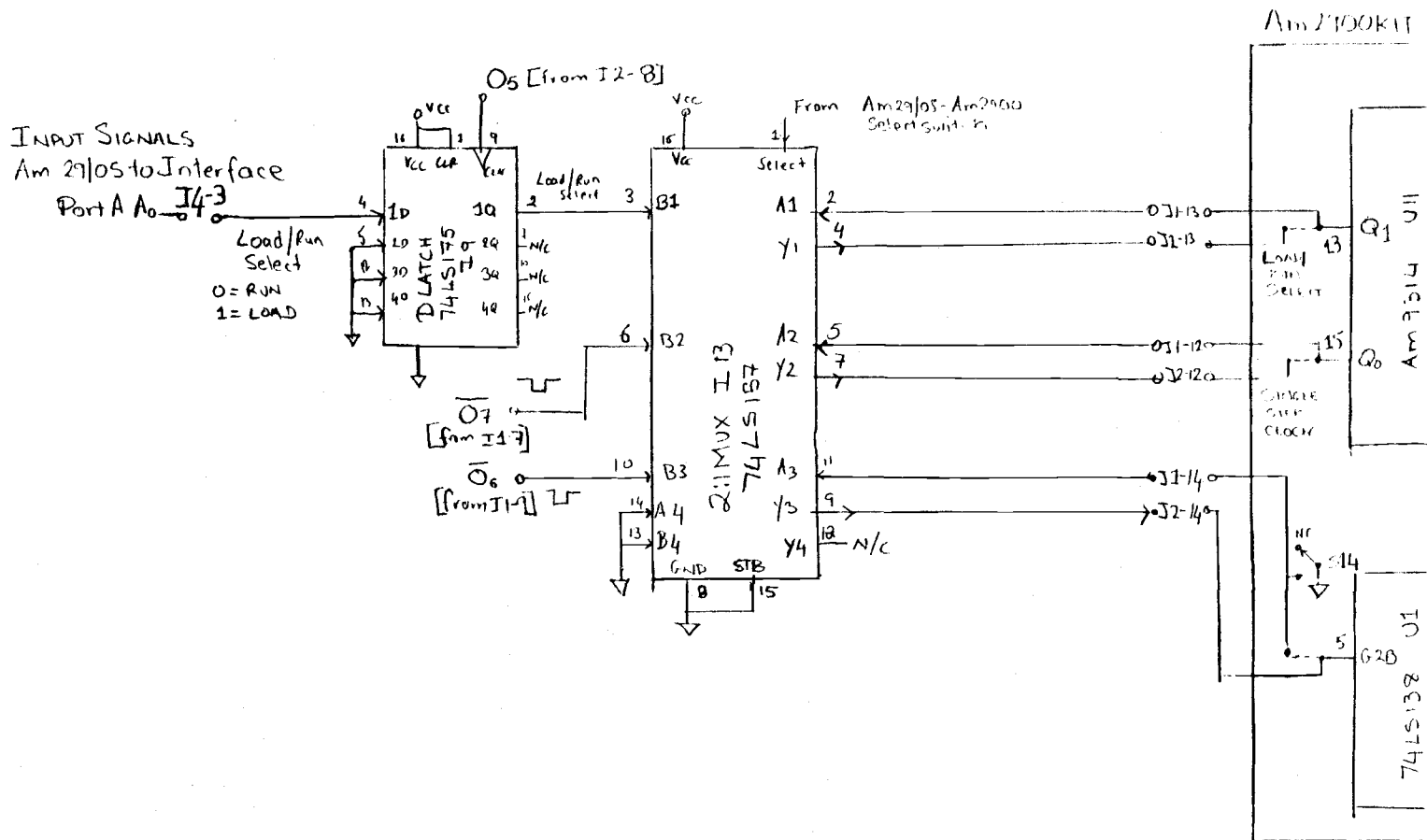


Fig. A4. Interface board schematics III.

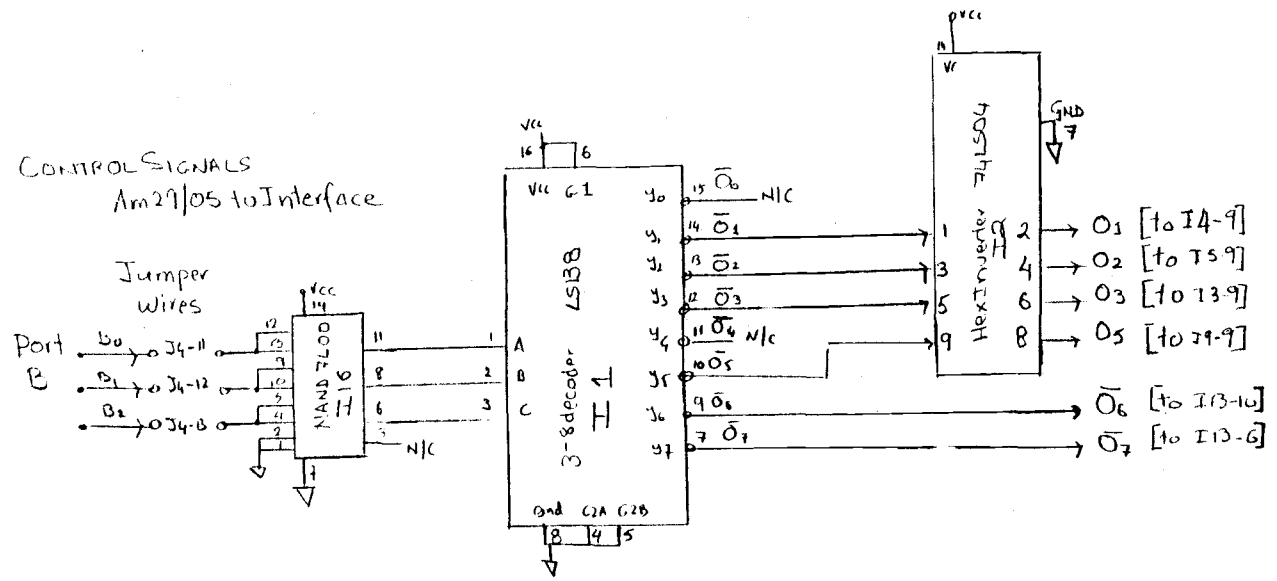


Fig. A5. Interface board schematics IV.

