

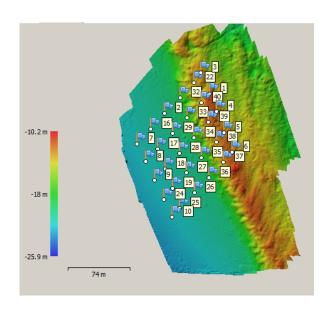






What's ahead

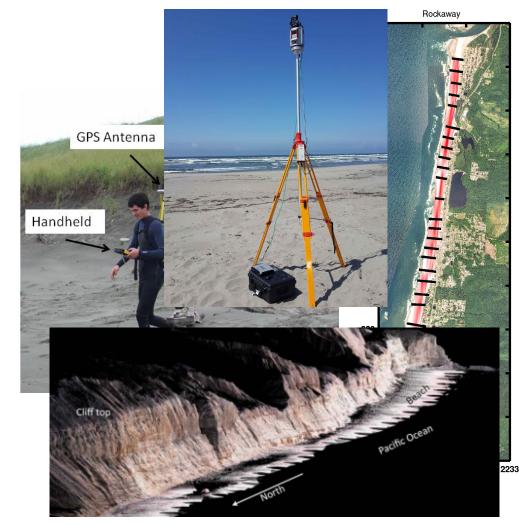
- Introduce a low-cost and efficient technique for geomorphic data extraction called Structure from Motion (SfM)
- Evaluation of multiple low-cost SfM data collection platforms through a cost vs. performance analysis





Background- measuring subaerial beach and dune morphology

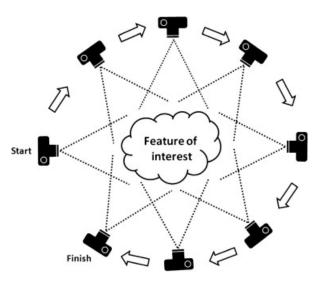
- Some current methods:
 - RTK GPS- ~5cm
 vertical accuracy, but
 requires lots of time
 and effort for
 relatively little data
 - TLS- highly accurate and spatially continuous data, but expensive and necessitates a high level of training

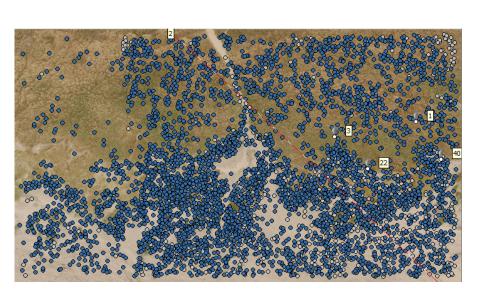


Next Steps

Structure from Motion: accurate, efficient, low-cost, and user-friendly

- 3-d reconstruction of a surface built from overlapping aerial photos
- Workflow:
 - Features ID'd and tracked across photos, solving automatically for camera intrinsic and extrinsic parameters, scene geometry





Next Steps

SfM is Flexible

- Many applications of SfM on the coast:
 - Sea cliff retreat rates (Warrick et al., 2016)
 - Intertidal ecology (Bryson et al., 2016)
 - Subaerial beach changes (Turner et al., 2016)
- This stems partially from flexibility in data collection platform
 - UAVs, kites, poles, balloons, airplanes, and any camera







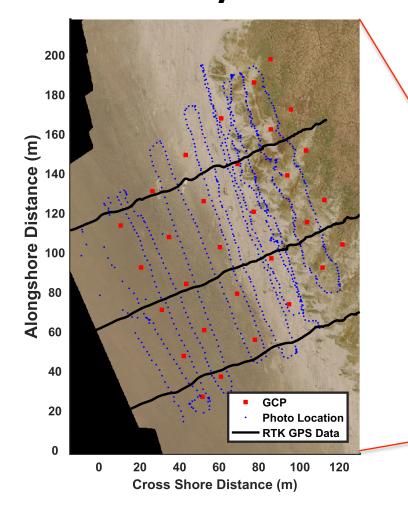
Next Steps

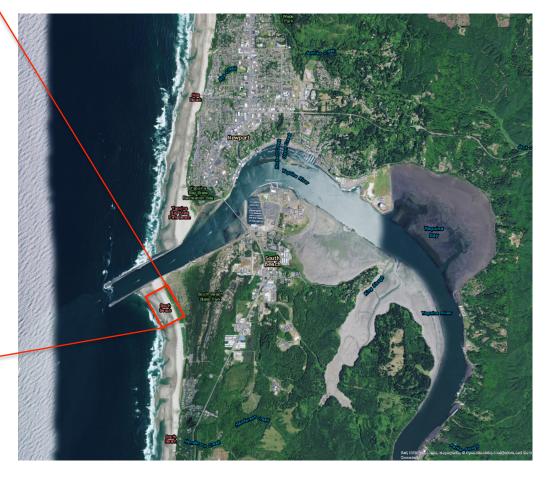
Aim of this Study

 Create quantitative comparison between lowcost SfM platforms on subaerial beaches and dunes