Software Listing

```

;LAST UPDATE 6/6/84
ORG 100H
        JMP      STARTPOINT
ORG 1000H
BDOS      EQU      5H      ;THE BDOS ENTRY POINT
                          ;THIS IS USED BY
                          ;SELECTING ONE OF THE MANY
                          ;CPM BDOS OPTIONS AS
                          ;DOCUMENTED IN THE REPORT
                          ;INSERTING THIS VALUE
                          ;INTO THE C REGISTER
                          ;AND CALL THE BDOS ROUTINE.

;
;THE FOLLOWING LOCATIONS ARE USED WITH PORT B AS CONTROL
;SIGNALS TO THE INTERFACE BOARD (THE AM2900 KIT)
DATA$LATCH      EQU      01H      ;SELECTS O1 AND LATCHES
                          ;IN THE DATA NYBBLES
MUX$LATCH        EQU      02H      ;SELECTS O2 AND LATCHES
                          ;IN THE RAM/MUX SELECT
ADDRESS$LATCH    EQU      03H      ;O3, LATCHES IN THE
                          ;ADDRESS
RUN$LOAD$LATCH   EQU      05H      ;05, LATCHES IN THE RUN
                          ;OR LOAD CHOICE
                          ;WHERE RUN=1, AND LOAD=0
MEMORY$LOAD      EQU      06H      ;PULSES TO LOAD MEMORY
PULSE            EQU      07H      ;THE CLOCK PULSE

;
;THE NEXT THREE LOCATIONS ARE USED WITH PORT C TO SELECT
;WHICH OF THE 3 2900 LED NYBBLES TO READ (I.E. IT
;CONTROLS THE MUX). THIS MUX IS CONTROLLED BY BITS 5
;AND 4 OF PORT C.
SEL$DATA         EQU      10H      ;DATA NYBBLE MUX C1,
                          ;C2=0,1 ETC.
SEL$PIPELINE     EQU      20H
SEL$MICROWORD    EQU      30H

;
;OTHER REGISTERS AND BUFFERS
;
TEMP:            DS      1      ;A SCRATCH REGISTER
ADDR:            DS      1      ;A REGISTER USED TO
                          ;STORE AN ADDRESS TEMP.
HEXADDR:         DS      1      ;USED TO STORE THE ABOVE
                          ;ADDRESS IN HEX
FLAG$ALL:        DS      1      ;USED AS A FLAG
PORT$A           EQU      70H      ;USED TO ADDRESS PORT A
PORT$B           EQU      71H      ;USED TO ADDRESS PORT B
PORT$C           EQU      72H      ;USED TO ADDRESS PORT C

```



```

BREAK$PT:      DS      1      ;THIS BYTE IS USED TO
                ;STORE THE BREAK POINT
                ;FOR THE GO COMMAND
DELAYS$AVE:    DS      2      ;USED TO SAVE HL REG FOR
                ;DELAY ROUTINE
DELAY$REG:     DS      1      ;COUNTER USED FOR
                ;DELAYING
SEL$LOAD       EQU     01H    ;WHEN LATCHED IN PUTS
                ;2900 IN LOAD MODE
SEL$RUN        EQU     00H    ;WHEN LATCHED IN PUTS
                ;2900 IN RUN MODE

MESSAGE:       DB      0AH,0AH,0AH
                DB      'THE AM2900 MICRO'
                DB      'PROGRAMING LEARN'
                DB      'ING SYSTEM',0DH,0AH
                DB      'NEIL MAMMEN, 1984',0AH,0AH,'$'

DATA$BUFFER:   DS      8      ;THIS 8 BYTE BUFFER IS
                ;USED TO STORE THE
                ;2900 LED DATA THAT IS
                ;READ. ONLY THE LSN'S ARE
                ;USED. INPUT FROM
                ;AM2900 TO Z-80

LOAD$BUFFER:   DS      8      ;AN 8 BYTE BUFFER USED
                ;TO STORE THE 8
                ;NYBBLES THAT WILL BE
                ;DOWN LOADED INTO
                ;THE AM2900 RAM I.E.
                ;THE MICROWORD. ONLY
                ;THE LSN ARE USED AND THE
                ;1ST LOCATION
                ;IS THE MOST SIGNIFICANT
                ;NYBBLE.

CONSOLE$BUFFER: DS     12     ;A 12 BYTE BUFFER USED TO
                ;STORE LETTERS/NOS
                ;WHICH ARE TO BE PRINTED.
                ;THE LAST CHAR HAS TO BE
                ;A '$'. OUTPUT FROM Z-80
                ;TO CRT
KEYBOARD$BUFFER:DS     12     ;A 12 BYTE BUFFER WHICH
                ;STORES THE INPUT FROM
                ;THE CRT/KEYBOARD. INPUT
                ;CONSOLE TO Z-80

```

;*****INITIALIZATION*****

```
STARTPOINT:  MVI    A,12    ;WE SET THE SIZE OF THIS
              ;          ;BUFFER BY PUTTING
              STA  KEYBOARD$BUFFER    ;THE SIZE IN THE
              ;          ;1ST LOCATION
              MVI    A,89H    ;SET THE PPI (AM9555)
              ;          ;TO HAVE PORTS
              OUT    73H    ;A&B AS OUTPUTS AND C AS
              ;          ;AN INPUT. OUT 73 WRITES
              ;          ;TO THE CONTROL
              MVI    C,09H    ;PRINT THE START MESSAGE
              LXI D,MESSAGE    ;
              CALL   BDOS    ;
```

;*****MAIN CONTROL PROGRAM*****

;THIS PROGRAM IS THE MAIN LOOP THAT CALLS ALL THE
;DIFFERENT BRANCHES

```
;
AM2900:
              MVI A,SEL$LOAD    ;RESET SYSTEM TO LOAD
              ;          ;MODE
              OUT   PORT$A    ;BY SENDING OUT A 1 TO
              ;          ;THE LATCH
              MVI A,RUN$LOAD$LATCH    ;AND BY LATCHING
              ;          ;IN THE 1
              OUT   PORT$B    ;
              LXI H,CONSOLE$BUFFER    ;SET UP THE
              ;          ;SYSTEM PROMPT '-'
              MVI   M,0DH    ;CR
              INX   H    ;
              MVI   M,0AH    ;LF
              INX   H    ;
              MVI   M,'-'    ;
              INX   H    ;LOAD IT INTO THE
              ;          ;CONSOLE BUFFER
              MVI   M,'$'    ;PUT THE '$' TO INDICATE
              ;          ;THE END OF STRING
              CALL  CONSOUT    ;PRINT IT BY
              ;          ;CALLING THE
              ;          ;PRINT ROUTINE
              CALL  CON$IN    ;READ THE USER'S
              ;          ;INPUT
              CALL  CR$LF    ;DO A CR AND LF
              LDA  KEYBOARD$BUFFER+1    ;CHECK IF USER
              ;          ;ONLY ENTERED CR
              CPI   0H    ;
              JZ   AM2900    ;IF SO WE JUST LOOP
              ;          ;AROUND
```

```

LDA KEYBOARD$BUFFER+2 ;READ IN THE
                        ;FIRST CHAR
CPI 'L' ;CHECK IF IT IS AN 'L'?
JZ LOADING ;IF SO DO THE LOAD
                        ;ROUTINE
CPI 'X' ;'X'?
JZ EXAMINE
CPI 'G' ;'G'?
JZ GORUN
CPI 'S' ;'S'?
JZ SINGSTEP
CPI 'E' ;'E' FOR EXIT/END
JNZ ERROR ;IF THNOT AN 'E' THEN
                        ;WE HAVE AN ERROR
MVI C,0H ;IF 'E' WAS INPUT WE
                        ;RETURN TO CPM
CALL BDOS ;BY USING THE BDOS RESET
                        ;COMMAND
JMP AM2900 ;LOOP

```

```

;*****
;
;THE READ KEYBOARD SUBROUTINE- THIS SUBROUTINE SELECTS
;THE APPROPRIATE VALUE FOR THE C REGISTER AND CALLS BDOS.
;BDOS EXPECTS THE BUFFER LOCATION IN THE DE REGISTER, AND
;THE SIZE OF THE INPUT BUFFER IN THE FIRST BUFFER
;LOCATION. THE ROUTINE RETURNS WITH THE NO. OF CHARS
;INPUTTED IN THE SECOND BUFFER LOCATION. THE BUFFER HERE
;IS KEYBOARD$BUFFER.

```

CON SIN:

```

MVI C,10 ;THE 9 SELECTS THE 'INPUT
          ;STRING' ROUTINE IN BDOS
LXI D,KEYBOARD$BUFFER ;SET THE BUFFER
                       ;LOCATION
CALL BDOS ;
RET ;

```

```

;THE PRINT ROUTINE- THIS SUBROUTINE USES THE BDOS
;MONITOR ALSO, THE END OF THE STRING TO BE PRINTED IS
;DENOTED BY A '$' IN THE BUFFER.

```

CONSOUT:

```

MVI C,09 ;THE 10 SELECTS THE BDOS
          ;'OUTPUT STRING'
LXI D,CONSOLE$BUFFER ;THE LOCATION OF
                     ;THE BUFFER IS
                     ;GIVEN
CALL BDOS ;
RET ;

```

```

;
;THE ERROR ROUTINE- THIS ROUTINE PRINTS A '?', IGNORES
;ALL INPUT AND RETURNS CONTROL TO THE MAIN PROGRAM
;('AM2900').

```

ERROR:

```

CALL CR$LF ;
LXI H,CONSOLE$BUFFER ;SET UP THE
;BUFFER
MVI M,'?' ;PUT A '?' IN THE BUFFER
INX H ;SET UP THE NEXT BUFFER
;LOCATION
MVI M,07H ;PUT A 'BELL' IN BUFFER
INX H
MVI M,0AH ;'LF'
INX H ;
MVI M,0DH ;'CR'
INX H ;NEXT LOCATION
MVI M,'$' ;PUT A '$' TO INDICATE
;THE END OF THE STRING.
CALL CONSOUT ;GO TO PRINT THE BUFFER
JMP AM2900 ;GO BACK TO THE MAIN
;PROGRAM

```

```

;
;THE DELAY ROUTINE- THIS DELAY ROUTINE IS USED JUST AS
;TO ALLOW FOR PROPAGATION DELAYS AND ETC WHEN ADDRESSING
;THE AM2900.

```

DELAY:

```

SHLD DELAYSAVE ;SAVE THE HL REGISTER
LXI H,DELAYREG ;SET UP A COUNTER
MVI M,001H ;COUNT DOWN FROM FFFFH
DELAY1: DCR M ;
JNZ DELAY1 ;
LHLD DELAYSAVE ;RESTORE THE HL REGISTER
RET

```

```

;
; SUBROUTINE TO READ THE AM2900 BOARD LEDS- THIS
; SUBROUTINE READS ANY ONE OF THE DATA, PIPELINE OF
; MICROWORD NYBBLES. THE CHOICE OF WHICH SET TO READS
; IS SELECTED BY PASSING THE CHOICE THROUGH THE C REGISTER
; AS EXPLAINED AHEAD IN THE RD$PRINT$8NYBBLES ROUTINE.
; THE CHOICE OF RAM/MUX FOR THE AM2900 IS PASSED THROUGH
; THE ACCUMULATOR. THE DATA IS RETURNED IN THE LSN OF
; THE ACCUMULATOR.