 Provide outline for other SfMers to select optimal platform to obtain desired data

Study Site and Image Collection





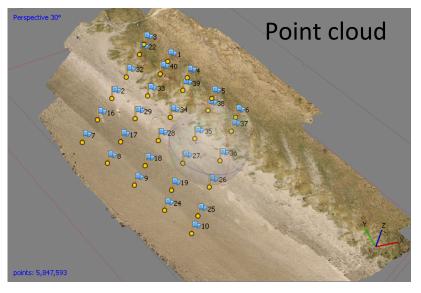
Data Collection Platforms

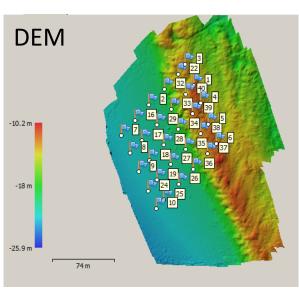


Frames Cameras

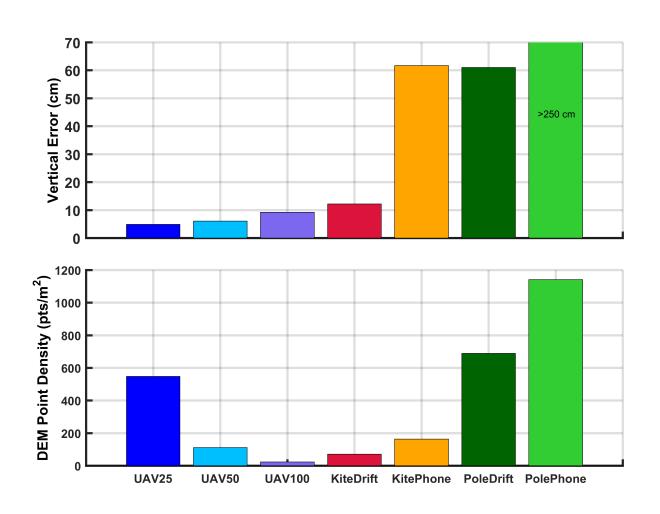
SfM Image Processing

- Images from each platform run through SfM workflow using Agisoft Photoscan
- DEM created for each platform's data





Comparison of Platforms



Notes:

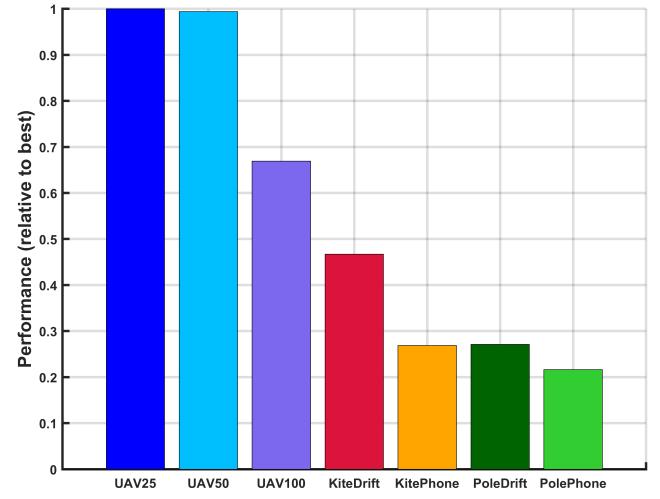
- UAV creating very accurate DEMs, kite and pole less
- Pole creating very spatially denseDEMs
- 3. Lower quality camera producing more accurate results with kite and pole

Platform Evaluation- a Cost vs. Performance Analysis

- Compare platforms through cost vs. "performance"
- Use methods adapted from environmental systems analysis and operational research
 - Scored categories
 - Category weights

$$Performance = \frac{\sum_{i=1}^{i=n} (Score_i * Weight_i)}{n}$$

Initial Results of the Cost vs. Performance Analysis



Category	Vertical Accuracy	DEM Point Density	Proportion of Area Modeled	Time to collect photos	RMS GCP Position Error	Processing Time per Image
Weight	.61	.07	.07	.21	.02	. 02

Preliminary Conclusions and Work to Do...

- UAV only platform creating consistently reliable data
- Lower cost platforms could still be useful
- To do:
 - Solidify PIs, perform full cost vs. performance analysis
 - Explain why some platforms perform better than others



Acknowledgements

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