```

RDLEDS:

```

      OUT      PORT$A      ; SEND OUT MUX/RAM SELECT
                          ; THROUGH PORT A
      MOV      A,C         ; MOV THE CHOICE OF LED'S
                          ; TO BE READ INTO ACC.
      ORI     MUX$LATCH    ; SET UP THE SIGNAL TO
                          ; LATCH IN THE
                          ; MUX/RAM SELECT AND TO
                          ; SEND OUT THE CONTROL
                          ; SIGNALS THAT SELECT
                          ; WHICH SET OF LEDS TO READ
      OUT      PORT$B      ; SO IT IS READY FOR NEXT
                          ; TIME
      IN       PORT$C      ; READ IN THE LEDS
      ANI     0FH         ; MASK OFF THE UNWANTED
                          ; BITS (I.E. THE MSN)
      RET                          ; RETURN WITH DATA IN LSN
                          ; OF ACCUMULATOR

```

```

;
; THE READ WORD ROUTINE- THIS SUBROUTINE READS ALL 8
; NYBBLES OF ANY OF THE 3 AM2900 LED OUTPUTS. WHAT IT IS
; IS JUST AN EXPANSION ON THE LAST RD$DATA SUBROUTINE.
; THE WHOLE WORD (DATA, PIPELINE OR MICROWORD) IS READ AND
; STORED IN THE DATA$BUFFER. WHAT THE ROUTINE DOES IS GO
; THRU ALL 8 RAM/MUX COMBINATIONS. THE INFO IS STORED
; STARTING WITH MUX/RAM SELECT EQUAL TO 7 FIRST, THEN 6
; ETC. OBVIOUSLY ONLY THE LSN OF EACH OF THE DATA$BUFFER
; BYTES ARE USED.

```

RD\$WORD:

```

      MVI     B,8         ; USED TO ADDRESS THE
                          ; MUX/RAM
      LXI H, DATA$BUFFER ; SET UP THE
                          ; BUFFER TO STORE
                          ; THE INFO

```

```

RD$WORD1:
      DCR     B           ; COUNTDOWN AND MUX/RAM
                          ; ADDRESS
      MOV     A,B        ; MOVE ADDRESS INTO
                          ; ACCUMULATOR

```

```

CALL    RD$LEDS ;GO TO READ THE LEDS, THE
          ;C REGISTER SHOULD
          ;ALREADY HAVE THE CHOICE
          ;OF WHICH OF THE 3 LEDS
          ;WE ARE TO BE READING
MOV     M,A     ;RD$LEDS RETURNS WITH THE
          ;NYBBLE IN THE ACC
          ;SO WE STORE IT IN THE
          ;BUFFER
MVI     A,0     ;LOWER THE LATCH SIGNAL
OUT     PORT$B  ;SO THE LATCH CAN BE USED
          ;AGAIN
INX     H       ;SET UP THE NEXT BUFFER
          ;LOCATION
MOV     A,B     ;CHECK FOR ALL 8 NYBBLES
ADI     0       ;TRIGGER THE FLAGS
JNZ     RD$WORD1;IF NOT GO BACK
RET     ;WHEN DONE, RETURN.

```

```

;
;READING AND PRINTING ALL 8 NYBBLES OF ANY OF THE THREE
;REGISTERS - THIS ROUTINE TAKES THE PRESENT LATCHED IN
;ADDRESS AND PRINTS ALL 8 NYBBLES OF ANY OF THE DATA,
;PIPELINE OR MICROWORD REGISTERS ON THE CONSOLE. THE
;CHOICE OF WHICH REGISTER TO PRINT IS SELECTED BY SETTING
;BITS 5 AND 4 OF THE C REGISTER AND SUBSEQUENTLY B PORT
;AS SHOWN:

```

```

;           C=SEL$DATA (10H)

```

```

;           C=SEL$PIPELINE (20H)

```

```

;           C=SEL$MICROWORD (30H)

```

```

;THIS ROUTINE IS A FURTHER EXPANSION OF THE RD$WORD
;SUBROUTINE ABOVE.

```

```
RD$PRINT$8NYBBLES:
```

```

CALL    RD$WORD ;1ST READ ALL 8 NYBBLES
          ;SELECTED BY C

```

```

MVI     B,8     ;SET UP THE 8 NYBBLE
          ;COUNTER

```

```

LXI D,CONSOLE$BUFFER ;SET UP THE
          ;CONSOLE BUFFER
          ;TO ACCEPT THE
          ;8 NYBBLES TO
          ;PRINTED ON THE
          ;CONSOLE

```

```

LXI H,DATA$BUFFER   ;SET UP TO READ
          ;THE DATA BUFFER
          ;WITH THE DATA
          ;WE JUST READ.

```

```

RD$PRINT1:  MOV     A,M     ;READ THE 1ST NYBBLE
CALL     ASC$ENCODE  ;CONVERT FROM HEX
          ;TO ASCII

```

```

STAX    D           ; STORE IT IN THE CONSOLE
                ; (PRINT) BUFFER
INX     D           ; SET UP FOR THE NEXT
                ; NYBBLE
INX     H           ;
DCR     B           ;
JNZ     RD$PRINT1  ; DONE? IF NOT
                ; RETURN FOR NEXT
                ; NYBBLE

MVI     A,09H      ; IF DONE PUT A 'TAB'
STAX    D           ;
INX     D           ;
MVI     A,'$'      ; AND AN 'END OF STRING'
                ; MARKER
STAX    D           ;
CALL    CONSOUT    ; GO TO PRINT THE BUFFER
RET     ; RETURN

```

; THE HEXCHECK AND DECODE ROUTINE- THIS ROUTINE CHECKS IF
; THE VALUE IN THE ACC IS AN ASCII HEX DIGIT, I.E.
; BETWEEN 0-9 OR A-F. IF IT IS IT CONVERTS IT INTO HEX.
; IF IT ISN'T IT SETS THE CARRY BIT TO INDICATE A NON-HEX
; CHARACTER. IT IS DONE BY USING THE CPI COMMAND WHICH
; COMPARES AND SETS THE CARRY FLAG IF THE ACC. IS LESS
; THAN THE COMPARED VALUE.

HEXCHECK:

```

CPI     30H        ; LESS THAN 30H?
JC      HEXBAD    ; IF YES IT'S NOT A HEX NO.
CPI     3AH        ; MORE THAN 39H?
JC      HEXGOOD   ; IF LESS THAN 39H IT COULD
                ; BE BETWEEN 0AH TO 0FH
CPI     41H        ; CHECK IF IT IS LESS
                ; THAN 41H
JC      HEXBAD    ; IF LESS THAN 41H AND
                ; MORE THAN 39H MEANS BAD
CPI     47H        ; IF IT IS MORE THAN 41H
                ; SEE IF MORE THAN 46H
JNC     HEXBAD    ; IF MORE THAN 46H IT IS
                ; BAD
ADI     09H        ; IF BETWEEN 0AH AND 0FH
                ; WE ADD 9H TO GET HEX VALUE
HEXGOOD: ANI     0FH        ; CLEAR THE CARRY FLAG AND
                ; MASK OFF THE TOP NYBBLE
RET
HEXBAD:  STC          ; BAD HEX VALUE, INDICATE
                ; BY RAISING CARRY FLAG.
RET

```

```

;
;THE HEX TO ASCII ENCODING ROUTINE- THIS ROUTINE
;ENCODS HEX VALUES TO THEIR EQUIVALENT ASCII VALUES.
;THE HEX VALUE IS PASSED THROUGH THE ACC AND THE ASCII
;VALUE IS RETURNED IN THE ACC.

```

ASC\$ENCODE:

```

ANI      0FH      ;GET RID OF TOP NYBBLE
           ;GARBAGE
ADI      30H      ;ADD 30H
CPI      3AH      ;CHECK IF VALUE WAS
           ;0AH-0FH?
RC       ;IF NOT WE ARE DONE-
           ;RETURN
ADI      07H      ;IF ABOVE 9H WE ADD 7 TO
           ;GET ASCII EQU.
RET

```

```

;
;THE RAM LOADING SUBROUTINE- THIS SUBROUTINE LOADS ONE
;NYBBLE OF THE MICROWORD (RAM) WITH THE DATA PASSED TO IT
;IN THE ACC. THE ADDRESS OF THE RAM (INCLUDING THE
;RAM/MUX ADDRESS) IS PASSED THROUGH REGISTER B. NOTE
;THIS ADDRESS IS THEN 7 BITS LONG, THE LOWER THREE BITS
;BEING THE RAM/MUX SELECT BITS.

```

LOAD\$NYBBLE:

```

OUT      PORT$A   ;SEND THE DATA OUT PORT A
MVI A,DATA$LATCH ;SET UP TO LATCH
           ;THE DATA IN
OUT      PORT$B   ;SEND IT OUT PORT B WHICH
           ;LATCHES THE DATA IN
MVI      A,00H   ;
OUT      PORT$B   ;
MOV      A,B     ;LOAD ADDRESS INTO ACC FROM
           ;THE B REG.
OUT      PORT$A   ;SEND THE ADDRESS OUT
           ;PORT A
MVI A,ADDRESS$LATCH ;SET UP TO LATCH
           ;IN THE ADDRESS
OUT      PORT$B   ;LATCH IT
MVI A,MUX$LATCH  ;SET UP TO LATCH IN THE
           ;RAM/MUX SELECT
OUT      PORT$B   ;LATCH IT
MVI A,MEMORY$LOAD ;SET UP TO STROBE
           ;THE MEMORY LOAD
OUT      PORT$B   ;LOAD THE MEMORY
CALL     DELAY    ;DELAY FOR PROPAGATION
           ;ETC.
MVI      A,0H    ;
OUT      PORT$B   ;LOWER THE MEMORY LOAD
           ;PULSE
RET

```


;

;THE LOAD WORD SUBROUTINE- AN EXPANSION OF THE LOAD

;NYBBLE ROUTINE EARLIER. THIS ROUTINE LOADS ALL 8

;NYBBLES OF THE MICROWORD FROM THE LSN OF THE 8 BYTE LONG

;BUFFER CALLED LOAD\$BUFFER. THE ADDRESS OF THE MICROWORD

;TO BE LOADED SHOULD BE PASSED IN REGISTER B.

LOAD\$WORD:

```

MVI A,SEL$LOAD ;MAKE SURE SYSTEM IS IN
                ;LOAD
OUT    PORT$A ;MODE
MVI A,RUN$LOAD$LATCH ;LATCH IN
OUT    PORT$B ;
MVI    A,00H ;
OUT    PORT$B ;LOWER LATCH SIGNAL
MOV    A,B ;PUT THE MICROWORD
                ;ADDRESS IN THE ACC
ANI    0FH ;MASK OFF GARBAGE
RLC
RLC
RLC
                ;PUT THE ADDRESS INTO
                ;BITS A3 TO A6
ORI    07H ;SO THAT THE MUX/RAM
                ;ADDRESS CAN BE IN
MOV    B,A ;BITS A0 TO A2, RETURN IT
                ;TO REG B
MVI    C,8 ;SET UP A COUNTER FOR
                ;8 NYBBLES
LXI H,LOAD$BUFFER ;SET UP TO READ
                ;THE BUFFER
LOAD$WORD1: MOV    A,M ;GET THE NYBBLE
CALL   LOAD$NYBBLE ;LOAD IT INTO
                ;THE MICROWORD
INX    H ;SET UP TO GET NEXT
                ;NYBBLE OF DATA
DCR    B ;SET UP NEXT MUX/RAM
                ;ADDRESS
DCR    C ;DECREMENT THE COUNTER
JNZ   LOAD$WORD1 ;IF NOT DONE JUMP BACK
                ;TO CONT.
RET ;IF DONE- RETURN.

```

;

;THE PRINT AND PULSE ROUTINE- THIS ROUTINE PRINTS THE

;ADDRESS THAT IS STORED IN THE MEMORY AS 'ADDRESS' AND

;THEN PRINTS EACH OF THE PRESENT AM2900 DISPLAY REGISTERS

;I.E. THE DATA, PIPELINE AND MICROWORD REGISTERS. WHEN

;THIS IS COMPLETED THE ROUTINE SENDS OUT A CLOCK PULSE

;TO THE AM2900.

PRINT\$PULSE:

```

LDA    ADDR    ;CALL IN THE PRESENT
                    ;ADDRESS
STA    CONSOLE$BUFFER    ;PUT IT IN THE
                    ;BUFFER TO
                    ;PRINT IT
MVI    A, '='    ;PUT AN '=' IN BUFFER
STA    CONSOLE$BUFFER+1    ;
MVI    A, '$'    ;INDICATE END OF STRING
STA    CONSOLE$BUFFER+2    ;
CALL    CONSOUT    ;PRINT THE BUFFER
CALL    XD        ;PRINT OUT THE DATA
                    ;REGISTER
LDA    CONSOLE$BUFFER+7    ;THE LAST
                    ;POSITION IN THIS
                    ;REGISTER
STA    ADDR    ;IS GOING TO BE THE NEXT
                    ;ADDRESS SO WE SAVE IT.
CALL    HEXCHECK    ;CHANGE IT TO HEX
STA    HEXADDR    ;AND SAVE IT
CALL    XP        ;PRINT OUT THE PRESENT
                    ;PIPELINE REG'S CONTENTS
CALL    XM        ;PRINT OUT THE PRESENT
                    ;MICROWORD REG'S CONTENTS
CALL    CR$LF    ;DO A CR AND A LF
MVI    A, PULSE    ;SEND OUT A CLOCK PULSE
                    ;TO AM2900
OUT    PORT$B    ;
MVI    A, 0H    ;CLEAR THE SIGNAL
OUT    PORT$B    ;
RET                    ;RETURN WITH NEXT ADDRESS
                    ;IN 'ADDRESS'. NOTE: IT
                    ;IS IN ASCII.

```

;

;THE SET UP TO RUN ROUTINE- THE ROUTINE IS USED TO LOAD

;IN THE FIRST ADDRESS INTO THE PIPELINE BEFORE YOU START

;RUNNING THE PROGRAM. IT IS DONE BY SENDING OUT A CLOCK

;(SINGLE STEP) PULSE TO THE AM2900 WHILE IT IS STILL IN

;LOAD MODE. WHEN THAT IS COMPLETED THE ROUTINE PUTS THE

;AM2900 INTO RUN MODE. THE START ADDRESS SHOULD BE IN

;THE ACC. WHEN THE CALL IS MADE.

RUN\$SETUP:

```

ANI      0FH      ;
RLC      ;
RLC      ;
RLC      ;MOVE ADDRESS INTO BITS
          ;A6-A3
OUT      PORT$A   ;SEND OUT THE ADDRESS
MVI A,ADDRESS$LATCH ;LATCH IT IN
OUT      PORT$B   ;
MVI      A,00H   ;
OUT      PORT$B   ;
MVI A,SEL$LOAD   ;SELECT LOAD MODE
OUT      PORT$A   ;SEND IT OUT
MVI A,RUN$LOAD$LATCH ;LATCH IT IN
OUT      PORT$B   ;
MVI      A,PULSE ;SEND OUT THE SING STEP
          ;PULSE
OUT      PORT$B   ;TO LOAD THE FIRST
          ;MICROWORD INTO THE
          ;PIPELINE
MVI      A,0H    ;
OUT      PORT$B   ;
MVI A,SEL$RUN    ;SELECT RUN MODE.
OUT      PORT$A   ;
MVI A,RUN$LOAD$LATCH ;
OUT      PORT$B   ;
MVI      A,00H   ;
OUT      PORT$B   ;LOWER LATCH SIGNAL
RET      ;

```

;

;THE GO ROUTINE- THIS ROUTINE RUNS THE AM2900 BOARD. THE

;FORMAT FOR THIS COMMAND IS GN,M WHERE S N IS THE START

;ADDRESS AND M IS THE BREAK ADDRESS NOTE THE ',M' IS OPTIONAL.

GORUN:

```

MVI    A,0H      ;WE USE A FLAG LATER ON
STA    FLAG$ALL ;SO WE CLEAR IT HERE
LDA    KEYBOARD$BUFFER+1 ;WE CHECK IF
CPI    02H       ;LESS THAN 2 CHAR WERE
                        ;ENTERED
JC     ERROR     ;
JZ     GORUN3   ;IF EXACTLY 2 CHAR WERE
                        ;ENTERED WE JUMP AHEAD.
CPI    04H       ;IF MORE THAN 2 CHAR WE
                        ;CHECK FOR 4 CHARS
JNZ    ERROR     ;IF NOT 4 CHARS WE HAVE
                        ;AN ERROR
MVI    A,0FFH   ;IF 4 CHARS WE SET THE
                        ;FLAG, THAT MEANS
STA    FLAG$ALL ;WE HAVE A BREAK POINT
                        ;TO LOOK OUT FOR.
LDA    KEYBOARD$BUFFER+4 ;CHECK FOR A
                        ;COMMA
CPI    ', '     ;
JNZ    ERROR     ;
LDA    KEYBOARD$BUFFER+5 ;GET THE BREAK
                        ;ADDRESS
CALL   HEXCHECK  ;CHECK IF 'M' IS A VALID
                        ;HEX VALUE
JC     ERROR     ;
STA    BREAK$PT ;SAVE THE BREAKPOINT
                        ;ADDRESS

```

GORUN3:

```

LDA    KEYBOARD$BUFFER+3 ;GET 'N'
STA    ADDR             ;SAVE THE ADDRESS IN
                        ;ASCII
CALL   HEXCHECK        ;CHECK IF START ADDRESS
                        ;IS VALID
JC     ERROR           ;
STA    HEXADDR         ;SAVE THE ADDRESS IN HEX
CALL   RUN$SETUP       ;SET UP THE PIPELINE
                        ;REGISTER ETC

```

GORUN1:

```

CALL   PRINT$PULSE    ;SINGLE STEP
LDA    FLAG$ALL       ;CHECK TO SEE IF WE
                        ;HAVE A BREAKPOINT
CPI    0H             ;THAT NEEDS TO BE CHECKED
JZ     GORUN2        ;IF NOT JUMP AHEAD
LDA    HEXADDR        ;IF WE HAVE A BREAKPOINT
                        ;CHECK IT AGAINST THE HEX
                        ;VALUE OF THE ADDRESS
LXI   H,BREAK$PT     ;GET THE BREAK POINT
                        ;ADDRESS

```

```

                                CMP      M      ;COMPARE THEM
                                JZ       AM2900  ;IF WE HAVE REACHED THE
                                                ;ADDRESS WE EXIT
GORUN2:                        MVI      C,11    ;
                                CALL     BDOS   ;WE CHECK FOR ANY INPUT
                                                ;ON CONSOLE
                                CPI      0H     ;
                                JZ       GORUN1  ;IF NOT WE GO BACK TO
                                                ;LOOP
                                JMP      AM2900  ;IF ANY INPUT WE BREAK
                                                ;AND EXIT

```

```

;
;CARRIAGE RETURN, LINE FEED SUBROUTINE- PRINTS A 'CR'
;AND A 'LF'.

```

CR\$LF:

```

                                MVI      A,0DH  ;'CR'
                                STA     CONSOLE$BUFFER      ;PUT INTO OUTPUT
                                                                ;BUFFER
                                MVI      A,0AH  ;'LF'
                                STA     CONSOLE$BUFFER+1    ;
                                MVI      A,'$'   ;END OF STRING MARKER
                                STA     CONSOLE$BUFFER+2    ;
                                CALL     CONSOUT ;
                                RET      ;

```

```

;
;THE SINGLE STEP COMMAND- THIS COMMAND EXPECTS AN INPUT
;OF THE FORMAT -SN...WHERE N IS THE ADDRESS AT WHICH TO
;START. IF NO N IS ENTERED THE DEFAULT IN 0H.

```

SINGSTEP:

```

                                LDA     KEYBOARD$BUFFER+1  ;FIND OUT HOW
                                                                ;MANY CHARS WERE
                                                                ;INPUT
                                CPI      02H   ;2 CHARS?
                                MVI      A,30H  ;ONLY 'S' INPUT THEN
                                                                ;DEFAULT ADDR=0H
                                JC       SINGSTEP1         ;JUMP AHEAD
                                JNZ     ERROR  ;IF MORE THAN 2 CHARS -
                                                                ;ERROR

```

SINGSTEP1:

```

                                LDA     KEYBOARD$BUFFER+3  ;GET N INTO ACC.
                                STA     ADDR  ;SAVE THE ASCII ADDRESS
                                CALL    HEXCHECK ;VALID N?
                                JC       ERROR  ;
                                STA     HEXADDR ;SAVE THE START ADDR
                                CALL    RUN$SETUP ;SET UP PIPELINE ETC

```

```

SINGSTEP2:    CALL PRINT$PULSE          ;SINGLE STEP!
              CALL   CONSIN           ;READ USER'S INPUT
              LDA   KEYBOARD$BUFFER+1 ;
              CPI   00H              ;WAS IT A 'CR', I.E. ONLY
              ;                       ;ONE CHAR WAS ENTRD
              JNZ   AM2900           ;IF NOT RETURN TO MAIN
              ;                       ;ROUTINE
              JMP   SINGSTEP2       ;IF 'CR' CONTINUE SINGLE STEP

```

```

;
;THE LOAD COMMAND- THIS COMMAND ALLOWS THE USER TO
;MICROPROGRAM THE AM2900, IT ALSO ALLOWS THE USER TO VIEW
;AND OPTIONALLY CHANGE THE CONTENTS OF THE MICROPROGRAM
;RAM. THE COMMAND FORMAT IS '-LN' WHERE N IS THE START
;ADDRESS. N IS OPTIONAL AND IF IT IS NOT PRESENT THE
;DEFAULT ADDRESS IS 0.

```

LOADING:

```

              LDA   KEYBOARD$BUFFER+1 ;FIND OUT HOW
              ;     ;MANY CHARS WERE
              ;     ;JUST READ IN
              CPI   02H              ;CHECK FOR 2 CHARS
              MVI   A,30H            ;DEFAULT ADDRESS IS ZERO
              JC    LOADING1         ;ONLY ONE CHAR USE
              ;     ;DEFAULT ADDRESS
              JNZ   ERROR            ;MORE THAN 2 CHARS -
              ;     ;ERROR

```

```

              LDA   KEYBOARD$BUFFER+3 ;READ THE ADDRESS
              ;     ;IF THERE
              ;     ;WAS ONE.

```

```

LOADING1:    STA   ADDR              ;SAVE THE ADDRESS
LOADING2:    LDA   ADDR              ;GET THE ASCII ADDRESS
              STA   CONSOLE$BUFFER   ;STORE IT TO
              ;     ;PRINT IT
              CALL  HEXCHECK         ;MAKE SURE AND CONVERT
              ;     ;TO HEX
              JC    ERROR            ;
              STA   ADDR              ;SAVE THE HEX VERSION
              ;     ;OF ADDRESS
              MVI   A,'-'           ;
              STA   CONSOLE$BUFFER+1 ;SET UP DISPLAY
              MVI   A,'$'           ;END MARKER
              STA   CONSOLE$BUFFER+2 ;
              CALL  CONSOUT          ;
              LDA   ADDR              ;CALL BACK HEX ADDRESS
              ANI   0FH              ;MASK OFF GARBAGE
              RLC                      ;MOVE ADDRESS TO BITS
              ;                       ;A6-A3
              RLC                      ;
              RLC                      ;

```

```

OUT     PORT%A    ;SEND THE ADDRESS OUT
                    ;TO AM2900
MVI A,ADDRESS$LATCH    ;LATCH IN THE
                    ;ADDRESS

OUT     PORT%B    ;
MVI     A,00H     ;
OUT     PORT%B    ;
MVI C,SEL$MICROWORD    ;SET UP TO READ
                    ;THE MICROWORD]
CALL RD$PRINT$8NYBBLES    ;LEDS, GO TO
                    ;READ THEM
CALL     CONSIN    ;READ THE USERS INPUT
LDA KEYBOARD$BUFFER+1    ;CHECK TO SEE IF
                    ;WE ARE TO
                    ;LOAD, CONTINUE
                    ;OR EXIT

ADI     0          ;SET ZERO FLAG IF ACC IS
                    ;ZERO
JZ      AM2900    ;IF NO INPUT I.WE. CR
                    ;ONLY WE EXIT
CPI     01H       ;CHECK FOR 1 CHAR INPUT
                    ;I.E. A 'SP'
JZ      LOADING3  ;IF ONLY 1 CHAR WE
                    ;CHECK IT
CPI     08H       ;CHECK FOR 8 CHAR INPUT
JNZ     ERROR     ;IF NONE OF THE ABOVE WE
                    ;HAVE AN ERROR
LXI H,KEYBOARD$BUFFER+2 ;NOW WE CHECK TO
                    ;SEE IF ALL
MVI     B,08H     ;8 CHARS INPUT ARE VALID
                    ;FOR DATA
LXI D,LOADBUFFER  ;SET UP THE BUFFER THAT
                    ;WE WILL USE TO LOAD THE
                    ;NEW DATA INTO THE
                    ;AM2900
LOADING4: MOV     A,M    ;GET THE CHAR
CALL    HEXCHECK  ;CHECK IF IT IS A VALID
                    ;HEX DIGIT
JC      ERROR     ;
STAX   D          ;IF VALID PUT IT IN THE
                    ;LOAD BUFFER
INX    H          ;SELECT NEXT CHAR
INX    D          ;SELECT NEXT LOAD BUFFER
                    ;LOCATION
DCR    B          ;COUNTDOWN
JNZ    LOADING4  ;ALL NOT DONE GO BACK
                    ;FOR NEXT CHAR

```

```

LDA    ADDR    ;PUT THE START ADDRESS
                ;IN THE B REG
MOV    B,A     ;SO WE CAN CALL THE
                ;LOAD$WORD SBR
CALL   LOAD$WORD ;
JMP    LOADING5; JUMP AHEAD TO REPEAT ROUTINE.

```

```

LOADING3:      LDA  KEYBOARD$BUFFER+2    ;CHECK IF INPUT
                ;WAS A SPACE.
CPI        20H    ;
JNZ        ERROR  ;IF IT WASN'T A SPACE WE
                ;HAVE AN ERROR
;
LOADING5:      LDA  ADDR    ;GET NEXT ADDRESS TO LOAD
INR        A      ;BY INCREMENTING CURRENT
                ;ADDRESS
CALL   ASC$ENCODE ;CHANGE ADDRESS BACK TO
                ;ASCII
STA        ADDR    ;STORE IT BACK
;
CALL       CR$LF   ;NEXT LINE
JMP        LOADING2 ;RETURN TO CONTINUE
                ;ROUTINE.

```

```

;
;THE EXAMINE COMMAND- THIS COMMAND HAS 4 PARTS, AN
;EXAMINE ALL OPTION WHICH DISPLAYS THE PRESENT CONTENTS
;OF ALL THE THREE DISPLAY REGISTERS ON THE AM2900
;(I.E. THE DATA, PIPELINE AND MICROWORD REGISTERS).
;THE OTHER OPTIONS ARE TO VIEW ANY ONE OF THE REGISTERS
;INDIVIDUALLY. NOTE OF COURSE THAT YOU CANNOT CHANGE
;THE CONTENTS OF THESE REGISTERS.

```

```

EXAMINE:
LDA  KEYBOARD$BUFFER+1    ;AS USUAL WE
                ;FIRST CHECK
CPI        02H           ;TO MAKE SURE THE
                ;RIGHT COMMAND
JZ  EXAMINE$ONE          ;WAS ENTERED
JNC        ERROR        ;IF IT WASN'T WE GO TO
                ;THE ERROR ROUTINE
;
EXAMINE$ALL:  CALL   XD      ;DISPLAY ALL THE
                ;REGISTERS, DATA FIRST
CALL        XP           ;PIPELINE SECOND
CALL        XM           ;MICROWORD LAST
CALL        CR$LF       ;DO A 'CR' AND 'LF'
JMP        AM2900      ;RETURN TO THE MAIN
                ;ROUTINE

```



```

;
EXAMINE$ONE:   LDA  KEYBOARD$BUFFER+3   ;DISPLAY ONLY
;ONE REGISTER
                CPI    'D'           ;IS IT 'D'
                JNZ    EXAM1          ;NO TRY NEXT LETTER
                CALL   XD             ;IF IT WAS DISPLAY IT
                CALL   CR$LF          ;
                JMP    AM2900         ;EXIT
EXAM1          CPI    'P'           ;CHECK FOR 'P'
                JNZ    EXAM2          ;IF NOT JUMP AHEAD
                CALL   XP             ;
                CALL   CR$LF          ;
                JMP    AM2900         ;EXIT
EXAM2          CPI    'M'           ;CHECK FOR 'M'
                JNZ    ERROR          ;IF NONE OF THE ABOVE WE
;HAVE AN ERROR
                CALL   XM             ;
                CALL   CR$LF          ;
                JMP    AM2900         ;

```

```

;
; THE XD,XP AND XM ROUTINES-
;

```

```

XD:            MVI    A, 'D'         ;PUT A 'D' IN THE BUFFER
;TO PRINT IT
                STA  CONSOLE$BUFFER ;
                MVI  A, '-'         ;
                STA  CONSOLE$BUFFER+1 ;
                MVI  A, '$'         ;PUT AND END OF STRING
;MARKER FOR
                STA  CONSOLE$BUFFER+2 ;THE BDOS
;SUBROUTINE
                CALL  CONSOUT        ;PRINT THE 'D-'
                MVI  C, SEL$DATA     ;SELECT THE DATA REGISTER
;TO BE LOADED
                CALL  RD$PRINT$8NYBBLES ;LOAD IN AND
;PRINT OUT THE
;DATA
                RET                    ;

```

```

;
XP:            MVI    A, 'P'         ;
                STA  CONSOLE$BUFFER ;
                MVI  A, '-'         ;
                STA  CONSOLE$BUFFER+1 ;
                MVI  A, '$'         ;
                STA  CONSOLE$BUFFER+2 ;
                CALL  CONSOUT        ;
                MVI  C, SEL$PIPELINE ;
                CALL  RD$PRINT$8NYBBLES ;
                RET
;

```

```
XM:      MVI      A, 'M'      ;
          STA     CONSOLE$BUFFER      ;
          MVI     A, '-'      ;
          STA     CONSOLE$BUFFER+1    ;
          MVI     A, '$'      ;
          STA     CONSOLE$BUFFER+2    ;
          CALL    CONSOUT      ;
          MVI     C, SEL$MICROWORD    ;
          CALL    RD$PRINT$8NYBBLES  ;
          RET

          ;

          END      100H
```